

GLOBAL STORM SURGES

Theory, Observations and Applications
by

Gabriele Gönner, Shishir K. Dube,
Tad Murty and Winfried Siefert

Edited by:
German Coastal Engineering
Research Council

Die Küste

ARCHIV FÜR FORSCHUNG UND TECHNIK
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ON THE NORTH SEA AND BALTIC COAST

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Prof. Dr. Winfried Siefert

6th March 1940 to 17th March 1999



Winfried received his Ph.D. in Hydraulic Engineering in 1968 at the Franzius Institut, University of Hannover, and his thesis topic was storm surge forecasting. Thus began his life long interest in tidal and storm surge research.

Many projects concentrated on the Elbe Estuary but were followed by topics such as environmental impact in the Wadden Sea, morphology and wave climate. The latter was also the topic of his habilitation in Hydraulic Engineering. His interest in storm surges never diminished, and he gave new dimensions to storm surge prediction and established himself as not only a national, but also an international expert in this field of great practical importance. He developed very precise storm surge forecasting methods for Hamburg and contributed to the definition of design water levels for dikes.

During the IUGG conference in 1987 held in Vancouver, Canada, Tad Murty and Winfried Siefert met for the first time, even though they had been well aware of each other's work for a long time. At that first meeting mutual collaboration was discussed and as a consequence, Winfried spent six weeks visiting Tad at the Institute of Ocean Sciences, Department of Fisheries and Oceans, in Victoria, Canada. Subsequent to this visit, both collaborated within the International Hydrology Programme of UNESCO. They organized and participated in three conferences held in Germany in 1991, Netherlands in 1993 and in Thailand in 1995.

Winfried taught coastal engineering as well as carried out research projects at the University of Braunschweig and also at the Technical University of Hamburg. He published more than 100 scientific papers. He was an excellent and very popular teacher and always made difficult and complex appear simple to his students. With his wit and short stories from his research experience, he always made drab and routine topics sound very exciting. His sense of humor facilitated following weary discussions and committee meetings and always led to sensible conclusions.

We, the co-authors, Gabriele Gönner, Shishir Dube and Tad Murty express our deep appreciation and gratitude not only to an accomplished scientist, but also to a great colleague and friend, without whose vision and dedicated effort, this monograph would not have been possible. Therefore, we dedicate it to him. His friends and colleagues around the world, particularly in the field of storm surge research, will greatly miss him.

Global Storm Surges: Theory, Observations and Applications

GÖNNERT, G. M. / DUBE, S. K. / MURTY, T. S. / SIEFERT, W.

Vorwort

Im Mai 1979 bat die World Meteorological Organization (WMO) den Meteorologen Dr. TAD MURTY, Wissenschaftler bei der Bundesregierung von Kanada, den meteorologischen Dienst von Bangladesh (BMD) bei der Entwicklung von Sturmflutvorhersagemodellen für Bangladesh zu unterstützen. Bei der Literaturrecherche stellte er fest, dass es kein umfassendes Lehrbuch über Sturmfluten gab. Mit Unterstützung der Bundesregierung von Kanada schrieb er deshalb das Buch „Storm Surges – Meteorological Ocean Tides“, das 1984 als Monographie veröffentlicht wurde. Die dem Buch zugrunde liegenden Literaturrecherchen reichten bis in das Jahr 1982.

Wegen der starken Entwicklung in der Sturmflutforschung in den Jahren 1985 bis 1995 schlugen viele Kollegen TAD MURTY vor, das Buch zu überarbeiten und die neuesten Forschungsergebnisse einzubeziehen. Während einer Diskussion mit dem verstorbenen Prof. Dr.-Ing. WINFRIED SIEFERT, Leiter der Hydrologie in der Wirtschaftsbehörde Strom- und Hafenbau Hamburg und Experte in den Bereichen Sturmfluten und Vorhersage, einigte man sich auf eine gemeinsame Überarbeitung und Neuauflage dieses Buches. In den Kreis der Mitautoren wurden Prof. Dr. SHISHIR K. DUBE aus Indien, der zu den wichtigsten Sturmflutmodellierern der Welt gehört, und Dr. GABRIELE GÖNNERT, wissenschaftliche Mitarbeiterin von Prof. SIEFERT bei der Wirtschaftsbehörde Strom- und Hafenbau Hamburg, einbezogen. Frau GÖNNERT hat zudem die Veröffentlichung des neuen Buches mit dem Titel „Global Storm Surges: Theory, Observations and Applications“ geplant und organisiert. Es war die Absicht der Autoren, die wichtigen und grundlegenden Abschnitte der Monographie „Storm Surges – Meteorological Ocean Tides“ von Dr. MURTY in einer überarbeiteten Version zu übernehmen.

Zwei Treffen von je einer Woche in Hamburg 1996 und 1998 dienten der Koordination der Buchinhalte, die von den vier Autoren geschrieben wurden. Das Abschlusstreffen über zwei Wochen fand im Centre of Atmospheric Sciences, Indian Institute of Technology, Delhi, Indien, statt. Hier wurde das gesamte Manuskript fertiggestellt.

Das Bundesministerium für Forschung und Technologie (BMBF) stellte Fördermittel für die Arbeit am Buch, die Arbeitstreffen und den Druck zur Verfügung. Darüber hinaus entschied das Kuratorium für Forschung im Küsteningenieurwesen (KFKI), dass das Buch als Sonderheft des *Archivs für Forschung und Technik an Nord- und Ostsee* „Die Küste“ erscheinen soll. Für Beantragung von Geldmitteln für den Druck, Organisation und Revision des Buches danken die Autoren Dr.-Ing. V. BARTHEL.

Dr. GÖNNERT möchte den Mitgliedern der Projektgruppe des Forschungsprojektes „Windstauanalysen in Nord- und Ostsee“ mit LBD P. PETERSEN, Dr.-Ing. G. FLÜGGE, RD H. SCHMIDT, Dr.-Ing. E. RENGGER, Prof. Dr.-Ing. H. KUNZ und Dipl.-Ing. D. SCHALLER für die Diskussionen und Ideen während der Forschungsarbeit zu Sturmfluten und der Neubearbeitung des Buches danken. RD R. ANNUTSCH gilt besonderer Dank für die Unterstützung bei der Diskussion wesentlicher Fragen im Forschungsbereich Sturmfluten. Er investierte viel Zeit in die Gespräche zum Thema Tide und Sturmfluten.

Keine Worte können den tiefen Dank von Dr. GÖNNERT gegenüber Prof. Dr.-Ing. WINFRIED SIEFERT realistisch beschreiben. Er war ihr Lehrer im Küsteningenieurwesen, Doktorvater und ihr Vorgesetzter in der Hydrologie bei Strom- und Hafenbau Hamburg.

Prof. DUBE dankt dem Indian Institute of Technology, Delhi, und hier besonders Direktor Prof. V. S. RAJU dafür, dass er alle Einrichtungen des Instituts zur Verfügung stellte sowie für die moralische Unterstützung bei der Fertigstellung des Buches. Großer Dank geht an Prof. SINHA, Dr. A. D. RAO, Dr. P. CHITTIBABU, Dr. BHASKARAN, Ms. RUCHI KALRA und Mr. DEBASIS MAHAPATRA vom Centre for Atmospheric Sciences, IIT Delhi für ihre Beiträge.

Dr. MURTY dankt der Regierung von Kanada, die das erste Buch ermöglicht hat, und dem Ingenieurbüro Baird and Associates Coastal Engineers, Ottawa, Kanada, für die Möglichkeit, das zweite, hier vorliegende Buch, zu erstellen. Dank und Anerkennung gilt weiterhin den Beiträgen von Prof. GEORGE W. PLATZMAN von der Universität von Chicago und den Kollegen Dr. D. RAO, Dr. R. F. HENRY sowie den verstorbenen Dr. T. J. SIMONS und Dr. M. I. EL SABH bei der Weiterentwicklung des Verständnisses des Sturmflutphänomens. Dr. M. B. DANRD und Dr. JOHN LUICK und dem verstorbenen Dr. N. G. FREEMAN sei ebenfalls für ihre Beiträge gedankt.

Preface

In May 1979 the World Meteorological Organization (WMO) invited Dr. TAD MURTY, a senior Research Scientist working for the Federal Government of Canada, to help the Bangladesh Meteorological Department (BMD) with the development of storm surge prediction models for the Bay of Bengal. Dr. MURTY looked for lecture material on storm surges for talks in Bangladesh and elsewhere and found that as yet there was no textbook on storm surges. Using the resources of the Canadian Government, he wrote a book titled "Storm Surges – Meteorological Ocean Tides" which was published as a monograph by the Canadian Government. This book was published in October 1984, and the references that were cited were up to date till the end of 1982.

During the years 1985 to 1995, several colleagues of MURTY around the world suggested to him that in view of the tremendous advances made in storm surge research during those years, it will be very useful for the global research community to have an updates version of the book which includes a synthesis of the new material and this should be the goal of an updated version. In 1995 during discussions with the late Dr. WINFRIED SIEFERT, head of hydrology at the Department of Port and River Engineering of Free and Hanseatic City of Hamburg and specialist in storm surges and protection, Drs. MURTY and SIEFERT realised that the book by Dr. MURTY should be updated. Subsequently Prof. SHISHIR K. DUBE, an eminent storm surge modeler from India, who is among the top surge modelers in the world was recruited to be a co-author in this effort. Also Dr. GABI GÖNNERT, scientist for climatology, tides, storm surges and protection at the Department of Port and River Engineering of Free and Hanseatic City of Hamburg was recruited to be a co-author and she took the lead in organizing, planning and publication of the new book, which is titled "Global Storm Surges: Theory, Observations and Applications". It is the intention in this new book to use necessary and basic parts from the monograph of Dr. MURTY "Storm Surges – Meteorological Ocean Tides". Therefore revised repetitions from the book of MURTY (1984) were included in the new book.

Two meetings (each one week long) were held in Hamburg during 1996 and 1998 to co-ordinate the parts written by the four authors. A final meeting, two weeks long was held at

the Centre for Atmospheric Sciences, Indian Institute of Technology, Delhi, India, to put together the full manuscript.

The Federal Government of Germany (BMBF) provided funding for work on the book, for the necessary meetings and for printing. Moreover, the Coastal Engineering Research Council (KFKI) decided to have the book printed as a special issue of "Die Küste". For providing funding for printing, organization and for reviewing the book the authors express their gratitude to Dr. V. BARTHEL.

Dr. GÖNNERT would like to recognize the contributions of the members of the working group for the research project "Storm Surges in the German Bight" with LBD PETERSEN, Dr. G. FLÜGGE, RD H. SCHMIDT, Dr. E. RENGEL, Prof. Dr. H. KUNZ and Dipl.-Ing. D. SCHALLER for discussion and productive ideas enabling her research in storm surges and revising this book. RD RALF ANNUTSCH's help is greatly acknowledged. He assisted in developing her understanding in storm surges and took always time for discussions on tides and storm surges.

No words can describe realistically Dr. GÖNNERT's acknowledgement of and deep gratitude towards the late Prof. Dr. W. SIEFERT. He was her teacher in coastal engineering, supervisor and head at the Department of Port and River engineering.

Professor DUBE is grateful to the Indian Institute of Technology Delhi in general and Professor V. S. RAJU, Director in particular for extending all facilities and providing moral support for the completion of the book. Contributions made by Professor P. C. SINHA, Dr. A. D. RAO, Dr. P. CHITTIBABU, Dr. P. K. BHASKARAN, Ms. RUCHI KALRA and Mr. DEBASIS MAHAPATRA of the Centre for Atmospheric Sciences, IIT Delhi is greatly acknowledged.

Dr. MURTY expresses his gratitude to the Government of Canada to make the first book possible and to Baird and Associates Coastal Engineers of Ottawa, Canada, to make the second book possible. He also would like to recognize the contributions from Prof. GEORGE. W. PLATZMAN of the University of Chicago, and his professional colleagues Dr. D. B. RAO, Dr. R. F. HENRY and the late Drs. T. J. SIMONS and M. I. EL-SABH, in developing his understanding of the storm surge phenomena. Contributions made by Dr. M. B. DANARD and Dr. JOHN LUICK and the late Dr. N. G. FREEMAN are also greatly acknowledged.

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1. Introduction and General Considerations

1.1 Introduction to Oceanographical Aspects of Storm Surges

Storm surges are oscillations of the water level in a coastal or inland water body in the period range of a few minutes to a few days, resulting from forcing from the atmospheric weather systems. By this definition, the so-called wind-generated waves (often referred to as wind waves) and swell, which have periods of the order of a few to several seconds, are excluded. The term “storm surge” is commonly used in European literature, especially in the literature pertaining to the water level oscillations in the North Sea. In North American literature, the terms “wind tides” and “storm tides” are also used to refer to the same phenomenon.

Unfortunately, the term “wind tides” has occasionally been used as a synonym for low storm tides and – in aeronomy – to refer to atmospheric tides (which have the same astronomical origin as oceanic tides). Hence, the term will not be used here. The term “storm tide” is used in North American literature in a confusing manner: at times it is used in the same sense as storm surge, and at other times it is used to denote the sum of the storm surge and the astronomical tide. Here, the term will be used only in the latter sense and describes the whole event. Sometimes the term “storm tide” is meant to be the highest peak due to interaction of tide and storm surge. This parameter will be denoted here as “high water level” (HWL). As an alternative to the term “storm surges”, the term “meteorological ocean tides” will be used. In some sense, storm surges are similar to astronomical tides: although storm surges are not periodic in the sense that tides are, they do exhibit certain periodicities, and since the forcing functions are due to meteorological causes, it is not inappropriate to call them meteorological ocean tides. Here, the word “ocean” is used to denote a water body of any scale, and not necessarily the oceans. In Russian literature (e.g. see LAPPO and ROZHDESTVENSKIY, 1979), the term “meteorological ocean tide” is commonly used.

The spectrum of ocean waves is shown schematically in Fig. 1.1, and it can be seen that storm surges are centered at about 10^{-4} cycles per second (cps or Hz), which gives a period of about 3 h. However, depending mainly on the topography of the water body and secondarily on other parameters, such as the direction of movement of the storm, strength of the storm, stratification of the water body, presence or absence of ice cover, nature of tidal motion in the water body, etc., the periods in the water level oscillations may vary consider-

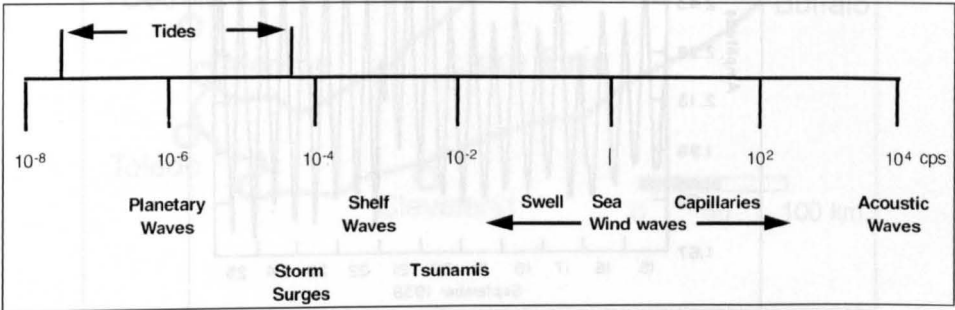


Fig. 1.1: Frequencies of oceanic wave motion in cycles per second (cps) (PLATZMAN, 1971)

ably. Even the same water body, storm surge records at different locations can exhibit different periods.

Although storm surges belong to the same class known as long waves, as do astronomical tides and tsunamis, there are at least two important differences. First, whereas tides and tsunamis occur on the oceanic scale, storm surges are simply a coastal phenomenon. Second, significant tsunamis and tides cannot occur in a completely closed small coastal or inland water body, but storm surges can occur even in completely enclosed lakes, or in canals and rivers.

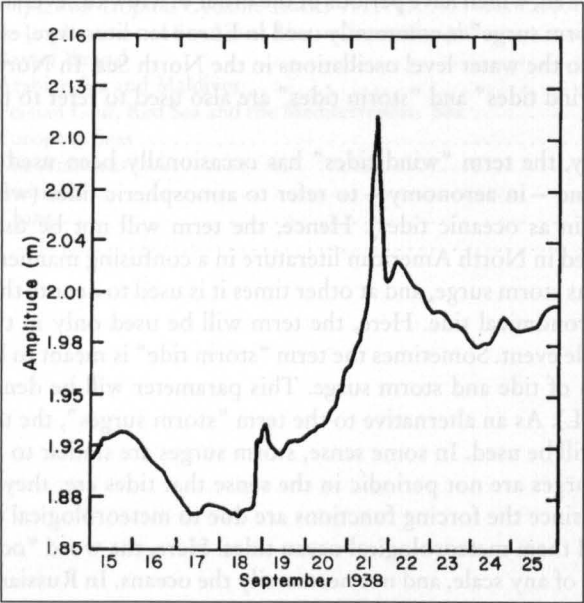


Fig. 1.2: Storm Surge at Forest Hills, New York (PAULSEN et al., 1940)

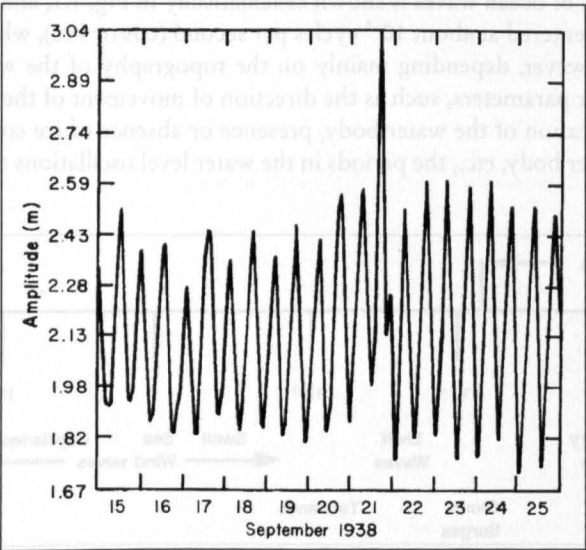


Fig. 1.3: Storm Surge at Rockaway Park, New York (PAULSEN et al., 1940)

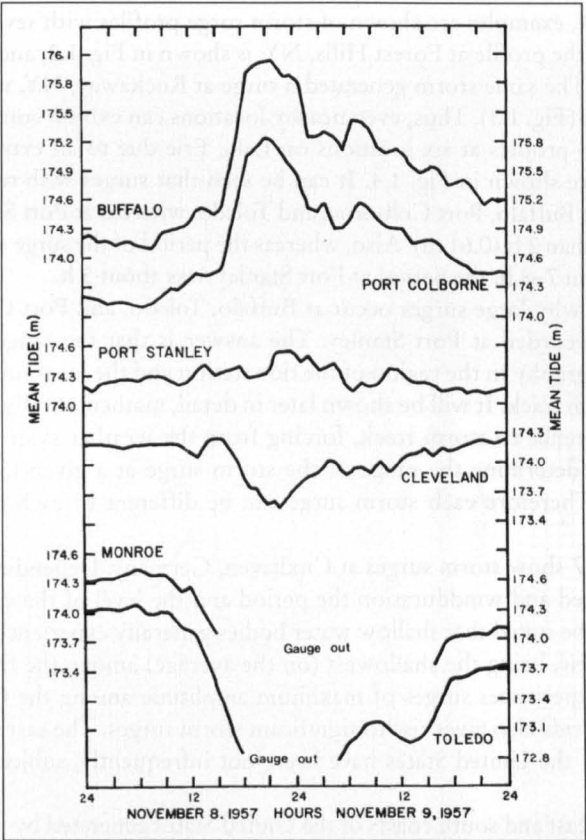


Fig. 1.4: Observed storm surges at six locations on Lake Erie. Mean tides are shown on the left ordinate for Buffalo, Port Stanley, and Monroe and on the right ordinate for Port Colborne, Cleveland, and Toledo. Mean tides are metres above the Great Lakes Datum with reference to the mean tide at New York (HUNT, 1959)

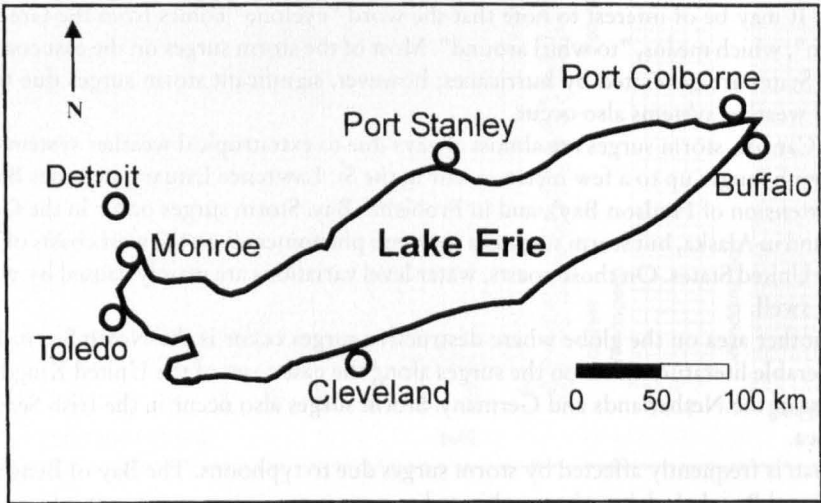


Fig. 1.5: Map of Lake Erie

In Fig. 1.2–1.4, examples are shown of storm surge profiles with several different periods. For example, the profile at Forest Hills, NY, is shown in Fig. 1.2, and a period of about 2.5 d can be seen. The same storm generated a surge at Rockaway, NY, with periods of the order of 1 d or less (Fig. 1.3). Thus, even nearby locations can exhibit considerably differing periods. The surge profiles at six locations on Lake Erie due to an extratropical storm in November 1957 are shown in Fig. 1.4. It can be seen that surges with ranges of up to 8 ft (2.4 m) occurred at Buffalo, Port Colborne, and Toledo, whereas at Port Stanley the range of the surge was less than 2 ft (0.61 m). Also, whereas the period of the surge at Buffalo and Port Colborne was about 7–8 h, the period at Port Stanley was about 3 h.

One may ask why large surges occur at Buffalo, Toledo, and Port Colborne and only small surges are recorded at Port Stanley. The answer is that the range of the surge depends on the topography in the region of the tide station and the location of the tide station relative to the storm track. It will be shown later in detail, mathematically, how topography, position with reference to storm track, forcing from the weather systems, plus a host of secondary factors determine the range of the storm surge at a given location in a specified water body. Therefore each storm surge can be different to each other at one location.

Fig. 1.6 and 1.7 show storm surges at Cuxhaven, Germany. Depending upon the wind-direction, windspeed and windduration the period and the level of the surge differs considerably. But it can be stated that shallow water bodies generally experience surges with greater ranges. Lake Erie, being the shallowest (on the average) among the five Great Lakes of North America, experiences surges of maximum amplitude among the Great Lakes. Lake Okeechobee in Florida also gives rise to significant storm surges. The east coast and the Gulf of Mexico coast of the United States have been, not infrequently, subjected to destructive storm surges.

Surges on the east and south coasts of the United States generated by tropical storms are referred to as “hurricanes”. Similar tropical storms in the Pacific are referred to as “typhoons”. (The Japanese refer to them also as “Reppus”.) In Australia, they are called “willy-willies”, in the Philippines “Baguios”, and in Arabia “Asifat”. Tropical cyclones in the Indian Ocean, Bay of Bengal, and the Arabian Sea are popularly referred to as “depressions”, although there is a strict classification based on maximum wind speed attained in the weather system. It may be of interest to note that the word “cyclone” comes from the Greek word „kyklon“, which means, “to whirl around”. Most of the storm surges on the east coast of the United States are generated by hurricanes; however, significant storm surges due to extratropical weather systems also occur.

In Canada, storm surges are almost always due to extratropical weather systems. Storm surges with ranges up to a few metres occur in the St. Lawrence Estuary, in James Bay (southern extension of Hudson Bay), and in Frobisher Bay. Storm surges occur in the Canadian Arctic and in Alaska, but storm surge is a very rare phenomenon on the west coasts of Canada and the United States. On those coasts, water level variations are mainly caused by wind waves and swell.

Another area on the globe where destructive surges occur is the North Sea in Europe. Considerable literature exists on the surges along the east coast of the United Kingdom and the coast of the Netherlands and Germany. Storm surges also occur in the Irish Sea and the Baltic Sea.

Japan is frequently affected by storm surges due to typhoons. The Bay of Bengal coasts of India and Bangladesh have been subjected to very severe storm surges not infrequently. It will be seen later that the peculiar topography (i.e. triangular or V-shaped basin), shallowness

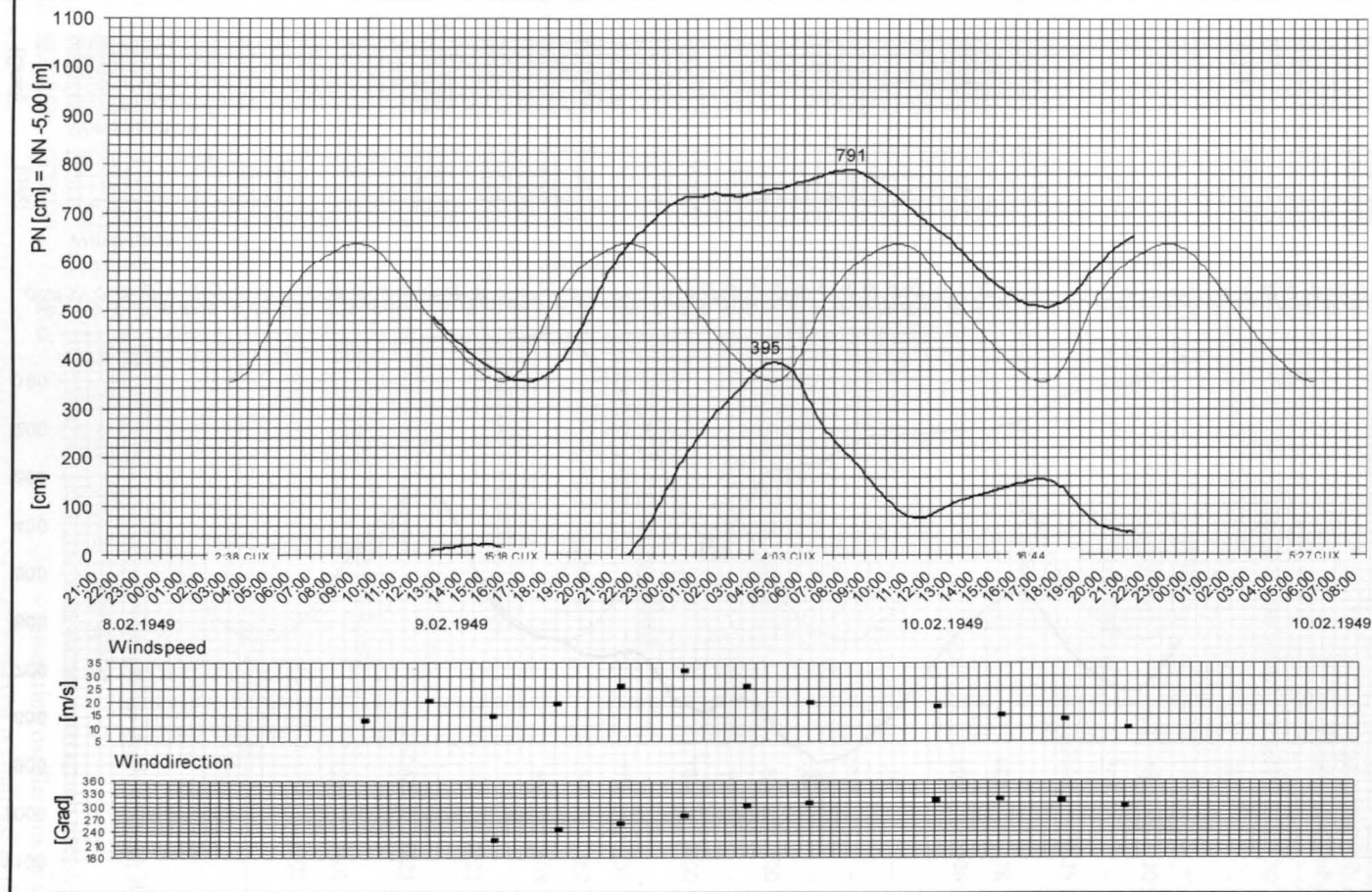


Fig. 1.6: Storm Surge from February 10, 1949 at Cuxhaven

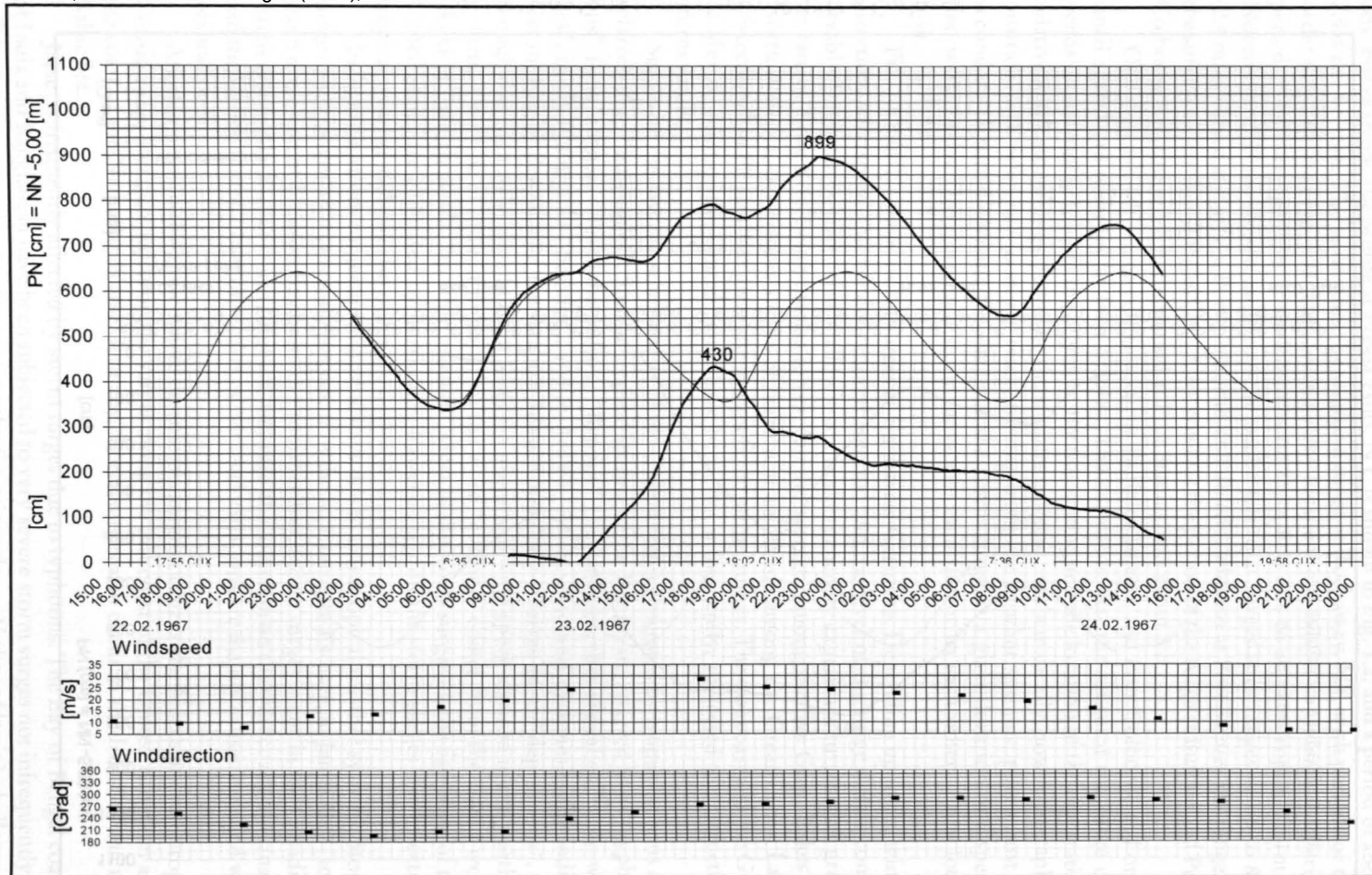


Fig. 1.7: Storm Surge from February 23, 1967 at Cuxhaven

Table 1.1: Some of the most disastrous hurricanes affecting the United States (1900–1979)

Date	Name of hurricane	Area affected	No. of people killed	Damage in millions of dollars
Sept. 8, 1900	–	Storm surge at Galveston greater than 6.5 m	6000	30
Sept. 20, 1909	–	Louisiana coast (Grand Isle)	353	–
Sept. 29, 1915	–	Mississippi Delta (New Orleans)	284	–
Sept. 14, 1919	–	Florida Keys, Corpus Christi (Texas)	600–900	20
Sept. 20, 1926	–	Miami and Pensacola to Southern Alabama	243	–
Sept. 16, 1928	–	Palm Beach, Okeechobee	2000	25
Sept. 1, 1935	Labor Day storm	Florida Keys (winds greater than 332 km · h ⁻¹)	408	76
Sept. 21, 1938	–	New England and Long Island	600	306
Aug. 7–11, 1940	–	South-eastern United States (Georgia to Tennessee)	50	–
Sept. 14–15, 1944	–	Atlantic coast	390	–
Sept. 19, 1947	–	Florida, Louisiana, Mississippi	51	–
Aug. 31, 1954	Carol	North Carolina to New England	60	500
Oct. 13–17, 1954	Hazel	South Carolina to New York	95	–
Aug. 16–20, 1955	Diane	Northeast United States	184	1000
June 27, 1957	Audrey	Texas to Alabama (4-m surge inundated Louisiana 40 km inland)	390	150
Sept. 9–11, 1960	Donna	Florida, New York, New England	50	387
Sept. 7–12, 1961	Carla	Texas	46	408
Sept. 8, 1965	Betsy	Florida, Louisiana, mid-Atlantic States, New England	75	1421
Aug. 15–16, 1969	Camille	Louisiana, Mississippi, Virginia (7.4-m surge on Pass Christian, Mississippi)	>250	1421
Mid-June, 1972	Agnes	Florida, Virginia, Maryland, Pennsylvania, North Carolina to New York	122	2100
Late Aug.–early Sept. 1979	David and Frederic	Alabama, Mississippi, Florida	5	2300

of the water body, together with a large tidal range make storm surges on the low-lying Bay of Bengal coast more dangerous than in any other region of the globe.

It is recognised by now that the storm surge problem is an air-sea interaction problem; i.e. the atmosphere forces the water body, which responds by generating oscillations of the water level with various frequencies and amplitudes. Our present interest is confined to that part of the oscillation between a few minutes and a few days. Study of the storm surge problem will begin with a consideration of the global weather systems.

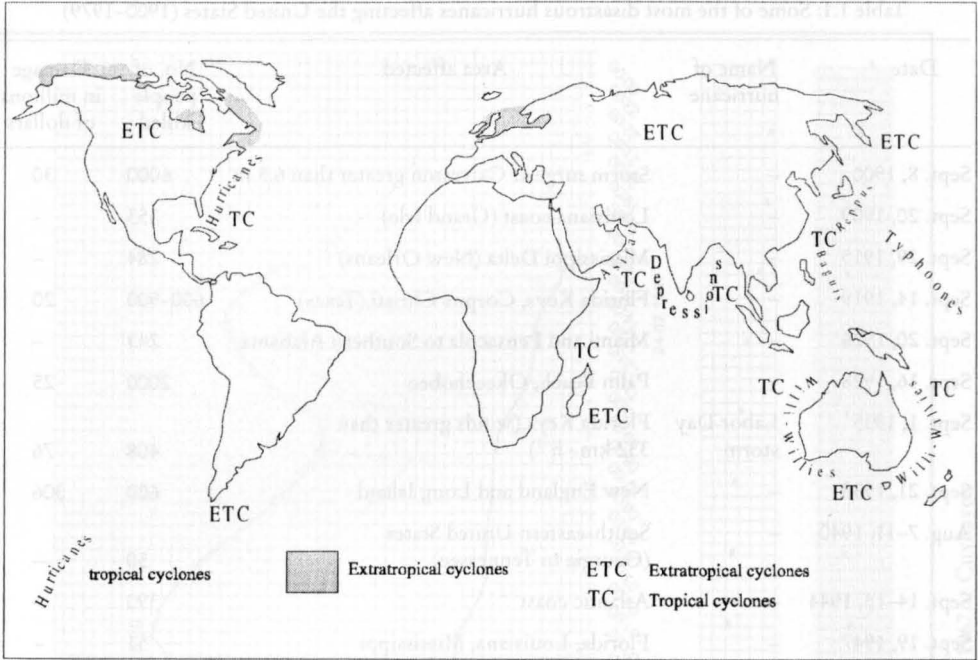


Fig. 1.8: Global Storm Surges due to Tropical Cyclones (TC) and Extratropical Cyclones (ETC)

1.2 Global Weather Systems

In order to understand global weather systems, it is convenient to begin with the so-called “general circulation of the atmosphere,” which refers to the motion of the atmosphere around the globe in an average sense, both in space and time. Before discussing the general circulation, it is appropriate to introduce certain nomenclature. There are two important characteristics of the atmosphere, which can be seen in Fig. 1.9:

- the pressure decrease with height above the earth surface
- the change of temperature with height above the earth surface.

The pressure decreases with height in a monotonic fashion, as can be seen from the ordinate on the right side of Fig. 1.9. The units of pressure are millibars (another internationally used unit is the kilopascal, 1 kPa = 10 mb). On average, the atmospheric pressure at sea level is 1013.2 mb. The height scale (kilometres) is shown on the left hand side of the graph. For general interest, the maximum heights of three mountain peaks, namely, Mount Everest, Mount Blanc, and Ben Nevis, are included. The heights of different cloud types are also indicated.

The second important characteristic is the change of temperature with height, indicated by the curve in Fig. 1.9. Temperature inversions occur several times with increasing height, and this gives rise to three warm and two cold regions. The warm regions are near the earth’s surface, at a height between 40 and 60 km, and above 150 km (i.e. more or less the top of the atmosphere). The first cold region extends from about 10 to 35 km and the second cold region from about 80 to 90 km. The exact distribution of temperature with height depends on latitude and, to a certain extent, on the season.

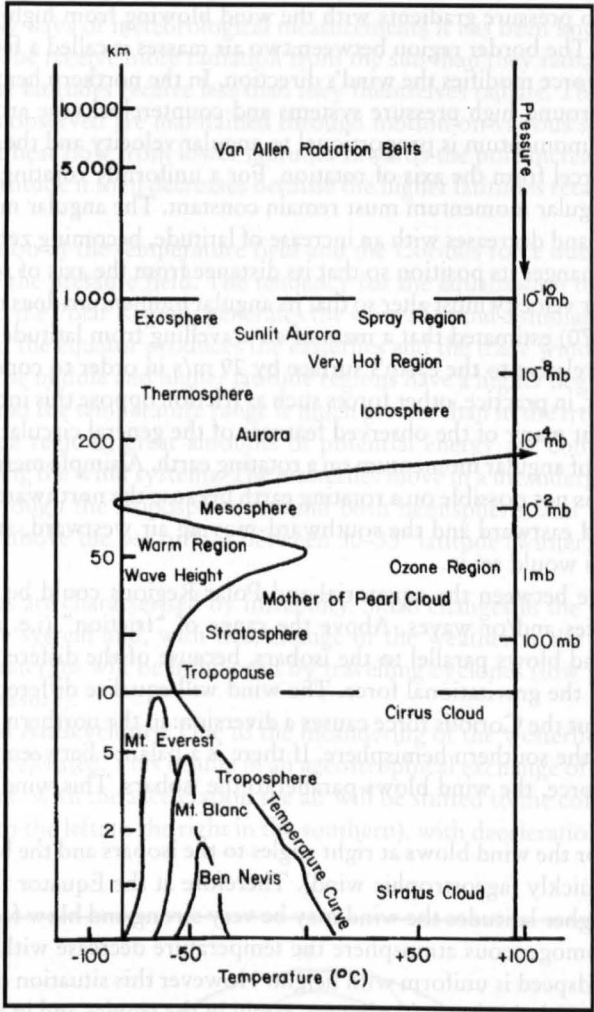


Fig. 1.9: Vertical structure of the atmosphere (DOBSON, 1963)

It can be seen that the temperature decreases from the earth's surface as far as the tropopause. The atmosphere below the tropopause is called the troposphere, and the region immediately above the troposphere is referred to as the stratosphere. The electrical conductivity of air above the 80-km level is much greater than that at lower levels, especially during sun-light hours. This region of the atmosphere, called the ionosphere, allows radio waves to pro-pagate great distances.

The knowledge obtained from the observations of troposphere and stratosphere led to a more definitive theory concerning the general circulation of the atmosphere. The founda-tion among the general circulation is the interdependence of the three-dimensional fields of temperature, pressure and wind (FLOHN, 1971). There are three possible movements of an air mass: 1) vertical, 2) horizontal and 3) partly vertical and partly horizontal. The vertical move-ments means that wind blows at the height from warm to cold regions and near the ground from cold to warm areas, which is thermally induced. The horizontal movement of an air

mass occurs due to pressure gradients with the wind blowing from high pressure area to a low pressure area. The border region between two air masses is called a frontal zone.

The Coriolis force modifies the wind's direction. In the northern hemisphere, the wind blows clockwise around high pressure systems and counterclockwise around areas of low pressure. Angular momentum is proportional to angular velocity and the square of the distance of the air parcel from the axis of rotation. For a uniformly rotating earth and atmosphere, the total angular momentum must remain constant. The angular momentum is greatest at the equator and decreases with an increase of latitude, becoming zero at the poles. If a large mass of air changes its position so that its distance from the axis of rotation also changes, then its angular velocity must alter so that its angular momentum does not change. BARRY and CHORLEY (1970) estimated that a mass of air travelling from latitude 42° to 46° would increase its speed relative to the earth's surface by 29 m/s in order to conserve angular momentum. However, in practice, other forces such as friction oppose this increase, but it is important to note that many of the observed features of the general circulation are due to the poleward transfer of angular momentum on a rotating earth. A simple meridional (i.e. north-south) circulation is not possible on a rotating earth because the northward-moving air mass would be deflected eastward and the southward-moving air westward, and thus zonal (i.e. east-west) motions would set in.

Heat exchange between the equatorial and Polar Regions could be achieved through a system of vortices and/or waves. Above the range of "friction" (i.e. above a height of $>1-2$ km), the wind blows parallel to the isobars, because of the different direction of the Coriolis force and the gravitational force. The wind will equalise differences in pressure at the frontal zone, but the Coriolis force causes a diversion: in the northern hemisphere to the left, to the right in the southern hemisphere. If there is a balance between the gradient force and the Coriolis force, the wind blows parallel to the isobars. This wind is called the geostrophic wind.

At the Equator the wind blows at right angles to the isobars and the balance of pressure is regained very quickly (ageostrophic wind). Therefore at the Equator the winds are very light whereas at higher latitudes the wind may be very strong and blow for a long duration.

In an ideal homogeneous atmosphere the temperature decrease with height is about 10° C/km and the windspeed is uniform with height. However this situation of an ideal air mass never happens in mid-latitudes and only very rarely in the tropics and in the Polar Regions. The horizontal exchange of air is carried out (geostrophically) by travelling weather systems such as cyclones and anticyclones; the ageostrophic wind of the vertical circulation is proportionally much smaller, but cannot be ignored. Furthermore the horizontal component of the movement can either be stable or not unstable. If the horizontal gradient of the wind exceeds a threshold value – which may occur in the frontal zone – the situation of the wind and pressure fields will be changed on a large scale. That will result in the development of new cyclones (low pressure) and anticyclones (high pressure).

In a frontal zone the windspeed is much greater in the upper layers. These strong winds at a height of about 8 to 12 km above sea level are referred to as the Jet stream. There are at least two types of Jet streams, one in the polar front and the other in the subtropics.

For weather and climate purposes, as well as for the atmospheric forcing of storm surges, interest here is primarily in the troposphere and, to a lesser extent, in the lower part of the stratosphere. Earlier, the term "general circulation of the atmosphere" was introduced. In practice, this term is used to describe the more or less permanent wind and pressure systems of the troposphere and the lower stratosphere. To explain the dynamics of the climate system, initially we will omit orographical effects (FLOHN, 1971, BARRY and CHORLEY, 1992)

Since the early days of meteorological measurements it has been known that the tropical areas of the globe receive more radiation from the sun than they radiate back into space, whereas the higher latitudes receive less than they themselves radiate. The average temperature distributions observed are maintained through motion on various scales in the atmosphere. The rate of heat flow from lower latitudes towards the pole increases from the equator to about 35° latitude it then decreases because the higher latitudes retain some of this imported heat.

The distribution of the temperature field and the Coriolis force due to earth's rotation largely determine the pressure field. The tendency for the equalisation of pressure between the subtropics and the Polar Regions generates the westerlies and a similar tendency between the subtropics and the equator produces the easterlies and the trade winds.

Westerlies: The middle and higher latitude regions have a higher degree of baroclinicity than the tropics, and the temperature range is much greater than in the tropics. In the middle and higher latitude regions, great amounts of potential energy are converted into kinetic energy, thus creating the wind systems. The westerlies move in a meandering path (Fig. 1.10). They meander through the troposphere around both hemispheres and reach their highest speed at 9–11 km above the sea surface between 30 – 35° latitude (winter) and in summer at 40 – 45° latitude.

The westerlies are characterised by instability. Small changes in the Jet stream result in disturbance to the system and, with this, change of the weather at the earth's surface. At the surface the westerlies will be influenced by travelling cyclones (low pressure) and anticyclones (high pressure).

Cyclones and Anticyclones: Due to the meandering of the westerlies the wind is both accelerated and decelerated. This results in an ageostrophical exchange of air mass perpendicular to the isobars. With the acceleration the air will be shifted to the cold side (in the northern hemisphere to the left; to the right in the southern), with deceleration on the warm side

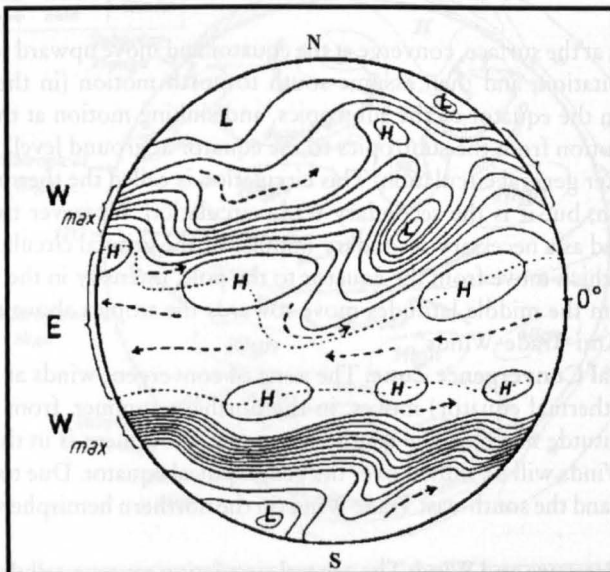


Fig. 1.10: Schematic representation of general circulation (4–10 km; line = isobars; winds = broken line; trade = dotted line) (FLOHN, 1971)

(in the northern to the right; to the left in the southern). This results in cells of low and high pressure: cyclones and anticyclones.

Due to the Coriolis force, the cyclones move with their winds rotating around them in an anticlockwise sense in the Northern Hemisphere.

Secondary Trade Circulation: The subtropical high pressure cells at 30° latitude north and south indicate a drop in pressure from the subtropics to the equator, which is due to the ageostrophical east wind, the Trade Winds (Fig. 1.11). This Trade Wind may reach a level of 10 km above the sea surface and also have an effect at ground level. Frictional effects mean that the wind at the surface moves to the southeast in the northern hemisphere/northeast in the southern hemisphere.

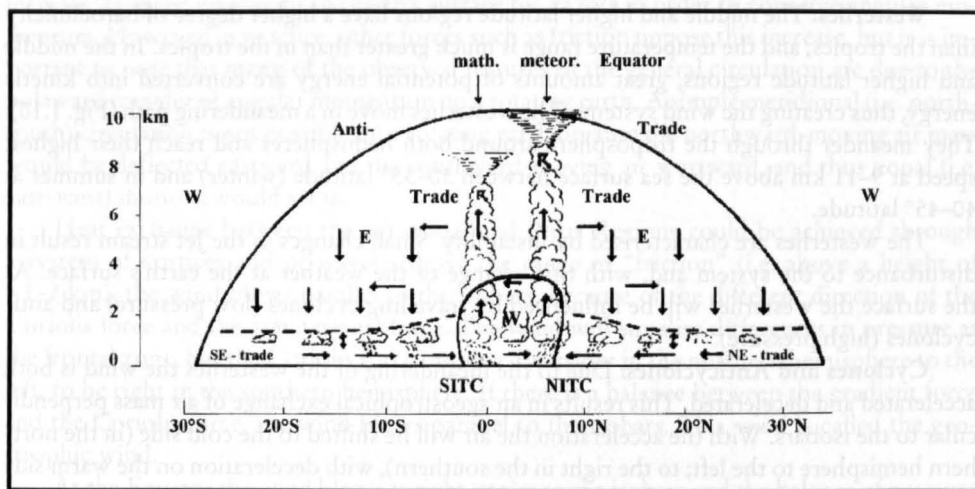


Fig. 1.11: Trade winds with ITCZ and equatorial westerlies (FLOHN, 1971)

These winds, at the surface, converge at the equator and move upward to the tropopause, producing precipitation, and then assume south to north motion (in the northern hemisphere) aloft from the equator to the subtropics, and sinking motion at the subtropics and south to north motion from the subtropics to the equator at ground level, referred to as the thermal motor after general circulation. This circulation is called the thermal motor of the general circulation, but it is the secondary trade circulation. However the thermic motor must be considered as a necessary secondary impulse of the general circulation.

The winds, which move from the equator to the pole, intensify in the westerlies. When the westerlies from the middle latitudes move towards the tropics above the Trade Winds, they are called "Anti-Trade-Winds".

Inter-Tropical Convergence Zone: The zone of convergent winds at ground level and lowest pressure (thermal equator) moves, in the northern summer, from the geographical equator to 20° latitude north, in the southern summer, movement is in the opposite direction. The Trade Winds will be shifted over the geographical equator. Due to this the pressure situation changes and the south-east Trade Wind (in the northern hemisphere) becomes equatorial westerlies.

Patterns of Pressure and Wind: The general circulation causes a cellular pattern of pressure and wind at the surface (level of 0–2 km). This structure changes with the season, because of the inclination of the earth and, with this, the changing solar radiation.

It must be considered that the “only true zonal distribution of pressure exists in the region of the subpolar low in the southern hemisphere where the ocean is continuous. To a lesser extent, the equatorial low is zonal. At other latitudes, particularly in the northern Hemisphere, where the bulk of the land exists, large seasonal temperature differences disrupt the idealised zonal patterns.” (LUTGENS and TARBUCK, 1986).

The sea level pressure distribution for the month of July (representative of summer in the northern hemisphere) and January (representative of winter) is shown in Fig. 12. It can be seen that the observed pressure regimes are cellular. The high pressure centres are over the eastern side of the Atlantic and Pacific oceans (this affects the west coast climates of adjacent continents), north and south of the equator, South Indian Ocean, Arctic Ocean, and Antarctica. Occasionally, names are given to these centres. For example the one over the eastern Pacific is called the “Hawaiian High” and the one over the eastern Atlantic is called the “Azores High”. The low pressure centres are the “Iceland Low” (over the North Atlantic), the “Aleutian Low” (over the North Pacific), and one each over the South Atlantic, South Pacific and Indian oceans in a shifting zone along the equator, and one in the Southern Ocean near Antarctica. The two semipermanent cells, the Iceland Low and the Aleutian Low “represent the great number of cyclonic storms that migrate eastward across the globe and converge in these areas.” (LUTGENS and TARBUCK, 1986).

With reference to Fig. 1.13, the following remarks may be made. Pressure is higher and the gradients are steeper in the winter hemisphere (i.e. the hemisphere that has winter at that time), and the pressure centres shift northward in July and southward in January (TREWARTHA, 1968). The pressure belts in the subtropics are more or less continuous in the winter hemisphere, whereas in the summer hemisphere, the heated continents break the continuity. Between the subtropical high and the subpolar lows lies the main zone of travelling

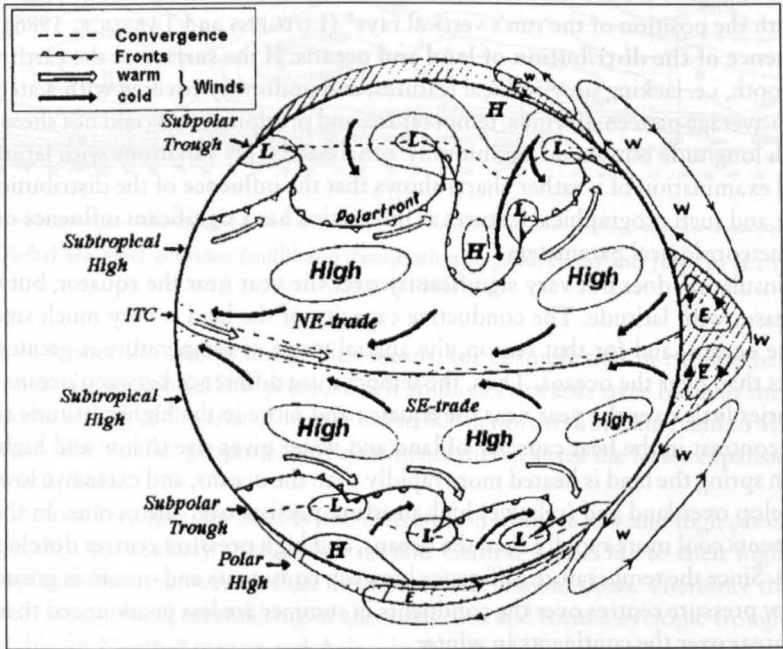


Fig. 1.12: Schematic representation of atmospheric circulation between 0–2 km height and vertical circulation to 15 km height (FLOHN, 1971)

Table 1.2: Planetary Pressure and vertical Wind Belts

Pressure belt	latitude	Wind belt (0-3 km)	Wind belt (> 3 km)	
Polar High	80-90°	Polar Easterlies (0-3 km)	westerlies 18-30 km; during winter more than 50 km	Sinking air dominates, with evaporation of clouds and dryness.
Subpolar Trough	55-65°	extratropical (mid-latitude) westerlies		Cyclonic disturbance with clouds and precipitation moving from west to east.
Subtropical High Pressure Area	25-30°	Tropical Easterlies (Trade; 0-10 km) Tropical		Sinking air dominates, with evaporation of clouds and dryness.
Equatorial Trough	0-10°	Easterlies and equatorial westerlies		Cyclonic disturbance with clouds and precipitation moving from west to east.

cyclones and anticyclones (westerlies). The high and low pressure areas are called centres of action, because their strength over a given period (e.g. week, month or season) as compared with long term averages, is an indication of the departure of the weather from its average.

“Relatively little pressure variation occurs from midsummer to midwinter in the southern hemisphere, a fact we attribute to the dominance of water in that hemisphere. The most noticeable changes here are the seasonal 5- to 10 degree shifts of the subtropical highs that moves with the position of the sun’s vertical rays” (LUTGENS and TARBUCK, 1986).

Influence of the distribution of land and oceans: If the surface of the earth were perfectly smooth, i.e. lacking orographical features, and uniformly covered with water, then the long-term average pattern of winds, temperature, and precipitation would not show any variation with longitude but would exhibit only zonal bands (i.e. variations with latitude only). A general examination of weather charts shows that the influence of the distribution of land and water and such orographical features as mountains has a significant influence on the patterns of meteorological parameters.

The insulation does not vary significantly over the year near the equator, but the variation increases with latitude. The conductive capacity of the land is very much smaller than that of the oceans, and for that reason, the annual range of temperature is greater over the continents than over the oceans. Thus, the temperature difference between oceans and continents varies little over the year near the equator and more in the higher latitude regions.

This contrast in the heat capacity of land and water gives rise to low and high pressure centres. In spring the land is heated more rapidly than the oceans, and extensive low pressure areas develop over land and (relative) high pressure persists over the oceans. In the autumn the continents cool more rapidly than the oceans, and high pressure centres develop over the land areas. Since the temperature difference between continents and oceans is greater in winter, the low pressure centres over the continents in summer are less pronounced than the high pressure areas over the continents in winter.

The different heat capacity of land and water results in the following significant consequences: in summer the planetary low pressure belts will be taken over the continents and

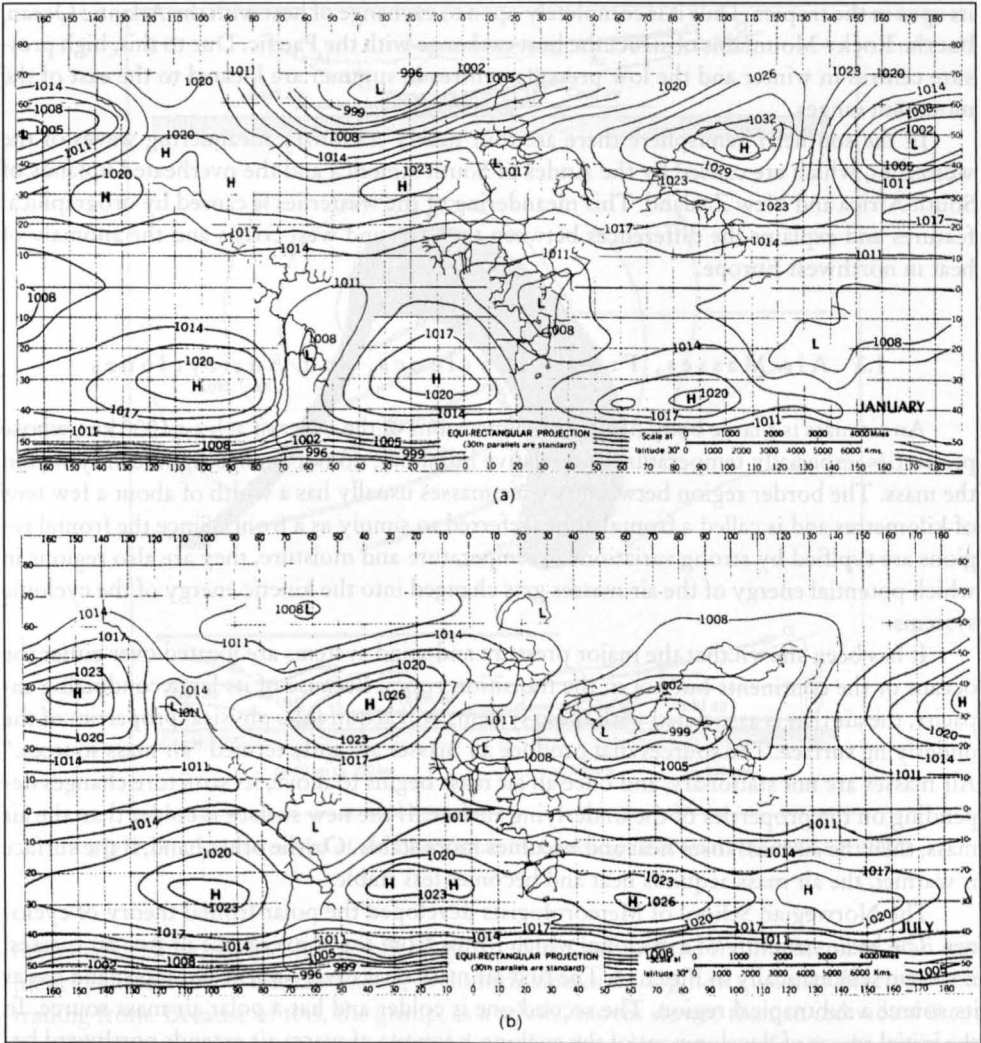


Fig. 1.13: Global sea-level pressure (millibars) distribution in January (a) and July (b) (LUTGENS and TARBUCK, 1986)

reinforced, in winter the anticyclones. This means, for example that in the northern hemisphere summer the equatorial low pressure belt shifts northwards over India to the 30° latitude and an expanding of the area of west wind to 60° in northern summer and to 40° in southern summer. The smaller proportion of continents there causes the lesser expansion in the southern hemisphere.

Large mountain ranges can modify the distribution of these low and high pressure centres considerably, particularly the Cordilleras and Central Asia. Due to their high heating area these uplands become warmer than the atmosphere around them. Therefore the mountains cause an anticyclonal meandering of the westerlies and form a cyclonic trough in their lee. Due to this, in North America and Asia – in the lee of the mountains of Central Asia – there is a high trough with cold air on the eastern side and warm air on the western side (FLOHN, 1971). North America may be considered as a triangle with its base in the Arctic and

its apex in the tropics. Thus it is completely open to exchange of heat with the Atlantic Ocean, but the Rocky Mountains obstruct the heat exchange with the Pacific. Due to this, high pressure centres in winter and the low pressure centres in summer are located to the east of the mountain ranges.

In the southern hemisphere there are four nearly stationary meandering waves of the westerlies, which are caused by the Andes of South America and the overheated uplands of South Africa and New Zealand. This meandering of the westerlies is caused by orographical features and explains the differences between the east- and west coasts and the anomaly of heat in northwest Europe.

1.3 Air Masses, Fronts, Cyclones, and Anticyclones

An air mass is a large body of air with dimensions of the order of at least 1000 km, whose properties, especially temperature and relative humidity, do not change significantly within the mass. The border region between two air masses usually has a width of about a few tens of kilometres and is called a frontal zone (referred to simply as a front). Since the frontal regions are typified by strong variations in temperature and moisture, they are also regions in which potential energy of the air masses gets changed into the kinetic energy of the cyclonic systems.

It has been shown that the major pressure and wind systems are located over either the oceans or the continents but not in the transition zones. Because of its large conducting capacity, the air that is associated with these systems will acquire the physical properties of the underlying surface. The sources that produce air masses are aptly termed "air mass sources." Air masses are not stationary, and once an air mass begins to move, its structure changes depending on the properties of the underlying surface. If the new surface is colder than the air mass, then the air mass loses heat and becomes more stable. On the other hand, if the surface is warmer, the air mass acquires heat and becomes less stable.

The Norwegian School of Meteorologists developed the polar frontal theory of cyclones. The basic structure of a cyclone, which forms from the convergence of two air masses, is shown schematically in Fig. 1.14. The first air mass is relatively warm and moist and has as its source a subtropical region. The second one is colder and has a polar air mass source. In the initial stages of development of the cyclone, a tongue of warm air extends northward between these two air masses. The narrow region separating the air masses is the front and is referred to as the polar front, since it represents the southern edge of the polar air mass.

A warm front is one along which cold air is displaced by warm air, and a cold front is one in which the reverse is true; a stationary front is one that does not move.

In the frontal theory of cyclones, the initial stage is characterised by a quasi-stationary front separating a warm and a cold air mass. The next stage involves the development of wave motion on the front, with the subsequent development of a low pressure center. At this stage of cyclogenesis, the cyclone is referred to as nascent. In the next stage, the cold front overtakes the warm front, and this process is called occlusion. With the progress of the occlusion process, the warm air is lifted to higher levels and becomes replaced at the lower levels by colder and heavier air. Because of this, the center of gravity of the air mass is lowered, and large amounts of potential energy are released. This potential energy is converted into kinetic energy of the wind systems that surround the cyclone center.

PETTERSEN (1969) stated that an extratropical cyclone is usually accompanied by three or four similar cyclones to form a series, or a family. The first member of this family is an

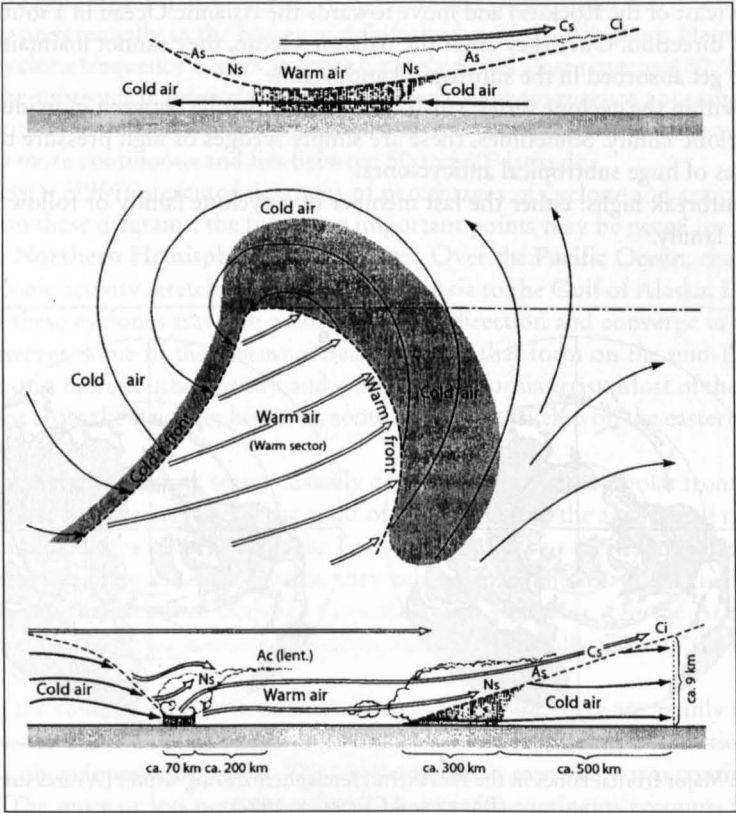


Fig. 1.14: Cyclone model of the Norwegian Meteorological School (WARNECKE, 1997)

occluded cyclone, the second member is partly occluded, and the trailing member is an incipient cyclone wave. While the leading cyclone dissipates slowly, new cyclones develop on the trailing front. Because of this, the group, as a whole, moves slower than an individual member. While the first cyclone is in the higher latitudes, the subsequent cyclones take more southerly paths, and in the rear of the frontal member, cold air moves southward into the subtropics. This phenomenon is called a polar outbreak and will lead to the development of an arctic cyclone. At times, on the surface weather charts, it is difficult to recognise a coherent cyclone family. This is especially true in North America because of the influence of the Rockies. Coherent cyclone families, with three to six members, travel eastward over the northern oceans with a period of 3–8 d.

Anticyclones, as the name implies, are opposite to cyclones, i.e. they are centers of high pressure. Their intensities are lower than those of cyclones, they exhibit a more irregular behaviour than cyclones, as a rule, they move slower. PETERSSEN (1969) gave the following classification for anticyclones.

- (1) Subtropical highs: vast, elongated, and deep (in height) anticyclones located in the subtropics. These are highly persistent, are either stationary or slowly moving, and can be seen on practically any weather chart.
- (2) Polar continental highs: anticyclones that develop predominantly over northern continents during winter. In North America, they develop mainly in Alaska and western

Canada (east of the Rockies) and move towards the Atlantic Ocean in a southeasterly to easterly direction. Once they enter the Atlantic Ocean, they cannot maintain their identity and get absorbed in the subtropical anticyclone.

- (3) Highs within the cyclone series: small anticyclones that lie between individual members of a cyclone family. Sometimes, these are simply wedges of high pressure that travel at the edges of huge subtropical anticyclones.
- (4) Polar-outbreak highs: either the last member of a cyclone family or follow any intense cyclone family.

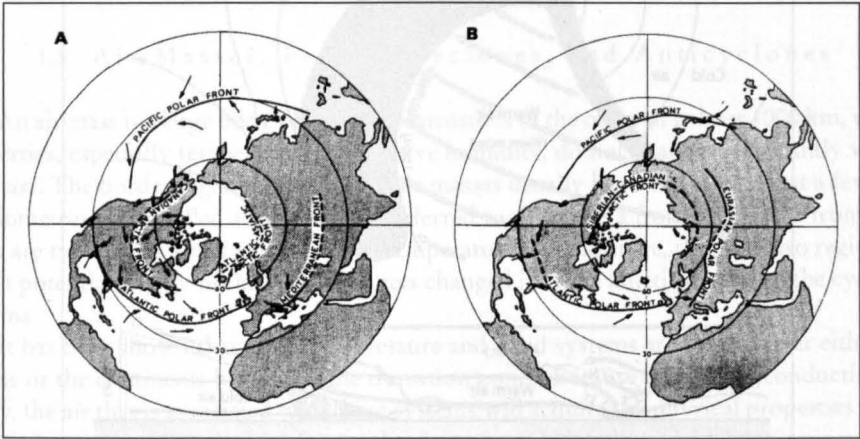


Fig. 1.15: Major frontal zones in the Northern Hemisphere during winter (A) and summer (B) (BARRY and CHORLEY, 1992)

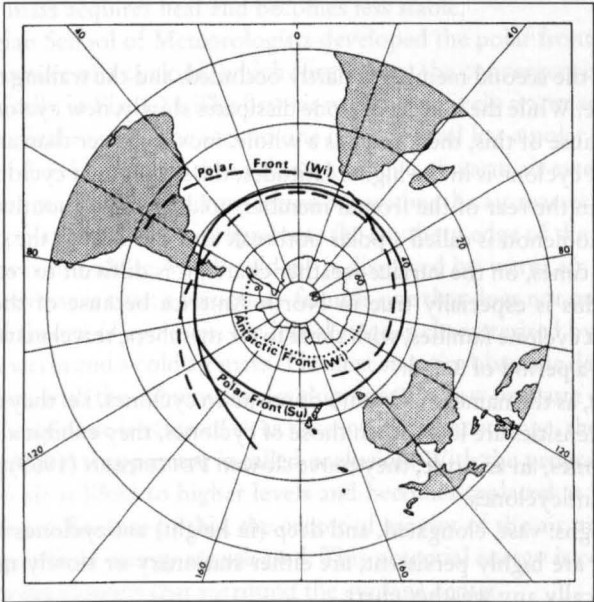


Fig. 1.16: Major frontal zones in the Southern Hemisphere during summer (Su) and winter (Wi) (BARRY and CHORLEY, 1992)

Next, the **geographical distribution** of cyclones and anticyclones will be discussed. Cyclones occur preferentially in the higher middle latitudes. In the Northern Hemisphere, the maximum cyclone frequency occurs at approximately 60°N in summer and 50°N in winter. Note that the subtropical anticyclones and the equatorial convergence zone also have a similar 10° latitude seasonal shift. In the Southern Hemisphere, the belt of maximum cyclone frequency is more continuous and lies between 50 and 60° latitude.

PETTERSEN (1969) presented diagrams of percentages of cyclone and anticyclone centers. Based on these diagrams, the following important points may be noted for cyclone activity in the **Northern Hemisphere** during winter. Over the **Pacific Ocean**, there is a wide zone of cyclonic activity stretching from Southeast Asia to the Gulf of Alaska. During winter, most of these cyclones travel in a northeastward direction and converge in the Gulf of Alaska. However, some of the storms, especially those that form on the mid-Pacific polar front, travel on a more southerly track and reach the California coast. Most of the Pacific cyclones cannot cross the Rockies; however, some of them redevelop on the eastern side of the Rockies.

Over the **Atlantic Ocean**, storms usually develop on the Atlantic polar front (Fig. 1.15). One of the most favoured regions is the coast of Virginia and to the area east of the southern Appalachians. These are referred to as the East Coast Storms or the Cape Hatteras Storms, and while moving along the Gulf Stream, they achieve great intensity, and finally they become stagnant near Iceland or between Greenland and Labrador. On the Atlantic-Arctic front, many cyclones either form or redevelop, and they generally move in the direction of the Barents Sea.

During the summer period for the Northern Hemisphere, there are mainly two belts of high frequencies of storm occurrence. The northern belt surrounding the Arctic is irregular and consists of cyclones with fronts. The southerly belt is over the warm continents of the subtropics. The more or less permanent heat low over the continents accounts for the high frequencies found over southern California, Nevada, Arizona, and northern Mexico. At the higher levels, there is an anticyclone with strong subsidence, and because of this, clouds and weather systems are absent in the second belt.

The principal tracks of the depressions in the Northern Hemisphere for the winter period are shown in Fig. 1.17. Note that these tracks basically reflect the influence of the major frontal zones.

Next, the geographical distribution of the anticyclones in the Northern Hemisphere will be briefly discussed. There is a belt over the oceans with a maximum occurrence frequency off the subtropical west coast. In the eastern North Pacific, strong frequencies occur. Regarding the distribution of the anticyclonic centres in the Northern Hemisphere during summer, note that the belt of subtropical anticyclones is now farther north than in winter. The occurrence frequency is again significant in the eastern Pacific but is low in the western Pacific because of the summer monsoon.

Earlier, a front was defined as a sloping zone of transition between two air masses of different density. Although a front is several kilometres wide, it is narrow compared with the horizontal dimensions of the air masses. On weather charts, fronts appear as lines of discontinuity in wind and temperature. At the front, there is a kink in the isobars (i.e. lines of equal pressure) directed from low to high pressures.

Next, the **principal frontal zones on the globe** will be identified. Although fronts are not usually stationary, certain regions nevertheless consistently show high frequency of fronts, these regions being the areas of confluence between the main air mass sources discussed earlier. Fig. 1.17 shows the major frontal zones in the Northern Hemisphere during

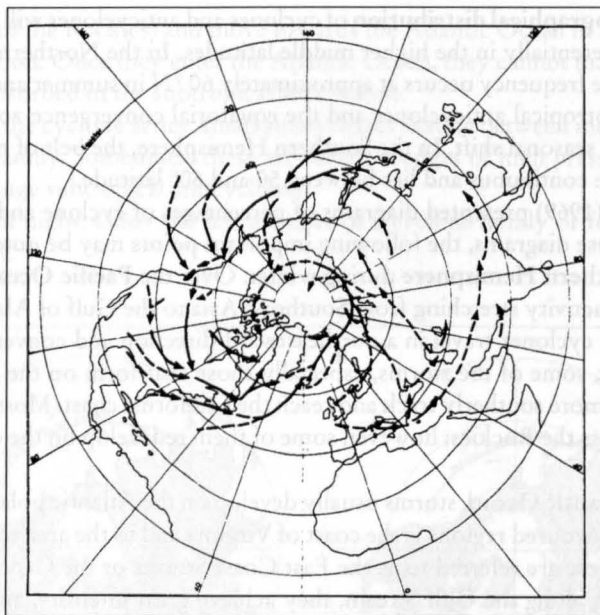


Fig. 1.17: Principal Northern Hemisphere depression tracks in January. Tracks represented by broken lines are less certain than those represented by solid lines (KLEIN, 1957)

winter. In the Atlantic Ocean region, one has the Atlantic polar front, which is the confluence region between the polar continental and the tropical maritime air mass sources, and the opposing currents indicated maintain the front. Quite often, the Atlantic polar front extends eastward over Europe. Its position varies quite drastically in the meridional direction; i.e. it can be anywhere from the West Indies to Portugal in the south to the Great Lakes and Iceland in the north (PETTERSEN, 1969). This frontal zone is responsible for the cyclones that bring precipitation over a wide belt from the eastern part of the North American continent to northwest Europe.

In the southern hemisphere the Polar Front has more cyclonic activity in summer than the northern hemisphere in its summer. The Polar Front is located in January about 45°S with branches spiralling poleward towards eastern South America and from 30°S in the South Pacific (150°W) (Fig. 1.16). In winter of the southern hemisphere there are two Frontal zones spiralling towards Antarctica from about 20° (BARRY and CHORLEY, 1992).

A second important frontal zone is formed by the Atlantic-Arctic fronts, which are in the confluence region between the arctic source region and the polar maritime air. The storms that form on this frontal zone usually travel from Iceland along the northern part of Norway to the Barents Sea. A third important frontal zone is the Mediterranean front, which forms at the confluence of the cold air from Europe and the mild air from North Africa and Mediterranean Sea area. The cyclones that develop here usually travel in northeasterly direction to southern parts of central Asia. However, some travel eastward to northwest India.

Over the North Pacific Ocean, there are usually two polar fronts, the one nearest the Arctic coast being the more pronounced. Most of the North Pacific storms form along this frontal zone and travel towards the Gulf of Alaska, but some of them take a southerly route to California and northern Mexico. The Pacific-Arctic front usually extends towards the Great Lakes, and many of the storms between the Great Lakes and the Rockies develop on

this front. Cold air from the Arctic may reach as far south as Texas, or even northern Mexico, in the rear of these storms.

A second weak polar front is found in winter in the southern hemisphere at 65° – 70° S. Zones of airstream confluence in the southern hemisphere are less numerous and more persistent, particularly in coastal regions, than in the northern hemisphere.

The frontal zone distribution during the summer period for the Northern Hemisphere is shown in Fig. 1.15. Since, in summer, the differences in the properties of the various air masses are not as pronounced as in winter, one can find permanent frontal zones only in the Arctic region. The polar fronts over the western Atlantic and Pacific are usually 10° farther north in summer as compared with their winter positions. There is now a frontal zone over Eurasia and over the middle part of North America. These new zones reflect the prevailing meridional temperature gradient and the large scale orographical influences. The Arctic front, in summer, is formed along the Arctic coasts of Siberia and North America and is associated with the snow (and ice) boundaries of the higher latitudes.

1.4 Regional Weather System

In this section, the regional weather systems of North America, South America, Europe, Africa, Asia, Australia, and the ocean region will be briefly considered. The detailed meteorological problems associated with storm surges will be considered in Chapter 5.

1.4.1 Weather Systems of North America

The climate of North America is determined by its location in the Northern Hemisphere and its great range from 9° N (Isthmus of Panama) to 71° N (Point Barrow) and to 84° N if the Arctic Archipelago is included. Furthermore it is influenced by its great Landmass with its greatest breadth (4250 km along 40° N) in the temperate zone, the long meridional barrier of the Western Cordilleras, the cold Hudson Bay in the North and the warm Gulf of Mexico from the south, the surrounding oceans and their currents with the warm Gulf Stream, cold Labrador Current, the warm Alaska Current and the cool California Current. The region, where the currents meet – for example the region of Newfoundland where the Gulf stream meets the Labrador Current – its one of cyclogenesis and fog formation.

The atmospheric circulation develops from the interaction of the stationary Hawaiian, Azores, Arctic and Greenland Highs and of the Aleutian and Icelandic Lows, which are semipermanent, are seasonable and variable in intensity (MARTYN, 1992).

During both winter and summer, the mean pressure field at the midtropospheric level shows a prominent trough over the eastern part of North America. The origin of this can be traced to the influence of the Rockies on the upper westerlies, but in winter, the strongly baroclinic zone along the east coast of North America is also responsible. Over the midwestern states, cyclones generally move in a southeast direction, bringing continental polar air southward, whereas along the Atlantic coast the cyclones travel northeastward. If the upper air trough is far to the west of its average position, then depressions form ahead of it over the South Central States (PETTERSEN, 1969) and move in a north-easterly direction towards the lower St. Lawrence.

Considering January as a typical month for the winter period, the surface pressure chart shows an extension of the subtropical high over the southwest part of the United States (this

high being referred to as the "Great Basin High") and a polar anticyclone over the Mackenzie River area. On both the Atlantic and Pacific coasts, the pressure is low because of the Icelandic and Aleutian lows. Because of heating over the land, the Icelandic low is split and a secondary low appears over the northeastern part of Canada. The cyclone frequency is maximum on the Pacific coast and in the Great Lakes area during winter, whereas in the Great Plains, the maximum frequency is in spring and early summer. On the average, in the month of December, the Gulf of Alaska has the maximum frequency of lows and the Great Basin region has the maximum frequency of highs, as compared with any other region in the Northern Hemisphere.

In winter, there are three main depression tracks across North America

- (1) Depressions from the west move eastward between 45 and 50° N.
- (2) Some depressions first travel southeastward as far as the Central States and then travel northeastward towards New England and the Gulf of St. Lawrence. Depressions developing over the Pacific cross the western mountains as upper troughs and redevelop in the lee of the mountains in Alberta and Colorado.
- (3) Depressions form on the polar front off the east coast of the United States and move northeastward towards Newfoundland.

In the summer period, the frequency of depressions originating in the east coast is less, and the tracks of depressions from the west are somewhat northward as compared with their winter positions. The tracks pass over Hudson Bay, Ungava Bay, Labrador, or the Gulf of St. Lawrence. The maritime frontal zone that gives rise to these depressions is not pronounced.

In early April, the Aleutian low (which is located approximately at 55° N, 165° W during September to March) splits into two; one centre is over the Gulf of Alaska and the other is over northern Manchuria. Cyclogenesis increases in Alberta and Colorado. By the end of June, the subtropical high pressure cells in the Northern Hemisphere are displaced northward, and because of this, the depression tracks also move northward.

The essential features of the sea level circulation in the eastern and central parts of the United States and Canada can be determined from sea level pressure maps. However, due to the presence of mountains and rugged orographical features in the west, sea level pressure gradients do not accurately reflect the wind distribution. Because of the presence of high coastal mountains, the Aleutian low pressure system does not extend far inland. HAURWITZ AUSTIN (1944) stated that because the inland pressures are reduced to sea level, they appear quite high compared with those over the surrounding ocean, and this sea level correction gives rise to steep fictitious pressure gradients in northern British Columbia and southern Alaska. Due to the presence of several fjords and the banking effect produced by the coastal mountains, the average surface winds do not agree with the mean isobaric pattern.

1.4.2 Weather Systems of Mexico and Central America

Central America includes the continental strip joining North to South America (between 18 and 8° N) and the West Indies, a string of islands from Florida (25° N) to Venezuela (10° N) separating the Caribbean Sea from the Atlantic (MARTYN, 1992).

The main mountain range in Central America is the Sierra Madre in Mexico. This region generally lies between the subtropical belt of high pressure and the equatorial belt of low pressure, whose boundary changes with the ITCZ. The Hawaiian High and the Azores in-

fluence it. The prevailing winds are trade wind (easterly) and the migratory low pressure centers generally move from east to west. Thus, these secondary circulations are significantly different from those of middle and high latitudes.

Central America is exposed to tropical cyclones, which spring up from June to November over the Gulf of Mexico, the Caribbean Sea and in the vicinity of the Bahamas and over the tropical part of eastern Pacific. These affect the coast of Central America, and all the way to Newfoundland (MARTYN, 1992). The number varies from 1 (1890) to 21 (1933) a year (DUNN AND MILLER, 1960).

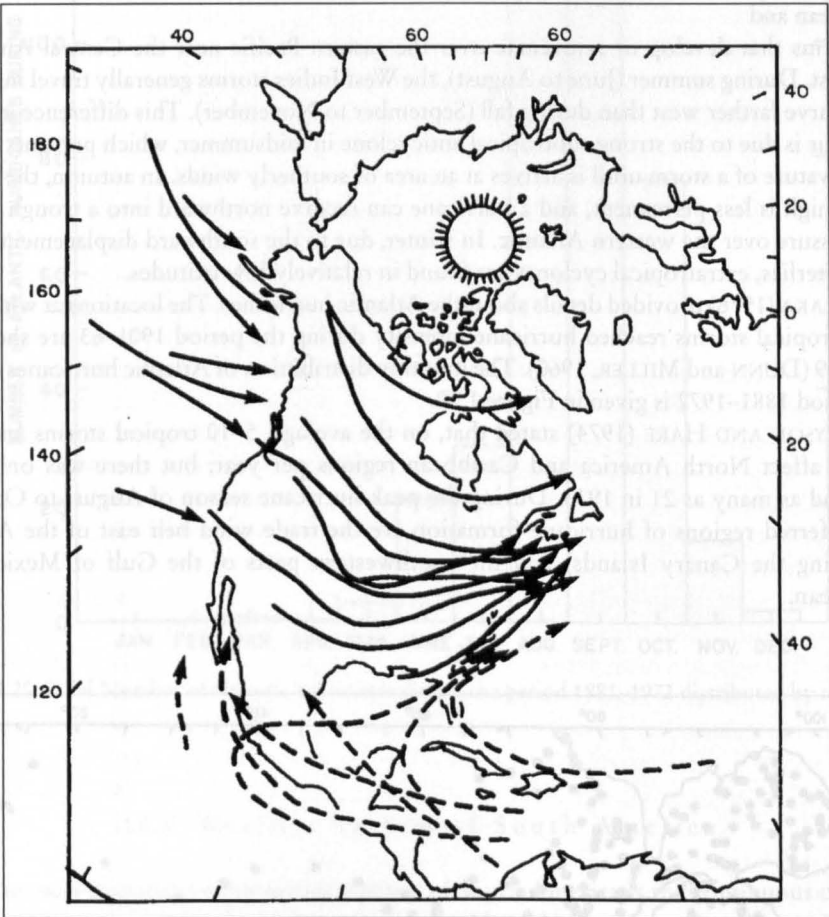


Fig. 1.18: Cyclone tracks of North and Central America. Solid lines represent extratropical cyclones and broken lines represent tropical cyclones. (HAURWITZ and AUSTIN, 1944)

The tracks of the hurricanes are shown in Fig. 1.18. The following is a summary of the average conditions associated with these tracks in Mexico and Central America:

- (a) The Antillean hurricanes recurve in the eastern part of the Gulf of Mexico, and the hurricane season is August to October. During August, the recurvature occurs farther north than during October.

- (b) A frequently observed track is over the Caribbean Sea, the Yucatan Peninsula, and then over the northeast coast of Mexico or along the coast of Texas.
- (c) Occasionally, the hurricanes, after crossing the Yucatan Peninsula, travel over Central Mexico and arrive at the Pacific coast and then travel northwestward.
- (d) Similar to across Central America, and then the track is towards the north-west, parallel to the Pacific coast and passing over the Gulf of California.
- (e) These storms develop over the southeast Pacific and travel towards the Gulf of Mexico. Some tropical cyclones also form south of the Revillagigedo Islands.

Thus, two main classes of cyclones can be noted:

- (1) hurricanes that develop over the warm waters of the Caribbean Sea and the Atlantic Ocean and
- (2) storms that develop or rejuvenate over the eastern Pacific near the Central American coast. During summer (June to August), the West Indies storms generally travel inland or recurve farther west than during fall (September to November). This difference in behaviour is due to the strong subtropical anticyclone in midsummer, which prevents the recurvature of a storm until it arrives at an area of southerly winds. In autumn, the Atlantic high is less permanent, and a hurricane can recurve northward into a trough of low pressure over the western Atlantic. In winter, due to the southward displacement of the westerlies, extratropical cyclones are found in relatively low latitudes.

ALAKA (1976) provided details about the Atlantic hurricanes. The locations at which Atlantic tropical storms reached hurricane intensity during the period 1901–63 are shown in Fig. 1.19 (DUNN and MILLER, 1960). The monthly distribution of Atlantic hurricanes during the period 1881–1972 is given in Figure 1.20.

BRYSON AND HARE (1974) stated that, on the average, 5–10 tropical storms and hurricanes affect North America and Caribbean regions per year; but there was only 1 in 1914 and as many as 21 in 1933. During the peak hurricane season of August to October, the preferred regions of hurricane formation are the trade wind belt east of the Antilles (including the Canary Islands) and the southwestern parts of the Gulf of Mexico and Caribbean.

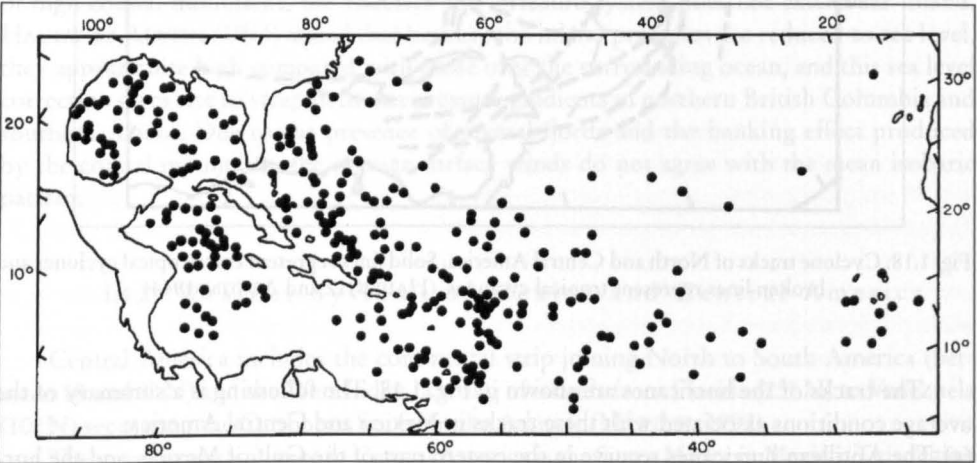


Fig. 1.19: Locations at which Atlantic tropical storms reached hurricane intensity during the period 1901–63. (DUNN and MILLER, 1960)

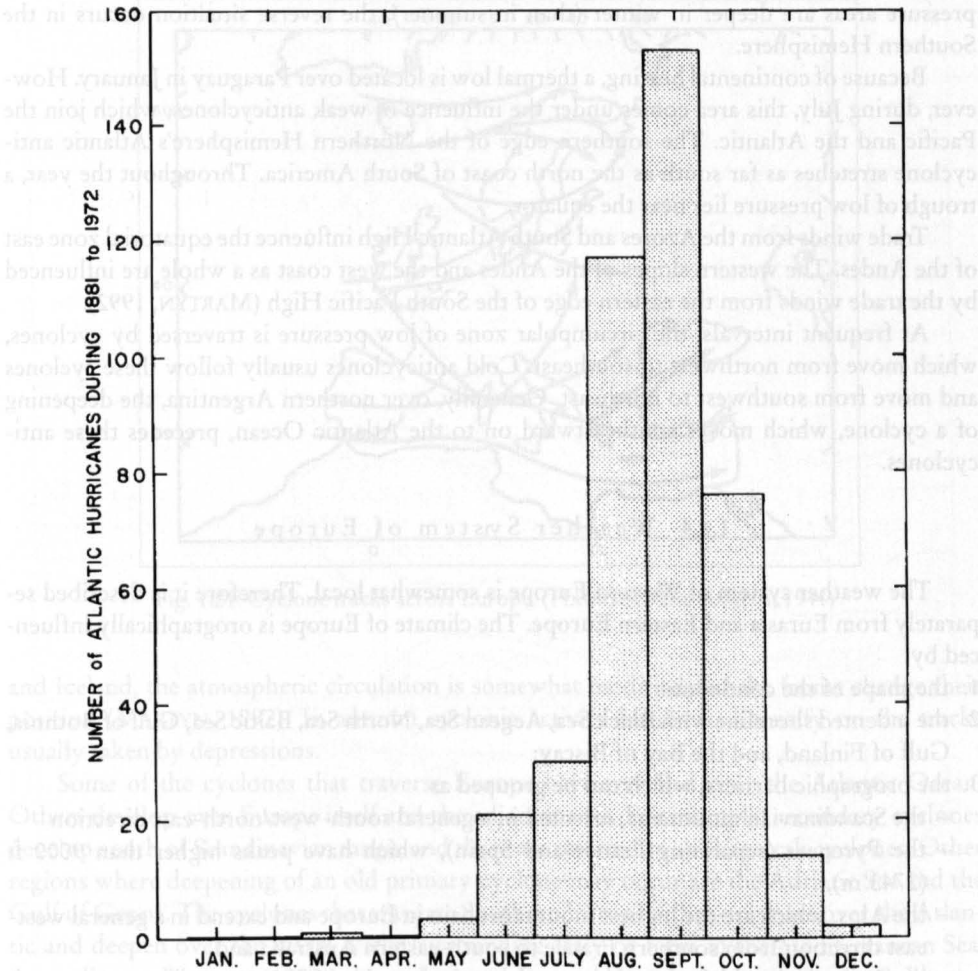


Fig. 1.20: Total Number of Atlantic hurricanes during the period 1881–1972 distributed by month

1.4.3 Weather System of South America

The most important orographical feature of South America is the continuous chain of high mountains, known as the Andes, which extend from Venezuela to Cape Horn. Another topographical feature is that South America does not have prominent coastal indentations (such as Hudson Bay, Gulf of St. Lawrence, and Gulf of Mexico in North America) or large inland lakes.

A more or less persistent feature is the presence of two semipermanent anticyclones, one over the Atlantic and the other over the Pacific, near the east and west coasts, respectively. The southern end of South America is affected by the zone of polar front depressions, which in July reach as far north as 35–45°S (MARTYN, 1992). South of Cape Horn, there are deep semipermanent cyclones of the Weddel and Belgique seas. One main difference between the Northern and Southern hemispheres is that, whereas in the Northern Hemisphere the low

pressure areas are deeper in winter (than in summer), the reverse situation occurs in the Southern Hemisphere.

Because of continental heating, a thermal low is located over Paraguay in January. However, during July, this area comes under the influence of weak anticyclones, which join the Pacific and the Atlantic. The southern edge of the Northern Hemisphere's Atlantic anticyclone stretches as far south as the north coast of South America. Throughout the year, a trough of low pressure lies near the equator.

Trade winds from the Azores and South Atlantic High influence the equatorial zone east of the Andes. The western slopes of the Andes and the west coast as a whole are influenced by the trade winds from the eastern edge of the South Pacific High (MARTYN, 1992).

At frequent intervals, the circumpolar zone of low pressure is traversed by cyclones, which move from northwest to southeast. Cold anticyclones usually follow these cyclones and move from southwest to northeast. Generally, over northern Argentina, the deepening of a cyclone, which moves southeastward on to the Atlantic Ocean, precedes these anticyclones.

1.4.4 Weather System of Europe

The weather system of Western Europe is somewhat local. Therefore it is described separately from Eurasia and Eastern Europe. The climate of Europe is orographically influenced by

1. the shape of the continent;
2. the indented shoreline with Black Sea, Aegean Sea, North Sea, Baltic Sea, Gulf of Bothnia, Gulf of Finland, and the Bay of Biscay;
3. the orographic barriers, which can be grouped as
 - the Scandinavian mountains, oriented in a general south-west/north-east direction
 - the Pyrenees (separating France and Spain), which have peaks higher than 9000 ft (2743 m),
 - the Alps, which are the highest mountain chain in Europe and extend in a general west-east direction from southern France to south-eastern Australia and
 - the Apennines, which extend almost the entire length of Italy;
4. the huge continental mass to the east and
5. the extensive ocean to the west.

MARTYN (1992) summarised that the climate of Europe is influenced by the permanent Icelandic Low stationed over the North Atlantic and the Azores High. While the Icelandic Low is deeper in winter, the Azores High reinforces in summer. The seasonal Asian High influences Europe in winter. Summer is characterised by the presence of the Arctic High in the Spitzbergen region and the South Asian Low. This pressure system gives rise to prevailing south-westerlies over northern, western and central Europe, and north-westerlies and westerlies in southern Europe (MARTYN, 1992). The westerly airstream changes in easterly or northeasterly, when high pressure develops over eastern or northeastern Europe.

In winter, the cyclones that travel across North America, or those that develop on the Atlantic Front, travel south of Iceland in a general northeasterly direction towards Norway. The latitudinal variation of cyclones that approach the west coast of Europe for the different seasons of the year is listed in Table 1.3. The cyclone tracks across Europe are shown in Fig. 1.21. This difference in frequency is more pronounced in summer than in winter.

„In summer, when the Azores High becomes stronger and extend in a ridge across western Europe, the Iceland Low weakens and the Arctic High lies across eastern Greenland

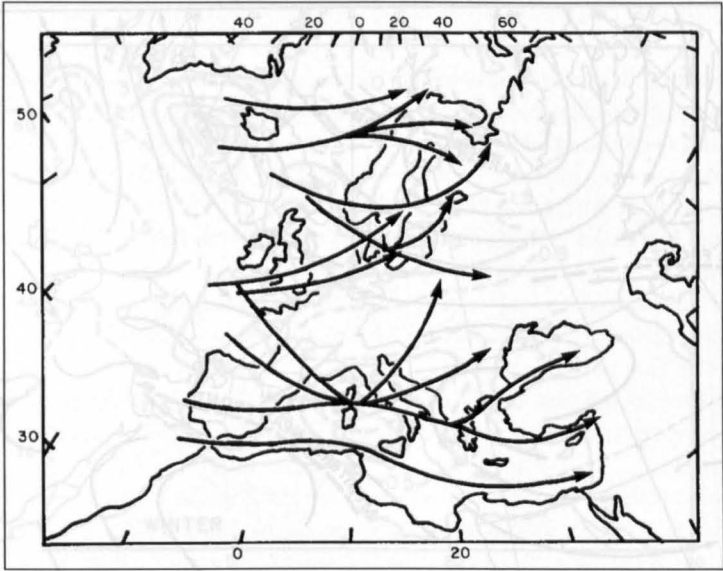


Fig. 1.21: Cyclone tracks across Europe. (HAURWITZ and AUSTIN, 1944)

and Iceland, the atmospheric circulation is somewhat modified and the fronts change their position (MARTYN, 1992). In autumn cyclonic activity begins to intensify on the tracks usually taken by depressions.

Some of the cyclones that traverse Europe have travelled over the Atlantic Ocean. Others develop over Europe itself and the adjacent seas. For example, secondary cyclones develop south of Scandinavian range, and these are referred to as Skagerrak cyclones. Other regions where deepening of an old primary cyclone may occur are the Adriatic Sea and the Gulf of Genoa. The cyclones that traverse Southern Europe either originate over the Atlantic and deepen over the warm water surrounding Italy or form in the Mediterranean Sea. According to WALLÉN (1970), the cyclones of Europe have duration of usually 8 d but at times up to 17 d. Fig. 1.23 shows the frequency of cyclones in winter and summer for Europe.

Table1.3: Cyclone frequency (% of the total annual occurrence) at 15° W longitude (Atlantic Ocean). (HAURWITZ and AUSTIN, 1944).

Latitude	Winter	Spring	Summer	Autumn	Year
30–35 °N	1.7	2.0	0.4	2.0	6.1
35–40 °N	3.0	3.9	1.1	3.8	11.8
40–45 °N	3.3	4.2	2.3	3.1	12.9
45–50 °N	2.1	3.0	3.7	2.7	11.5
50–55 °N	2.3	3.7	4.5	2.4	12.9
55–60 °N	3.0	4.5	6.0	4.1	17.6
60–65 °N	3.2	5.1	5.0	5.4	18.7
65–70 °N	1.9	2.1	2.2	2.3	8.5
30–70 °N	20.5	28.5	25.2	25.8	100.0

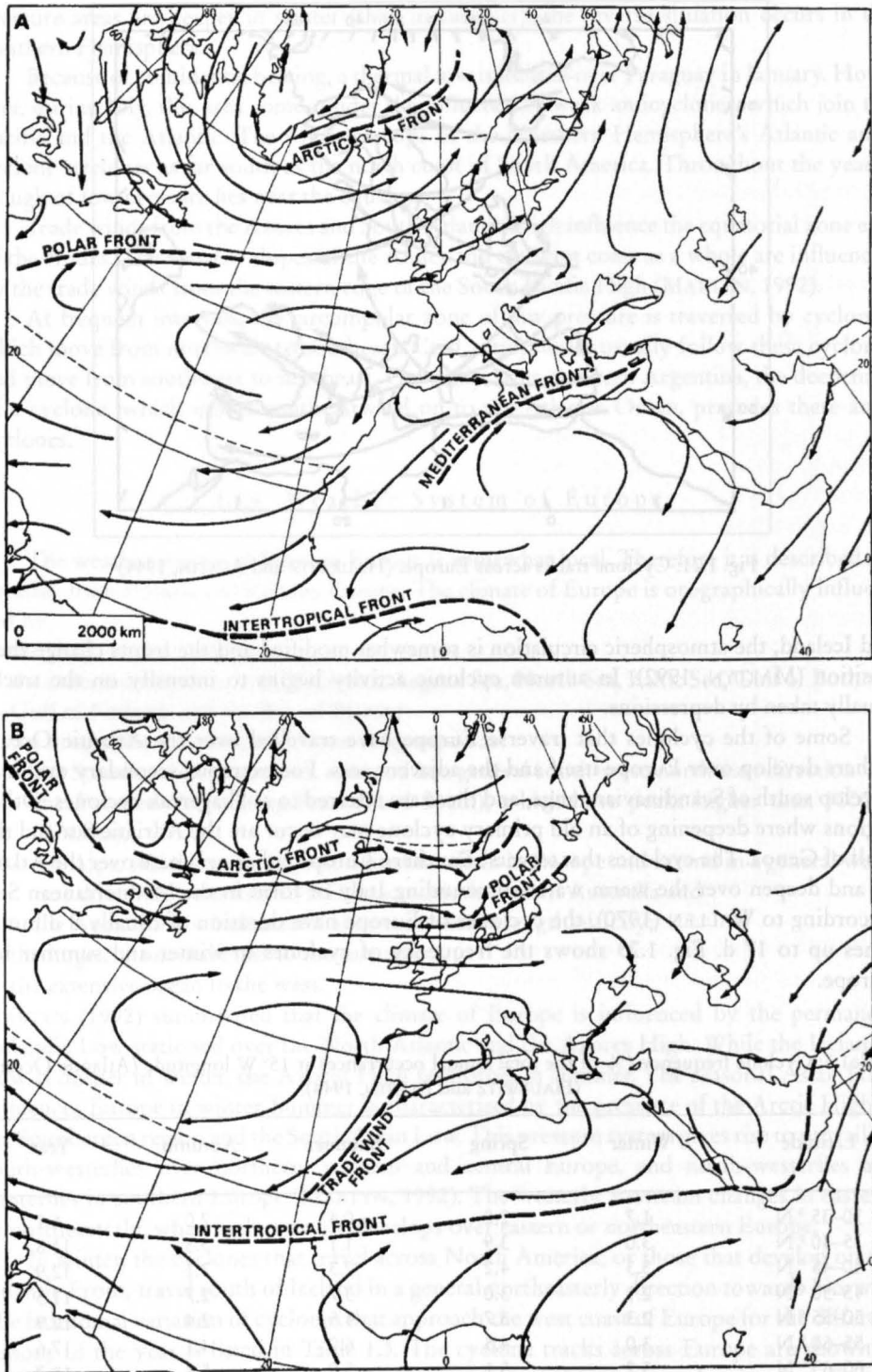


Fig. 1.22: Prevailing wind directions and atmospheric fronts over Europe and the North Atlantic. January (A) July (B) (MARTYN, 1992)

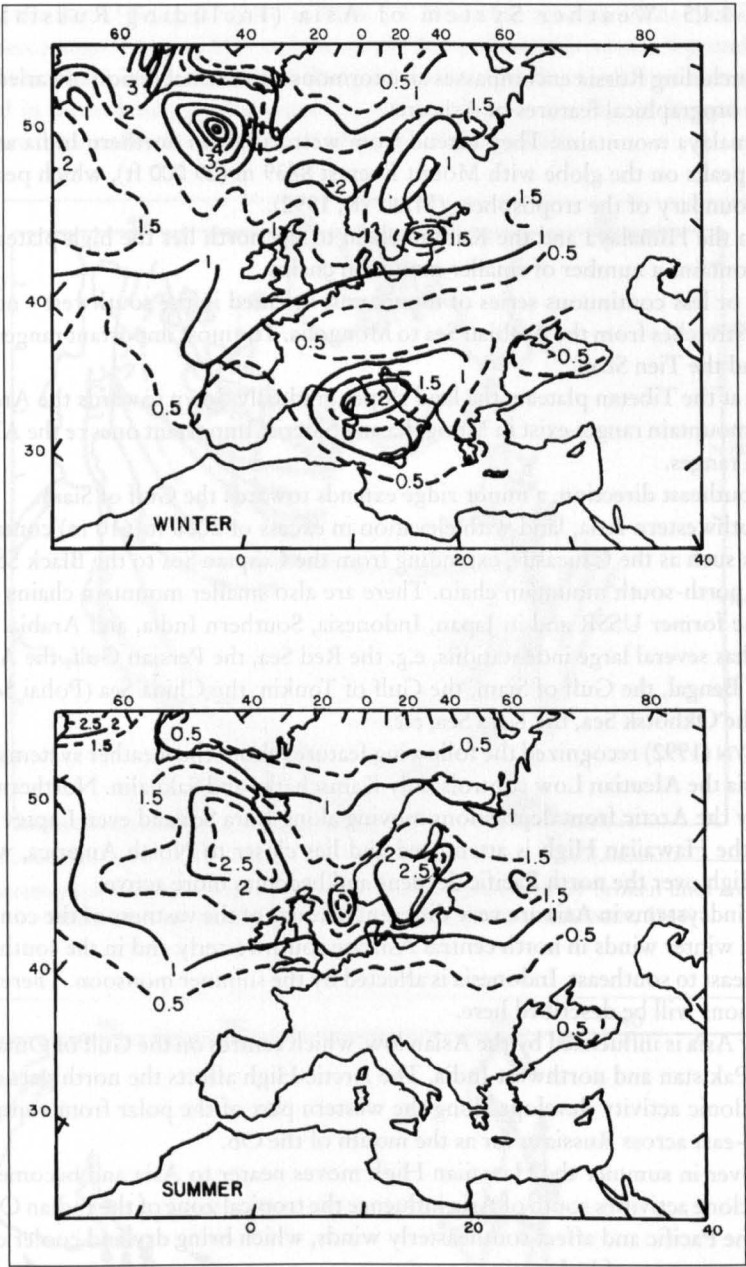


Fig. 1.23: Average Frequency of cyclones with central pressure less than 1000 MB during a winter season (top) and a summer season (bottom) (HAURWITZ and AUSTIN, 1944)

1.4.5 Weather System of Asia (Including Russia)

Asia including Russia encompasses an enormous continental region of varied relief. The important orographical features of Asia are:

1. The Himalaya mountains: They extend from west to east in northern India and have the highest peaks on the globe with Mount Everest 8839 m (29 000 ft), which penetrates the upper boundary of the troposphere (MARTYN, 1992).
2. Between the Himalaya and the Kunlun chain to the north lies the high plateau of Tibet, which contains a number of smaller mountain chains.
3. A more or less continuous series of mountains, oriented in the southwest - northeast direction, stretches from the Arabian Sea to Mongolia. The most important ranges are Hindu Kush and the Tien Shan.
4. Starting at the Tibetan plateau, the land slopes gradually down towards the Arctic Ocean. Several mountain ranges exist in Mongolia and Siberia. Important ones are the Altai and Yablonova ranges.
5. In the southeast direction, a minor ridge extends towards the Gulf of Siam.

In southwestern Asia, land with elevation in excess of 2000 ft (610 m) contains mountain ranges such as the Caucasus, extending from the Caspian Sea to the Black Sea. The Urals form a north-south mountain chain. There are also smaller mountain chains on the east coast of the former USSR and in Japan, Indonesia, Southern India, and Arabia. The Asian continent has several large indentations, e.g. the Red Sea, the Persian Gulf, the Arabian Sea, the Bay of Bengal, the Gulf of Siam, the Gulf of Tonkin, the China Sea (Pohai Sea), the Sea of Japan, the Okhotsk Sea, the Kara Sea, etc.

MARTYN (1992) recognized the following features about the weather systems in Asia. In Eastern Asia the Aleutian Low controls only Kamchatka and Sakhalin. Northern Asia is influenced by the Arctic front depressions moving along Kara Sea and even Laptev Sea coasts. In winter the Hawaiian High is attenuated and lies closer to North America, whereas the Aleutian High over the north Pacific deepens and becomes more active.

The windsystems in Asia are very different because of the vastness of the continent. For example, in winter winds in north central Asia are southwesterly and in the south they blow from northeast to southeast. Indonesia is affected by the summer monsoon. Therefore not all wind directions will be described here.

In July Asia is influenced by the Asian low, which centres on the Gulf of Oman, the Persian Gulf, Pakistan and northwest India. The Arctic High affects the north part of the continent. Cyclonic activity develops along the western part of the polar front running southwest-north-east across Russia as far as the mouth of the Ob.

Moreover in summer the Hawaiian High moves nearer to Asia and becomes stronger. The anticyclone activities south of Asia influence the tropical zone of the Indian Ocean, Australia and the Pacific and affect southeasterly winds, which bring dry and cooler continental tropical air over parts of Indonesia.

South-east and east Asia, the coasts of the Seas of Okhotsk and Japan, the Amur, Sakhalin and Kamchatka regions, the Philippines and Indonesia are dominated by a monsoon circulation. In winter the wind blows opposite its direction in summer. Then cyclonic activities increase rapidly over very warm seas and oceans and, though the affected area is limited, it is extremely violent and can be disastrous owing to the exceptional heights of waves, and the torrential rain (tropical cyclones known as typhoons).

The tracks of extratropical and tropical cyclones across Asia are shown in Fig. 1.24 and 1.25, respectively. The approximate percentage distribution of tropical cyclones in the Ara-

bian Sea and the Bay of Bengal is given in Table 1.4. Note that whereas in the Arabian Sea the maximum percentage is during May to June, in the Bay of Bengal it is from September to October. Later the Arabian Sea and Bay of Bengal cyclones and the resulting storm surges will be discussed in more detail. Special attention will be given to the Bay of Bengal surges because they are responsible for almost half of the lives lost globally.

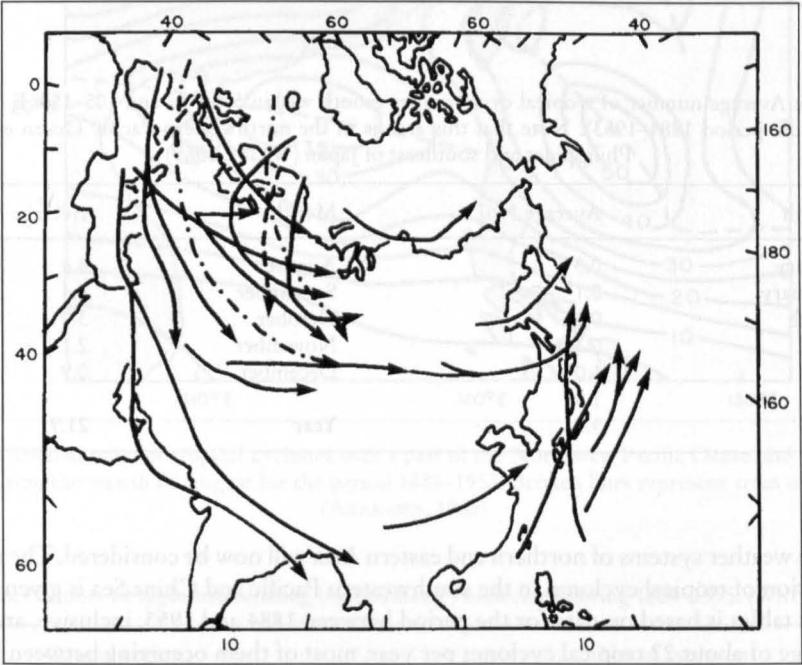


Fig. 1.24: Extratropical cyclone tracks across Asia. Tracks represented by broken lines are less certain than those represented by solid lines. (HAURWITZ and AUSTIN, 1944)

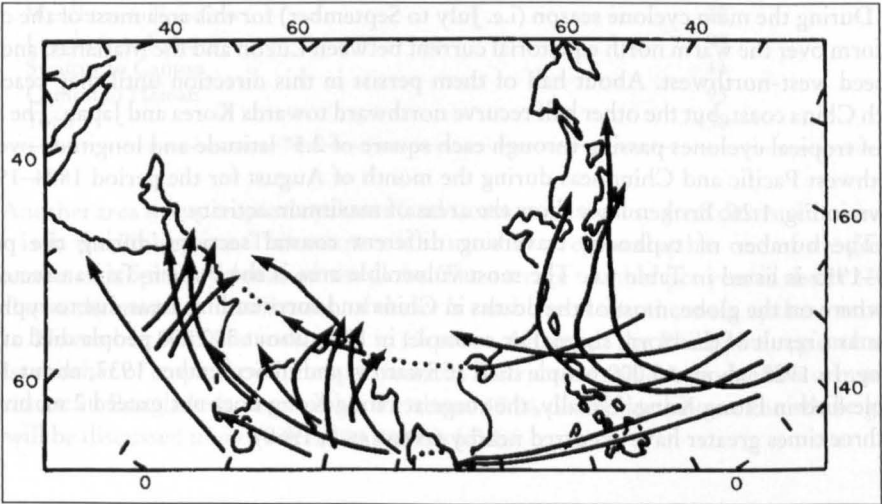


Fig. 1.25: Tropical cyclone tracks across Asia. (HAURWITZ and AUSTIN, 1944)

Table 1.4: Bimonthly distribution (approximate %) of tropical cyclones in the Arabian Sea and the Bay of Bengal (HAURWITZ and AUSTIN, 1944)

Water body	Jan.–Feb.	Mar.–Apr.	May–June	July–Aug.	Sept.–Oct.	Nov.–Dec.
Arabian Sea	1	11	50	1	11	26
Bay of Bengal	1	2	17	29	34	17

Table 1.5: Average number of tropical cyclones per month within 5–30° N and 105–150° E (based on data for the period 1884–1953). Note that this area is in the northwestern Pacific Ocean east of the Philippines and southeast of Japan (WATTS, 1969)

Month	Average No.	Month	Average No.
January	0.3	August	4.4
February	0.1	September	4.4
March	0.1	October	3.0
April	0.3	November	2.1
May	1.0	December	0.9
June	1.5		
July	3.8	Year	21.9

The weather systems of northern and eastern Asia will now be considered. The monthly distribution of tropical cyclones in the southwestern Pacific and China Sea is given in Table 1.5. This tables is based on data for the period between 1884 and 1953, inclusive, and shows an average of about 22 tropical cyclones per year, most of them occurring between July and October (ARAKAWA, 1969). During July to September, tropical cyclones frequently travel over the coasts of China and Korea; however, the southern parts of China experience them sometimes as early as May and as late as mid-November. Between mid-November and April, tropical cyclones rarely traverse the mainland of China.

During the main cyclone season (i.e. July to September) for this area most of the cyclones form over the warm north equatorial current between Luzon and the Marianas, and they proceed west-northwest. About half of them persist in this direction until they reach the South China coast, but the other half recurve northward towards Korea and Japan. The number of tropical cyclones passing through each square of 2.5° latitude and longitude over the Northwest Pacific and China seas during the month of August for the period 1884–1953 is shown in Fig. 1.26. Broken lines show the areas of maximum activity.

The number of typhoons traversing different coastal sections during the period 1884–1955 is listed in Table 1.6. The most vulnerable area is the Fukien-Taiwan sector. As elsewhere on the globe, most of the deaths in China and surrounding areas due to typhoons occur as a result of the storm surge. For example, in 1881, about 300 000 people died at Haiphong. In 1922, about 60 000 people died at Swatow, and in September 1937, about 11 000 people died in Hong Kong. Usually, the surge at Hong Kong does not exceed 2 m, but surges three times greater have occurred nearby (ARAKAWA, 1969).

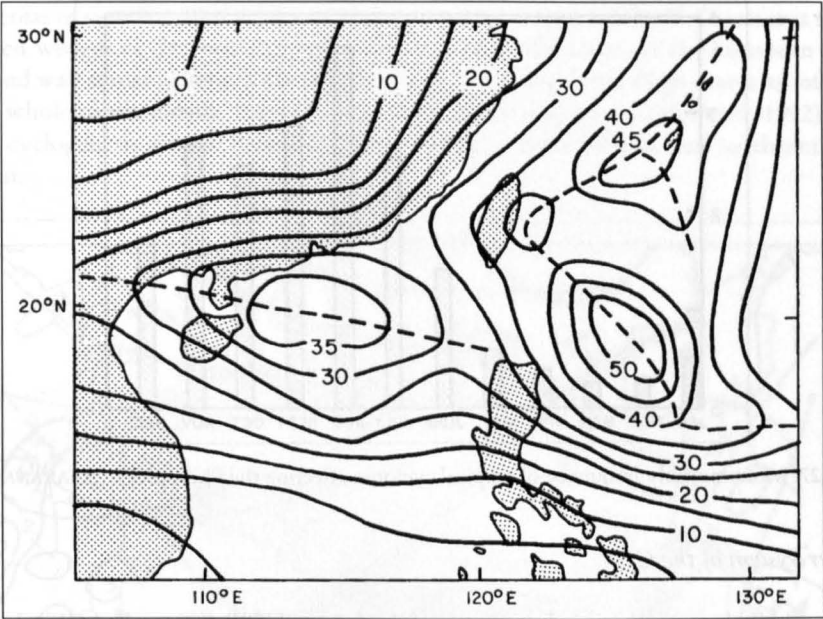


Fig. 1.26: Total number of tropical cyclones over a part of the Northwest Pacific Ocean and the Sea of China during the month of August for the period 1884–1953. Broken lines represent areas of maxima. (ARAKAWA, 1969)

Table 1.6: Number of typhoons crossing the Southeast Asian coast during 1884–1955. (WATTS, 1969)

Coastal region	No. of typhoons
Korea and further east	87
Liaoning to Shantung Peninsula	39
Shantung Peninsula to Shanghai	22
Shanghai to Wenchow	34
Wenchow to Foochow	30
Foochow to Swatow	90
Swatow to Canton	43
Canton to Hainan	93
Total	438

Another area where tropical cyclones (and storm surges) cause great destruction and loss of life is in the Philippines. This country is situated in a region that has one of the greatest frequencies of tropical cyclones on the globe. The average number per year is about 22. Fig. 1.27 shows the monthly distribution of these. It can be seen that the main cyclone season is July to November, with the maximum in October. Although the Philippine region has the highest number of tropical cyclones per year, the destruction and deaths due to storm surges are greatest in Bangladesh, responsible for about 40 % of the deaths over the whole globe. This will be discussed in more detail in section 6.3.1.

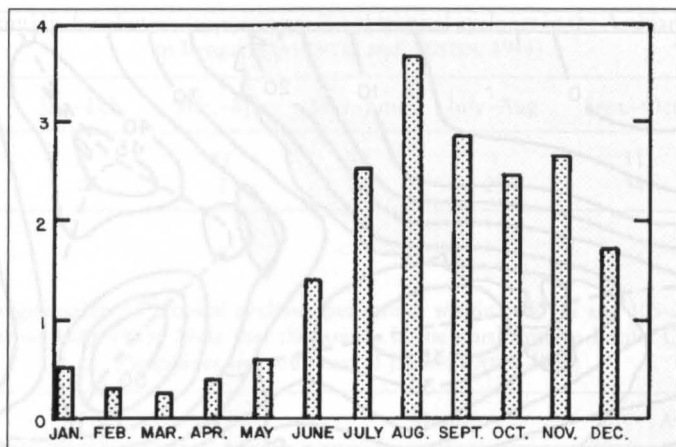


Fig. 1.27: Mean monthly frequency of tropical cyclones affecting the Philippines. (ARAKAWA, 1969)

Weather System of the CIS

Considered next is the weather system of the former USSR (now called CIS). LYDOLPH (1977) mentioned that during winter, the strong dominance of a high pressure cell over Eurasia causes the majority of fronts and cyclone tracks to be located along the edges of the land mass. In winter, the polar front generally lies south of the former CIS. This front has two branches: the western branch lies in the Mediterranean – Asia Minor – Middle East area, and an eastern segment lies off the coast of China and across Japan, stretching into the Aleutians. Many cyclones that affect the weather over the CIS develop on the western segment. The cyclones forming in the eastern Mediterranean usually move northeastward across the Black Sea, the Caucasus, Ukraine, the lower Volga, and western Siberia. Cyclones developing in the Middle East travel into Soviet Central Asia. Cyclones forming along the eastern branch of the polar front in winter travel north of the CIS.

Thus, many of the cyclones affecting the CIS in winter either originate in the Icelandic low area or in the Mediterranean Sea. The Barents Sea also acts as a region of cyclogenesis and redevelopment. The Black Sea and the Caspian Sea also act as areas of cyclogenesis during winter. Other areas of cyclogenesis are western Siberia, the Baltic Sea, and southern Finland. In the Far East, cyclogenesis occurs over the northern part of the Okhotsk Sea (sea level pressures as low as 970 mb occur). However, in the Far East, most of the cyclogenesis occurs over Japan and the Sea of Japan. These cyclones affect southern portions of the Kamchatka Peninsula, Sakhalin Island, and Kuril Islands.

In winter, one of the stormiest areas in the CIS is the Ob Estuary region where cyclones travelling from the west along the Arctic coast meet those from the southwest travelling along the Black and Caspian seas. During spring, the center of maximum cyclone frequency shifts eastward from the Barents Sea to the Ob Gulf. In summer, the location of maximum cyclone frequency shifts southeastward into central Siberia south of the Taymyr Peninsula. In summer, the frequency of cyclones over the Black and Caspian seas diminishes considerably. In the Far East, the Aleutian low becomes weak, and the Amur Valley becomes a region of strong cyclogenesis.

Generally speaking, cyclones are more evenly distributed across the CIS landmass in summer. In winter, most of the cyclones affecting the former CIS originate outside the coun-

try, whereas in summer, most of the cyclogenesis occurs in the CIS itself. Summer is the season when wedges of the Azores High can stretch over the centre of the European former USSR and way across as far as Lake Baykal. In the north the Arctic High exerts its influence, but the whole south, mostly Turestan, is covered by the Asian Low (MARTYN, 1992). Areas of high cyclogenesis are the Amur Valley, the Urals, western Siberia, and northcentral Kazakhstan.

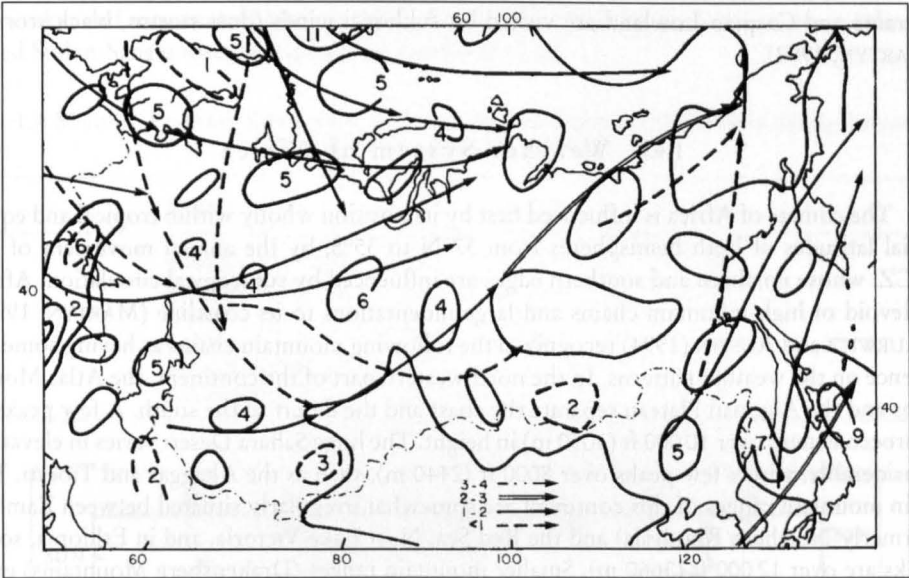


Fig. 1.28: Total number of cyclones during a 20-yr-period over the Soviet Union during the month of January. The principal tracks of cyclones are also shown. (LYDOLPH, 1977)

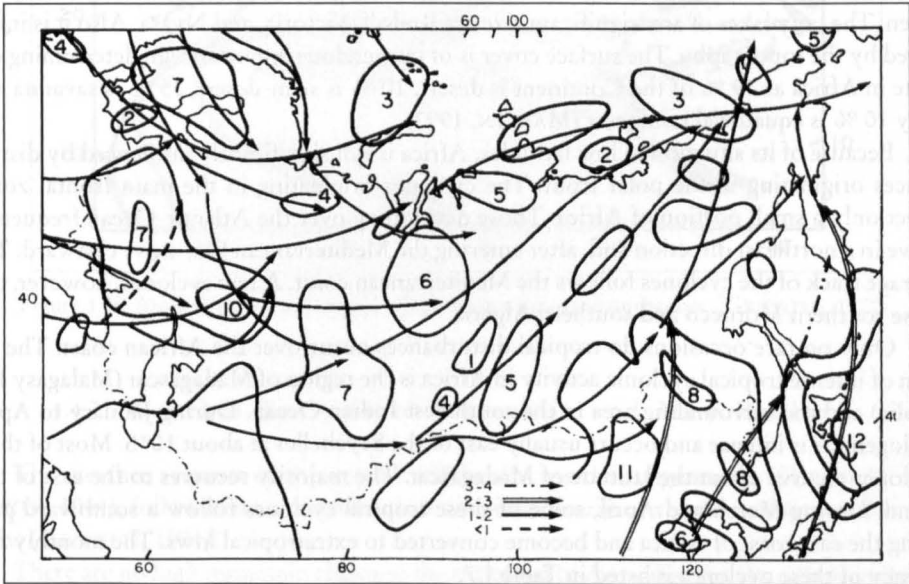


Fig. 1.29: Total number of cyclones during a 20-yr-period over the Soviet Union during the month of July. The principal tracks of cyclones are also shown. (LYDOLPH, 1977)

Generally, the movement of cyclones and fronts over the former CIS is slower than over the eastern part of North America. Also, there is frequent stagnation for a day or more. On the average, about 32 cyclones per year affect central Asia. The frequencies of cyclogenesis and the main routes of cyclones in January and July are shown in Fig. 1.28 and 1.29, respectively.

In winter, strong winds causing blizzards in the steppes and deserts of central Asia go by the name of buran, and in the north are called purga. In the summer months the eastern Ukraine and Caspian Lowland are visited by sukhovei winds (dust storms, black storms) (MARTYN, 1992).

1.4.6 Weather System of Africa

The climate of Africa is influenced first by its position wholly within tropical and equatorial latitudes of both hemispheres from 37°N to 35°S, by the annual movement of the ITCZ, whose northern and southern edges are influenced by subtropical circulation. Africa is devoid of high mountain chains and large indentations to its coastline (MARTYN, 1992). HAURWITZ and AUSTIN (1994) recognized the following mountain chains as having some influence on the weather patterns. In the northwestern part of the continent, the Atlas Mountains and the Algerian Plateau separate the coast and the desert to the south. A few peaks in Morocco extend over 10 000 ft (3050 m) in height. The huge Sahara Desert varies in elevation considerably, with a few peaks over 8000 ft (2440 m), such as the Ahaggar and Tibesti. The main mountain ranges of this continent are somewhat irregularly situated between Zamibia (formerly Northern Rhodesia) and the Red Sea. Near Lake Victoria, and in Ethiopia, some peaks are over 12 000 ft (3660 m). Smaller mountain ranges (Drakensberg Mountains) exist in the southeast; the Auaz Mountains in the southwest, the Cameroon Mountains in Cameroon, and the Ankaratra Mountains in Madagascar (Malagasy Republic) are other examples.

The only indentations along the coastline are the gulfs of Guinea, Gabès, Sidra, and Aden. The only lakes of any significant size are Rudolf, Victoria, and Nyasa. Also it is influenced by the topography. The surface cover is of tremendous importance in determining climate in Africa as 39 % of the Continent is desert, 10 % is semi-desert, 35 % is savanna and only 10 % is equatorial rainforest (MARTYN, 1992).

Because of its situation in low latitudes, Africa is not significantly influenced by disturbances originating in the polar front. The cyclones originating in the main frontal zones affect only a small portion of Africa. Those developing over the Atlantic Ocean frequently move in a northeast direction and, after entering the Mediterranean Sea, move eastward. The average track of the cyclones follows the Mediterranean coast. A few cyclones, however, traverse southern Morocco and southern Algeria.

Only on rare occasions do tropical disturbances occur over the African coast. The region of intense tropical cyclonic activity in Africa is the region of Madagascar (Malagasy Republic) and the surrounding area in the southwest Indian Ocean. During January to April, cyclogenesis is intense and occurs usually east of the Seychelles at about 10° S. Most of these cyclones recurve about the latitude of Madagascar. The majority recurves to the east of this island. During March and April, some of these tropical cyclones follow a southward path along the east coast of Africa and become converted to extratropical lows. The monthly frequency of these cyclones is listed in Table 1.7.

GRIFFITHS (1972) provides the following information about the weather systems of Africa, with particular reference to those of Egypt. During winter, the Mediterranean Sea is

a center of cyclogenesis. These Mediterranean depressions mainly affect northern parts of Egypt. During spring (March to May), the tracks of the Mediterranean depressions shift southward, and during this season, these are referred to as the „desert“ or „Khamisin“ depressions. The frequency of these varies from two to six per month. Also, these depressions, in spring, are smaller in size than the winter depressions.

During summer, the depressions do not traverse Egypt. In fall (October to November), Khamisin-type depressions move across Egypt. Compared with the spring depressions, these are weaker and move more slowly towards the east. The most frequent trajectories of the so-called Sudan-Sahara disturbances are shown in Fig. 1.30.

Table1.7: Monthly distribution (totals) of cyclones in the Mozambique Channel area during the period 1848–1966. (GRIFFITHS, 1972)

Month	No.
January	28
February	30
March	18
April	6
May–November	3
December	15

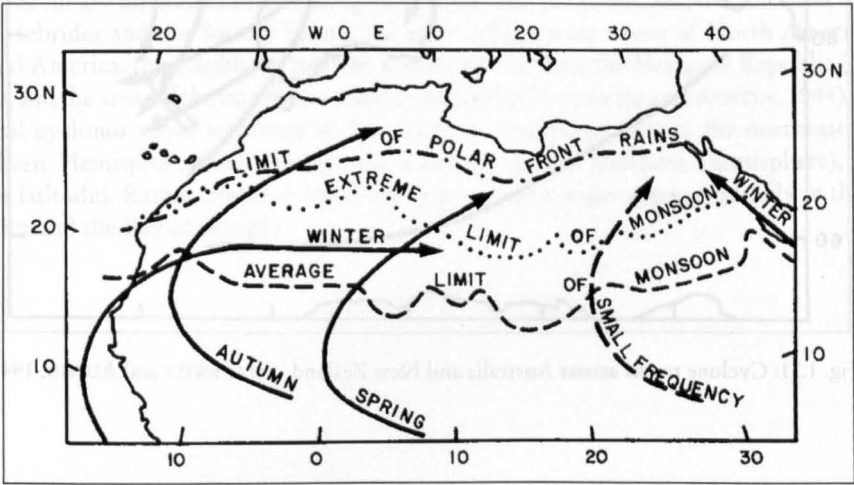


Figure 1.30: Most frequent trajectories of the Sudan-Sahara disturbances. (GRIFFITHS, 1972)

1.4.7 Weather Systems of Australia and New Zealand

The weather systems of this region will be discussed first generally (HAURWITZ and AUSTIN, 1944), followed by a consideration of certain details of the Australian weather systems (GENTILLI, 1971).

There are no high mountain chains in the mainland of Australia, and the only significant indentations to the coastline are the Great Australian Bight and the Gulf of Carpentaria. However, Tasmania is mountainous. New Zealand is also relatively mountainous. The con-

continent is small and no other continents are in its vicinity. Therefore the two neighbouring oceans, the Indian and the Pacific, have a very great influence. In January low pressure centre forms over northern Australia. The ITCZ is lying at around 20°S , north of it there are north-westerly winds, south are south-east trade winds. In July an anticyclonic centre comes into existence over central Australia and joins up along an axis over 30°S with permanent tropical highs over the adjacent oceans.

The tracks of cyclones across Australia and New Zealand are shown in Fig. 1.31 Cyclones developing along the polar front off South Africa usually move south-eastward to the south of New Zealand. Also, stationary cold fronts over Queensland lead to cyclones that move in a general south-easterly direction, either to the north of New Zealand or across North Island of New Zealand. Cyclones developing over New South Wales travel across South Island of New Zealand. Sometimes, cyclones develop along the south coast of Australia.

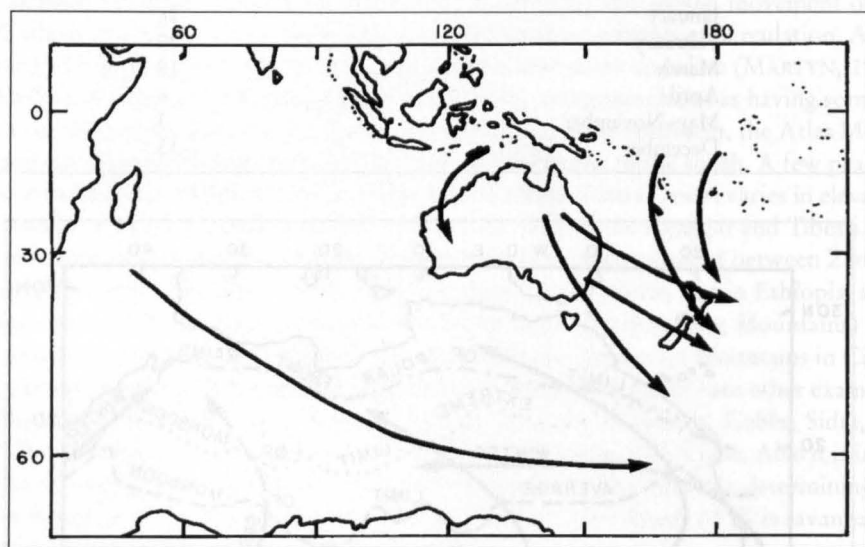


Fig. 1.31: Cyclone tracks across Australia and New Zealand. (HAURWITZ and AUSTIN, 1944)

GENTILLI (1971) stated that, because of its shape, Australia is the only continent that has roughly the same frequency of tropical cyclones on both the east and west coasts. Data for the period 1870–1955 show that, on the average, Northern Territories and Queensland together experience about 3.3 tropical cyclones per year, whereas the west coast average is 2.1. As far as the monthly distribution is concerned, western Australia experiences the highest frequency during December to April.

Generally, in the Australian region, tropical cyclones originate in the belt of $4\text{--}20^{\circ}$ latitude (north and south). One significant feature of tropical cyclones in the region of Australia are their relatively short tracks. Those originating in the Timor Sea travel in a southwest direction with a speed ranging from 8 to 24 km s^{-1} .

1.4.8 Weather Systems of the Oceanic Regions

Since tropical and extratropical cyclogenesis depends on the positions of the various frontal zones, the positions of these will be briefly summarized. The intertropical front lies in the low pressure belt between the large anticyclones of both hemispheres, whereas the polar fronts are mainly located off the east coasts of the continents, and the Arctic and Antarctic fronts lie in the troughs that extend from the high latitude deep cyclones (HAURWITZ and AUSTIN, 1944).

The cyclones of the middle and high latitudes generally develop as wave disturbances on the polar front. Since the position of the front varies considerably, the positions of cyclogenesis also vary with the season. In the Northern Hemisphere, most of these cyclones move in a north-easterly direction towards the Aleutian and Icelandic lows, whereas in the Southern Hemisphere, they move southeastward toward the circumpolar low. The seasonal variation is more pronounced in the Northern Hemisphere. In summer, cyclogenesis usually occurs farther north; the cyclones move slower and they are shallower than the winter cyclones.

Tropical cyclones develop in the intertropical front beyond 5° latitude in the summer hemisphere. Tropical cyclones are a rare phenomenon in the South Atlantic and eastern part of the South Pacific. Their frequency in the North Indian Ocean is quite different from elsewhere. In the Arabian Sea and the Bay of Bengal, they occur mainly in the periods between the southwest and the northeast monsoon seasons. Other water bodies where tropical cyclones occur are the waters surrounding the Philippines, the China Sea, the Solomon Islands, New Hebrides and the Society Island, the areas off the west coasts of North America and Central America, the Caribbean Sea, the waters surrounding the Malagasy Republic (Madagascar, and the area off the northwest coast of Australia (HAURWITZ and AUSTIN, 1944). These tropical cyclones move westward in low latitudes and then towards the northeast in the Northern Hemisphere (and towards the southeast in the Southern Hemisphere), in the higher latitudes. Rather irregular trajectories can occur in many areas, especially in the Arabian Sea and the Bay of Bengal.

2. Basic Storm Surge Equations and Standard Methods of Solutions

2.1 Formulation of the Storm Surge Equations

In numerical models for storm surges, the equations most frequently used are linearized versions of the Navier-Stokes equations in vertically integrated form. MURTY (1984) has given the detailed derivation of these equations. He used a right-handed rectangular Cartesian coordinate system with the origin located at the undisturbed level of the free surface. The coordinate system is such that the x-axis points towards east, the y-axis points towards north, and the z-axis points upwards.

Linear Storm Surge Equations and Boundary Conditions

We will first consider the linear storm surge equation most commonly used, following WELANDER (1961). Assume that the water is homogeneous and incompressible, and that friction due to vertical shear is much more important than horizontal friction. Then, the equations of motion in a right-handed Cartesian coordinate can be written as

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv = -\frac{1}{\rho_0} \frac{\partial P}{\partial x} + \frac{1}{\rho_0} \frac{\partial \tau_x}{\partial z} \quad (2.1)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} + fu = -\frac{1}{\rho_0} \frac{\partial P}{\partial y} + \frac{1}{\rho_0} \frac{\partial \tau_{yx}}{\partial z} \quad (2.2)$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho_0} \frac{\partial P}{\partial z} - g \quad (2.3)$$

The continuity equation is

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad (2.4)$$

where u , v , w are velocity fields in the x , y , and z directions, f is the Coriolis parameter, g is gravity, ρ_0 is the uniform density of water, P is the pressure and τ_x and τ_y are the x and y components of the frictional stress.

With reference to the origin of the coordinate system located at the undisturbed level of the free surface ($z = 0$), the free surface can be denoted by $z = h(x, y, t)$ and the bottom by $z = -D(x, y)$. Let τ_{sx} and τ_{sy} denote the tangential wind stress components and let P_a be the atmospheric pressure on the water surface. Then, the following boundary conditions must be satisfied. At the free surface $z = h$:

$$\tau_x = \tau_{sx}, \tau_y = \tau_{sy} \quad (2.5)$$

$$P = P_a \quad (2.6)$$

Since the free surface has to follow the fluid, we have an additional condition given by

$$\frac{\partial h}{\partial t} + u \frac{\partial h}{\partial x} + v \frac{\partial h}{\partial y} = w \quad \text{at } z = h \quad (2.7)$$

At the bottom, all the velocity components have to vanish. Thus

$$u = v = w = 0 \text{ at } z = -D \quad (2.8)$$

The traditional storm surge equations are derived by performing two operations of vertical integration and linearization. To perform the vertical integration, we define the x and y components of horizontal transport as follows:

$$M \equiv \int_{z=-D}^h u dz \quad \text{and} \quad N \equiv \int_{z=-D}^h v dz \quad (2.9)$$

Integrating the horizontal equations of motion (2.1) and (2.2) and the continuity equation (2.4) with respect to z from $z = -D$ to h and using the boundary conditions defined by equations (2.5)–(2.8) gives

$$\frac{\partial M}{\partial t} + \frac{\partial}{\partial x} \tilde{u}^2 + \frac{\partial}{\partial y} \tilde{u}v - fN = -\frac{1}{\rho_0} \int_{z=-D}^h \frac{\partial p}{\partial x} dz + \frac{1}{\rho_0} (\tau_{sx} - \tau_{sx}) \quad (2.10)$$

$$\frac{\partial N}{\partial t} + \frac{\partial}{\partial y} \tilde{v}^2 + \frac{\partial}{\partial x} \tilde{u}v + fM = -\frac{1}{\rho_0} \int_{z=-D}^h \frac{\partial p}{\partial y} dz + \frac{1}{\rho_0} (\tau_{sy} - \tau_{sy}) \quad (2.11)$$

$$\frac{\partial h}{\partial t} + \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} = 0 \quad (2.12)$$

where, τ_{Bx} and τ_{By} are the x and y components of the bottom stress τ_B . In equations (2.10) and (2.11), the following notation was used:

$$\frac{\partial}{\partial x} \tilde{u}^2 = \frac{\partial}{\partial x} \int_{-D}^h u^2 dz \quad (2.13)$$

$$\frac{\partial}{\partial y} \tilde{u}v = \frac{\partial}{\partial y} \int_{-D}^h uv dz$$

Next, the hydrostatic approximation will be made ignoring the nonlinear acceleration terms. To justify this, two assumptions are made: (a) the amplitude of surge is small with the water depth and (b) horizontal scale of the surge is large compared with the water depth. Following CHARNOCK and CREASE (1957), the following scale analysis can be performed to ascertain the relative importance of the various terms. Let L and H represent the characteristic horizontal scale and depth, respectively. The vertical velocity varies from zero at the bottom to about Z/T at the surface, where Z is characteristic amplitude of the surge and T is a characteristic period. The horizontal velocity is of the order of $L/H \cdot Z/T$.

From equations (2.1) and (2.3), the pressure field is eliminated to obtain the following equation:

$$\frac{\partial^2 u}{\partial t \partial z} + \frac{\partial^2}{\partial x \partial z} u^2 + \frac{\partial^2}{\partial y \partial z} uv + \frac{\partial^2}{\partial z^2} uw - f \frac{\partial v}{\partial z} = \frac{\partial^2 w}{\partial t \partial z} + \frac{\partial^2}{\partial x^2} uw + \frac{\partial^2}{\partial x \partial y} vw + \frac{\partial^2}{\partial x \partial z} w^2 \quad (2.14)$$

$$1 \quad \frac{Z}{H} \quad \frac{Z}{H} \quad \frac{Z}{H} \quad fT \quad \left(\frac{H}{L}\right)^2 \quad \frac{Z}{H} \left(\frac{H}{L}\right)^2 \quad \frac{Z}{H} \left(\frac{H}{L}\right)^2 \quad \frac{Z}{H} \left(\frac{H}{L}\right)^2$$

In equation (2.14), the order of magnitude of each term relative to the first term is indicated under the term. If $(H/L)^2$ is small, all the term on right hand side of equation (2.14) can be neglected. This means that the amplitude of the surge is at most equal to water depth. Ignoring these terms amounts to the hydrostatic approximation. If Z/H is small, one can ignore the three nonlinear terms on the left side of equation (2.14).

The pressure terms can be evaluated follows:

$$\frac{\partial P}{\partial x} = g\rho_0 \frac{\partial h}{\partial x} + \frac{\partial P_a}{\partial x} = 0 \quad (2.15)$$

On vertical integration

$$\int_{-D}^h \frac{\partial P}{\partial x} dz \sim g\rho_0 D \frac{\partial h}{\partial x} + D \frac{\partial P_a}{\partial x} \quad (2.16)$$

Note that, here, h relative to D is ignored, which is consistent with the above approximation. Under the above simplifications, equations (2.14) and (2.12) finally reduce to so called linear storm surge prediction equations:

$$\frac{\partial M}{\partial t} - fN = -gD \frac{\partial h}{\partial x} - \frac{D}{\rho_0} \frac{\partial P_a}{\partial x} + \frac{1}{\rho_0} (\tau_{sx} - \tau_{Bx}) \quad (2.17)$$

$$\frac{\partial N}{\partial t} + fM = -gD \frac{\partial h}{\partial y} - \frac{D}{\rho_0} \frac{\partial P_a}{\partial y} + \frac{1}{\rho_0} (\tau_{sy} - \tau_{By}) \quad (2.18)$$

$$\frac{\partial h}{\partial t} + \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} = 0 \quad (2.19)$$

For convenience, hereafter, the subscript on the density field will be omitted.

In this linear storm surge prediction equations, the dependent variables are the transport components M and N and the water level h . The forcing functions are the atmospheric pressure gradients given by $\partial P_a / \partial x$ and $\partial P_a / \partial y$ and the wind stress components τ_{sx} and τ_{sy} . The retarding force is the bottom stress. At this stage, there are more unknowns than the available equations. To get a closed system of equations, the bottom stress must be expressed in terms of the known parameters, such as the volume transports.

Bottom Stress

Here, parameterization of bottom stress, based on SIMONS (1973), will be discussed. Let \mathbf{V}_B denote the velocity vector near the bottom. Then, the bottom stress τ_B can be expressed as

$$\tau_B = \rho k |\mathbf{V}_B| \mathbf{V}_B \quad (2.20)$$

where, k is a non dimensional coefficient referred to as skin friction; the value of k is about 2.6×10^{-3} . If one assumes a uniform velocity distribution in the vertical and nothing that the horizontal transport vector \mathbf{M} is given by

$$\mathbf{M} = (M, N) = \int_{-D}^h \mathbf{V}_B dz = \int_{-D}^h (u, v) dz \quad (2.21)$$

one obtains

$$\frac{\tau_B}{\rho} = B \mathbf{M} \quad \text{where} \quad B = \frac{k |\mathbf{M}|}{(D+h)^2} \quad (2.22)$$

In most storm surge studies, either for obtaining analytical solutions or for economizing on computer time in numerical models, the bottom stress relation (2.20) is linearized by assuming typical values either for the average velocities or the transport components. For a model of Lake Ontario, SIMONS (1973) assumed average velocities of the order of 10 cm s^{-1} in the shallow waters and about 1 cm s^{-1} in the deep waters of the lake. Thus, B varies from $0.0025/D$ to $0.025/D$ in C.G.S. units. RAO and MURTY (1970) used value of $0.01/D$ for B in their model for Lake Ontario.

Instead of the average velocity field, one can examine the mass transport, which varies more smoothly, for Lake Ontario, SIMONS (1973) gave a value of 2×10^4 to $4 \times 10^4 \text{ cm}^2 \text{ s}^{-1}$ in the shallow as well as deep water, and this leads to $B = 50/D^2$ to $100/D^2$ in C.G.S. units. Another approach to prescribing the bottom stress is to specify the vertical turbulent diffusion of momentum by a constant eddy viscosity ν . PLATZMAN (1963) deduced bottom friction coefficients as a function of the Ekman number, $D\sqrt{f}/2\nu$, in such a way that $B \rightarrow 0$ for grate depth and gives $B = 2.5 \nu/D^2$ for shallow water. For lake Erie, PLATZMAN (1958a) took $\nu = 40 \text{ cm}^2 \text{ s}^{-1}$, which gives $B = 100/D^2$ in C.G.S. units.

Thus the alternative for the bottom friction can be summarized

$$\begin{aligned} \text{linear form } B &= a/D, a \sim 0.01 \text{ cm s}^{-1} \\ \text{quasilinear form } B &= b/D^2, b \sim 100 \text{ cm}^2 \text{ s}^{-1} \\ \text{non linear form } B &= k|\mathbf{V}|/D^2, k \sim 0.0025 \end{aligned} \quad (2.23)$$

In most early storm surge studies the linear form has been used. FISCHER (1959) used the quasi-linear form, where as HANSEN (1956), UENO (1964), and JOHNS et. al (1981) used the nonlinear forms.

Forcing Terms and Lateral Boundary Conditions

In eq. (2.17) and (2.18), the forcing terms are gradients of the atmospheric pressure, $\delta P_a/\delta x$ and $\delta P_a/\delta y$, and the components of the wind stress, τ_{sx} and τ_{sy} . In chapter 5, the meteorological problems will be considered in detail; here the forcing term will be discussed briefly. In principle, the atmospheric pressure gradients can be prescribed either from observations or from the prognosis of numerical weather prediction models. However, the wind stress is not routinely measured and must be deduced from wind observations or predicted winds. The wind stress is usually expressed as

$$\tau_S = \rho_a k |\mathbf{V}_a| \mathbf{V}_a \tag{2.24}$$

where, ρ_a is the density of air (1.2×10^{-3} gm. cm^{-3}) and \mathbf{V}_a is the wind velocity at the anemometer level. The parameter K is the drag coefficient (non dimensional) and is usually given a value of about 3×10^{-3} (PLATZMAN, 1958a; UENO, 1964). However, SIMONS (1973) suggested that for the Great Lakes, a more appropriate value for k is about 1.2×10^{-3} .

Next follows a brief consideration of the lateral boundary conditions to be specified so that the system of equations described by equation (2.17) and (2.19) is complete (details of the lateral boundary conditions will be discussed later). The main lateral boundary condition is that the transport normal to the coastline is zero, i.e.

$$M \cos \phi + N \sin \phi = 0 \tag{2.25}$$

where, ϕ is the angle between the x -axis and the normal to the coastline. If it is assumed that the depth of the water is zero at the shoreline, then the tangential component of the volume transport vector must also be zero. The boundary condition in the open part of the water body is more difficult to prescribe. Since the contribution to the storm surges comes mainly from the shallow water region, a generally followed procedure is to locate the outer boundary in the deep water and assume that the water level perturbation there is zero. However, this may not be satisfactory in certain situations, as will be shown later.

2.2 Numerical Finite Difference Solutions

Beginning in the late 1940s, several finite-difference techniques were developed by people working in the field of meteorology with the aim of predicting the weather through numerical solutions of the governing partial differential equations.

MURTY (1984) has discussed in detail the numerical finite-difference solutions for two-dimensional models for storm surges and tides. Finite differencing of the time derivative and the computational stability of the finite difference schemes has also been described in detail by MURTY (1984). Readers are advised to refer to the book of MURTY (1984) for detailed mathematical description.

2.3 Staggered and Nonstaggered Grid Schemes

MURTY (1984) described in detail the numerical integration using conjugate Richardson lattice. The Richardson lattice is a "staggered grid" because the variables are staggered in

space on the grid. The leapfrog scheme for integration in time is also a staggered scheme (in time). Nonstaggered grids and time integration were used in storm surge calculations until the early 1960s.

Away from the boundaries, central differencing is the most convenient manner of space discretization. However, near (and at) the boundaries, special attention is required; one can place fictitious points outside the boundary or use one-sided difference schemes.

MURTY (1984) has discussed various kind of grid schemes used in discretization of storm surge model equations. He has also described the advantages and the limitations of these grids.

2.4 Treatment of Open Boundaries

At times, storm surge calculations might have to be performed in a limited region of a large water body. This problem could be tackled in at least two different ways. In one approach, one can perform the calculations in the large water body of which the smaller water body is a part and then use the results for the area of interest. However, this approach is not economical and may not even be possible for certain water bodies. Also, there may be a problem with the resolution, since one has to model a larger water body. In the second approach, artificial open boundaries can be introduced around the area of interest and the calculations can be performed in the limited region of interest. However, along these artificial open boundaries, certain conditions have to be introduced, and without proper considerations, these conditions might make the results in the interior region inaccurate.

The commonly used practice of putting zero surface elevation at the sea boundary is not at all satisfactory, because this amounts to perfect reflection at the sea boundary. A better approximation (HEAPS, 1974; HENRY and HEAPS, 1976) is to assume that all outward travelling waves are normal to the boundary and to calculate the volume transports M (or N) from the water level h at the nearest interior grid point; i.e. $M = [g(D + h)]h^{1/2}$. This is the so-called radiation condition.

REID (1975) corrected a misconception commonly held (e.g. FORRISTALL, 1974) in applying open boundary conditions. FORRISTALL (1974, p. 2722) stated at shallow water (lateral) boundary points, derivative of velocity perpendicular to the boundary is set equal to zero so that the transport across the boundary may be calculated from the adjacent flow. This condition is designed to let long waves pass unimpeded through the artificial boundary.

Reid showed that, although such a condition will permit flow of fluid to or from the system, it would produce total reflection of long waves and not zero reflection as FORRISTALL stated.

HERPER and SOBEY (1983) considered the specification of realistic open-boundary conditions for the numerical simulations of hurricane storm surge in the context of the very considerable spatial extend of the meteorological forcing. They reviewed existing practice and proposed an alternative approach, a Bathystrophic Storm tide approximation to open boundary water level. This boundary condition is closely related to the Hydrodynamics, responds realistically to storm forcing and also gives realistic water level contour and flow pattern close to the open boundaries.

BODE and HARDY (1997) while giving a detailed review of open boundary conditions conclude that in spite of the effort expended on the development of artificial open boundary conditions, model studies show that the ideal way to minimise the problem is to use as large a domain as possible.

2.5 Numerical Treatment of the Nonlinear Advective Terms

The linearized versions of the storm surge equations have widely been used in storm surge modelling. However, in shallow-water areas and in the computation of the horizontal motion, at time the nonlinear advective terms might have to be included. CHARNOCK and CREASE (1957) showed through dimensional analysis that the nonlinear advective terms become important when the free surface height is of the same order of magnitude as the water depth.

FLATHER and HEAPS (1975) developed a model for Morecambe Bay allowing for the inclusion of the nonlinear advective terms.

The scheme for the nonlinear advective terms used by FLATHER and HEAPS (1975) is based on the angled derivative approach suggested by ROBERTS and WEISS (1966).

FALCONER (1980) introduced a conditionally stable three time level implicit scheme including the nonlinear advective terms. This scheme is especially suitable for narrow entrance harbors and estuaries where the nonlinear instability problems associated with rapidly changing velocity fields might be very important.

JOHNS et al. (1981) and DUBE et al. (1985a) used conditionally stable semi-explicit finite difference scheme to model storm surge in the Bay of Bengal and Arabian Sea. Vertically integrated predictive equations written in the flux form for their models are:

$$\frac{\partial \zeta}{\partial t} + \frac{\partial \tilde{u}}{\partial x} + \frac{\partial \tilde{v}}{\partial y} = 0 \tag{2.26}$$

$$\begin{aligned} \frac{\partial \tilde{u}}{\partial t} + \frac{\partial}{\partial x} (u \tilde{u}) + \frac{\partial}{\partial y} (v \tilde{u}) = \tilde{f} u = -g(\zeta + h) \frac{\partial \zeta}{\partial x} + \frac{F_s}{\rho} - \\ \frac{c_f + \tilde{u}}{(\zeta + h)} (u^2 + v^2)^{1/2} \end{aligned} \tag{2.27}$$

$$\begin{aligned} \frac{\partial \tilde{v}}{\partial t} + \frac{\partial}{\partial x} (u \tilde{v}) + \frac{\partial}{\partial y} (v \tilde{v}) = \tilde{f} v = -g(\zeta + h) \frac{\partial \zeta}{\partial y} + \frac{G_s}{\rho} - \\ \frac{c_f + \tilde{v}}{(\zeta + h)} (u^2 + v^2)^{1/2} \end{aligned} \tag{2.28}$$

where, $\tilde{u} = (\zeta + h)u$ and $\tilde{v} = (\zeta + h)v$; and depth integrated currents are defined as

$$(u, v) = \frac{1}{(\zeta + h)} \int_{-h}^{\zeta} (u, v) \, dz$$

(F_x, G_y) are the x and y components of wind stress and $(\zeta + h)$ represents the total water depth. The grid scheme used by the authors is a staggered grid in which there are three distinct computational points. The arrangement of grid points is indicated in Fig. 2.1.

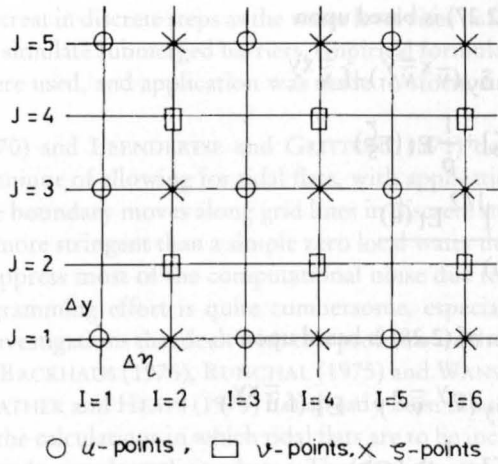


Fig. 2.1: Grid point arrangement.

Any variable X , at a grid point (i, j) may be represented by

$$X(x_i, y_j, t_p) = X_{ij}^p$$

In order to describe the finite – difference equations, they defined difference operators by

$$\begin{aligned} \Delta_t x &= (X_{ij}^{p+1} - x_{ij}^p) / \Delta t \\ \delta_{xx} &= (X_{i+1,j}^p - X_{i-1,j}^p) / (2 \Delta x) \\ \delta_{yy} &= (X_{i,j+1}^p - X_{i,j-1}^p) / (2 \Delta y) \end{aligned}$$

Averaging operations are defined by

$$\begin{aligned} \overline{X}^x &= \frac{1}{2} (X_{i+1,j}^p + X_{i-1,j}^p) \\ \overline{X}^y &= \frac{1}{2} (X_{i,j+1}^p + X_{i,j-1}^p) \\ \overline{X}^{xy} &= \overline{\overline{X}^x}^y \end{aligned} \tag{2.29}$$

and a shift operator is defined by

$$E_t X = X_{ij}^{p+1} \tag{2.30}$$

The continuity equation is discretized as

$$\Delta t (\xi) + \delta x (\tilde{u}) + \delta y (\tilde{v}) = 0 \tag{2.31}$$

Equation (2.31) yields an updating procedure to compute the elevation at all the interior ξ -points and is consistent with the mass conservation in the system.

The discretization of (2.27) is based upon

$$\begin{aligned} \Delta t (\bar{u}) + \delta_x (\bar{u}^x \bar{u}^x) \delta_y (\bar{v}^x \bar{v}^y) - f \bar{v}^{xy} \\ = -g \text{Et}[(\bar{\zeta}^x + h) \delta_x \zeta] + \frac{1}{\rho} \text{Et}(F\bar{\zeta}) \\ - \frac{C_f + [(\bar{u}^x)^2 + (\bar{v}^y)^2]^{1/2}}{\text{Et}(\bar{\zeta}^x + h)} \text{Et}(\bar{u}) \end{aligned} \quad (2.32)$$

A similar discretization of (2.28) is based upon

$$\begin{aligned} \Delta t (\bar{v}) + \delta_x (\bar{u}^y \bar{v}^x) \delta_y (\bar{v}^y \bar{v}^y) + \text{ET}(f \bar{u}^{xy}) \\ = -g \text{Et}[(\bar{\zeta}^y + h) \delta_x \zeta] + \frac{1}{\rho} \text{Et}(G\bar{\zeta}) \\ - \frac{C_f + [(\bar{u}^{xy})^2 + \bar{v}^2]^{1/2}}{\text{Et}(\bar{\zeta}^y + h)} \text{Et}(\bar{v}) \end{aligned} \quad (2.33)$$

The following general points are made about the discretizations. In equations (2.32) and (2.33), the pressure gradient terms are evaluated at the advanced time-level. This is possible explicitly using values of ζ previously updated by application of (2.31) and, following SIELECKI (1968), ensures computational stability subject only to the time-step being limited by the space increment and gravity wave speed. In (2.32), the Coriolis term is evaluated explicitly at the old time level whereas in (2.33) it is evaluated at the advanced time level using the previously updated value of u . Finally in both (2.32) and (2.33), the friction term is evaluated partly implicitly, the resulting difference equations being solved algebraically before their incorporation into the updating scheme. This ensures unconditional computational stability with reference to the treatment of the dissipative terms.

DAVIS (1976) included nonlinear advective terms in the equations of motion and continuity written in the spherical polar coordinate system.

BOOK et al. (1975) developed "flux-correlated" transport schemes for the proper inclusion of the nonlinear advective terms. In this scheme, any artificial diffusion added to the advection term in the first step is subtracted in the subsequent step. LAM (1977) compared various schemes of this type and showed that a central-difference scheme produces oscillations of great amplitude, whereas a one-sided upstream-differencing scheme shows a large false diffusion. However, the one-sided upstream-differencing scheme combined with a flux-corrected transport scheme gave reliable results.

2.6 Moving Boundary Models and Inclusion of Tidal Flats

Moving boundary models have been developed to allow for the climbing of the surge on the coastline as well as to include tidal flats, which become submerged during flood and dry during ebb.

Omitting the non-linear advective and Coriolis terms, REID and BODINE (1968) developed a technique for the inclusion of tidal flats. The coastal boundary that follows the grid

lines can advance or retreat in discrete steps as the water level rises or falls. To allow for flooding of dry land and to simulate submerged barriers, empirical formulae based on the concept of flow over weirs were used, and application was made to storm surges in Galveston Bay, TX.

LEENDERTSE (1970) and LEENDERTSE and GRITTON (1971) developed an alternating direction implicit technique of allowing for tidal flats, with application to Jamaica Bay, NY. In this model also, the boundary moves along grid lines in discrete steps. However, the condition for dry area is more stringent than a simple zero local water depth (the stringent condition was used to suppress most of the computational noise due to the movements of the boundary). The programming effort is quite cumbersome, especially due to the implicit scheme used. Other investigations that dealt with this problem are those of RAMMING (1972), ABBOTT et al. (1973), BACKHAUS (1976), RUNCHAL (1975) and WANSTRATH (1977a, 1977b).

The model of FLATHER and HEAPS (1975) has already been introduced in the section on nonlinear terms. For the calculations in which tidal flats are to be included, they omitted the advective terms and used a simple explicit scheme. The conditions they used depended on an examination of the local water depth and the slope of the water level. Use of the condition on the water level slope specially suppresses the unrealistic movements of the boundary. As in the models of REID and BODINE (1968) and LEENDERTSE and GRITTON (1971), the water-land boundary follows grid lines in discrete time steps.

Before the calculation of current u and v in the x and y directions at each time step, each grid point was tested to see if it was wet (i.e. positive water depth) or dry (zero water depth). If the point was dry, then the current was prescribed as zero. For wet points, u and v were computed from the relevant equations.

YEH and YEH (1976) developed a moving boundary model; i.e. the boundary between dry land and the water can move with time using an ADI technique. Since the technique was found to be numerically inefficient, YEH and CHOU (1979) developed an explicit technique. They showed that the moving boundary (MB) model gives storm surge amplitudes that could be 30 % smaller than those given by a fixed boundary (FB) model, FB models that assume a fixed vertical wall at the water-land boundary could overestimate the surge by about 30 %. YEH and CHOU (1979) used a model to compute surges in the Gulf of Mexico.

TETRA TECH INC. (1978) developed coastal flooding storm surge models, which included the nonlinear advective terms. Coriolis terms, wind stress, atmospheric pressure gradients, and bottom stress. Here, discussion will be confined to the treatment of the land-water boundary. Usually, the landslope onshore is much greater than the slope of the ocean floor. In such situations, the coastal surge is assumed to propagate overland to its corresponding contour level (when the distance to that contour line is much less than one grid interval). However, there are certain regions, such as western Florida, where the onshore slope is very small and the limiting contour interval may be several kilometers inland. For such cases, a one-dimensional run up model is used at various traverses.

SIELECKI and WURTELE (1970) developed a moving boundary scheme in which the lateral boundary of the fluid is determined as a part of the solution. They tested the validity of their scheme by comparing the results of some simple numerical experiments with the results from analytical solutions. Actually, their scheme consists of three different methods: (a) Lax-Wendroff scheme (LAX and WENDROFF, 1960) as modified by RICHTMEYER (1963); (b) using the principle of energy conservation as formulated by ARAKAWA (1966); (c) using the quasi implicit character of the difference equations.

REID and WHITAKER (1976) and REID et al. (1977b) allowed for vast stretches of vegetation and marsh grass (such as in Lake Okeechobee in Florida) in storm surge models. They

showed that when the marsh grass extends above the water surface, a single canopy flow regime results, whereas when the vegetation does not extend above the water surface, a two-layer regime exists. Flooded marsh areas are treated as an ensemble of subgrid scale obstacles.

For submerged vegetation the model is similar to a two-layer system. The interfacial stress is formulated in terms of a coupling coefficient and the flow differential. The friction due to individual canopies is parameterized through a drag coefficient and the dimensions of the elements. When the canopy elements are not submerged, a sheltering factor is introduced.

JOHNS et al. (1982) and subsequently DUBE et al. (1986a) describe a finite difference method, which models a continuously moving lateral boundary. JOHNS et al. (1982) applied it to the numerical simulation of the surge generated by 1977 Andhra cyclone which struck the east coast of India while DUBE et al. (1986) applied it to 1970 Bangladesh cyclone. In both the studies author employ a curvilinear representation of the lateral boundaries, which allow the continuous deforming of the coastline to be model in a fairly realistic way.

For the formulation of model they considered the coastal boundary as time variant situated at $x = b_1(y, t)$ and an off shore open sea boundary situated at $x = b_2(y)$. They also introduced a coordinate transformation to facilitate the numerical treatment of an irregular boundary configuration. The transformation is of the type

$$\xi = \frac{x - b_1(y, t)}{b(y, t)} \tag{2.34}$$

where, $b_1(y, t) = b_2(y) - b_1(y, t)$

The equation of continuity and momentum are written in flux form with ξ, y, t as new independent variables

$$\frac{\partial}{\partial t} (Hb) + \frac{\partial}{\partial \xi} (HbU) + \frac{\partial}{\partial y} (\tilde{v}) = 0 \tag{2.35}$$

$$\frac{\partial \tilde{u}}{\partial t} + \frac{\partial}{\partial \xi} (U\tilde{u}) + \frac{\partial}{\partial y} (v\tilde{u}) - \tilde{f}u = -gH \frac{\partial \zeta}{\partial \xi} + \frac{bF_s}{\rho} - \frac{c_f \tilde{u}}{H} (u^2 + v^2)^{1/2} \tag{2.36}$$

$$\begin{aligned} \frac{\partial \tilde{v}}{\partial t} + \frac{\partial}{\partial \xi} (U\tilde{v}) + \frac{\partial}{\partial y} (v\tilde{u}) + \tilde{f}u = & -gH \left[\frac{\partial \zeta}{\partial y} - \left\{ \frac{\partial b_1}{\partial y} + \xi \frac{\partial b}{\partial y} \right\} \frac{\partial \zeta}{\partial \xi} \right] \\ & + \frac{bG_s}{\rho} - \frac{c_f \tilde{u}}{H} (u^2 + v^2)^{1/2} \end{aligned} \tag{2.37}$$

Where

$$bU = u - \left[\frac{\partial b_1}{\partial t} + \xi \frac{\partial b}{\partial t} \right] - v \left[\frac{\partial b_1}{\partial y} + \xi \frac{\partial b}{\partial y} \right],$$

$$\tilde{u} = Hbu \quad \tilde{v} = Hbv \text{ and } H \text{ is total depth } (\zeta + h)$$

The changing position of the coastline is determined by the condition that the depth of the water be zero at the coastline. This leads to

$$H = 0 \text{ at } x=b_1(y, t) \tag{2.38}$$

or equivalently,

$$\zeta(\xi = 0, y, t) + h[x = b_1(y, t), y] = 0 \quad (2.39)$$

Depending on whether $b_1(y, t) \geq b_1(y, 0)$ the authors either interpolate or use new inland orographical data to fix the value of $h[b_1(y, t), y]$. This is done by differentiating (2.39) with respect to t . This leads to

$$\zeta(\xi = 0, y, t) + \frac{\partial b_1}{\partial t} s = 0 \quad (2.40)$$

where,

$$S = \left[\frac{\partial h}{\partial x} \right]_{x=b_1(y, t)} \quad (2.41)$$

If S is prescribed, (2.40) yields a prognostic equation for b_1 . The most simple case corresponds to constant value of s when (2.41) immediately integrates to

$$b_1(y, t) = b_1(y, 0) - \frac{1}{S} \zeta(\xi = 0, y, t) \quad (2.42)$$

Then if $\zeta(\xi = 0, y, t) < 0$ the sea surface at the shoreline depressed and the shoreline has consequently recoded from its initial position. If $\zeta(\xi = 0, y, t) > 0$, there is a positive surge; the elevation at the shoreline is raised above its equilibrium level and there is a corresponding inland penetration of water.

2.7 Nested Grids and Multiple Grids

In this section, the use of multiple grids, such as combinations of coarse and fine grids, to model storm surges in a water body will be considered. The philosophy behind using multiple grids is to be able to reduce the total computational effort by placing a coarse grid in the deep (and offshore) region and couple this with a finger grid in the shallow coastal area.

In connection with storm surge studies in the Beaufort Sea, HENRY (1975) and HENRY and HEAPS (1976) used a combination of coarse and fine grids but the grids were not coupled dynamically. Examples of studies in which the grids are dynamically coupled are those of ABBOTT et al. (1973), RAMMING (1976), SIMONS (1978), and JOHNS and ALI (1980) and JOHNS et al. (1983a).

GREENBERG (1975, 1976, 1977, 1979) used a combination of grids in his numerical model tides in the Bay of Fundy.

3. Finite-Element Models

3.1 Introduction

This chapter will be concerned with the finite-element approach to storm surges and tides. Compared with the finite-difference methods, the finite-element methods are more recent (they began to appear in the literature in the middle 1960s) but they are better suited for representing the topography realistically than are regular-grid finite-difference techniques.

Following WANG and CONNOR (1975a), the literature on finite-element methods will be briefly reviewed. Unlike in the finite-difference method, in the finite element method the variables satisfying the governing equations and boundary conditions are approximated by piecewise polynomials. The main advantage of the finite-element method is the highly flexible grid so that real water bodies can be modeled more realistically.

WANG and CONNOR (1975a) distinguished between the finite-element method and the discrete-element method as follows. The discrete-element method makes use of both the finite difference and finite-element methods. The discrete-element method, rather than using differential equations for the infinitesimal element, one can perform all the balances on the computational discrete element which can have an arbitrary shape. However, one generally uses square, rectangular, or triangular elements. In an element the variation of any given parameter is represented by discrete nodal values. Usually, these nodes are located at the center of the sides of the elements. To satisfy conservation, the discrete equation must approximate the differential equations as the control volume is reduced to zero. This may be difficult to prove for odd-shaped elements. SIMON-TOV (1974) and ERASLAN (1974) gave some examples of the discrete-element method. WANG and CONNOR (1975a) pointed out that one drawback of the discrete-element method is that if one wants to refine the grid at one point, e.g. (x_0, y_0) , then one must have the same value of Δx for all the elements along the line $y = y_0$ and the same value of Δy for all elements along the line $x = x_0$. However, this is not a serious shortcoming, because either an interpolation technique or trapezoidally shaped elements can be developed to get around this problem.

According to WANG and CONNOR (1975a) the finite-element method was first used in 1956 in aeronautics. Until the late 1960s its use was mainly confined to solid and structural mechanics (ZIENKEWICZ, 1971). In the early stages the success of the finite-element method dependent on the existence of a variational statement of the problem. However, FINLAYSON and SCRIVEN (1965) showed that Galerkin's method can be derived from the method of weighted residuals and there is no need for a variational statement.

Consider the differential equation

$$Lu = f_0 \quad (3.1)$$

where, L is a differential operator, u is an exact solution, and f_0 is the inhomogeneous term. Define the residual R as

$$R = L\hat{u} - f_0 \quad (3.2)$$

Application of a weighting function w to the residual and summation over the complete domain Ω gives

$$WR = \int_{\Omega} R w d\omega = \int_{\Omega} (L\hat{u} - f_0) w d\omega \quad (3.3)$$

where, WR is the weighted residual. The finite-element solution is based on the condition that the weighted residual should vanish.

For some application of the finite-element method to circulation in shallow water bodies, see GALLAGHER and CHAN (1973), who calculated the steady wind driven circulation in shallow lakes under the rigid lid approximation. TAYLOR and DAVIS (1972) used a fourth-order predictor-corrector method for the time integration. They compared the trapezoidal rule and the finite elements in time. GROTKOP (1973) studied the same problem using linear finite elements in time. According to WANG and CONNOR (1975a) this method is less accurate than the trapezoidal rule. Consider the equation

$$\tilde{M} \dot{\tilde{x}} = \tilde{F} \quad (3.4)$$

where the tilde denotes a matrix quantity. Applying the linear finite elements in time to this equation gives the following recurrence relation:

$$\tilde{M} \tilde{x}_{n+1} = \tilde{M} \tilde{x}_n + \Delta t \left(\frac{1}{3} \tilde{F}_n + \frac{2}{3} \tilde{F}_{n+1} \right) \quad (3.5)$$

On the other hand, the trapezoidal rule can be written as

$$\tilde{M} \tilde{x}_{n+1} = \tilde{M} \tilde{x}_n + \frac{\Delta t}{2} (\tilde{F}_n + \tilde{F}_{n+1}) \quad (3.6)$$

Note that the trapezoidal form is centered around time $n + 1/2$ and is better than the skewed form (eq. 3.5). TAYLOR and DAVIS (1972) made use of a cubic expansion in time based on trial runs. It should be noted that the predictor-corrector method and the cubic finite-element method give more accurate results than the trapezoidal rule; however, they require much more computational effort. Because of asymmetric matrices, even the trapezoidal rule is not very efficient.

NORTON et al. (1973) used the Newton-Raphson method including the nonlinear terms. WANG and CONNOR (1975a, 1975b) gave some new concepts, which helped to solve troublesome details encountered in an earlier studies. The boundary condition of nonzero slip in the tangential velocity field is conceptually difficult to apply when curved land boundaries are approximated by triangular elements. At the break points of the model boundary, the non-zero tangential velocity component gives rise to flow across the adjoining segments. Then, to satisfy the continuity equation at the break points, one is forced to equate both velocity components to zero. NORTON et al. (1973) suggested that one should keep as few break points as possible and these points both the velocity component must be prescribed equal to zero. Once one is forced to do this, the flexibility of the finite-element grid is sacrificed; also, near the break points one must use a fine grid. This will necessitate the use of the long and narrow triangles (distorted elements) WANG and CONNOR (1975a) resolved this problem by a proper definition of a normal direction at the break points, and this permits a nonzero tangential component of the velocity without reducing the number of break points.

For a detailed derivation of the equations involved in the finite-element method see WANG and CONNOR (1975a). They solved several simple problems to enable comparison with analytical solutions. Finally, they applied the technique to a study of tides in the Massachusetts Bay. WANG and CONNOR (1975a) also formulated a two-layer model (for other details see CONNOR and WANG [1973] and WANG and CONNOR [1975b]).

WEARE (1976) compared the computational expenses for the shallow-water problems using finite-difference and finite-element methods and concluded that, at present, finite-element methods are less economical due to the use of band algorithms. However, the situation is changing now. GRAY and PINDER (1976) made a comprehensive comparison of finite-difference and finite-element methods and showed that the finite-element representation of the differential equations is essentially a spatial average of standard finite-difference equations written for each mode of the grid.

KLEINSTREUER and HOLDEMAN (1980) developed an interactive triangular finite-element mesh generator for water bodies of the arbitrary geometry. NIEMEYER (1979a) applied a finite-element technique to study tidal flow in certain water bodies in Hawaii. ORLOB (1972) used triangular grids for studying circulation in the San Francisco Bay area, but he wrote the equation in finite-difference form. FIX (1975) used a finite-element model to study the circulation in a limited area of the mid-ocean.

GROTKOP (1973) used a finite-element technique for studying waves in the North Sea. CHENG (1972, 1974), CHENG et al. (1976), CHENG and TUNG (1970), GALLAGHER et al. (1973), GALLAGHER and CHAN (1973) and HUEBNER (1974) applied finite-element techniques to study wind-driven circulation in lakes. Other relevant works are those of CHENG (1978), WALTERS and CHENG (1980a, 1980b), JAMART and WINTER (1979), MEI and CHEN (1975), REICHARD and CELIKOL (1978), HAUGUEL (1978), LE PROVOST (1978), LEIMKUHLER et al. (1975), and TAYLOR and HOOD (1973).

JAMART and WINTER (1978) used the finite-element approach to study tidal propagation. One of their important assumptions is periodic motion. Because of this assumption, this model cannot be used to study storm surges (which are not periodic). KAWAHARA et al. (1977) used a mixed approach of the finite element method and perturbation method, again with the assumption of periodic motion. THACKER (1977) studied the normal modes in a circular basin using an irregular-grid finite difference model (this will be considered in detail below). WANG (1977) criticized Thacker's work and pointed that Thacker's model is unstable and inaccurate.

MEI and CHEN (1975) introduced a hybrid-element method for water problems in infinite fluid domain. They introduced artificial boundaries and thus divided the fluid into a finite-element region, in the neighborhood of infinity or of singular points. In the finite element region polynomial interpolating functions are used to approximately represent the unknown functions. In the super-element region, infinite series solutions are used. Numerical computations involve only integrals in a finite domain and the inversion of a banded symmetric matrix. Examples of shallow-water waves in a harbor are included.

HOUSTON (1978) used a finite-element numerical model to study the interaction of tsunamis with the Hawaiian Islands. This model solves the generalized Helmholtz equation:

$$\nabla[D(x, y)\nabla\phi(x, y)] + \frac{\omega^2}{g}\phi(x, y) = 0$$

where, $\phi(x, y)$ is the velocity potential, ω is the angular frequency, and $D(x, y)$ is the water depth. This equation is not relevant for storm surge studies, at least in its present simple form.

3.2 Finite-Element Models for Tides and Storm Surges

BREBBIA and PARTRIDGE (1976) studied the tides and storm surges in the North Sea using two finite-element models. In both models they used six-noded triangular elements. One model made use of an implicit integration scheme with curved sides, and the other utilized an explicit integration scheme. The models are vertically integrated and include tides, wind stress, atmosphere pressure gradients, bottom friction, Coriolis force, and advection terms.

Following BREBBIA and PARTRIDGE (1976), a Cartesian coordinate system, with the origin at the equilibrium water level and the z-axis pointing upwards, is used. Let $D(x, y)$ be the deviation of the free surface from its equilibrium position. The horizontal momentum equations can be written in the following form:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = B \tag{3.7}$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = B$$

$$B_x = fv - g \frac{\partial h}{\partial x} - \frac{\partial}{\partial x} \left(\frac{P_a}{\rho} \right) + \frac{1}{\rho} \tau_{sx} - \frac{1}{\rho} \tau_{Bx} \tag{3.8}$$

$$B_y = fu - g \frac{\partial h}{\partial y} - \frac{\partial}{\partial y} \left(\frac{P_a}{\rho} \right) + \frac{1}{\rho} \tau_{sy} - \frac{1}{\rho} \tau_{By}$$

where, u and v the x and y components of the velocity field averaged in the vertical direction. The following expressions can be written for the surface stress, τ_s , and the bottom stress, τ_B ,

$$\tau_{s_i} = \frac{\gamma}{\rho} \frac{W_i}{H^2} (W_x^2 + W_y^2)^{1/2}, \quad i = x \text{ or } y \tag{3.9}$$

$$\tau_{B_i} = \frac{-g}{C^2} \rho \frac{V_i}{H} (u^2 + v^2)^{1/2}, \quad i = 1, 2$$

If $i = 1$, $V_i = u$; if $i = 2$, $V_i = v$. Here, C is a Chezy coefficient, W_x and W_y are the x and y components of the wind, and γ is a parameter related to the atmospheric density, ρ_a ($\gamma = \rho_a$, constant). Finally, $H = D + h$.

The vertically integrated from of the continuity equation is

$$\frac{\partial H}{\partial t} + \frac{\partial}{\partial x} (Hu) + \frac{\partial}{\partial y} (Hv) = 0 \tag{3.10}$$

At closed boundaries, the velocity component perpendicular to the boundary is set to zero, while the tangential component is nonzero. At open boundaries, either the normal component of the velocity or the water level is prescribed.

To develop the finite-element model, two momentum equations and the continuity equation (3.10) together with the influx type boundary condition must be written in the following weighted residual manner:

$$\begin{aligned} \iint \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} - B_x \right) \delta u dA &= 0 \\ \iint \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} - B_y \right) \delta v dA &= 0 \\ \iint \left[\frac{\partial H}{\partial t} + \frac{\partial}{\partial x} (Hu) + \frac{\partial v}{\partial y} (Hv) \right] \delta H dA &= \int (H V_n - H \bar{V}_n) \delta H dS = \int H \bar{V}_n \delta H dS \end{aligned} \quad (3.11)$$

Where n denotes the normal and V_n denotes the component of the velocity. It will be assumed that over an element, the same interpolation for the unknown u , v , and H . Thus

$$\begin{aligned} u &= \phi u^n \\ v &= \phi v^n \\ H &= \phi H^n \end{aligned} \quad (3.12)$$

where, ϕ is the interpolation function and u^n , v^n , and H^n are the nodal of u , v , and H . A six-nodal triangular finite-element grid was used. These elements were referred to as "isoparametric" by BREBBIA and PARTRIDGE (1976). The advantage of using curved elements is the suppression of the spurious forces generated on the boundaries by straight-line segments joining at an angle (CONNOR and BREBBIA 1976).

From eq. (3.11) and (3.12)

$$\begin{aligned} M \frac{\partial u^n}{\partial t} + K u^n - f M v^n + G_x H^n + F_x &= 0 \\ M \frac{\partial v^n}{\partial t} + K v^n - f M u^n + G_y H^n + F_y &= 0 \\ M \frac{\partial H^n}{\partial t} + C_x u^n - C_y v^n + F_H &= 0 \end{aligned} \quad (3.13)$$

with the following definitions (superscript T denotes the transpose):

$$\begin{aligned} K &= \int \frac{\partial}{\partial x} (\phi^T \phi) u dA + \int \frac{\partial}{\partial y} (\phi^T \phi) v dA + \frac{g}{C^2} \int \frac{\phi^T (u^2 + v^2)^{1/2}}{H} \phi dA \\ G_x &= g \int \frac{\partial}{\partial x} (\phi^T \phi) dA \\ G_y &= g \int \frac{\partial}{\partial y} (\phi^T \phi) v dA \\ M &= \int \phi^T \phi dA \\ F_x &= \int \phi^T \frac{\partial}{\partial x} \left(\frac{P_a}{\rho} \right) dA + \frac{\gamma}{\rho} \int \phi^T \frac{W_x}{H} (W_x^2 + W_y^2)^{1/2} dA \\ F_y &= \int \phi^T \frac{\partial}{\partial y} \left(\frac{P_a}{\rho} \right) dA + \frac{\gamma}{\rho} \int \phi^T \frac{W_y}{H} (W_x^2 + W_y^2)^{1/2} dA \\ C_x &= \int \frac{\partial}{\partial x} (\phi^T) H \phi dA \\ C_y &= \int \frac{\partial}{\partial y} (\phi^T) H \phi dA \\ F_H &= \int H \bar{V}_n \phi^T dA \end{aligned}$$

$$\begin{bmatrix} M & & \\ & M & \\ & & M \end{bmatrix} \begin{bmatrix} \frac{\partial u^n}{\partial t} \\ \frac{\partial v^n}{\partial t} \\ \frac{\partial H^n}{\partial t} \end{bmatrix} + \begin{bmatrix} K & -fM & G_x \\ fM & K & G_y \\ -C_x & -C_y & 0 \end{bmatrix} \begin{bmatrix} u^n \\ v^n \\ H^n \end{bmatrix} + \begin{bmatrix} F_x \\ F_y \\ F_H \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (3.14)$$

or in the abbreviated form

$$MQ + KQ = F \quad (3.15)$$

Then, all such elements must be assembled and the boundary conditions applied. Two different time integration procedures were used. The first one an implicit scheme involving the trapezoidal rule. Assume

$$\begin{aligned} \dot{Q} &= \frac{Q_T - Q_0}{\Delta t} \\ Q &= \frac{Q_T + Q_0}{2} \\ F &= \frac{F_0 + F_t}{2} \end{aligned} \quad (3.16)$$

Then eq (3.15) becomes

$$\left(\frac{2}{\Delta t} M + K \right) Q_t = (F_0 + F_t) + \left(\frac{2M}{\Delta t} - K \right) Q_0 \quad (3.17)$$

This can be written in the abbreviated form as

$$K^* Q_t = F^* \quad (3.18)$$

Then, the recurrence relationship is given by

$$Q = \left(K^* \right)^{-1} F^* \quad (3.19)$$

The K^* matrix which must be inverted will generally be a large asymmetrical banded matrix of size approximately three times the number of nodes by six times the element band width (i.e. the maximum difference between element nodal point numbers plus one). The explicit time integration used here follows the fourth-order Runge-Kutta method.

HAMBLIN (1976) and WILLIAMSON (1999) used finite-element techniques to study seiches, circulation and storm surges in Lake Winnipeg. His paper will be considered in some detail below. With reference to a Cartesian coordinate system (x, y) directed towards east and north, respectively, for a homogeneous fluid, under the hydrostatic approximation, with the neglect of the nonlinear terms and assuming a uniform value for the Coriolis parameter f :

$$\begin{aligned} \frac{\partial u}{\partial t} - f v + g \frac{\partial h}{\partial x} &= 0 \\ \frac{\partial v}{\partial t} + f u + g \frac{\partial h}{\partial y} &= 0 \\ \frac{\partial h}{\partial t} + \frac{\partial}{\partial x} (D u) + \frac{\partial}{\partial y} (D v) &= 0 \end{aligned} \quad (3.20)$$

where u and v are the vertically averaged horizontal velocity components in the x and y directions, $D(x, y)$ is the water depth, and $h(x, y, t)$ is the deviation of the water level from its equilibrium position.

Since we are concerned with periodic motion, the explicit time dependence can be eliminated by using an exponential time factor in the investigation of seiches. Then, the modified set of equations in (3.20) can be written using an elliptical operator (self-adjoint) for all boundary conditions (except when energy radiates through the openings). A variational formulation of the problem may be made and a numerical solution can be sought. For this, multiply the first equation of (3.20) by u^* (u^* is the complex conjugate of u) and add this to the product of the second equation (3.20) of with v^* . Then, use the continuity equation, integrate over the volume of the lake, and use Green's theorem to give the total kinetic and potential energy in the lake:

$$I(h) = \int_A \left\{ h h^* + \frac{gD}{f^2 + \sigma^2} \left[\frac{f}{i\sigma} \left(\frac{\partial h}{\partial y} \frac{\partial h^*}{\partial x} - \frac{\partial h}{\partial x} \frac{\partial h^*}{\partial y} \right) + \left(\frac{\partial h}{\partial x} \frac{\partial h^*}{\partial x} + \frac{\partial h}{\partial y} \frac{\partial h^*}{\partial y} \right) \right] \right\} dx dy \quad (3.21)$$

Where $i = \sqrt{-1}$ and σ is the frequency of oscillation (i.e. seiche).

In deriving this equation, it is assumed that any of the following three boundary conditions can be used, noting that all of them permit zero energy flux across the boundaries: (a) vanishing depth at the shore line and finite values of h and its gradients, (b) finite depth at shoreline and zero velocity normal to the shoreline, and (c) finite depth and nonzero normal current but zero value of h across the boundary. HAMBLIN (1976) took zero depth at the coastline.

It can be shown that the function that minimizes eq. (3.21) will be the solution of eq. (3.20). The parameters h and h^* are expanded in a series of trial functions Ψ_i and weighting coefficients q_i :

$$h = \sum_i q_i \Psi_i \quad \text{and} \quad h^* = \sum_i q_i^* \Psi_i^*$$

Substituting into eq. (3.21) gives

$$I(q, q'^*) = q'^*{}^T \sigma^3 [L] q' + q'^*{}^T \sigma [M] q' + q'^* [N] q' \quad (3.22)$$

Here, $[L]$, $[M]$, and $[N]$ are Hermitian matrices, q' is the vector of unknown coefficients, and $q'^*{}^T$ is the transpose of q'^* .

To determine the minimum of the approximating function:

$$\frac{\partial I}{\partial q^*} = 0$$

which gives form eq. (3.22)

$$\sigma^3 [L]z + \sigma [M]z + [N]z = 0 \tag{3.23}$$

where, z is the vector of weights minimizing I. The calculation of the approximating function proceeds as follows.

Lake Winnipeg is subdivided into triangular elements (Fig. 3.1a) giving a total of 144 elements. In the interior, the sides of the elements are straight lines, whereas at the coast they are curved. In locations where details are not important, a coarser grid has been used. The trial function is chosen such that the weighting coefficients become the free surface displacements, h, at the vertices and the three middle points (left side of Fig. 3.1b). Six points are required to determine the six coefficients of the second order polynomial in x and y. The quadratic surface determined in this manner is continuous across the edges between the triangles, but the gradients may not be continuous.

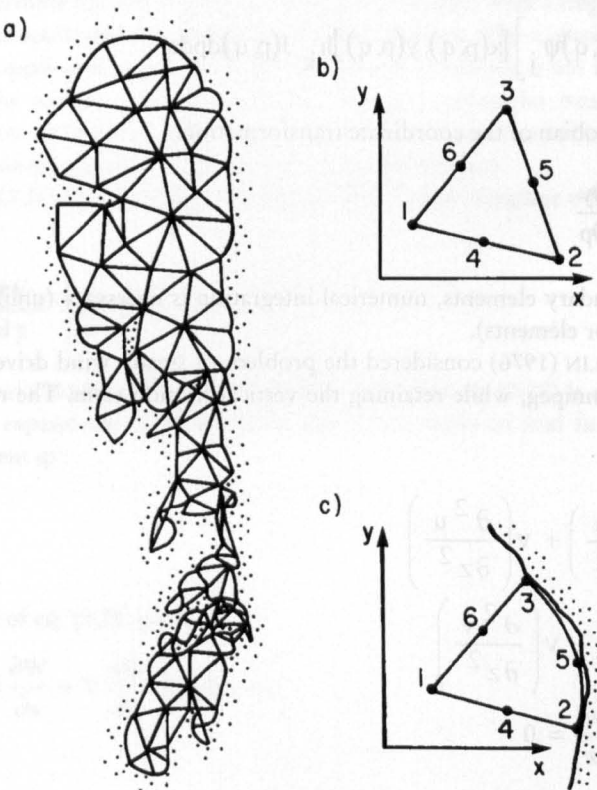


Fig. 3.1: (a) Triangular finite-element grid for Lake Winnipeg (144 elements); (b) a typical triangular element in the interior of the lake (the six nodes defining the element are numbered); (c) element adjacent to a boundary. (HAMBLIN, 1976)

Next, the depth D is expanded using an identical polynomial expression, in which the weighting coefficients become the specified depths at the six nodes of the triangle. If one expresses the Lagrangian interpolation functions in terms of the local triangular coordinates (rather than the global x and y coordinates), all the integrations in eq. (3.21) can be performed analytically for the interior elements. The matrices $[L]$, $[M]$, and $[N]$ are formed by summing the contributions from each element I . Owing to the symmetry of the variational formulation, the computer storage requirements and the number of integrations required are halved.

In general, the side of a triangle along the coastline will not coincide with the boundary (right side of Fig. 3.1b) and one must transform the curved shoreline into a straight line by means of a coordinate transformation. Define a coordinate system such that

$$x = x(p, q)$$

$$y = y(p, q)$$

Then, a boundary integration of the form

$$\iint \Psi_i(x, y) \Psi_j(x, y) h_k \, dx dy$$

becomes

$$\iint \Psi_i[x(p, q), y(p, q)] \Psi_j[x(p, q), y(p, q)] h_k J(p, q) \, dp dq$$

where, J is the Jacobian of the coordinate transformation:

$$J = \frac{\partial x}{\partial p} \frac{\partial y}{\partial q} - \frac{\partial x}{\partial q} \frac{\partial y}{\partial p}$$

For the boundary elements, numerical integration is necessary (unlike analytical integration for interior elements).

Next, HAMBLIN (1976) considered the problem of steady wind driven circulation and setup in Lake Winnipeg, while retaining the vertical friction term. The relevant equations are

$$\begin{aligned} -fv &= -g \left(\frac{\partial h}{\partial x} \right) + v \left(\frac{\partial^2 u}{\partial z^2} \right) \\ fu &= -g \left(\frac{\partial h}{\partial y} \right) + v \left(\frac{\partial^2 v}{\partial z^2} \right) \end{aligned} \tag{3.24}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

where, ν is the vertical eddy viscosity and w is the vertical component of the velocity (here, u and v are not vertically averaged).

The boundary conditions are the following:

$$v\left(\frac{\partial u}{\partial z}\right)_{z=0} = \frac{\tau_{sx}}{\rho} \quad \text{and} \quad v\left(\frac{\partial v}{\partial z}\right)_{z=0} = \frac{\tau_{sy}}{\rho} \tag{3.25}$$

where, τ_{sx} and τ_{sy} are the wind stress components at the surface and

$$u\xi_{z=-D} = 0 \text{ and } v\xi_{z=-D} = -D = 0 \tag{3.26}$$

In the vertically integrated form the continuity equation is

$$\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} = 0 \tag{3.27}$$

where

$$(U, V) = \int_{-D}^0 (u, v) dz$$

is the horizontal transport vector. At the lateral boundaries the normal transport is taken as zero.

Making use of the Galerkin method, HAMBLIN (1976) developed a technique, which enables one to determine the free surface and transport variables with a single solution of the equations, which is applicable for multiple-connected regions. The variational formulation used earlier is not applicable because the self-adjointness condition is not satisfied owing to the presence of the surface wind stress terms. Hence, a somewhat weaker formulation, namely the Galerkin method, is used. In this method, a stationary point (rather than a minimum) of an expression related to the function will be determined.

Multiply eq. (3.27) by a weighting function $W(x, t)$ and integrate over the area of the whole lake to give

$$\int W \left(\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} \right) dx dy = 0 \tag{3.28}$$

Using Galerkin's method, W must be chosen such that eq. (3.27) is satisfied at all the nodes. As above, expand the variables U, V , and h in a series of trial functions i and the weighting coefficient q_i :

$$h = \sum_i q_i \psi_i$$

Partial integration of eq. (3.28) gives

$$\oint W(\tilde{v}d\tilde{n}) - \iint \left(U \frac{\partial W}{\partial x} + V \frac{\partial W}{\partial y} \right) dx dy = 0$$

Note that the line integral is zero in the case where there is no river input or outflow. Using eq. (3.26) one can eliminate U and V and write

$$\begin{aligned} & \iint gD \left(E \frac{\partial h}{\partial x} - F \frac{\partial h}{\partial y} \right) \frac{\partial W}{\partial x} dx dy + \iint gD \left(F \frac{\partial h}{\partial x} + E \frac{\partial h}{\partial y} \right) \frac{\partial W}{\partial y} dx dy \\ &= - \iint \left[C\tau_{sx} - D\tau_{sy} \right] \frac{\partial W}{\rho \partial x} dx dy - \iint \left[A\tau_{sx} + C\tau_{sy} \right] \frac{\partial W}{\rho \partial x} dx dy \end{aligned} \quad (3.29)$$

(For details on the parameters C , A , E and F , see WELANDER (1957). In this section, Welander's parameter D has been replaced by A .)

For evaluating eq. (3.29) the parameters D , C , A , E , F , τ_{sx} and τ_{sy} are expanded in a series of the same trial functions, i.e.:

$$\tau_{sx} = \sum_{i=1}^6 \tau_{sx_i} \psi_i$$

Then, eq. (3.29) gives a system of six equations for each element:

$$\begin{aligned} & \sum_{j=1}^6 \iint gD \left(E \frac{\partial \psi_j}{\partial x} - F \frac{\partial \psi_j}{\partial y} \right) \frac{\partial \psi_i}{\partial x} dx dy + \iint gD \left(F \frac{\partial \psi_j}{\partial x} + E \frac{\partial \psi_j}{\partial y} \right) \frac{\partial \psi_i}{\partial y} dx dy \\ &= - \iint \left(C\tau_{sx} - A\tau_{sy} \right) \frac{\partial \psi_i}{\rho \partial x} dx dy - \\ & \iint \left(A\tau_{sx} - C\tau_{sy} \right) \frac{\partial \psi_i}{\rho \partial x} h_j dx dy \quad \text{for } i=1 \text{ to } 6 \end{aligned} \quad (3.30)$$

For the whole water body, the equations are obtained by successive integrations of each element and by adding all these, which assumes continuity of h_i at each node. The matrix

$$[M]h = B$$

is solved by Gaussian elimination.

Finally, HAMBLIN (1976) considered storm surges in Lake Winnipeg by beginning with the following time-dependent equations:

$$\begin{aligned} \frac{\partial u}{\partial t} - fv + g \frac{\partial h}{\partial x} &= \frac{\tau_{sx}}{D\rho} + \frac{\tau_{Bx}}{D\rho} \\ \frac{\partial v}{\partial t} - fu + g \frac{\partial h}{\partial y} &= \frac{\tau_{sy}}{D\rho} + \frac{\tau_{By}}{D\rho} \\ \frac{\partial h}{\partial t} + \frac{\partial}{\partial x} (Du) + \frac{\partial}{\partial y} (Dv) &= 0 \end{aligned} \quad (3.31)$$

where, τ_B is the bottom stress.

HAMBLIN used a semianalytic technique (spectral method) in which the time variable is treated analytically and the space variables are treated numerically. Equations (3.31) can be written as in the finite element method as

$$\frac{dQ}{dt} = [M]Q + T(t) \tag{3.32}$$

where, the vector Q consists of the individual components of the current and h, the vector T consists of the wind stress components at each node, and the matrix [M] consists of coefficients which include f, g, D and the bottom friction.

For the initial condition, Q(0), the general solution of eq. (3.32) can be written as

$$Q(t) = [X(t)]Q(0) + \int_0^t [X(t-t')]T(t')dt' \tag{3.33}$$

where,

$$[X(t)] = [C] \begin{bmatrix} e^{\sigma_1 t} & & \\ & \ddots & \\ & & e^{\sigma_n t} \end{bmatrix} [C]^{-1}$$

Here, σ are the eigenvalues and [C] is the matrix of eigenvectors of

$$\{[M] - \sigma[I]\} \{C_i\} = 0$$

If the water body is initially at rest, Q(0) = 0 and a suddenly imposed wind stress can be written as T(t) = K. Integrating of eq. (3.33) gives

$$[Q(t)] = -[C] \begin{bmatrix} \frac{1}{\sigma_1} & & \\ & \ddots & \\ & & \frac{1}{\sigma_n} \end{bmatrix} [C]^{-1}K + [C] \begin{bmatrix} \frac{e^{\sigma_1 t}}{\sigma_1} & & \\ & \ddots & \\ & & \frac{e^{\sigma_n t}}{\sigma_n} \end{bmatrix} [C]^{-1}K \tag{3.34}$$

The first term in this equation can be shown to be $[M]^{-1}K$, which is the solution to the steady-state problem

$$[M]Q = K$$

The second term is a weighted sum of the free modes of oscillation of the discrete problem of order n:

$$\sum_{i=1}^n W_i \{C_i\} e^{\sigma_i t}$$

The transient response of the lake interpreted in this manner shows the connection between the general time-dependent problem and the steady-state seiche problems considered earlier.

Let the vector of the free surface displacements be denoted by S and let the eigenvectors, C_p , consist only of h ; then, eq. (3.34) can be approximated:

$$h(t) \sim S + \sum_i^{n'} W_i \{C_i\} e^{\sigma_i t}$$

Where the limit n' is a subset of the total n eigenvectors of $[M]$. Since the water body is at rest initially, $h(0) = 0$. Then

$$[C] W = S$$

noting that the imaginary part of S is zero. Since initially, u and v are zero, then

$$\left. \frac{\partial h}{\partial t} \right|_{t=0} = 0 \quad \text{and} \quad \left. \frac{\partial^2 h}{\partial t^2} \right|_{t=0} = 0$$

Hence,

$$[C] \sigma W = 0 \quad \text{and} \quad [C] \sigma^2 W = 0$$

From these equations the weighting coefficients may be determined by minimizing the square of the free surface deviation, h , at each node in the water body.

After obtaining the step function response, h may be calculated for a general time history of wind forcing using the convolution integral. The unit impulse response can be obtained by differentiation of the step function response. The free surface displacement, h , can be calculated by convoluting the wind input, $T(t)$, with h_{imp}

$$h(t) = \int_0^t h_{imp}(t - t') T(t') dt'$$

In the discrete form, this can be written as

$$h_K = \Delta t \sum_{i=0}^j h_{imp}^i T_{K-i}$$

3.3 Development in the late 1970s and early 1980s

PLATZMAN (1979) paid particular attention to proper treatment of the multiconnected regions in finite-element models and applied these concepts to a study of the normal modes of the world ocean. PLATZMAN (1981) discussed the response characteristics of finite-element tidal models.

LYNCH and GRAY (1980b) developed a variable size triangular-grid finite-element model in which the boundary is permitted to deform. This technique is especially suitable for simulating the penetration of storm surges over land. Certain details of their earlier works lea-

ding to this model are contained in GRAY and LYNCH (1977, 1979), LYNCH (1980) and LYNCH and GRAY (1978, 1979, 1980a). Here, mainly the moving boundary model will be considered.

LYNCH and GRAY (1980b) used the Galerkin finite-element approach (for fixed boundaries) with certain modifications to the moving boundary problem. First, consider the fixed boundary problem. In their notation, the problem may be stated as

$$Lu = f \tag{3.35}$$

where, L is a differential operator with derivatives in space and time, $u(X, t)$ is the unknown function, $f(X, t)$ is the known forcing function, X is the set of independent space variables, and t is time. One can use an approximate solution (x, t) as

$$u \sim \hat{u} = \sum_{j=1}^N u_j(t) \phi_j(X) \tag{3.36}$$

where, $\phi_j(X)$ are known basic functions.

Substituting eq. (3.36) into eq. (3.35) produces a nonzero residual $r(X, t)$:

$$L \cdot \hat{u} \equiv r(X, t) \tag{3.37}$$

The basic requirement in the Galerkin procedure is that the residual must be orthogonal to each of the basis functions ϕ_j , i.e.:

$$\langle r(X, t), \phi_i \rangle = 0 \quad i = 1, \dots, N \tag{3.38}$$

where, angle brackets denote the inner product. It can be seen that eq. (3.38) forms a set of ordinary differential equations for the function $u_j(t)$.

For the moving boundary problem, the following modifications must be made to this procedure. The basis function ϕ_j now becomes an implicit function of time because its value at any point depends on the location of the nodes (of a grid which is deforming):

$$\phi_j = \phi_j[X, X_b(t)] = \phi_j(X, t) \tag{3.39}$$

where, the node coordinates are denoted by $X_b(t)$. In eq. 3.38, the integration domain of the inner product changes in time. Thus, the equations becomes nonstationary and nonlinear, as can be seen, for example, from the fact that the mass matrix, $\langle \phi_j, \phi_i \rangle$, which multiplies the time derivative terms, du_j/dt , changes with time.

Next, an additional relation must be added for the node motion:

$$\frac{d}{dt} X_b(t) = V_b(t) \tag{3.40}$$

where, V_b is the velocity of node b. Generally, for the interior nodes $V_b = 0$ and for the boundary nodes $V_b = v_b$ where V_b is the velocity of the node and v_b is the fluid velocity at node b. Finally, eq. (3.36) must be replaced with

$$\hat{u}(X, t) = \sum_{j=1}^N u_j(t) \phi_j(X, t) \tag{3.41}$$

where, $u_j(t)$ is the value of \cdot at node j (i.e. at the moving joint, $X_j(t)$).

The time derivatives of (X, t) will have, as expected, additional terms (underlined>) not contained in a fixed boundary model:

$$\frac{\partial \hat{u}}{\partial t} = \sum_{j=1}^N \frac{du_j}{dt} \phi_j + \sum_{j=1}^N u_j \frac{d\phi_j}{dt} \tag{3.42}$$

and

$$\frac{\partial^2 \hat{u}}{\partial t^2} = \sum_{j=1}^N \frac{d^2 u_j}{dt^2} \phi_j + 2 \sum_{j=1}^N \frac{du_j}{dt} \frac{d\phi_j}{dt} + \sum_{j=1}^N u_j \frac{d^2 \phi_j}{dt^2} \tag{3.43}$$

Since the spatial domain is changing with time, the terms $\partial \phi_j / \partial t$ and $\partial^2 \phi_j / \partial t^2$ must be defined throughout the domain. Since these terms depend exclusively on the node locations $X_b(t)$ and their derivatives, in principle one can write expressions for $\partial \phi_j / \partial t$ and $\partial^2 \phi_j / \partial t^2$. However, since this is a tedious procedure, LYNCH and GRAY (1980b) developed an alternate procedure, which is applicable to any isoparametric element. For any two-dimensional isoparametric element, let x and y represent the global coordinates and ξ and η represent the local coordinates. It is convenient to transform this element from the global domain (in which it may have an irregular shape) to the local domain in which it will always have the shape of a square (in the ξ, η) domain the basis functions depend only on ξ and η). Since the (ξ, η) space does not deform, a basis function $\phi(\xi, \eta)$ at a location (ξ_0, η_0) will not change with time. The corresponding location to (ξ_0, η_0) in the (x, y) domain, however, may change with time and it depends on the isoparametric transformation:

$$X(t) = \sum_{i=1}^N X_i(t) \phi_i(\xi, \eta)$$

From this at a given point (ξ, η) :

$$\frac{dX}{dt} = \sum_{i=1}^N \frac{dX_i}{dt} \phi_i(\xi, \eta) = \sum_{i=1}^N V_i(t) \phi_i(\xi, \eta) = V^e \tag{3.44}$$

Where V^e is the elemental velocity (i.e. the velocity with which the element is moving). In a reference frame, which is moving with the elemental velocity, there is no change in ϕ_i , and one can write

$$\frac{d\phi_i}{dt} = \frac{\partial \phi_i}{\partial t} + V^e \nabla \phi_i = 0 \tag{3.45}$$

Similarly, one can write

$$\frac{\partial^2 \phi_i}{\partial t^2} = - \left[\sum_{i=1}^N \frac{dV_i}{dt} \phi_j \right] \nabla \phi_i + 2V^e (\nabla V^e) \nabla \phi_i + V^e (\nabla \nabla \phi_i) V^e \tag{3.46}$$

LYNCH and GRAY (1979) showed that, for the shallow-water problem, rather than using the continuity equation in its ordinary form, a computationally superior way is to use the following wave equation, which can be derived form the momentum and continuity equations:

$$\frac{\partial^2 H}{\partial t^2} + \tau \frac{\partial H}{\partial t} = \nabla (g H \nabla \zeta) + H V (\nabla \tau) + \nabla [\nabla (H V V) + f X H V - w] \tag{3.47}$$

This has to be integrated in time together with the horizontal momentum equation

$$\frac{\partial \mathbf{V}}{\partial t} = -\mathbf{V} \nabla V - f \mathbf{X} \mathbf{V} - g \nabla \zeta - \boldsymbol{\tau} \mathbf{V} + \frac{\mathbf{W}}{H} \quad (3.48)$$

where, $H(\mathbf{X}, t)$ is the total depth, $\zeta(\mathbf{X}, t)$ is the free surface perturbation, $h(\mathbf{X})$ is the equilibrium water depth, $\mathbf{V}(\mathbf{X}, t)$ is the horizontal velocity vector (vertically averaged), f is the Coriolis parameter, g is gravity, and $\mathbf{W}(\mathbf{X}, t)$ is the wind stress. The bottom stress is written as

$$\boldsymbol{\tau} \mathbf{V}(\mathbf{X}, t) = \frac{g |\mathbf{V}| \mathbf{V}}{C^2 H} \quad (3.49)$$

where, $C(\mathbf{X}, t)$ is the Chezy coefficient.

The boundary condition is

$$H = 0 \text{ on } \mathbf{X} = \mathbf{X}_0 + \int_0^t \mathbf{V} dt \quad (3.50)$$

Where $\mathbf{X}(t)$ is the location of the boundary at time t , \mathbf{X}_0 is the initial time position of the boundary, \mathbf{V} is the velocity of the boundary, and \mathbf{v} is the velocity of the fluid.

Solutions of eq. (3.47) and (3.48) can be written in the finite-element form as follows:

$$\begin{aligned} H(\mathbf{X}, t) &\sim \sum_{j=1}^N H_j(t) \phi_j(\mathbf{X}, t) \\ \mathbf{V}(\mathbf{X}, t) &\sim \sum_{j=1}^N \mathbf{V}_j(t) \phi_j(\mathbf{X}, t) \\ \boldsymbol{\tau}(\mathbf{X}, t) &\sim \sum_{j=1}^N \boldsymbol{\tau}_j(t) \phi_j(\mathbf{X}, t) \end{aligned} \quad (3.51)$$

Substituting eq. (3.51) into eq. (3.47) and (3.48) and equating the weighted residuals to zero gives the following set of ordinary differential equations:

$$\begin{aligned} \sum_{j=1}^N \left(\frac{d^2 H_j}{dt^2} \langle \phi_j, \phi_i \rangle + 2 \frac{d H_j}{dt} \left\langle \frac{\partial \phi_j}{\partial t}, \phi_i \right\rangle + H_j \left\langle \frac{\partial^2 \phi_j}{\partial t^2}, \phi_i \right\rangle \right. \\ \left. + \frac{d H_j}{dt} \langle \boldsymbol{\tau} \phi_j, \phi_i \rangle + H_j \left\langle \pi \frac{\partial \phi_j}{\partial t}, \phi_i \right\rangle \right) = \langle \mathbf{R}_w, \phi_i \rangle \end{aligned} \quad (3.52)$$

and

$$\sum_{j=1}^N \left(\frac{d \mathbf{V}_j}{dt} \langle \phi_j, \phi_i \rangle + \mathbf{V}_j \left\langle \frac{\partial \phi_j}{\partial t}, \phi_i \right\rangle \right) = \langle \mathbf{R}_M, \phi_i \rangle, i = 1, \dots, N \quad (3.53)$$

Here $\mathbf{R}_w(\mathbf{X}, t)$ and $\mathbf{R}_M(\mathbf{x}, t)$ are the right sides of eq. (3.47) and (3.48), respectively.

For the time derivative terms, a standard three-level finite-difference scheme has been used. For a stationary grid and one-dimensional case the C-F-L stability criterion reduces to

$$gH\left(\frac{\Delta t}{\Delta x}\right)^2 \leq \frac{1}{3} \tag{3.54}$$

The boundary condition $v = v$ (i. e. fluid velocity equals the velocity of boundary movement) may lead to significant shearing of the boundary elements. To avoid this, LYNCH and GRAY (1980b) satisfied the mass conservation by requiring that

$$H = 0 \quad \text{or} \quad X = X_0 + \int_0^t V \, dt \quad (V - v)n = 0 \tag{3.55}$$

Where n is a unit vector normal to the boundary. Rather than attempting to satisfy this relation at every boundary grid point, one can satisfy it in an average sense by requiring that

$$\int_S (V - v)ndS = 0 \tag{3.56}$$

Using the finite-element solution forms for V and v :

$$V \sim \sum_i V_i \phi_i \tag{3.57}$$

$$v \sim \sum_i v_i \phi_i$$

Substituting eq. 3.57 into 3.56 gives

$$\sum_i \int_S (V_i - v_i)n\phi_i \, dS = 0 \tag{3.58}$$

To obtain an expression for the local normal direction that each term of eq. (3.58) be zero, i.e.:

$$(V_i - v_i) \int_S n\phi_i \, dS = 0 \tag{3.59}$$

From this one can define the modal normal direction, n_i , as follows:

$$n_i \equiv \frac{\int_S n\phi_i \, dS}{\left| \int_S n\phi_i \, dS \right|} \tag{3.60}$$

where, node i represent the junction of two moving segments of the boundary. Using the divergence theorem:

$$\int_S n\phi_i \, dS = \iint_A \nabla \phi_i \, dA \tag{3.61}$$

where, A is the total domain. The moving boundary condition becomes, finally,

$$H_i = 0 \quad \text{on} \quad X_i = X_{i,0} + \int_0^t V_i dt, \quad (V_i - v_i)n_i = 0 \quad (3.62)$$

$$V_i \lambda_i = 0$$

where, i represent all moving boundary nodes. Here, is the tangential direction at node λ_i . The second relation in eq. (3.62) is invoked to reduce element shearing.

A typical time step proceeds as follows.

- 1) Using eq. (3.60) and based on the existing grid, the nodal normal directions are determined.
- 2) The nodal velocities at the boundary are determined eq. (3.62). The locations of the nodes are calculated from the following finite-difference from of the first relation in eq. (3.62).

$$X_{i,t+\Delta t} \sim X_{i,t-\Delta t} + 2\Delta t V_{i,t} \quad (3.63)$$

- 3) The term dV_i/dt (which is required to evaluate $\partial^2 \phi / \partial t^2$ is calculated from

$$\frac{dV_i}{dt} = \frac{d^2 X_i}{dt^2} \sim \frac{X_{i,t+\Delta t} - 2X_{i,t} + X_{i,t-\Delta t}}{(\Delta t)^2} \quad (3.64)$$

- 4) From eq. (3.52) and (3.53) H_i and V_i are calculated at $t + \Delta t$. Then steps are repeated by beginning with the determination of the nodal normals.

3.4 The Corps of Engineers Models

In a series of reports and papers (BLAIN, 1997; CIALONE, 1991; LUETTICH et al., 1991, 1992; MARK and SCHEFFNER, 1993; SCHEFFNER et al., 1994; WESTERINK et al., 1992, 1993a, 1993b) the so-called “ADCIRC” model of the U.S. Army Corps of Engineers has been described. The following material is based on (WESTERINK et al., 1993b). “ADCIRC” stands for “An advanced three-dimensional circulation model for shelves, coasts and estuaries”. The ADCIRC – 2DDI is a depth-integrated option of a system of two and three-dimensional hydrodynamic codes of “ADCIRC”.

ADCIRC – 2DDI uses the depth-integrated equations of mass and momentum conservation, subject to the incompressibility, Boussinesq, and hydrostatic pressure approximations. Using the standard quadratic parameterization for bottom stress and neglecting baroclinic terms and lateral diffusion/dispersion effects leads to the following set of conservation statements in primitive non-conservative form expressed in a spherical coordinate system (FLATHER, 1988; KOLAR et al., 1994):

$$\frac{\partial \zeta}{\partial t} + \frac{1}{R \cos \varphi} \left[\frac{\partial UH}{\partial \lambda} + \frac{\partial (VH \cos \varphi)}{\partial \varphi} \right] = 0 \quad (3.65)$$

$$\frac{\partial U}{\partial t} + \frac{1}{R \cos \varphi} U \frac{\partial U}{\partial \lambda} + \frac{1}{R} V \frac{\partial U}{\partial \varphi} - \left(\frac{\tan \varphi}{R} U + f \right) V =$$

$$- \frac{1}{R \cos \varphi} \frac{\partial}{\partial \lambda} \left[\frac{p_s}{\rho_0} + g(\zeta - \eta) \right] + \frac{\tau_{s\lambda}}{\rho_0 H} + \tau_* U \quad (3.66)$$

$$\frac{\partial V}{\partial t} + \frac{1}{R \cos \varphi} U \frac{\partial V}{\partial \lambda} + \frac{1}{R} V \frac{\partial V}{\partial \varphi} + \left(\frac{\tan \varphi}{R} U + f \right) U = -\frac{1}{R} \frac{\partial}{\partial \varphi} \left[\frac{p_s}{\rho_0} + g(\zeta - \eta) \right] + \frac{\tau_{s\varphi}}{\rho_0 H} - \tau_* V \quad (3.67)$$

where

t = time

λ, φ = degrees longitude (east of Greenwich positive) and degrees latitude (north of the equator positive)

ζ = free surface elevation relative to the geoid

U, V = depth-averaged horizontal velocities

R = radius of the earth

$H = \zeta + h$ = total water column

h = bathymetric depth relative to the geoid

$f = 2 \Omega \sin \varphi$ = Coriolis parameter

Ω = angular speed of the earth

p_s = atmospheric pressure at the free surface

g = acceleration due to gravity

η = effective Newtonian equilibrium tide potential

ρ_0 = reference density of water

$\tau_{s\lambda}, \tau_{s\varphi}$ = applied free surface stress

$$\tau_* = C_f \frac{(U^2 + V^2)^{1/2}}{H}$$

C_f = bottom friction coefficient

A practical expression for the effective Newtonian equilibrium tide potential as given by REID (1990) is:

$$\eta(\lambda, \varphi, t) = \sum_{n,j} \alpha_{jn} C_{jn} f_{jn}(t_0) L_j(\varphi) \cos \left[\frac{2\pi(t-t_0)}{T_{jn} + j\lambda + V_{jn}(t_0)} \right] \quad (3.68)$$

where

C_{jn} = constant characterizing the amplitude of tidal constituent n of species j

α_{jn} = effective earth elasticity factor for tidal constituent n of species j

f_{jn} = time-dependent nodal factor

V_{jn} = time-dependent astronomical argument

$j = 0, 1, 2$ = tidal species ($j = 0$, declinational; $j = 1$, diurnal; $j = 2$, semidiurnal)

$L_0 = 3 \sin^2 \varphi - 1$

$L_1 = \sin(2\varphi)$

$L_2 = \cos^2(\varphi)$

λ, φ = degrees longitude and latitude, respectively

t_0 = reference time

T_{jn} = period of constituent n of species j

Values for C_{jn} are presented by REID (1990). The value for the effective earth elasticity factor is typically taken as 0.69 for all tidal constituents (SCHWIDERSKI, 1980; HENDERSHOTT, 1981) although its value has been shown to be slightly constituent dependent.

To facilitate an FE solution to equations (3.65)–(3.67), these equations are mapped from spherical form into a rectilinear coordinate system using a Carte Parallelogrammitique (CP) projection (PEARSON, 1990):

$$x' = R (\lambda - \lambda_0) \cos \varphi_0 \quad (3.69)$$

$$y' = R \varphi \quad (3.70)$$

where, λ_0, φ_0 = center point of the projection. Applying the CP projection to equations (3.65)–(3.67) gives the shallow-water equations in primitive non-conservative form expressed in the CP coordinate system:

$$\frac{\partial \zeta}{\partial t} + \frac{\cos \varphi_0}{\cos \varphi} \frac{\partial (UH)}{\partial x'} + \frac{1}{\cos \varphi} \frac{\partial (VH \cos \varphi)}{\partial y'} = 0 \quad (3.71)$$

$$\begin{aligned} \frac{\partial U}{\partial t} + \frac{\cos \varphi_0}{\cos \varphi} U \frac{\partial U}{\partial x'} + V \frac{\partial U}{\partial y'} - \left(\frac{\tan \varphi}{R} U + f \right) V = \\ - \frac{\cos \varphi_0}{\cos \varphi} \frac{\partial}{\partial x'} \left[\frac{p_s}{\rho_0} + g(\zeta - \eta) \right] + \frac{\tau_{s\lambda}}{\rho_0 H} - \tau_* U \end{aligned} \quad (3.72)$$

$$\begin{aligned} \frac{\partial V}{\partial t} + \frac{\cos \varphi_0}{\cos \varphi} U \frac{\partial V}{\partial x'} + V \frac{\partial V}{\partial y'} - \left(\frac{\tan \varphi}{R} U + f \right) U = \\ - \frac{\partial}{\partial y'} \left[\frac{p_s}{\rho_0} + g(\zeta - \eta) \right] + \frac{\tau_{s\varphi}}{\rho_0 H} - \tau_* V \end{aligned} \quad (3.73)$$

Utilizing the FE method to resolve the spatial dependence in the shallow-water equations in their primitive form gives inaccurate solutions with severe artificial near 2. Δ However, reformulating the primitive equations into a GWCE (Generalized Wave Continuity Equation) form gives highly accurate, noise free, FE-based solutions to the shallow-water equations (LYNCH AND GRAY, 1979; KINNMARK, 1984). The GWCE is derived by combining a time-differentiated form of the primitive continuity equation and a spatially differentiated form of the primitive momentum equations recast into conservative form, reformulating the convective terms into non-conservative form and adding the primitive form of the continuity equation multiplied by a constant in time and space, τ_0 (LYNCH and GRAY, 1979; LUETTICH et al., 1992). The GWCE in the CP coordinate system is:

$$\begin{aligned}
& \frac{\partial^2 \zeta}{\partial t^2} + \tau_0 \frac{\partial \zeta}{\partial t} + \frac{\cos \varphi_0}{\cos \varphi} \frac{\partial}{\partial x'} \frac{\partial \zeta}{\partial t} \\
& \left\{ U - \frac{\cos \varphi_0}{\cos \varphi} U_H \frac{\partial U}{\partial x'} - V_H \frac{\partial U}{\partial y'} + \left(\frac{\tan \varphi}{R} U + f \right) V_H - \right. \\
& \left. H \frac{\cos \varphi_0}{\cos \varphi} \frac{\partial}{\partial x'} \left[\frac{p_s}{\rho_0} + g(\zeta - \eta) \right] - (\tau_* - \tau_0) U_H + \frac{\tau_s \lambda}{\rho_0} \right\} \\
& + \frac{\partial}{\partial y'} \left\{ V \frac{\partial \zeta}{\partial t} - \frac{\cos \varphi_0}{\cos \varphi} U_H \frac{\partial V}{\partial x'} - V_H \frac{\partial V}{\partial y'} - \right. \\
& \left. \left(\frac{\tan \varphi}{R} U + f \right) U_H - \right. \\
& \left. H \frac{\partial}{\partial y'} \left[\frac{p_s}{\rho_0} + g(\zeta - \eta) \right] - (\tau_* - \tau_0) V_H + \frac{\tau_s \varphi}{\rho_0} \right\} \\
& - \frac{\partial}{\partial t} \left(\frac{\tan \varphi}{R} V_H \right) + -\tau_0 \left(\frac{\tan \varphi}{R} V_H \right) = 0
\end{aligned} \tag{3.74}$$

The GWCE (equation 3.74) is solved in conjunction with the primitive momentum equations in non-conservative form (equations 3.72 and 3.73).

The high accuracy of GWCE-based FE solutions is a result of their excellent numerical amplitude and phase propagation characteristics. In fact, Fourier analysis indicates that in constant depth water and using linear interpolation, a linear tidal wave resolved with 25 nodes per wavelength is more than adequately resolved over the range of Courant numbers ($C \equiv \sqrt{gh} \Delta t / \Delta x \leq 1.0$ (LUETTICH et al., 1992)). Furthermore, the monotonic dispersion behavior of GWCE-based FE solutions avoids generating artificial near 2. Δx modes, which plague primitive-based FE solutions (PLATZMAN, 1981; FOREMAN, 1983). The monotonic dispersion behavior of GWCE-based FE solutions are very similar to that associated with staggered finite difference solutions to the primitive shallow-water equations (WESTERINK and GRAY, 1991). GWCE-based FE solutions to the shallow-water equations allow for extremely flexible spatial discretizations, which result in a highly effective minimization of the discrete size of any problem, (FOREMAN, 1988).

The details of ADCIRC, the implementation of the GWCE-based solution to the shallow-water equations, are described by LUETTICH et al. (1992). As most GWCE-based FE codes, ADCIRC applies three-noded linear triangles for surface elevation, velocity and depth. Furthermore, the decoupling of the time and space discrete form of the GWCE and momentum equations, time-independent and/or tri-diagonal system matrices, elimination of spatial integration procedures during time-stepping, and full vectorization of all major loops results in a highly efficient code.

SCHEFFNER et al. (1994) used ADCIRC to simulate storm surges from hurricanes on the Gulf of Mexico and east coasts of U. S. A. Fig. 3.2 shows the finite element grid used in these simulations.

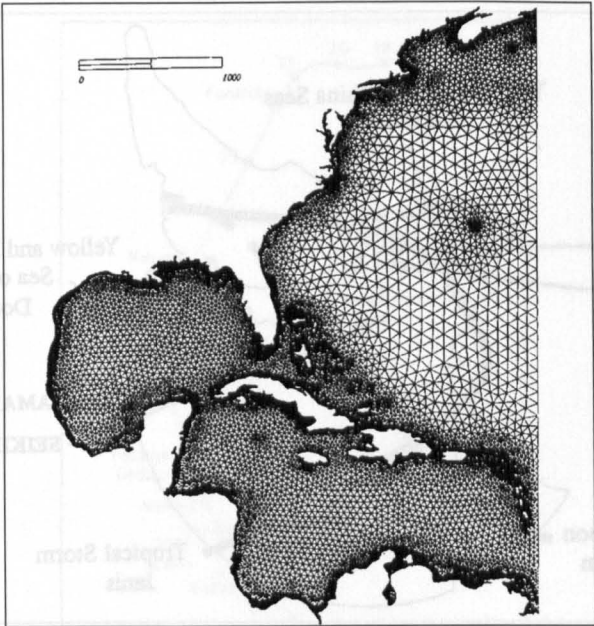


Fig. 3.2: The east coast, Gulf of Mexico, and Caribbean Sea computational domain. (SCHEFFNET et al., 1994).

BLAIN (1997) simulated hurricane generated storm surges on the coast of Florida and also for the coast of Northeast Asia. These model domains are respectively shown in Fig. 3.3 and 3.4.

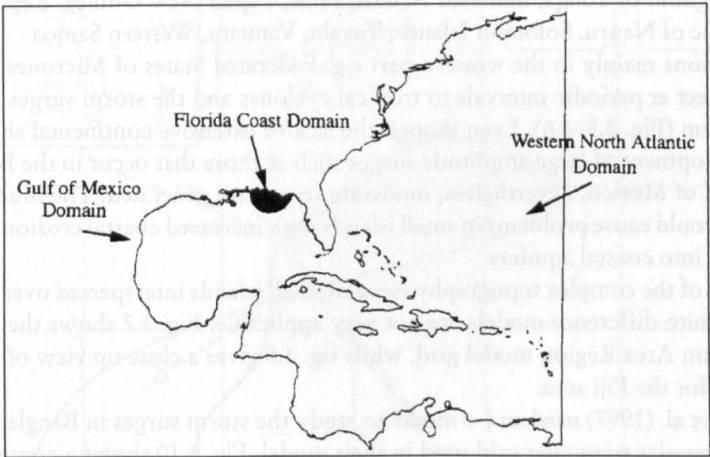


Fig. 3.3: Three domain sizes evaluated in the prediction of storm surge on the US Florida coast from hurricane Kate, 1985. (BLAIN, 1997).

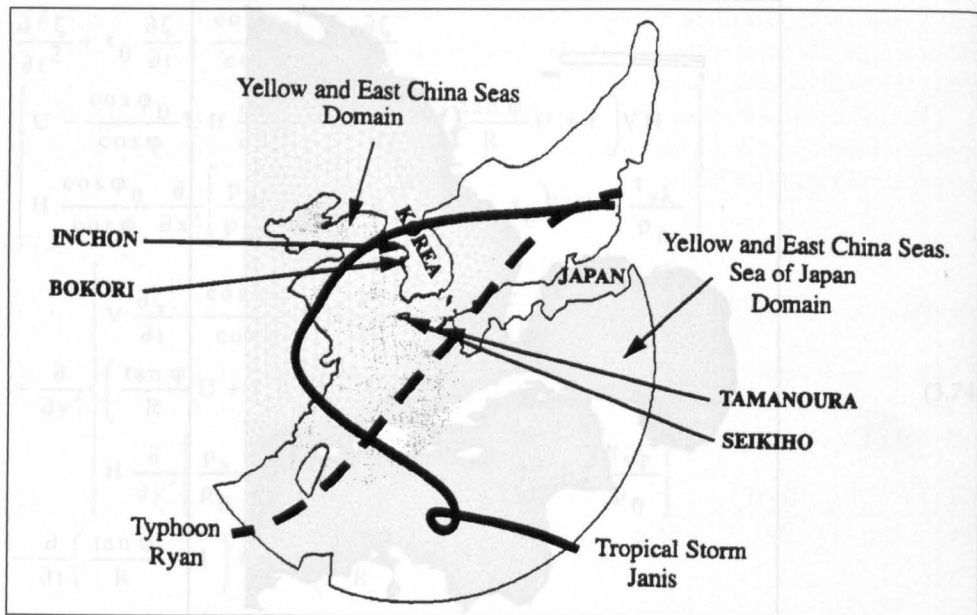


Fig. 3.4: Two domain sizes for the Yellow and East China Seas region, together with the paths of tropical storm Janis (August, 1995) and typhoon Ryan (September, 1995) and four hydrograph station locations. (BLAIN, 1997)

3.5 Other f-e Models

LUICK et al. (1997) studied storm surges in the Pacific forum region. The South Pacific region consists of the following island nations: Cook Islands, Federated States of Micronesia, Fiji, Kingdom of Tonga, Marshall Islands, Niue, Papua New Guinea, Republic of Kiribati, Republic of Nauru, Solomon Islands, Tuvalu, Vanuatu, Western Samoa.

The nations mainly in the western part e.g. Federated States of Micronesia (FSM) and Fiji, are subject at periodic intervals to tropical cyclones and the storm surges that are produced by them (Fig. 3.5–3.6). Even though the lack of extensive continental shelves precludes the development of large amplitude surges such as those that occur in the Bay of Bengal and the Gulf of Mexico, nevertheless, moderate surges are generated. The inundation from such surges could cause problems in small islands with increased coastal erosion and salt-water intrusion into coastal aquifers.

Because of the complex topography (several small islands interspersed over a large area), traditional finite-difference models are not very applicable. Fig. 3.7 shows the irregular triangular Forum Area Region model grid, while fig. 3.8 gives a close up view of irregular triangular grid for the Fiji area.

HENRY et al. (1997) used an f-e model to study the storm surges in Bangladesh. Fig. 3.9 shows the irregular triangular grid used in their model. Fig. 3.10 shows a zoom-in-view for the Meghna Estuary region. Fig. 3.11 and 3.12 respectively compare the computed and observed surges at Cox's Bazaar, Khepupara (April 1991 event). The discrepancies between the observed and computed surges could be mostly attributed to deficiencies in the prescribed meteorological input data.

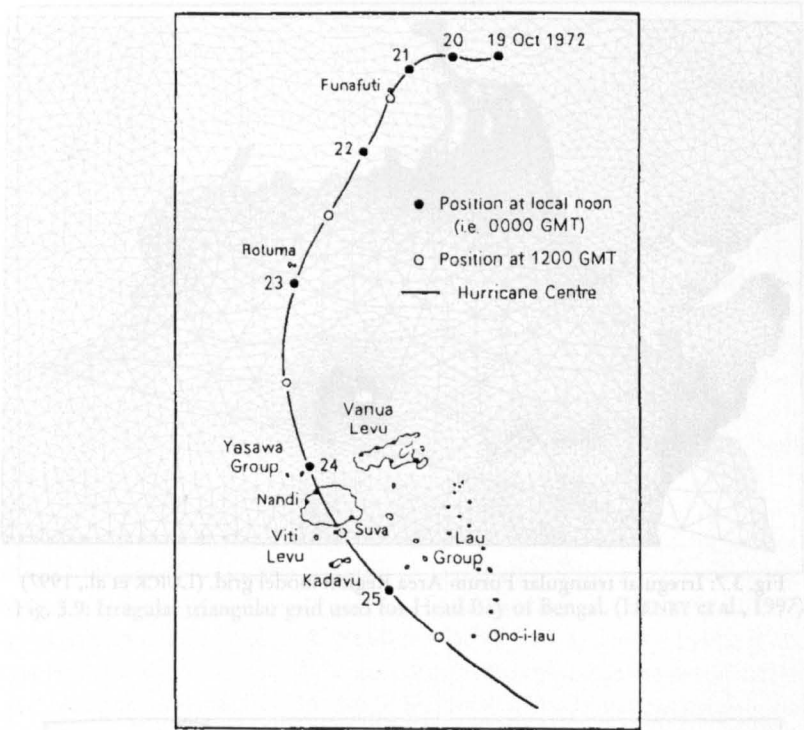


Fig. 3.5: Track of Hurricane Bebe October 1972 (from New Zealand Meteorological Service)

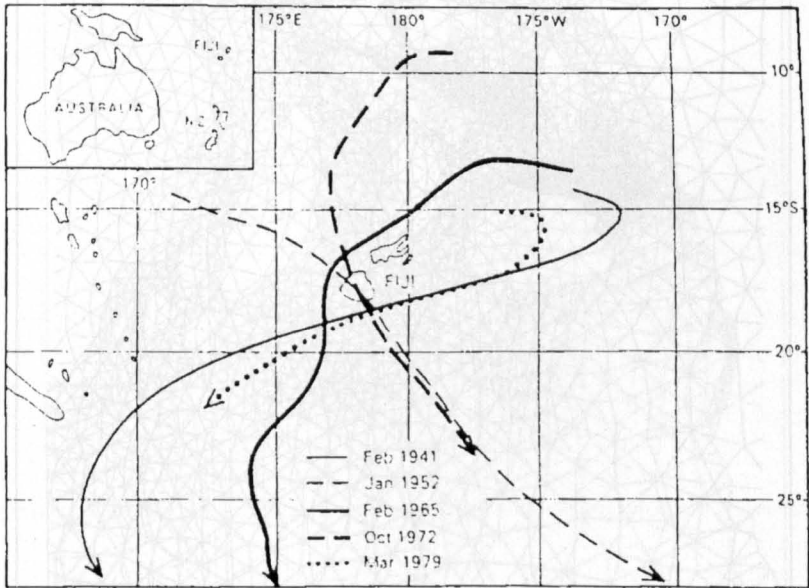


Fig. 3.6: Tracks of severe Hurricanes in Fiji area between 1940 and 1979 (from Fiji Meteorological Service)

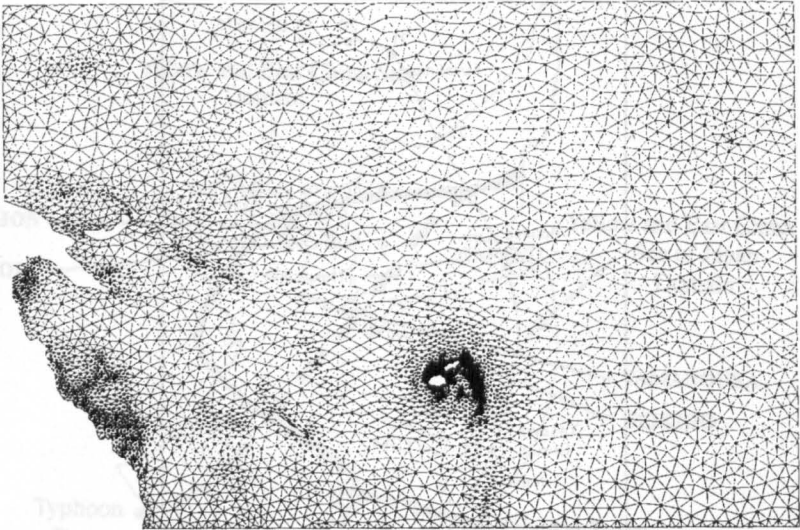


Fig. 3.7: Irregular triangular Forum Area Region model grid. (LUICK et al., 1997)

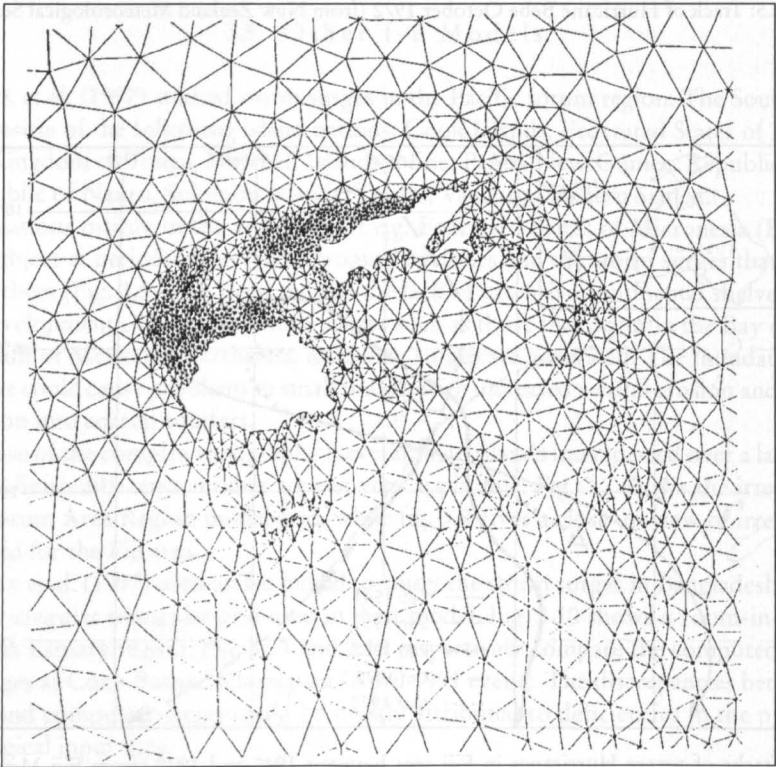


Fig. 3.8: Close up view of irregular triangular grid for the Fiji area. (LUICK et al., 1997)

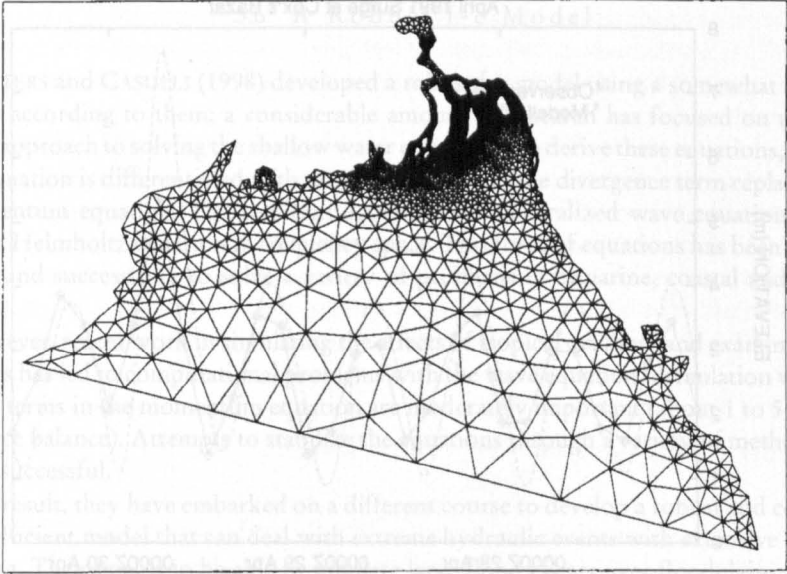


Fig. 3.9: Irregular triangular grid used for Head Bay of Bengal. (HENRY et al., 1997)

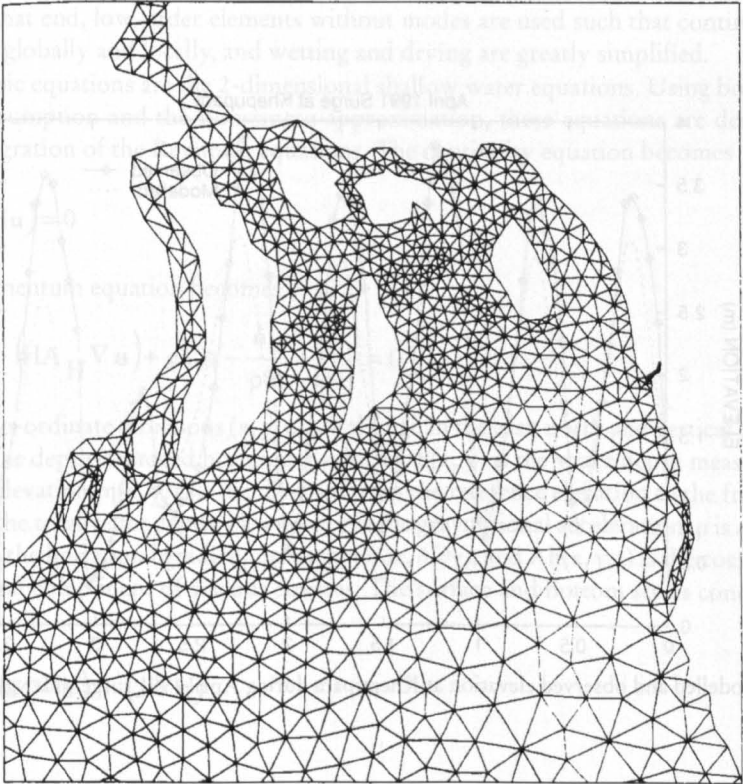


Fig. 3.10: Close up of part of grid covering Meghna Estuary. (HENRY et al., 1997)

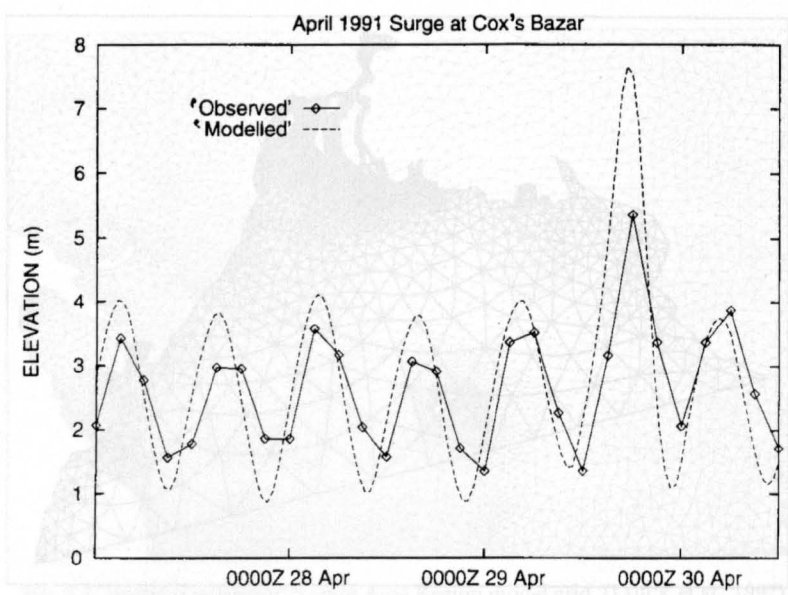


Fig. 3.11: Modelled and observed elevation at Cox's Bazaar during April 1991 surge. (HENRY et al., 1997)

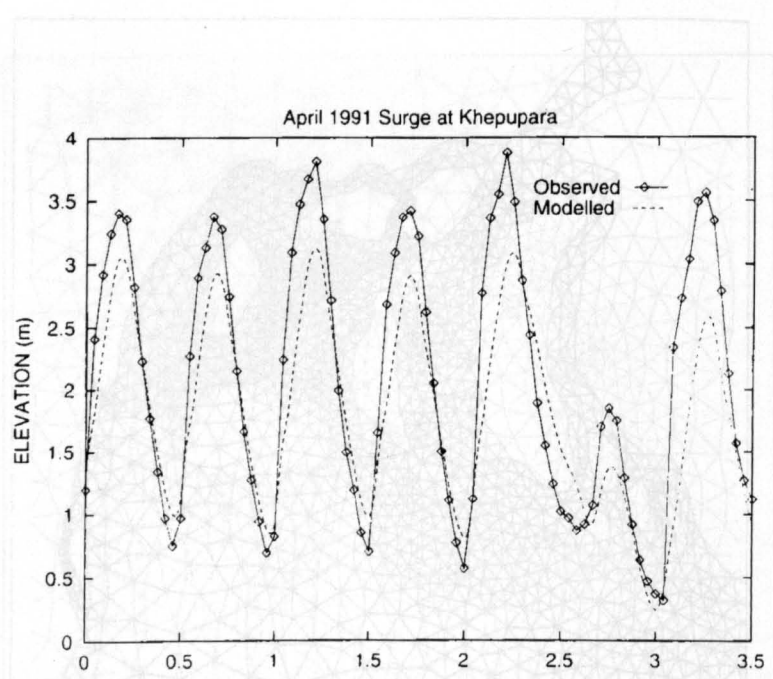


Fig. 3.12: Modelled and observed elevation at Khepupara during April 1991 surge. (HENRY et al., 1997)

3.6 A Robust f-e Model

WALTERS and CASULLI (1998) developed a robust f-e model using a somewhat different approach according to them; a considerable amount of research has focused on the wave equation approach to solving the shallow water equations. To derive these equations, the continuity equation is differentiated with respect to time, and the divergence term replaced with the momentum equation. The resultant equations are generalized wave equation in time space or a Helmholtz equation in frequency space. This form of equations has been used extensively and successfully to solve a variety of problems in estuarine, coastal and oceanic flows.

However, recent work in simulating the effects of tropical cyclones and examining river hydraulics has led to computational problems with the wave equation formulation when the advective terms in the momentum equation are moderately important (about 1 to 5 per cent of the force balance). Attempts to stabilize the equations through a variety of methods have not been successful.

As a result, they have embarked on a different course to develop a robust and computationally efficient model that can deal with extreme hydraulic events with extensive flooding and drying. Their goal is to be able to simulate large flood events over floodplains of variable extent.

The method adopted here is to use the primitive shallow water equations and form a wave equation at the discrete level. This procedure carries through the properties of the original discretized equations so that the use of elements without computational modes is essential. To that end, low-order elements without modes are used such that continuity is satisfied both globally and locally, and wetting and drying are greatly simplified.

The basic equations are the 2-dimensional shallow water equations. Using both the hydrostatic assumption and the Boussinesq approximation, these equations are derived by a vertical integration of the Reynolds equations. The continuity equation becomes

$$\frac{\partial \eta}{\partial t} + \nabla \cdot (H \mathbf{u}) = 0 \quad (3.75)$$

and the momentum equation becomes

$$\frac{d \mathbf{u}}{dt} - \frac{1}{H} \nabla \cdot (H A_H \nabla \mathbf{u}) + g \nabla \eta - \frac{\hat{\sigma}_s}{\rho H} + \frac{\hat{\sigma}_b}{\rho H} = 0 \quad (3.76)$$

where, the co-ordinate directions (x, y, z) are aligned in the east, north and vertical directions; $\mathbf{u}(x, y, t)$ is the depth-averaged horizontal velocity; $h(x, y)$ is the water depth measured from a reference elevation; $\eta(x, y, t)$ is the distance from the reference elevation to the free surface; $H(x, y, t)$ is the total water depth, $H = \eta - h$; g is the gravitational acceleration; ρ is a reference density; ∇ is the horizontal gradient operator ($\partial/\partial x, \partial/\partial y$); and $A_h(x, y, t)$ is the coefficient for the horizontal component of viscous stresses. The surface and bottom stress conditions are given by

$$\frac{\hat{\sigma}_s}{\rho} = \gamma_T H (\mathbf{u}_a - \mathbf{u}) \quad (z = \eta) \quad (3.77)$$

$$\frac{\hat{\sigma}_b}{\rho} = C_D |\mathbf{u}| \mathbf{u} = \gamma_B H \mathbf{u} \quad (z = h) \quad (3.78)$$

where, the surface and bottom stress are denoted as τ_s and τ_b respectively, \mathbf{u}_a is the wind velocity, and C_D is a bottom drag coefficient. Essential boundary conditions on η or volumetric flux are set at open boundaries, and $(\mathbf{u} \cdot \hat{\mathbf{n}}) = 0$ (no normal flow, where $\hat{\mathbf{n}}$ is the unit normal) is set on land boundaries.

This study focuses on the solution for surface elevation in the two-dimensional, discrete wave equation form of the continuity equation and the solution for the horizontal velocity components in the momentum equation. The governing equations are approximated using standard Galerkin techniques. The equations are discretized after defining a set of 2-dimensional triangular elements in the horizontal plane. Mixed methods are used in such a way that the elements use a piecewise constant basis for η and a constant normal velocity on each edge.

The continuity equation (3.75) can be expressed in weighted residual form as: find $\eta \in S$ such that

$$\int_{\Omega} \hat{\eta} \frac{\partial \eta}{\partial t} d\Omega + \int_{\Omega} \hat{\eta} \nabla \cdot (\mathbf{H} \mathbf{u}) d\Omega = 0, \quad \forall \hat{\eta} \in S \quad (3.79)$$

Here S is the space of square integrable functions and Ω is the flow domain. Expanding η , $\hat{\eta}$ in terms of the finite basis ϕ and numerically integrating produces an algebraic problem for the nodal unknowns.

The weak form of momentum equation can be given as: find $\mathbf{u} \in U$ such that

$$\int_{\Omega} \hat{\mathbf{u}} \left[\frac{d\mathbf{u}}{dt} + \gamma_B \mathbf{u} - \gamma_T (\mathbf{u}_a - \mathbf{u}) - \nabla \cdot (\mathbf{A}_h \nabla \mathbf{u}) \right] d\Omega = - \int_{\Omega} \hat{\mathbf{u}} g \nabla \eta d\Omega, \quad \forall \hat{\mathbf{u}} \in U \quad (3.80)$$

where, the equation is interpreted component-wise and U is the space of vector functions that have a divergence. Note that the term $(\nabla H/H)(\mathbf{A}_h \nabla \mathbf{u})$ arising from the expansion of the horizontal viscous stress term has been neglected. Expanding \mathbf{u} , $\hat{\mathbf{u}}$ in terms of the finite element basis ϕ again produces an algebraic problem for the nodal unknowns. The surface pressure gradient term and the horizontal stress term are integrated by parts to give

$$\begin{aligned} & \int_{\Omega} \hat{\mathbf{u}} \left[\frac{d\mathbf{u}}{dt} + \gamma_B \mathbf{u} - \gamma_T (\mathbf{u}_a - \mathbf{u}) \right] d\Omega + \int_{\Omega} \nabla \hat{\mathbf{u}} \cdot (\mathbf{A}_h \nabla \mathbf{u}) d\Omega \\ &= \int_{\Omega} g \nabla \hat{\mathbf{u}} \cdot \nabla \eta d\Omega - \oint_{\Gamma} [g(\hat{\mathbf{u}} \cdot \nabla \eta) - \hat{\mathbf{u}} \cdot \nabla \mathbf{u} \cdot \hat{\mathbf{n}}] d\Gamma \end{aligned} \quad (3.81)$$

where, Γ is the boundary of the flow domain Ω . The line integral in this equation provides a convenient means to specify the boundary conditions on η and horizontal stress.

These equations are discretized in time using a semi-implicit method such that the equations are evaluated in the time interval (τ^m, τ^{m+1}) , where the superscript denotes the time level. The distance through the interval is given by the weight θ . The semi-implicit approach is given as

$$\frac{\eta^{m+1} - \eta^m}{\Delta t} + \nabla \cdot \left[\mathbf{H}^m \left(\theta \mathbf{u}^{m+1} + (1-\theta) \mathbf{u}^m \right) \right] = 0 \quad (3.82)$$

$$\frac{\mathbf{u}^{m+1} - \mathbf{u}^*}{\Delta t} + \theta \mathbf{G}^{m+1} + (1-\theta) \mathbf{G}^* = \mathbf{F}^* \quad (3.83)$$

$$\mathbf{G} = \gamma_B \mathbf{u} - \gamma_T (\mathbf{u}_a - \mathbf{u}) + g \nabla \eta \tag{3.84}$$

$$\mathbf{F}^* = \nabla \cdot (\mathbf{A}_h \nabla \mathbf{u})^* \tag{3.85}$$

Semi-Lagrangian methods are used in order to take advantage of the simplicity of Eulerian methods and the enhanced stability and accuracy of Lagrangian methods. Here the superscripts m and $m+1$ denote variables evaluated at the fixed nodes in the Eulerian grid at times t^m and t^{m+1} . The subscript $*$ denotes a variable evaluated at time t^m at the end of the Lagrangian trajectory from a computational node (see Fig. 3.13). At each time step, the velocity is integrated backwards with respect to time to determine where a particle would be at time t^m to arrive at a grid node at time t^{m+1} . The material derivative in equation (3.83), the first term, thus has a very simple form.

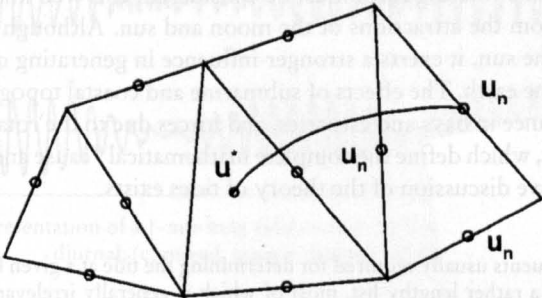


Fig. 3.13: Definition of the elements used and the Lagrangian trajectories. At time t^m , a particle starts at the location where velocity is u^* , and arrives at a node in the grid at time t^{m+1} . (WALTERS AND CASULLI, 1998)

There are three test problems studied (i) a simulation of tides in a polar quadrant region that indicates that there are no computational nodes; (ii) a simulation of tides in a regular channel with sloping bottom that provides an assessment of accuracy and convergence rate; and (iii) a simulation of a flood on the Big Lost River, Idaho, that assesses performance in a highly irregular but realistic geometry. The results look quite satisfactory.

KAWAHARA et al. (1982, 1983) used multi-level f-e models including stratification. Such models will be useful for the computation of currents associated with storm surges.

4. Special Hydrodynamic Problems

4.1 Tides

Tide is the rise and fall of the sea surface due to gravitational forces. To following material based on LEBLOND and MYSAK (1978) and GODIN (1972, 1980a, 1980b, 1988, 1991, 1996), IHP-OHP (1987, 1991), DEAN (1966), DIETRICH et al. (1975), DEFANT (1961).

An extremely useful qualitative description of some tidal phenomena is obtained by considering the equilibrium shape that a layer of water on a spherical earth would assume under the action of a tide-producing body. This is the "Equilibrium Theory of Tides", presented by Darwin in 1898 and describing the tides as those water fluctuations apparent to an observer traversing along a constant latitude line through the stationary and deformed water layer.

To describe the tides in a more realistic manner, dynamic aspects of the tidal waves in the oceanic basins and on a rotating earth must be considered. It is well known that the oceanic tides arise mainly from the attractions of the moon and sun. Although the moon is a much smaller body than the sun, it exerts a stronger influence in generating oceanic tides because of its proximity to the earth. The effects of submarine and coastal topography in altering the tidal features, resonance in bays and estuaries, and forces due to the rotating earth all contribute to tidal features, which define the complete mathematical "cause and effect" description. Therefore an extensive discussion of the theory of tides exists.

Table 4.1: Tidal constituents usually required for determining the tide at a given location. Note that this is only a small part of a rather lengthy list, most of which is generally irrelevant for storm surge-tide interaction purposes

Nature of constituent	Symbol for constituent	Frequency (degrees.h ⁻¹)	Period (h)
Semidiurnal	M ₂	28.98	12.42
Semidiurnal	N ₂	28.44	12.66
Semidiurnal	S ₂	30.00	12.00
Semidiurnal	K ₂	30.08	11.97
Diurnal	O ₁	13.94	25.82
Diurnal	K ₁	15.04	23.94
Diurnal	P ₁	14.96	24.06

Following GODIN (1980a, 1980b), the vertical component z (t) of the tide is defined as follows:

$$z(t) = z_0 + \sum_{j=1}^n A_j \cos(\sigma_j t - a_j) \tag{4.1}$$

where, z₀ is a constant that denotes the reference level, which is chosen such that the observed water level rarely, if ever, falls below z₀, and the other term on the right is a summation of n constituents of amplitude A_j, frequency σ_j, and phase a_j where j varies from 1 to n. Note that the frequencies y_j of the constituents are the same for any tidal record (for the same constituent); however, the amplitude and phase of the constituent might vary from one tidal station to another. Through a harmonic analysis of the observed tidal record, one can determine the amplitudes and phases of the various tidal constituents. In principle, the total number of

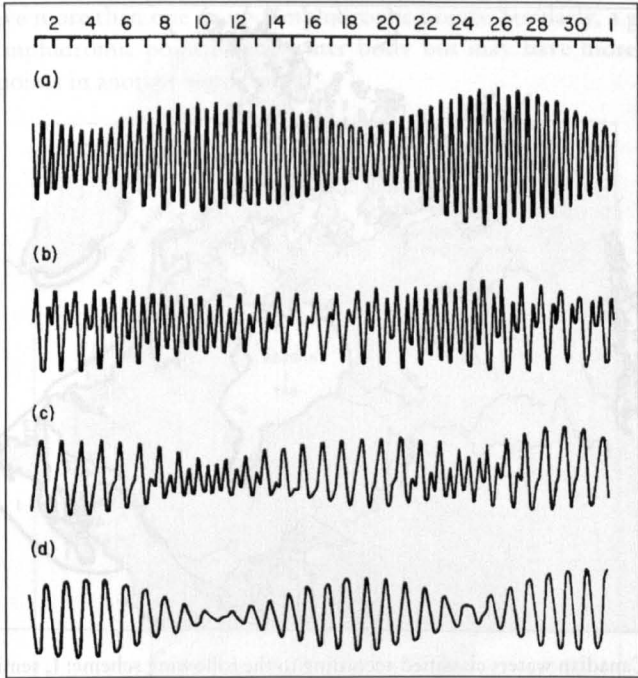


Fig. 4.1: Schematic representation of a 1-mo-long tidal record. (a) Semidiurnal; (b) mixed, mainly semi-diurnal; (c) mixed, mainly diurnal; (d) diurnal

constituents could be as high as 500, but rarely must one use more than a dozen or so of the important constituents in representing a tidal record.

As described above, the tide is the rise and fall of the sea's surface. The flowing to and fro is called tidal current. The tide is a wave period of about 12.4 hours, the semi-diurnal tide, or of about 24.8 hours (diurnal tide) or of varying periods (mixed tides). The most important of the semidiurnal and diurnal tidal constituents that are needed in representing an observed tidal record are listed in Table 4.1.

In practical tidal studies, it was found convenient to classify the tides into these four types: semidiurnal, mixed-mainly semidiurnal, mixed-mainly diurnal, and diurnal. A tide is referred to as semidiurnal if there are two high waters and two low waters daily of roughly the same amplitude (Fig. 4.1a). Mixed tides of the mainly semidiurnal type have two high waters and two low waters with the amplitudes being unequal (Fig. 4.1b). Mixed tides of the mainly diurnal type are said to exist if at times there is only one high water and one low water per day and at other times there are two large inequalities (Fig. 4.1c). For diurnal tides, there is one high water and one low water per day (Fig. 4.1d).

Three examples will be shown with this classification. First DOHLERS (1967) has classified the Canadian waters according to this scheme in Fig. 4.2, second EASTON (1970) for Australia (Fig. 4.3) and third PRIDA (1990, personal communication, quotation from IHP-OHP-BERICHT 1991) (Fig. 4.4).

A cotidal chart is a convenient way of presenting tidal information for each tidal constituent separately. Two sets of lines exist on a cotidal chart. Corange (coamplitude) lines represent contours of the range (amplitude) of the constituent, whereas cophase lines represent the contours of equal phase (usually with reference to Greenwich, expressed in degrees per

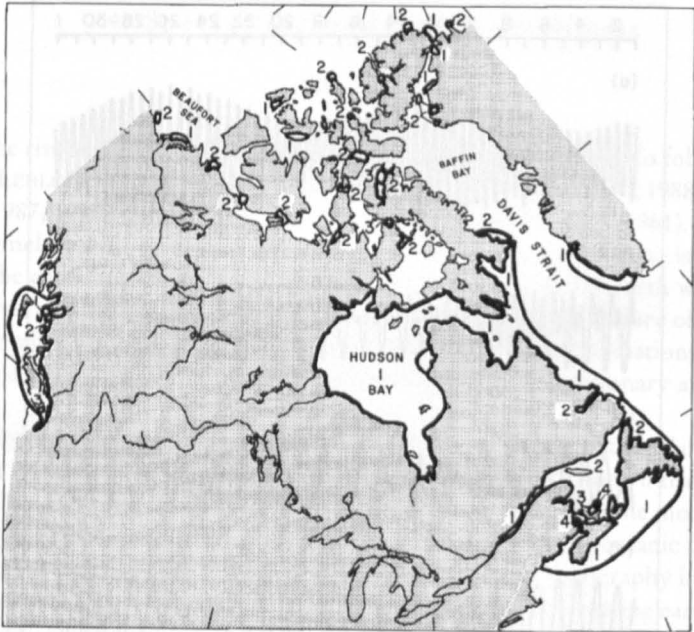


Fig. 4.2: Tides in Canadian waters classified according to the following scheme: 1, semidiurnal; 2, mixed, mainly semidiurnal; 3, mixed, mainly diurnal; 4, diurnal. (DOHLER, 1967)

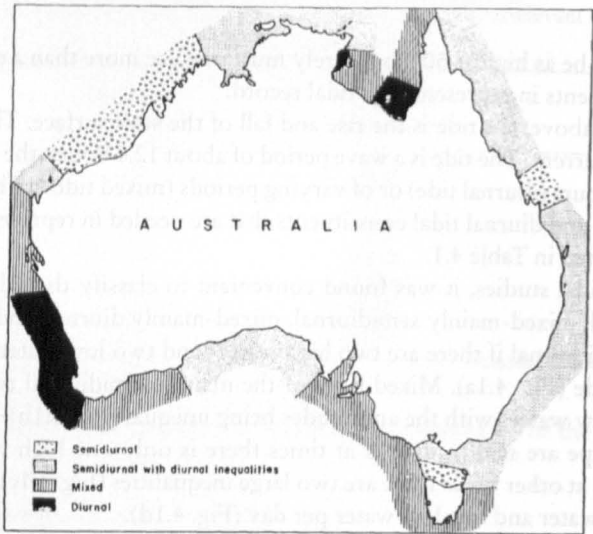


Fig 4.3: Tidal types along the Australian coast (EASTON, 1970)

hour). Amphidromic points, which appear for certain constituents in water bodies, are the locations where the range (amplitude) of the particular constituent is zero. Thus, it is basically a node for the vertical motion, the nodal line becoming just a point either due to the presence of transverse motion or due to the influence of the earth's rotation (GEORGE, 1980). In a water body, one tidal constituent may have an Amphidromic point, whereas another con-

stituent may have more than one or no Amphidromic points. Similarly, a given constituent may have an Amphidromic point in one water body but may have more than one or no Amphidromic points in another water body.

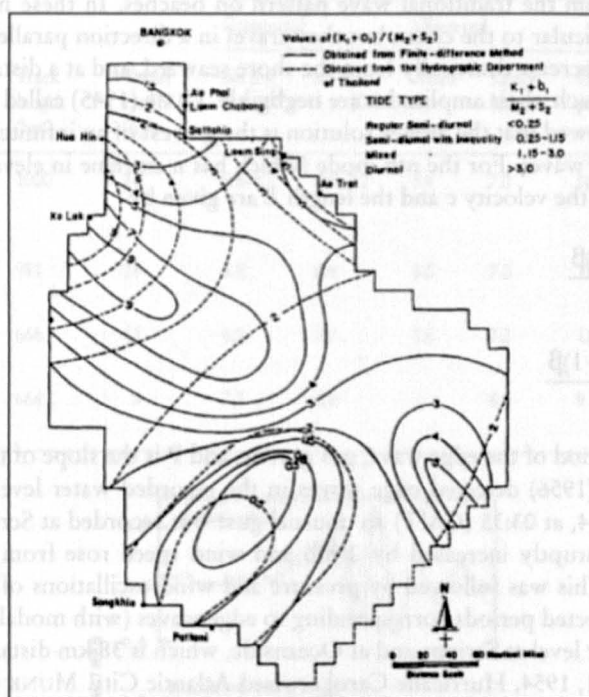


Fig. 4.4: Types of tide in the Gulf of Thailand (Prida, personal comment, quotation from IHP-OHP-BERICHT, 1991)

4.2 Resonance, Edge Waves

The topic of resonance, although relevant to storm surges, is so vast that it cannot be considered in detail here.

Any water body, such as a lake, inlet, bay, gulf, or a continental shelf, has natural modes of oscillation whose periods are determined by the geometry of the water body and the water depth. A knowledge of the natural modes of the water body is quite important in determining whether a given storm surge will be amplified or not and in determining the detailed characteristics of the surge in a particular water body for a given forcing.

For convenience, this section will be divided into three subsections: in the first subsection the theory of seiches will be described in some detail; in the second subsection the Helmholtz mode will be considered; in the final subsection the correct boundary conditions at the open part of the water body will be discussed.

Edge Waves and Their Role in Storm Surges

The literature on the topic of edge waves has grown enormously in recent times, and the reader is referred to LEBLOND and MYSAK (1978) and MURTY (1977) for a review. Here, edge

waves will be considered strictly for the role they play in storm surges; discussion will not deal with the general phenomenon of edge waves.

STOKES (1847) obtained solutions for wave motion over a sloping beach, these solutions being different from the traditional wave pattern on beaches. In these new solutions, the crests are perpendicular to the coast, but they travel in a direction parallel to the coast and their amplitudes decrease drastically from the shore seaward, and at a distance of one wavelength from the beach, their amplitudes are negligible. LAMB (1945) called them edge waves. URSELL (1952) showed that the Stokes solution is the gravest of an infinite number of possible modes of edge waves. For the n th mode (which has n extreme in elevation between the coast and the sea), the velocity c and the length L are given by

$$c = \frac{gT \sin(2n+1)\beta}{2\pi} \quad (4.2)$$

$$L = \frac{gT^2 \sin(2n+1)\beta}{2\pi} \quad (4.3)$$

where, T is the period of the edge wave, g is gravity, and P is the slope of the beach.

MUNK et al. (1956) detected edge waves in the recorded water levels at Scripps Pier. On January 6, 1954, at 03:35 (GMT) an unusual gust was recorded at Scripps Pier. Atmospheric pressure abruptly increased by 2 mb and wind speed rose from 3 to 14 mi. h⁻¹ (4.8-22 km.h⁻¹). This was followed by pressure and wind oscillations of an 8-min period. These authors detected periods corresponding to edge waves (with modal number $n = 1$) in the recorded water level at Scripps and at Oceanside, which is 38 km distant.

On August 31, 1954, Hurricane Carol crossed Atlantic City. MUNK et al. (1956) computed the edge wave modes at Atlantic City and Sandy Hook and compared the calculated periods with observed periods. The main result is that the edge wave periods are largely due to the gently sloping bottom. The longest edge wave period is associated with the fastest hurricane.

MUNK et al. (1956) also computed the edge wave modes for Osaka Bay, Japan, over which a storm passed on August 29, 1953. The bottom slope in Osaka Bay is about 15 times greater than that of the New Jersey coast. Hence, the periods of edge waves in Osaka Bay should be about 1/15 those on the New Jersey coast, and this result is supported by observations.

GREENSPAN (1970) did a theoretical study of edge waves in an exponentially stratified fluid. He showed that the first mode is completely insensitive to the density field. Stratification modifies the range of existence of higher modes.

On June 26, 1954, a squall line passed over the southern part of Lake Michigan and caused a surge on the Chicago waterfront. Several people were killed. This was explained by resonant coupling between the squall line and the resulting gravity waves generated in the lake (DONN and EWING, 1956). A resurgence (i.e. reflection of the waves from the eastern shore of the lake) explains its unexpected arrival at Chicago some 2 h after the squall line had passed.

On July 6-7, 1954, another squall line crossed Lake Michigan from north to south with an average speed of 50 mi. h⁻¹ (80.5 km. h⁻¹). Long-period waves were recorded at several locations following this squall line. DONN and EWING (1956) invoked edge waves to account for these water level disturbances. The time of arrival of the squall line and the magnitude of the pressure change at several stations are listed in Table 4.3, and the travel time curves of the

Table 4.2: Periods and durations of edge waves generated by four hurricanes. (MUNK et al., 1956)

Hurricane	Velocity <i>U</i> (km.h ⁻¹)	Track length (km)	Y	Travel time (h)	D	Wave period <i>T</i> (h)		Duration (h)				
						Computed		Observed		Observed		
						$\sin \beta = 5 \times 10^{-4}$	$\sin \beta = 5 \times 10^{-4}$	Atlan- tic City	Sandy Hook	Com- puted	Atlan- tic City	Sandy Hook
Aug. 30– Sept. 1 (Carol)	59–63	1000		24		5.8–6.1	6.9–7.2	5.5	7.0	16–24	20	26
Sept. 11–12, 1954 (Edna)	59	981		24		5.8	6.9	6.0	7.0	17–24	23	?
Sept. 14–15, 1944	61	666		12		6.0	7.1	5.6	7.2	11–12	23	30
Sept. 21–22, 1938	74	666		9		7.3	8.6	–	8.0	9	–	16

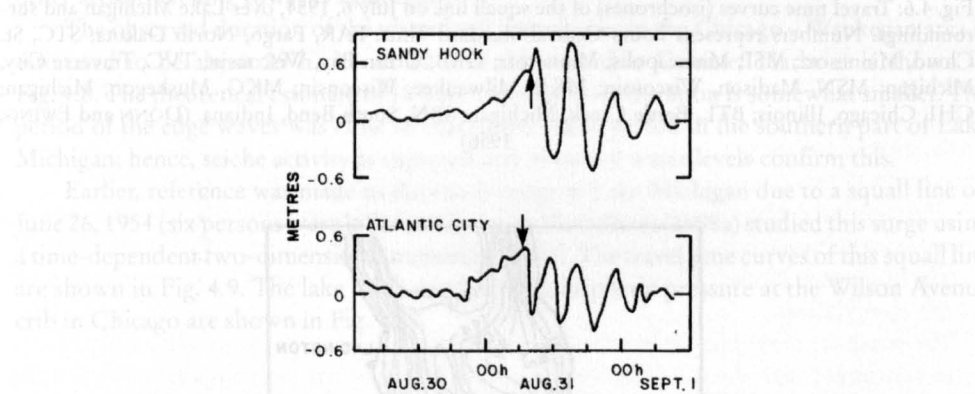


Fig. 4.5: Storm surges at Sandy Hook and Atlantic City, New Jersey, during Hurricane Carol of August 30–September 1, 1954. Arrows indicate the time of passage of the storm centre. (MUNK et al., 1956)

Table 4.3: Time of occurrence and pressure change for the squall line of July 6, 1954, in the United States. (DONN and EWING, 1956)

Station name	Station code	State	Time (CST) of occurrence of pressure change	Magnitude of Pressure change (mb)
Fargo	FAR	North Dakota	06:50	2.03
St. Cloud	STC	Minnesota	08:39	3.05
Minneapolis	MSP	Minnesota	09:54	2.37
Green Bay	GRB	Wisconsin	11:00	1.36
Traverse City	TVC	Michigan	12:30	0.68
Madison	MSN	Wisconsin	13:02	2.71
Milwaukee	MKE	Wisconsin	13:24	2.03
Muskegon	MKG	Michigan	14:00	1.36
Chicago	CHI	Illinois	15:30	3.39
Battle Creek	BTL	Michigan	15:30	1.36
South Bend	SBN	Indiana	15:55	2.03

squall line are shown in Fig. 4.6. The abbreviations for the stations shown in this diagram are the same as in Table 4.3. The water level records from Waukegan, Wilson Avenue (Chicago), Calumet Harbour (Chicago), and Ludington (see Fig. 4.7) were used.

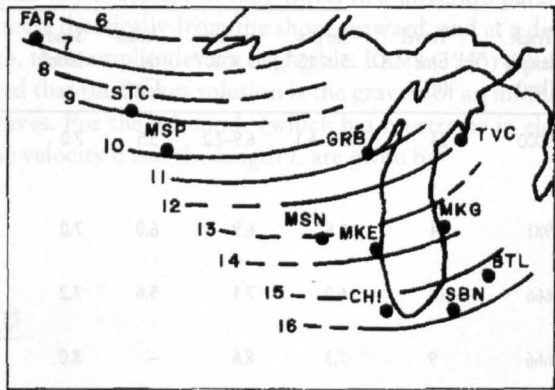


Fig. 4.6: Travel time curves (isochrones) of the squall line on July 6, 1954, over Lake Michigan and surroundings. Numbers represent hours Central Standard Time. FAR, Fargo, North Dakota; STC, St. Cloud, Minnesota; MSP, Minneapolis, Minnesota; GRB, Green Bay, Wisconsin; TVC, Traverse City, Michigan; MSN, Madison, Wisconsin; MKE, Milwaukee, Wisconsin; MKG, Muskegon, Michigan; CHI, Chicago, Illinois; BTL, Battle Creek, Michigan; SBN, South Bend, Indiana. (DONN and EWING, 1956)

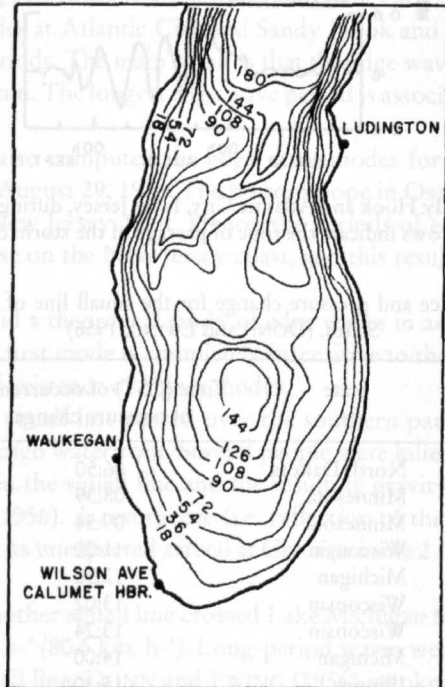


Fig. 4.7: Bottom topography of the southern port of Lake Michigan and the water level stations used in the study. (DONN and EWING, 1956)

The pertinent meteorological and water level data at these four stations are summarised in Table 4.4. It can be seen from Fig. 4.7 that the depth increases more or less uniformly with distance from the shore. The distance (i.e. $X/21r$) at which the edge wave amplitude should be negligible is about 16 mi (25.6 km). Starting just north of Chicago to up to 50 mi (80.5 km) north of Waukegan, the bottom slope was determined to the 300-ft (91.4 m) contour at six different locations. These values (i.e. of $\sin P$) were 0.0016, 0.0021, 0.0024, 0.0035, 0.0034, and 0.0029. For the phase velocity c of the edge wave a value of 72.5 ft. s⁻¹ (22 m. s⁻¹) was used. This gives from eq. (4.2) (for $n = 1$) a period of 103 min. From Table 4.4 the average period is 109 min. Thus, the calculated period of edge waves agrees with the observed period.

Calculations gave values of 50 mi. h⁻¹ (80.4 km. h⁻¹) and 61 mi. h⁻¹ (98 km. h⁻¹), respectively, for the edge wave velocity in the northern and southern parts of Lake Michigan. Since the speed of travel of the squall line was 50 mi. h⁻¹ (80.4 km. h⁻¹), resonance transfer of energy occurred from the squall line to the gravity waves in the water. At Ludington, the bottom topography precludes generation of edge waves. Hence, just after the passage of the squall line (at 1:00 p.m.) the amplitudes of the water waves were small. However, at 8:00 p.m. much larger waves appeared at Ludington. This was explained due to the reflected larger waves from other areas travelling towards Ludington.

The observed duration of the water level disturbance in the Chicago – Waukegan area is estimated to be about 29 h. About 20 h of this record at Calumet Harbour is shown in Fig. 4.8. The theoretical estimate of 18 h for the edge wave duration is somewhat smaller. The period of the edge waves was close to that of the seiche period in the southern part of Lake Michigan; hence, seiche activity is expected and observed water levels confirm this.

Earlier, reference was made to the storm surge in Lake Michigan due to a squall line on June 26, 1954 (six persons were killed in Chicago). PLATZMAN (1958a) studied this surge using a time-dependent two-dimensional numerical model. The travel time curves of this squall line are shown in Fig. 4.9. The lake level, wind, and atmospheric pressure at the Wilson Avenue crib in Chicago are shown in Fig. 4.10.

Table 4.4: Arrival time of pressure jump and first wave of surge and wave periods and duration of the water level disturbance at four stations in Lake Michigan associated with the squall line of July 6, 1954. (DONN and EWING, 1956)

Station	Pressure jump arrival time (CST)	Time of arrival of first wave of surge (CST)	Period (min) ^a		Duration of wave disturbance (h)
			Long- period waves	Short- period waves	
Waukegan (Illinois) Wilson Ave. (Chicago)	~15:00	15:30	110–120	20	29
Calumet Harbour (Chicago)	15:30	15:30	97–100	18–20	29
Ludington (Michigan)	15:30	15:30	115	20	— ^b
	~13:00	20:00–22:00	84	—	— ^b

^a Not to be confused with wind waves whose periods are of the order of a few seconds.

^b Record incomplete.

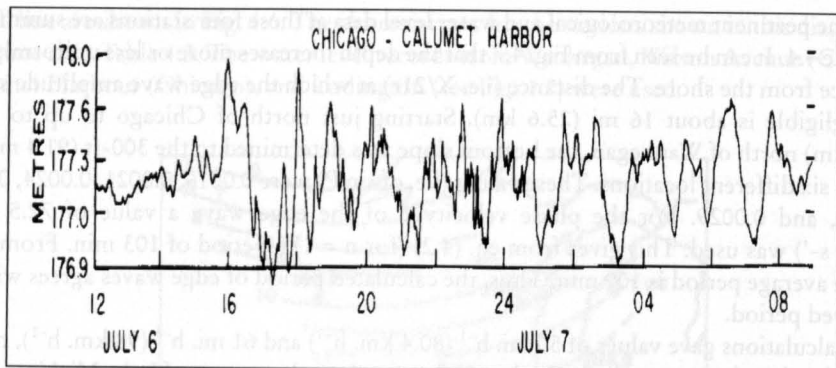


Fig. 4.8: Water level disturbance at Chicago's Calumet Harbour during July 6–7, 1954. (DONN and EWING, 1956)

PLATZMAN made five computations, i.e. using five different speeds of propagation for the squall line. These were 42, 48, 54, 60 and 66 knots ($1 \text{ knot} = 1.85 \text{ km} \cdot \text{h}^{-1}$). In each of these five computations he took the direction of propagation of the squall line as north-west to south-east, the width of the squall line as 10 nautical miles (18.5 km) and the magnitude of the pressure rise as 4 mb. The observed and computed results are compared in Table 4.5. In interpreting these results, it should be noted that the computations include atmospheric pressure gradient as a forcing term, but not wind stress. (Also, the Coriolis terms were ignored, although this omission may not be significant.)

PLATZMAN (1958a) summarised the results at the Wilson Avenue crib as follows:

- 1) The computed amplitude of the main (reflected) surge is approximately one-half the observed amplitude, but the inclusion of wind stress probably will remove this discrepancy.
- 2) The computed phases between significant events (Table 5.6) are in good agreement with the observations.
- 3) The structure of the tail of the reflected surge (and probably also the primary surge) is not in agreement with the observed structure, probably because the resolving power of the grid is inadequate for this purpose.

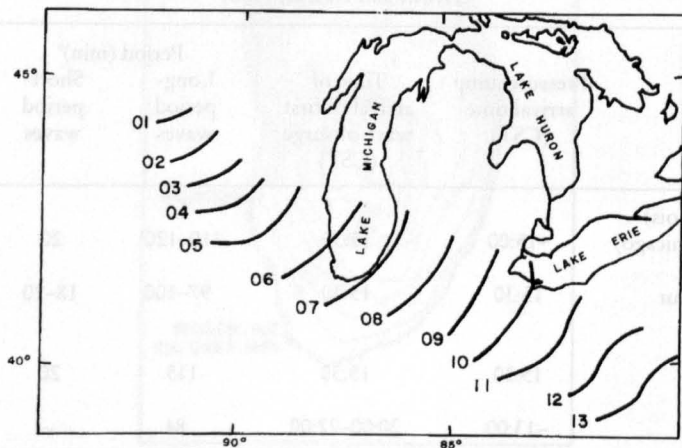


Fig. 4.9: Isochrones of the pressure jumpline of June 26, 1954, over Lake Michigan and surroundings. Numbers represent hours Central Standard Time. (PLATZMAN, 1958a)

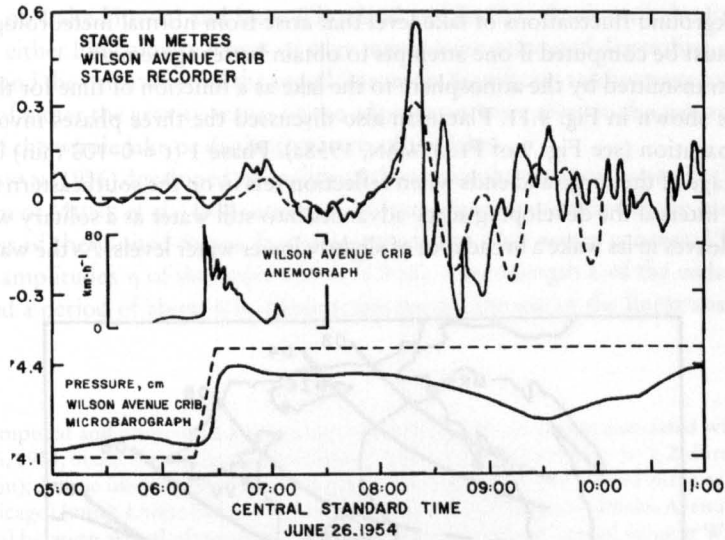


Fig. 4.10: Lake level, wind and atmospheric pressure records at Wilson Avenue crib on June 26, 1954. The broken curve of lake level shows the results of numerical computation for a squall line speed of 100 km. h⁻¹; the broken curve of pressure gives the corresponding pressure increase assumed in the calculation. (PLATZMAN, 1958a)

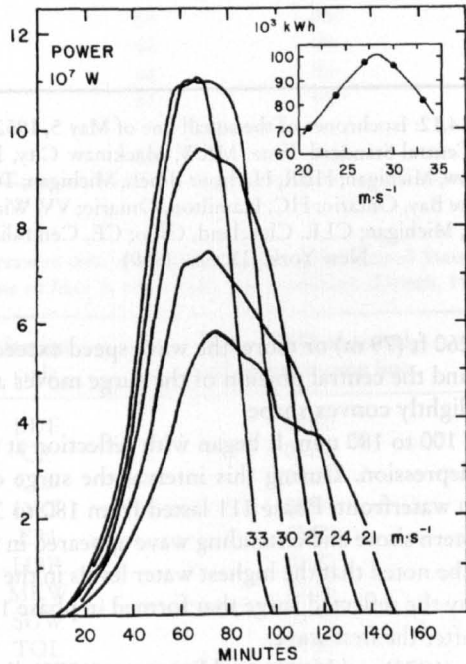


Fig. 4.11: The power transmitted by the atmosphere to the lake as a function of time for each of the five computed cases. Inset shows the total energy absorbed by the lake as a function of a squall line speed. (PLATZMAN, 1958a)

4) The background fluctuations of lake level that arise from normal meteorological disturbances must be computed if one attempts to obtain better agreement. The power transmitted by the atmosphere to the lake as a function of time for the five cases computed is shown in Fig. 4.11. Platzman also discussed the three phases involved in this surge's propagation (see Fig. 9 of PLATZMAN, 1958a). Phase 1 ($t = 0-100$ min) includes the formative stage of the surge and ends when reflection sets in on the southeastern shore of the lake. In this interval the developing surge advances into still water as a solitary wave (of elevation) and leaves in its wake a broad area of slightly lower water levels. As the wave advances

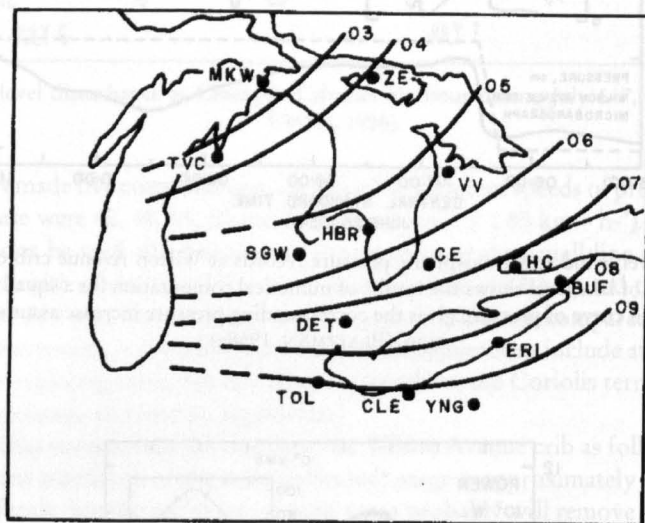


Fig. 4.12: Isochrones of the squall line of May 5, 1952.

Numbers represent hours Central Standard Time. MKW, Mackinaw City, Michigan; TVC, Traverse City, Michigan; SGW, Saginaw, Michigan; HBR, Harbour Beach, Michigan; TOL, Toledo, Ohio; YNG, Youngstown, Ohio; ZE, Gore Bay, Ontario; HC, Hamilton, Ontario; VV, Warton, Ontario; ERI, Erie, Pennsylvania; DET, Detroit, Michigan; CLE, Cleveland, Ohio; CE, Centralia, Ontario; BUF, Buffalo, New York. (DONN, 1959)

into depths greater than 260 ft (79 m) or more, the wave speed exceeds the squall line speed (54 knots [100 km. h⁻¹]) and the central portion of the surge moves ahead of the squall line and the surge assumes a slightly convex shape.

Phase 11 lasted from 100 to 180 min. It began with reflection at the southeastern shore followed by a wave of depression. During this interval the surge contracted and moved southwest to the Chicago waterfront. Phase 111 lasted from 180 to 300 min. It began with reflection at the southwestern shore and a standing wave appeared in the southernmost portion of the lake. It should be noted that the highest water levels in the Chicago area were not produced in phase 1 but by the reflected surge that formed in phase 11 and arrived from the north-east about 85 min after the first wave.

FREEMAN and MURTY (1972) and MURTY and FREEMAN (1973) discussed a squall line generated surge on Lake Huron. This will be discussed in section 7.1. DONN (1959) studied the storm surges in Lakes Huron and Erie due to a squall line on May 5, 1952. The travel time curves of the squall line are shown in Fig. 4.6. The pressure and wind data are summarised in Tables 4.6 and 4.7, respectively. Water level data are used from MacKinaw City and Harbour

Beach (both on Lake Huron) and from Cleveland and Buffalo (both on Lake Erie). DONN showed that either long gravity waves or edge waves were generated depending on the local topography and the orientation of the squall line track. Significant seiches were excited when the periods of either the gravity waves or the edge waves were close to the natural modes of oscillation of the whole lake or distinctive parts of the lake.

GREENSPAN (1956) developed an analytical theory for the transient aspects of the steady-state problem of MUNK et al. (1956) and applied it to edge wave generation by hurricanes on the east coast of the United States. It was assumed that edge waves generated here in this fashion had amplitudes η of the order of 3 ft (0.9 m), a wavelength λ of the order of 200 mi (322 km), and a period of about 6 h. These scales permit the use of the linear shallow-water theory.

Table 4.5: Computed and observed time intervals between significant events associated with the squall line of June 26, 1954, in the United States. Columns: 1, speed of squall line (km – h⁻¹); 2, duration of pressure jump (min); 3, time interval between first surge at Michigan City and second surge at Wilson Avenue Crib (Chicago) (min); 4, time interval between first and second surges at Wilson Avenue Crib (min); 5, time interval between arrival of pressure jump and occurrence of and second surge at Wilson Avenue Crib (min); 6, time interval between second surge and first one following depression at Wilson Avenue Crib (min). (PLATZMAN, 1958a)

1	2	3	4	5	6
Computed					
78	14.3	55	85	109	35
89	12.5	63	85	114	25
100	11.1	66	85	118	20
111	10.0	68	85	121	18
122	9.1	67	85	121	18
Observed					
	5	68	88	113	6

Table 4.6: Atmospheric pressure data at several stations in the United States and Canada for the squall line of May 5, 1952 (NA, not available). (DONN, 1959)

Location	Station code	Time (EST) of arrival of pressure jump line	Magnitude of pressure jump (mb)
Buffalo, NY	BUF	08:00	4.06
Centralia, Ont.	CE	06:30	5.08
Cleveland, OH	CLE	09:28	2.71
Detroit, MI	DET	07:38	2.37
Erie, PA	ERI	08:00	3.39
Harbour Beach,	HBR	05:20	NA
Mackinaw City, MI	MKW	02:36	NA
Saginaw, MI	SGW	05:40	2.03
Toledo, OH	TOL	09:40	0.68
Traverse City, MI	TVC	03:45	0.68
Youngstown, OH	YNG	09:30	3.39
Gore Bay, Ont.	ZE	04:30	3.39
Hamilton, Ont.	HE	07:30	NA
Warton, Ont.	VV	05:15	4.74

The equations of motion and continuity are in the usual notation:

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho} \frac{\partial p}{\partial x} \tag{4.4}$$
$$\frac{\partial v}{\partial t} = -\frac{1}{\rho} \frac{\partial p}{\partial y}$$

Table 4.7: Wind data at several stations in the United States and Canada for the squall line of May 5, 1952. (DONN, 1959)

Station	Wind data
Buffalo, NY	On arrival of pressure jump, weak winds shifted from east to north
Cleveland, OH	On arrival of pressure jump, winds at 32 km. h ⁻¹ from north-east shifted to 48 km. h ⁻¹ from south-east
Detroit, MI	On arrival of pressure jump, winds at 40 km. h ⁻¹ from south east shifted to 63 km. h ⁻¹ from north-east
Erie, PA	Winds of 35 km. h ⁻¹ from the north. On arrival of pressure jump, winds shifted to south-east
Mackinaw City, MI	Winds of 58 km. h ⁻¹ shifted at 02:36 (EST)
South Bend, IN	Winds of 29 km. h ⁻¹ from northwest. On arrival of jump, wind shifted to north-east to north-north-east
Toledo, OH	On arrival of jump, wind shifted from south to north (19–24 km.h ⁻¹)
Traverse City, MI	On arrival of jump, wind shifted from south-east to east (32–40 km. h ⁻¹)
Youngstown, OH	On arrival of jump, wind shifted from north to southeast. (48–56 km. h ⁻¹)
Centralia, Ont	On arrival of jump, wind shifted from south-south-west to north-north-east
Gore Bay, Ont.	Wind shifted from east to north (16–41 km. h ⁻¹)
Hamilton, Ont.	Wind from northeast at 16 km/h ⁻¹ .
Warton, Ont	Wind speed increased from 5 to 27 km. h ⁻¹ and shifted from north-east to north-north-east

The computed and observed edge wave periods and duration for four hurricanes are compared in Table 4.2.

REDFIELD and MILLER (1957) divided hurricane-produced surges into three parts: the forerunner, the hurricane surge, and resurgence. The forerunner is a slow and gradual change in the water level, commencing several hours before the arrival of the storm. There appears to be good coherence between the records at nearby stations in this stage, and one must consider winds over a more extended region than the hurricane proper. Facing the coast from the ocean, if the hurricane moves to the right along the coast, the forerunner usually is a rise in the water level and if the hurricane moves to the left, the forerunner consists of a decrease in the water level.

The hurricane surge is a sharp rise in the water level that occurs at about the time the hurricane center passes over the station. The duration of this stage usually does not exceed 2.5-5 h. In this stage, the coherence between neighbouring stations is not good. This means that the strong winds in the hurricane proper are responsible for the water level oscillations. In the Northern Hemisphere, the highest water levels occur to the right of the hurricane track.

The resurgence, being unexpected (since the storm has passed), could be dangerous. These were attributed by MUNK et al. (1956) to a wake of waves in the trail of the hurricane, and these have periods of free edge waves. KAJIURA (1959) mentioned that even at stations close by (i.e. separated only by one wavelength) the periods could be considerably different. He attributed the resurgence to a free onshore-offshore standing wave on the shelf.

WEBB (1976) considered resonance problems of long gravity waves on the continental shelf. He began with a simple model of a rectangular continental shelf at the end of a canal. It is assumed that a Kelvin wave propagates along the canal, which is partly absorbed and partly reflected by the continental shelf. The depth of the canal is of the same order as that of the deep oceans and the shelf parameters are taken to represent the Patagonian Shelf off Argentina. The simple analytical model showed that usually most of the incident wave energy is reflected by the edge of the shelf. However, at the dominant shelf resonance frequencies, more than 95% of the energy is absorbed by the shelf.

4.3 Interaction between Storm Surges and Tides

The traditional method of subtracting the astronomical tide from the observed water level and treating the residue as storm surge assumes that tide and surge are linearly additive and that there is no non-linear interaction. However, observations show that there are situations in which there is an interaction (i.e. tide influencing the propagation of the surge and vice-versa), especially in shallow areas. The interaction phenomenon, although probably present in other water bodies as well, appears to be quite pronounced in the Thames Estuary of the North Sea. In a series of papers, PROUDMAN (1955a, 1955b, 1957, 1958) studied this problem analytically.

4.3.1 Numerical Models of Tide-Surge Interaction in the Bay of Bengal

FLIERL and ROBINSON (1972) have documented many cases where the occurrence of abnormally high sea-surface level in the Bay of the Bengal has led to coastal flooding and inundation. The genesis of these events is to be found in the combined effect of the astronomical tide and a surge generated by a tropical cyclone. The principle component is the surge but, depending on the relative phase of the two processes, the sea-surface elevation may either be increased above, or decreased below its pure surge value. The mutual interaction is, however, nonlinear and the dynamics of both processes must be considered simultaneously.

Many analyses of surge generation by hurricanes, typhoons and tropical cyclones have now been made. Particular mention is made here of the numerical modelling of these phenomena by JELESNIANSKI (1965, 1966, 1967), MIYAZAKI et al. (1961), DAS et al. (1974) and SINHA et al. (1996). More recently, JOHNS et al. (1981, 1982, 1983 a, b) have developed several numerical models for application along the east coast of India. A fully nonlinear model to

analyse tide-surge interaction in the Bay of Bengal has been described and applied to the coastal waters off Bangladesh by JOHNS and ALI (1980), JOHNS et al. (1985), ROY (1995, 1999 a, 1999 b), ALI et al. (1997a, b) and ALI (1980c), DAS (1980), HENRY et. al (1997).

The general procedure followed in the modelling of tide-surge interaction is to begin by generating the co-oscillating tide in a semi-enclosed basin by prescribing the temporal variation of the sea-surface elevation along the open boundary. The value of this is supposed known from observations of the tidal state in the adjacent ocean. The pure tidal solution developed in the basin then provides the initial dynamical conditions for the storm surge simulation with tidal forcing along the open-sea boundary continuing during the integration. This method has been successfully applied in studies of the tide-surge interaction in the North Sea (see, for example, BANKS, 1974) but its practical application in the Bay of Bengal is hampered by the absence of adequate tidal data along the boundary separating the Bay from the northern Indian Ocean.

DAS (1980) used a nonlinear model to study the tide-surge interaction in the Meghna estuary. ALI (1980c) stated that about one third of the area of Bangladesh is penetrated by tide (through estuaries and rivers). Maximum tidal range (up to 6.1 m) and surge are found in the Meghna estuary.

Tide-surge interaction during the November 1970 Chittagong cyclone is shown in Fig. 4.13–4.15. It may be seen that at Patenga, maximum surge occurred at time of high tide whereas at Amatali the peak surge occurred after the occurrence of high tide. However, at Kaikhali the peak water level elevation is smaller than due to the tide alone. ALI (1980c) ascribed this to the effect of the offshore wind component, which drives the water from the rivers located to the west of the cyclonic track. The two small peaks in the total elevation near the time of high tide are probably due to the tide-surge interaction.

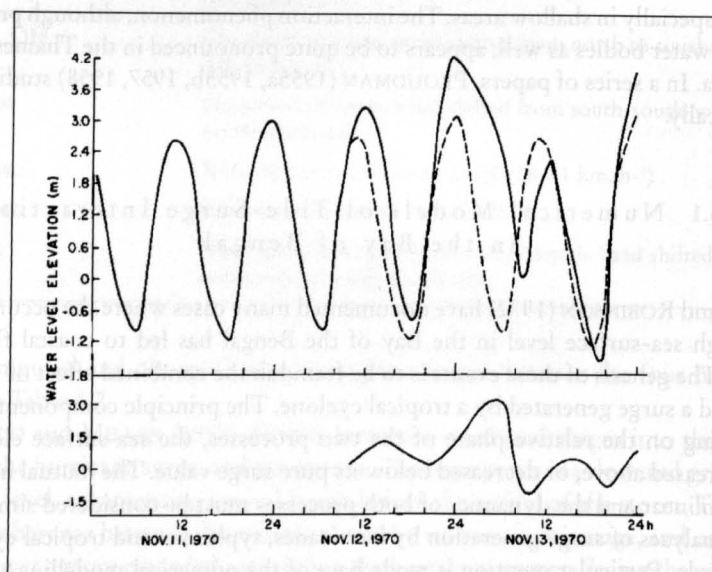


Fig. 4.13: Water level at Patenga, Bangladesh, during November 11–13, 1970. Top: Observed water level (tide + surge) is shown by the solid line and the computed water level by the broken line; bottom: observed storm surge. (ALI, 1980c)

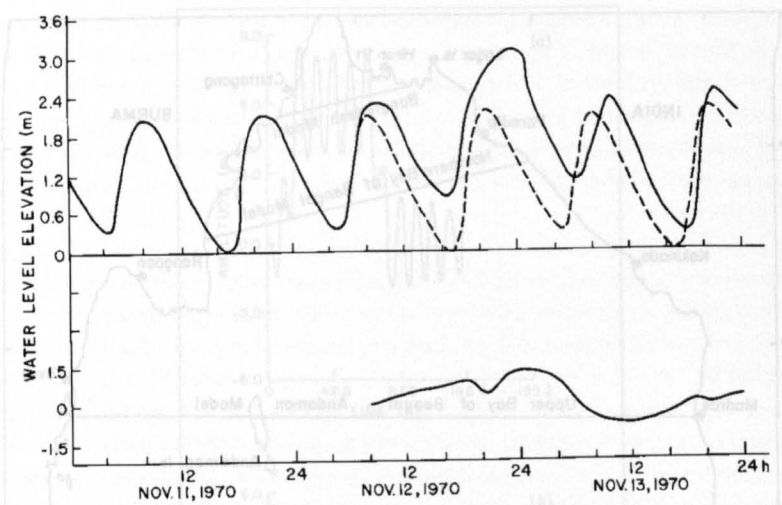


Fig. 4.14: Water level at Amtali, Bangladesh, during November 11–13, 1970. Refer to Fig. 4.13 for explanation. (ALI, 1980c)

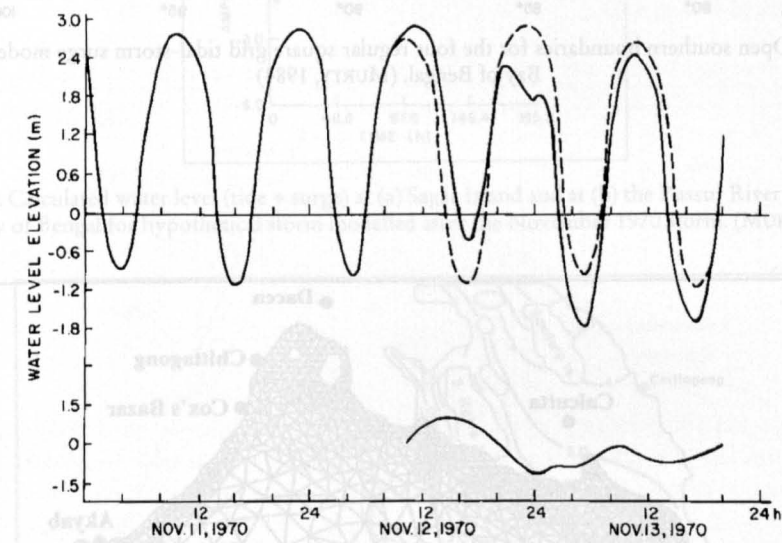


Fig. 4.15: Water level at Kaikhali, Bangladesh during November 11–13, 1970. Refer to Fig. 4.13 for explanation. (ALI, 1980c)

MURTY and HENRY (1983) and HENRY and MURTY (1982) developed a series of numerical models for tides and surges in the Bay of Bengal. The regions covered by the various regular grid models are shown in Fig. 4.16. The irregular triangular grid that has also been used is shown in Fig. 4.17. The computed water level (tide + surge) at Sagar Island and the Pussur River entrance is shown in Fig. 4.18. The contours of the computed surge are shown in Fig. 4.19.

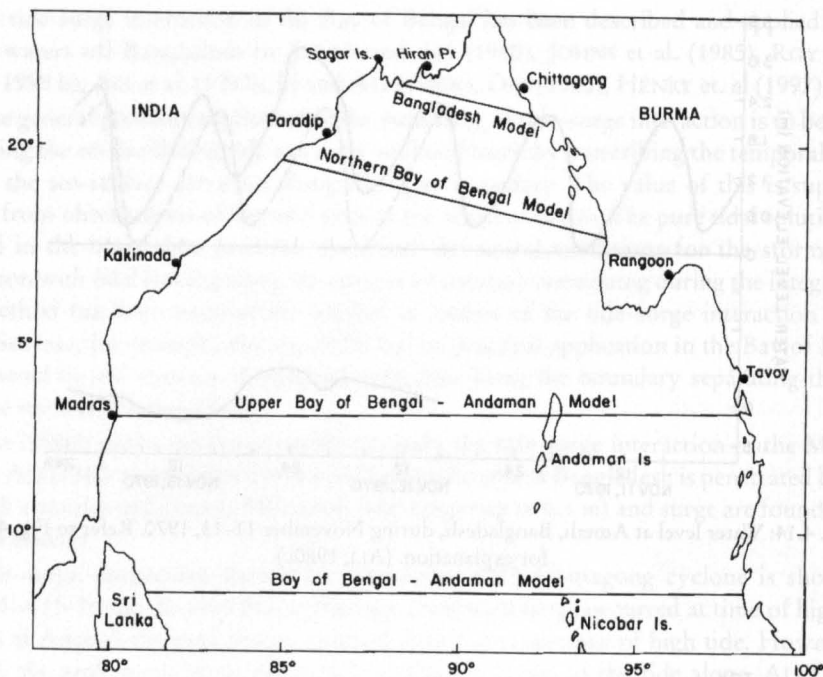


Fig. 4.16: Open southern boundaries for the four regular square grid tidal-storm surge models for the Bay of Bengal. (MURTY, 1984)

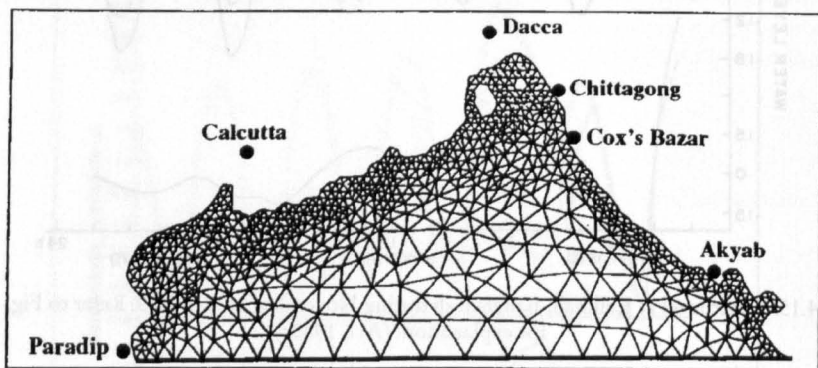


Fig. 4.17: Irregular triangular grid model for tides and storm surges in the northern part of the Bay of Bengal. (MURTY, 1984)

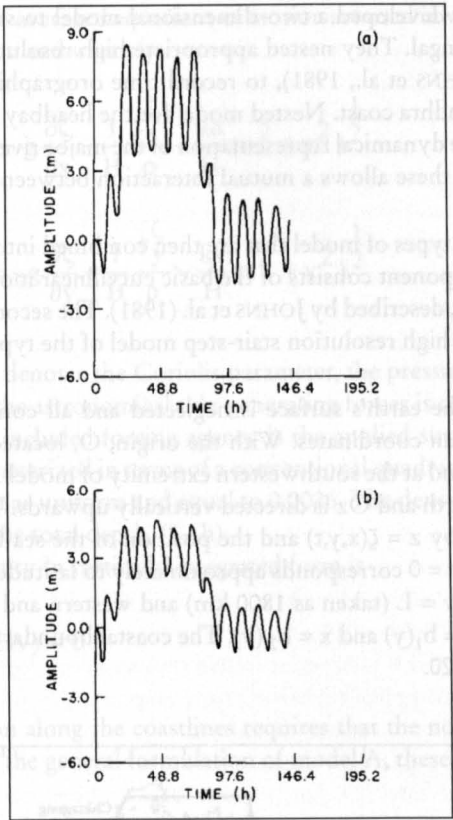


Fig. 4.18: Calculated water level (tide + surge) at (a) Sagar Island and at (b) the Pussur River entrance in the Bay of Bengal for hypothetical storm modelled after the November 1970 storm. (MURTY, 1984)

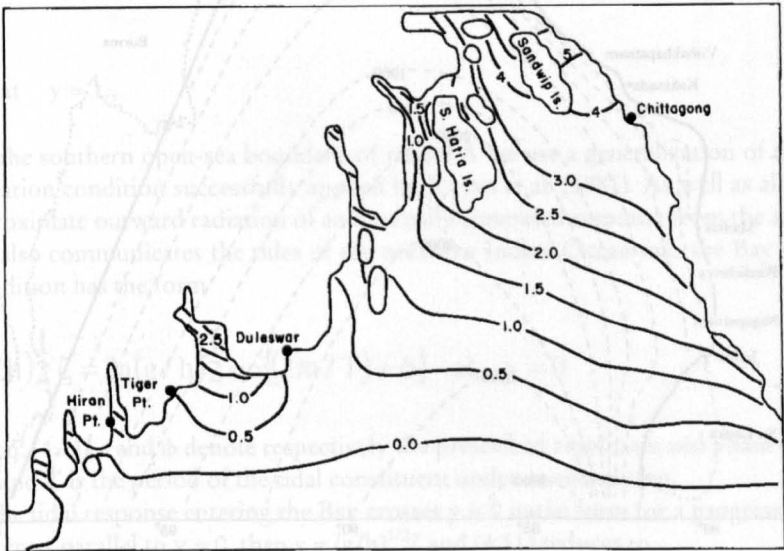


Fig. 4.19: Storm surge heights in the northern part of the Bay of Bengal from the hypothetical storm modelled after the November 1970 storm. (MURTY, 1984)

JOHNS et al. (1985) developed a two-dimensional model to study the tide-surge interaction in the Bay of Bengal. They nested appropriate high resolution models in their basic storm surge model (JOHNS et al., 1981), to record time orographical detail in the headbay region and along the Andhra coast. Nested model for the headbay region is particularly important as it includes the dynamical representation of the major rivers comprising the Ganges Delta. The inclusion of these allows a mutual interaction between the dynamics in the Bay and those in the Delta.

They consider two types of model that are then combined into a unified computational scheme. The major component consists of the basic curvilinear model for the Bay of Bengal (referred to as model A), described by JOHNS et al. (1981). The second component is a nested, and more conventional, high resolution stair-step model of the type described, for example, by HEAPS (1969).

The curvature of the earth's surface is neglected and all conditions are referred to a system of plane Cartesian coordinates. With the origin, O, located within the equilibrium level of the sea-surface and at the southwestern extremity of model A, Ox points towards the east, Oy towards the north and Oz is directed vertically upwards. The displaced position of the sea surface is given by $z = \zeta(x,y,t)$ and the position of the sea floor by $z = -h(x,y)$. An open / sea boundary at $y = 0$ corresponds approximately to latitude 6°N. A northern coastal boundary is situated at $y = L$ (taken as 1800 km) and western and eastern coastlines correspond respectively to $x = b_1(y)$ and $x = b_2(y)$. The coastal boundary configuration in model A is delineated in Fig. 4.20.

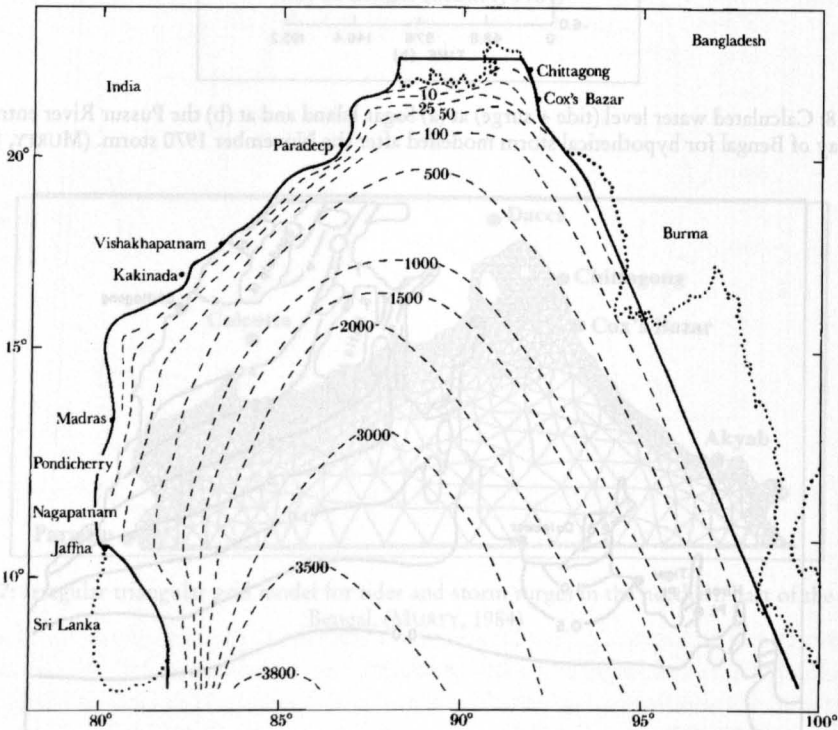


Fig. 4.20: The coastal configuration in model A and the isobaths of the model bathymetry. The numbers refer to depth in meters. (JOHNS et al., 1985)

Conventional depth-averaged equations of motion are used in which the depth-averaged components of velocity, u and v satisfy

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - fv = -g \frac{\partial \zeta}{\partial x} - \frac{1}{H} \frac{\tau_x^{\zeta}}{\rho} - \frac{ku}{H} (u^2 + v^2)^{\frac{1}{2}} \quad (4.5)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} - fu = -g \frac{\partial \zeta}{\partial y} + \frac{1}{H} \frac{\tau_y^{\zeta}}{\rho} - \frac{kv}{H} (u^2 + v^2)^{\frac{1}{2}} \quad (4.6)$$

In (4.5) and (4.6), f denotes the Coriolis parameter, the pressure is taken as hydrostatic and the direct effect of the astronomical tide-generating forces is omitted.

The sole explicitly included forcing agency is the applied surface wind stress (τ_x^{ζ} , τ_y^{ζ}). Bottom friction is parameterized in terms of a conventional quadratic stress law with the friction coefficient, k , taken as uniform and equal to 0.0026. The density of the water, ρ , is assumed uniform and H is the total depth, $(\zeta + h)$.

The equation of continuity in vertically integrated form is

$$\frac{\partial \zeta}{\partial t} + \frac{\partial}{\partial x} (Hu) + \frac{\partial}{\partial y} (Hv) = 0 \quad (4.7)$$

Boundary condition along the coastlines requires that the normal component of velocity is zero. In terms of the general formulation of model A, these lead to

$$u - vb_1'(y) = 0 \quad \text{at} \quad x = b_1(y), \quad (4.8)$$

$$v - vb_2'(y) = 0 \quad \text{at} \quad x = b_2(y), \quad (4.9)$$

and

$$v = 0 \quad \text{at} \quad y = L, \quad (4.10)$$

At the southern open-sea boundary of model A we use a generalization of the linearized radiation condition successfully applied by JOHNS et al. (1981). As well as allowing for the approximate outward radiation of an internally generated response from the analysis region, it also communicates the tides of the northern Indian Ocean into the Bay of Bengal. The condition has the form

$$v + (g/h)^{\frac{1}{2}} \zeta = 2a(g/h)^{\frac{1}{2}} \sin\{(\frac{2\pi}{T})t + \phi\} \quad \text{at} \quad y = 0 \quad (4.11)$$

In eq. (4.11) a and ϕ denote respectively the prescribed amplitude and phase of the tidal forcing and T is the period of the tidal constituent under consideration.

If the tidal response entering the Bay crosses $y = 0$ in the form for a progressive wave with its crest parallel to $y = 0$, then $v = (g/h)^{1/2} \zeta$ and (4.11) reduces to

$$\zeta = a \sin\{(\frac{2\pi}{T})t + \phi\} \quad \text{at} \quad y = 0 \quad (4.12)$$

In this case, a and ϕ correspond to the amplitude and phase of the tidal elevation along $y = 0$. A consequence of applying (4.11) rather than (4.12) is that the values of neither ζ nor v are separately prescribed along the open-sea boundary of model A. Thus, during the solution process, the boundary values of both ζ and v may correlatively adjust subject only to (4.11). We anticipate that such a solution procedure, which is based on prescribing conditions on an incoming characteristics will be superior to one using (4.12), especially if $y = 0$ should coincide with a nodal line. Further generalization of (4.11) to a discrete spectrum of tidal constituents follows without difficulty.

High resolution stair-step models are nested within model A so as to represent more fully the orographical detail of the headbay region and the Andhra coast of India. For the headbay, the nested model is referred to as model B and the stair-step boundary configuration is delineated Fig. 4.21. In contrast with the parent model A, the northern boundary of model B does not consist of a continuous vertical wall. Instead, one-dimensional dynamical models have been included to represent some of the rivers entering the head of the Bay of Bengal. The southernmost limit of model B consists of an open-sea boundary along latitude $19^{\circ} 33' N$ where elevation values are prescribed. These are determined from the response in model A. An important feature of the scheme is that the response in model A is independent of that in model B. On the other hand, the response in model B is dependent on that generated in model A. Indeed, we find that the results from model A become increasingly unrealistic in the region of the Ganges Delta owing to the omission of any representation of the complex river system. Model B is superior in this respect as the representation of the rivers, although crude, avoids a complete refraction of the response at $y = L$ and the local development of unrealistically high sea-surface elevations.

In model B, east-west separation distance between points at which the elevation is computed is approximately 17.6 km. The north-south distance between computational points is approximately 19.8 km. The grid-point arrangement is staggered in such a way that ζ is computed at the centre of a grid cell while u and v are computed at the mid-points of its y -directed and x -directed sides respectively. The vanishing of the normal component of velocity at a coastline is then readily achieved by an appropriate stair-step representation of the boundary.

Conditions in each of the rivers satisfy equations of the form.

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial y} = -g \frac{\partial \zeta}{\partial y} - \frac{kv|v|}{H} \quad (4.13)$$

and

$$b \frac{\partial \zeta}{\partial t} + \frac{\partial}{\partial y} (bHv) = 0 \quad (4.14)$$

Thus, in the dynamical equation (4.13), we omit the effect of wind-stress forcing in the rivers. At the point of entry into model B, the elevation and momentum flux are made continuous. In the continuity equation (4.14), b denotes the local breadth of the river. At the river's point of communication with model B, the mass flux is made continuous. Juncture conditions of a similar kind have been described by JOHNS and ALI (1980). It is noteworthy that the resulting interaction between the rivers and model B is two-way because the dynamical response in either may affect that in the other.

Each of the rivers is taken to have a length of 200 km with no mass flux of water through its head. Each river has a uniform breadth of 18 km except the Meghna (in the extreme east),

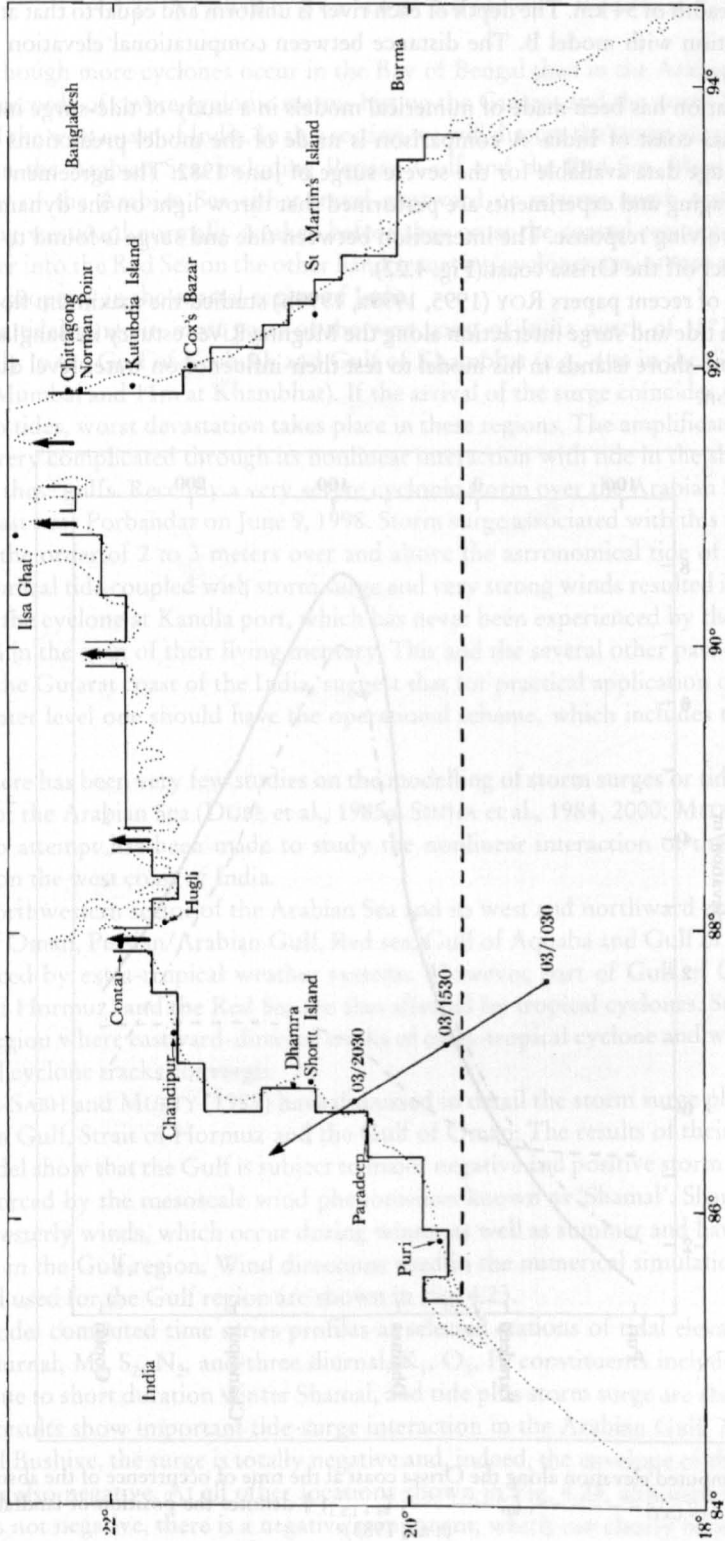


Fig. 4.21: The coastal configuration in model B and the idealized track of the Orissa cyclone. The numbers on the track refer to the times (IST) at which the centre of the cyclone passed through the marked positions on 3 June 1982. (JOHNS et al., 1985)

which has a breadth of 54 km. The depth of each river is uniform and equal to that at its point of communication with model B. The distance between computational elevation points is taken as 20 km.

An application has been made of numerical models in a study of tide-surge interaction along the Orissa coast of India. A comparison is made of the model predictions with the limited tide-gauge data available for the severe surge of June 1982. The agreement between these is encouraging and experiments are performed that throw light on the dynamical character of the evolving response. The interaction between tide and surge is found to lead to a substantial effect off the Orissa coast (Fig. 4.22).

In a series of recent papers ROY (1995, 1999a, 1999b) studied the maximum flood levels associated with tide and surge interaction along the Meghna River estuary in Bangladesh. He also included off-shore islands in his model to test their influence on water level due to tide surge interaction.

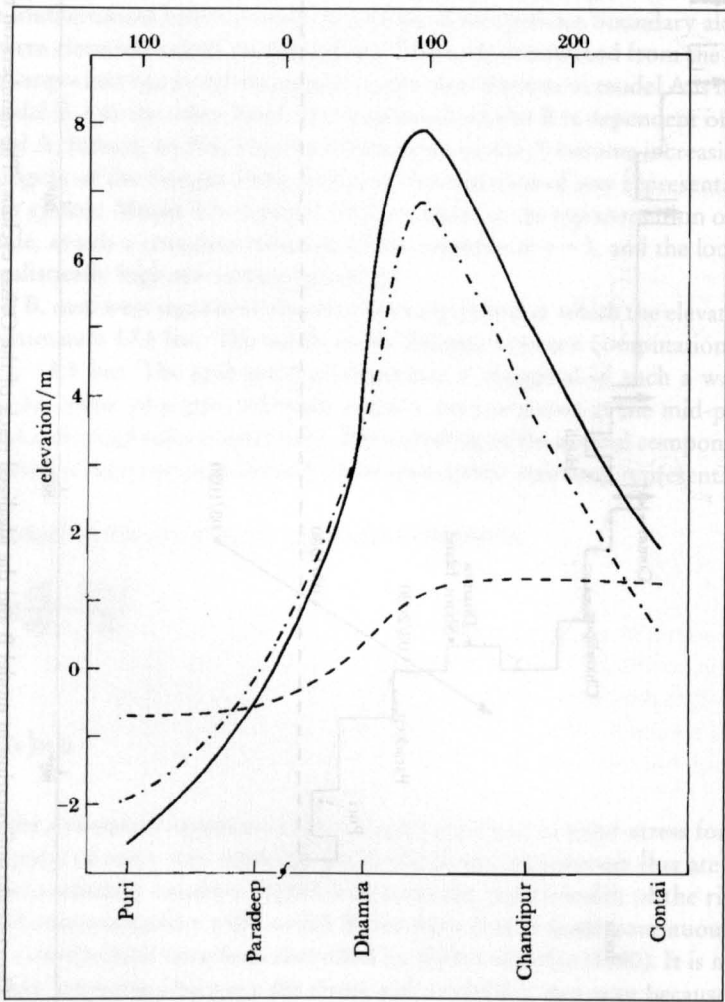


Fig. 4.22: The computed elevation along the Orissa coast at the time of occurrence of the absolute peak elevation; —, $\zeta_{s+t+I.S.T}$; - - - - -, ζ_p ; — · —, $\zeta_{s+I.S.T}$; § denotes the position of landfall. (JOHNS et al., 1985)

4.3.2 Arabian Sea and Adjacent Persian Gulf

Although more cyclones occur in the Bay of Bengal than in the Arabian Sea, there are several records of severe cyclonic storms hitting the Gujarat and the north Maharashtra regions of the west coast of India. In this section we will discuss the storm surge and tide interaction in the Arabian Sea, including Persian Gulf and the Red Sea. Most of the tropical cyclones of the Arabian Sea either travel westward or recurve north eastward, cyclones travelling westward normally weaken before they cross the coastal regions of Saudi Arabia and enter into the Red Sea on the other hand recurring cyclones are intense and cause loss of life and property in the coastal region of India.

The tidal range in most parts of the west coast of India north of 18°N is quite large especially in the Gulf of Kachchh and Gulf of Khambhat (e.g., 4 m in the Gulf of Kachchh, 8 m at Mumbai and 11m at Khambhat). If the arrival of the surge coincides with the time of the high tides, worst devastation takes place in these regions. The amplification of surge becomes very complicated through its nonlinear interaction with tide in the shallow water region of these gulfs. Recently a very severe cyclonic storm over the Arabian Sea crossed Gujarat coast near Porbandar on June 9, 1998. Storm surge associated with this tropical cyclone was of the order of 2 to 3 meters over and above the astronomical tide of 6.6 meters. The astronomical tide coupled with storm surge and very strong winds resulted in a phenomenal fury of the cyclone at Kandla port, which has never been experienced by the community of the area in the span of their living memory. This and the several other past cyclones, which struck the Gujarat coast of the India, suggest that for practical application of predicting the total water level one should have the operational scheme, which includes tide-surge interaction.

There has been very few studies on the modelling of storm surges or tides in the eastern sector of the Arabian Sea (DUBE et al., 1985a; SINHA et al., 1984, 2000; MITRA, 1990). However, no attempt has been made to study the nonlinear interaction of the tide and storm surges on the west coast of India.

Northwestern sector of the Arabian Sea and its west and northward extension through Gulf of Oman, Persian/Arabian Gulf, Red sea, Gulf of Aquaba and Gulf of Suez are mainly influenced by extra-tropical weather systems. However, part of Gulf of Oman (South of Strait of Hormuz) and the Red Sea are also affected by tropical cyclones. Strait of Hormuz is the region where eastward-directed tracks of extra-tropical cyclone and westward moving tropical cyclone tracks converge.

EL-SABH and MURTY (1989) have discussed in detail the storm surge phenomena in the Arabian Gulf, Strait of Hormuz and the Gulf of Oman. The results of their two-dimensional model show that the Gulf is subject to major negative and positive storm surges. The model is forced by the mesoscale wind phenomenon known as 'Shamal'. Shamal refers to the northwesterly winds, which occur during winter as well as summer and have significant influence in the Gulf region. Wind directions used in the numerical simulation together with the grid used for the Gulf region are shown in Fig. 4.23.

Model computed time series profiles at selected stations of tidal elevation (with three semi-diurnal, M_2 , S_2 , N_2 , and three diurnal, K_1 , O_1 , P_1 constituents included), storm surge alone due to short duration winter Shamal, and tide plus storm surge are shown in Fig. 4.24. These results show important tide-surge interaction in the Arabian Gulf. At Shat-Al-Arab Bar and Bushive, the surge is totally negative and, indeed, the envelope of the tide plus surge curve is also negative. At all other locations shown in Fig. 4.24, although the predominant surge is not negative, there is a negative component, which can clearly be seen. These nega-

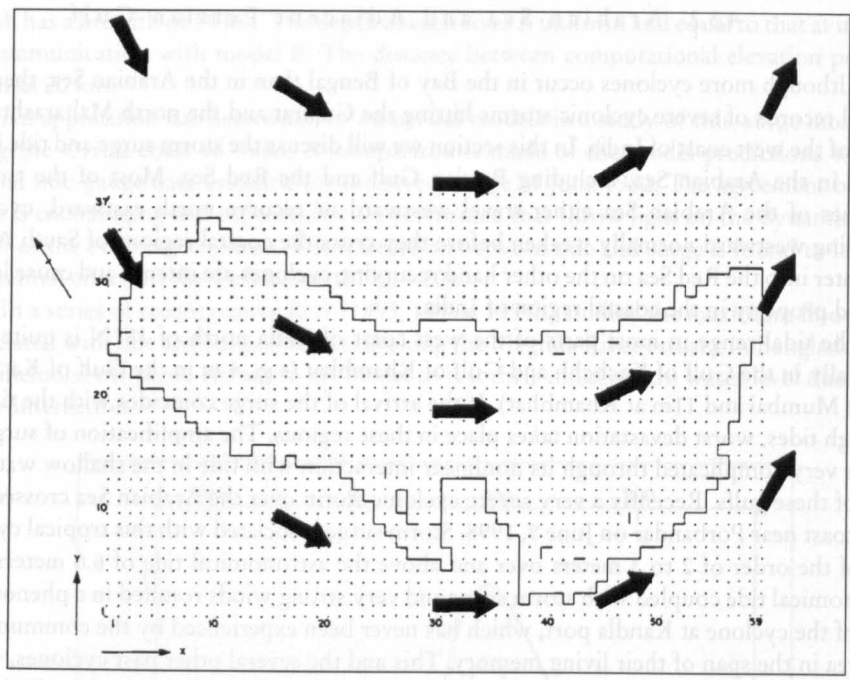


Fig. 4.23: Wind directions used in the numerical simulation. (EL-SABH and MURTY, 1989)

tive surges are due to the orientation of the storm track with reference to the topography. It may, overall, be seen that maximum amplitude of the negative surge reaches to about 3 m while maximum amplitude of positive surges is only 1m. The nature of the tide-surge interaction is different at different locations, due to the change in the tidal and surge regimes at various areas in Gulf.

4.3.3 Gulf of Suez-Red Sea System

Gulf of Suez is located in the extreme north of the Red Sea bounded by the Sinai Peninsula to the east and the Eastern Desert of the Egypt to the west (Fig. 4.25). It is connected with the Mediterranean Sea through the Suez Canal and with the Red Sea through the strait of Jubal.

Storm surges are considered to be one of the most important natural hazards that affect the Gulf and its surroundings. The analysis made by MURTY and EL-SABH (1981), based on the water levels at Port Suez for the year 1965–1966, indicated that significant surges could develop in the Gulf of Suez. On the other hand, M_2 semidiurnal tidal component dominates the tidal signal. Generally, the tidal range decreases from the entrance of the Gulf towards the bank of Tor where it reaches a very small value, and then increases again to about 1.5 m at Suez. A difference of 6 hours exists between the times of high water at the southern and northern ends of the Gulf (MORCOS, 1970). RADY et al. (1994a) used a vertically integrated two-dimensional and a five-layer three-dimensional numerical model to simulate Gulf is principal tidal component M_2 . Known to be an area that is vulnerable to significant surges (MURTY and EL-SABH, 1984) and that has the largest tidal range and the shallowest water

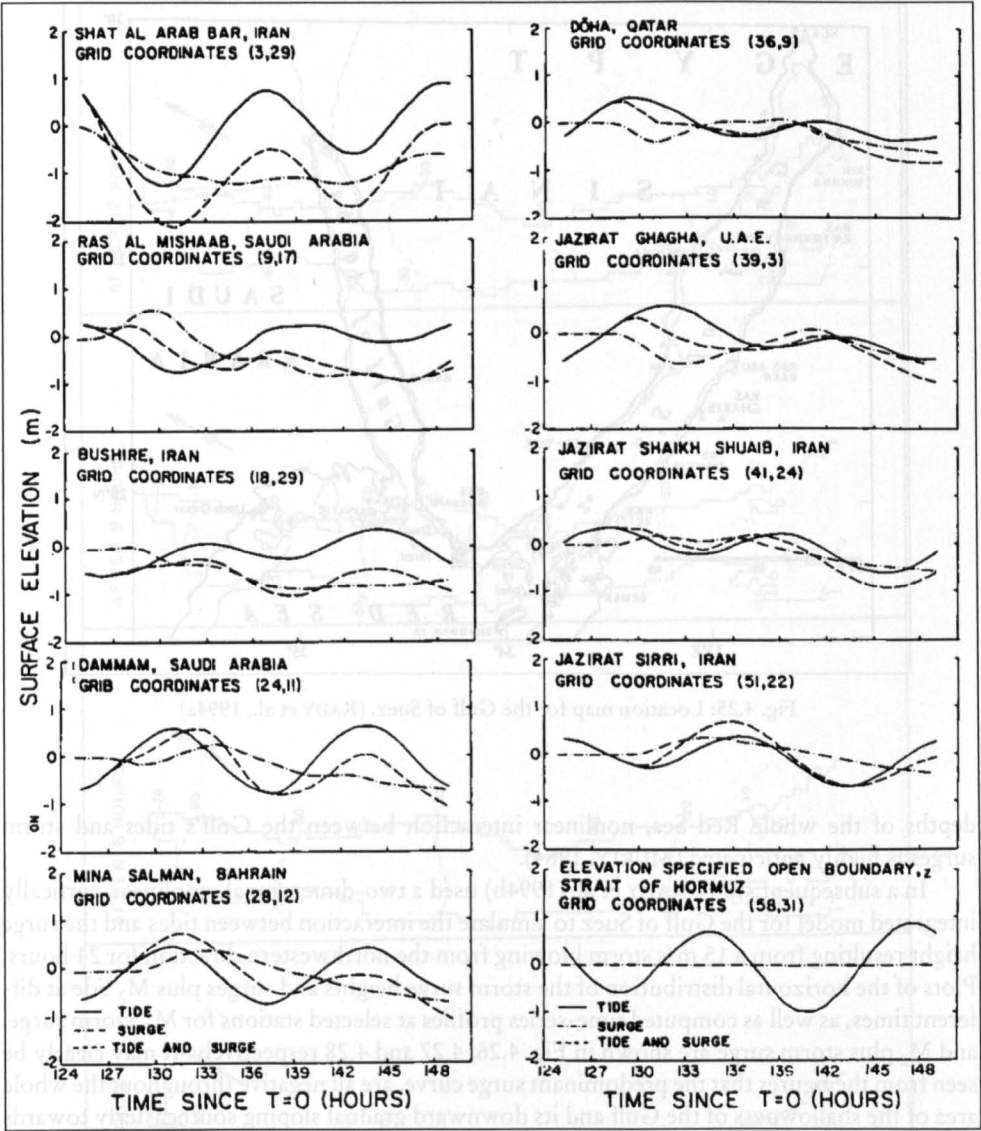


Fig. 4.24: Computed profiles of tides (including six constituents), surge only and surge plus tide at selected locations. (EL-SABH and MURTY, 1989)

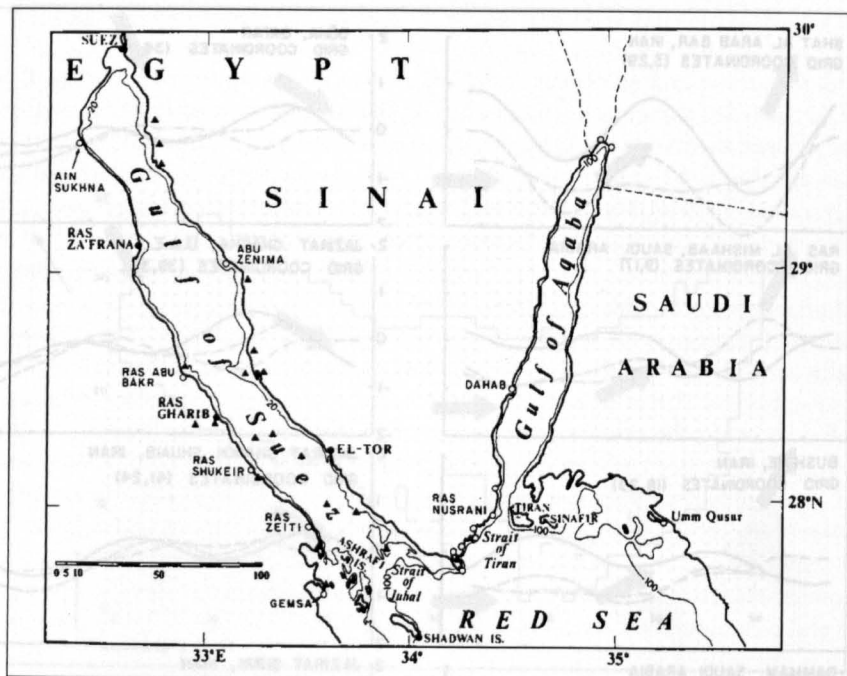


Fig. 4.25: Location map for the Gulf of Suez. (RADY et al., 1994a)

depths of the whole Red Sea, nonlinear interaction between the Gulf's tides and storm surges is highly anticipated (MURTY, 1984).

In a subsequent study RADY et al. (1994b) used a two-dimensional, nonlinear, vertically integrated model for the Gulf of Suez to simulate the interaction between tides and the surge height resulting from a 15 m/s storm blowing from the northwestern direction for 24 hours. Plots of the horizontal distribution of the storm surge heights and surges plus M_2 tide at different times, as well as computed time-series profiles at selected stations for M_2 , storm surge, and M_2 plus storm surge are shown in Fig. 4.26, 4.27 and 4.28 respectively. It may clearly be seen from the figures that the predominant surge curve, are all negative throughout the whole area of the shallowness of the Gulf and its downward gradual sloping southeasterly towards the great depths of the Red Sea in the same direction of the blowing storm. Since the Gulf of Suez is part of the Red Sea system, positive surges should be expected to occur in other parts of the Red Sea. This aspect has been discussed in detail by RADY et al. (1994b).

Surge heights increase from a few centimeters at the southern end of the Gulf to over one meter in the extreme north at Suez. These heights become larger when the effect of the tide is included.

Generally, the tidal range decreases from the entrance of the Gulf towards the back of Tor where it reaches a very small value, and then increases again to about 1.5 m at Suez. A difference of 6 hours exists between the times of high water at the southern and northern ends of the Gulf (MORCOS, 1970). RADY et al. (1994a) used a vertically integrated two-dimensional and a five-layer three-dimensional numerical model to simulate Gulf is principal tidal component M_2 . Known to be an area that is vulnerable to significant surges (MURTY and EL-SABH, 1984), and that has the largest tidal range and the shallowest water

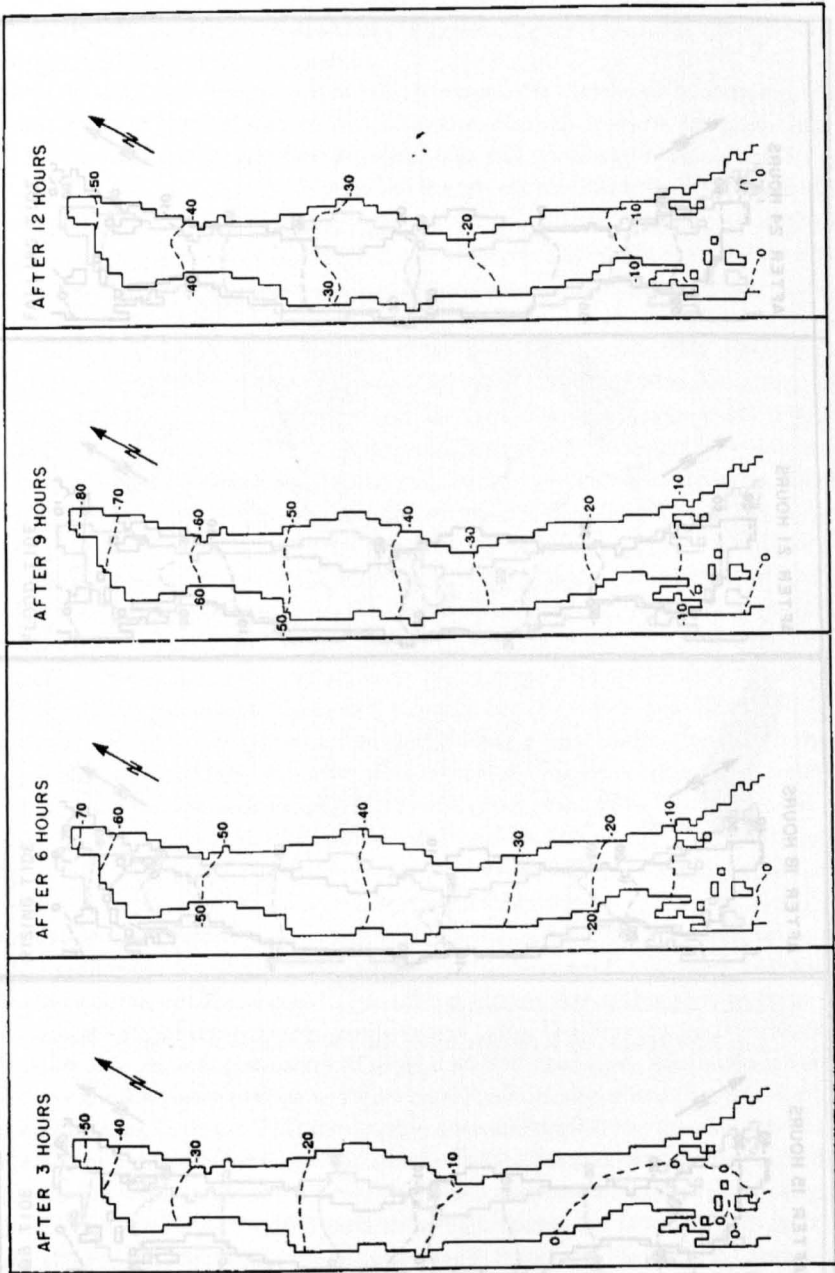


Fig. 4.26: Distribution of storm surge heights at eight different times. Elevations are in centimeters. (RADY et al., 1994 b)

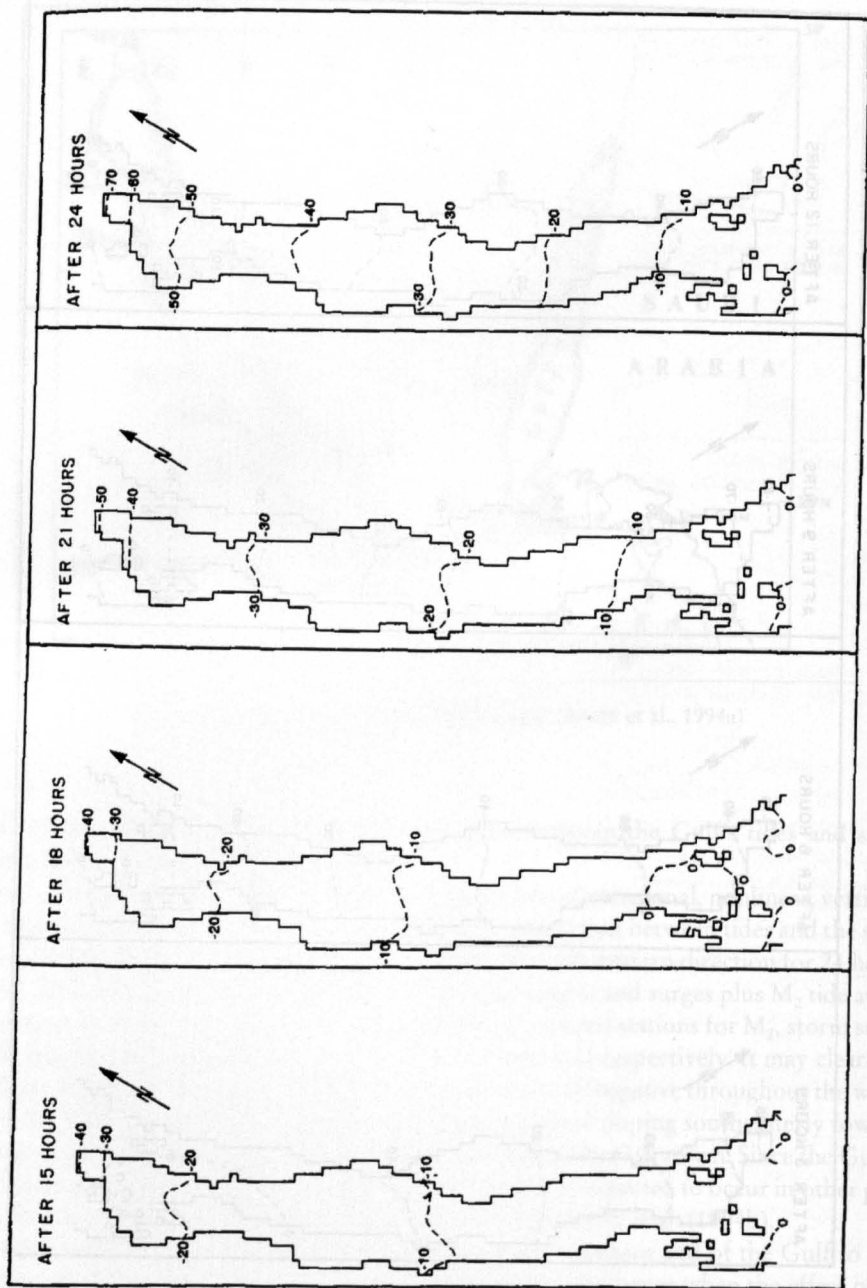


Fig. 4.27: Distribution of storm surge heights at eight different times. Elevations are in centimeters.
(RADY et al., 1994 b)

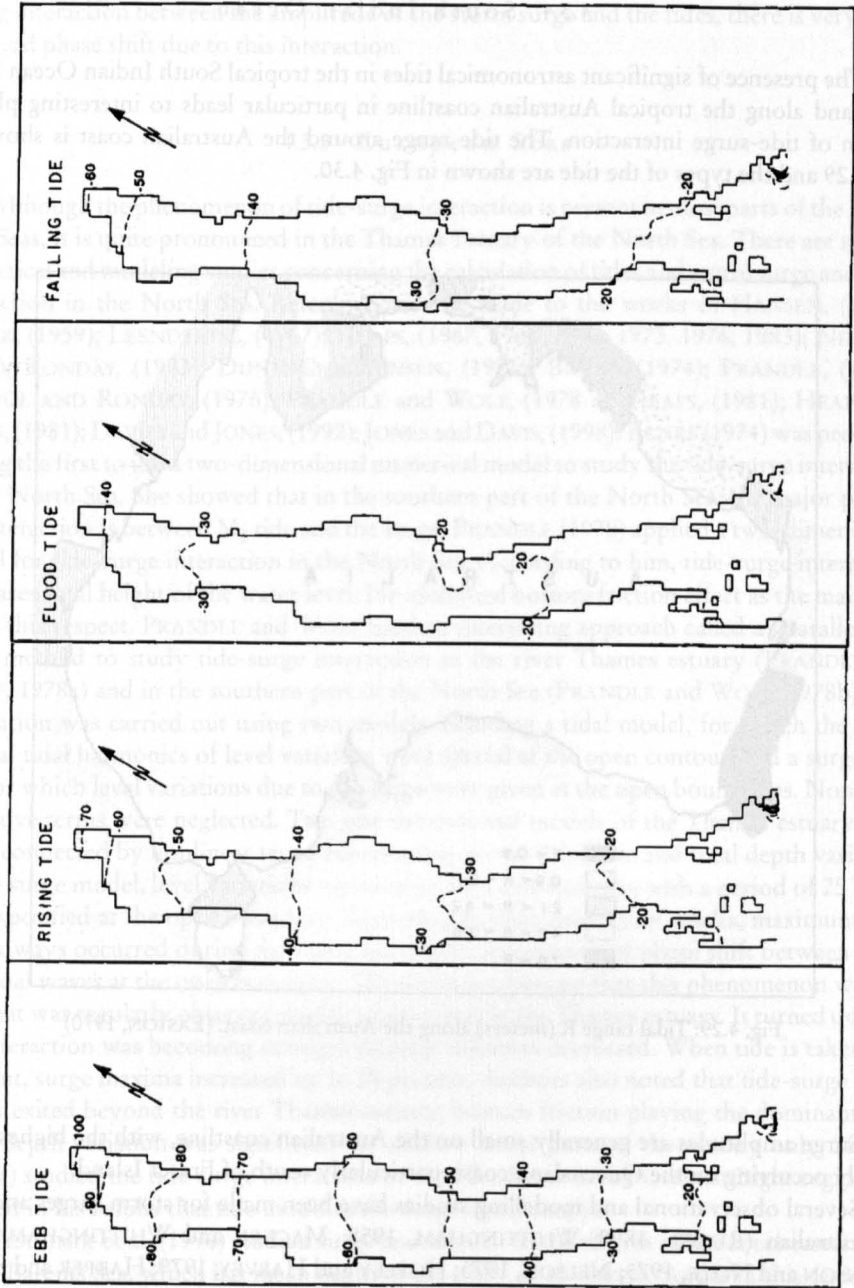


Fig. 4.28: Distribution of storm surge heights plus M_2 tide during the different stages of tide. (RADY et al., 1994 b)

4.3.4 South Indian Ocean

The presence of significant astronomical tides in the tropical South Indian Ocean in general and along the tropical Australian coastline in particular leads to interesting phenomenon of tide-surge interaction. The tide range around the Australian coast is shown in Fig. 4.29 and the types of the tide are shown in Fig. 4.30.

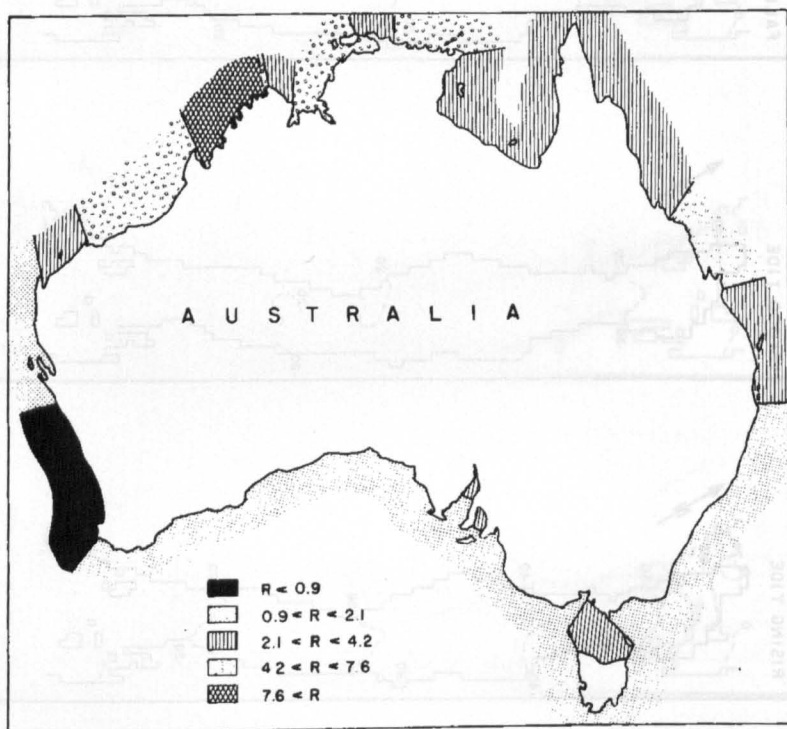


Fig. 4.29: Tidal range R (meters) along the Australian coast. (EASTON, 1970)

Surge amplitudes are generally small on the Australian coastline, with the highest level usually occurring on the Queensland coast, particularly south of Fraser Island.

Several observational and modelling studies have been made for storm surges and tides in Australian (RUSSEL, 1898; WHITTINGHAM, 1958; MACKEY and WHITTINGHAM, 1956; TRONSON and NOYE, 1973; NELSON, 1975; HOPLEY and HARVEY, 1979; HARPER and SOBEY, 1983; MIDDLETON et al., 1984; ANDREWS and BODE, 1988; HUBBERT et al., 1991). TANG et al. (1996) appear to have done the first detailed study of the tide-surge interaction for the Mackay region of the North Queensland coast. They used a two-dimensional model to simulate storm surge and tides. Their results show that with the tides included in the storm surge model the sea level elevation is generally lower than if astronomical tides are simply added to the surges. This effect is attributed by authors to the quadratic bottom friction law rather than the commonly explained reason of nonlinear interaction between the storm surge and the tides. Further, they note that although the quadratic bottom friction does cause a

strong interaction between the amplitude of the storm surge and the tides, there is very little observed phase shift due to this interaction.

4.3.5 European Seas

Although the phenomenon of tide-surge interaction is present in most parts of the European Seas, it is quite pronounced in the Thames Estuary of the North Sea. There are several theoretical and modeling studies concerning the calculation of tides and storm surge and their interaction in the North Sea. Reference may be made to the works of HANSEN, (1956); FISHER, (1959); LEENDERTSE, (1967); HEAPS, (1967, 1969, 1972, 1973, 1976, 1983); NIHOUL, (1973); RONDAY, (1973); DUNN-CHRISTENSEN, (1971), BANKS, (1974); PRANDLE, (1975); NIHOUL AND RONDAY, (1976); PRANDLE and WOLF, (1978 a); HEAPS, (1981); HEAPS and JONES, (1981); DAVIES and JONES, (1992); JONES and DAVIS, (1998). BANKS (1974) was probably among the first to use a two-dimensional numerical model to study the tide-surge interaction in the North Sea. She showed that in the southern part of the North Sea, the major part of the interaction is between M_2 tide and the surge. PRANDLE (1978) applied a two-dimensional model for tide-surge interaction in the North Sea. According to him, tide-surge interaction decreases total height of the water level. He identified bottom friction effect as the main factor in this respect. PRANDLE and WOLF used an interesting approach called a "parallel models" method to study tide-surge interaction in the river Thames estuary (PRANDLE and WOLF, 1978a) and in the southern part of the North Sea (PRANDLE and WOLF, 1978b). The simulation was carried out using two models including a tidal model, for which the semi-diurnal tidal harmonics of level variation were special at the open contour, and a surge model, for which level variations due to the surge were given at the open boundaries. Nonlinear advective terms were neglected. Two one-dimensional models of the Thames estuary were used, connected by nonlinear terms representing power 2 friction and total depth variation. In the surge model, level variations represented by a sine function with a period of 25 hours were specified at the open boundary. According to their simulation results, maximum total level always occurred during the rising tide phase, irrespective of phase shift between surge and tidal waves at the open boundary. The authors supposed that this phenomenon was the one that was regularly observed during surge events in the Thames estuary. It turned out that the interaction was becoming stronger as surge duration decreased. When tide is taken into account, surge maxima increased up to 25 percent. Authors also noted that tide-surge interaction existed beyond the river Thames estuary, bottom friction playing the dominant role. Total depth variation was significant for shallow water parts of the estuary only. SIEFERT (1978a) studied the tide-surge interaction in the Elbe River in the German Bight region. He showed in his results that tide modifies the surge significantly.

VLADIMIR et al. (1996) studied surge and tides in the shelf area of the southeastern part of the Barents Sea, which has mean depth of the order of 45 meters. Surges in this region are of the same order as the tides and may even exceed them. For the model verification and for obtaining information necessary for specification of boundary conditions, results of a special observational programme in the shallow water Pechorskaya Guba were used, which provided data for the analysis of total motion and estimation of tide-surge interaction. Their results show strong nonlinear tide-surge interaction for Shvedskie Stvory where total water level decreases during rising tide period and increase during the opposite phase.

There have also been several attempts to simulate the nonlinear interaction of tides and storm surges in North Sea and Irish Sea using a three-dimensional model. It may not be pos-

sible to describe here the details of these studies. However, one may refer to the works of HEAPS, (1973, 1976, 1981); HEAPS and JONES, (1981); DAVIES and JONES, (1992, 1996); JONES and DAVIES, (1998).

4.3.6 Canada and United States

In this section we will discuss the interaction between storm surges and tides in selected water bodies in Canada and North America. The tidal range along the Canadian coast is significant. In the Bay of Funding the tidal range is more than 12 m. Along the Atlantic coast of Canada, the tide is semidiurnal and the tidal range is usually less than 2 m while the tidal range in the Gulf of St. Lawrence is less than 2.5 m. MURTY (1984) has described in detail the tidal regimes in the coastal waters of Canada and North America. In these shallow coastal waters the interaction between storm surge and tides is found to be significant.

In the St. Lawrence estuary in eastern Canada, observations indicate a predominant occurrence of positive storm surges with low tide and negative surges with high tide. MURTY and EL-SABH (1981) studied the interaction between astronomical tides and storm surges in the St. Lawrence estuary by extending simple analytical theory developed by PROUDMAN (1955a, b, 1957) for the Thames estuary. Based on PROUDMAN (1957) it can be shown that an estuary is short (with reference to long wave propagation) provided the following two conditions are satisfied

$$\left. \begin{aligned} \frac{\sigma L}{c} A &<< 1 \\ \frac{K \sigma^2 L^3 A}{h c^2} A &<< 1 \end{aligned} \right\} \quad (4.15)$$

Where σ is the angular frequency of the tide, L is the length of the estuary, and $c = \sqrt{gh}$
The parameter A is defined as

$$A \equiv \frac{B}{2H} \quad (4.16)$$

where, B is the tidal amplitude at the mouth. Parameter K is a coefficient of bottom friction and is taken as 0.0025. Note that it is not the physical length alone that determines whether or not an estuary is short, in the sense used by PROUDMAN.

Length L , Average depth h , and tidal amplitude B for the two portions of the St. Lawrence Estuary are summarized in Table 4.8. The values of the two PROUDMAN parameters defined by eq. (4.15) are also listed for the two sections. Based on these values, the classification into long or short estuary is made in the final column.

Table 4.8: Dimensions and classifications of the two sections of the St. Lawrence Estuary.

System	Length (km)	Average depth (cm)	Tide amplitude, B (cm)	Proudman's 1 st parameter	Proudman's 2 nd parameter	Classification
Sept-Iles to Sagueny River	350	25×10^3	107	0.002	0.007	Short estuary
Sagueny River to Quebec City	193	1800	215	0.12	6.7	Long estuary

Table 4.9: Number of occasions of positive and negative surges exceeding a given height at Tadoussac during 1965-75. Each hourly reading is treated as one occasion.

State of tide	Surge height (cm)																
	10	20	30	40	50	60	70	80	90	100	110	120	130	140	150	300	
Low Rising High Falling	3806	1763	904	468	260	147	(a) Positive surges										
	4195	2090	1016	515	263	129	77	48	26	16	10	5	3	2	0	0	
	4063	1843	849	390	185	96	81	61	47	29	12	8	4	3	3	3	
	4210	2082	1057	571	315	187	59	33	23	14	3	2	2	2	2	2	
Low Rising High Falling	4466	2046	894	412	192	94	(b) Negative surges										
	4533	2275	1146	634	324	178	44	22	8	1	0	0	0	0	0	0	
	3441	1513	710	363	205	108	94	56	35	16	5	3	2	1	0	0	
	4110	1934	851	385	205	102	52	34	19	15	13	12	9	7	4	2	
							53	35	18	12	8	7	5	3	1	0	

Table 4.10: Comparison between theory and observation of the tide-surge interaction in the St. Lawrence Estuary. H, High tide; L, low tide; R, rising tide; F, falling tide; A, inagreement; D, in disagreement; N, neither agreement nor disagreement.

Station	State of tide with which the Maximum surge is associated		
	Theory	Observation	Comparison
Ste-Anne-des-Monts	H-F	F	A
Baie-Comeau	H-F	H	A
Pointe-au-Pere	H-F	R-H	N
Tadoussac	H-F	R-H	N
Rivriere-du-Loup	L-R	L	A
St-Joseph-de-la-Rive	L-R	H-R	N
St-Jean-Port-Joli	L-R	H	D
St-Francois	L-R	L-R	A
Quebec City	L-R	L	A

Table 4.11: Tidal range and maximum amplitudes of positive and negative surges in the St. Lawrence Estuary

Station	Spring tidal range (cm)	Amplitud maximum positive surge (cm)	Amplitud maximum negative surge (cm)	No. of occurrence of positive surges with amplitude ≥ 180 cm during the period 1965–75 ^a	No. of occurrences of negative surges with amplitude ≥ 130 cm
Ste-Anne-des-Monts	347	180	140	2 (24)	2
Baie-Comeau	402	290	130	2 (15)	8
Pointe-au-Pere	460	300	130	2 (2)	5
Tadoussac	519	300	160	5 (11)	16
Rivriere-du-Loup	567	300	180	3 (3)	21
St-Joseph-de-la-Rive	695	300	250	5 (29)	20
St-Jean-Port-Joli	573	190	180	4 (34)	33
St-Francois	686	240	230	17 (100)	93
Quebec City	580	300	210	32 (157)	20

^a Value in parentheses is number of occurrence for ≥ 130 cm.

The results of PROUDMAN (1957) can be summarized as follows: (a) for a long estuary, for a tide of progressive wave type, maximum surges are associated more with low tide; (b) for a long estuary, for a tide of standing wave type, maximum surges are associated more with high tide; (c) for a short estuary, maximum surges are associated more with high tide. PROUDMAN’s results were reinterpreted (with justification) to read low tide (or rising tide) and high tide (or falling tide) wherever “low tide” or “high tide” appears in the above statements.

The nature of the tide in the section between Sept-Iles and Tadoussac is more of a standing wave type than of a progressive wave type, whereas between Tadoussac and Quebec City the tide is more of a progressive wave type. The cumulative frequency of surges of given amplitude associated with a given state of the tide for Tadoussac is listed in Table 4.9. Although the theory does not distinguish between positive and negative surges, they are listed separately. Similar tables were prepared (not shown here) for the other stations. The observed and theoretical results are compared in Table 4.10. Some pertinent data on the surges in the St. Lawrence Estuary are given in Table 4.11.

The astronomical tide is quite significant in the northern parts of the east coast of the United States and it becomes less and less important as we proceed south and also along the Gulf coast. The problem of tide-surge interaction has not received much attention in the United States. MURTY (1984) has summarised the results of few tide-surge interaction studies carried out for the east coast of United States.

The degree of importance of interaction between tides and surges in United States depends on the location. The tide, surge, and the observed water level at Atlantic City on November 25, 1950, are shown in Fig. 4.30. It can be seen that the maximum surge occurred almost at the time of low tide (SWANSON, 1976).

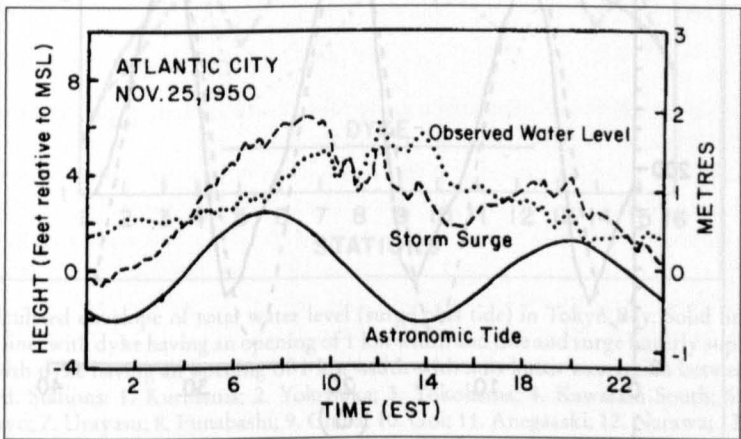


Fig. 4.30: Observed water level, storm surge and astronomical tide at Atlantic City on November 25, 1950. (MURTY, 1984)

4.3.7 China and Japan

Storm surges up to 6 m can occur occasionally on the coast of China, with surges up to 2–3 m occurring frequently. Nonlinear coupling of storm surges and tides is quite pronounced in the shallow water regions of Shanghai on the East China Sea. The mechanism of tide-surge interaction in the coastal waters of China has been investigated by many workers using both analytical and numerical models (CHAI and JINGYONG, 1990; QIN et al., 1994; ZHANG and WANG, 1989; CHOI, 1986; FENGSHU and WENLAN, 1990; YANTING and WANG, 1986, 1990; CHUNYAN, 1990; JINQUAN et al., 1990; YANTING et al., 1992).

More recently QIN and DUAN (1996) have made a detailed study of tide-surge interaction in the coastal water of Shanghai. They used a two-dimensional model to simulate the surge generated by eight tropical cyclones of different tracks crossing the East China Sea

coast near Shanghai. They also analysed in detail the contributions of various nonlinear terms in the dynamic equations to the water levels. Their results show that the nonlinear bottom friction term is of prime importance in controlling the water level and nonlinear tide surge interaction.

Other conclusions drawn by the authors may be summarized as:

- (i) Nonlinear tide surge interaction is prominent in coastal waters of Shanghai.
- (ii) The simulated storm surges comprising the nonlinear tide-surge effect give better results than pure storm surge simulations both in their peak values and the temporal variations (Fig. 4.31)
- (iii) The oscillations with the main tidal period occurring in temporal variation of the water level residuals during tropical cyclone passage are attributed to nonlinear tide-surge interaction.
- (iv) Generally the peak surges occur on rising tides whereas they become weaker during the falling tides. This is because of the nonlinear tide-surge interaction.

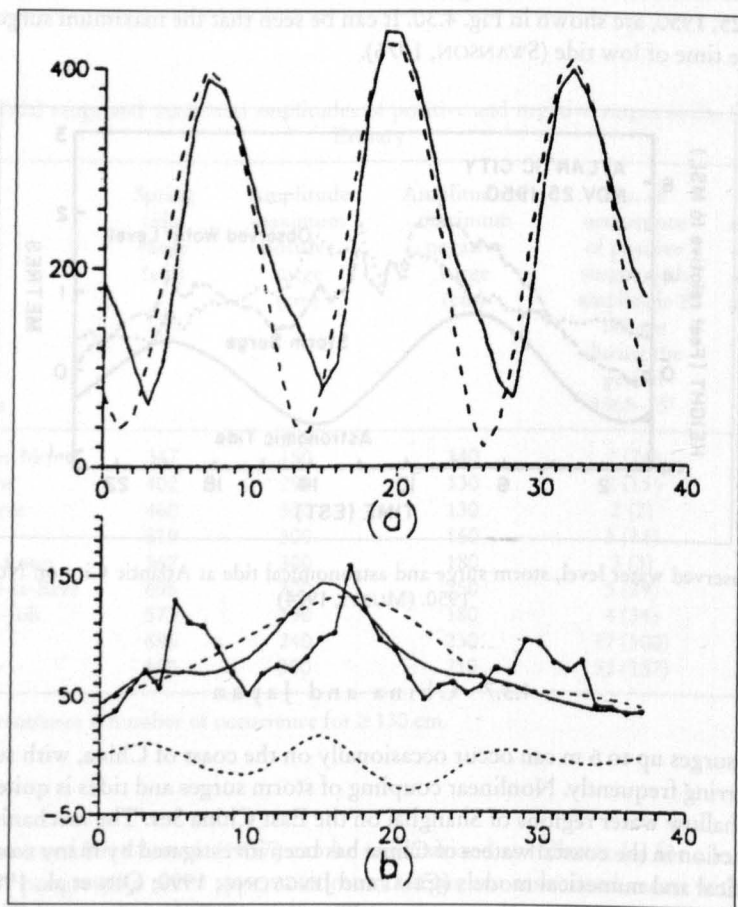


Fig. 4.31: Simulations of tide, storm surge and water level caused by nonlinear T-S coupling during TC Mary (1974). (a) Tide level: solid line – tidal level prediction with 63 constituents (observed), dash line – tidal level prediction with 8 constituents (simulated). (b) Storm surge: solid line with symbols – observed surge, solid line without symbols – simulated surge comprising T-S coupling effects, long dash line: simulated pure surge, short dash line: simulated. (QIN and DUAN, 1996)

Tide-Surge interaction on the coast of Japan is not as important as in China Sea and therefore not many studies have been done in this area. Using two-dimensional numerical model, ITO et al. (1965) studied the problem of tide-surge interaction and the influence of a dyke in Tokyo Bay. Based on the analysis of the results of several runs they conclude that linear superposition of the tide and surge tends to overestimate the total water level (Fig. 4.32).

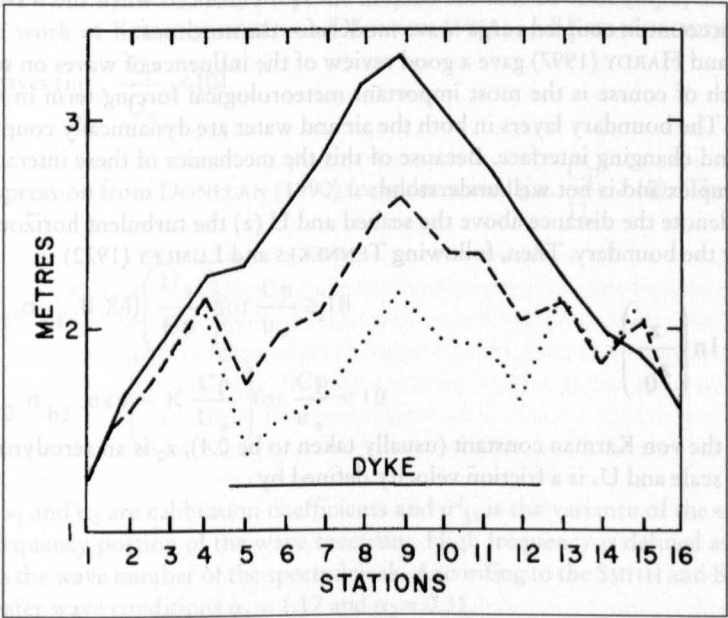


Fig. 4.32: Calculated envelope of total water level (surge plus tide) in Tokyo Bay. Solid line: without dyke; broken line: with dyke having an opening of 1 km width and tide and surge linearly superimposed; dotted line: with dyke having an opening of 1 km width with non-linear interaction between tide and surge included. Stations: 1. Kurihama; 2. Yokosuka; 3. Yokohama; 4. Kawasaki South; 5. Kawasaki North; 6. Tokyo; 7. Urayasu; 8. Funabashi; 9. Chiba; 10. Goi; 11. Anegasaki; 12. Narawa; 13. Kisarazu; 14. Futtusu; 15. Ison; 16. Kaiho II. (ITO et al., 1965)

4.4 Surge-Wind wave Interaction

The state of the art in this field is still evolving and there are at present no universally accepted and definitive approaches. Hence we will discuss the methodologies used by a few different authors.

We start with the excellent review of BODE and HARDY (1997). They point out that the specification of wind stress only as a function of the wind speed – underestimates the very important role played by wind waves in the transfer of momentum across the atmosphere-ocean interface, particularly for tropical cyclones.

These interactions occur through at least the following three mechanisms:

- 1) Radiation Stress
- 2) Enhanced Surface Wind Stress
- 3) Enhanced Bottom Stress

The Radiation Stress concept, originally proposed by LONGUET-HIGGINS and STEWART (1964) has been used in computing wave set up in storm surge models (e.g., HUBERTZ, 1985).

MASTENBROEK et al. (1993) included radiation stress forcing in a coupled storm surge-wind wave model. They subtracted the gradient of the radiation stress from the wind stress terms in the momentum equations. Their results for the North Sea showed that the contribution from the radiation stress is negligible compared to the contribution from the wind stress. The tide, surge and wind wave components of the water level contribute to the bottom current. The bottom stress depends upon the bottom current in a nonlinear fashion. In shallow water, waves could have a significant influence on the bottom current. WU and FLATHER (1992) and WU et al. (1994) showed that the bottom stress is enhanced when the wave effects are taken into account in coupled surge-wave models for the north sea.

BODE and HARDY (1997) gave a good review of the influence of waves on surface wind stress, which of course is the most important meteorological forcing term in storm surge generation. The boundary layers in both the air and water are dynamically coupled through a moving and changing interface. Because of this the mechanics of these interactions is extremely complex and is not well understood.

Let z denote the distance above the seabed and $U(z)$ the turbulent horizontal velocity profile near the boundary. Then, following TENNEKES and LUMLEY (1972)

$$U(z)=\frac{U_*}{k}\ln\left(\frac{z}{z_0}\right) \tag{4.17}$$

where, k is the von Karman constant (usually taken to be 0.4), z_0 is an aerodynamic roughness length scale and U_* is a friction velocity defined by

$$U_*^2=\frac{\tau_s}{\rho_w} \tag{4.18}$$

where τ_s is the surface stress and ρ_w is the density of air.

CHARNOCK (1955) suggested that

$$z_*=\frac{gz_0}{U_*^2}=\alpha \tag{4.19}$$

where, α is a constant. This means that z_0 (which is a measure of the aerodynamic roughness) varies linearly with the surface stress τ_s .

Field observations suggest that α is not constant but is dependent on at least the water depth and wave age. The value of α varies from about 0.011 for older or deep water waves SMITH (1980, 1988) to about 0.018 for younger or shallow water waves (WU, 1980, 1982)

Further analysis of field data showed that z_0 is a function of wave age, usually specified as C_p/U_* where C_p is the wave celerity of the peak frequency and U_* is the friction velocity. Hence

$$z_*=\frac{gz_0}{U_*^2}=f\left(\frac{C_p}{U_*}\right) \tag{4.20}$$

As given by DONELAN (1982), GEERNAERNT et al. (1986) and SMITH et al. (1992). Equation (4.20) was rewritten as

$$z_* = \frac{gz_0}{U_*^2} = \frac{\mu}{C_p/U} \tag{4.21}$$

where, μ is a constant (MAAT et al., 1991)

JOHNSON and VESTED (1992) proposed a hybrid model for the computation of Z_0 , following the work of KITAIGORODSKII and VOLKOV (1965) and KITAIGORODSKII (1973) for younger waves (i.e., $\frac{C_p}{U_*} < 10$).

With an expression from DONELAN (1990) for older waves (i.e. $\frac{C_p}{U_*} \geq 10$). This leads to

$$Z_0 = \begin{cases} \alpha_1 \cdot \sigma_{hf} \cdot (1.84) \left(\frac{U_*}{C_p} \right) & \text{for } \frac{C_p}{u_*} \geq 10 \\ \alpha_2 \cdot \sigma_{hf} \cdot \exp \left(-K \frac{C_p}{U_*} \right) & \text{for } \frac{C_p}{u_*} < 10 \end{cases} \tag{4.22}$$

Here α_1 and α_2 are calibration coefficients and σ_{hf}^2 is the variance of the sea surface in the high frequency portion of the wave spectrum. High frequency is defined as $K > 1.5 K_p$, where K_p is the wave number of the spectral peak. According to the SMITH and BANKE (1975) for deep water wave conditions $\alpha_1 = 1.17$ and $\alpha_2 = 0.31$.

This means that the drag coefficient is a function of wave age, wave height and water depth. MASTENBROEK et al. (1993) examined the effect of waves on the drag coefficient. Instead of parameterizing the dimensionless roughness coefficient, they followed the theory of JANSSEN (1991), which hypothesizes that close to the water surface waves contribute separately to the surface shear stress. Thus

$$\tau_s = \tau_t + \tau_w \tag{4.23}$$

Where τ_t is the turbulent shearing stress and τ_w is the wave-induced stress.

This τ_w changes the boundary layer in the air close to the surface, so that the velocity profile assumes a modified logarithmic form.

They coupled the surge and wave models dynamically, and their results were significantly greater surges than would be obtained by using the drag coefficient of SMITH and BANKE (1975).

However, the disappointing point is that, instead of these more complicated computations, a simple increase of the drag coefficient of SMITH and BANKE (1975) would have given same results.

Approach by Yamashita and Watson

During surges there are complex mutual interactions between wind, waves and currents. The wind generates waves, which influence the wind drag coefficient and hence the wind-driven currents and the surge height. In turn, the currents influence the wave field and the waves influence the wind field. In order more accurately to predict surges, waves and flooding, a thorough understanding of these air-sea interaction processes is important.

The relation between mean wind and wind stress and the influence of waves on this relationship is investigated using data from a new observation tower about 2 km offshore in Tanabe Bay. This measures wave elevation, 20-m wind and 10-m depth current in about 30 m of water. Wind stress and drag coefficient estimates are made using the inertial dissipation method. Data taken during a typhoon are found to show enhanced stress compared with values from empirical formulae in the literature.

For storm surge modelling, the most important forcing terms are the atmospheric pressure, the surface wind stress and the bottom friction stress. The former is of course theoretically well defined and depends only on a reasonably accurate knowledge of the relevant time-dependent pressure field. The stress terms however are not so simple and are normally represented using empirical approximations. These are based on what data are available, which are rather limited and scattered. There is much room for improving our physical understanding of these stresses and then the accuracy of the corresponding forcing terms.

One current area of research is the influence of waves, on both wind stress and bottom stress. Waves are a crucial and complex part of the process of momentum transfer between air and sea, involving the two-dimensional wave spectrum wave growth and decay, non-linear interactions and wave breaking. A forcing term in which the surface stress is a simple function of wind speed is a useful first approximation, and produces acceptable results in many circumstances. However, it is certainly oversimplified and there may be important cases where it is inaccurate, especially in situations where the wind is rapidly changing (such as in tropical storms), near the coast where the water is shallow and the waves fetch-limited, or where the wave spectrum has more than one significant component. Such cases could potentially be more accurately represented by a theory, which correctly accounts for momentum transfer between wind and waves, and between waves and the mean current.

Another effect of waves, which may be important in some circumstances, is their influence on the bottom, stress. In shallow water, wave orbital velocities can be quite large and the flow over the rough bottom produces turbulence. This increases the eddy viscosity experienced by the mean flow and thus the force acting between the mean flow and the bottom.

Using a wave model to predict wave conditions during surge generation, and then modifying the surface may estimate the effect of these processes on surge models and bottom drag coefficients, depending on appropriate properties of the local wave spectrum as outlined below.

The mean force acting on the surface of a body of water due to wind stress is usually approximated as

$$\bar{\tau}_s = \rho_a C_{D10} \bar{U}_{10} |\bar{U}_{10}| \quad (4.24)$$

where, $\bar{\tau}_s$ is the wind stress at the surface (the horizontal force per unit area acting on the surface), ρ_a the air density, \bar{U}_{10} the mean wind at 10 m and C_{D10} the drag coefficient for wind at 10 m.

With a constant drag coefficient, this formula is found to be reasonable for airflow over

solid rough surfaces. However, as wind speed increases over the sea, the waves get bigger and the surface gets rougher. Thus, for eq. (4.24) to be useful, the drag coefficient must be allowed to vary with wind speed: $C_D(U)$.

For fully developed seas in which the waves are approximately in equilibrium with the local wind, observations of wind stress as a function of wind speed have led to several empirical relations for $C_D(U)$. The data are scattered, but the relationships resulting from the various datasets are all quite similar. Four examples of such formulae are listed in Table 4.12. Note that these data mainly apply to wind speeds greater than about $5\text{--}10\text{ ms}^{-1}$.

However, these results only apply to well-developed seas in deep water. Higher values of C_D found both in growing waves, such as during the onset of a storm and in shallow water. Both of these conditions are necessary for the development of a storm surge, so the effect is potentially important. However, what field data exist are hard to interpret, because the effect is comparable in size with measurement errors, and therefore cannot be determined very accurately. It has not so far been possible to derive any empirical relationship between wind stress and wave conditions, based on the data.

JANSSEN (1991) considers the extra momentum extracted from the wind by growing waves, and then passing into the mean flow. This enhancement of momentum transfer effectively increases the drag. An important parameter here is the ratio of dominant wave phase speed to wind speed, known as the wave C_p/U , which is a measure of whether or not the wind and waves should have reached equilibrium. The effect is not usually incorporated in surge models, and it is uncertain how significant it may be.

The mean retarding force acting on a body of water due to bottom friction is usually approximated as

$$\bar{\tau}_b = \rho_w C_{Db} \bar{u} |\bar{u}| \quad (4.25)$$

where, $\bar{\tau}_b$ is the bottom stress, ρ the water density, \bar{u} the wave-averaged bottom current and C_{Db} a bottom drag coefficient. For many applications, it is found good enough to use a constant value for C_{Db} .

In shallow water, wave-induced flow near the bottom results in an increase in turbulence. Amongst other things, this increases the rate of vertical transfer of horizontal momentum, and hence the mean drag force between the water and the seabed. This is represented theoretically as an increase in eddy viscosity (which parameterizes the effect of small-scale turbulence in increasing the shear stresses) and hence of the drag coefficient in eq. (4.25).

MASTENBROEK (1992) estimated the size of this effect for storm surges in the North Sea using the relationship between drag coefficient and significant wave height, $C_{Db}(H_s)$. He found that in some shallow areas it could significantly affect the predicted surge, more so than the effect of a wave-dependent wind drag coefficient. However, the size of this effect is similar to that of geographical variations in C_{Db} due to variations in bed roughness. This makes practical implementation difficult because of the lack of sufficiently detailed data on bed roughness.

It should also be pointed out that another effect of waves on local water level at the coast is that of wave set-up. Depending on the beach topography and wave conditions, this can sometimes raise sea level within the surf zone by up to about 1 m. It is an effect that should also be taken into account when considering the flood risk during storms and surges.

The Kyoto University Disaster Prevention Research Institute's Tanabe-Nakajima Storm Surge Observation Tower is located in 30 m of water about 2 km from the coast near Tanabe, in southern Honshu Island, Japan (Wakayama Prefecture). The tower stands at the mouth of

Tanabe Bay, on a plateau of about 10 m depth, around 100 m in diameter, in an area where the depth is predominantly 30 m. It is possible that this plateau will have some local influence on the waves, but it is difficult to determine. The site is in the approaches to the densely – populated area around Osaka Bay. Typhoons regularly cause surges in this area and defenses against these form a significant element of coastal engineering works.

The main instruments of interest here are a 3-component ultrasonic anemometer at about 20 m heights, and a downward-looking ultrasonic wave gauge. Data are recorded at 20 Hz during 20 minutes of each hour. There is also an electromagnetic current meter at a depth of 10 m.

Following YELLAND et al. (1994), wind stress was estimated from the anemometer data using the turbulent (or inertial) dissipation method. This is one of the two commonly used methods, the other being the direct, or eddy-correction method. The latter was also attempted but it was found that 20-minute data samples were not long enough to give convergent results.

The turbulent dissipation method is based on the assumption of a cascade of energy from lower to higher frequencies, at a rate, which is governed, by the rate of dissipation of energy by turbulence at the high-frequency end of the spectrum. The turbulence is assumed to be “frozen”, i.e. the time scales are slow compared with the time scale of advection past the observation point. These assumptions yield:

$$S(f) = K \epsilon^{2/3} f^{-5/3} \left(\frac{U}{2\pi} \right)^{2/3} \tag{4.26}$$

where, $S(f)$ is the power spectrum of the down-wind component, K is the 1-D Kolmogorov constant, taken as 0.55, and ϵ is the high frequency turbulent dissipation rate. If the measured spectrum is found to obey the $f^{-5/3}$ law reasonably well, then an average value of $S(f)f^{5/3}$ over an appropriate frequency range (0.8–2.0 Hz was used here) may be used in (4.22) to estimate ϵ . The wind stress τ is then estimated from

$$\tau = \rho (k_v \epsilon z)^{2/3} \tag{4.27}$$

where, k_v is the von Karman constant (here taken as 0.4), z is the measurement height (20 m). The drag coefficients is then obtained from (4.20) after correcting the observed mean wind to an estimated value at 10 m using the relation for a logarithmic boundary layer,

$$\frac{U(z)}{U(10)} = \frac{\ln(z/z_0)}{\ln(10/z_0)} \tag{4.28}$$

where, z_0 is the roughness length $z_0 = e^{-k_v} \sqrt{C_D}$. It should be noted that (4.26) applies to neutral atmospheric stability. A correction is possible for non-neutral conditions, but was found to be small in this case.

The final estimates of wind stress for 29th Sept 1994, excluding the data from 22:00 and 23:00 are plotted against mean wind speed in Fig. 4.33. The four empirical relations from Table 4.12 are plotted for comparison. Particularly at intermediate wind speeds (5–15 ms⁻¹), the data lie well above these curves. These data appear to be an example of departure from

the standard formulae and are thus worthy of further investigation. There is no obvious trend with wind speed, and as with other such data, they are rather scattered. If anything, these data suggest that a constant drag coefficient may be appropriate in this instance. The mean value is 2.2×10^{-3} . However, this is only a small amount of data and it will be necessary to examine a larger amount, including normal wind conditions, in order to draw firm conclusions.

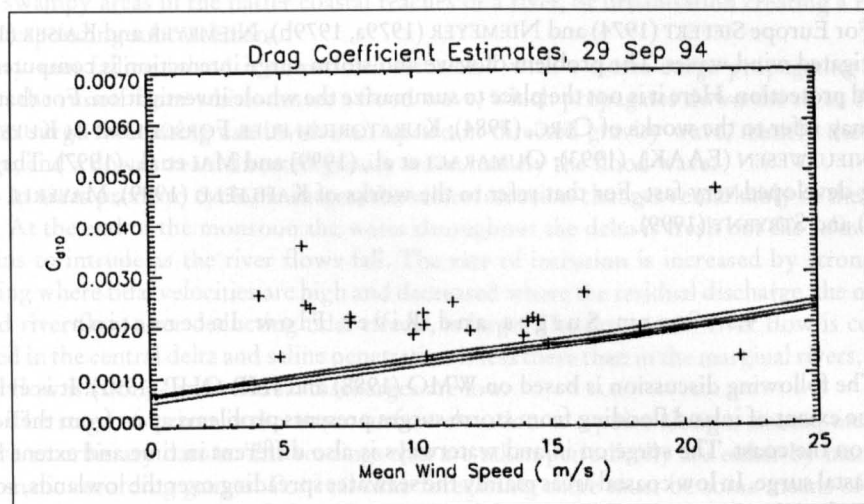


Fig. 4.33: Drag coefficient estimates against wind speed during the typhoon.
(YAMASHITA and WATSON, 1997)

The next stage of this work, in addition to further analysis of the wind stress data, will be to incorporate wave effects into a surge model. The first step is to use an ocean wave model to predict the time-dependent wave field during the storm. This has been done for the cyclone, which struck Bangladesh in April 1991, causing a severe disaster in which 150,000 people died. The model is that of YAMAGUCHI et al. (1979) and is a second-generation model, whereas third generation models, which include a more accurate calculation of non-linear interactions, such as WAM, are now available. However, it is uncertain whether this would be any more applicable in the highly nonlinear situation in the extensive shallow region near Bangladesh, and so the more convenient second-generation model was used. Qualitative differences are not expected.

The calculation gives contours of significant wave height during the approach of the cyclone, with a maximum of 15 m being predicted near the cyclone centre. The next step will be to take the results for wave height and use them to modify the surface and bottom drag coefficients in the surge model, as outlined above. In this way the size of wave effects on the surge prediction will be accessed.

ZHANG and LI (1996) have implemented a coupled wave-surge model using JANSSEN's theory for the effect of waves on wind stress, including radiation stress terms, but not considering the effect of waves on bottom stress.

Table 4.12: Empirical Formulae for Wind Drag Coefficient as a function of Wind Speed. (From YAMASHITA and WATSON [1997])

YELLAND and TAYLOR (1996)	$C_{D10} = (0.60 + 0.070U_{10}) \times 10^{-3}$	$U > 6 \text{ ms}^{-1}$
SMITH et al. (1992)	$C_{D10} = (0.66 + 0.072U_{10}) \times 10^{-3}$	(HEXOS data)
ANDERSON (1993)	$C_{D10} = (0.49 + 0.071U_{10}) \times 10^{-3}$	
SMITH and BANKE (1975)	$C_{D10} = (0.63 + 0.066U_{10}) \times 10^{-3}$	

For Europe SIEFERT (1974) and NIEMEYER (1979a, 1979b), NIEMEYER and KAISER (1997) investigated wind waves. The problem of wave and storm surge interaction is computed for coastal protection. Here it is not the place to summarize the whole investigation. For that readers may refer to the works of CERC, (1984); KURATORIUM FUER FORSCHUNG IM KUESTEN-INGENIEURWESEN (EAAK), (1993); OUMARACI et al., (1999) and MAI et al., (1997). The modeling developed very fast. For that refer to the works of KAHLFELD (1999), MAYERLE et al. (1994) and STRYBNY (1999).

4.5 Storm Surges and River Flow Interaction

The following discussion is based on WMO (1988) and IHP-OHP (1991). It is evident that the extent of inland flooding from storm surges presents problems apart from the actual surge on the coast. The surge on inland waterways is also different in time and extent from the coastal surge. In low coastal areas mainly the seawater spreading over the lowlands, sometimes as far inland as 100 km, disposes of the surge. In Bangladesh storm surges are reported to reach as far as 160 km inland in recent times. The invasion of the surge water into the marshes creates and expands open bodies of water. The waves, generated by the wind over these bodies, help to transport greater amounts of water inland. The return of this water to the sea is a slow complicated process.

The seiches in inland lakes must be taken into consideration along with the surge to determine flooding possibilities.

As more industries and people continue to move into coastal areas subject to flooding, the determination of the extent of inland flooding becomes increasingly important for the protection of life and property. It is also becoming more difficult to determine the extent of the flooding. The continual construction or changing of levees, canals, navigable waterways, drainage, protective barriers, and other factors, contribute to the complexity of the inland inundation problem. Further complications arise by the changes, which occur in the maze of levees. Natural changes, erosion and subsidence take their toll; also pilfering of the fill or actual cutting of the levees weakens the systems.

An important distinction arises between the tropical and extra-tropical situations; although much more intense, the rainfall flooding arising from tropical cyclones are much more limited in extent than the low-pressure systems associated with extra-tropical surges. Thus, only small regions adjacent to landfall will be affected, but this response will very probably coincide with the most severe portion of the surge. If coincidence occurs in the larger, longer lag-time basins affected by extra-tropical low-pressure systems, it is probable that the cause of the flood was due to an earlier event.

Thus the following sets of conditions can be listed as criteria for joint fluvial and surge flooding (WMO, 1988):

- (a) In small islands subject to hurricanes, such as the Philippines, Japan and the West Indies, where river response times are short;
- (b) Where antecedent conditions have predisposed a larger river to flood and this coincides with a sea surge. This can occur in both tropical and extratropical locations. As an example of the former, a stationary front often lies over Japan in September and early October; the saturated conditions and regular rainfall, often intensified by a typhoon, lead to regular coincidences of floods and surges;
- (c) Where human activities have shortened the lag time. Examples are reclamation of the swampy areas in the flatter coastal reaches of a river, or urbanisation creating a rapidly responding subcatchment.

Heavy rain falling inland is sometimes associated with a storm surge propagating into a river, the runoff from which causes a flood wave, which propagates down the river. Hence, storm surge forecasting can involve an upstream-directed gravity wave, namely the storm surge, and a downstream directed gravity wave, namely the flood wave.

In areas prone to cyclonic surges, the saline intrusion changes remarkably in the estuaries. At the end of the monsoon the water throughout the delta is fresh but the saline front begins to intrude as the river flows fall. The rate of intrusion is increased by strong tidal mixing where tidal velocities are high and decreased where the residual discharge, the net seaward river flow after deducting tidal effects, is large. The dry season river flow is concentrated in the central delta and saline penetration is less there than in the marginal rivers, where tidal flow is strong- and residual discharges are low.

The stage of a river is the water surface elevation at a point along a stream, measured above an arbitrary datum. The readings that are taken periodically are either by manual or automatic recording gauges. For real-time forecasting there must be some means of transmitting the stage to the forecast centre.

If required, the stage is converted to a discharge by a stage discharge relationship (often termed the rating curve). A regular programme of current measurements of simultaneous flow and stage observations calibrates the relationship. Such a curve is approximately parabolic, or else linear, on double logarithmic paper. Detailed guidelines on observational practices are to be found in many textbooks and manuals including the WMO Guide to Hydrological Practices.

In a tidally affected river the uniqueness of the stage discharge relationship will be lost. However, it is often possible to construct an approximate relationship for a given downstream stage if a sufficient number of current measurements is available and the estuary level is also read simultaneously.

Efforts should also be made to derive a roughness coefficient for the river. This will be required for the models to be described in subsequent chapters. Again, techniques for this are to be found in hydrometric manuals such as the WMO Manual on Stream Gauging (WMO, 1988).

Tropical cyclones produce large amounts of rainfall. Extra-tropical surges also are associated with rain-producing weather systems. While rain does not have a direct influence on the surge magnitude in the sea, its influence on the river and its coincidence with the sea surge can create critical conditions.

Statistical information required for design work is obtained from climatological reports. Information should include depth-duration-frequency data, areal reduction factors and temporal patterns of past major events.

Rivers are small compared with the adjacent ocean region. The tidal energy of the river can therefore be regarded as originating in the estuary and arriving at the river mouth as a

specifiable boundary condition. The theory that has been applied has related mainly to idealised estuaries and has discussed the surge in terms of standing waves, progressive waves or possible resonance effects. As a general statement, frictional damping becomes the dominant influence in long narrow shallow water bodies. This is the factor most difficult to assess accurately hydrodynamic computer models as well as in empirical formulations.

If water levels fail to respond to upstream floods then the location is tidedominated. Conversely, river domination can be assumed for a location with no response to the flows.

4.5.1 Elbe Estuary (Germany) as case study

The following is based on IHP-OHP (1987, 1991) using SIEFERT (1978b, 1979, 1991) and SIEFERT and HAVNOE (1989).

The concept for understanding the dynamics of storm surges is very simple: Storm surge behaviour in a river is treated as a problem of combination of boundary values and eigenvalues. To solve these problems mathematically, a lot of differential equations have to be solved. Alternatively a hydraulic model (including all eigenvalues) with variation of the boundary values can be applied. This was done for the Elbe (for 200 long river-km) with special respect to Hamburg (Fig. 4.34) and consequently transferred to other rivers (Fig. 4.35).

It turned out that all other influences than astronomical result in a special, individual surge curve in the estuary. Thus we have to consider only two curves as seaward boundary values: the (more or less regular) tide curve and the (irregular) surge curve. These have to be combined with the eigenvalues of the tide-river dynamics. The latter can be considered constant during individual storm events. They are mainly changed by man (deepening and widening of fair-way, course corrections, new dyke lines, weirs, dams, sluices etc.) and are varying through the decades. The upper boundary value (discharge) can also be treated as constant during a surge.

The identification of the seaward boundary values is done by separation of the astronomical or (in first-order approximation for this area) of the mean tide and the surge (Fig. 4.36).

In a first step of approximation the surge curve was characterised by 5 parameters as shown in Fig. 4.37. After these treatments it was investigated how these curves behave when they proceed in a river, and especially, how they interact.

Correlations between storm tide elevations at different locations along a tidal river show no significant coherence. For interpretation of tidal dynamics it is necessary to take into account the complete curves.

HAARLEMAN and LEE give some methods for the solution of tidal propagation in estuaries. The harmonic solution of the linear function equation for the tidal elevation at any x and t

$$\eta = \frac{\eta_0 H}{2} \cdot e^{-\frac{\delta x}{2}} \cdot (e^{\mu x} \cos(\sigma t + kx) + e^{-\mu x} \cos(\sigma t + kx)) \tag{4.29}$$

contains the amplitude attenuation coefficient μ or the damping parameter μx .

Using μ and the variation of the damping parameter $d\mu x / dx$ the simple equation for wave propagation in shallow water could be modified to

$$c = S \sqrt{g \cdot d^*} \tag{4.30}$$

with g = acceleration of gravity d^* = representative water depth in a river

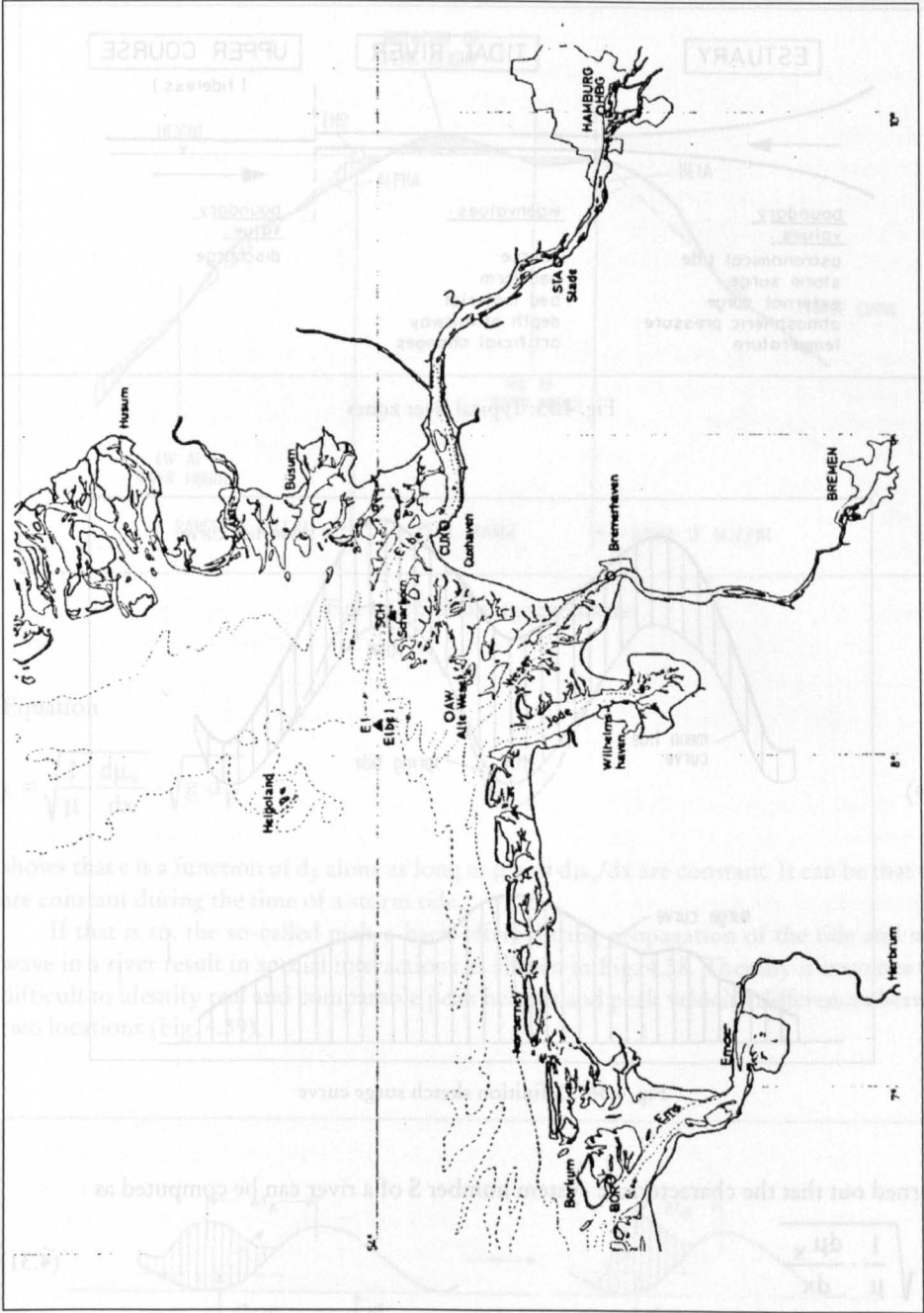


Fig. 4.34: German Bight with Elbe estuary

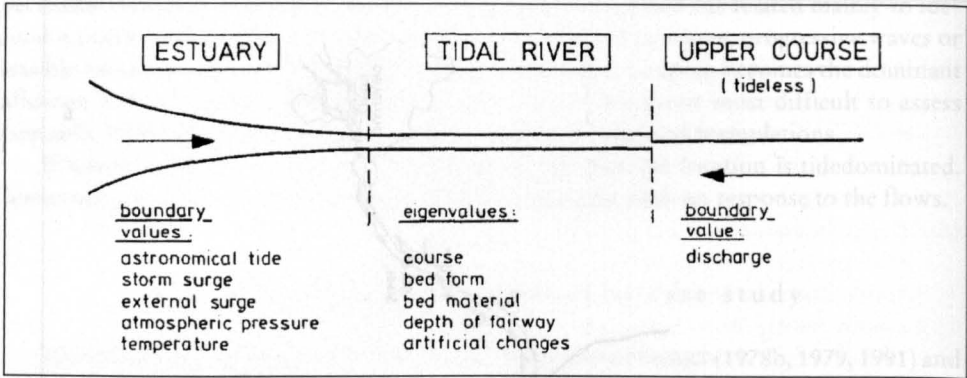


Fig. 4.35: Typical river zones

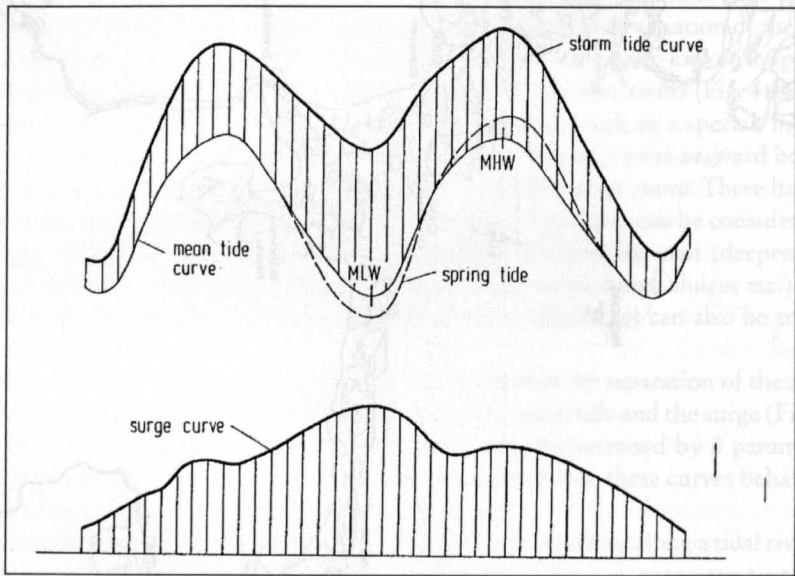


Fig. 4.36: Definition sketch surge curve

It turned out that the characteristic system number S of a river can be computed as

$$S = \sqrt{\frac{1}{\mu} \cdot \frac{d\mu_x}{dx}} \tag{4.31}$$

The values vary from 0.56 for the Elbe to 1.11 for the Delaware. It changes with time, i. e. with secular changes in the river as was mentioned before.

Computations of a lot of tide and storm surges showed that the “representative water depth” d^* in a river is characterised by the depth of the fair-ways d_F . This fact is best proved in rivers with a distinct fair-way of a certain length, as tide and storm surge dynamics are the more concentrated at the fair way the deeper it is, relative to the remaining cross-section.

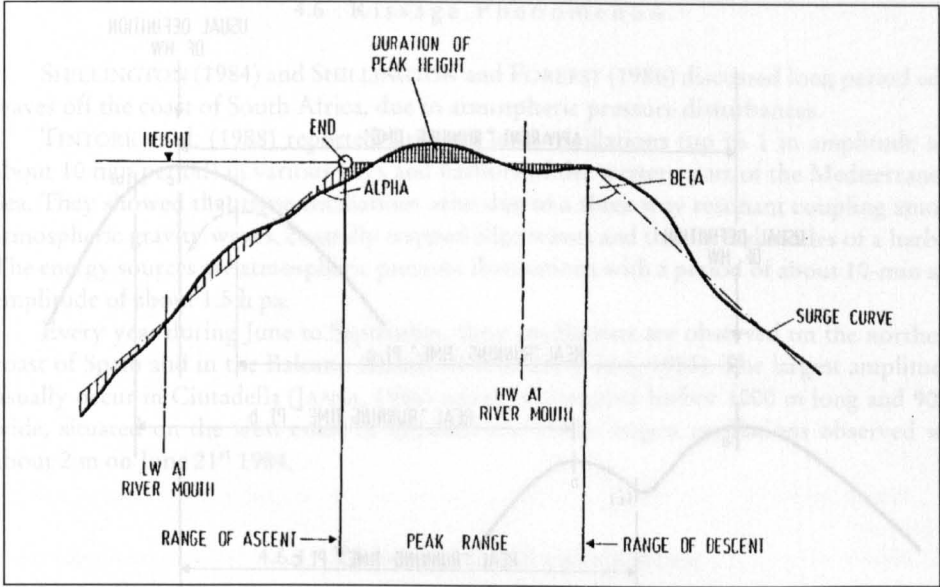


Fig. 4.37: Storm surge parameters

Equation

$$c = \sqrt{\frac{1}{\mu} \cdot \frac{d\mu_x}{dx}} \cdot \sqrt{g \cdot d_F} \tag{4.32}$$

shows that c is a function of d_F alone as long as μ and $d\mu_x/dx$ are constant. It can be that they are constant during the time of a storm tide.

If that is so, the so-called pick-a-back-effect during propagation of the tide and surge wave in a river result in special interactions as shown in Fig. 4.38. Thereby it becomes very difficult to identify real and comparable peak heights and peak velocity differences between two locations (Fig. 4.39).

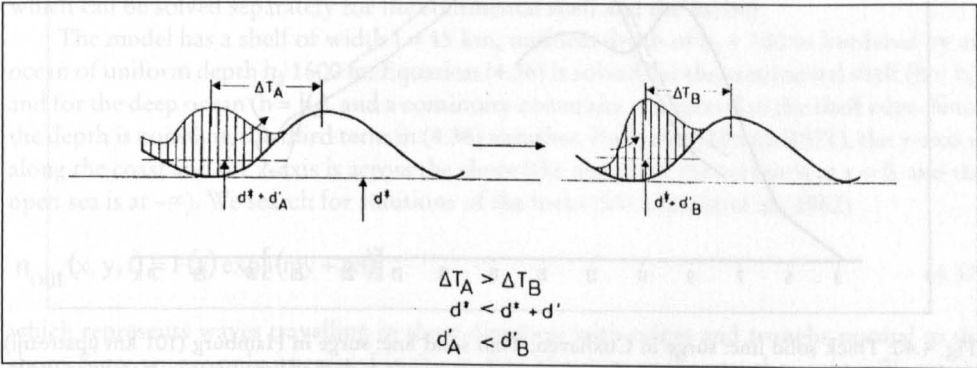


Fig. 4.38: So-called pick-a-back-effect

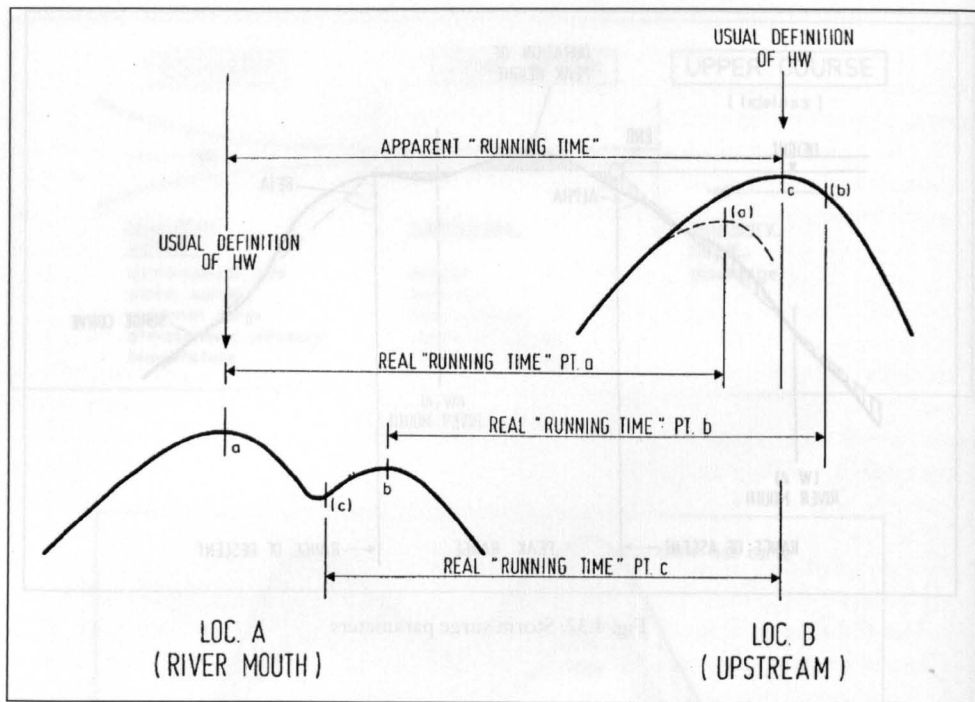


Fig. 4.39: Example of shape variation of the tide curve between two locations

The interactions result in differing propagation velocities not only of the surge, but also of the tide. The shape of the surge curves in Fig. 4.40 may illustrate this. Surges occurred on January 3, 1976, during the highest storm tide ever registered in the Elbe. The comparison of shapes indicates that tidal wave must run a lot faster than usual. As only small alterations of the surge curves are to be expected, best-fit shifts have to be found.

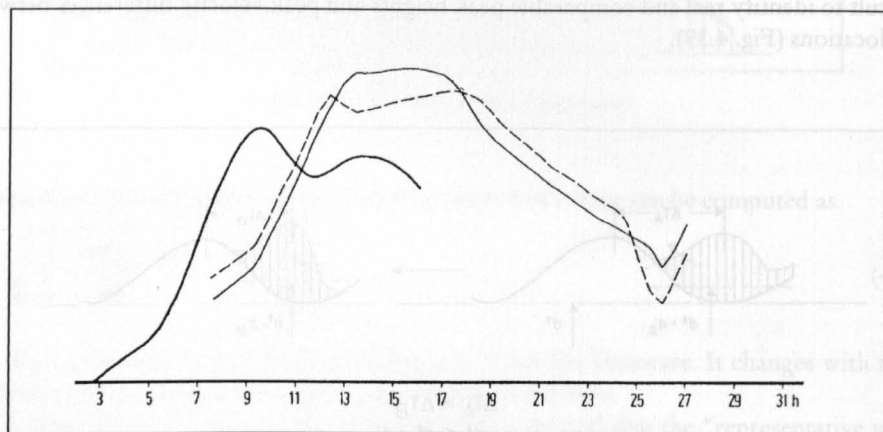


Fig. 4.40: Thick solid line: surge in Cuxhaven; Thin solid line: surge in Hamburg (101 km upstream), evaluated under the hypothesis of undisturbed tidal propagation; dashed line: surge in Hamburg, evaluated under the hypothesis that tidal propagation from C. to H. lasted 3 h instead of the usual 4 h

4.6 Rissaga Phenomenon

SHILLINGTON (1984) and SHILLINGTON and FOREEST (1986) discussed long period edge waves off the coast of South Africa, due to atmospheric pressure disturbances.

TINTORE et al. (1988) reported large sea level oscillations (up to 1 m amplitude and about 10 min period) in various bays and harbors of the western part of the Mediterranean Sea. They showed that these oscillations arise due to a three way resonant coupling among atmospheric gravity waves, coastally trapped edge waves and the normal modes of a harbor. The energy sources are atmospheric pressure fluctuations with a period of about 10-min and amplitude of about 1.5 h pa.

Every year during June to September, these oscillations are observed on the northeast coast of Spain and in the Balearic Islands (RAMIS and JANSÁ, 1983). The largest amplitudes usually occur in Ciutadella (JANSÁ, 1986) which is elongated harbor 1000 m long and 90 m wide, situated on the west coast of Minorca one of the largest oscillations observed was about 2 m on June 21st 1984.

4.6.1 Theoretical Explanation

For the theoretical development, we follow TINTORE et al. (1988) closely. The linearised shallow-water equations for a nonrotating inviscid fluid with variable depth h are

$$\partial u / \partial t + g \partial \eta / \partial x = 0 \quad (4.33)$$

$$\partial v / \partial t + g \partial \eta / \partial y = 0 \quad (4.34)$$

and the continuity equation is

$$\partial \eta / \partial t + \partial(hu) / \partial x + \partial(hv) / \partial y = 0 \quad (4.35)$$

where, u , v are the x , y velocities, η is the surface elevation and g is the gravitational acceleration. Eliminating u and v from (4.33)–(4.35), we obtain the wave equation

$$\partial^2 \eta / \partial t^2 - gh(\partial^2 \eta / \partial x^2 + \partial^2 \eta / \partial y^2) - g \partial h / \partial x \partial \eta / \partial x = 0 \quad (4.36)$$

which can be solved separately for the continental shelf and the harbor.

The model has a shelf of width $l = 15$ km, uniform depth of $h_1 = 100$ m bordered by an ocean of uniform depth $h_2 = 1600$ m. Equation (4.36) is solved for the continental shelf ($h = h_1$) and for the deep ocean ($h = h_2$), and a continuity constraint is imposed at the shelf edge. Since the depth is constant, the third term in (4.36) vanishes. Following MILES (1971), the y -axis is along the coast and the x -axis is across the shore (the mouth of the harbor is at $x = 0$, and the open sea is at $-\infty$). We search for solutions of the form (SNODGRASS et al., 1962)

$$\eta_{\text{out}}(x, y, t) = F(x) \exp[i(my + wt)] \quad (4.37)$$

which represents waves travelling in the y direction with ridges and troughs normal to the shore. Since we are only interested in the surface elevation at the mouth $\eta_{\text{out}}(x = 0)$, we can replace $F(x = 0)$ by A_{out} .

Edge waves are trapped if the phase velocity c is in the range (BUCHWALD and DE SZOEKE, 1973).

$$(gh_1)^{1/2} \leq c \leq (gh_2)^{1/2} \quad (4.38)$$

For the edge waves trapped in the Balearic Shelf the phase speed must be between 30 ms^{-1} and 125 ms^{-1} . Substitution of (4.37) into (4.36) gives the dispersion relation for trapped edge waves

$$(h_1/h_2) \tan \left[(w^2/gh_1 - m^2)^{1/2} l \right] = \left[\frac{(m^2 - w^2/gh_2)}{(w^2/gh_1 - m^2)} \right]^{1/2} \quad (4.39)$$

Equation (4.39) is solved numerically to obtain the wave number m in terms of the frequency w .

Next we consider the normal modes of the harbor. We solve (4.36) analytically for a rectangular harbor with a constant cross-channel depth and an exponential along-channel sloping bottom of the form

$$h(x) = h_0 \{1 - \exp[\alpha(x - L)]\} \quad (4.40)$$

The x coordinate is taken along the channel (the mouth being at $x = 0$, and the head at $x=L$) and the y coordinate is across the channel (harbor sides at $y = \pm d$). Values for the harbor of Ciutadella are:

Length = $L = 1000 \text{ m}$.

Width = $2d = 90 \text{ m}$.

$\alpha = 4.549 \times 10^{-3} \text{ m}^{-1}$

$h_0 = 5.75 \text{ m}$.

The following boundary conditions are used: no flow at the side walls, $v = 0$

At $y = \pm d$, and finite values for the surface elevation and the along-channel velocity at the closed end, η ($x = L$) and u ($x = L$). At the mouth, η ($x = 0$) and u ($x = 0$) remain undetermined since they must match with the outside solution. We look for solutions of the form (MILES, 1971) and the substitution into (4.36) yields a differential equation for each variable.

$$\eta_{in}(x, y, t) = X(x)Y(y)\exp(i\omega t) \quad (4.41)$$

The equation for Y (y) is easily solved; applying boundary conditions we obtain

$$Y(y) = C_n \cos[n\pi(y-d)/2d], \quad n = 0, \pm 1, \pm 2, \dots \quad (4.42)$$

The equation for X (x) is more complicated; after some algebra, it reduces to a special form of Gauss' hypergeometric equation (ABRAMOVITZ and STEGUN, 1965) with two linearly independent solutions expanded about the regular singular point at $x = L$; because of the boundary conditions one of these solutions must be rejected, and we obtain (LEMON, 1975)

$$X(x) = B \exp \left[\alpha (k^2 - \sigma^2)^{1/2} (x - L) \right] {}_2F_1 \{a, b; l; 1 - \exp[\alpha(x - L)]\} \quad (4.42a)$$

where,

$${}_2F_1(a, b; l; z) = \sum_{j=0}^{\infty} \left[\frac{\Gamma(a+j)\Gamma(b+j)}{\Gamma(a)\Gamma(b)j!} \right] z^j \quad (4.42b)$$

$$a = \frac{1}{2} \left[1 + 2(k^2 - \sigma^2)^{1/2} \pm (1 + 4k^2)^{1/2} \right] \quad (4.42c)$$

$$b = \frac{1}{2} \left[1 + 2(k^2 - \sigma^2)^{1/2} \mp (1 + 4k^2)^{1/2} \right] \quad (4.42d)$$

$$k = n\pi/2d \quad \sigma^2 = w^2/gh_0\alpha^2 \quad (4.42e)$$

The full expression for the free surface elevation for the n^{th} cross-channel mode is

$$\eta_{\text{in}}(x, y, t) = \text{Re} \left\{ A \exp \left[\alpha (k^2 - \sigma^2)^{1/2} (x - L) \right] {}_2F_1[a, b; l; 1 - \exp(\alpha(x - L))] \right\} \cdot \cos[n\pi(y - d)/2d] \exp(i\omega t) \quad (4.43)$$

Note that for a given frequency, both surface elevation and velocity obtained from (4.43) using (4.33) at any position in the harbor are completely determined for each mode except for a constant A_n .

To determine the constant A_n in (4.43), the interior solution has to match the outside co-astally trapped wave at the mouth of the harbor. The boundary conditions are continuity of pressure and of mass flux across the mouth.

For a correct matching, the outside edge wave must be expressed in terms of the interior cross-channel modes given by (4.43) (to achieve the matching for the whole hierarchy of modes). However, since the wavelengths of the outside edge waves are much longer than the width of the mouth, we may neglect the excitation of higher cross-channel modes, leaving only the fundamental mode ($n=0$); the surface elevation will not depend on y . On the other hand, an oscillating free surface in an open basin will radiate energy out into the open ocean. Therefore a complete solution outside the harbor must include the radiated long waves as well as the co-astally trapped waves. The matching conditions are

$$\eta_{\text{in}}(0) = \eta_{\text{out}}(0) + \eta_s(0) \quad (4.44a)$$

$$u_{\text{in}}(0) = u_{\text{out}}(0) + u_s(0) \quad (4.44b)$$

where, η_s and u_s are the free surface elevation and the offshore velocity for scattered waves.

To account for scattered waves, we followed the equivalent circuit analysis originated by MILES (1971) and modified by GARRETT (1975). In that scheme the sea level elevations at the mouth (m) are taken as voltages inducing a current between the harbor and the open sea. Equation (4.44a) becomes

$$\int_m K_m(y, y') F(y') dy' = \eta_{out}(y) - \int_m K_s(y, y') F(y') dy' \quad (4.45)$$

where, $K_{in}(y, y')$ and $K_s(y, y')$ are respectively the responses of the harbor and the open sea, produces by a point source of transport $\delta(y-y') = hu.n$ at the mouth. Equation (4.45) becomes an integral equation for the velocity distribution across the mouth. However, the exact solution is difficult to obtain. We use a normalized trail function

$$F(y) = I f(y) \quad \int_m f(y) dy = 1 \quad (4.46)$$

Where I is the mass flux at the mouth.

Defining the voltages V as the mean surface elevation across the mouth weighted by the velocity distribution $f(y)$, (4.45) becomes

$$Z_{in} I = V_{out} - Z_s I \quad (4.47)$$

where,

$$V_{out} = \int_m \eta_{out} f(y) dy \quad (4.48)$$

$$Z_{in} = \int_m K_{in}(y, y') f(y) f(y') dy dy' \quad (4.49)$$

$$Z_s = \int_m K_s(y, y') f(y) f(y') dy dy' \quad (4.50)$$

(Z_{in} and Z_s are the impedances of the equivalent circuit). Resonance occurs for maximum fluxes across the mouth. These fluxes can be directly obtained from (4.47).

$$I = V_{out} / (Z_{in} + Z_s) \quad (4.51)$$

Therefore we need to know the voltage V_{out} and the impedances Z_{in} and Z_s .

1. V_{out} is obtained just introducing (4.37) into (4.48). Using the velocity distribution estimated by RAYLEIGH (1945), $f(y) = 1/2d$.

$$V_{out} = A_{out} \sin(md) / m \quad (4.52)$$

where, m (which is a function of frequency) has to be substituted by its value obtained from eq.(4.39).

2. Since the inside solution is known and does not depend on y, (4.49) reduces to

$$Z_{in} = V_{in} / I = \eta_{in}(0) / \{2dh_m u_{in}(0)\} \quad (4.53)$$

where, h_m is the water depth at the mouth.

We use (4.33) to obtain $u_{in}(L)$ from (4.43). There is always a phase difference of $\pi/2$ between surface elevation and velocity and therefore (4.53) becomes a pure imaginary number of the form $g(w) \exp(-i\pi/2)$ (the sign of $g(w)$ can be positive or negative).

$$Z_{in} = -iw \operatorname{Re}[X(0)] \left\{ 2gdh_0 (1 - \exp[\alpha(x-L)]) \cdot \operatorname{Re}[X'(0)] \right\} \quad (4.54)$$

On a first approximation (without taking Z_s into account), resonance occurs for $Z_{in} = 0$ ($\eta_{in}(0) = 0$). Physically, Z_{in} accounts for the free surface oscillations of a harbor open to an ocean of infinite depth.

3. The problem of scattered waves is solved for an ocean of constant depth h_{out} . The solution is obtained by using Hankel functions as Green's function (MILES, 1971; BUCHWALD, 1971). Using velocity distribution the following expression for Z_s is obtained

$$Z_s = (w / 2gh_{out}) \left\{ 1 + (2i/\pi) \left[3/2 - \Gamma - \ln(wd/(gh_{out})^{1/2}) \right] \right\} \quad (4.55)$$

where, $\Gamma = 0.5772\dots$ is the Euler's constant, and $h_{out} = 100$ m is the depth of the open shelf.

In an equivalent circuit, the real part of Z_s , would be the resistance linearly depending on w . Physically the main effect of Z_s , is to prevent the flux from becoming infinite (Z_s accounts for the energy radiated from the harbor out into the open sea).

However, Z_s , also produces a shift of the resonant frequencies from the frequencies of the harbor free oscillations.

A physical interpretation of (4.51) may be deduced from the above observation on impedances, taking into account that (4.51) is also a time dependent relationship. When $Z_{in} = -\operatorname{Im}(Z_s)$, V_{out} and I have the same time dependency; therefore there is phase difference of $\pi/2$ between η_{in} and η_{out} . On the other hand, when $|Z_{in}| \gg |Z_s|$, V_{out} and I have a phase difference of $\pi/2$; therefore η_{in} at the head and η_{out} are in phase if $g(w) > 0$ and are out of phase if $g(w) < 0$.

Since we are interested in oscillations with periods of about 10 min, we computed the mass flux through the mouth of the harbor for frequencies lower than $4 \times 10^{-2} \text{ rad s}^{-1}$ ($T = 2.6$ min). Due to the narrowness of the mouth, $\sin(md)/md \approx 1$, evaluation of Z_{in} and Z_s shows that Z_{in} has much higher amplitude than Z_s for most frequencies and it also varies much faster. Consequently,

1. Resonance occurs when $Z_{in} = -\operatorname{Im}(Z_s)$. The location of the resonant peaks depends mainly on the geometry of the harbor and is almost independent of the shelf geometry.
2. The height of the peaks I_{max} depends only on the real part of Z_s , and since this is proportional to w , then $I_{max} \propto w^{-1}$. Resonant peaks appear at $w = 1.123 \times 10^{-2} \text{ rad s}^{-1}$ ($T = 9.33$ min) and at $w = 3.060 \times 10^{-2} \text{ rad s}^{-1}$ ($T = 3.43$ min). Coastally trapped waves with these frequencies have wavelengths of 18 km and 5 km, respectively. Their corresponding phase velocities are 33 ms^{-1} and 31 ms^{-1} .

Given the flux at the mouth (I), and dividing it by the cross sectional area, $u_{in}(L)$ can also be obtained from (4.33) and (4.43). Therefore the constant A_0 in (4.43) is determined. For the first frequency peak $A_0 = 300A_{out}$ the surface elevation at the head is 300 times the amplitude of the edge wave. At the mouth of the surface elevation is 3 times the amplitude of the edge wave (the two are not equal at the mouth because of the presence of scattered waves). For example, with an outside wave of amplitude 1cm, we obtain surface elevations of 3 m at the head and a current of about 3 ms^{-1} at the mouth. It is also interesting to note that because of the

phase difference of $\pi/2$, the maximum surface elevation inside the harbor occurs at the zero elevation of the edge wave.

4.6.2 The Work of Monserrat and Colleagues

MONSERRAT and THORPE (1992) summarized the vertical structure of the atmosphere and the synoptic situation during the Rissaga phenomena as follows:

- i) Two distinct air masses in the mid and lower troposphere, one cold and humid below and the other warm and dry above, separated by a shallow and usually strong temperature inversion near the surface.
- ii) Very weak winds normally from the east or southeast below the inversion veering toward southwest above it.
- iii) Strong wind shear at middle levels with a layer of small Richardson number near 500 Mb.

They point out that above meteorological factors while providing a general synoptic situation, cannot fully describe the necessary conditions for gravity wave generation, since the above are not the most dynamically significant factors.

These authors examined the vertical structure of the atmosphere to determine the potential for wave generation by shearing instability and see whether it fulfills the requirements postulated by LINDZEN and TUNG (1976) for the existence of a wave duct to account for maintaining wave coherence.

MONSERRAT and THORPE (1992) considered various source mechanisms and concluded that the vertical profiles of wind and temperature suggest that wind shear is the most likely mechanism. They go onto say that these gravity waves could be trapped modes in a duct and this could be the reason why in certain cases, the waves maintain their coherence for long distances involving at least one full wave-length. RABINOVICH and MONSERRAT (1996, 1998) expanded this study further and included the Kuril Islands also. Fig. 4.41 shows some typical Rissaga type water level oscillations in Japan and China. Figs. 4.42 and 4.43 respectively show the locations of the instruments used in this study for Balearic and Kuril Islands. Fig. 4.44 shows types A, B, C oscillations.

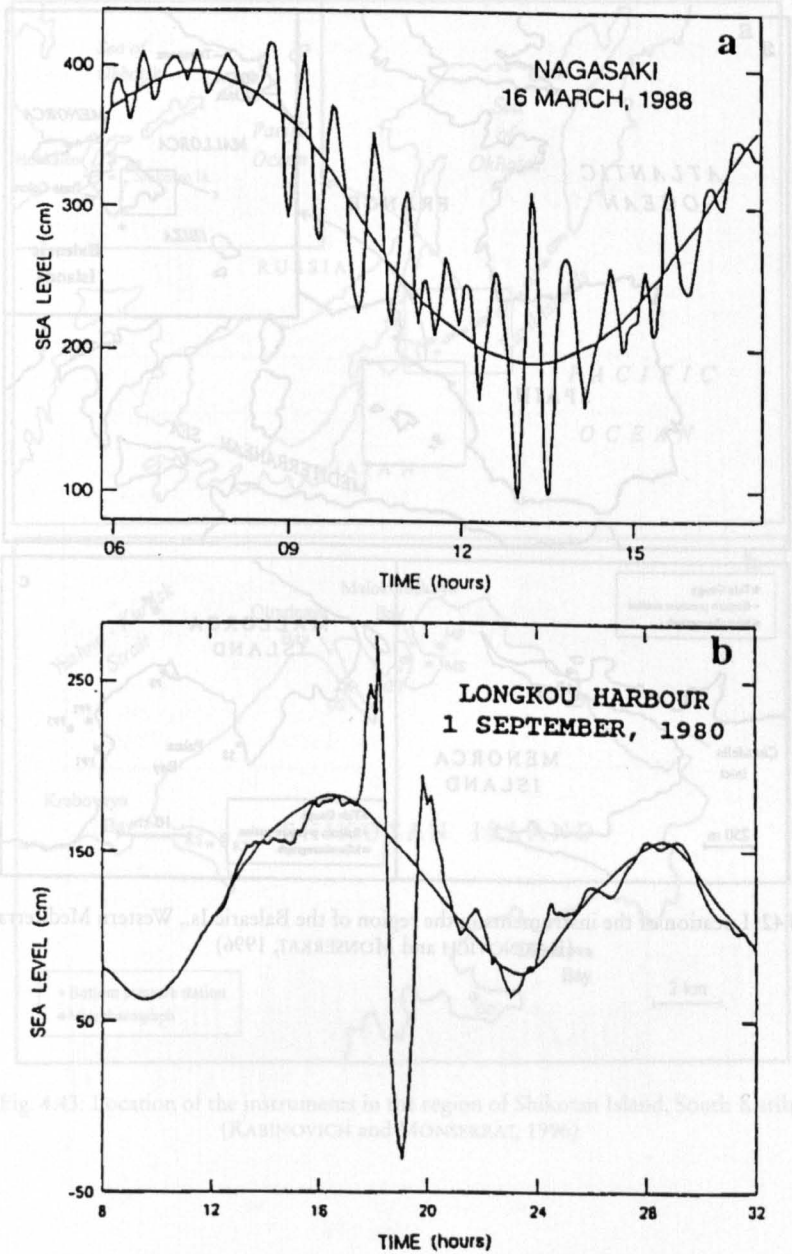


Fig. 4.41: Strong seiche oscillations recorded in Nagasaki Bay, Japan (courtesy of Japan Meteorological Agency) (a) and in Longkou Harbour, China. (WANG et al., 1987) (b)

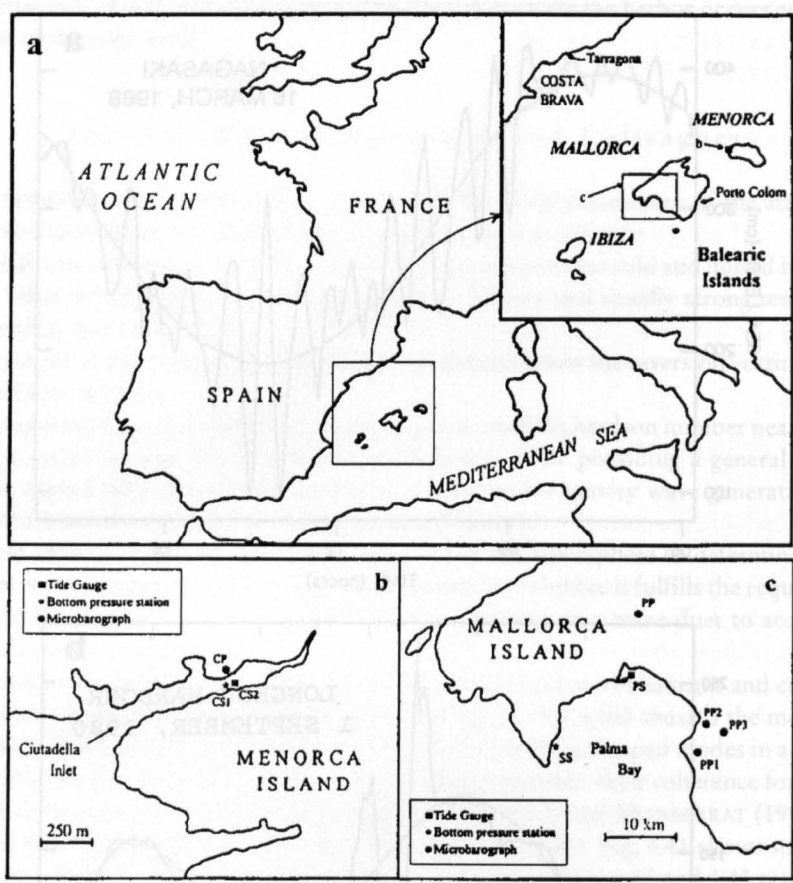


Fig. 4.42: Location of the instruments in the region of the Balearic Is., Western Mediterranean.
(RABINOVICH and MONSERRAT, 1996)

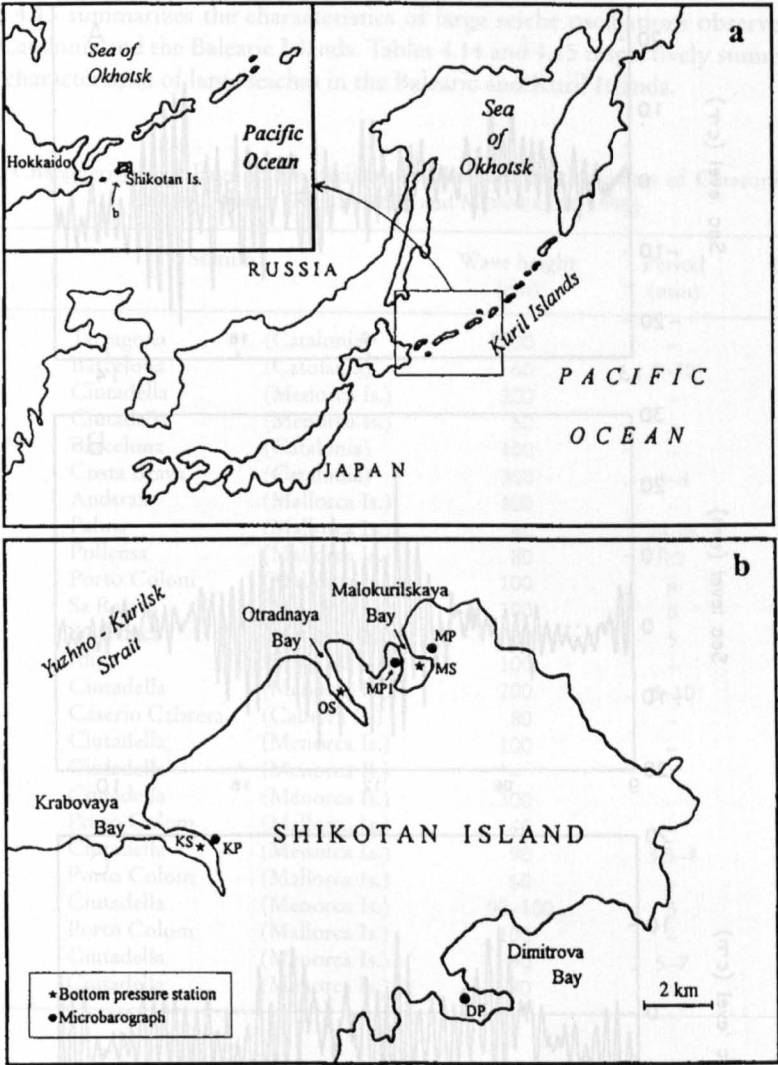


Fig. 4.43: Location of the instruments in the region of Shikotan Island, South Kurils. (RABINOVICH and MONSERRAT, 1996)

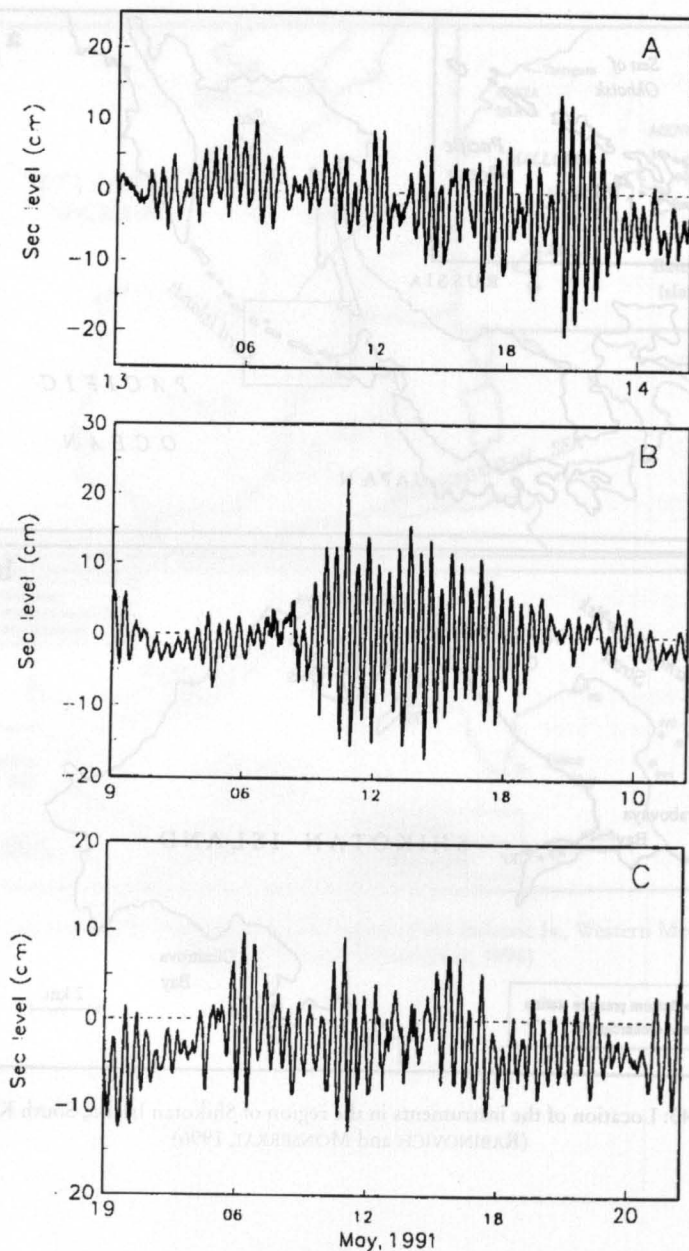


Fig. 4.44: Three recording sections of significant seiches observed in Krabovaya Bay (KS) in May 1991 which may be considered as examples of different types (A, B, and C) of 'seiche events'. (RABINOVICH and MONSERRAT, 1996)

Table 4.13 summarizes the characteristics of large seiche oscillations observed on the coasts of Catalonia and the Balearic Islands. Tables 4.14 and 4.15 respectively summarize the statistical characteristics of large seiches in the Balearic and Kuril Islands.

Table 4.13: Characteristics of large seiche oscillations observed on the coasts of Catalonia and the Balearic Islands (RABINOVICH and MONSERRAT, 1996)

Date	Station		Wave height (cm)	Period (min)	Duration (hours)
11-Jul-72	Tarragona	(Catalonia)	300	—	—
16-Sep-75	Barcelona	(Catalonia)	60	8–10	12
16-Sep-75	Ciudadella	(Menorca Is.)	200	—	48
14-Jul-77	Ciudadella	(Menorca Is.)	50	—	—
2-Jul-81	Barcelona	(Catalonia)	100	—	—
2-Jul-81	Costa Brava	(Catalonia)	300	3–4	—
2-Jul-81	Andrax	(Mallorca Is.)	100	—	—
2-Jul-81	Palma	(Mallorca Is.)	40	14,28	—
2-Jul-81	Pollensa	(Mallorca Is.)	80	10	—
2-Jul-81	Porto Colom	(Mallorca Is.)	100	6	—
2-Jul-81	Sa Rapita	(Mallorca Is.)	100	5	—
2-Jul-81	Sta Ponca	(Mallorca Is.)	200	5	—
2-Jul-81	Ibiza	(Ibiza Is.)	100	—	—
2-Jul-81	Ciudadella	(Menorca Is.)	200	8–10	15
2-Jul-81	Caserio Cabrera	(Cabrera Is.)	80	—	—
18-Jul-81	Ciudadella	(Menorca Is.)	100	—	—
29-Jul-82	Ciudadella	(Menorca Is.)	—	—	48
21-Jun-84	Ciudadella	(Menorca Is.)	300	—	—
14-Jun-85	Porto Colom	(Mallorca Is.)	40	—	—
14-Jun-85	Ciudadella	(Menorca Is.)	90	3.5–4	7
19-Jun-85	Porto Colom	(Mallorca Is.)	60	—	—
19-Jun-85	Ciudadella	(Menorca Is.)	90–100	5	10
3-Jul-85	Porto Colom	(Mallorca Is.)	100	—	2
3-Jul-85	Ciudadella	(Menorca Is.)	90	5–7	8
31-Jul-85	Ciudadella	(Menorca Is.)	80	—	4

Table 4.14: Statistical characteristics of large seiche oscillations recorded in the Balearic Islands in 1989–90 (RABINOVICH and MONSERRAT, 1996)

		Stations												
Event		Ciutadella					Palma					Sol de Mallorca		
No.	Beginning Time	Duration (hours)	Type	Max height (cm)	Mean height (cm)	Mean Period (min)	Max height (cm)	Mean height (cm)	Mean Period (min)	Max height (cm)	Mean height (cm)	Mean Period (min)		
1989														
1	04/07	21:20	63.4	C/A	196.7	39.1	10.7	32.3	14.3	27.5	—	—		
2	05/08	3:35	19.2	B	126.8	34.2	10.5	23.9	9.3	25.8	10.3	10.9		
3	10/08	20:38	10.2	A	103.8	44.4	11.7	23.5	10.8	25.9	15.1	15.7		
4	31/08	10:58	0.9	C	44.3	38.5	10.8	—	—	—	—	—		
5	04/09	18:09	4.6	C	64.4	26.2	11.1	—	—	—	—	—		
6	05/09	5:27	30.0	C	72.8	23.7	10.8	—	—	—	—	—		
7	07/09	16:40	21.5	C	51.5	18.6	10.3	—	—	—	—	—		
8	10/09	10:42	7.7	B	95.8	42.4	11.5	—	—	—	—	—		
1990														
1	24/09	12:31	4.8	B	66.4	28.5	9.6	—	—	—	—	—		
2	25/09	12:45	11.5	C	92.8	36.6	10.9	—	—	—	—	—		

Table 4.15: Statistical characteristics of large seiche oscillations recorded in the region of Shikotan Island in May 1991 (RABINOVICH and MONSERRAT, 1996)

Event		Stations											
		Krabovaya					Otradnaya					Malokurilskaya	
No.	Beginning Time	Duration (hours)	Type	Max height (cm)	Mean height (cm)	Mean Period (min)	Max height (cm)	Mean height (cm)	Mean Period (min)	Max height (cm)	Mean height (cm)	Mean Period (min)	
1	09/05	7:14	9.6	B	37.4	21.8	28.6	15.2	5.9	15.4	23.8	9.3	18.3
2	13/05	12:00	12.0	A	34.0	13.8	26.7	15.3	5.7	15.8	21.7	10.8	18.1
3	19/05	6:00	>24.0	C	21.9	8.5	26.1	12.9	3.8	15.1	—	—	—

A key question related to the problem of generation of the *rissaga* phenomenon is the following:

– Why are such strong sea-level oscillations generated in just some specific places?

The stable recurrence of such disastrous events in the same places proves that they are certainly strongly related to the topography and geometry of the correspondingly bays, inlets, or harbors. Ciutadella inlet, Menorca Island (as well as Nagasaki Bay, Japan and some other basins) is just one of such remarkable places. Simultaneous sea-level measurements in Ciutadella inlet and Palma Bay, presented above, demonstrated that during the same events, seiches in Ciutadella are about 6 times larger. What is the reason?

MILES and MUNK (1961) demonstrated that the relative intensity of seiche oscillations in harbours and bays is determined first of all by the Q-factor of the corresponding basin. Reducing the harbour entrance by wave-protection constructions increases the Q-factor and therefore the harbour oscillations. From this point of view it is quite understandable why the narrow inlet of Ciutadella has much stronger seiches than the open-mouthed inlets and harbours in the Balearic Islands with seiches much weaker than in Ciutadella.

GOMIS et al. (1993) tried to explain this fact by the influence of the inlet geometry. They estimated the amplification factor (1) for three inlets in this region (Ciutadella, Mahon and Porto Colom) and showed that in Ciutadella it is much larger than in the other two inlets. But in the region of the Japanese Islands there are several other bays and inlets with this factor no lesser (or even greater) than in Nagasaki Bay although abnormal seiches are known only in the latter basin.

RABINOVICH (1993) proposed that the extreme seiche oscillations observed in some places are forced by some kind of double resonance effect, e.g., by the coincidence of resonant frequencies of the shelf and inner basin, or eigenfrequencies of the harbour and outer bay. The relatively small probability of such coincidences is the main reason of the rareness of basins where large-amplitude seiches are reported.

5. Meteorological Aspects

Storm surges occur because of meteorological problems associated with extratropical and tropical cyclones. This chapter will discuss the dynamics of extratropical cyclones and tropical cyclones and the meteorological problems associated with these cyclones in the Pacific, Atlantic, and Indian oceans, as well as in other smaller water bodies. The problems associated with obtaining wind stress data for synoptic scale and mesoscale weather systems will be examined in detail.

5.1 Extratropical Cyclones

5.1.1 Development Theory

The treatment in this section follows closely PETERSSSEN (1956) and WARNECKE (1997). FITZ-ROY (1863) appears to be among the first to propose a model of an extratropical cyclone as originating on the boundary between two different air masses (e.g. a warm and moist air mass originating in subtropical latitudes and a colder and drier air mass originating in the polar regions). Some later authors who recognized that discontinuities in temperature, moisture content, and speed of motion were essential for cyclone development were BLASIUS (1875), HELMHOLTZ (1888, 1889), MARGULES (1905) and SHAW (1921).

BJERKNES (1919) proposed the first dynamical model for cyclones and agreed with MARGULES (1905) that the kinetic energy of the cyclones comes from the potential energy due to the juxtaposition of warm and cold air masses and a decrease of the potential energy that follows the development of a cyclone. According to Bjerknnes the cold air forms a wedge under the warm air, with a slope of separation of about 1 : 100, and the cyclonic disturbances travel along the frontal surface similar to waves traveling along a discontinuity.

The life cycle of a cyclone has several stages. In the initial stage, a small amplitude wave forms on a more or less straight quasi-stationary front. The currents on either side of the front could be in the same direction or in opposite directions. In the second stage, the warm air rises to higher levels over the warm front and the cold front wedges in under the warm air. In the third stage, the warm air sectors become progressively narrower and the cold front tends to overtake the warm front. At this stage the cyclone has reached the occlusion stage (Fig. 5.1).

It is customary to refer to cyclone families (Fig. 5.2), rather than individual cyclones (FITZ-ROY, 1863). Usually there would be two to four or five cyclones in a series, one following the other and all moving in a general southwest to northeast direction. BJERKNES and SOLBERG (1921, 1922) accounted for cyclone families as wave disturbances on the polar front. In a family of four cyclones, typically the first one would be old and occluded, the second would be somewhat younger, the third would be a young wave cyclone, and the fourth would be a nascent cyclone wave. On the average, a cyclone family takes 5–6 d to pass a given location. The occurrence of cyclone families is a regular phenomenon over the North Atlantic and Western Europe (because of regular major polar outbreaks from the Greenland-Labrador area) and not as regular over North America and Central Eurasia.

Usually, cyclone formation begins near sea level and develops to higher levels in the atmosphere as the occlusion develops. Once a complete occlusion occurs, generally a closed cyclonic circulation can be found in the middle and upper troposphere (located over the cold rear of the occluded sea level cyclone). Sometimes, the depression in the pressure field aloft

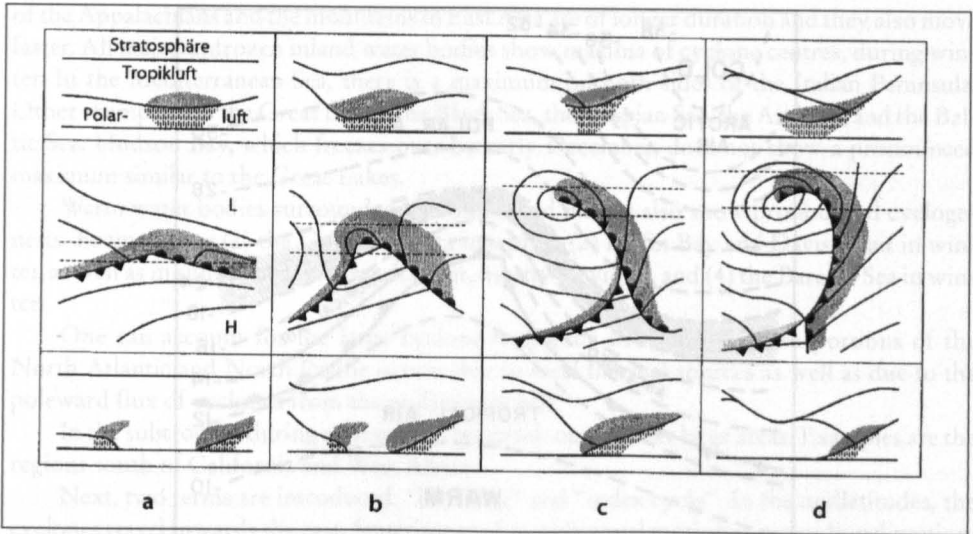


Fig. 5.1: Stages of cyclogenesis (WARNECKE, 1997)

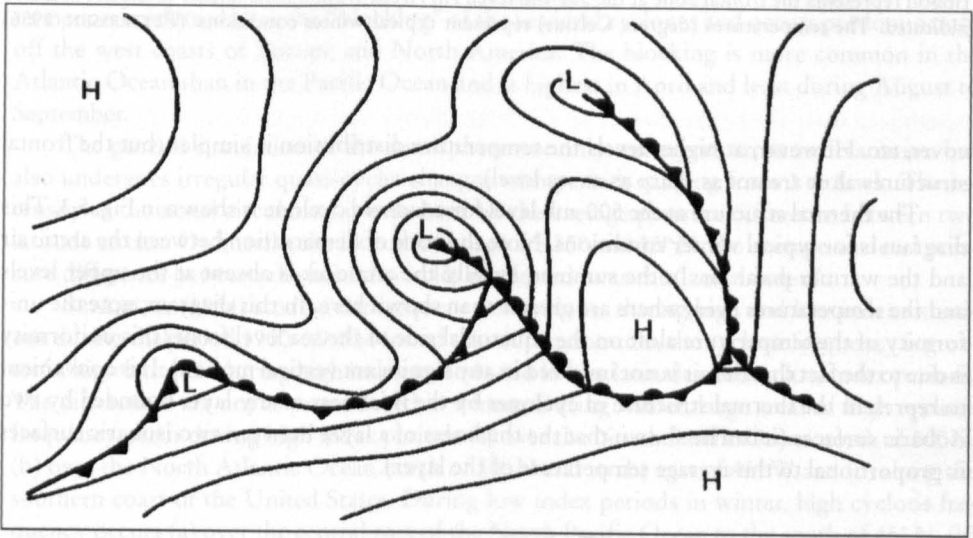


Fig. 5.2: Cyclone families (WARNECKE, 1997)

may merge with the semipermanent low over the polar region. When this happens, a high-level trough can be noticed in the rear of the occluded sea level cyclone. Thus, these upper level troughs represent the vertical extension of the cyclones. However, sometimes (particularly during winter), cyclone development may begin at the higher levels and at other times simultaneously with the lower level development. One refers to these more or less independent developments aloft (middle and upper troposphere) as “cutoff” cyclones.

Next, the thermal structure of cyclones will be briefly examined. At sea level there is no definite thermal pattern and irregularities occur because of the diurnal variations, cloud

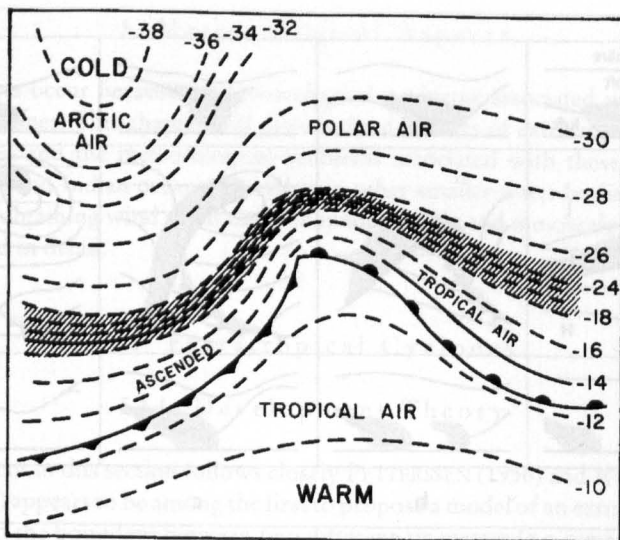


Fig. 5.3: Schematic representation of the isotherms at the 500-mb level associated with a wave cyclone. The front at sea level is represented by conventional symbols (● warm front; ● cold front) and a hatched ribbon represents the frontal zone at the 500-mb level. An Arctic frontal zone farther to the north is also indicated. The temperatures (degrees Celsius) represent typical winter conditions. (PETTERSEN, 1956)

cover, etc. However, at higher levels the temperature distribution is simpler (but the frontal structures aloft are not as sharp as at sea level).

The thermal structure at the 500-mb level for a 1-d-old cyclone is shown in Fig. 5.3. This diagram is for typical winter conditions. Note the zone of demarcation between the arctic air and the warmer polar air. In the summer, usually the arctic air is absent at the upper levels and the temperatures everywhere are greater than shown here. In this diagram, note the uniformity of the temperature aloft on the equatorial side of the sea level front (this uniformity is due to the fact that the air is not involved in any significant vertical motion). It is convenient to represent the thermal structure of cyclones by the thickness of any layer bounded by two isobaric surfaces (it can be shown that the thickness of a layer between two isobaric surfaces is proportional to the average temperature of the layer).

Cyclone Patterns

The patterns of cyclogenesis during winter will be examined first. In the North Pacific Ocean a zonal pattern exists around 30–35°N. Also, over the continents, large maxima of cyclogenesis occur in the lee of great mountain chains. These patterns are not sensitive to seasonal variations. Three pronounced maxima are associated with the Rockies: Sierra Nevada, Colorado, and Alberta regions. Similar maxima can be located to the east of the Appalachian mountains, the Scandinavian mountains, and also in East Asia.

If the frequency of cyclone centres is examined, the influence of mountain ranges can be seen even more. Examples are the leeward side of the Colorado and Alberta ranges. The cyclones that develop here are mostly of short duration, whereas those that develop in the lee

of the Appalachians and the mountains in East Asia are of longer duration and they also move faster. All major unfrozen inland water bodies show maxima of cyclone centres, during winter. In the Mediterranean Sea, there is a maximum on both sides of the Italian Peninsula. Other examples are the Great Lakes, the Black Sea, the Caspian Sea, the Aral Sea, and the Baltic Sea. Hudson Bay, which freezes over by early December, does not show a pronounced maximum similar to the Great Lakes.

Warm water bodies surrounded by colder land masses also show pronounced cyclogenesis. Examples are (1) the Gulf of Alaska in winter, (2) Baffin Bay and Davis Strait in winter, as well as in summer, (3) Denmark Strait, mostly in winter, and (4) the Barents Sea in winter.

One can account for the large cyclone frequency over the northern portions of the North Atlantic and North Pacific oceans due to local thermal sources as well as due to the poleward flux of cyclones from the midlatitude belt.

In the subtropics, during summer, cyclogenesis occurs over large areas. Examples are the regions south of California and West Africa.

Next, two terms are introduced: "blocking" and "index cycle". In the midlatitudes, the cyclones travel towards the east. Superimposed on this zonal motion is a meridional motion. The thermal wind in the middle troposphere to some extent guides the movement of the cyclones. Sometimes, when a warm cutoff high forms in the middle and upper troposphere, cyclones at sea level are steered either to the south or to the north of these highs. This phenomenon is referred to as the "blocking" of the sea level cyclones and occurs predominantly off the west coasts of Europe and North America. The blocking is more common in the Atlantic Ocean than in the Pacific Ocean and is highest in April and least during August to September.

The general circulation of the atmosphere not only undergoes an annual variation but also undergoes irregular quasi-cyclic changes with periods ranging from 3 to 8 wk. The intensity of the zonal circulation is expressed by the average pressure difference between two latitude circles. Ordinarily, the latitudes chosen are 35° and 55° N, the average sea level pressure difference between the latitude circles is referred to as the "zonal index".

BRADBURY (1954) studied the frequency of cyclones during high and low index situations during the period 1900–39. She found that during summer, the cyclone frequency is greater in high latitudes during high index periods and in low latitudes during low index periods. The differences are not as pronounced in winter. During winter, large areas of high cyclone frequency occur during high index periods (a) over the North Pacific Ocean north of 50° N, (b) over the North Atlantic Ocean north of 50° N and to the east of 45° W and (c) along the southern coast of the United States. During low index periods in winter, high cyclone frequency occurs (a) over the central part of the North Pacific Ocean to the south of 45° N, (b) over the western part of the North Atlantic Ocean and (c) over the Mediterranean Sea.

Instability Theories

MARGULES (1905) speculated that the potential energy associated with horizontal temperature gradients provides the kinetic energy of cyclones. SOLBERG (1936) showed that frontal cyclones would grow as a result of the inherent instability of the polar front (similar to the growth of a wave at a discontinuity). CHARNEY (1947), EADY (1949), BERSON (1949), and FJORTOFT (1950) have shown that the baroclinicity of the zonal current may lead to instability in which the kinetic energy of the growing perturbations is derived from the potential

and internal energies due to horizontal thermal gradients. KUO (1949) and FJORTOFT (1950) showed that certain categories of horizontal velocity patterns across a zonal current would lead to instability.

It has generally been observed that cyclones develop within a period of 1–3 d. In this short time scale, it is customary to assume that the motion is adiabatic and frictionless. Another assumption is that even during growth, the energy of an unstable zonal current is conserved. Let K , P , and E denote the kinetic, potential, and internal energies, respectively. Hence, according to the above assumptions:

$$K + P + E = \text{constant}$$

The kinetic energy per unit mass can be expressed as

$$\frac{1}{2} V^2 = \frac{1}{2} \bar{V}^2 + \bar{V} \cdot V' + \frac{1}{2} V'^2 \quad (5.1)$$

where, V is the averaged velocity of the undisturbed current and V' is a deviation from this value. The kinetic energy K can be determined by integration over the total mass. During this integration, the second term on the right side of the above equation disappears. Hence

$$K = K_m + K_d \quad (5.2)$$

where, K_m and K_d are the integrated forms of the first and third terms, respectively, and these are referred to as the kinetic energy of the mean current and the kinetic energy of the perturbation. Equation (5.2) may be rewritten as

$$K_m + K_d + P + E = \text{constant} \quad (5.3)$$

Since K_d represents the average intensity of all the disturbances, for the growth of these, K_d must increase with time. This means that K_d can increase only at the expense of one of the three sources K_m , P , or E or from combinations of these.

Next, the potential energy of a column of air of unit cross-section is given by

$$P = \int_0^{\infty} g z p \, dz$$

Using the hydrostatic equation $dp = -g p \, dz$ and integrating by parts:

$$P = \int_0^{p_0} z \, dp = [z p]_{p=p_0} - [z p]_{p=0} - \int_0^{p_0} p \frac{\partial z}{\partial p} \, dp$$

where, p_0 is the pressure at the bottom of the air column. In this equation, on the right side the first term becomes zero at $z = 0$ (bottom of the air column) and the second term vanishes because $p z \rightarrow 0$ as $p \rightarrow 0$. The third term becomes, after noting $\alpha = 1/p$ where α is the specific volume.

The equation of state is

$$\alpha P = R T$$

Using this, the above equation becomes

$$P = R \int_0^{\infty} T p dz \quad (5.4)$$

The internal energy of the air column may be written as

$$E = C_v \int_0^{\infty} T p dz \quad (5.5)$$

where, C_v , is the specific heat of air at constant volume. Hence

$$\frac{P}{E} = \frac{R}{C_v} \sim 0.4 \quad (5.6)$$

Thus, it can be seen that the potential and internal energies of a column of air (from the sea level to the top of the atmosphere) will change proportionately to each other. For this reason, the potential and internal energies in eq. (5.3) should not be treated as two different energy sources; hence, only two energy sources exist for the perturbations to amplify: (1) the kinetic energy K_m of the mean motion and (2) the sum of the potential and internal energies $P + E$.

The perturbations of the basic zonal current may grow through three different types of instability. The first one is the so-called linear current instability. The energy for the perturbations is derived from the kinetic energy of the basic current. This instability mechanism is similar to the hydrodynamic instability of a linear flow of a homogeneous and incompressible fluid between two parallel walls. The second type of instability is referred to as baroclinic instability. In this case, the potential and internal energies of the basic baroclinic current supply the energy for the growth of the disturbances. The third type of instability is referred to as Solberg-Holland instability. SOLBERG (1936) considered a system that initially consists of two barotropic layers separated by a sloping frontal surface in the east-west direction. Both layers are assumed to move towards the east, with the warmer (southern) layer moving faster. He found that waves with lengths less than a few kilometres and also those with lengths between 1000 and 3000 km will amplify and waves with lengths in the remaining range will dissipate. The growth of the waves with lengths shorter than a few kilometers is similar to the classical Helmholtz instability problem, and these short waves are of no relevance to the cyclone problem. A sharp discontinuity is essential for their generation. The growth of waves with lengths of 1000–3000 km can account for the growth of cyclone disturbances.

It can be shown that each of these barotropic layers can give rise to stable wave motion. The wave motion in each layer can be tuned so that each can grow as a result of a resonance effect. In this type of instability the disturbances derive energy from the kinetic energy of the mean motion whereas the potential and internal energies are sink terms.

Some Examples of Cyclone Development

REITAN (1974) summarized the frequencies of cyclones and cyclogenesis for North America. DANARD and ELLENTON (1980) examined the physical influences on the cyclogenesis on the east coast of North America making use of an eight-level primitive equation model. This model includes sensible and latent heat from the ocean surface, parameterized convective and large-scale precipitation and release of latent heat, surface frictional drag and

orography. One of the important results of this study is that input of heat and water vapour from the ocean surface did not contribute significantly during the deepening of the low. However, these fluxes produced an initial vertical distribution of temperature and moisture that helped subsequent development.

BRAND and GUARD (1979) studied the evolution of extratropical storms from tropical cyclones. According to these authors, a tropical cyclone is identified as becoming extratropical when it loses its tropical nature (i.e. northward displacement from the tropics as well as the conversion of the cyclone's primary energy source from latent heat release to baroclinic processes). The movement of recurved tropical cyclones is difficult to predict. According to BURROUGHS and BRAND (1973), errors as high as 30 % could occur. Even when the recurved tropical cyclone becomes somewhat weaker, if it becomes an extratropical cyclone, it could

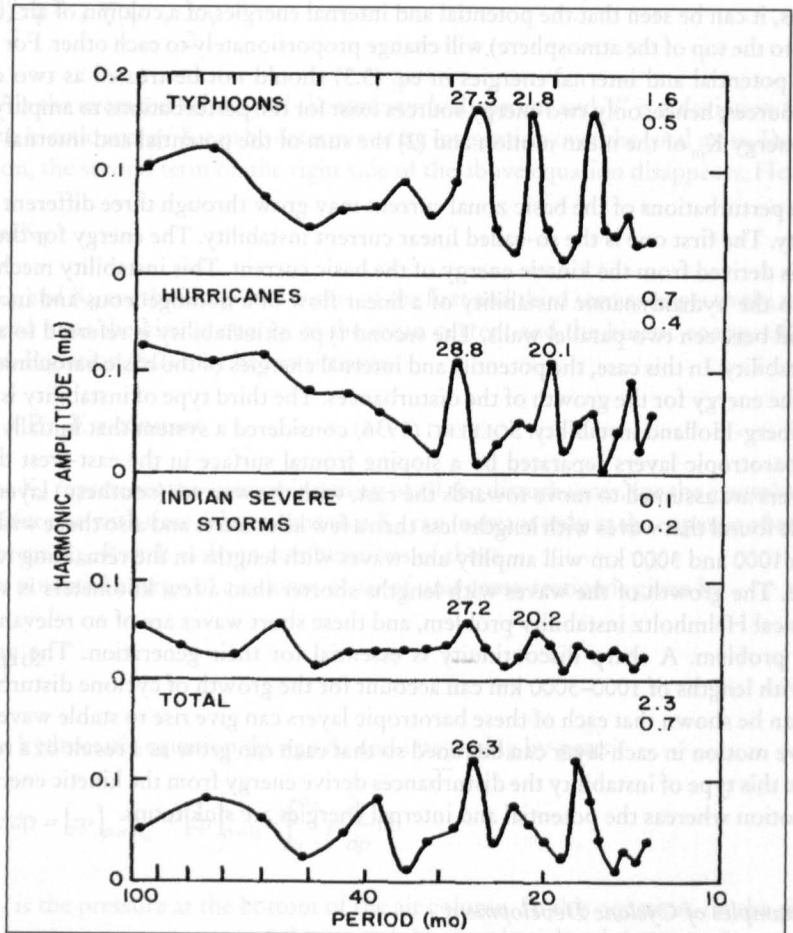


Fig. 5.4: Harmonic amplitude of the mean monthly frequency of North Pacific typhoons, North Atlantic hurricanes, severe storms (winds greater than 25 m s^{-1}) in the vicinity of India, and the total of all three. Numbers above the peaks indicate the dominant quasi-biennial periods of oscillation (months). The two numbers in the upper right-hand corner represent the harmonic amplitudes of the annual (upper number) and semiannual (lower number) oscillations in surface pressure at the station. (ANGELL et al., 1969)

still be important. For typhoons to the east of China, during the period 1971–75, the average value of the maximum wind when the cyclones extratropical at 34°N and at that time the maximum wind speed was 51 m s^{-1} .

According to SEKIOKA (1970, 1972a, 1972b) and MATANO and SEKIOKA (1971a, 1971b), this transformation of tropical cyclones to extratropical cyclones can occur at least in two ways: (1) a tropical cyclone meets an already existing front causing a new extratropical cyclone to form and grow on the front and (2) a pre-existing extratropical cyclone merges with a tropical cyclone and usurps the tropical vortex.

ANGELL et al. (1969) detected a quasi-biennial (period of about 28 mo) variation in the centres of action such as the Icelandic and Aleutian low pressure centers. They related the frequency of hurricanes and typhoons to this quasi-biennial activity. Mean monthly surface pressures at stations with long data records were subjected to harmonic analysis. The following important results emerged.

Quasi-biennial variations in the surface pressure occur near the North Atlantic and North Pacific subtropical highs and subpolar lows, with amplitudes up to 0.4 mb. The quasi-biennial variations in latitude and longitude of the subtropical highs are about 1° .

The Atlantic high moves in a northwest-southeast direction. Hurricanes in the North Atlantic, typhoons in the North Pacific, and severe storms in the vicinity of India show a quasi-biennial variation in frequency (Fig. 5.4).

It is possible that the relatively large annual oscillation may contaminate the harmonic analysis for the quasi-biennial band. For this reason ANGELL et al. (1969) also performed an alternate analysis. In the so-called even-minus-odd-year difference method, the number of hurricanes or typhoons in the odd-numbered years is subtracted, year-by-year, from the number in the even-numbered years, and these first differences are smoothed through determination of a 3-yr running average. The results agree reasonably with observations.

It will not be discussed here in detail, but it must be considered that the work on reason and results of the existence of storm tracks continues. HOSKINS and VALDES (1990) investigate the question, why concentrated regions of eddy activity exist, i.e. storm tracks in the Northern Hemisphere. They have found that “the direct thermal effect of the eddies does indeed act against the storm tracks. Their vorticity fluxes lead to some reduction of this effect. It is argued that the mean diabatic heating in the storm track region is an indirect eddy effect.” (HOSKINS and VALDES, 1990).

5.1.2 Regions of occurrence

Extratropical Storm Surges in Canada

Storm surges are generated in Canada by extratropical storms and occasionally by a hurricane that has transformed into an extratropical storm. In eastern Canada, storm surges occur in the Great Lakes, St. Lawrence Estuary, Gulf of St. Lawrence, Bay of Fundy and along the Atlantic coast. Storm surges also occur in Hudson Bay, James Bay, Lake Winnipeg, Beaufort Sea, Hecate Strait and Queen Charlotte Sound. The main storm surge season is autumn and early winter, and occasionally, storm surges could occur in summer and in late winter. Since all the surge-producing storms are extratropical in origin, the calculation of the meteorological forcing terms from the weather charts is straightforward (it does not necessarily mean the values are accurate). For convenience, Alaska will be discussed in this section along with western Canada. Similarly, the Great Lakes will be treated in this section. How-

ever, meteorological problems associated with mesoscale systems such as squall lines will be deferred to section 5.7.

Principal tracks of intense storms (based on the data for the period 1963–67) are shown in Fig. 5.5 (A) for January to March, in Fig. 5.5 (B) for July and August, and in Fig. 5.5 (C) for October to December. The tracks of storms of tropical origin are shown in Fig. 5.6, and the tracks of storms for the Hudson Bay region for different months are shown in Fig. 5.7A–5.7D. However, occasionally, rather irregular tracks can occur. In Fig. 5.8 are shown the tracks for four storms in 1969 over Hudson Bay. While the track for the November storm is not unusual, the tracks for the other three storms show forward – backward

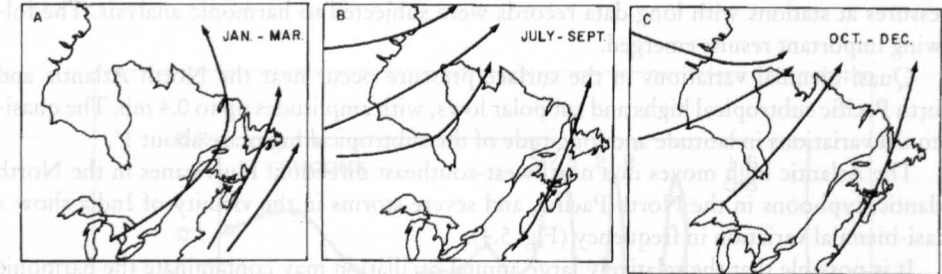


Fig. 5.5: Tracks of intense storms over eastern Canada (A) January–March, (B) July–September, and (C) October–December. (ARCHIBALD, 1945)

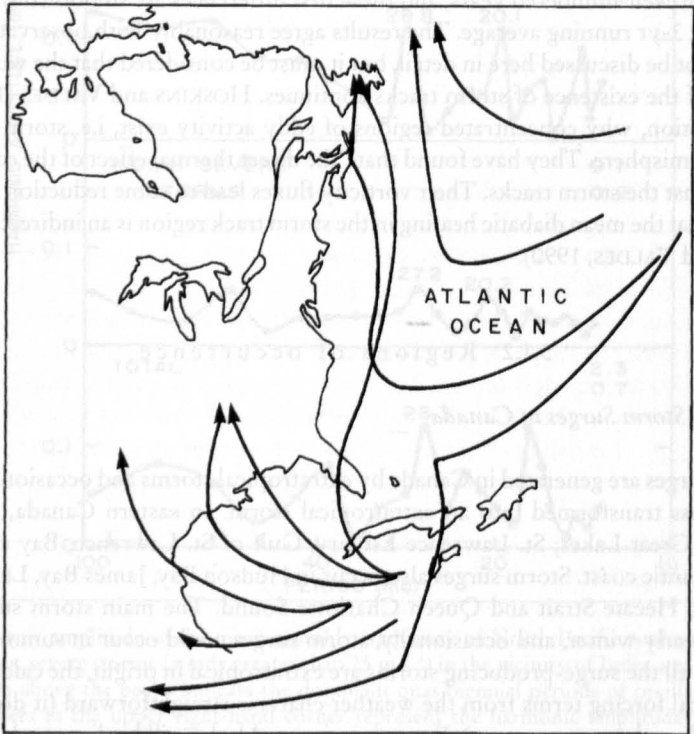


Fig. 5.6: Tracks of storms of tropical origin along the east coast of North America. (ARCHIBALD, 1945)

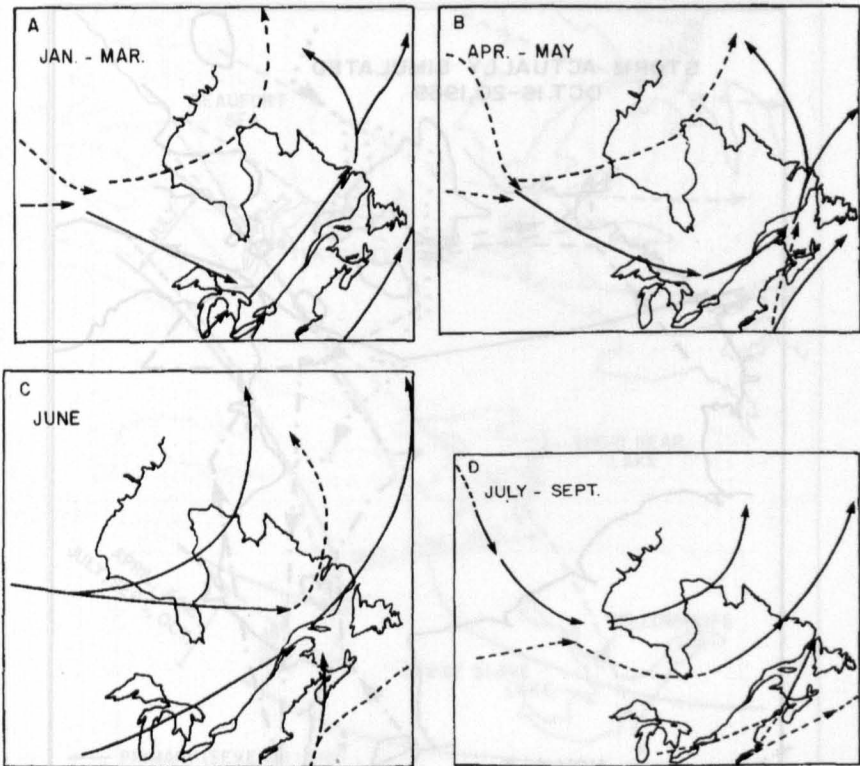


Fig. 5.7: Storm tracks over Hudson Bay and surroundings (A) January–March, (B) April and May, (C) June, and (D) July–September. (Archibald, 1945)

Fig. 5.8: Corridors of primary and secondary storm tracks over Hudson Bay and surroundings (Archibald, 1945)

movements of the storm center, which could be the result of improper observations or could be real on certain occasions.

The corridors for the tracks of intense and ordinary storms in the northwestern part of Canada are shown in Fig. 5.9. The surface weather map for the Alaska area during a storm on October 3, 1963, is given in Fig. 5.10A. The distribution of the computed wind stress field is illustrated in Fig. 5.10B and the variation of the computed wind stress with time near Barrow, Alaska, is shown in Fig. 5.10C.

Great Lakes

BARRIENTOS (1970) discussed objective methods for predicting winds over Lakes Erie and Ontario. Making use of 1000-mb geostrophic wind and sea level pressure forecasts issued routinely for eight stations surrounding these lakes, as well as marine observations from anemometer-equipped vessels, two sets of regression equations were derived for predicting wind speed.

VENKATESH and DANARD (1976) used a one-level primitive equation model for computing the mesoscale influences of orography, friction, and heating on surface winds. They included the influence of atmospheric stability and land-water temperature contrast. ESTOQUE

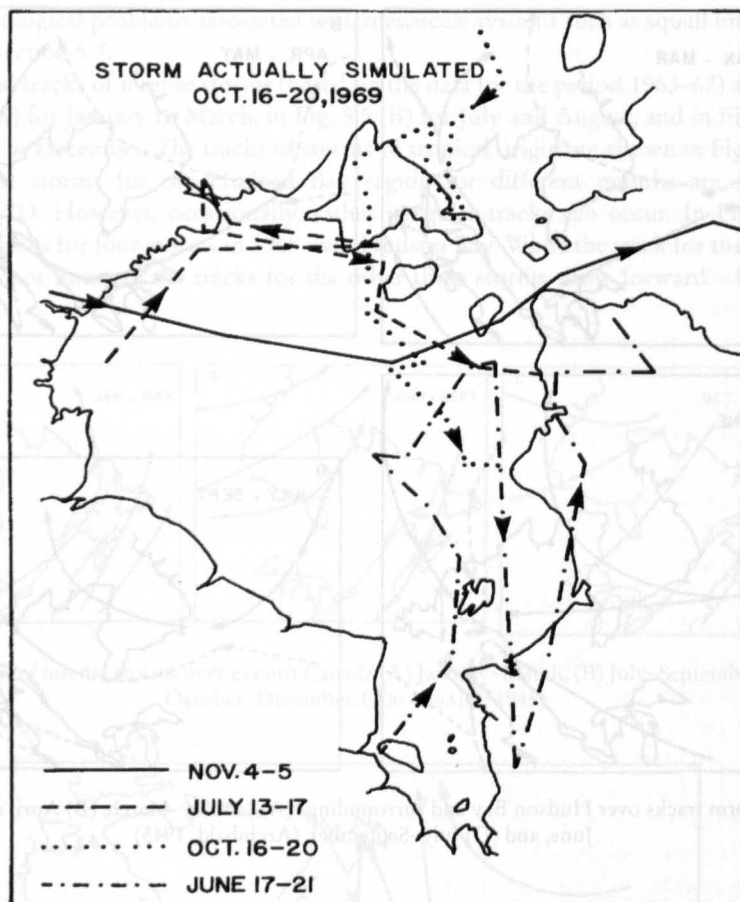


Fig. 5.8: Selected storm tracks over Hudson Bay for the year 1969

and GROSS (1979) discussed diurnal wind variations over Lake Ontario, as deduced from Rawinsonde data at six stations.

RESIO and VINCENT (1977) estimated winds over the Great Lakes knowing winds over adjacent land. FEIT and PORE (1978) discussed objective wind forecasting for all of the Great Lakes using a technique developed by FEIT and BARRIENTOS (1974). The predictors are the various forecast parameters computed by the National Meteorological Center's primitive equation (PE) model. The 12 locations at which wind forecasts are made at 6-h intervals, 36 h in advance, are shown in Fig. 5.11. Mean absolute error in wind speed is 5-8 knots ($2.6-4.1 \text{ m. S}^{-1}$) and mean absolute error in wind direction is about 20° for short-term forecasts (6-12 h) and about 70° for long-term forecasts (30-36 h).

KEULEGAN (1953) took a somewhat different approach. He derived the wind stress and the roughness parameter for Lake Erie using water level data for a 50-yr period. In other words, he used the observed storm surge data to estimate the wind stress. He defined an effective lake wind velocity as the wind velocity that would be needed to produce the observed storm surge, assuming that the wind blows with this effective velocity along the lake axis. Recently, SCHWAB (1982) used a similar but more sophisticated inverse technique.

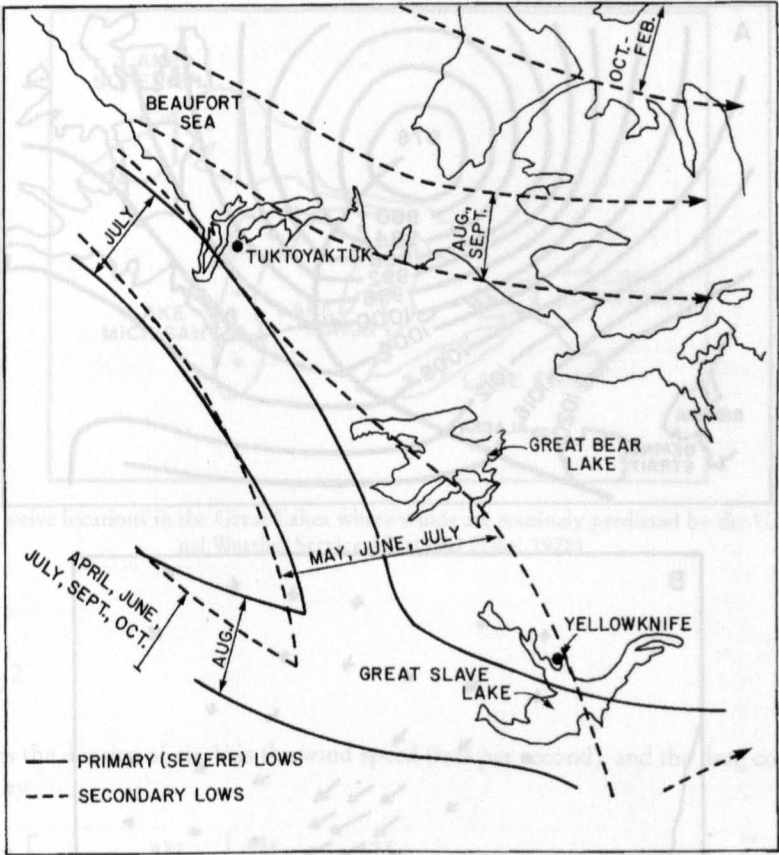


Fig. 5.9: Corridors of primary and secondary lows over the northwest part of Canada. (BURNS, 1973)

KEULEGAN (1953) used the following relationship to deduce the wind stress from the storm surge:

$$\frac{(\tau_s + \tau_0)}{\rho g H_0} \frac{L}{H_0} = 0.867 \frac{\Delta H_0}{H_0} - 0.134 \left(\frac{\Delta H_0}{H_0} \right)^2 \tag{5.7}$$

where, τ_s is the wind stress, τ_0 is the bottom stress, ρ is the density of water, g is gravity, H_0 is the average water depth, ΔH is the storm surge (feet), and L is the length of the lake (feet). The bottom stress τ_0 was related to the surface wind stress through

$$\tau_0 = n \tau_s \tag{5.8}$$

Then, eq. (5.7) becomes

$$\tau_s = \frac{1}{(1+n)} \left[0.867 \frac{\Delta H_0}{H_0} - 0.134 \left(\frac{\Delta H_0}{H_0} \right)^2 \right] \frac{H_0}{L} \tag{5.9}$$

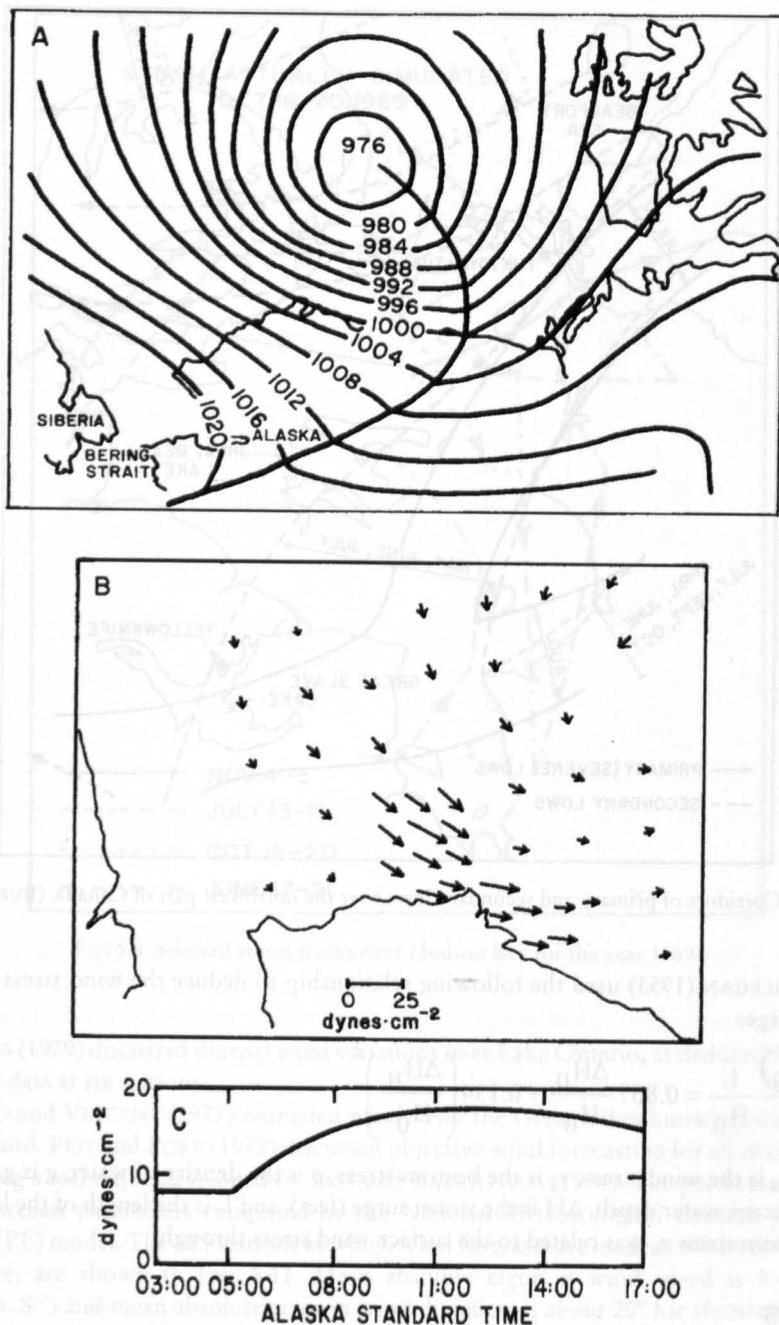


Fig. 5.10: (A) Simplified surface weather chart for October 3, 1963, at 11:00 (Alaska Standard Time); (B) computed wind stress field for 11:00-14:00; (C) variation of wind stress with time at Barrow, Alaska (1 dyne = 10 N). (SCHAFFER, 1966)

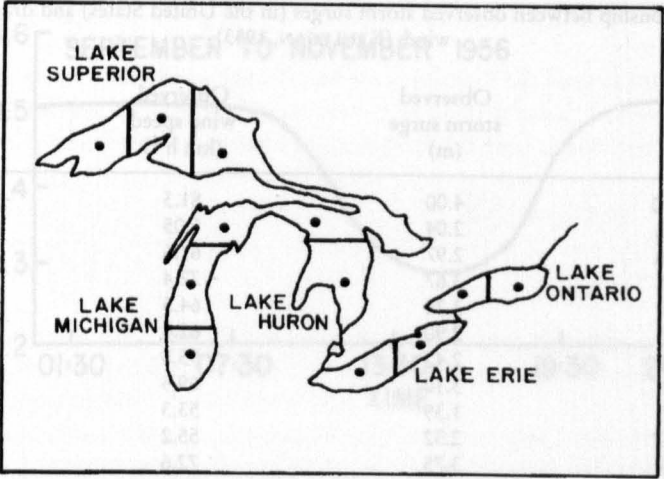


Fig. 5.11: Twelve locations in the Great Lakes where winds are routinely predicted by the U.S. National Weather Service. (FEIT and PORE, 1978)

Write

$$\tau_S = \gamma \rho_a V^2 \tag{5.10}$$

where, ρ_a is the density of air, V is the wind speed (feet per second), and the drag coefficient γ is given by

$$\gamma = \frac{0.867}{(1+n)} \left[1 - 0.16 \frac{\Delta H_0}{H_0} \right] \frac{\Delta H_0}{H_0} \frac{\rho}{\rho_a} \frac{g H_0}{V^2} \tag{5.11}$$

The 22 storms during the period 1900–47 on Lake Erie, the observed wind speed, the observed storm surge (during westerly winds), and the calculated value of γ from eq. (5.11) are listed in Table 5.1.

HUNT (1959) discussed the relationship between the parameter α defined as

$$\alpha \equiv \frac{\tau_S + \tau_B}{\tau_S} \tag{5.12}$$

and D/K where D is the water depth, K is the bottom roughness coefficient, and τ_S and τ_B are the wind and bottom stresses. The relationship for Lake Erie is shown in Fig. 5.12. HUNT (1959) also gave diagrams showing the variation with time in fall and spring of the ratio U_w/U_L at Cleveland on Lake Erie (Fig. 5.13). Here, U_w and U_L are the overwater and overland wind speeds. The reason for examining this ratio is to account for atmospheric stability. The ratio U_w/U_L at four stations on Lake Erie for stable, adiabatic, and unstable atmospheric conditions is given in Table 5.2. The overwater wind speeds on Lake Erie at 21:00 on November 8, 1957, are shown in Fig. 5.14.

IRISH and PLATZMAN (1961) discussed the meteorological conditions associated with extreme storm surges on Lake Erie. The monthly frequency distributions of severe storms

Table 5.1: Relationship between observed storm surges (in the United States) and drag coefficients of wind. (KEULEGAN, 1953)

Date of storm surge	Observed storm surge (m)	Observed wind speed (km h ⁻¹)	Drag coefficient $\gamma \cdot 10^3$
Nov. 21, 1900	4.00	81.3	2.13
Oct. 20, 1905	2.04	5.05	2.87
Oct. 20, 1906	2.97	61.6	2.78
Jan. 20, 1907	3.67	77.4	2.17
Dec. 7, 1909	3.20	64.5	2.73
Dec. 31, 1911	2.90	62.6	2.63
Jan. 31, 1914	2.42	55.8	2.76
Dec. 9, 1917	3.10	69.5	2.23
Dec. 9, 1917	1.39	53.3	1.78
Dec. 10, 1917	2.32	55.2	2.71
Dec. 18, 1921	3.75	72.6	2.52
Dec. 8, 1927	4.04	76.3	2.44
Dec. 9, 1927	1.26	43.8	2.35
Dec. 9, 1927	1.05	42.0	2.15
Dec. 9, 1927	0.53	35.6	1.53
Apr. 1, 1929	4.06	82.6	2.88
Jan. 22, 1939	2.87	62.4	2.64
Sept. 25, 1941	2.76	57.5	2.96
Jan. 2, 1942	3.82	65.0	3.22
Jan. 3, 1942	0.73	31.4	2.68
Nov. 22, 1946	2.55	55.0	2.99
Mar. 25, 1947	2.54	57.5	2.77

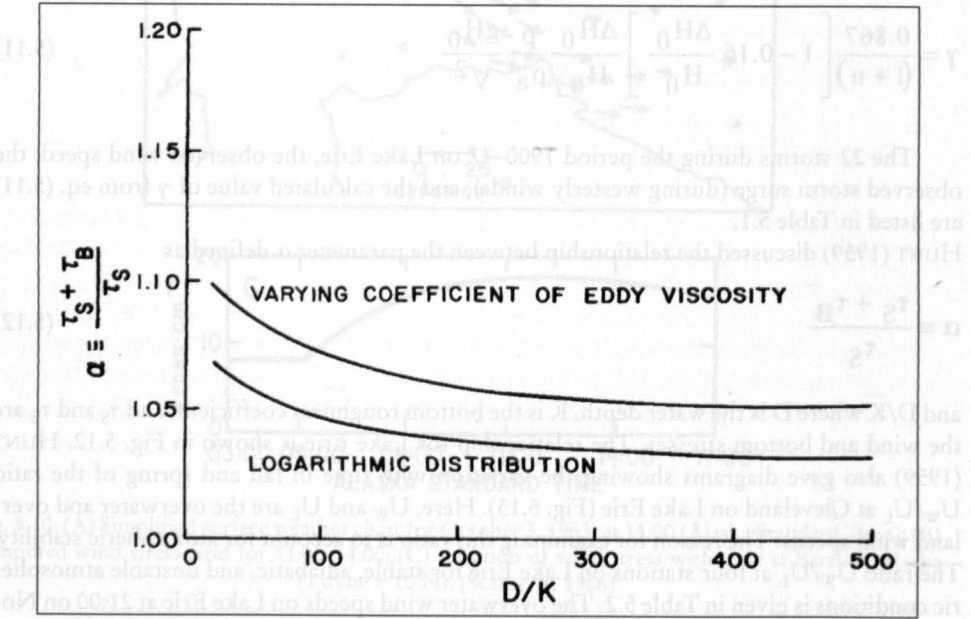


Fig. 5.12: Variation of a versus D/K (D = water depth, K = bottom roughness parameter, τ_s = wind stress, and τ_B = bottom stress). The relationship is shown for two different distributions of bottom stress. (HUNT, 1959)

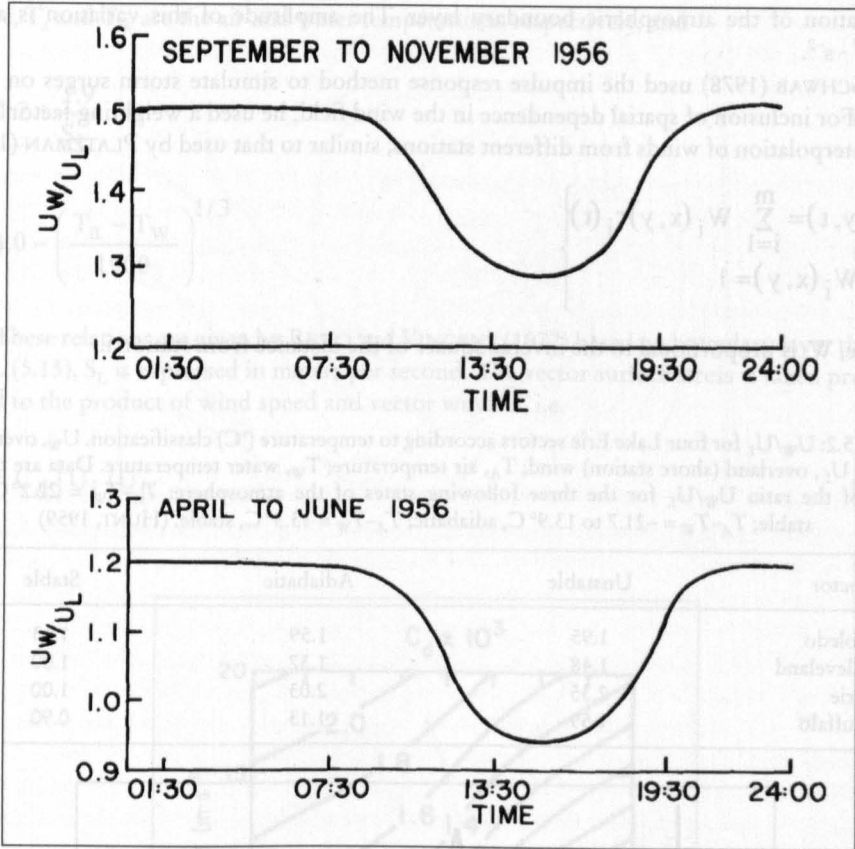


Fig. 5.13: Daily variation in U_W/U_L for southwesterly winds by season at Cleveland, Ohio, during 1956. (HUNT, 1959)

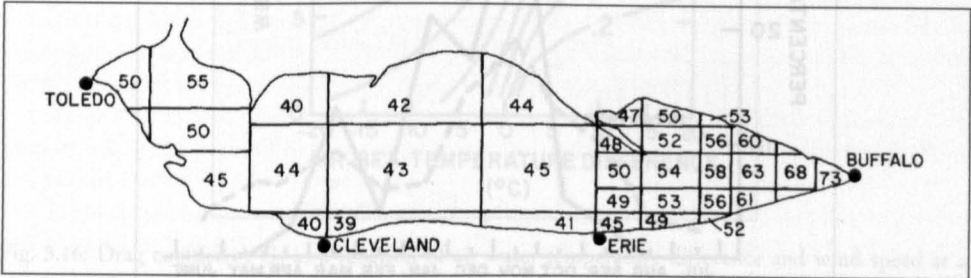


Fig. 5.14: Overwater wind speeds (feet per second) in Lake Erie (1 ft = 0.3048 m). (HUNT, 1959)

on the Great Lakes, as given by these authors for the period 1876–1900, are given in Fig. 5.15. It can be seen that maximum frequency occurs during October to December, November being the month of greatest frequency.

PLATZMAN (1965) showed that over Lake Erie, there is a distinct diurnal constituent of the longitudinal component of the wind square vector, with maximum in the direction Toledo to Buffalo shortly after noontime. This variation is due to the usual convective

oscillation of the atmospheric boundary layer. The amplitude of this variation is about $10 \text{ m}^2 \cdot \text{s}^{-2}$.

SCHWAB (1978) used the impulse response method to simulate storm surges on Lake Erie. For inclusion of spatial dependence in the wind field, he used a weighting factor W_i in the interpolation of winds from different stations, similar to that used by PLATZMAN (1963):

$$\left. \begin{aligned} \tau(x, y, t) &= \sum_{i=1}^m W_i(x, y) \tau_i(t) \\ \sum_{i=1} W_i(x, y) &= 1 \end{aligned} \right\} \tag{5.13}$$

where, W_i is proportional to the inverse square of the distance from station i .

Table 5.2: U_w/U_L for four Lake Erie sectors according to temperature ($^{\circ}\text{C}$) classification. U_w , overwater wind; U_L , overland (shore station) wind; T_A , air temperature; T_w , water temperature. Data are the values of the ratio U_w/U_L for the three following states of the atmosphere: $T_A - T_w = 22.2^{\circ}\text{C}$, unstable; $T_A - T_w = -21.7$ to 13.9°C , adiabatic; $T_A - T_w = 13.3^{\circ}\text{C}$, stable. (HUNT, 1959)

Sector	Unstable	Adiabatic	Stable
Toledo	1.95	1.59	1.13
Cleveland	1.48	1.37	1.00
Erie	2.35	2.03	1.00
Buffalo	1.59	1.13	0.90

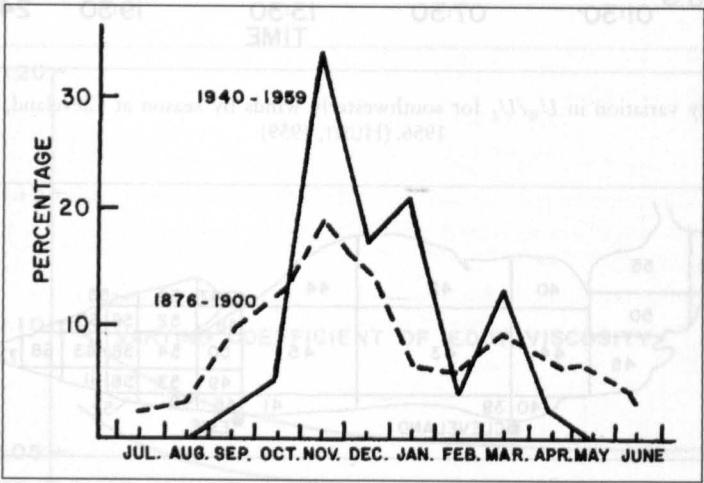


Fig. 5.15: Monthly frequency distribution of severe storms on the Great Lakes for the period 1940–59 (solid line) and for the period 1876–1900 (broken line). (IRISH and PLATZMAN, 1961)

SCHWAB (1978) converted the observed wind speeds S_L at the coastal stations into over-lake wind speeds S_w through

$$\frac{S_w}{S_L} = \psi(S_L) \phi(T_a - T_w) \tag{5.14}$$

where, T_a and T_w are the air and water temperatures, respectively, and

$$\psi = 1.2 + \frac{1.9}{S_L} \tag{5.15}$$

$$\phi = 1.0 - \left(\frac{T_a - T_w}{1900} \right)^{1/3} \tag{5.16}$$

These relations are given by RESIO and VINCENT (1977) based on boundary layer theory. In eq. (5.15), S_L is expressed in meters per second. The vector surface stress is taken proportional to the product of wind speed and vector wind U , i.e.

$$\frac{\tau_i}{\rho_a} = C_d |U_i| U_i \tag{5.17}$$

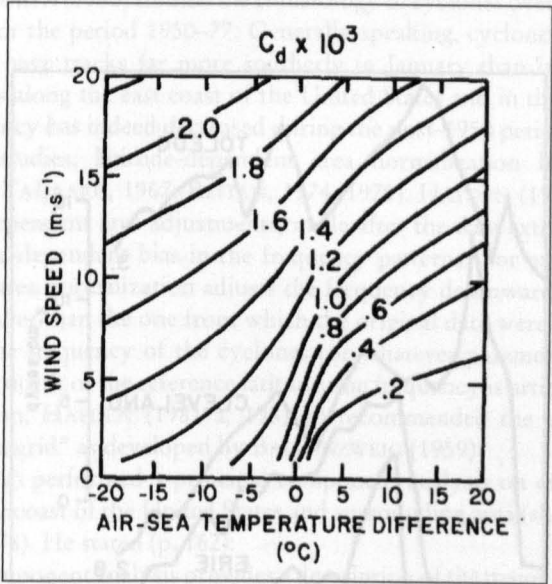


Fig. 5.16: Drag coefficient C_d as a function of air-water temperature difference and wind speed at a 10-m height. (SCHWAB, 1978)

The air density ρ_a is taken as $1.25 \times 10^{-3} \text{ g} \cdot \text{cm}^{-3}$. The drag coefficient C_d as a function of $(T_a - T_w)$ and wind speed (at a 10-m height) is shown in Fig. 5.16.

HAMBLIN (1979) numerically simulated the storm surge of April 6, 1979, which produced a record set-up of 4.5 m on Lake Erie. The surface isobaric field for this storm is shown in Fig. 5.17 and the time variation of the wind stress at four stations is given in Fig. 5.18. HAMBLIN (1979) mentioned that the computed drag coefficients varied from 0.9×10^{-3} to 3.5×10^{-3} during the duration of the storm.

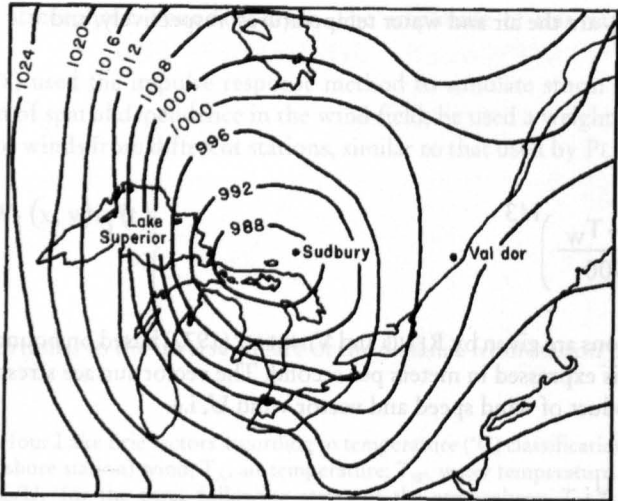


Fig. 5.17: Simplified surface weather chart at 01:00 (Eastern Standard Time) on April 6, 1979. The pressure field is in millibars. (HAMBLIN, 1979)

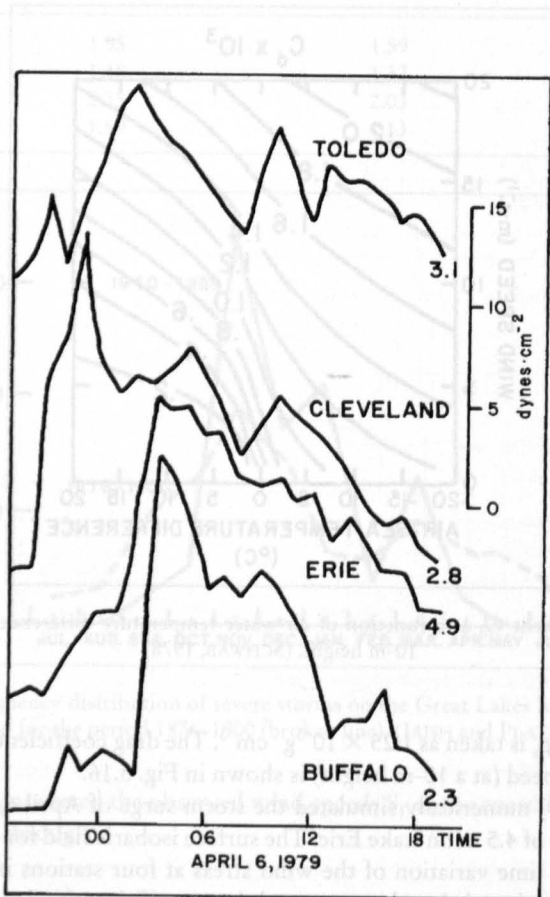


Fig. 5.18: Time history of wind stress at four locations on Lake Erie. (HAMBLIN, 1979)

SIMONS (1975) determined the effective wind stress over Lakes Erie and Ontario from long-term numerical water level simulations. He showed that the effective wind stress over water is greater than indicated by atmospheric boundary layer measurements over Lake Ontario; the theoretically derived drag coefficient appears to be about 1.85×10^{-3} . Over Lake Erie, the drag coefficient is about the same magnitude in spring and early summer, but increases to about 2.5×10^{-3} during the stormy autumn season. These results confirm DONELAN's (1975) study of the interaction between wind waves and the atmospheric boundary layer, whose primary result was that the drag coefficient increases significantly if the wave field is not completely adjusted to the wind field. Usually, boundary layer observations are made during steady winds (when no storms are present) and, hence, such measurements are not representative of drag coefficient during stormy periods.

Extratropical Storm Surges in the United States

REITAN (1979) extended his earlier study (REITAN, 1974) to cover the period 1949–76, which is characterized by gradually decreasing temperature in the Northern Hemisphere. This study showed a general trend for a decrease in the number of cyclonic events in recent years. ZISHKA and SMITH (1980) studied the climatology of cyclones over North America and surrounding area for the period 1950–77. Generally speaking, cyclones are more frequent, more intense, and have tracks far more southerly in January than in July. Predominant cyclogenesis occurs along the east coast of the United States and in the lee of the Rockies. The cyclone frequency has indeed decreased during the post-1950 period.

In a lot of studies, latitude-dependent area normalization has been used (e.g. O'CONNOR, 1964; TALJAARD, 1967; REITAN, 1974, 1979). HAYDEN (1981a, 1981b) pointed out that latitude-dependent area adjustments, made after the data extraction is completed, introduce a latitude-dependent bias in the frequency patterns. For example, south of the reference latitude, area normalization adjusts the frequency downward and forces it to represent an area smaller than the one from which the original data were extracted. This artificially decreases the frequency of the cyclones (or whatever parameter being tabulated). On the other hand, north of the reference latitude, the frequency is artificially increased. To correct this situation, HAYDEN (1981 a, 1981 b) recommended the use of the so-called "practical equal area grid" as developed by BALLENZWEIG (1959).

HAYDEN (1981a) performed a principal component analysis on extratropical cyclone data for the Atlantic coast of the United States and surrounding area (shown in Fig. 5.19 for the period 1885–1978). He stated (p. 162):

... principal component analysis provides a description of the major modes of variability in the data set. Typically, each component is identified with some property of the data field. The analysis also provides an index, which measures the importance of each component within each year. Finally, the analysis provides an estimate of the total percent of variance in the data set, which can be explained on the basis of each component.

The objective of the analysis is to isolate characteristic, recurrent, and independent modes of covariance among variables into a new set of independent variables. Basically, the analysis transforms a set of intercorrelated variables into a new coordinate system in which the axes are linear combinations of the original variables and are mutually orthogonal. To prevent those grid cells with high mean cyclone frequencies (high latitudes) from dominating the total variance and consequently from dominating the eigenvector forms, the correlation matrix was used rather than the covariance matrix.

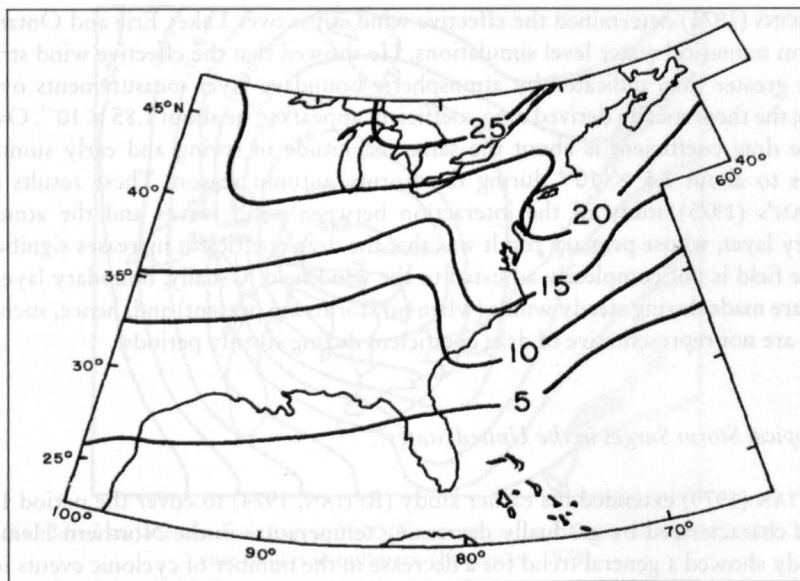


Fig. 5.19: Average annual frequency of extratropical cyclones over the eastern part of the United States. (HAYDEN, 1981a)

The area shown in Fig. 5.19 was divided into 74 rectangles (2.5° latitude by 5° longitude). The first principal component showed that, since the beginning of the twentieth century, the frequency of cyclones over the marine areas has increased whereas the frequency decreased over the continental areas. This trend peaked in the 1960s. The second principal component was identified as a cyclogenesis function for the east coast of the United States. This showed an increased cyclogenesis starting at the beginning of the twentieth century with a maximum in the 1950s. The third and fourth components explain the geographic variations in cyclogenesis in the Gulf coast and Great Lakes regions. The average cyclone frequencies over the eastern United States for the period 1885–1978 are also shown in Fig. 5.19.

Usually, one uses the Norwegian cyclone model to explain extratropical cyclogenesis. REED (1979) pointed out that it is not always necessary for the cyclone to originate as a wave perturbation on a polar front separating tropical and polar air masses. An alternate mechanism is the formation of cyclones in polar air streams behind or poleward of the polar front, as sometimes happens in winter over the oceans.

Cyclones that form in this manner are relatively small in size. One interesting feature is that, in their mature stage, these cyclones exhibit a comma-shaped pattern. A surface low pressure centre may not always be easily identifiable. When it exists, such a low pressure centre is situated beneath the head of the comma. Also, under the trailing edge of the comma tail, there is almost always a surface trough of low pressure. Thus, cyclones of this type somewhat resemble large frontal cyclones.

Wind Stress and pressure in extratropical cyclones over the United States

TANCRETO (1958) used the significant wave (wind waves) height as an indication of the intensity of the storm. An extratropical cyclone generated storm surge during March 1962

caused tremendous damage in Atlantic City (New Jersey). The surge was so severe it bisected a steel pier (PORE, 1964). Extratropical cyclone generated storm surges are not rare on this part of the east coast of the United States (e.g. February 1958).

MILLER (1957) showed that maximum surges at Norfolk are associated with east-north-east winds. There is a lag of 12 h between the wind and the surge. PORE (1964) studied 18 storm surges during the period 1956–61. For these 18 storms, there was a total of 1910 hourly observations available. Most of these storms passed over the southeastern United States and then moved offshore over the Atlantic Ocean. Maximum wind speeds varied from 22 to 50 knots ($41\text{--}93\text{ km h}^{-1}$). Three meteorological forcing terms were considered separately:

- a) onshore component of the wind stress (which produces a set-up),
- b) alongshore component of the wind stress (which generates alongshore currents, which then are deflected to the right by the Coriolis force, and this creates an upward slope of the water surface toward the right) and
- c) atmospheric pressure (inverse barometer effect).

An interesting result of this study is that the storm surge at Atlantic City is strongly dependent on the alongshore component of the wind. There appears to be little difference between the results obtained using linear wind stress and quadratic wind stress.

WANG (1979) examined the response of the water level in Chesapeake Bay to the time scale of atmospheric forcing. For time scales longer than 7 d, the water levels in the bay were driven nonlocally by the coastal water levels. For periods between 4 and 7 d, the water level in the bay was driven both by the coastal sea level as well as the lateral component of the wind. For time scales of 1–3 d, the water level in the bay was driven by the longitudinal component of the wind.

SAUNDERS (1977) computed seasonal averages of wind stress over the eastern continental shelf of North America making use of about 1 million ship observations for the period 1941–72. He assumed a drag coefficient that increases with the wind speed from 1.0×10^{-3} at 5 m s^{-1} wind speed to 2.3×10^{-3} at 25 m s^{-1} . Atmospheric stratification was found to have little effect. The stress is strongest in winter ($1\text{--}15\text{ dynes cm}^{-2}$) and weakest in fall ($0.25\text{--}0.5\text{ dynes cm}^{-2}$). In summer the stress is directed towards the northeast whereas in the other three seasons it is directed south and east. The wind stress generally increases with increasing latitude, but local maxima are found over the Gulf of Maine and the Gulf of St. Lawrence. SAUNDERS (1977) attributed the local maxima and minima to cyclonic activity.

Storm Surges in Europe

Cyclones causing storm surges in the waters in and around Europe are mainly of the extratropical type, and the meteorological problems associated with these storms are somewhat simpler than those due to tropical cyclones. Most of the storm surges in Europe occur in the North Sea; other areas where surges occasionally occur are the Baltic Sea, the Irish Sea, Adriatic Sea, Ligurian Sea, the Atlantic coast of Portugal and the coasts of Norway and Sweden.

North Sea and Baltic Sea

A special meteorological situation must occur to induce storm surges in the North Sea. When a depression reaches the North Sea from west or northwest, an air stream develops.

The strength of an air stream depends on the pressure situation in the high, the location of the storm depression to the neighbouring high pressure area, the location of the fronts and speed and direction of the depression. For example, when the centre of the depression travels north of the Southern North Sea Coast wind there coming from west to northwest is generated and can lead to storm surges at this coast.

The depressions take different routes (Fig. 5.20). The meteorological situation leading to high or very high storm surges at the Southern North Sea Coast can be classified into three types (PETERSEN and ROHDE, 1991), here complemented by the fourth, called mixed type:

1. Jutland-Type

It forms south of 60°N over Newfoundland and travels from west to east from England over the North Sea to Jutland and then either over the south of Sweden in easterly direction or turns off to northeast. These low pressure systems travel mostly very fast and cause strong storms for a short period. The winds change from southwest to northwest or north. As pointed out by GÖNNERT (1999), a fast increase of wind speed causes high storm surge peaks at the coast of the German Bight. Examples of the storm surge of February 23–24, 1967 and January 3, 1976 are shown in Fig. 5.21. The curve of the surge has mostly a steep slope. When high wind speed persists for more than 2–5 hours and water levels only drop slowly this type of cyclonic track can cause dangerous storm surges.

2. Scandinavia-Type:

These depressions form over Greenland and Iceland and travel towards southeast. They cross Scandinavia between 60°N and 65°N . This type causes storms with long duration from northwest over the North Sea. Therefore more than one tidal peak (sometimes with 3–4 lower peaks following) is caused from this type of cyclone. The storm surge curve shows a slow ascent and a slow drop. Due to the long duration of this type of storm surge with its high water level dikes can become water-saturated, soggy and unstable. Examples for this type can be found on February 16–17, 1962 and January 20–22, 1976 (Fig. 5.22).

Sometimes the tracks of the Jutland-Type and of the Scandinavia-Type are mixed. The Storm surge of November 22–23, 1981 started with a path of the Scandinavia-Type, but changed direction and travelled over Scandinavia to the southern Baltic Sea like the Jutland-Type.

3. Skagerrak-Type

The tracks of these cyclones lie between both types described before. They cross the 8^{th} degree of Longitude between 57° to 60°N . Mostly they travel from WNW to ESE, but sometimes they travel from W to E and NW to SE. The wind blows from WNW and NW towards the entire coast of the North Sea and causes storm surges. The storm surges of February 12, 1894, March 13, 1906, February 13 and 16, 1916, October 10, 1926, October 18 and 27, 1936 and November 16, 1973 were caused by this cyclonic type.

4. Mixed-Types

Many surges are not caused by one type of meteorological situation only. The track of the depression is composed of different types. For example, the storm depression of February 1, 1953, which caused a very high storm surge at the coast of the Netherlands and at the east coast of the United Kingdom, took the direction of the Skagerrak-Type and then changed direction between Scotland and south of Norway to the south. Because of the change of direction at the German Coast only a small storm surge occurred. WEMELS-FELDER (1954) mentioned that the meteorological conditions associated with the storm of February 1, 1953, were quite different from the traditional storm tracks that emerge over Scotland and disappear over Norway or Denmark. In this 1953 case, the storm track cross-

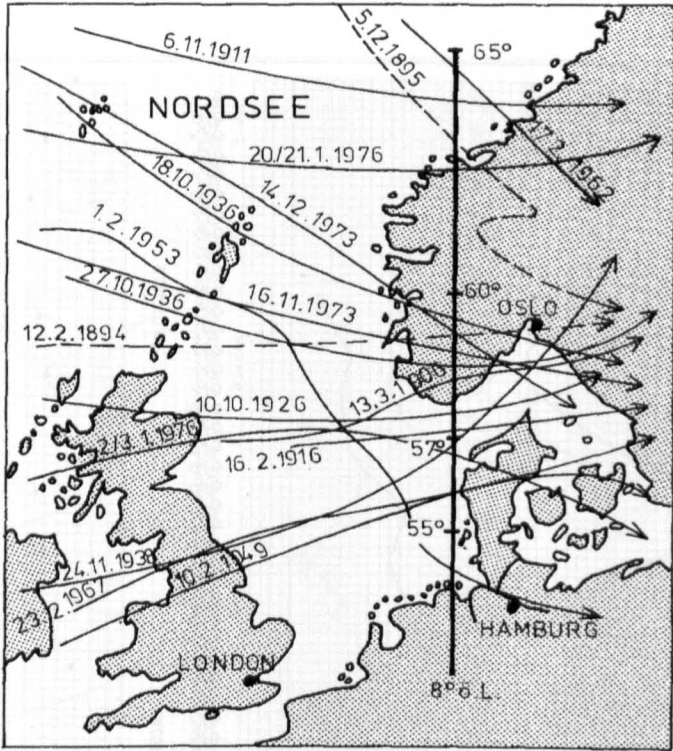


Fig. 5.20: Storm depression, which causes storm surge tracks at the North Sea Coast (PETERSEN and ROHDE, 1991)

sed the North Sea from Scotland to Hamburg. The Netherlands coast is very vulnerable to this type of track. Detailed meteorological data about this storm are presented by SNEYERS (1953).

DOODSON (1929) classified the meteorological situations for the Thames Estuary in the same way as presented here. Most of the major storm surges in the Thames Estuary are associated with type I meteorological situations. One example of type I is the storm of December 30–31, 1921, which reached a speed of 161 km/h (NNW) and caused a very high storm surge. The surface isobaric patterns at two different instants of time are shown in Fig. 5.23. DOODSON (1929) and DINES (1929) listed the storm surges in the Thames Estuary during the period 1912–28 (MURTY, 1984).

The Baltic Sea can be described as a relatively closed basin because the connection between North Sea and Baltic Sea is very small in relation to the surface of the bordering sea. Strong wind from southwest causes storm surges in the North and low water levels in the South. A change of wind direction to NNE causes high water levels in the southern part of the Baltic Sea. At the north-eastern as well as at the south-western part of the longitudinal axis of the Baltic Sea high water levels of more than 3 m over mean water level can be observed.

The special meteorological situation in Europe causes stormy weather and, with this, storm surges only during the period from September to April. The highest frequency occurs in the period from October to February, the highest level was reached in the same period. Fig. 5.24 shows the average annual distribution of storm surges at Cuxhaven for the period

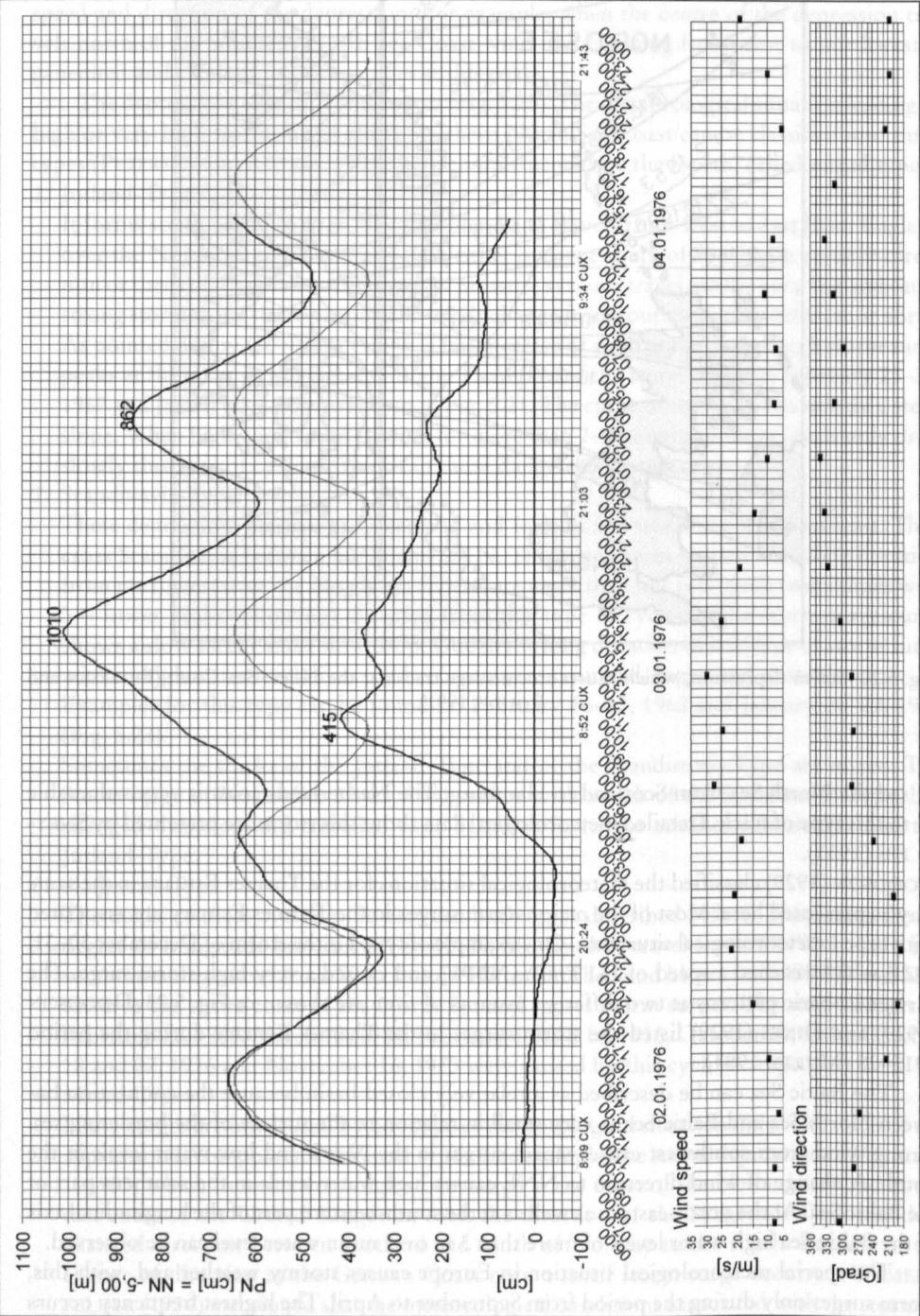


Fig. 5.21: Storm surge at Cuxhaven from January 3, 1976 (GÖNNERT and SIEFERT, 1998)

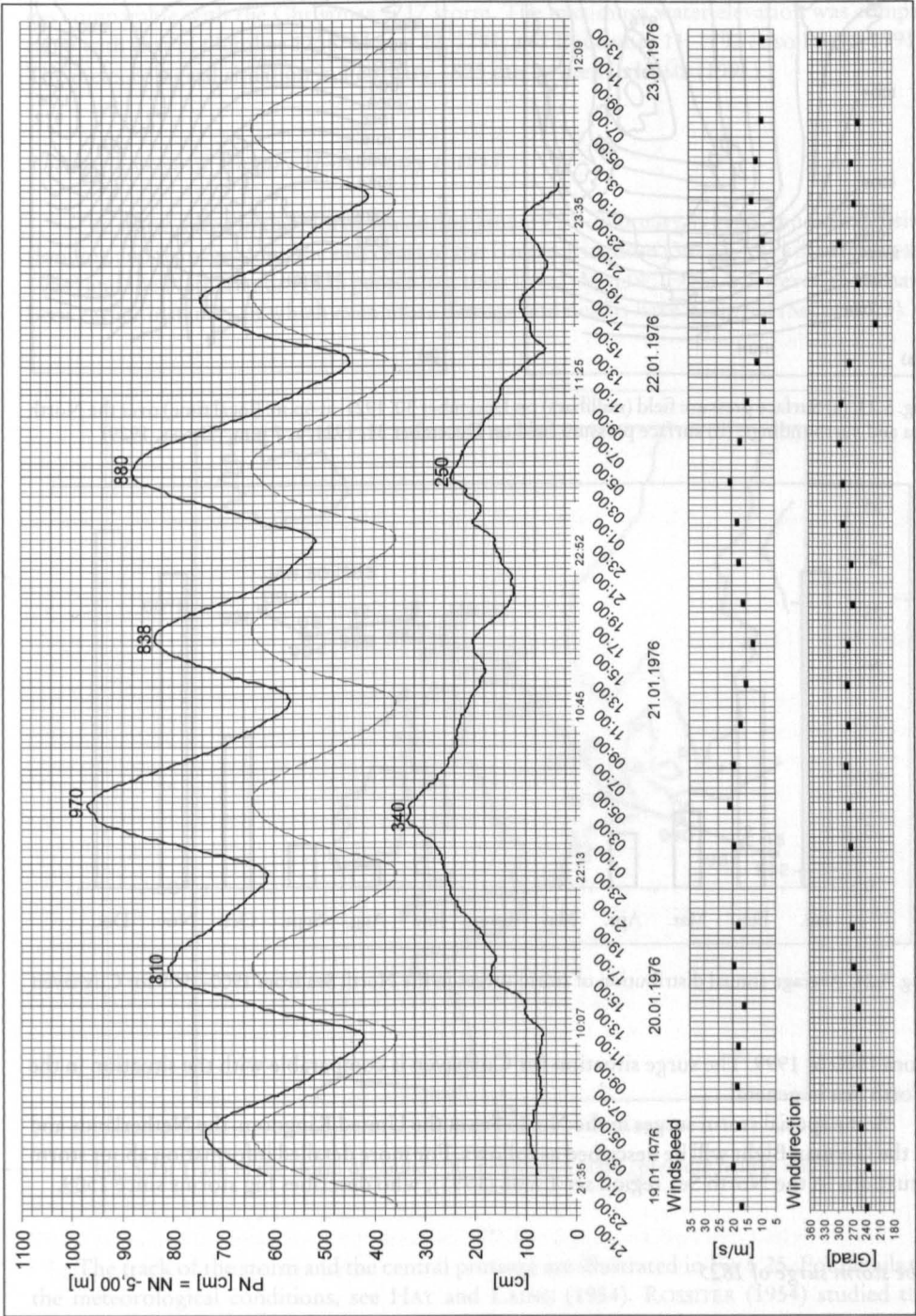


Fig. 5.22: Storm surge at Cuxhaven from January 20–22, 1976 (GÖNNERT and SIEFERT, 1998)

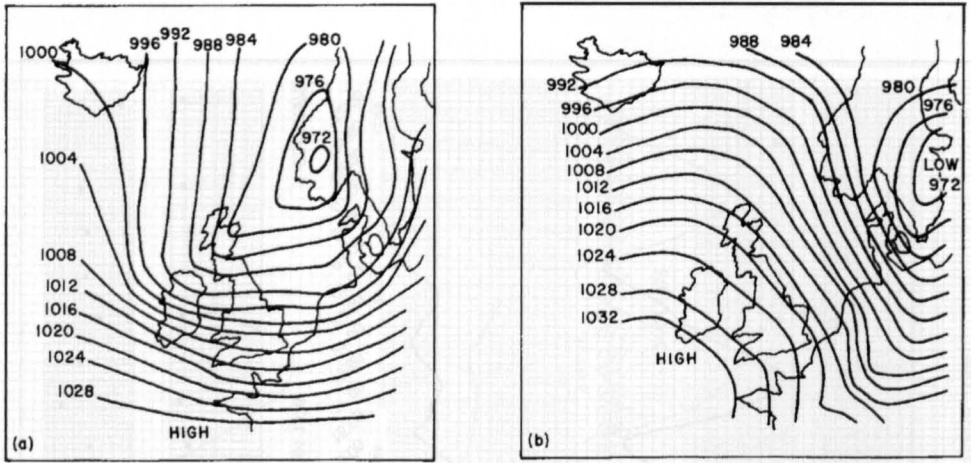


Fig. 5.23: (a) Surface pressure field (millibars) on December 30, 1921, at 6 p.m. (local time) over the North Sea and surroundings; (b) surface pressure field on December 31, 1921, at 7 p.m. (DINES, 1929)

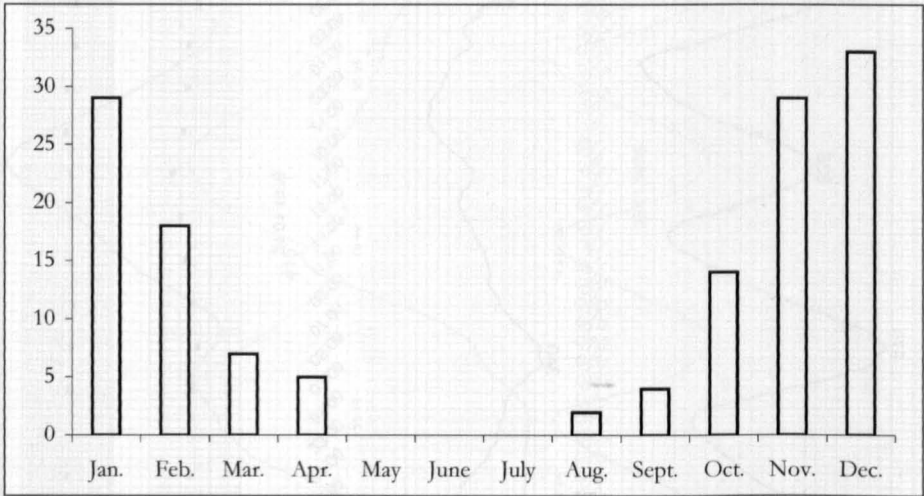


Fig. 5.24: Average annual distribution of storm surges in the North Sea from 1900–1999 for Cuxhaven

from 1900 to 1999. The surge situation for Cuxhaven is comparable with the situation in the North Sea in general.

Some special storm surges in the North Sea at the United Kingdom, the Netherlands and in the German Bight will be described as follows. For more detailed information about storm situations in the North Sea region see LAMB (1991), who describes big storms since 1509.

The storm surge of 1825

The storm of February 1–2, caused storm surges in Scotland and the neighbouring sea areas to north and east. The storm of February 2–5 caused a disastrous storm surge from

Holland to Denmark. The storm tide crest reached a level of more than 350 cm over mean high tide level at Cuxhaven (German Bight) and was therefore one of the highest storm surges comparable with the Christmas 1717 storm. The maximum water elevation was comparable with that of October 1756, March 22, 1791, and December 11, 1792 (also LAMB, 1991). The meteorological situation in February 1825 can be seen in LAMB (1991).

The storm surge of January 31–February 1, 1953

The storm surge in the North Sea during January 31–February 1, 1953, caused extensive flooding and damage along the east coast of the United Kingdom (307 people killed) (STEERS, 1954) and the Netherlands (1835 people lost their lives) (MALDE, 1996). However, there have been earlier instances in which even more damage and deaths have occurred (Section 7.3).

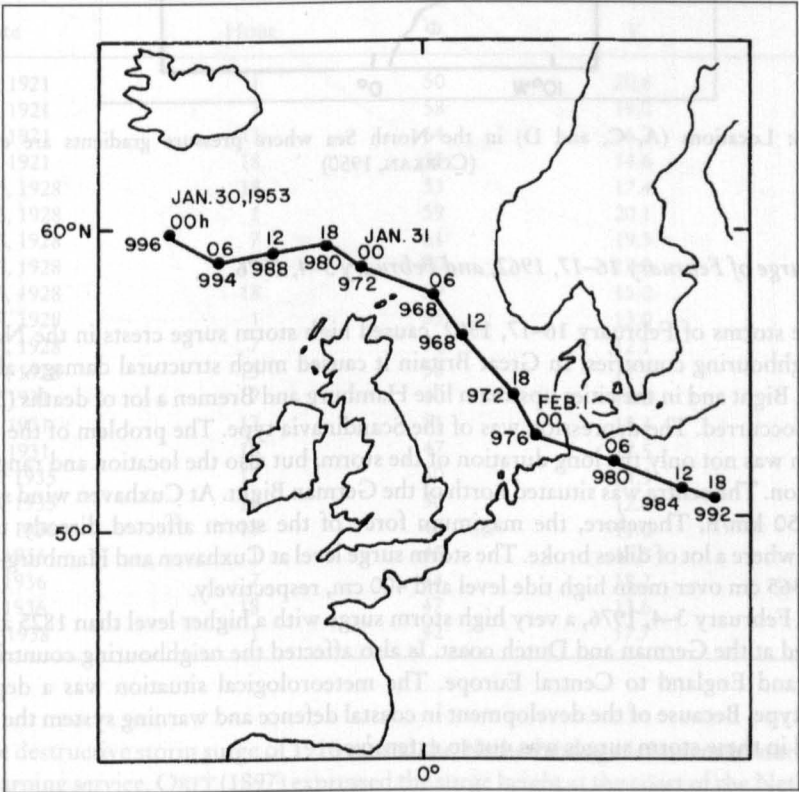


Fig. 5.25: Track of the storm of January 30–February 1, 1953 (pressure field in millibars).

The track of the storm and the central pressure are illustrated in Fig 5.25. For details on the meteorological conditions, see HAY and LAING (1954). ROSSITER (1954) studied this storm surge and also used the same pressure points (Fig. 5.26) and the same method as DOODSON (1924, 1929) and CORKAN (1948, 1950).

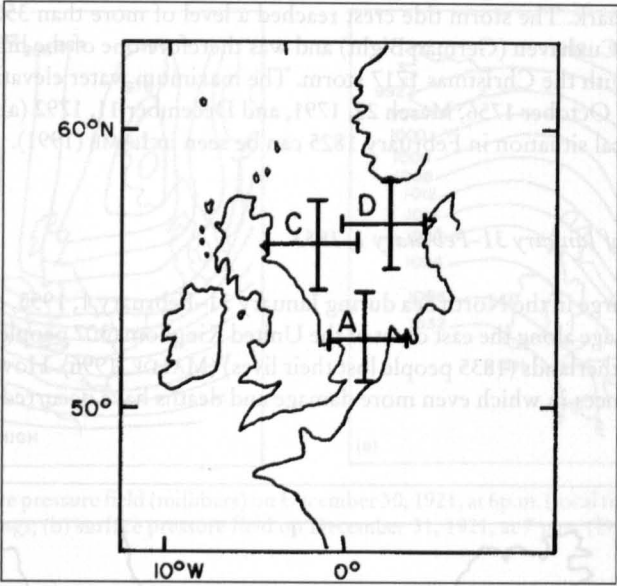


Fig. 5.26: Locations (A, C, and D) in the North Sea where pressure gradients are evaluated. (CORKAN, 1950)

Storm surge of February 16–17, 1962, and February 3–4, 1976

The storms of February 16–17, 1962, caused high storm surge crests in the North Sea and neighbouring countries. In Great Britain it caused much structural damage, along the German Bight and in the cities upstream like Hamburg and Bremen a lot of deaths (340) and damage occurred. The depression was of the Scandinavia type. The problem of the weather situation was not only the long duration of the storm, but also the location and range of the depression. The centre was situated north of the German Bight. At Cuxhaven wind speed reached 150 km/h. Therefore, the maximum force of the storm affected directly the Elbe estuary, where a lot of dikes broke. The storm surge level at Cuxhaven and Hamburg-St Pauli rose to 365 cm over mean high tide level and 400 cm, respectively.

On February 3–4, 1976, a very high storm surge with a higher level than 1825 and 1962 happened at the German and Dutch coast. Is also affected the neighbouring countries from Ireland and England to Central Europe. The meteorological situation was a depression Jutland type. Because of the development in coastal defence and warning system the damage incurred in these storm surges was not so extensive.

Surges in the German Bight and at the coast of the Netherlands

SCHALKWIJK (1947) gave a comprehensive analysis of storm surges at the coast of the Netherlands until 1940, and the following discussion is based on his paper.

Table 5.3: International and Bleck equivalents of the Beaufort Scale. (SCHALKWIJK, 1947)

Degrees Beaufort	International equivalent of wind speed (m·s ⁻¹)	Bleck equivalent of wind speed (m·s ⁻¹)	Degrees Beaufort	International equivalent of wind speed (m·s ⁻¹)	Bleck equivalent of wind speed (m·s ⁻¹)
1	1.1	1.8	7	13.8	17.4
2	2.5	4.4	8	16.7	20.0
3	4.3	7.0	9	19.9	22.6
4	6.3	9.6	10	23.3	25.2
5	8.6	12.2	11	27.1	27.8
6	11.1	14.8	12	>29.0	>29.0

Table 5.4: Values of deviation angle Ψ (degrees), wind speed V (m·s⁻¹), and surge η (cm) for the storm surges at the Netherlands coast. (SCHALKWIJK, 1947)

Date	Hour	Φ	V	η
Jan. 19, 1921	1	50	20.8	155
Jan. 19, 1921	7	58	19.0	134
Jan. 19, 1921	13	64	16.7	99
Jan. 19, 1921	18	55	14.6	70
Nov. 25, 1928	18	53	17.4	115
Nov. 26, 1928	1	59	20.1	172
Nov. 26, 1928	7	61	19.3	142
Nov. 26, 1928	13	60	17.0	105
Nov. 26, 1928	18	59	15.0	86
Nov. 27, 1928	1	55	13.0	74
Nov. 27, 1928	7	54	12.1	71
Nov. 27, 1928	13	58	12.3	71
Jan. 17, 1931	7	40	18.9	133
Jan. 17, 1931	13	51	18.4	139
Jan. 18, 1931	18	47	12.5	45
Oct. 30, 1935	13	50	14.3	71
Oct. 20, 1935	18	50	12.4	44
Oct. 20, 1936	18	46	11.0	54
Dec. 1, 1936	1	43	18.3	141
Dec. 1, 1936	7	44	18.2	176
Dec. 2, 1936	18	47	13.6	71
Jan. 30, 1938	1	42	17.7	119

The destructive storm surge of 1916 caused the Netherlands government to start a storm surge warning service. ORIT (1897) expressed the surge height at the coast of the Netherlands through

$$\eta = KR + R_b(76 - p)$$

(5.18)

where η is the storm surge (centimetres), K is a factor representing the influence of the strength of the wind, R is a factor representing the wind direction, R_b is a factor representing the effect of atmospheric pressure, and p is the atmospheric pressure (centimetres of mercury).

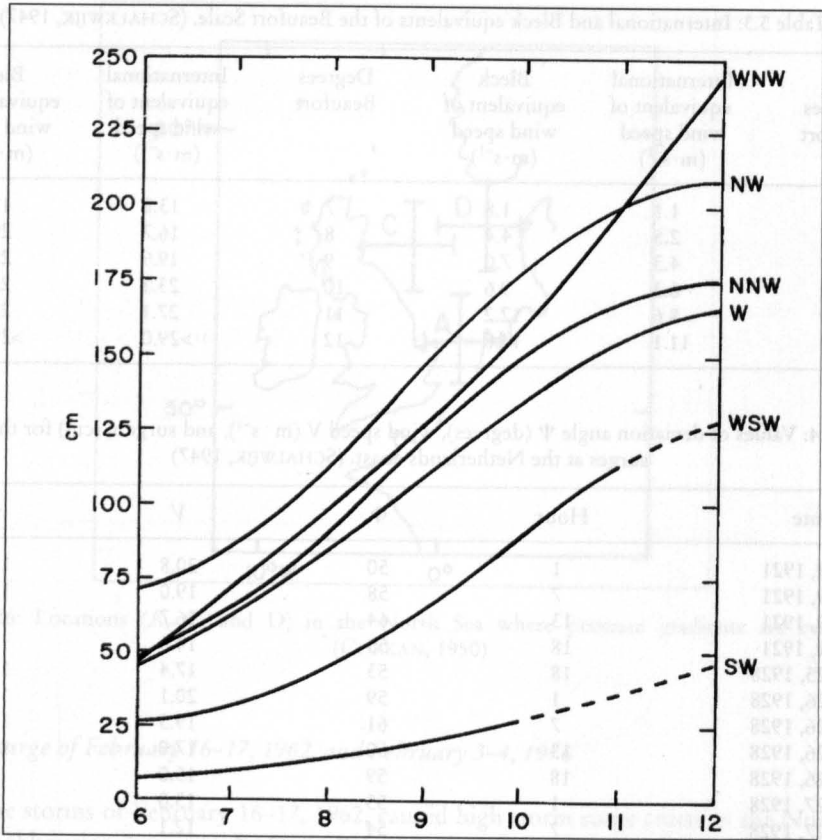


Fig. 5.27: Storm surge versus wind speed at Hook of Holland. Schalkwijk, based on earlier studies by a Netherlands Government committee, summarized these results. (SCHALKWIJK, 1947)

For the Netherlands coast

$$K = 0.14V^2 \tag{5.19}$$

where, V is the wind velocity. SCHALKWIJK (1947) gave tables of R and R_b for various wind directions. ORTT (1897) showed that large surges are produced by W to WNW winds and the smallest surges are produced by E to ESE winds and, in general, there is a lag of about 6 h between the wind and the surge.

The committee (Rotterdamsche Waterweg) established by the Netherlands government in 1920 studied 19 storm surges for the period 1887–1917. They related the surges to the wind but ignored time lag and atmospheric pressure gradients. The results of this study are shown in Fig. 5.27 (the Beaufort Scale is explained in Table 5.3). One interesting result is that the winds over the southern part of the North Sea are more relevant than the local winds in generating these surges.

$$\eta = \frac{aV^2 L \cos \psi}{H} \tag{5.20}$$

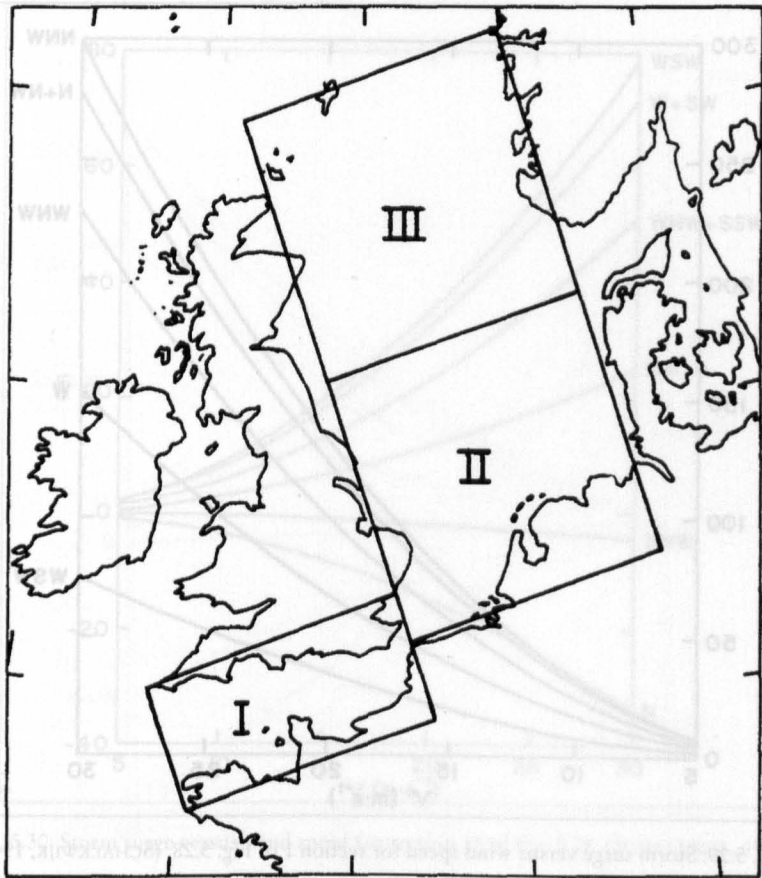


Fig. 5.28: Three sections of the North Sea for which the storm surge study was made. (SCHALKWIJK, 1947)

where, $a = 0.0036$, V is the wind velocity (metres per second), η is the surge (centimetres), H is the water depth (metres), L is the channel length (kilometres), and Ψ is the angle between the wind direction and the channel axis. COLDING (1880, 1881) used a slightly different formula:

$$\eta = \frac{0.048LV^2 \cos^2 \Psi}{H} \tag{5.21}$$

This formula was successfully used to hindcast the storm surges of November 12–14, 1872, on the Danish coast and in the Baltic Sea.

Based on several studies (MAZURE, 1937; PALMEN, 1932) and verified by more recent research (GÖNNERT, 1999), the following results can be deduced for the Southern North Sea coast. The time lag between the wind and surge is 3–6 h. The most effective wind direction in generating surges is NW. The relationship between the surge and atmospheric pressure gradient is related to the structure and movement of the pressure field. The surge in the southern part of the North Sea is closely related to the average wind over the whole North

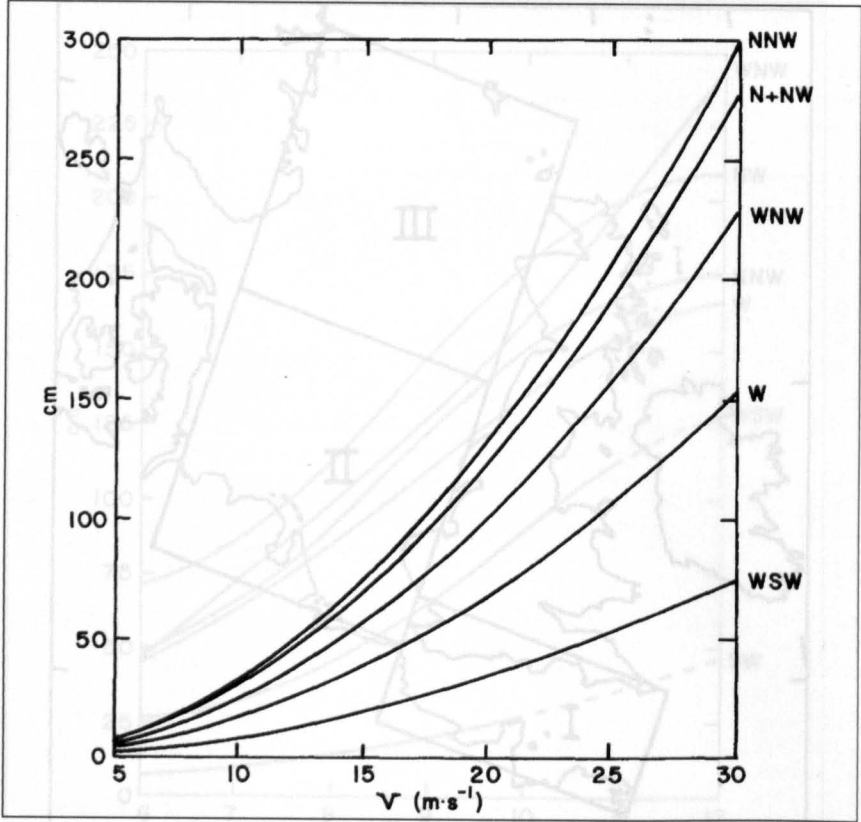


Fig. 5.29: Storm surge versus wind speed for section 1 of Fig. 5.28. (SCHALKWIJK, 1947)

Sea. Along the coast of the Netherlands, the variations in the surge south of Helder are not significant.

SCHALKWIJK (1947) developed an analytical theory applicable to an enclosed sea, a partly open sea, a bay of uniform depth, and a bay of variable depth. He included the influence of the Dover Strait and inhomogenities and time variations in the wind field. He selected 14 surges for the period 1920–40. These cases with factors Ψ , V , and η (from eq. 5.20) are listed in Table 5.4 (in this table, 22 cases appear because some cases are broken down into separate events).

Schalkwijk's 1947 study showed that the average deviation of the wind from the isobars is 8° , which is somewhat smaller than the values given by other authors, which ranged from 13 to 20° . He also found that on the rising part of the curve the time lag between wind and surge is 2.2 h whereas on the falling part of the curve the lag is 2.8 h.

The three separate regions of the North Sea for which this study is made are shown in Fig. 5.28. The results for sections 1, 11, and 111 are summarized in Fig. 5.29, 5.30, and 5.31, respectively. The results for the whole North Sea are shown in Fig. 5.32. Comparison of Fig. 5.27 and 5.32 shows that differences exist between the results of SCHALKWIJK's (1947) study and the Netherlands government committee's earlier study.

Schalkwijk also examined the surges in the East Scheldt Estuary. The results for this case are summarized in Fig. 5.33.

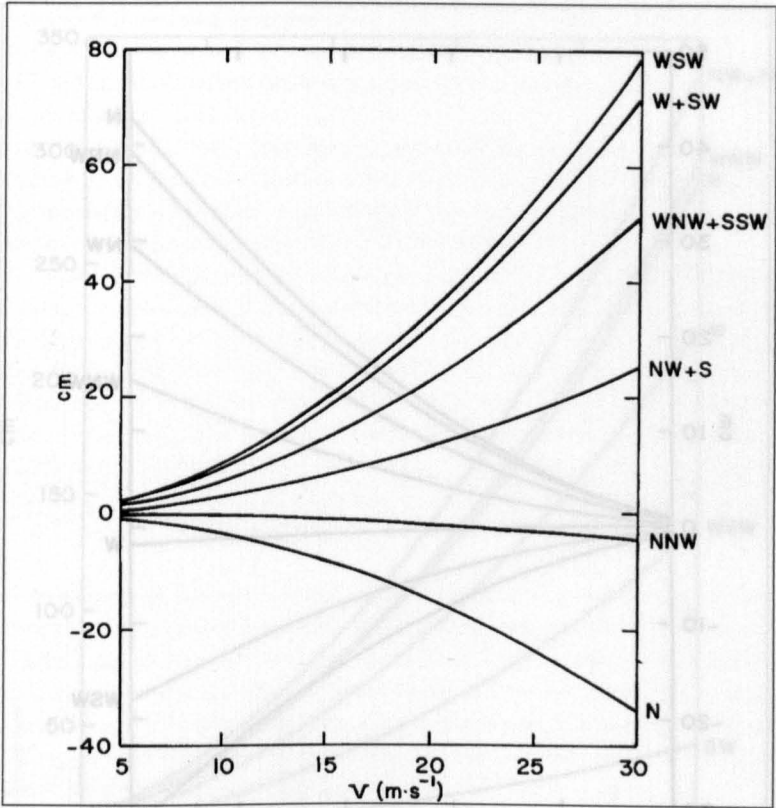


Fig. 5.30: Storm surge versus wind speed for section 11 of Fig. 5.28. (SCHALKWIJK, 1947)

Special Meteorological Influence on Storm Surges in the North Sea (Atmospheric Pressure Gradient / External Surges)

TIMMERMAN (1975) showed that storm surges can be generated in the North Sea not only by westerly winds over the continental shelf but also by atmospheric pressure gradients near the area of transition from deep to shallow water. He mentioned that this effect is usually disregarded in storm surge calculations. For the storm surge of February 16, 1962, the atmospheric pressure gradient effect was very significant. KOOPMAN (1963) studied the surge of October 16–17, 1963. In this case, atmospheric pressure gradients were also a significant factor. Other important storm surge dates are December 11–15, 1972, and January 29, 1974, where atmospheric pressure gradients were important (TIMMERMAN, 1975).

Until now the issue of externally generated surges in the German Bight has not been adequately addressed. External surges originated in deep water in the open sea (SCHMITZ 1965). Their genesis in the North Sea depends upon the speed of movement and the pressure deficit of the extratropical cyclone travelling over the Atlantic Ocean. Note that the amplitude of this external surge is completely independent of the local meteorological conditions over the German Bight. These external surges travel from Aberdeen to Immingham, then through the Straits of Dover to arrive at the Dutch and German coasts.

KOOPMANN (1962) investigated external surges for the period of 1956–1960; SCHMITZ et

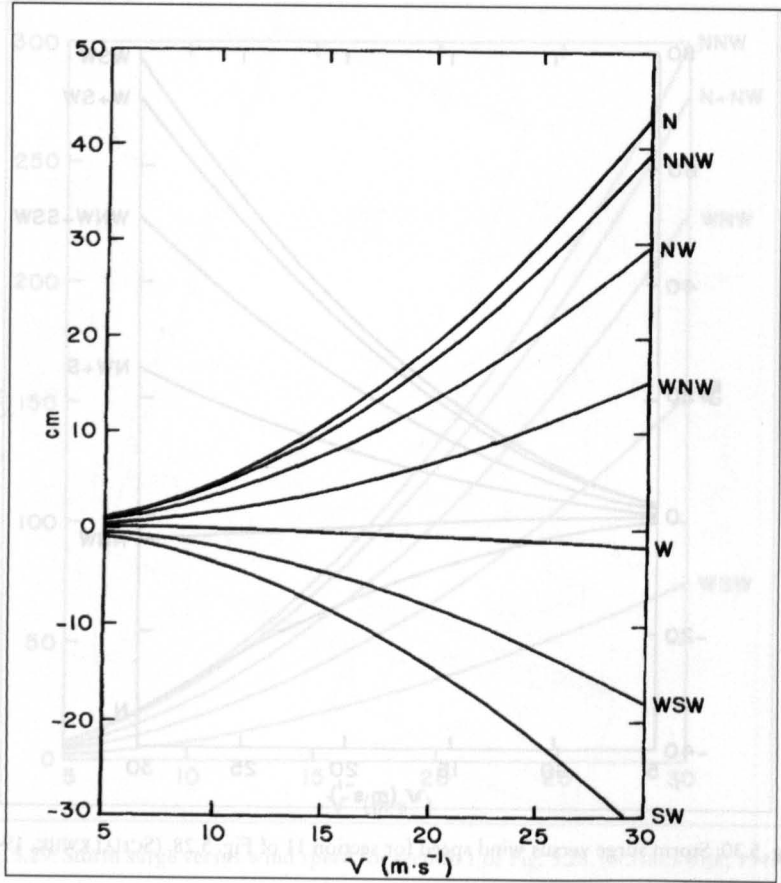


Fig. 5.31: Storm surge versus wind speed for section III of Fig. 5.28. (SCHALKWIJK, 1947)

al. (1988) specified the meteorological situation. GÖNNERT (1999) investigated this phenomenon in the North Sea and its influence on the normal tide level and storm surge level for the period of 1971–1995. The research showed that at Cuxhaven a peak level of 10 cm to 108 cm (Fig. 5.35) can occur. The peak external surge needs not coincide with the high tide at the coast. Normally it is disturbed over the entire tide, mostly 3 h before high tide and 3 h after high tide. External surges occur from October to March, sometimes also in August, September and April (Fig. 5.34). This is the same period as the storm surge period in the German Bight. Furthermore, for every 4th to 5th storm surge case an external surge influences the water level, till now mostly before and after the high water level. Because of the fact that external surges at Cuxhaven have a long duration they influence the storm surge. Till now, the peak external surge never coincided with the local surge peak.

Storm surges in the Irish Sea

Storm surge studies for the Irish Sea are fewer than those for the North Sea, although large surges occur in the Irish Sea. Surges in the Irish Sea originate in the Atlantic (AMIN, 1985). LENNON (1963) examined the meteorological situations associated with large surges

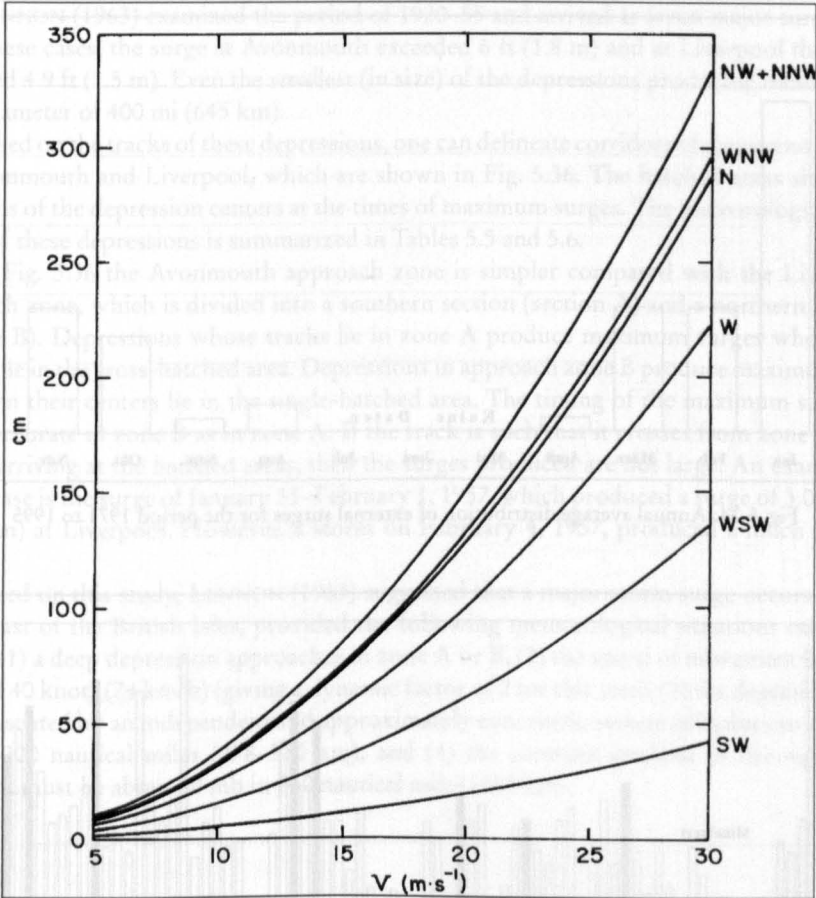


Fig. 5.32: Storm surge versus wind speed for the entire North Sea based on Schalkwijk's results (SCHALKWIJK, 1947)

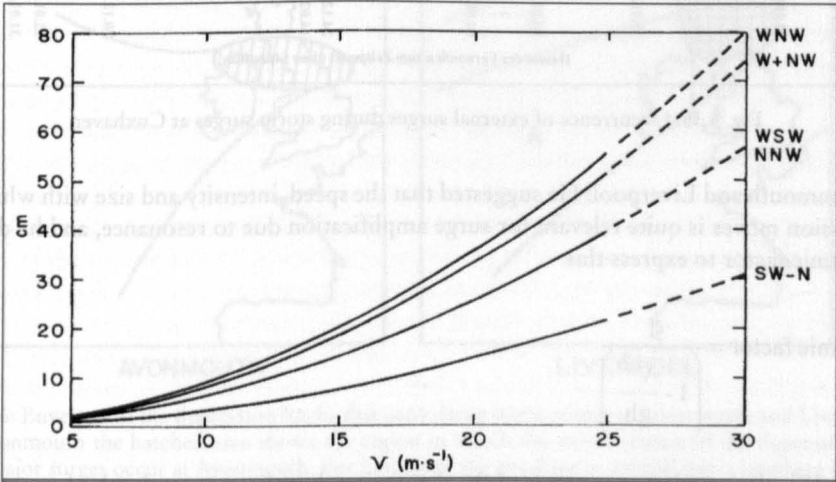


Fig. 5.33: Storm surge versus wind speed for the East Scheldt Estuary. (SCHALKWIJK, 1947)

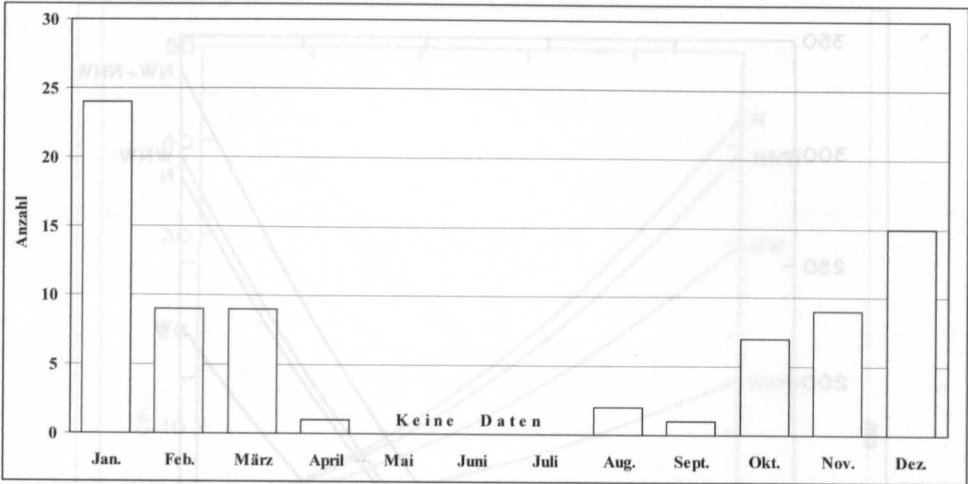


Fig. 5.34: Annual average distribution of external surges for the period 1971 to 1995

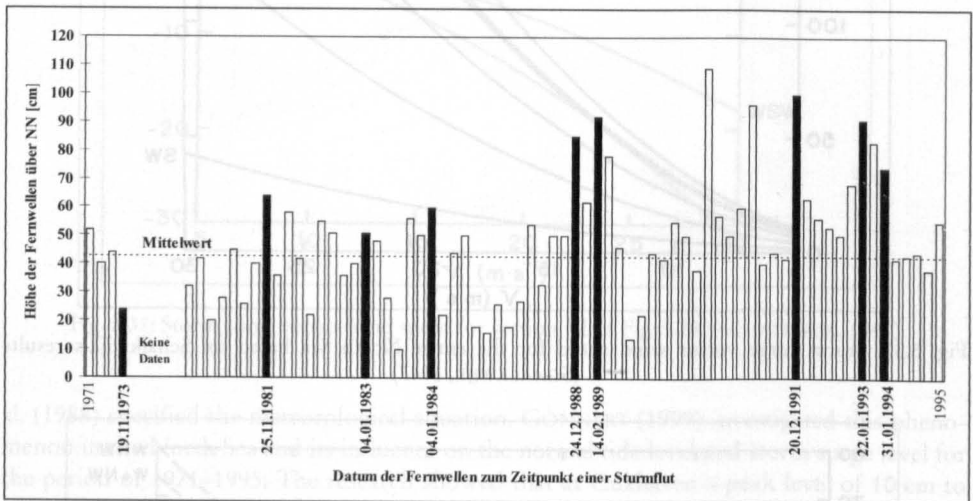


Fig. 5.35: Occurrence of external surges during storm surges at Cuxhaven

at Avonmouth and Liverpool. He suggested that the speed, intensity and size with which the depression moves is quite relevant for surge amplification due to resonance, and he defined a dynamic factor to express this:

$$\text{Dynamic factor} = \frac{1}{\left(1 - \frac{V^2}{gh}\right)} \quad (5.22)$$

where, V is the speed of movement of the depression, h is the average depth of water, and g is the acceleration of gravity.

LENNON (1963) examined the period of 1920–55 and arrived at seven major surges; i.e. in all these cases, the surge at Avonmouth exceeded 6 ft (1.8 m) and at Liverpool the surge exceeded 4.9 ft (1.5 m). Even the smallest (in size) of the depressions producing these surges has a diameter of 400 mi (645 km).

Based on the tracks of these depressions, one can delineate corridors of dangerous zones for Avonmouth and Liverpool, which are shown in Fig. 5.36. The hatched areas show the positions of the depression centers at the times of maximum surges. The meteorological character of these depressions is summarized in Tables 5.5 and 5.6.

In Fig. 5.36 the Avonmouth approach zone is simpler compared with the Liverpool approach zone, which is divided into a southern section (section A) and a northern section (section B). Depressions whose tracks lie in zone A produce maximum surges when their centers lie in the cross-hatched area. Depressions in approach zone B produce maximum surges when their centers lie in the single-hatched area. The timing of the maximum surges is not as accurate in zone B as in zone A. If the track is such that it crosses from zone A to B before arriving at the hatched areas, then the surges produced are not large. An example of such a case is the surge of January 31–February 1, 1957, which produced a surge of 3.0 ft (less than 1 m) at Liverpool. However, a storm on February 4, 1957, produced a much greater surge.

Based on this study, LENNON (1963) suggested that a major storm surge occurs on the west coast of the British Isles, provided the following meteorological situations occur together: (1) a deep depression approaches in zone A or B, (2) the speed of movement is of the order of 40 knots (74 km/h) (giving a dynamic factor of 2 for this area), (3) the depression can be represented by an independent and approximately concentric system of isobars to a radius of 150–200 nautical miles (278–370 km), and (4) the pressure gradient in the right rear quadrant must be about 30 mb in 250 nautical miles (463 km).

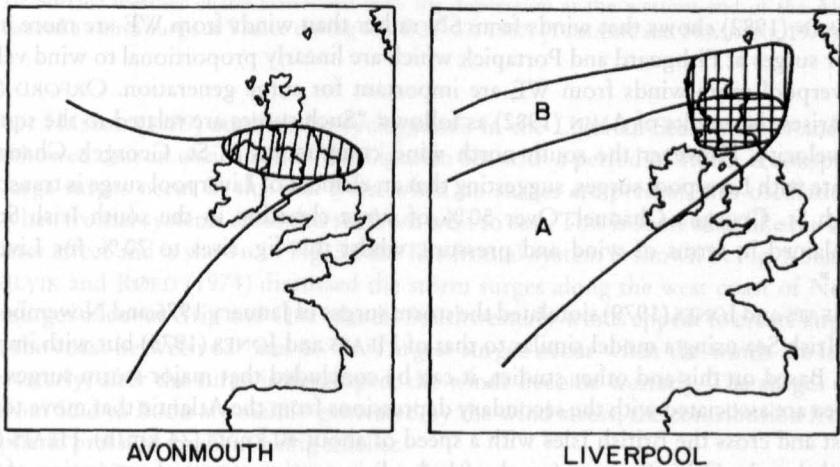


Fig. 5.36: Envelope of the depression tracks that cause large storm surges at Avonmouth and Liverpool. For Avonmouth the hatched area shows the region in which the storm centers of the depressions lie when major surges occur at Avonmouth. For Liverpool the envelope is divided into a southern section (A) and a northern section (B). The cross-hatched and single-hatched areas are, respectively, associated with zones A and B. (LENNON, 1963)

Table 5.5: Some details of the depressions that caused large storm surges at Avonmouth. (LENNON, 1963)

Date	Speed of movement (km/h)	Location of depression center at time of maximum surge	Radius of depression (km)	Pressure gradient (mb) over 463 km
Jan. 12, 1930	87	Irish Sea	241	24
Sept. 17, 1935	74	Irish Sea	333	32
Jan. 9, 1936	78	Ireland	296	34
Nov. 23, 1938	65	South Scotland	389	26
Mar. 16, 1947	72	North England	333	26
Apr. 23, 1947	74	North Ireland	370	28
Nov. 30, 1954	59	East England	333	38

Table 5.6: Some details of the depressions that caused large storm surges at Liverpool, U.K. (LENNON, 1963)

Date	Speed of movement (km/h)	Location of depression center at time of maximum surge	Radius of depression (km)	Pressure gradient (mb) over 463 km
Jan. 9, 1936	78	Ireland	296	34
Oct. 27, 1936	69	North of Scotland	278	32
Nov. 23, 1938	65	North England	389	26
Jan. 25, 1944	65	West Scotland	482	23
Dec. 2, 1946	70	Off West Scotland	333	23
Apr. 23, 1947	74	North Ireland	370	28
Nov. 30, 1954	59	East Ireland	296	34

AMIN (1982) shows that winds from SN rather than winds from WE are more important for surges at Fishguard and Portapick which are linearly proportional to wind velocity. At Liverpool more winds from WE are important for surge generation. ORFORD (1989) summarises the results of AMIN (1982) as follows: "Such surges are related to the square of wind velocity. However the south north wind components in St. George's Channel do correlate with Liverpool surges, suggesting that an element of Liverpool surge is transported through St. George's Channel. Over 50 % of surge elevation in the south Irish Sea can be explained in terms of wind and pressure, whilst this fig. rises to 70 % for Liverpool surges."

HEAPS and JONES (1979) simulated the storm surges of January 1976 and November 1977 in the Irish Sea using a model similar to that of HEAPS and JONES (1975) but with improvements. Based on this and other studies, it can be concluded that major storm surges in the Irish Sea are associated with the secondary depressions from the Atlantic that move towards the east and cross the British Isles with a speed of about 40 knots (74 km/h). HEAPS (1965) showed that the Celtic Sea area (south of Ireland) is a major region of generation of storm surges.

Meteorological conditions associated with storm surges in other parts of Europe

Storm surges occur on the northern part of the Atlantic coast of Portugal. MORAIS and ABECASIS (1975) discussed the storm surge that occurred on Leixoes during January 16–17, 1973.

In the city of Venice at the Adriatic Sea and the Ligurian Sea storm surges occur. The Ligurian Sea is a region of cyclogenesis. Depressions from the Atlantic reaching this sea are intensified here and then travel eastwards. Southeast winds appear to generate the greatest surges in the Venice area. The surface weather charts for two time slots during the surge of April 21–22, 1967, are shown in Fig. 5.37. Note the depression at the western end of the Alps.

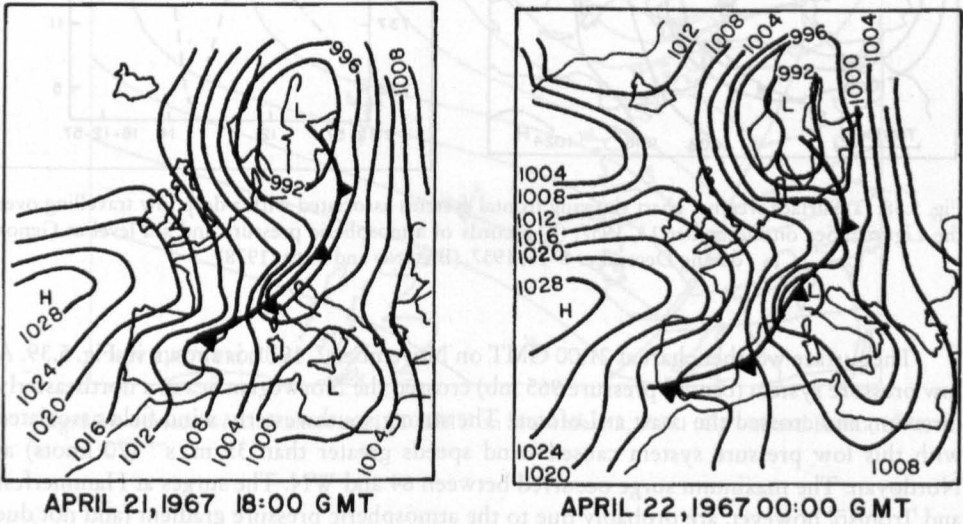


Fig. 5.37: Surface weather charts associated with the depression at the western end of the Alps that caused a storm surge at Venice during April 21–22, 1967. (TOMASIN and FRASETTO, 1979)

VAN HAMME (1979) studied the cyclogenesis in the Ligurian Sea. BASANO and PAPA (1978) showed that an oscillation of the Ligurian Sea with a period of 3.66 h is conspicuous when large surges occur in this sea. Even when no surges are present, this oscillation can occur when frontal systems cross this sea from west to east. This is somewhat like the inverse barometer effect and is shown in Fig. 5.38b. The frontal system is shown in Fig. 5.38a.

GJEVIK and RØED (1974) discussed the storm surges along the west coast of Norway. Severe surges occur at Grip and Ona islands. Southwesterly winds appear to create large surges on the coast between 62° and 66° N. Largest surges occur when the winds are initially southwesterly; after the surge is developed, the winds become westerly. The surges on the coast from Stad to Bodø are mainly generated by the wind stress, the contribution from the atmospheric pressure gradient being smaller.

GJEVIK and RØED (1974) studied especially three storm surges: (1) November 2, 1971, (2) December 30, 1972, and (3) December 31, 1972. The second and third are typical surges that frequently occur along the coast between 62 and 68° N. The first one is exceptional because the peak surge coincided with the peak tide along the coast between Sula and Sandnessjøen.

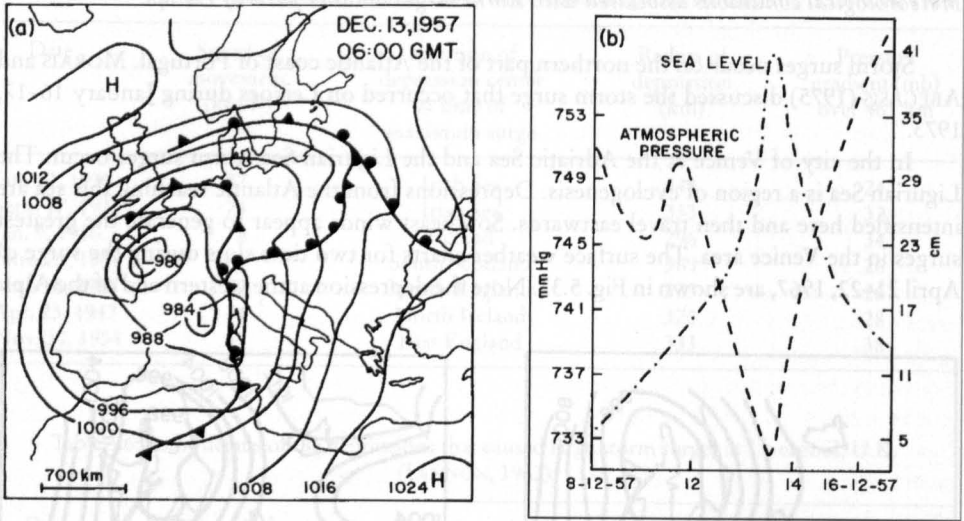


Fig. 5.38: (a) Surface weather chart showing frontal systems associated with a deep low travelling over the Ligurian Sea on December 13, 1957; (b) records of atmospheric pressure and sea level at Genoa during December 8–16, 1957. (BASANO and PAPA, 1978)

The surface weather chart at 21:00 GMT on November 2, 1971, is shown in Fig. 5.39. A low pressure system (central pressure 965 mb) crossed the Norwegian Sea in a northeasterly direction and crossed the coast at Lofoten. The strong southwesterly wind field associated with this low pressure system caused wind speeds greater than 35 m s^{-1} (70 knots) at Nordøyen. The maximum surge occurred between 64 and WN. The surges at Hammerfest and Tromsø, however, are probably due to the atmospheric pressure gradient (and not due to wind stress) because these two stations are located to the north of the wind field associated with this system.

GJEVIK and RØED (1974) presented detailed surface weather charts for the three surge cases considered here. They showed that the meteorological situation was somewhat similar for cases 1 and 3. The peak of the wind field moved with an average speed of about 25 m s^{-1} . These authors used the following values of drag coefficients for different wind speeds:

2.5	X	10^{-3}	for 25 m s^{-1}
$C_D = 3.0$	X	10^{-3}	for 30 m s^{-1}
3.5	X	10^{-3}	for 35 m s^{-1}

In the analytical model for the surges on the Norwegian coast, these authors considered surge development due to a wind field moving along the coast. The following forms are assumed for the wind stress components and the pressure field:

$$\begin{aligned}\tau_{S_x} &= \rho T_{0x} F(x, t) e^{-\alpha y} \\ \tau_{S_y} &= \rho T_{0y} G(x, t) e^{-\beta y} \\ P_0 &= \text{const} \tan t\end{aligned}\tag{5.23}$$

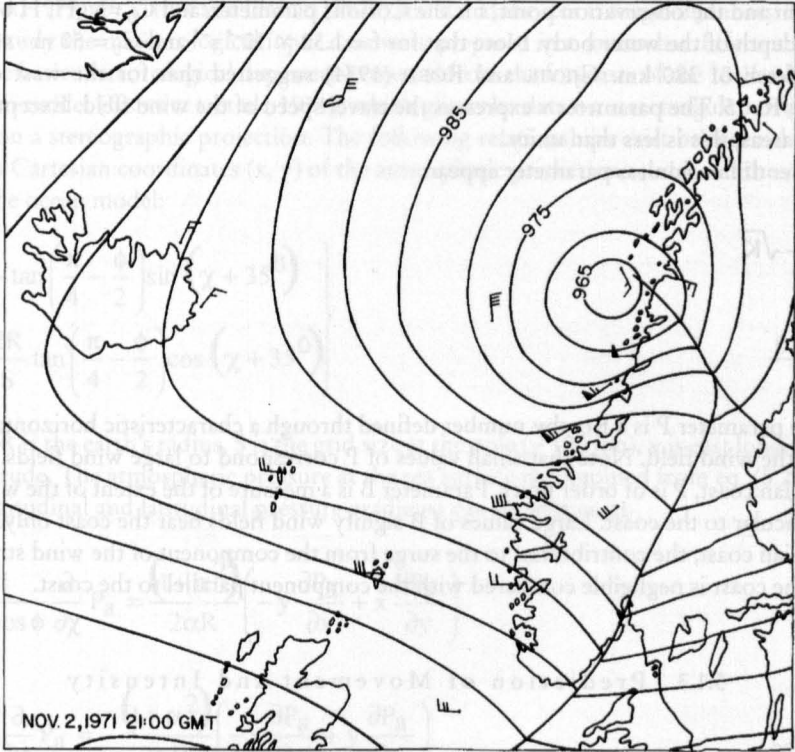


Fig. 5.39: Surface weather chart at 21:00 GMT on November 2, 1971. (GJEVIK and RØED, 1974)

for $t \geq 0$, where T_{0x} , T_{0y} , \hat{a} , and \hat{a} are constants and F and G are functions of x and t only. Here, \tilde{n} is the water density and the horizontal coordinate y is directed perpendicular to the coast. The following forms are prescribed for F and G :

$$\left. \begin{aligned} F &= e^{-K(x-u_0t)^2} \\ G &= e^{-Kx^2} h(t) \end{aligned} \right\} \tag{5.24}$$

where, $h(t)$ is a function of time and $0 \leq h(t) \leq 1$.

In the non-dimensionalisation of the equations of motion and continuity, the following two parameters appear:

$$R \equiv \frac{f}{C_0} x \tag{5.25}$$

where, R is a dimensionless wind fetch (i.e. distance between the initial position of the wind

$$v \equiv \frac{u_0}{C_0} \tag{5.26}$$

maximum and the observation point, f is the Coriolis parameter, and $C_0 = v_g H$, H being the average depth of the water body. Note that for $f = 1.32 \times 10^{-4} \text{ s}^{-1}$ and $C_0 = 50 \text{ m} \cdot \text{s}^{-1}$, $R = 1$ gives a fetch of 380 km. GJEVIK and RØED (1974) suggested that for the west coast of Norway, $R < 5$. The parameter v expresses the travel speed of the wind field. Except in very shallow areas, this is less than unity.

Two other dimensionless parameter appear:

$$P \equiv \frac{C_0}{f} \sqrt{K} \quad (5.27)$$

$$B \equiv \frac{\alpha C_0}{f} \quad (5.28)$$

The parameter P is a Rossby number defined through a characteristic horizontal length scale of the wind field. Note that small values of P correspond to large wind fields. For the Norwegian coast, P is of order unity. Parameter B is a measure of the extent of the wind field perpendicular to the coast. Large values of B signify wind fields near the coast only. For the Norwegian coast, the contribution to the surge from the component of the wind stress normal to the coast is negligible compared with the component parallel to the coast.

5.1.3 Prediction of Movement and Intensity

North Sea

DAVIES and FLATHER (1977) developed numerical models to study the storm surge of April 1–6, 1973. A coarse grid covered the whole northwestern European continental shelf and a fine grid covered only the North Sea. They determined the wind field from the geopotential height field extracted from 12-h weather charts for a period of 36 h. From the forecast data at 7 and 19 h, the geopotential height H of the 1000-mb level was used. The sea surface pressure p is calculated from

$$p = 1000 + \rho_a g H \quad (5.29)$$

where ρ_a is the air density and g is gravity. From the pressure gradients the geostrophic wind was determined. The surface wind w is determined from the geostrophic wind w using the empirical relationship of HASSE and WAGNER (1971):

$$w = A w + B \quad (5.30)$$

where, $A = 0.56$ and B has a range of values depending on atmospheric stability. The above formula is valid when w and w are in meters per second. FLATHER and DAVIES (1975, 1976) used the above formula with $B = 2.4 \text{ m} \cdot \text{s}^{-1}$. This gave reasonable results for the storm surge of March 26–30, 1972, but gave unsatisfactory results for the surge of April 1–6, 1973.

There was a series of storm surges in the North Sea during the period November 4–December 18, 1973. DAVIES and FLATHER (1978) simulated these numerically, again using a coarse model for the whole shelf and a fine model for the North Sea alone. The meteorological input data were obtained in a manner similar to their earlier study (DAVIES and

FLATHER, 1977). FLATHER and DAVIES (1978) simulated the storm surge of January 2–4, 1976. In this study the meteorological input data were prepared in a somewhat different manner.

The basic meteorological data were extracted from the forecasts of the 10-level Bushby-Timpson model (BENWELL et al., 1971), which gives the data on a rectangular array of grid points on a stereographic projection. The following relationships exist between the dimensionless Cartesian coordinates (x, y) of the atmospheric prediction model and the coordinates of the ocean model:

$$\left. \begin{aligned} x &= \frac{2R}{S} \tan\left(\frac{\pi}{4} - \frac{\phi}{2}\right) \sin(\chi + 35^\circ) \\ y &= -\frac{2R}{S} \tan\left(\frac{\pi}{4} - \frac{\phi}{2}\right) \cos(\chi + 35^\circ) \end{aligned} \right\} \tag{5.31}$$

where, R is the earth’s radius, S is the grid size at the pole (~ 100 km), χ is east longitude, and φ is latitude. The atmospheric pressure at the sea surface is computed from eq. (5.29). Then, the longitudinal and latitudinal pressure gradients can be written as

$$P = \frac{1}{R \cos \phi} \frac{\partial}{\partial \chi} P_a = \frac{(1 + \alpha^2)}{2\alpha R} \left(-y \frac{\partial P_a}{\partial x} + x \frac{\partial P_a}{\partial y} \right) \tag{5.32}$$

$$Q = \frac{1}{R} \frac{\partial}{\partial \phi} P_a = -\frac{(1 + \alpha^2)}{2\alpha R} \left(-x \frac{\partial P_a}{\partial x} + y \frac{\partial P_a}{\partial y} \right)$$

where,

$$\alpha^2 \equiv \frac{S^2(x^2 + y^2)}{4R^2} \tag{5.33}$$

The eastward and northward components of the geostrophic wind are

$$\hat{w}_x = -\left[\frac{(1 + \alpha^2)}{(1 - \alpha^2)} \right] \frac{Q}{2\omega p_a} \tag{5.34}$$

$$\hat{w}_\phi = -\left[\frac{(1 + \alpha^2)}{(1 - \alpha^2)} \right] \frac{P}{2\omega p_a}$$

where, ω is the angular velocity of the earth’s rotation. A linear relationship was assumed between the geostrophic wind \hat{w} and the surface wind w:

$$\begin{aligned} w_\chi &= (\hat{w}_\chi \cos \delta - \hat{w}_\phi \sin \delta)(A\hat{w} + B)/\hat{w} \\ w_\phi &= (\hat{w}_\chi \sin \delta + \hat{w}_\phi \cos \delta)(A\hat{w} + B)\hat{w} \end{aligned} \tag{5.35}$$

where, δ is the angular deviation between the geostrophic and surface winds and a and b are empirical constants, as in the earlier model of DAVIES and FLATHER (1977).

FISCHER (1979) developed a combined atmosphere-ocean model to simulate the storm surge of January 3, 1976, in the North Sea. The atmospheric model has a grid size of 1.4° latitude and 2.8° longitude and has eight levels in the vertical. The ocean model has a 22-km grid. The surface wind calculated from the atmospheric model was used to determine the wind stress τ_0 in the following manner:

$$|\tau_0| = \rho_a C_D \gamma^2 |v_0| v_0 \quad (5.36)$$

where, v_0 is the wind at the anemometer level, C_D is the drag coefficient, $\gamma = 1$ (when observed winds were used) and $\gamma = 1.55$ (when predicted winds were used), and ρ_a is the density of air. Wind at the anemometer level is

$$|v_0| = 0.54 - 0.012\Delta\theta |v_{g0}| + 1.68 - 0.015\Delta\theta \quad (5.37)$$

where, the cross-isobar angle is 8° for an unstable atmosphere and 213° for the very stable case and θ is the potential temperature. The drag coefficient is

$$C_D = \left(1.18 + 0.016 |v_{g0}| \right) \times 10^{-3} \quad (5.38)$$

where, v_{g0} is in meters per second. Here, subscript 0 denotes the water surface.

The storm surge of January 11–12, 1978 (TOWNSEND, 1979), was the worst on record after the January 1953 surge in the North Sea. This surge was simulated successfully by using empirical methods (TOWNSEND 1979).

Storm surges in the Irish Sea

The next passage follows closely ORFORD (1989). HEAPS and JONES (1979, 1981) and FLATHER (1981) use running numerical models of Irish Sea conditions in which the dynamics of flow and velocity were addressed using first principle hydrodynamic equations to predict surge elevations. FLATHER (1987) give an example of this type of approach in which observed surge were modelled and predictive results indicate close approximation to observed data.

“He used a numerical model based on non-linear, depth-averaged hydrodynamical equations (FLATHER and PROCTER, 1983) to determine surface elevation, plus north and east components of current velocity, and predicted the water elevation due to combined tide and surge for a number of known parameterized storms over NW Europe (53 days of storm activity). Sea level elevation was obtained for grid points of size 0.5° lat.; 0.33° long. at hourly intervals through the storms. A re-run of the model without meteorological forcing allowed the prediction of tidal elevation per se. The differences between the two runs indicate the surge component. Surge values were calibrated against coastal data from PUGH and VASSIE (1979) for 50 year surge elevation status. The grided data was then interpolated using the nearest reference coastal sites that Pugh and Vassie cite. The resulting prediction of 50 year surge elevation was contoured as increments to the maximum tidal elevation in order to indicate the extreme 50 year height of water level above O.D.

Surge heights are 1–2 m on the west U.K. coast and 1.0–1.5 m on the Irish coast. Highest surge are predicted around the northeast margins of the basin. The joint probability of high

spring and 50 year surge achieves a sea-level elevation commensurate with the 100 year maximum seal-level elevation.”

HEAPS and JONES (1975) used a two-and-a-half-dimensional model (they called it a three-dimensional model) of the Irish Sea to simulate storm surges for the period January 10–18, 1965. The first storm surge of this period was associated with a storm of January 13–14. A deep depression moved from the Atlantic with a speed of about 35 knots (65 km. h') on a track (towards the east) lying to the north of Ireland. Fronts from this depression swept across the Irish Sea and winds veered from south to west. The second storm (January 16–18) was associated with a large slow-moving depression to the north of Scotland.

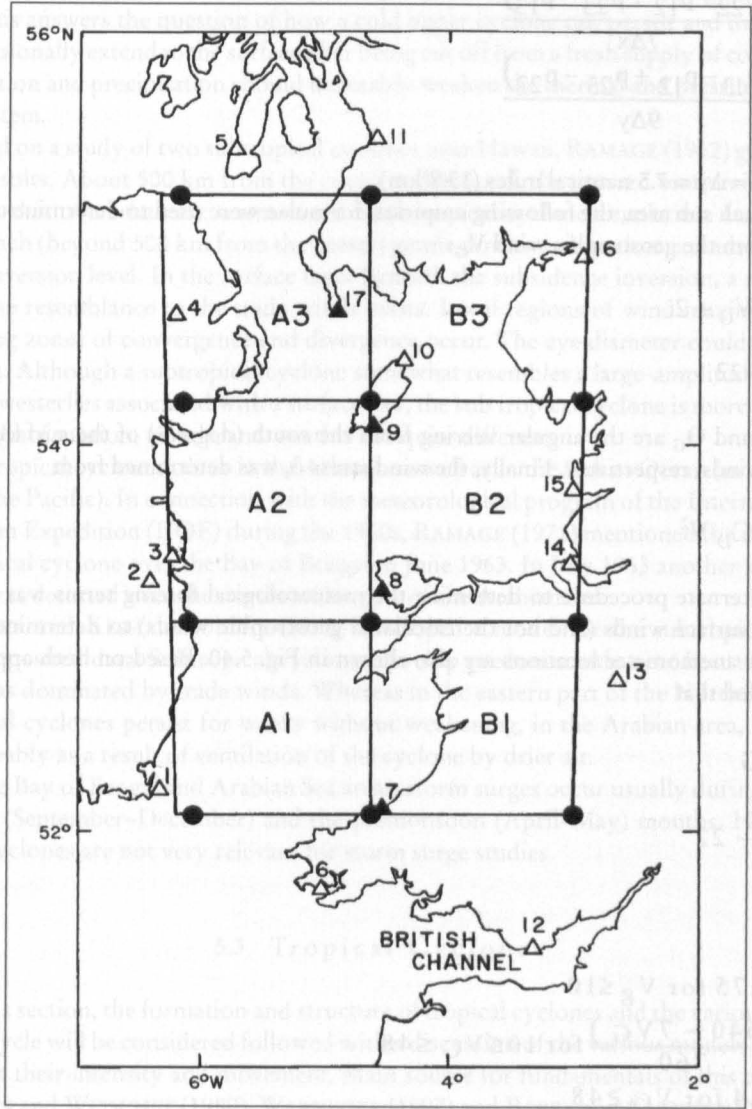


Fig. 5.40: Irish Sea model with six sub areas for determining atmospheric pressure gradients and wind stress. (HEAPS and JONES, 1975)

The following meteorological forcing terms were included in the numerical model: atmospheric pressure gradients over the water surface determined at 3-h intervals from pressure records and wind stress determined at 3-h intervals from geostrophic winds, or alternatively, at 6-h intervals from measured surface winds.

The six rectangular sub areas of the Irish Sea and surroundings (regions AI, A2, A3, B 1, B2, and B3) are shown in Fig. 5.40. From observations of atmospheric pressure, $p_{i,j}$ values were extrapolated for each grid point at each time step. The 16 meteorological stations whose pressure data are used are also shown. Heaps and Jones (1975) wrote the following for sub area A2

$$\frac{\partial p}{\partial x} = \frac{1}{2} \frac{(p_{22} - p_{12} + p_{23} - p_{13})}{7\Delta x} \quad (5.39)$$

$$\frac{\partial p}{\partial y} = \frac{1}{2} \frac{(p_{13} - p_{12} + p_{23} - p_{22})}{9\Delta y} \quad (5.40)$$

where, $\Delta x = \Delta y = 7.5$ nautical miles (13.8 km).

For each sub area, the following empirical formulae were used to determine the surface wind V from the geostrophic wind V_G :

$$V = 0.56 V_G + 2. \quad (5.41)$$

$$\Theta = \Theta_G - 22 \quad (5.42)$$

where, Θ and Θ_G are the angular veering from the south (degrees) of the surface and geostrophic winds, respectively. Finally, the wind stress τ_s was determined from

$$\tau_s = 12.5 C_D V^2 \quad (5.43)$$

An alternate procedure to determine the meteorological forcing terms was to use the measured surface winds (and not the calculated geostrophic winds) to determine the wind stress. The anemometer locations are also shown in Fig. 5.40. Based on both approaches it was deduced that

$$V = \beta V_G \quad (5.44)$$

$$\theta = \theta_G - 22$$

with

$$\beta = \begin{cases} 0.75 & \text{for } V_G \leq 10 \\ \frac{(640 - 7V_G)}{760} & \text{for } 10 \leq V_G \leq 48 \\ 0.4 & \text{for } V_G \geq 48 \end{cases} \quad (5.45)$$

where, V_G is in meters per second.

5.2 Subtropical Cyclones

SIMPSON (1952) referred to the upper level cutoff lows, which frequently develop over the eastern part of the North Pacific Ocean during winter, north of Hawaii (locally referred to as Kona storms and which occasionally cause heavy flooding in Hawaii), as subtropical cyclones. BARRY and CHORLEY (1992) use the same definition for this phenomenon, which is usually relatively weak near the surface, but well developed in the middle troposphere. These appear to be preceded by the injection of cold air aloft through the mechanism of large-amplitude troughs in the polar westerlies (PALMEN, 1949). The eye diameter could be of some 150 km with little cloud and precepation about 300 km wide (BARRY and CHORLEY, 1992). RAMAGE (1962) suggested that subtropical cyclones indeed are direct energy-creating systems. This answers the question of how a cold upper cyclone can persist and intensify and even occasionally extend to the surface after being cut off from a fresh supply of cold air when condensation and precipitation should inevitably weaken the thermal and pressure gradients of the system.

Based on a study of two subtropical cyclones near Hawaii, RAMAGE (1962) gave the following results. About 500 km from the center and beyond, the upward motion is weak and resembles that of a relatively warm-cored weak tropical cyclone circulation. In the downward branch (beyond 500 km from the center) gentle downward motion extends to the subsidence inversion level. In the surface layer beneath the subsidence inversion, a regime that bears some resemblance to the trade winds exists. Local regions of wind maxima and corresponding zones of convergence and divergence occur. The eye diameter could be as large as 200 km. Although a subtropical cyclone somewhat resembles a large-amplitude trough in the polar westerlies associated with a surface low, the subtropical cyclone is more symmetric and its field of motion, clouds, and weather are quite different.

Subtropical cyclones occur in the Atlantic as well as in the Indian Ocean (in addition to those in the Pacific). In connection with the meteorological program of the International Indian Ocean Expedition (IIOE) during the 1960s, RAMAGE (1971) mentioned the existence of a subtropical cyclone over the Bay of Bengal in June 1963. In July 1963 another subtropical cyclone was detected over the northeastern part of the Arabian Sea.

MILLER and KESHAVAMURTHY (1968) developed a model for the subtropical cyclone using composited data. Subtropical cyclones develop predominantly near heat troughs and in the areas dominated by trade winds. Whereas in the eastern part of the North Pacific, the subtropical cyclones persist for weeks without weakening, in the Arabian area, they dissipate, probably as a result of ventilation of the cyclone by drier air.

In the Bay of Bengal and Arabian Sea areas, storm surges occur usually during the post-monsoon (September–December) and the premonsoon (April–May) months. Hence, subtropical cyclones are not very relevant for storm surge studies.

5.3 Tropical Cyclones

In this section, the formation and structure of tropical cyclones and the various stages in their life cycle will be considered followed with a discussion of the various models being used to forecast their intensity and movement. Main source for fundamentals of this chapter are BLÜTHGEN and WEISCHET (1980), WARNECKE (1997) and BARRY and CHORLEY (1992).

5.3.1 Development Theory

The main source of material for this subsection is GRAY (1978a, 1978b, 1978c, 1978d, 1989) and BARRY and CHORLEY (1992).

Annually over the globe there are about 80 tropical cyclones with maximum sustained wind speeds of $20\text{--}25 \text{ m} \cdot \text{s}^{-1}$. About one half to two thirds of these cyclones reach hurricane strength (i.e. maximum sustained wind speeds greater than $33 \text{ m} \cdot \text{s}^{-1}$).

At first the necessary conditions for the development of tropical storms and hurricanes be described with six climatological genesis parameters:

- (1) low level relative vorticity, ζ_r
- (2) Coriolis parameter, f
- (3) the inverse of the vertical shear S_z of the horizontal wind between the lower and upper troposphere, $1/S_z$
- (4) ocean thermal energy, sea temperature excess above 26°C to a depth of 60 m, E
- (5) vertical gradient of Θ_e , between the surface and 500 mb, $\partial\Theta_e/\partial p$, where Θ_e is the equivalent potential temperature of air and
- (6) midtroposphere relative humidity, RH.

The rationale for selecting these parameters is the following. The first parameter is selected because, all things being equal, seasonal cyclone frequency should be related to the magnitude of the seasonal lower tropospheric relative vorticity. The Coriolis parameter is relevant because cyclones do not appear to form within $4\text{--}5^\circ$ of the equator. Cyclogenesis does not occur near the equator because wind accelerations are small due to weak pressure gradients whereas frictional dissipation is as large as at any other latitude. The third parameter is relevant because tropical cyclones form when there is minimum vertical shear of the horizontal wind between the lower and upper troposphere.

The fourth parameter becomes relevant when recognizing that tropical cyclones can have considerable influence on the temperature of the water body over which they travel. The feedback effect of the altered ocean temperature influences the cyclone. It appears that the inner region of the average-sized hurricane ($0\text{--}240 \text{ km}$) can consume up to $4000 \text{ cal} \cdot \text{cm}^{-2} \cdot \text{d}^{-1}$ from the ocean's sensible and latent heat energy (for details see LEIPPER and JENSEN, 1971; LEIPPER and VOLGENAU, 1972; HEFFERMAN, 1972; PERLROTH, 1967, 1969). On the other hand, MALKUS and RIEHL (1960) put this value at $3100 \text{ cal} \cdot \text{cm}^{-2} \cdot \text{d}^{-1}$. According to FRANK (1977) for Pacific typhoons for the inner 80 km , the consumption rate is around $1470 \text{ cal} \cdot \text{cm}^{-2} \cdot \text{d}^{-1}$. If a typhoon crosses the track of another typhoon, the second one may weaken sometimes because of the lowered sea surface temperature due to the upwelling caused by the first typhoon (BRAND, 1971).

The hurricane or typhoon can influence the ocean temperatures down to a depth of 60 m. LEIPPER and JENSEN (1971) and LEIPPER and VOLGENAU (1972) defined an ocean thermal energy potential (for cyclogenesis) E (calories per square centimeter) as the ocean thermal energy above 26°C down to a depth of 60 m, i.e.

$$E = \int \rho_w C_w (T - 26) dz \quad (5.46)$$

where, the integral is from the surface down to a depth of 60 m (or to where $T = 26^\circ \text{C}$). Here, ρ_w is the density of seawater, T is the ocean temperature (degrees Celsius) and C_w is the specific heat of water.

The importance of the fifth parameter is obvious when it is considered that cyclones do not form unless the lower and upper tropospheric flow patterns are well coupled. The pri-

mary mechanism for this coupling is the cumulonimbus convection. Hence, cyclogenesis should depend on the seasonally averaged moist buoyancy potential (i.e. the seasonal magnitude of the difference in the equivalent potential temperature Θ_e between the boundary layer and the middle troposphere). The importance of the sixth parameter can be seen from the observations that tropical cyclones form in areas where seasonal middle level humidity values are high. In other words, when the humidity is high, deep cumulus convection occurs leading to better coupling in the vertical.

Based on these considerations, GRAY (1978a, 1978b, 1978c, 1978d) defined a "seasonal genesis parameter" (SGP) as follows:

$$\text{SGP} = \text{vorticity parameter} \times \text{Coriolis parameter} \times \text{vertical shear parameter} \times \text{ocean energy parameter} \times \text{moist stability parameter} \times \text{humidity parameter} \quad (5.47)$$

Here, vorticity parameter $= \zeta_r + 5$ where ζ_r is in units of $10^{-6} \cdot \text{s}^{-1}$, Coriolis parameter $= f$, vertical shear parameter $= 1/(S_z + 3)$ where $S_z = |\partial V / \partial p|$ is in units of meters per second per 750 mb and V is the wind vector, ocean energy parameter $= E$ is defined by eq. 6.33 and is in units of $10^{-5} \text{ cal} \cdot \text{cm}^{-2}$, moist stability parameter $= \partial \Theta_e / \partial p \pm 5$ where $\partial \Theta_e / \partial p$ is in $\text{K} \cdot 500 \text{ mb}^{-1}$, and humidity parameter $= (RH - 40)/30$ where RH is the mean relative humidity between 500 and 700 mb but is zero for $RH \leq 40$ and for $RH \geq 70$. Note that in the above expressions, arbitrary units are added to enable daily values to be used instead of seasonal values.

Another interpretation of SGP is as follows:

$$\text{SGP} = \text{dynamic potential} \times \text{thermal potential} \quad (5.48)$$

where, dynamic potential $= f(\zeta_r + 5) [1/(S_z + 3)]$ and thermal potential $= E(\partial \Theta_e / \partial p + 5)(RH)$. The thermal potential might be thought of as potential for cumulonimbus convection. The dynamic potential is in units of $10^{-11} \text{ s}^{-2} (\text{m} \cdot \text{s}^{-1})/750 \text{ mb}$ and the thermal potential is in units of $10^{-5} \text{ cal} \cdot \text{cm}^{-2} \cdot \text{K} \cdot 500 \text{ mb}^{-1}$. The SGP is in units of $1.5 \times 10^{-8} \text{ cal} \cdot \text{K} \cdot \text{s}^{-1} \cdot \text{cm}^{-3}$. GRAY (1978a, 1978b, 1978c, 1978d) reported that there is very close agreement between the predicted (from SGP) and the observed cyclogenesis frequencies.

Life Cycle of a Tropical Cyclone

RIEHL (1979) summarized the life cycle of tropical cyclones. For storms with the strength of hurricanes, the duration from their birth to the time of landfall or recurvature into middle latitudes is usually about 6 d. The life cycle of a tropical cyclone may be considered to be made up of the following four stages: formative stage, immature stage, mature stage and terminal stage.

Tropical cyclones form in the vicinity of pre-existing weather systems. The deepening can occupy several days or may occur explosively in as short a time as 12 h. In the formative stage, winds are usually less than hurricane force (i.e. 1-min sustained winds are less than $74 \text{ mi} \cdot \text{h}^{-1}$ [$119 \text{ km} \cdot \text{h}^{-1}$]). Strongest winds occur in the quadrant that is to the east of the center and poleward. Surface pressure usually drops to 1000 mb.

Several of these incipient cyclones never deepen enough to become hurricanes. In those cases that do deepen, the lowest pressure rapidly decreases to less than 1000 mb. Winds with speeds of up to $74 \text{ mi} \cdot \text{h}^{-1}$ occur in a tight band around the centre (and not just in one quadrant). The disorganized squalls of the formative stage change into narrow and organized

bands of clouds spiralling inward. In this immature stage only a small area is involved in the intense inner core (30- to 50-km radius) although there may be a large outer core.

In the mature stage, the surface pressure at the center stops decreasing and the maximum wind speeds do not increase further. However, the area of intense circulation expands (up to 300-km radius in certain cases). The symmetry of the immature stage is destroyed and strong winds and bad weather preferentially occur to the right of the center looking downstream in the direction of movement of the cyclone. Some storms with a central low pressure as low as 950 mb could still be only 100–200 km in radius. RIEHL (1979) estimated that for a storm with an average surface pressure of 1000 mb, the total weight of air and water involved in the circulation is about 3×10^{11} to 1×10^{12} t (3.05×10^{14} to 1.016×10^{15} kg). However, another storm with a radius of 1000 km but with the same average surface pressure of 1000 mb will have a weight of about 5×10^{12} to 3×10^{13} t (5.8×10^{15} to 3.05×10^{16} kg). By comparison, in an ordinary midlatitude cyclone, the weight involved is about 5×10^{12} to 1×10^{13} t (5.8×10^{16} kg).

When the tropical cyclone hits land, usually its core size decreases and sometimes the storm dissipates within 1–2 d. Storms can dissipate even over the ocean if they travel over cold ocean currents (e.g. Northeast Pacific Ocean). Many cyclones recurve (both over land and ocean) into the westerlies and travel towards northeast or east (in the Northern Hemisphere).

Some Characteristics of Tropical Cyclones

RIEHL (1979) offered the following classification of tropical cyclones.

- (A) Tropical depression: at most, winds barely acquire gale force in one quadrant.
- (B) Tropical storm: winds acquire gale force but less than hurricane force of 64 knots ($119 \text{ km} \cdot \text{h}^{-1}$ or $74 \text{ mi} \cdot \text{h}^{-1}$).
- (C) Minimal hurricane: winds above 64 knots only in one quadrant.
- (D) Moderate hurricane: winds of 80–90 knots ($148\text{--}167 \text{ km} \cdot \text{h}^{-1}$) around the center, with the maximum wind being around 100 knots ($185 \text{ km} \cdot \text{h}^{-1}$) or more.
- (E) Severe hurricane: maximum winds up to 200 knots ($370 \text{ km} \cdot \text{h}^{-1}$).

Tropical cyclone intensity classification is not uniformly used in the various meteorological services for the various regions of the globe. For example, in the western part of the Pacific Ocean, unless the maximum winds are about 150 knots ($278 \text{ km} \cdot \text{h}^{-1}$), a typhoon will not be considered severe.

RIEHL (1979) mentioned that the word “hurricane” means “big wind” in the Taino.

Next, some characteristics of tropical cyclones will be briefly examined with respect to their surface pressure, winds, and thermal structure. Since ordinarily, surface pressure varies only by about 3 mb (0.3 %) in the tropics whereas pressure varies 5–10 % below average sea level pressure during tropical cyclones, a useful tool for analysis is the sea level isobar field. Gradients of $0.5\text{--}2 \text{ mb km}^{-1}$ can occur.

When the tropical cyclone is over an ocean, the increase of wind with height usually occurs in the first 100 m. Above that it increases slowly to about the 300-m level where the winds probably attain maximum values. For Hurricane Eloise of 1977 the wind speed at the 100-m level was $20 \text{ m} \cdot \text{s}^{-1}$; from 200 to 500 m it was $22 \text{ m} \cdot \text{s}^{-1}$. Then it decreased to $14 \text{ m} \cdot \text{s}^{-1}$ at 1200 m. Usually, the wind at 50 m is about three quarters the geostrophic wind speed (RIEHL, 1979).

In hurricanes, in the inner 80-km core, winds up to $45 \text{ m} \cdot \text{s}^{-1}$ can occur. Winds are grea-

ter on the right side because here the carrying current and the circulation are in the same direction whereas to the left they oppose each other. One of the safest ways to identify tropical cyclones is to look for this asymmetry in the surface wind field. For convenience, one may think of the following four quadrants around the center: right front, right rear, left front, and left rear. Inward spiralling of streamlines is pronounced in the rear quadrants. Here, the radial component of the motion is strongest.

RIEHL (1979) gave the following relationship between pressure and wind fields in a tropical cyclone (this was derived empirically based on 28 yr of Pacific typhoon data):

$$V_m = 3.35(1010 - p_c)^{0.644} \quad (5.49)$$

where, V_m is the maximum wind (metres per second) and p_c is the central pressure (millibars).

The theory of vortex flows shows that in the center of every revolving vortex, there is a singular point. In a tropical cyclone this center is referred to as the eye, near which the circulation is weak. At the edge of the eye, strong precipitation abruptly stops and the sky may clear at least partly. The diameter of the eye in a mature hurricane ranges from 30 to 50 km and probably twice this value in a severe typhoon. The eye need not be circular and sometimes it is diffuse and has a double structure.

RIEHL (1979) mentioned that one of the earliest controversies about tropical cyclones concerned their vertical extent. Estimates varied from 3 to 10 km or greater. According to HAURWITZ (1935) the tropical cyclone extends through the troposphere, and high level observations substantiated this idea. However, a surprising result revealed from Rawinsonde data was that the circulation at higher levels is opposite to that at lower levels. This change-over level is at about 300 mb.

As expected, the air inside a tropical cyclone is less dense than its surroundings. For Hurricane Daisy of 1958 near Florida, in the mature stage, the surface pressure in the eye was 950 mb and the maximum wind was 50 m s^{-1} . Hurricane Daisy is considered to be a hurricane of moderate intensity, and even in this case more than half the temperature gradient needed for its existence was internally generated. RIEHL (1979), WARNECKE (1997) maintained that this is the main reason why intense hurricanes occur rarely. In contrast, in extratropical cyclones, the cyclone grows at the expense of the potential energy in a pre-existing temperature field, which becomes pronounced. On the other hand, in a tropical cyclone, the cyclone itself must generate most of the required temperature gradient.

RIEHL (1979) suggested that a hurricane may be regarded as a rankine vortex with a velocity profile defined by $v_\theta/r = \text{constant}$ in the inner core of maximum winds and $v_\theta r = \text{constant}$ in the outer core. Here, r is the radial coordinate and v_θ is the azimuthal velocity. The outer core can be defined as

$$v \cdot r^x = \text{constant}, 0.4 \cdot x \cdot 0.6 \quad (5.50)$$

In the outer core, with increasing distance from the center, v_θ tends to zero.

Momentum And Energy Budgets For Tropical Cyclones

Following RIEHL (1979), the energy and momentum budgets for hurricanes will be considered. In polar coordinates the equations of horizontal motion with the neglect of lateral friction are

$$\frac{dv_{\theta}}{dt} + \frac{v_{\theta}v_r}{r} + fv_r = -\frac{1}{\rho} \frac{\partial p}{r \partial \theta} + \frac{1}{\rho} \frac{\partial \tau_{\theta z}}{\partial z} \quad (5.51)$$

$$\frac{dv_r}{dt} - \frac{v_{\theta}^2}{r} - fv_{\theta} = -\frac{1}{\rho} \frac{\partial p}{r \partial r} + \frac{1}{\rho} \frac{\partial \tau_{rz}}{\partial z}$$

Here, v_r and v_{θ} are the radial and azimuthal velocities respectively. After certain algebra involving these two equations, it can be shown that

$$\frac{d}{dt} \left(v_{\theta} r + \frac{fr^2}{2} \right) - \frac{r^2}{2} \frac{df}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial \theta} + \frac{r}{\rho} \frac{\partial \tau_{\theta z}}{\partial z} \quad (5.52)$$

The component of the earth's angular momentum (per unit mass) about the vertical axis of the tropical cyclone is

$$\Omega = v_{\theta} r + \frac{fr^2}{2} = \text{const} \tan t \quad (5.53)$$

For symmetrical storms, eq. (5.53) is a good representation in the upper troposphere. If eq. (5.52) is integrated over the entire volume in the storm, by definition the pressure term will disappear, but the frictional term will not because of transfer of momentum from the atmosphere to the ocean. To compute the momentum budget, integrate eq. (5.67) over the volume of the storm to obtain expressions for the transport F_{Ω} (radial) at any radius and F_{Ω} (vertical) between two radii. These are

$$F_{\Omega}(\text{radial}) = -\frac{2\pi r^2}{g} \left[\int_{p_2}^{p_1} \bar{v}_{\theta} \bar{v}_r dp + \int_{p_2}^{p_1} \overline{v'_{\theta} v'_r} dp + \frac{fr}{2} \int_{p_2}^{p_1} \bar{v}_r dp \right] \quad (5.54)$$

$$F_{\Omega}(\text{vertical}) = -\frac{2\pi}{g} \left[\int_1^2 \bar{v}_{\theta} \bar{\omega} r^2 dr + \int_1^2 \bar{v}_{\theta}^* \bar{\omega}^* r^2 dr + \frac{f}{2} \int_1^2 \bar{\omega} r^3 dr \right] \quad (5.55)$$

where, $\omega = dp/dt$.

The surface transport to the ocean is given by

$$E_{\Omega}(\text{surface}) = 2\pi \int_1^r \tau_{\theta,0} r^2 dr \quad (5.56)$$

where $\tau_{\theta,0}$ is the stress at the ship's deck level (or anemometer level).

In eq. (5.54) the first term represents the transport by the mean ageostrophic circulation v_r , the second term denotes the deviation from symmetry when one goes round the perimeter and the third term is the influence due to the earth's rotation, assuming the Coriolis parameter to be constant.

Table 5.7: Transports through 1° radius (1012 kJ · s⁻¹) showing the radial energy balance in two different hurricanes (RIEHL, 1979)

Parameter	Hurricane Daisy (1960)	Hurricane Helene (1951)
Net latent heat inflow	+ 34.1	+ 31.9
Flux of latent and sensible heat from the sea	+ 3.4	+6.2
Import of kinetic energy	+0.4	+0.2
Total energy source	37.9	38.3
Less net export of (C _p T + gz)	- 36.9	-37.4
Balance for radiation cooling	1.0	0.9

One can regard the atmosphere, and particularly a tropical cyclone, in the present situation as a thermal engine for which the efficiency (of converting heat to mechanical energy) is defined as the ratio of the mechanical energy produced to the heat released. For an average hurricane, the kinetic energy produced was estimated by RIEHL (1979) as 15×10^{18} ergs s⁻¹ or 0.36×10^{12} kWh⁻¹ (1 erg = 0.1 μJ, 1 kWh = 3.6 MJ). The latent heat released was 13.3×10^{12} kWh · d⁻¹. Thus, the efficiency E is 3 %. This is very low but is somewhat higher than for extratropical cyclones and the general circulation of the atmosphere. Hence, weather systems and the atmosphere are very inefficient heat engines. This low value of efficiency for the tropical cyclones indicates that the mechanism for energy release is in the central area with local oceanic heat source and not in the advection of large masses of water vapour into the system from outside.

The balance of radial energy for Hurricanes Helen of 1951 and Daisy of 1960 is shown in Table 5.7. Concerning oceanic input of energy, GRAY (1978a) provided the following analysis. In the tropical cyclone, moist static energy *h* can increase or decrease through latent and sensible heat exchange with the ocean *E_s* through radiation *R* and through horizontal transport through the boundaries ∇ · V*h*. One can write for this energy balance

$$\frac{\partial h}{\partial t} = E_s + R - \nabla \cdot Vh$$

(5.57)

where,

$$h = gz + C_p T + Lq$$

(5.58)

Note that all these terms have been integrated through the thickness of the troposphere. For the inner 4° radius of tropical storms, *E_s* + *R* is slightly positive for weak disturbances, but for hurricanes it is highly positive because strong input of energy takes place from the ocean. The vertical circulations in a tropical cyclone will act as an energy sink dissipating the system and the main energy source is the ocean. For this reason, many tropical systems weaken or dissipate once they are not traveling over the ocean.

Frequency and region of occurrence

The conditions for development of tropical storms form the boundary of areas and period of generation of tropical cyclones. Fig. 5.41 shows over a 20-yr period these areas. Over the globe, the percentage change in the number of tropical cyclones over a recent 20-yr period (1958–77) varied from + 23 to – 13, with an average of 8 (Table 5.8). The ratio of the number of tropical cyclones in the Northern Hemisphere to those in the Southern Hemisphere varied from 1.5 to 4.0.

Month by month occurrences of tropical cyclones for the same 20-yr period for the Northern and Southern Hemispheres are shown separately in Table 5.9 and Table 5.10, respectively. The data for the various ocean basins, which are identified in Fig. 5.41, are shown in Table 5.11.

About 80 % of the tropical cyclones occur in the belt between 20° N and 20° S. The rest occurs poleward of 20° latitude, but mainly in the Northern Hemisphere. Annually, about two thirds of all tropical cyclones occur in the Northern Hemisphere; similarly, about two thirds occur in the Eastern Hemisphere (as opposed to the Western Hemisphere). Most of the tropical cyclones form in the latitudinal belt 5–15°, and rarely do they form within 4–5° from the equator. In the Southern Hemisphere, tropical cyclones do not form poleward of 22°, whereas in the Northern Hemisphere they form at latitudes up to 36°.

Considering longitude, there are three favoured locations for the formation of tropical cyclones: 90° E, 140° E, and 105° W. The western part of the North Pacific Ocean accounts for about one third of all tropical cyclones. Generally, summer is the favoured season for tropical cyclone formation, but they do occur in other seasons, especially in the western part of the North Pacific Ocean.

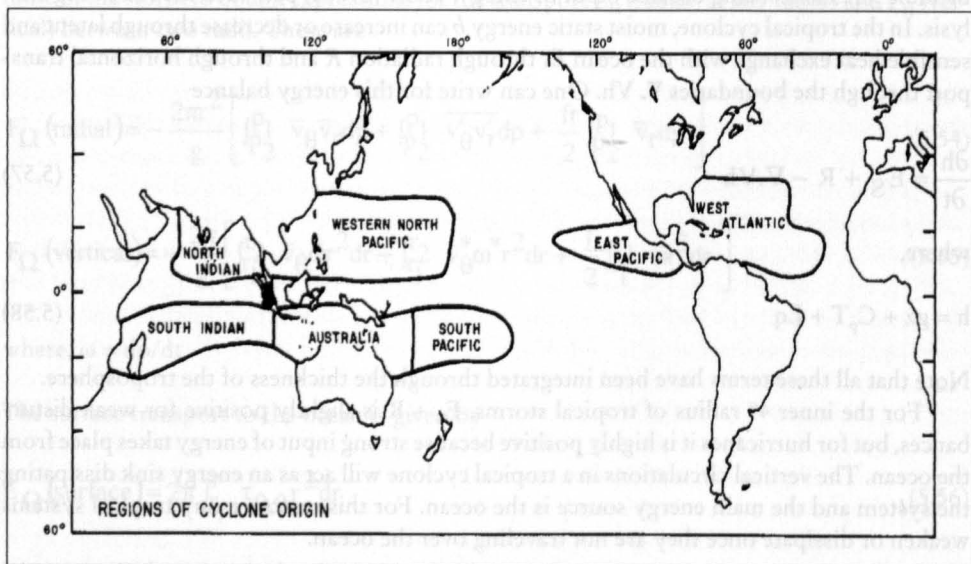


Fig. 5.41: Ocean basins for which tropical cyclone frequency is given in Table 5.10 (GRAY, 1978a)

Table 5.8: Tropical cyclone statistics for the period 1958–77. NH, Northern Hemisphere; SH, Southern Hemisphere (GRAY, 1978a)

Year		No. of cyclones			% deviation from 20-yr average	Ratio (NH:SH)
NH	SH	NH	SH	Total		
1958	1958–59	52	25	77	–3	2.1
1959	1959–60	48	21	69	–13	2.3
1960	1960–61	48	22	70	–12	2.2
1961	1961–62	58	23	81	+2	2.5
1962	1962–63	50	30	80	+1	1.7
1963	1963–64	49	23	72	–9	2.1
1964	1964–65	65	19	84	+6	3.4
1965	1965–66	56	22	78	–1	2.5
1966	1966–67	64	16	78	–1	4.0
1967	1967–68	63	28	91	+15	2.2
1968	1968–69	61	23	84	+6	2.6
1969	1969–70	49	23	72	–9	2.1
1970	1970–71	56	26	82	+4	2.1
1971	1971–72	70	27	97	+23	2.6
1972	1972–73	54	35	91	+15	1.5
1973	1973–74	46	28	74	–6	1.6
1974	1974–75	55	19	75	–5	2.9
1975	1975–76	47	29	76	–4	1.6
1976	1976–77	55	30	85	+7	1.8
1977	1977–78	47	20	67	–15	2.3
Total		1093	489	1583		
Average		54.6	24.5	79.1	± 8	2.3

Table 5.9: Frequency of Northern Hemisphere tropical cyclone genesis by year and month (GRAY, 1978a)

Year	Jan.	Feb.	Mar.	Apr.	May	June	July	Aug.	Sept.	Oct.	Nov.	Dec.	Total
1958	1	0	0	0	2	5	10	9	11	9	4	1	52
1959	0	0	0	1	2	6	7	11	9	8	2	2	48
1960	0	0	0	1	3	7	6	14	6	8	2	1	48
1961	1	1	1	1	4	5	10	5	14	9	6	1	58
1962	0	1	0	1	3	2	7	11	11	7	4	3	50
1963	0	0	0	1	3	5	6	5	14	11	0	4	49
1964	0	0	0	0	3	4	11	15	12	8	10	2	65
1965	2	2	1	1	4	8	8	8	12	3	4	3	56
1966	0	0	0	2	2	3	9	13	20	5	7	3	64
1967	2	1	1	1	2	4	10	12	12	13	3	2	63
1968	0	0	0	1	2	5	7	17	11	11	6	1	61
1969	1	0	1	1	1	0	7	13	10	9	4	2	49
1970	0	1	0	0	4	6	11	10	9	8	7	0	56
1971	1	0	1	3	7	3	15	11	15	9	4	1	70
1972	1	0	0	1	4	2	9	12	12	6	4	3	54
1973	0	0	0	0	0	5	12	8	8	7	5	1	46
1974	1	0	0	2	4	6	5	14	13	6	4	0	55
1975	2	0	0	0	2	3	6	11	9	8	6	0	47
1976	1	1	0	3	2	7	9	15	10	4	0	3	55
1977	0	0	1	0	3	4	8	4	13	9	4	1	47
Total	13	7	6	20	57	90	173	218	231	158	86	34	1093
Average	0.7	0.3	0.3	1.0	2.9	4.5	8.6	10.9	11.5	7.9	4.3	1.7	54.6

Table 5.10: Frequency of Southern Hemisphere tropical cyclone genesis by year and month (GRAY, 1978a)

Year	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.	May	Total
1958-59	1	1	3	5	7	6	2	0	25
1959-60	0	1	4	3	2	7	4	0	21
1960-61	0	1	1	9	7	4	0	0	22
1961-62	0	1	4	6	8	2	2	0	23
1962-63	1	0	4	6	9	5	2	3	30
1963-64	0	1	3	7	3	7	1	1	23
1964-65	0	2	5	4	5	3	0	0	19
1965-66	0	0	3	7	6	6	0	0	22
1966-67	0	1	3	5	1	3	2	1	16
1967-68	0	2	4	8	7	3	4	0	28
1968-69	1	1	3	7	8	2	1	0	23
1969-70	0	1	0	5	6	7	3	1	23
1970-71	1	3	6	4	7	4	1	0	26
1971-72	0	1	6	3	10	3	2	2	27
1972-73	1	3	4	10	6	7	3	1	35
1973-74	1	3	5	7	4	6	2	0	28
1974-75	0	0	2	6	2	5	4	0	19
1975-76	0	4	4	8	5	4	3	1	29
1976-77	1	0	4	8	9	5	3	0	30
1977-78	0	3	4	3	4	4	2	0	20
Total	7	29	72	121	117	93	41	10	489
Average	0.4	1.5	3.6	6.1	5.9	4.7	2.1	0.5	24.5

Table 5.11: Yearly variation of tropical cyclones by ocean basins. SH, Southern Hemisphere; NW Atl., Northwest Atlantic Ocean; NE Pac., Northeast Pacific Ocean; NW Pac., Northwest Pacific Ocean; S. Pac., South Pacific Ocean; Aust., Australia; N. Ind., North Indian Ocean; S. Ind., South Indian Ocean (GRAY, 1978a)

Year	SH	NW Atl.	NE Pac.	NW Pac.	N. Ind.	S. Ind.	Aust.	S. Pac.	Total
1958	1958-59	12	13	22	5	11	11	7	81
1959	1959-60	11	13	18	6	6	13	2	69
1960	1960-61	6	10	28	4	6	8	8	70
1961	1961-62	11	12	29	6	12	7	4	81
1962	1962-63	6	9	30	5	8	17	3	78
1963	1963-64	9	9	25	6	9	7	7	72
1964	1964-65	13	6	39	7	6	9	4	84
1965	1965-66	5	11	34	6	12	7	4	79
1966	1966-67	11	13	31	9	5	5	6	80
1967	1967-68	8	14	35	6	11	9	8	91
1968	1968-69	7	20	27	7	8	7	8	84
1969	1969-70	14	10	19	6	10	7	6	72
1970	1970-71	8	18	23	7	11	12	3	82
1971	1971-72	14	16	34	6	7	14	6	97
1972	1972-73	4	14	28	6	13	12	10	88
1973	1973-74	7	12	21	6	4	16	8	74
1974	1974-75	8	17	23	7	6	10	3	74
1975	1975-76	8	16	17	6	8	16	5	76
1976	1976-77	8	18	24	5	9	12	9	85
1977	1977-78	6	17	19	5	6	7	7	67
Total		176	268	526	121	168	206	118	1583
Average		8.8	13.4	26.3	6.4	8.4	10.3	5.9	79.1

In the North Indian Ocean, there are two seasons of cyclone formation in the $5\text{--}15^\circ$ latitude belt: a major period in the autumn associated with the retreat of the southwest monsoon and a minor period in the spring associated with the onset of the monsoon. Note that the Southeast Pacific Ocean and the South Atlantic Ocean are not regions of tropical cyclones. The seasonal location of the intertropical convergence zone (ITCZ) is a favoured region for tropical cyclogenesis.

According to GRAY (1978a, 1978b, 1978c, 1978d), tropical cyclones tend to cluster in time as well as in space. Within a period of 1–2 wk there may be as many as 5–15 tropical cyclones over the globe and then a lull for several weeks. During such active periods there may be as many as two to six times as many cyclones than in the less active periods. GRAY (1978a, 1978b, 1978c, 1978d) attributed this to the influence of the larger scale general circulation of the tropical atmosphere with time scales of 10–20 d.

About 80–85 % of the tropical cyclones originate in or near the poleward side of the ITCZ or the doldrums trough. The remainder occur in the trade winds at some distance from the ITCZ but usually in conjunction with an upper tropospheric trough to their northwest.

There are some anomalous warm core systems belonging to the class of subtropical or semitropical cyclones accounting for about 3–5 % of the tropical cyclones. These originate in the subtropics inside baroclinic regions where stagnant frontal zones exist to the east of the westerly troughs aloft (e.g. Northwest Atlantic and Northwest Pacific oceans). These mixed type of tropical midlatitude cyclones usually do not generate intense cyclones.

Since tropical cyclones spend most of their lifespan over the warm waters of the tropical oceans, traditional data sources are not dense enough. Aircraft data have contributed significantly. However, for an accurate vertical structure determination, Rawinsonde data are the most pertinent. Since enough synoptic Rawinsonde data are not available, it is necessary to combine the data of different periods for similar weather systems.

Hurricane Movement Over Ocean and Land

Earlier, it was seen that hurricanes are born primarily over oceanic areas and they weaken when they travel over the continents. A numerical model simulation by CHANG and MADALA (1980) showed that hurricanes appear to move into areas of higher sea surface temperature (SST) if the SST gradient is perpendicular to the mean ambient flow vector (MAFV). An area of warmer SST located to the right of MAFV is more favorable for hurricane intensification than an area situated to the left.

SCHWERDT (1978) studied the reduction of the wind field when a hurricane moves from the ocean to over land. Once a hurricane crosses the coast from the ocean to the land its central pressure starts increasing and the wind fields start decreasing, and this so-called filling process is most pronounced in the inner portion of the hurricane.

According to PALMÉN and NEWTON (1969), filling occurs because the heat flux from the land is negligible, which causes a reduction of the excess temperature of the hurricane core. Consequently, the kinetic energy decreases. BERGERON (1954) showed that a reduction in the equivalent potential temperature of the ascending air in the core leads to the filling process. MILLER (1963) showed that surface friction plays a minor role in the filling process.

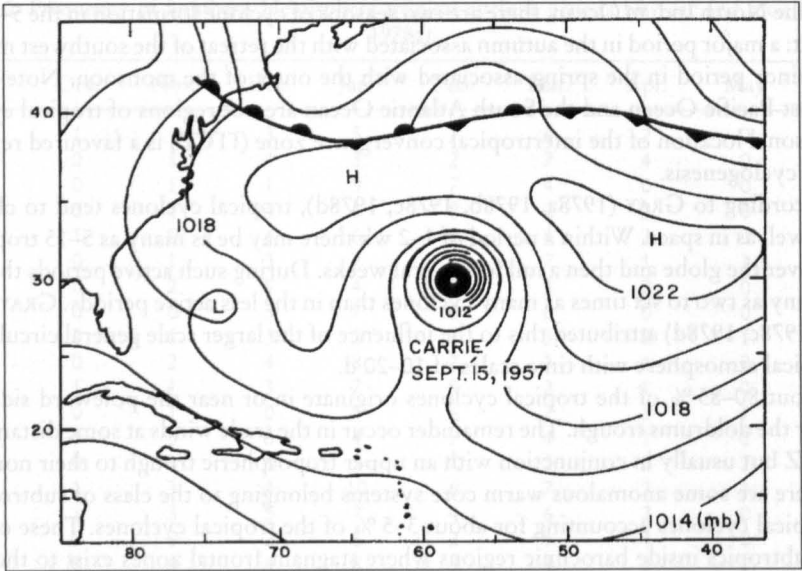


Fig. 5.42: Surface weather chart on September 15, 1957, showing Hurricane Carrie (SIMPSON and RIEHL, 1981)

SIMPSON and RIEHL (1981) defined the habitation layer as the lowest 500 m of the atmosphere. They considered the balance of forces in this layer at a coastal station as a hurricane approaches the station. The centrifugal force C_c and the Coriolis force C_0 are directed outwards, whereas the pressure gradient force P_g and the frictional force F_s are directed inward (perpendicular to the streamline). This leads to an acceleration of the tangential wind component as the air spirals inward. (Figs. 5.42, 5.43, 5.44, 5.45, 5.46, 5.67).

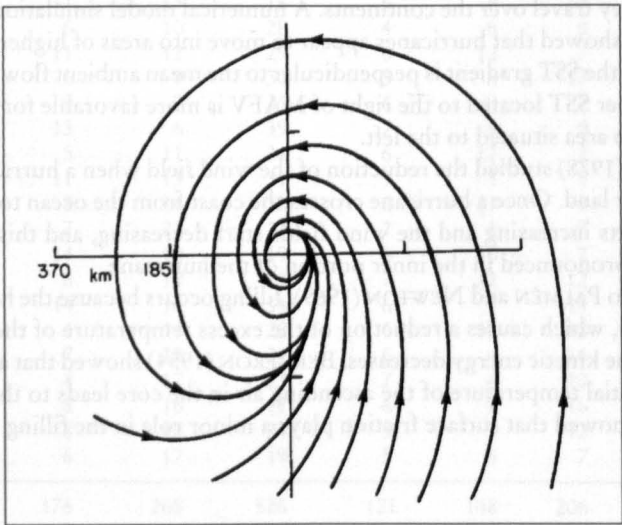


Fig. 5.43: Streamlines showing the circulation in a hurricane (SIMPSON and RIEHL, 1981)

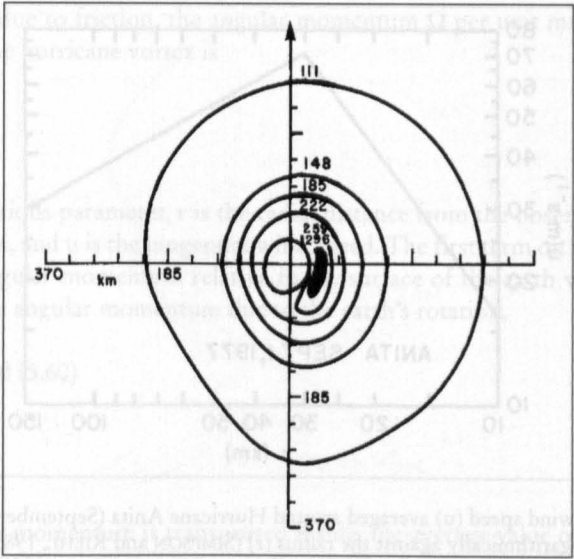


Fig. 5.44: Isotachs of surface wind speed (knots) in an intense hurricane. Black area shows the region of strongest winds (to the right of the eye) (1 knot = 1.852 km · h⁻¹) (SIMPSON and RIEHL, 1981)

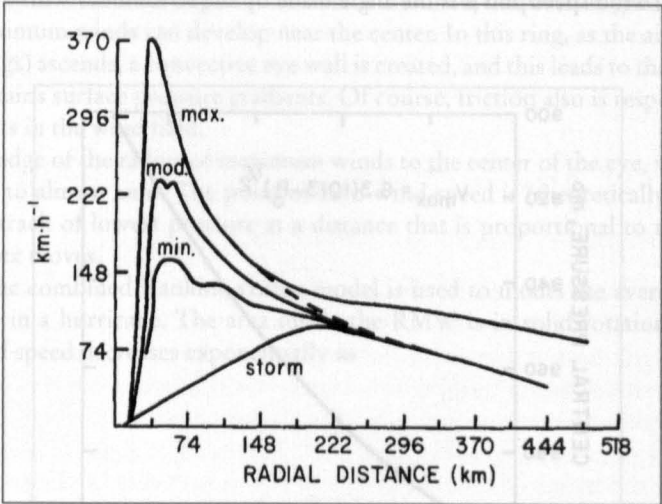


Fig. 5.45: Model of radial profiles of wind speed for three hurricane intensities and for a tropical storm (SIMPSON and RIEHL, 1981)

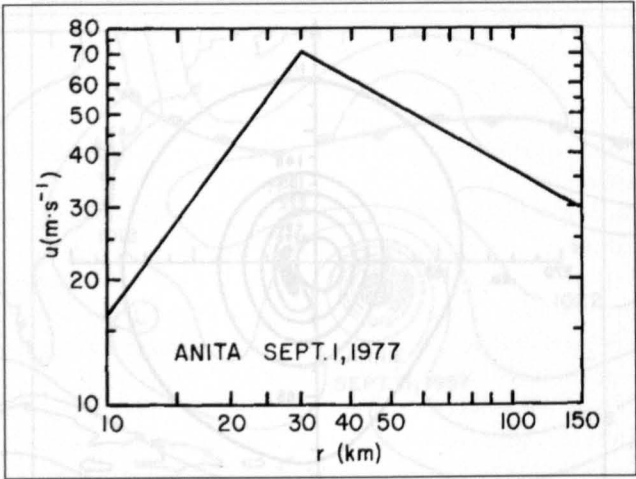


Fig. 5.46: Tangential wind speed (u) averaged around Hurricane Anita (September 1, 1977) and plotted logarithmically against the radius (r) (SIMPSON and RIEHL, 1981)

In a hurricane, mainly the tangential (rotational) component of the wind increases from the periphery of the vortex to the ring of maximum winds (RMW). According to SIMPSON and RIEHL (1981) this ring has a radius of less than 35 km:

$$u = V \cos \beta \tag{5.59}$$

where, V is the wind speed and β is the angle made by the streamlines with the isobars.

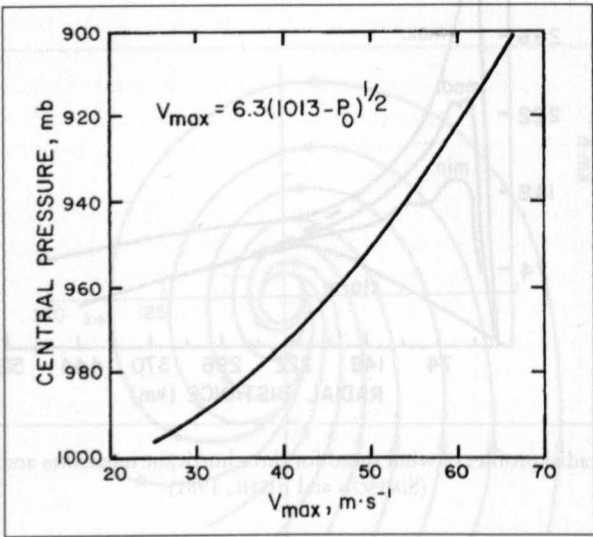


Fig. 5.47: Maximum sustained wind speed versus central pressure for Atlantic hurricanes (SIMPSON and RIEHL, 1981)

Neglecting losses due to friction, the angular momentum Ω per unit mass supplied by the surroundings to the hurricane vortex is

$$\Omega = ur + \frac{fr^2}{2}$$

(5.60)

where, f is the Coriolis parameter, r is the radial distance from the observation point to the centre of the vortex, and u is the tangential wind speed. The first term on the right side of eq. (5.60) gives the angular momentum relative to the surface of the earth whereas the second term represents the angular momentum due to the earth's rotation.

From eq. (5.59) and (5.60)

$$u = \frac{\Omega}{r} - \frac{fr}{2}$$

(5.61)

As the angular momentum is transported inside, the average value of u increases as can be seen from eq. (5.61) (ignoring frictional effects). The maximum value of u occurs for cyclostrophic balance (i.e. when the pressure gradient force balances the centrifugal plus Coriolis forces) and when β of eq. (5.59) tends to zero.

In principle, the increase of u with decreasing r would create centrifugal forces that would far exceed the pressure gradient forces, and the air should spiral outward towards higher pressure. However, surface friction reduces the value of Ω steadily and this outward spiralling tendency is offset. Hence, surface friction plays a dual role. First of all, it permits a crossing angle between the streamlines and isobars so that air from the surroundings is drawn towards the vortex center by pressure gradient forces. Second, it reduces the imported angular momentum so that the centrifugal forces cannot dominate the pressure gradient forces and a radius of maximum winds can develop near the center. In this ring, as the air (drawn from the surroundings) ascends, a convective eye wall is created, and this leads to the central warm core that maintains surface pressure gradients. Of course, friction also is responsible for the creation of gusts in the wind field.

From the edge of the radius of maximum winds to the center of the eye, wind decreases monotonically to almost zero. The point of zero wind speed is (theoretically) displaced to the left of the track of lowest pressure at a distance that is proportional to the speed with which the vortex moves.

Usually, the combined Rankine vortex model is used to model the average horizontal wind structure in a hurricane. The area inside the RMW is in solid rotation. Outside the RMW the wind speed decreases exponentially as

$$u = \frac{\text{const}}{r^x}$$

(5.62)

For a Rankine vortex, $x = 1$. However, for a hurricane, $0.4 < x < 0.8$.

Above the first few hundred meters, the strongest winds of a hurricane do not vary much up to 4–5 km of height. The wind speed variation with height in tropical cyclones is shown in Fig. 5.48.

The international standard for sustained winds is the average speed for a 10-min period. In the United States the sustained wind is a 1-min average. For extreme winds in the United

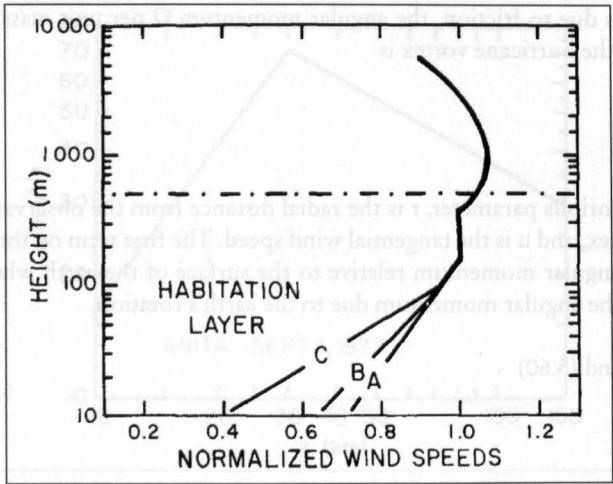


Fig. 5.48: Model of wind speed variation with height in tropical cyclones. Speeds are normalized with reference to wind speeds measured by aircraft in the 150- to 300-m layer. A, over water; B, over land; C, profile for 1/7-power law (BATES, 1977)

States the unit of measurement is the fastest mile (the highest speed at which 1 mi of wind passes the anemometer).

In the U. S. National Weather Service and in the U. S. Army Corps of Engineers, the ideas about Probable Maximum Hurricane (PMH) and Standard Project Hurricane (SPH) originated in the 1950s (e.g. GRAHAM and NUNN, 1959). The PMH is defined as a hypothetical hurricane having that combination of values of meteorological parameters that will make it the most severe that can probably occur at a particular coastal location. The SPH is defined as a hypothetical hurricane with the most severe combination of values of hurricane parameters reasonably characteristic of a specified geographic location, thus excluding extremely rare combinations (SCHWERDT, 1976; MOGOLESKO, 1976).

5.3.2 Prediction of Movement and Intensity

Modelling Of Hurricane Formation and Intensification

According to GRAY (1978a, 1978b) little effort has gone into numerically modelling tropical cyclogenesis. OYAMA (1964), CHARNEY and ELIASSEN (1964), OGURA (1964), KUO (1965) and several later authors modelled the intensification of hurricanes. The low level winds for different classes of tropical disturbances were deduced from Rawinsonde composite studies. These winds are much smaller than the initial cyclone strength assumed by numerical modellers, as summarized in Table 5.13. According to GRAY (1978a, 1978b, 1978c, 1978d) the transformation of a disturbance to a cyclone has yet to be realistically modelled.

GRAY (1978a, 1978b, 1978c, 1978d) classified the disturbance stages and gave estimates of central pressure and maximum sustained surface winds. These are shown in Table 5.13. Even in a stage 6 cyclone (i.e. typhoon) approximately 50 % of the mass inflow at 4° radius takes place above the 900-mb layer. Hence, there is significantly more mass inflow than can be accounted for by boundary layer processes. In fact, mass convergence could occur in a layer as high as 400 mb.

Table 5.12: Some numerical modeling papers on tropical cyclone intensification and their assumed initial lower tropospheric cyclone strength (GRAY, 1978a)

Modellers	Assumed initial maximum wind velocity (m s ⁻¹) and radius (km) of maximum wind		Vortex vorticity inside the radius of maximum winds (10 ⁻⁶ · s ⁻¹)	Type of vortex
KUO (1965)	10	141	142	Symmetrical
YAMASAKI (1968)	4.7	100	94	Symmetrical
OYOYAMA (1969)	10	50	400	Symmetrical
MILLER (1969)	10	200	100	Real vortex
ROSENTHAL (1970)	7	250	56	Symmetrical
SUNDQVIST (1970a, 1970b)	15	200	150	Symmetrical
CARRIER (1971)	21	50	840	Symmetrical
ANTHES et al. (1971a, 1971b)	18	240	150	Asymmetrical
ANTHES (1972)	18	240	150	Asymmetrical
MATHUR (1972)	15	200	150	Asymmetrical
HARRISON (1973)	~10	~120 ^a	~170	Asymmetrical
KURIHARA and TULEYA (1974)	12	200	120	Symmetrical
CESELSKI (1974)	17	~100–150	~200	Real vortex
KURIHARA and TULEYA (1974)	12	200	120	Symmetrical
ANTHES (1977)	18	240	150	Symmetrical
ROSENTHAL (1978)	7.2	220	65	Symmetrical

NOTE: Typical precyclone cloud cluster vorticity is 10 x 10⁻⁶ to 15 x 10⁻⁶ · s⁻¹.

^a Estimated from initial height field.

Table 5.13: Tropical disturbance classification stages and surface pressure and wind estimates at these various stages; two classes of nonintensifying disturbance and six stages of disturbance-to-cyclone intensification are shown. (GRAY, 1978a)

Disturbance classification	Stage	Estimated minimum sea level pressure (mb)	Estimate of maximum sustained surface winds (m · s ⁻¹)
General class of nondeveloping disturbances	0	1008	8
Nondeveloping disturbances of summer in cyclone genesis region	00	1008	8
Initial cluster	1	1007	8
Pre-typhoon cluster	2	1005	10
Genesis	3	1003	12
Intensifying	4	1000	18
Tropical storm (980–1000 mb)	5	990	25
Typhoon (950–980 mb)	6	965	40

Movement of Tropical Cyclones: Prediction and Modelling

Several different techniques are being used for predicting the tracks of tropical cyclones: empirical, statistical, and dynamical. Empirical techniques will be considered first. According to HEBERT (1979), these may be further classified into three categories:

- (a) persistence and climatology,
- (b) synoptic and
- (c) satellite.

These techniques can be used for prediction of the hurricane track for 12–24 h in advance. Any extrapolation beyond 24 h will result in large errors, except possibly in the deep easterlies of the tropics.

In the persistence technique, one simply extrapolates linearly the last track, assuming uniform speed and no change of direction. One can use a higher order persistence forecast by allowing for variation of speed of movement and direction of the hurricane in the past 12–24 h. The simplicity of this technique is its chief advantage. It is obvious that errors could occur if the persistence assumption does not hold.

In a climatological forecast one makes use of the knowledge of the temporal and spatial frequency of past hurricanes in given grid areas (e.g. 2.5° latitude-longitude squares and time scales up to 5 d). This method works well when the frequency of occurrence is great. It fails with increasing latitude (due to recurvature) as well as for untypical situations. Other time it fails is when a bimodal structure is present.

In the persistence plus climatology forecasts (BELL, 1962; AOKI, 1979) one uses the formula $np + mC$ where p and C represent the persistence and climatology, respectively, and n and m are weighting factors. Usually, $n = m = 0.5$ is used. AMADORE (1972) gave different weightings to get latitude and longitude components separately for the tropical cyclones east of the Philippines. However, according to HEBERT (1979), similar attempts for the South China Sea region did not significantly improve the results.

In the synoptic technique, the main assumption is that the air mass in which the tropical cyclone is embedded is homogeneous. In the surface geostrophic steering method, the zonal (east-west) and the meridional (north-south) components of the hurricane movement are determined by estimating (from the synoptic charts) the pressure gradient (millibars per degree of latitude) across the storm. Since the surrounding air mass is not uniform, one must apply a correction to the pressure gradient to account for the nonhomogeneity. The main advantage of this technique lies in the fact that almost all forecast centres have surface pressure analysis charts.

In the control point method (CHIN, 1970), which has been in use for several years at the Hong Kong Observatory, one makes use of the observed high correlation between the wind direction at certain locations in the midtroposphere and the direction of movement of the tropical cyclone. The disadvantage is that in areas of sparse data, midtropospheric analyses might be difficult to make.

In predicting the movement of cyclones, one should also consider the so-called Fujiwhara effect (FUJIWHARA, 1921) in which two vortices close to each other will rotate about a common point located on the line joining their centres.

Next, satellite techniques, which are playing an ever-increasing role in the prediction of the tracks of cyclones, will be considered. The basic principle is to relate past changes in cloud features to future changes in the direction of motion.

FETT and BRAND (1975) used six identifiable cloud patterns and extrapolated the rotation of one or more of these patterns during the previous 24 h to calculate the change in the motion direction for the next 24 h. In making this extrapolation, an analogy of the relationship of the turning of a tropical cyclone to its hyperbolic point was used.

The method that is occasionally used in the Australian Bureau of Meteorology was developed by LAJOIE and NICHOLLS (1974). From available satellite pictures, they identify certain cloud features and based on these, extrapolation is made for the next 12 h regarding

the change of direction of motion of the cyclone. The two main principles involved are as follows: tropical cyclones frequently move in the direction of the line connecting their centers to the most developed cumulonimbus cluster at or near the downstream end (i.e. in a cyclonic direction of the inflow current) of the outer cloud band and tropical cyclones usually do not move towards a cumulonimbus-free sector.

The advantage of the satellite techniques is that they can be used in regions where conventional data are sparse. The disadvantages are difficulty in obtaining good satellite pictures and the subjectivity involved in interpreting them. Nevertheless, certain simple concepts are useful in the prediction of the tracks. For example, RAMAGE (1973) noted the extent of cloudiness along the track of a tropical cyclone. In Japan, substantial observations exist to show that the successive positions of the spiral cloud band correlate well with the movement of recurring typhoons.

Cyclones moving towards the west sometimes recurve towards northeast after interaction with upper air troughs in the westerlies. CHAN (1978), based on a study of recurring typhoons in the western part of the North Pacific Ocean, suggested that the following two parameters, which can be determined from satellite imagery, can be used to estimate the recurvature: D/d , where D is the diameter of the central dense overcast of the tropical cyclone and d is the average width of the cloud band associated with the interacting trough, and θ , which is the angle between the axis of the cloud band and the latitude of the tropical cyclone center. If $30^\circ \leq \theta \leq 40^\circ$ and $D/d < 1.5$, then it is highly probable that a tropical cyclone will recurve.

Statistical Techniques of Track Prediction

Following NEUMANN (1979), statistical models will be discussed. These are broadly divided into two categories: models based on analogs and models based on regression equations. Regression equation models can be further classified into (i) models using predictors based on climatology and persistence, (ii) models that include, but are not limited to, predictors derived from observed synoptic data, and (iii) models that include, but are not limited to, predictors derived from numerically forecasted data. Models of type (i) are referred to as simulated analog, models of type (ii) are referred to as classical models (or statistico-synoptic), and models of type (iii) are called statistical-dynamical models.

The basic principle involved in these models is the recognition of the fact that temporal and spatial analyses of tracks reveal repetitiveness and close association with identifiable synoptic patterns.

The advantage of the analog method is that it is usually the first available forecast for the tracks. Its disadvantage is that it works well only for typical situations. Next, the regression methods will be considered. RIEHL (1956) gave the first objective technique for predicting the movement of tropical cyclones. In this method, known as the Riehl-Haggard technique, one makes use of the steering principle, namely that the tropical cyclone's movement speed is proportional to the speed of the vertically integrated flow surrounding the vortex. The 500-mb level was used for approximating this flow. This technique was originally used for the Atlantic hurricanes.

Dynamical Methods for Predicting Hurricane Movement

Following PELISSIER (1979), the numerical models that were developed for predicting hurricane motion will be considered. The numerical modelling effort has been slow until the 1970s principally because tropical storms mainly occur over the data-sparse areas of the tropical oceans, and it is difficult to provide the initial state of the atmosphere. From a grid resolution point, the scale of the intense part of the tropical cyclone is small compared with the synoptic weather disturbances. Generally, prediction of the tracks of tropical cyclones is more successful than prediction of the intensification because the movement of the storm is mainly related to the steering current in which the storm is embedded.

SANDERS and BURPEE (1968) originally developed a barotropic model, referred to as SANBAR, which was modified by PIKE (1972). In this model the tropical cyclone track is predicted based on the track of minimum stream function and maximum vorticity centers. On a Mercator projection using a grid size of 1.5° and extending from the equator to 55° N and from 36.5° W to 123.5° W and using a time step of 30 min, forecasts are made up to 72 h in advance. The initial observations are averaged over the 1000- to 100-mb layer.

After specifying the initial winds, the nondivergent part of the wind field is calculated through a relaxation of the stream function ψ in the interior of the grid using the relation

$$\nabla^2 \psi = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} + \frac{u \tan(\text{latitude})}{R_E} \quad (5.63)$$

where, u and v are the eastward and northward components, respectively, of the hurricane motion and R_E is the radius of the earth. One must specify the component of the wind parallel to the boundaries. Then, using the barotropic vorticity equation

$$(\nabla^2 - M) \frac{\partial \psi}{\partial t} = J(f + \nabla^2 \psi, \psi) \quad (5.64)$$

one can determine ψ where J is the Jacobian, ∇^2 is the horizontal Laplacian, and M is the Helmholtz coefficient.

One can identify the storm center with a local minimum in x - or a maximum in (or as an average between these two positions). Usually, the storm is replaced by an idealized circularly symmetric vortex defined by

$$v_\theta = 0.72 v_{\max} \left\{ \sin \left[\pi \left(\frac{r}{r_m} \right) \right] \left(\frac{\ln 0.5}{\ln r_c / r_m} \right) \right\}^{1.5} \quad (5.65)$$

where, v_θ is the symmetric tangential wind field.

The Japan Meteorological Agency developed a balanced barotropic model for typhoon track prediction northward of 20° using a 51×15 grid with a mesh length of 381 km at 60° N. At least three types of systematic errors appear: forecast positions for low latitude storms are occasionally poor due to a westward bias in the predicted tracks, the predicted speed of movement is usually smaller than observed values, and the predicted recurvature is usually less than the observed recurvature.

Table 5.14: Frequency distribution of direction using the balanced barotropic model. The angular intervals listed are the ranges of absolute differences between predicted and observed directions of displacement. Data listed under 24 and 48-h forecast periods are the number of typhoons that exhibited these directional deviations (PELISSIER, 1979)

Angular interval (degrees)	24-h forecast period	48-h forecast period
0-5	10	8
6-10	12	7
11-20	13	9
21-30	5	10
31-45	7	3
45	7	7

Table 5.15: Same as Table 5.14, except this is for eastward moving typhoons (PELISSIER, 1979)

Angular interval (degrees)	24-h forecast period	48-h forecast period
0-5	11	15
6-10	14	8
11-20	16	10
21-30	10	14
31-45	5	8
45	3	5

Table 5.16: Errors in predicted speed of movement relative to recurvature point. Overrun No. indicates number of typhoons that moved slower than the forecast. R , actual typhoon displacement; F , prediction by the balanced barotropic model (PELISSIER, 1979)

Typhoon position	24-h forecast period			48-h forecast period		
	Total No.	Overrun No.	$\frac{ R-F }{R}$	Total No.	Overrun No.	$\frac{ R-F }{R}$
Before recurvature	42	16	0.406	38	14	0.341
Near recurvature	45	13	0.334	34	12	0.498
After recurvature	20	0	0.340	9	0	0.379
Total (mean)	107	29	(0.381)	81	26	(0.401)

In this model the initial stream function ψ is determined from the geopotential by solving the balance equation

$$\nabla \cdot (f \nabla \psi) + 2 \left(\frac{\partial^2 \psi}{\partial x^2} \frac{\partial^2 \psi}{\partial y^2} - \frac{\partial^2 \psi}{\partial x \partial y} \right) = \nabla^2 \psi$$

(5.66)

where, (Φ is the geopotential and f is the Coriolis parameter. Using ARAKAWA'S (1966) finite-difference schemes, the equation is integrated in time. Based on the data at 00:00 and 12:00 GMT, forecasts are issued for 48 h in advance, twice daily.

The frequency distribution of direction errors for westward moving typhoons is shown in Table 5.14. In this table, the first row contains the ranges of absolute differences between observed and predicted directions of displacements. One can see that there is no directional bias in the forecast. The frequency distribution of the direction errors for eastward moving typhoons is shown in Table 5.15. The errors in the forecast speed of the hurricane are classified in Table 5.16 according to the location relative to the point of recurvature. The term "overrun" means the number of typhoons that moved slower than predicted. Usually, this happens before recurvature but never afterwards.

A primitive equation model is considered next. The Fleet Numerical Weather Center (FNWC) at Monterey, C-A, and the Joint Typhoon Warning Center (JTWC) at Guam use a primitive equation model referred to as the coarse mesh grid model (CMG), which is a simplified version of a more elaborate triple-nested grid model (HINSMAN, 1977). The primitive equations are expressed in the pressure coordinates as follows:

$$\frac{\partial u}{\partial t} = -L(u) + fv - M \frac{\partial \phi}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} \quad (5.67)$$

$$\frac{\partial v}{\partial t} = -L(v) - fu - M \frac{\partial \phi}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} \quad (5.68)$$

$$\frac{\partial \theta}{\partial t} = -L(\theta) \quad (5.69)$$

$$\frac{\partial \phi_{1000}}{\partial t} = -L(\phi_{1000}) \quad (5.70)$$

$$\frac{\partial w}{\partial p} = -M^2 \left[\frac{\partial}{\partial x} \left(\frac{u}{M} \right) + \frac{\partial}{\partial y} \left(\frac{v}{M} \right) \right] \quad (5.71)$$

$$\frac{\partial \phi}{\partial p} = \phi C_p \frac{\partial}{\partial p} \left(\frac{p}{1000} \right)^{R/C_p} \quad (5.72)$$

where,

$$L(S) = M^2 \left[\frac{\partial}{\partial x} \left(\frac{u_s}{M} \right) + \frac{\partial}{\partial y} \left(\frac{v_s}{M} \right) \right] + \frac{\partial}{\partial p} (w_s) \quad (5.73)$$

The region of computation is like a channel with cyclic boundary conditions in the east and west and free-slip conditions on the north and south walls. In the vertical there are three layers. A movable grid is placed over the tropical cyclone so that initially the storm is in the lower central portion of the grid, which covers a span of 56° of longitude and 48° of latitude, with a mesh interval of 2°. An objective analysis of the flow fields at the 850-, 700-, and 200-mb levels, as well as the temperature at the 850-mb level, serve as input. Using a time step of 10 min, the model is integrated in time. The errors in the predicted track for the western and eastern Pacific are shown separately and together in Table 5.17. The errors are in kilometres and the numbers in parentheses are the cases studied.

At the National Meteorological Center, a multilevel nested grid model was developed (HOVERMALE and LIVEZEY, 1978). This is referred to as the moving fine mesh (MFM) model.

This model appears to be unique in the sense that a nested high-resolution grid cantered over the tropical cyclone moves during the numerical integration through a coarse outer grid. The error analysis for the forecasts based on this model is given in Table 5.18 and comparison is made with the errors from other models. For a review of the forecast errors using barotropic models (SANDERS et al., 1978). HOPE and NEUMANN (1978) provided a survey of tropical cyclone models available worldwide. ELSBERRY (1979) summarized the three-dimensional models that are available for hurricane track prediction. In his survey he omitted the barotropic models. Since it is almost certain that all future forecasts will be made with baroclinic models, these three-dimensional models will be briefly reviewed. The features of some of the baroclinic models presently available are listed in Table 5.19. These models (except the FNWC-TCM) are capable of resolving the inner structure of the tropical cyclone. Although a 60-km grid such as that used by the NMC and NRL-NEPRF models can resolve the primary interaction between the vortex and the steering current, to predict intensification the inner core of the typhoon must be resolved. Since it is impractical to cover the whole region of the typhoon with a fine grid, one can use a nested grid, the fine grid having a resolution of 10 km. Also, this inner grid must be moved with the storm. At present, the JMA model has these capabilities, although the inner grid size is 36 km.

Table 5.17: Average forecast errors (km) for 1976 for the U. S. Navy primitive equation tropical cyclone prediction model (CMG). Number of cases in parentheses (PELISSIER, 1979)

Area	24-h forecast period	48-h forecast period	72-h forecast period
Western Pacific	287 (65)	480 (57)	693 (43)
Eastern Pacific	263 (18)	387 (15)	724 (15)
Both together	283 (81)	461 (72)	702 (58)

Table 5.18: Mean vector errors (km) of the MFM, official forecasts, and other operational objective techniques based on statistical, climatological, and persistence methods (homogeneous sample) for Hurricane Belle of August 7–8, 1976. MFM, movable fine mesh; NHC, National Hurricane Center; NHC-67, National Hurricane Center's 1967 model. For a description of SANBAR and CLIPER, see text (HOVERMALE and LIVEZEY, 1978)

Forecast period (h)	MFM	Official	NHC-67	NHC-72	NHC-73	SANBAR	CLIPER
12	124	87	67	72	67	86	76
24	213	185	200	226	152	228	204
36	215	–	241	365	270	426	454
48	280	404	311	507	369	644	748

Two types of boundary conditions are presently used in these models. In the one-way (OW) type, no feedback is allowed from the tropical cyclone to the hemispherical model. Note that the JMA nested grid model has a two-way (TW) interaction boundary condition for the inner grids. The statistics at 24 and 48 h for selected 1977 typhoons for official (JTWC), NMC-MFM, and FNWC-TCM models are shown in Table 5.20.

Table 5.19: Characteristics of several baroclinic models being applied for prediction of tropical cyclone motion based on operational data. NMC, National Meteorological Center (U.S.A.); MFM, movable fine mesh; FNWC, Fleet Numerical Weather Center (Monterey, CA); TCM, tropical cyclone model; NRL, Naval Research Laboratory; NEPRF, Naval Environmental Prediction Research Facility; PSU, Pennsylvania State University; NPS, Naval Post Graduate School (Monterey, CA); JMA, Japan Meteorological Agency; MNG, multiple-nested grid (ELSBERRY, 1979)

Agency-model	Vertical coordinate	No.of layers	Grid size (km)	No. of points	Relocatable grid	Lateral boundary conditions ^a
NMC-MFM	σ	10	60	50 x 50	Yes	OW
FNWC-TCM	ρ	3	205	32 x 24	No	OW
NRL-NEPRF	σ	5	60	51 x 51	No	OW
PSU-NPS	σ	5	120	40 x 40	No	OW
JMA-MNG	σ	3	291	31 x 31	No	OW
			145	31 x 31	Yes	TW
			73	31 x 31	Yes	TW
			36	31 x 31	Yes	TW

^a OW, one-way interaction; TW, two-way interaction

Table 5.20: Track error (km) statistics at 24 and 48 h for selected 1977 typhoons for official (JTWC), NMC-MFM, and FNWC-TCM. JTWC, Joint Typhoon Warning Center, Guam (ELSBERRY, 1979)

Typhoon	Official		NW-MFM		FNWC-TCM	
	24 h	48 h	24 h	48 h	24 h	48 h
Vera-1	178	107	294	289	106	111
Ivy	226	472	109	248	—	—
Dinah-1	181	778	356	559	152	285
Thelma	159	707	96	148	146	574
Jean	126	578	339	441	—	—
Dinah-2	206	437	56	385	250	270
Babe	583	—	282	885	437	—
Dinah-3	204	693	115	324	52	350
Vera-2	300	444	254	181	143	52
Gilda	243	407	183	580	100	376
Babe	191	782	217	198	196	726
Homogeneous Sample (N)	250	544	206	333	176	343
		9	8			

One important data source should be mentioned. The National Climatic Center's (Ashville, NC) magnetic tape deck 993 contains 12-h tropical storm movements for all ocean basins (CRUTCHER et al., 1978) for the period 1886–1975, and this file is continually being updated. CRUTCHER (1971a, 1971b) and CRUTCHER and QUINLAN (1971) used the bivariate normal elliptical distribution as a model for the statistics of the distributions of hurricane movements. CRUTCHER et al. (1978) deduced tropical storm accelerations based on the data contained in this vast file.

Forecasting Tropical Cyclone Recurvature

Most of the forecast errors associated with storm track prediction occur when the cyclones turn (or recurve). CHAN et al. (1980) studied tropical cyclones in the West Indies area for the period 1961–77 using compositing. These studies indicated that through an observation of certain parameters around a tropical cyclone (e.g. wind rotation, vertical wind shear between 200 and 900 mb, or a gradient of tropospheric mean temperature), better forecasts for 24–36 h ahead could be made. The basis for this statement is the fact that significant differences exist in the large-scale wind fields at 200-, 500-, and 900-mb levels for left-turning, straight-moving, and right-turning cyclones.

This study was limited to those cyclones west of 55° W and with maximum sustained winds of at least 18 m · s⁻¹. Three categories are defined as follows (Fig. 5.49):

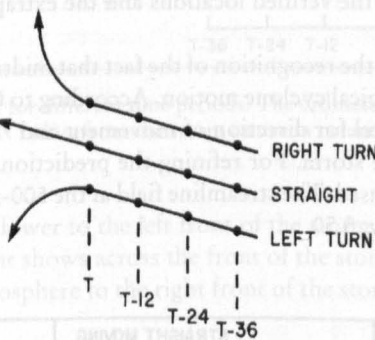


Fig. 5.49: Idealized picture of the three turn classes of tropical cyclones and of the time periods (hours) prior to the turn (CHAN et al., 1980)

Table 5.21: Average 24-h official tropical cyclone track forecast errors (km) issued by the National Hurricane Center, Miami. T, time when the storm begins to turn (CHAN et al., 1980)

Turn classification	T – 24	T	T + 24
Left turn (10 cases)	235	289	206
Straight (23 cases)	148	169	196
Right turn (22 cases)	178	324	239
Special right turn (16 cases)	148	417	245

Table 5.22: Directional deviation (degrees) of the mean 24-h forecast position made at turn time from the mean verifying position and the mean extrapolated track. A positive number means the forecast position is to the right of the verifying position of the extrapolated track (CHAN ET AL., 1980)

Turn classification	From mean extrapolated track	From mean verifying position
Left turn	21	50
Straight	9	11
Right turn	2	–38

Left-turning:

$$D(T + 12) - D(T) < -20$$

Straight-moving:

$$-10^\circ < D(T + 12) - D(T - 12) \tag{5.74}$$

Right-turning:

$$D(T + 12) - D(T) > 20^\circ$$

where, D is the direction of movement of the storm at a standard time T (00:00 or 12:00 GMT). A total of 16 left-turning, 33 straight-moving, and 28 right-turning storms were selected for this study.

The 24-h forecasts given by the National Hurricane Center were analysed for each case at three time periods: (a) 24 h before turn time, i.e. T - 24, (b) at turn time T, and (c) 24 h after turn time, i.e. T + 24. The forecast errors are listed in Tab 5.21. The special right-turn class is for those cases with an error greater than 350 km. The average directional deviation of the forecast locations from the verified locations and the extrapolated tracks are given in Table 5.22.

The basis for this study is the recognition of the fact that midtropospheric wind patterns have a strong influence on tropical cyclone motion. According to GEORGE and GRAY (1977), 500 mb is the best steering level for direction of movement and 700 mb is the best level for the speed of movement of the storm. For refining the prediction, flow fields at 900-, 700-, 500-, and 200-mb levels were used. The streamline field at the 500-mb level for the three classes of cyclones is shown in Fig. 5.50.

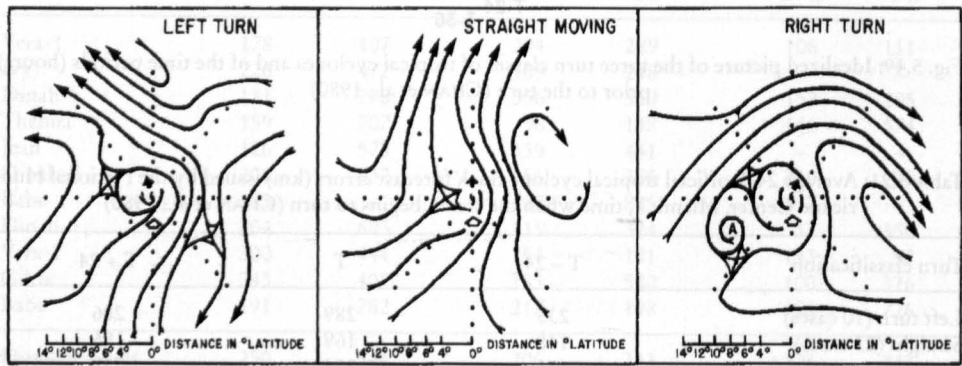


Fig. 5.50: Streamlines (500 mb) for the three turn cases shown in Fig. 5.49, at turn time. Open arrows indicate the instantaneous direction of storm motion. Solid arrows indicate the movement of the storm during the next 12 h (CHAN et al., 1980)

The vertical wind shear for these three classes is shown in Fig. 5.51. Here, V_p represents the wind component parallel to the track and V_N is the wind component perpendicular to the track. It can be seen from this diagram that usually the shear (i.e. V_p at 200 mb minus V_p at 900 mb) is greater than $5 \text{ m} \cdot \text{s}^{-1}$ for left-turning tropical cyclones, is in the range of -5 to $5 \text{ m} \cdot \text{s}^{-1}$ for straight-moving storms, and is less than $-5 \text{ m} \cdot \text{s}^{-1}$ for right-turning cyclones.

Sometimes it may not be possible to derive satellite winds at the 900- and 200-mb levels because of extensive cloud cover. In these situations, the satellite sounder (which can measure tropospheric difference) could be used. Generally, for left-turning storms the mean tro-

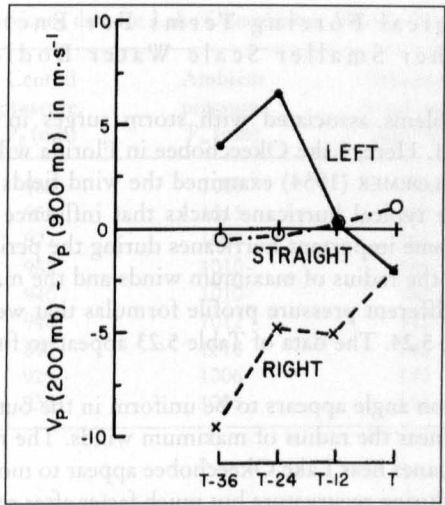


Fig. 5.51: Vertical wind shear for different time periods. The ordinate is the value of the average vertical wind shear within 7–11° radius from the storm centre in octants 1 and 5 (CHAN et al., 1980)

pospheric temperature is lower to the left front of the storm. For straight-moving storms a weak temperature gradient shows across the front of the storm. Right-moving storms indicate a relatively cold troposphere to the right front of the storm.

Project Stormfury

Project Storm fury is a scientific program aimed at studying the structure and dynamics of tropical cyclones and the possibility of modifying them, e.g. through cloud-seeding experiments (SHEETS and LASEUR, 1978). The project formally began in 1962, although some initial seeding experiments were done in 1961. These experiments are designed to effect a reduction in the maximum wind speeds in cyclones through changing the location of the energy released near the cyclone's centre. It is well known that the source of energy for a tropical cyclone is the latent heat released during convective overturning of the atmosphere. The active convective area in which updrafts of $10\text{--}20\text{ m} \cdot \text{s}^{-1}$ occur is less than 1 % of the area of the hurricane. Hence, one must modify only a small area of the hurricane to change its characteristics. The dynamics of the modification through seeding is explained by SHEETS and LASEUR (1978, p. 281) as follows:

Injection of silver iodide particles into the upper portion of these clouds causes the droplets to freeze, releasing the latent heat of fusion. This additional heat causes that portion of the cloud to be warmer and thereafter lighter than the surrounding air and thus triggers an increase in the ascending flow. As the air rises, it expands and cools, and water vapour condenses or sublimates, releasing considerably more latent heat. The result is that the seeded cloud grows to the outflow level, providing a new convective conduit that intercepts the inflowing low level air. The result is that a new eye wall is formed at a greater distance from the storm centre than the initial eye wall.

The tests on Hurricane Debbie of 1969 showed that winds could be reduced by 15–30 %. For experiments on typhoon modification, see World Meteorological Organization (1975) report No. 408.

5.3.3 Meteorological Forcing Terms For Enclosed Lakes and other Smaller Scale Water Bodies

Meteorological problems associated with storm surges in the Great Lakes were considered in section 7. 1. Here, Lake Okeechobee in Florida will be used as an example of an enclosed lake. SCHLOEMER (1954) examined the wind fields over Lake Okeechobee due to hurricanes. Some typical hurricane tracks that influence this lake are shown in Fig. 5.52. The dates of some important hurricanes during the period 1925–50 are listed in Table 5.23 together with the radius of maximum winds and the maximum wind speed and the pressure field. Ten different pressure profile formulas that were used by SCHLOEMER (1954) are listed in Table 5.24. The data of Table 5.23 appear to fit the second equation of Table 5.24.

The average deflection angle appears to be uniform in the outer portion of the storm, and it decreased rapidly near the radius of maximum winds. The most common deflection angle was 35° . The hurricanes near Lake Okeechobee appear to move with a speed of about $16 \text{ km} \cdot \text{h}^{-1}$ prior to and during recurvature but much faster after recurvature. However, the maximum winds appear to occur before recurvature. Hurricane winds over lake Okeechobee for a synthesized storm at 0, 1 and 2 h are shown in Fig. 5.53. Notice the changes in pattern that could occur even in a 1-h time interval.

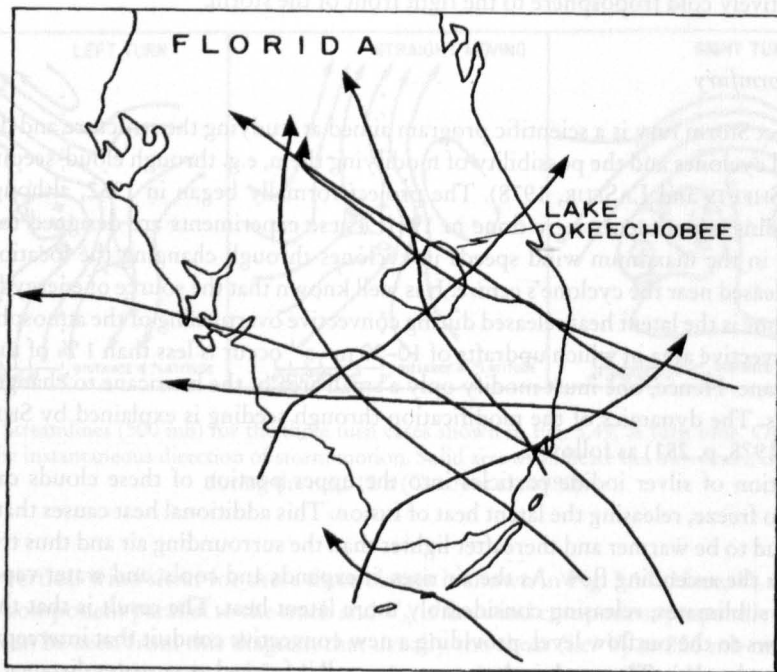


Fig. 5.52: Typical hurricane tracks over and near Lake Okeechobee, Florida (SCHLOEMER, 1954)

Table 5.23: Hurricane data for Lake Okeechobee, Florida (SCHLOEMER, 1954)

Date of hurricane	Central pressure, P ₀ (mb)	Ambient pressure, P _∞ (mb)	Maximum wind speed (km · h ⁻¹)	Radius of maximum winds (km)
Sept. 18, 1926	960	1009	199	28
Sept. 16–17, 1928	955	1015	185	43
Sept. 2–3, 1935	977	1008	163	27
Sept. 15–16, 1945	962	1010	185	24
Sept. 17, 1947	940	1010	180	37
Sept. 21–22, 1948	946	1012	140	30
Oct. 5, 1948	892	1010	142	51
Aug. 26–27, 1949	929	1006	140	37
Oct. 17–18, 1950	935	1005	117	21

Table 5.24: Ten different forms used to approximate $(P - P_0)/(P_\infty - P_0)$ in a hurricane. Here, P is the pressure at a distance r from the centre, P₀ is the central pressure, and P_∞ is the ambient pressure. Parameters n, i, and j must be determined empirically (SCHLOEMER, 1954)

(1) $1 - e^{-nri}$	(6) $\frac{2}{\pi} \arctan \frac{1}{nr^i}$
(2) e^{-n/r^i}	(7) $\frac{2}{\pi} \operatorname{arccot} \frac{1}{nr^i}$
(3) $\frac{1}{1 + 1/nr^i}$	(8) $\frac{2}{\pi} \operatorname{arcsec} (1 + nr^i)$
(4) $\frac{1}{(1 + 1/nr^j)^j}$	(9) $\frac{2}{\pi} \operatorname{arccsc} (1 + 1/nr^j)$
(5) $\frac{1}{(1 + 1/nr^i)^j}$	(10) $\tanh nr^i$

Earlier it was mentioned that tropical cyclones form over all the tropical oceans except in the South Atlantic and in the South Pacific east of 140° W. The highest frequency of tropical cyclones occurs in the western Pacific, although maximum damage has occurred on the coasts surrounding the Bay of Bengal. Indeed one may say that tropical cyclones and their

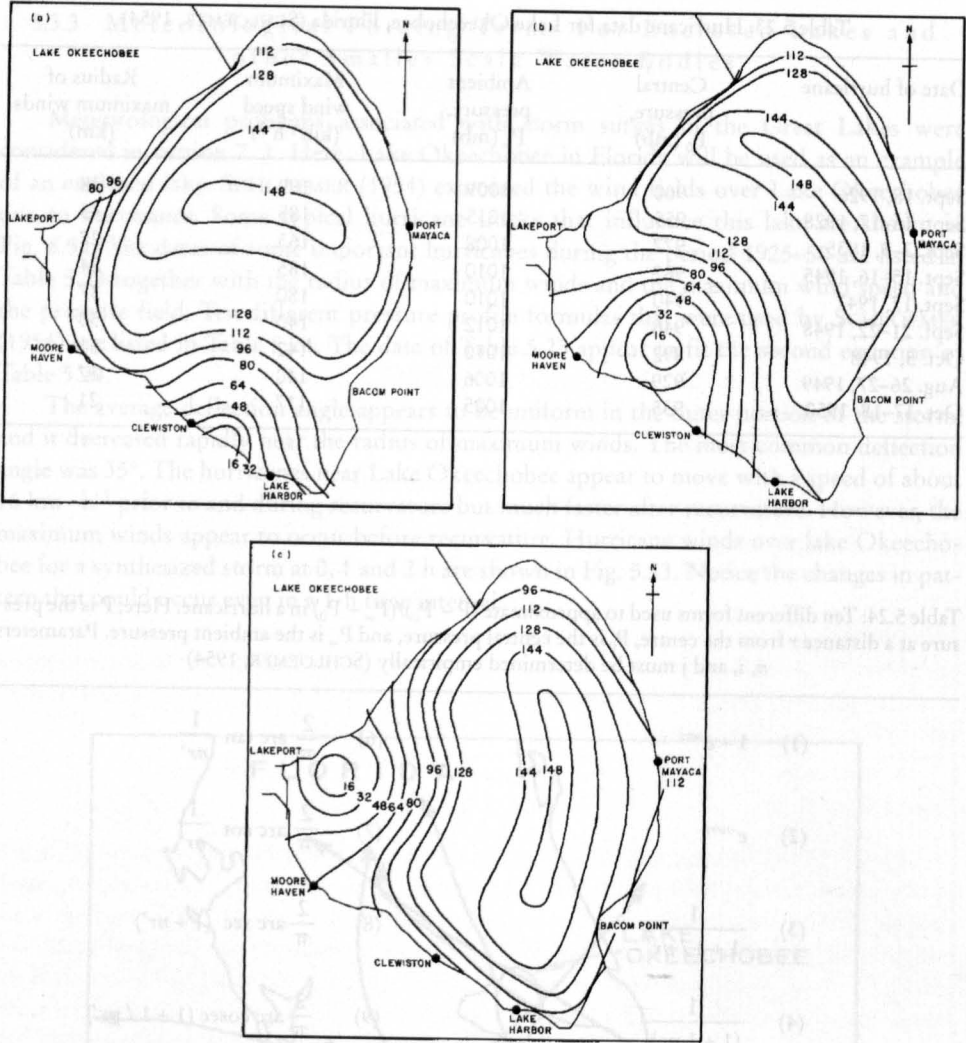


Fig. 5.53: Wind field (kilometers per hour) for a synthesized hurricane over Lake Okeechobee at (a) 0 h, (b) 1 h, and (c) 2 h after a specified zero time (SCHLOEMER, 1954)

Fig. 5.54: Typical hurricane tracks over and near Lake Okeechobee, Florida (SCHLOEMER, 1954)

5.4 Cyclones of the Pacific Ocean

Most of the damage from storm surges on the coast of the Pacific Ocean results from tropical storms. Hence, these will be emphasized in this section. Note that a storm surge is a rare event on the Pacific coasts of Canada and the United States (with the exception of Alaska); along these coasts, wind waves and swell are of primary importance.

Table 5.25: Record number of storms by basin based on data from 1968–1989 (1968/69 to 1989/90) for the Southern Hemisphere (NEUMANN, 1993)

Basin	Tropical Strom or stronger (greater than 17 m/s sustained winds)			Hurricane / Typhoon / Severe Tropical Cyclone (greater than 33 m/s sustained winds)		
	Most	Least	Average	Most	Least	Average
Atlantik *	18	4	9.7	12	2	5.4
NE Pacific	23	8	16.5	14	4	8.9
NW Pacific	35	19	25.7	24	11	16.0
N Indian	10	1	5.4	6	0	2.5
SW Indian	15	6	10.4	10	0	4.4
Aus SE Indian	11	1	6.9	7	0	3.4
Aus SW Pacific	16	2	9.0	11	2	4.3
Globally	103	7.5	83.7	65	34	44.9

* Note that the data include subtropical storms in the Atlantic basin numbers.

Table 5.26: Monthly average number of storms per year for each major ocean basin. T, tropical storms only; H, hurricanes only. For the North Indian Ocean, replace the term hurricane with cyclone (winds >– 89 kin -h-'). –, zero (CRUTCHER and QUAYLE, 1974)

Month	North Atlantic		Eastern North Pacific		Western North Pacific		Southwest Pacific and Australian area		Southwest Indian Ocean		North Indian Ocean	
	T	H	T	H	T	H	T	H	T	H	T	H
Jan.	–	–	–	0.2	0.3	2.7	0.7	2.0	1.3	0.1	–	–
Feb.	–	–	–	0.3	0.2	2.8	1.1	2.2	1.1	–	–	–
Mar.	–	–	–	0.3	0.2	2.4	1.3	1.7	0.8	–	–	–
Apr.	–	–	–	0.2	0.7	1.3	0.3	0.6	0.4	0.1	0.1	–
May	0.1	–	0.3	0.4	0.9	0.3	–	0.2	–	0.3	0.5	–
June	0.4	0.3	1.5	0.6	0.5	1.2	0.2	–	–	–	0.5	0.2
July	0.3	0.4	2.8	0.9	1.2	2.7	–	0.1	–	–	0.5	0.1
Aug.	1.0	1.5	2.3	2.0	1.8	4.0	–	0.1	–	–	0.4	–
Sept.	1.5	2.7	2.3	1.8	1.5	4.1	–	–	–	–	0.4	0.1
Oct.	1.2	1.3	1.2	1.0	1.0	3.3	0.1	–	0.3	–	0.6	0.4
Nov.	0.4	0.3	0.3	–	0.8	2.1	0.4	0.3	0.3	–	0.5	0.6
Dec.	–	–	–	0.6	0.7	1.5	0.5	0.8	0.5	0.3	0.2	–

Earlier it was mentioned that tropical cyclones form over all the tropical oceans except in the South Atlantic and in the South Pacific east of 140° W. The highest frequency of tropical cyclones occurs in the western Pacific, although maximum damage has occurred on the coasts surrounding the Bay of Bengal. Indeed one may say that tropical cyclones and their

associated storm surges together are probably the most devastating natural phenomena, even more so than earthquakes.

The number of tropical storms and hurricanes is listed by most, least and average for the period 1969–1989 and by month for various ocean basins in Table 5.25 and Table 5.26. It can be seen that the maximum frequency of tropical storms and Hurricanes occurs in the western part of the North Pacific Ocean during the months of August and September. The preferred tropical cyclone tracks over the globe are shown in Fig. 5.54. Again, it can be seen that the tracks in the Pacific Ocean and Indian Ocean have more fine structure than those in the Atlantic Ocean. Contours of the speed of movement of tropical storms for various ocean basins are shown in Fig. 5.55. Maximum values of 35 knots ($65 \text{ km} \cdot \text{h}^{-1}$) occur in the western North Pacific, with maximum values of 30 knots ($56 \text{ km} \cdot \text{h}^{-1}$) in the Atlantic, and with maximum values of 27.5 ($51 \text{ km} \cdot \text{h}^{-1}$) in the eastern edge of the South Indian Ocean. In the following subsections, certain characteristics of tropical cyclones in the eastern North Pacific, central North Pacific, and western North Pacific will be detailed. There are shown for every region special examples and not the whole research.

5.4.1 Characteristics of Tropical Cyclones in the Eastern North Pacific

This discussion will be based on the tropical cyclone seasons of 1976, 1977 and 1978 (GUNTHER, 1977, 1978, 1979). For the 1976 season, tropical cyclone activity began on June 1 and ended on October 29. The season was average in the sense that there were eight hurricanes, six tropical storms, and four tropical depressions. The 1977 season began on May 25 and ended on October 23. Thus, the length of the 1977 season was 152 d whereas in 1976 it was 150 d. The total number of tropical storms in 1977 was 17 compared with 18 in 1976. However, in 1977 only 47 % of the storms reached hurricane intensity. Note that the number of tropical cyclones reaching storm or hurricane intensity in 1977 was 47 % less than the average for the period 1966–76. For the 1976 season, the highest sustained wind speed was 125 knots ($231 \text{ km} \cdot \text{h}^{-1}$) whereas for the 1977 season it was 90 knots ($167 \text{ km} \cdot \text{h}^{-1}$).

1978, the season began on May 30 and ended on October 20, with duration of 144 d. Although the 1978 season was 8 d shorter than the 1977 season, there was an increase of 24 % in cyclone activity. The number of cyclones reaching storm or hurricane intensity was 86 % in 1978 compared with 47 % in 1977. The highest sustained wind speed in the 1978 season was 120 knots ($222 \text{ km} \cdot \text{h}^{-1}$).

The first tropical cyclone to hit southern California since 1939 was Hurricane Kathleen in 1976. In the 1977 season, Hurricane Doreen struck again and in the 1978 season Hurricane Norman reached the coast. Though none of these three hurricanes caused any storm surge activity on the California coast, the heavy rains associated with these caused extensive damage.

During the hurricane season bulletins are issued four times per day from the Eastern Pacific Hurricane Center in San Francisco. The number of eastern North Pacific tropical storms reaching hurricane intensity is given in Table 5.27. The tracks of Hurricanes Kathleen of September 1976 and Doreen of August 1977 are shown in Fig. 5.56. All the tropical cyclones during 1977 did not reach land, as they were dissipated over the ocean. Hence, the damage in the 1977 season was less than in the 1976 season (during this season, several hurricanes moved onshore). In the 1978 season, only three cyclones moved onshore. Hurricane statistics prior to 1966 were not used in this study because satellite coverage was not adequate prior to 1966 and some hurricanes might have been missed.

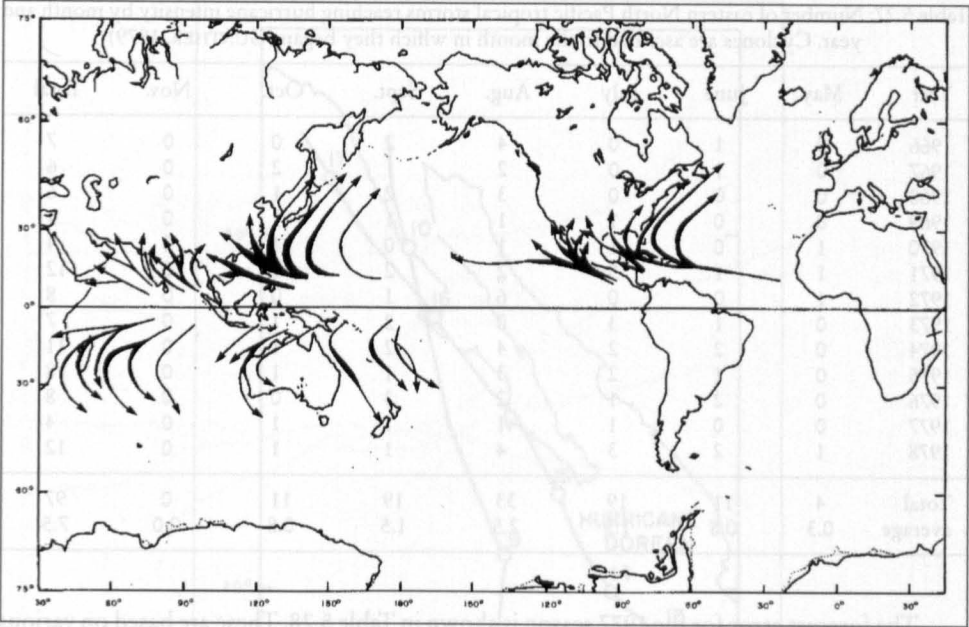


Fig. 5.54: Preferred annual tropical cyclone paths. Arrow widths are proportional to storm frequencies along indicated paths (CRUTCHER and QUAYLE, 1974)

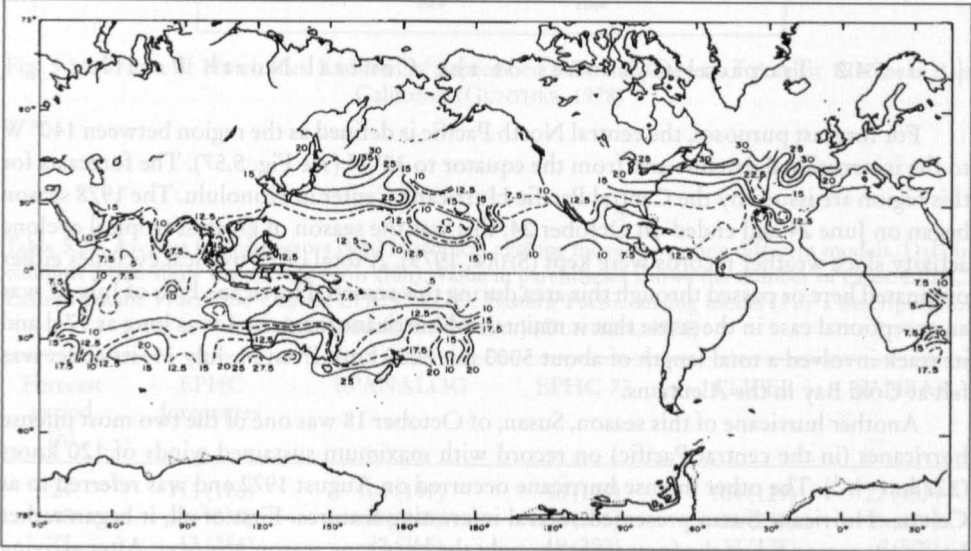


Fig. 5.55: Average (for annual data) speeds (knots) of storm movement (1 knot = $1852 \text{ km} \cdot \text{h}^{-1}$) (CRUTCHER and QUAYLE, 1974)

Table 5.27: Number of eastern North Pacific tropical storms reaching hurricane intensity by month and year. Cyclones are ascribed to the month in which they began (GUNTHER, 1979)

Year	May	June	July	Aug.	Sept.	Oct.	Nov.	Total
1966	0	1	0	4	2	0	0	7
1967	0	1	0	2	1	2	0	6
1968	0	0	0	3	2	1	0	6
1969	0	0	1	1	1	1	0	4
1970	1	0	1	1	0	1	0	4
1971	1	1	5	2	2	1	0	12
1972	1	0	0	6	1	0	0	8
1973	0	1	3	0	2	1	0	7
1974	0	2	2	4	2	1	0	11
1975	0	1	2	3	1	1	0	8
1976	0	2	1	2	3	0	0	8
1977	0	0	1	1	1	1	0	4
1978	1	2	3	4	1	1	0	12
Total	4	11	19	33	19	11	0	97
average	0.3	0.8	1.5	2.5	1.5	0.8	0.0	7.5

The forecast error for the 1977 season is shown in Table 5.28. These are based on various computer models available at the National Hurricane Center in Miami. In this table, EPI-IC stands for the Eastern Pacific Hurricane Center, CLIPER is a simulated analog model, EPHC77 is a statistical synoptic model, EPRANALOG is an analog model, and SANBAR is a barotropic model. Of these four computer models, EPHC77 gave the best results, and these were subjectively improved by the EPI-IC forecasters.

5.4.2 Tropical Cyclones of the Central North Pacific

For forecast purposes, the central North Pacific is defined as the region between 140° W to the international dateline and from the equator to 35° N (see Fig. 5.57). The forecasts for this region are issued by the Central Pacific Hurricane Center in Honolulu. The 1978 season began on June 24 and ended on October 24; this was the season of greatest tropical cyclone activity since weather records were kept (SHAW, 1979). A total of 13 tropical cyclones either originated here or passed through this area during this season. Hurricane Fico of July 17 was an exceptional case in the sense that it maintained hurricane intensity for as long as 17 d and its track involved a total length of about 5000 mi (8000 km). Even on July 31, its effect was felt at Cold Bay in the Aleutians.

Another hurricane of this season, Susan, of October 18 was one of the two most intense hurricanes (in the central Pacific) on record with maximum sustained winds of 120 knots (222 km · h⁻¹). The other intense hurricane occurred on August 1972 and was referred to as Celeste. Hurricane Susan presented several interesting features. First of all, it began rather late in the season when the forecasters thought the hurricane season was over. After arriving 220 mi (354 km) southeast of the big island of Hawaii, it abruptly turned southwestward and dissipated rapidly. The central pressure rose more than 50 mb in 24 h.

Hurricane Gilma of July 22 was also somewhat unusual in the sense that it covered an area as large as 3 × 10⁵ mi² (7.8 × 10⁵ km²). Hurricanes for the 1978 season in the central Pacific are summarized in Tab 5.29.

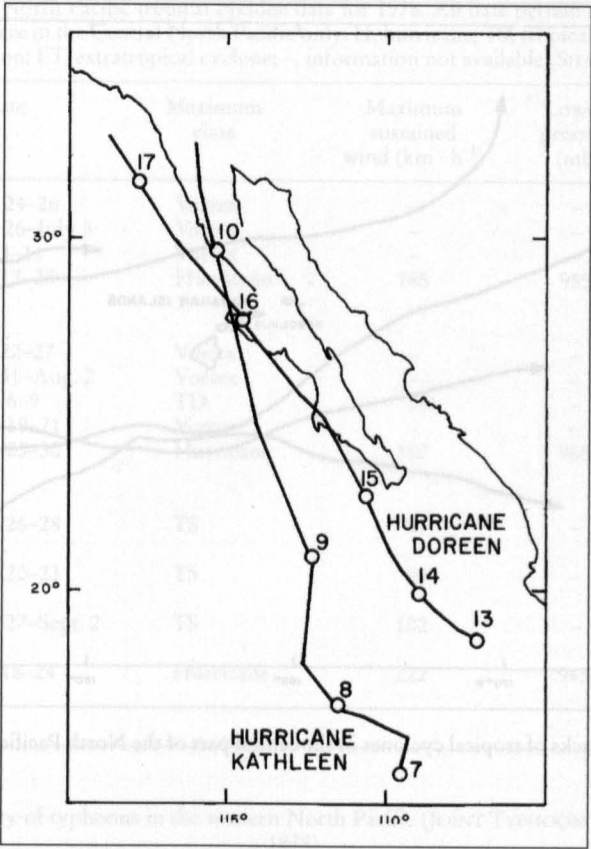


Fig. 5.56: Tracks of Hurricanes Kathleen of September 1976 and Doreen of August 1977 near Baja California (GUNTHER, 1978)

Table 5.28: Average forecast errors (km) in tropical cyclone movement using different models. Data in columns 2 to 6 show the average error (lun). Value in parentheses shows the number of cases. EPI4C, Eastern Pacific Hurricane Center; EPANALOG, Eastern Pacific analog model (For a description of these models, see the text.) (GUNTHER, 1978)

Forecast period (h)	EPHC forecasters	EPANALOG	EPHC-77	CLIPER	SANBAR
24	113 (126)	104 (141)	96 (129)	104 (129)	22 (137)
48	44 (239)	56 (265)	50 (255)	56 (255)	15 (271)
72	13 (284)	22 (365)	19 (292)	22 (378)	6 (508)

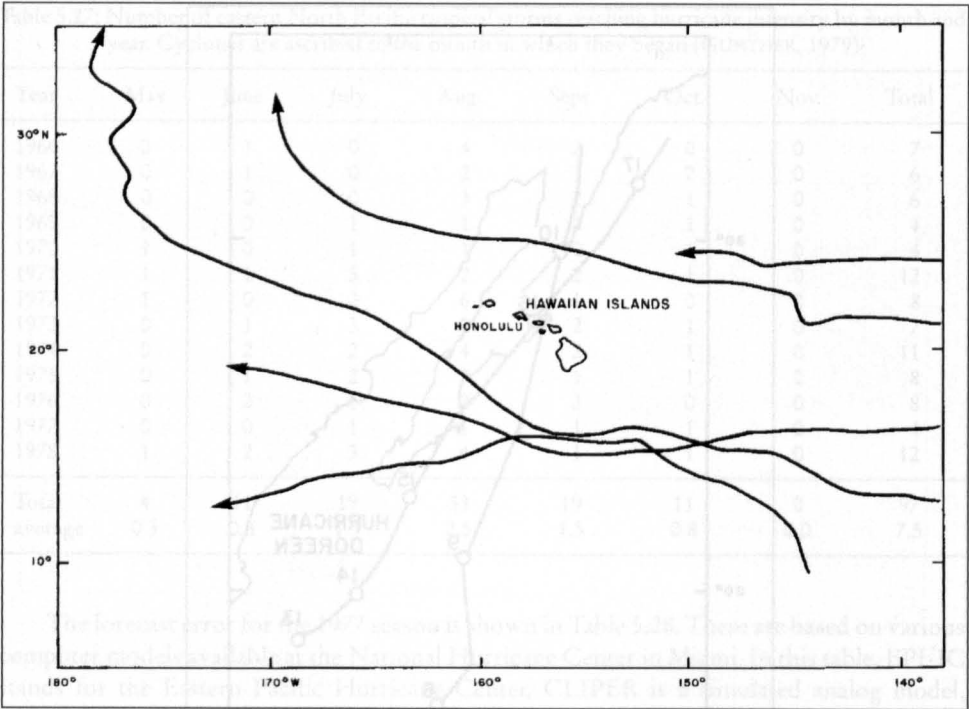


Fig. 5.57: Typical tracks of tropical cyclones in the central part of the North Pacific Ocean (SHAW, 1979)

5.4.3 Typhoons of the Western North Pacific

The Joint Typhoon Warning Center for the western North Pacific was set up at Guarn in 1959. The frequency of typhoons by month and year is listed in Table 5.30 and the western North Pacific tropical cyclones for the season of 1977 are listed in Table 5.31. The 1977 season began on March 13 and ended in January 1978. The 1978 season officially began on January 8 and ended on November 30. It can be seen that in the western North Pacific, typhoons can and do occur at any time of the year. In this respect this ocean basin is different from the central North Pacific, eastern North Pacific, and North Atlantic Ocean basins where the tropical cyclone season does not span the full year.

The seasons of 1977 and 1978 (JOINT TYPHOON WARNING CENTER, 1978, 1979) will be compared. The season of 1977 had the lowest number of tropical cyclones since 1959. Of a total of 21, 2 dissipated as depressions, 8 peaked out as tropical storms, and the remaining 11 matured into hurricanes. The monsoon systems of the Indian subcontinent and Southeast Asia appear to have some influence on tropical cyclones in the western North Pacific. During the 1977 season there were only 12 multiple storm days (a multiple storm day is one during which there is more than one tropical cyclone in the region). In 1970 and 1975, at certain times there were three or more tropical cyclones simultaneously. Storms with long durations could occur. Typhoon Kim of November 6, 1977, spanned 12 d. In this season, Typhoon Babe was classified as a super typhoon.

Table 5.29: Central North Pacific tropical cyclone data for 1978. All data pertain to the period during which the storms were in the Central North Pacific only. H, hurricane; TS, tropical storm; TD, tropical depression; ET, extratropical cyclone; -, information not available (SHAW, 1979)

Name of storm	Date	Maximum class	Maximum sustained wind (km · h ⁻¹)	Lowest pressure (mb)	Total hours observed
Bud	June 24–26	Vortex	–	–	48
Carlotta	June 26–July 3	Vortex	–	–	168
Daniel	July 3–11	Vortex	–	–	192
Fico	July 17–28	Hurricane	185	955	225 (H) 15 (TS) 36 (ET)
Gilma	July 22–27	Vortex	–	–	144
Hector	July 31–Aug. 2	Vortex	–	–	60
TD-10	Aug. 6–9	TD	56	–	84
Iva.	Aug. 19–21	Vortex	–	–	54
John	Aug. 23–30	Hurricane	167	965	48 (H) 72 (TS) 48 (TD)
Kristy	Aug. 26–28	TS	93	–	18 (TS) 45 (TD)
Lane	Aug. 20–23	TS	93	–	27 (TD) 66 (TS)
Miriam	Aug. 27–Sept. 2	TS	102	–	72 (TS) 6 (TD)
Susan	Oct. 18–24	Hurricane	222	945–954	81 (H) 30 (TS) 24 (TD)

Table 5.30: Frequency of typhoons in the western North Pacific (JOINT TYPHOON WARNING CENTER, 1978)

Year	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec	Total
1954–58 (average)	0.4	0.1	0.3	0.4	0.7	1.1	2.0	2.9	3.2	2.4	2.0	0.9	16.3
1959	0	0	0	1	0	0	1	5	3	3	2	1	20
1960	0	0	0	1	0	2	2	8	0	4	1	1	19
1961	0	0	1	0	2	1	3	3	5	3	1	1	20
1962	0	0	0	1	2	0	5	7	2	4	3	0	24
1963	0	0	0	1	1	2	3	3	3	4	0	2	19
1964	0	0	0	0	2	2	6	3	5	3	4	1	26
1965	1	0	0	1	2	2	4	3	5	2	1	0	21
1966	0	0	0	1	2	1	3	6	4	2	0	1	20
1967	0	0	1	1	0	1	3	4	4	3	3	0	20
1968	0	0	0	1	1	1	1	4	3	5	4	0	20
1969	1	0	0	1	0	0	2	3	2	3	1	0	13
1970	0	1	0	0	0	1	0	4	2	3	1	0	12
1971	0	0	0	3	1	2	6	3	5	3	1	0	24
1972	1	0	0	0	1	1	4	4	3	4	2	2	22
1973	0	0	0	0	0	0	4	2	2	4	0	0	12
1974	0	0	0	0	1	2	1	2	3	4	2	0	15
1975	1	0	0	0	0	0	1	3	4	3	2	0	14
1976	1	0	0	1	2	2	3	0	4	1	0	0	14
1977	0	0	0	0	0	0	3	0	2	3	2	1	11
1959–77 (average)	0.3	0.1	0.1	0.7	0.9	1.1	2.8	3.6	3.2	3.2	1.6	0.5	18.3

Table 5.31: Tropical cyclones in the western North Pacific for the season of 1977. TV, typhoon; TS, tropical storm; STY, supertyphoon (JOINT TYPHOON WARMING CENTER, 1978)

Name of typhoon	Period of warning	Intensity	Maximum surface wind ($\text{km} \cdot \text{h}^{-1}$)	Minimum observed sea level pressure (mb)
Patsy	Mar. 23–31	TS	93	981
Ruth	June 14–17	TS	111	980
Sarah	July 16–21	TY	139	970
Thelma	July 21–26	TY	157	957
Vera	July 28–Aug. 1	TY	204	926
Wanda	July 31–Aug. 4	TS	83	986
Amy	Aug. 20–23	TS	74	990
Babe	Sept. 2–10	STY	241	906
Carla	Sept. 3–5	TS	65	994
Dinah	Sept. 14–23	TY	139	964
Emma	Sept. 15–20	TS	111	966
Freda	Sept. 23–25	TS	102	997
Gilda	Oct. 3–10	TY	130	968
Harriet	Oct. 16–20	TS	102	984
Ivy	Oct. 21–27	TY	167	945
Jean	Oct. 28–31, Nov. 2–3	TY	120	972
Kim	Nov. 6–17	TY	232	916
Lucy	Nov. 28–Dec. 7	TY	213	919
Maïy	Dec. 20–Jan. 3	TY	185	947

One important feature of the typhoons in the western North Pacific is that they could have rather erratic tracks and loops (usually the loops occur when the steering currents are weak). The 1978 season had about an average number of tropical cyclones. However, there were several surprises. Ten storms and typhoons had erratic tracks. Typhoon Carmen was almost stationary for 3 d. Typhoon Faye's track had a large anticyclonic loop and then it deepened explosively (surface central pressure decreased by 18 mb in just 6 h). Typhoon Trix was the most ill-behaved of all. Storms Hester and Phyllis attained speeds of movement of 40 and 50 knots (74 and $93 \text{ km} \cdot \text{h}^{-1}$), respectively, after recurvature in their extratropical transition. Typhoons Virginia and Mamie were so compact in size (but not in intensity) that they were called midget typhoons. Typhoon Virginia traveled farthest north (to 42°N) still behaving like a tropical cyclone. Super typhoon Rita covered an amazing distance of 4142 mi (6669 km) and is second only to Typhoon Sarah of 1976, which traveled 4499 mi (8000 km). Some typical tracks of typhoons in the western North Pacific are shown in Fig. 5.58.

Northwest Pacific Ocean

LAPPO and ROZHDESTVENSKIY (1977, 1979) studied the energy transferred to the ocean from a typhoon via the storm surge. They referred to the storm surge as meteorological ocean tides. In their calculations they ignored the influence of the wind but included the effect of the atmospheric pressure. When the cyclone is stationary, the energy transferred to the ocean is equal to the potential energy associated with the change in the sea level. For a moving cyclone, however, there is an additional transfer of kinetic energy.

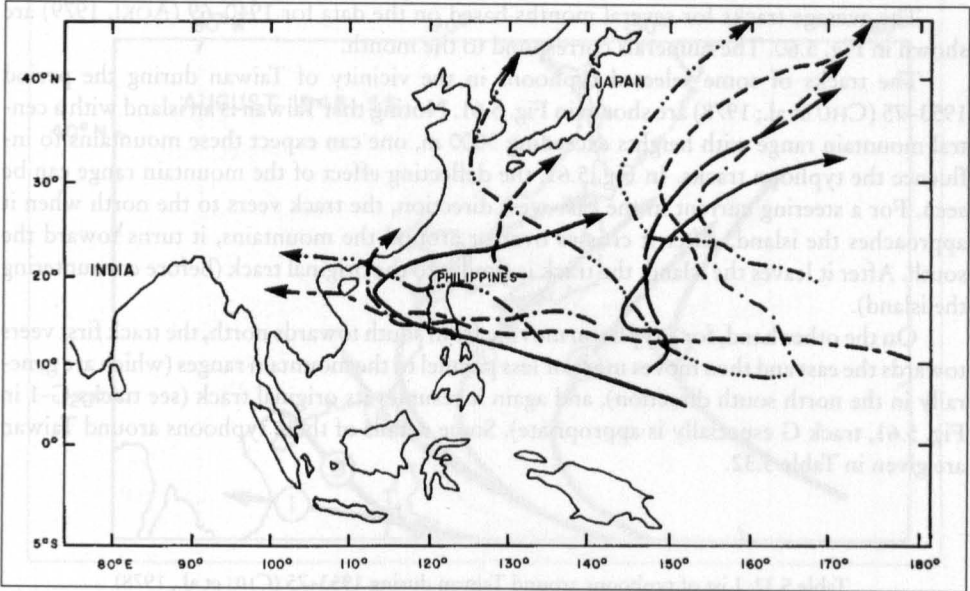


Fig. 5.58: Typical tracks of tropical cyclones in the western North Pacific (JOINT TYPHOON WARNING CENTER, 1977, 1978)

LAPPO and ROZHDESTVENSKIY (1977) formulated this problem along the lines of the classical quasi-stationary Proudman problem (PROUDMAN, 1929). For a plane pressure disturbance, with a pressure deficit of 40 mb, a cross-sectional diameter of the cyclone of 10^3 km, and the distance traveled as 5×10^3 km, these authors gave the following values for an average cyclone (Joules):

- Total energy of cyclone $= E_1 = 5 \times 10^{17}$ to 8×10^{17}
- Kinetic energy $= E_2 = 5 \times 10^{16}$ to 8×10^{16}
- Mechanical energy imparted to the ocean (ignoring wind stress) $= E_l = 5 \times 10^{15}$
- Potential energy of the storm surge created $= E_0 = 10^{15}$

Tropical Cyclone Tracks Near Japan, Taiwan And The Philippines

JAMISON (1956) described the average tracks of typhoons in this region for the month of August based on 11 yr of data (1945–55). These tracks are illustrated in Fig. 5.59. During this period there was a total of 43 typhoons, of which 15 had rather erratic tracks (not known here). The number along each track is the number of typhoons that occurred during this 11-yr. period. Note that the lowest frequency is for the track that crosses Vietnam and the highest is for the Philippines area and continuing towards the Gulf of Tonkin. The number of tropical cyclones that traveled over Korea and Japan during this period was five.

The average tracks for several months based on the data for 1940–69 (AOKI, 1979) are shown in Fig. 5.60. The numerals correspond to the month.

The tracks of some selected typhoons in the vicinity of Taiwan during the period 1953–75 (CHU et al.; 1978) are shown in Fig. 5.61. Noting that Taiwan is an island with a central mountain range with heights exceeding 3000 m, one can expect these mountains to influence the typhoon tracks. In Fig. 5.61, the deflecting effect of the mountain range can be seen. For a steering current in the east-west direction, the track veers to the north when it approaches the island. After it crosses over or around the mountains, it turns toward the south. After it leaves the island, the track is similar to the original track (before encountering the island).

On the other hand, for a typhoon moving from south towards north, the track first veers towards the east and then moves more or less parallel to the mountain ranges (which are generally in the north south direction), and again it resumes its original track (see tracks G-1 in Fig. 5.61, track G especially is appropriate). Some details of these typhoons around Taiwan are given in Table 5.32.

Table 5.32: List of typhoons around Taiwan during 1953–75 (CHU et al., 1978)

Name of typhoon	Date	Maximum wind speed (km · h ⁻¹)	Name of typhoon	Date	Maximum wind speed (km · h ⁻¹)
Judy	June 1953	74–111	Gilda	Nov. 1967	148–185
Kit	July 1953	204	Elsie	Sept. 1969	194
Thelma	Apr. 1956	157	Betty	Aug. 1972	157–222
Trix	Aug. 1960	204–222	Joan	Aug. 1973	56–83
Agnes	Aug. 1960	74–102	Nora	Oct. 1973	111–176
Pamela	Sept. 1961	222–278	Jean	July 1974	93
Sally	Sept. 1961	130	Wendy	Sept. 1974	93
Wendy	July 1963	185–250	Nina	Aug. 1975	250
Dinah	June 1965	74–241	Betty	Sept. 1975	157–167
Nora	Aug. 1967	111–120	Elsie	Oct. 1975	222–259

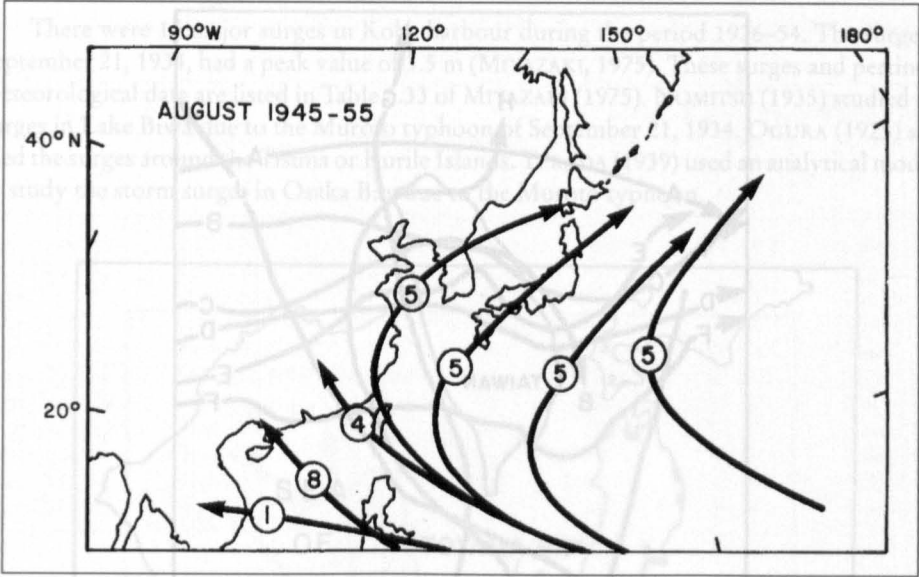


Fig. 5.59: Mean typhoon tracks and frequency (over an 11-yr period) for August in the western North Pacific (JAMISON, 1956)

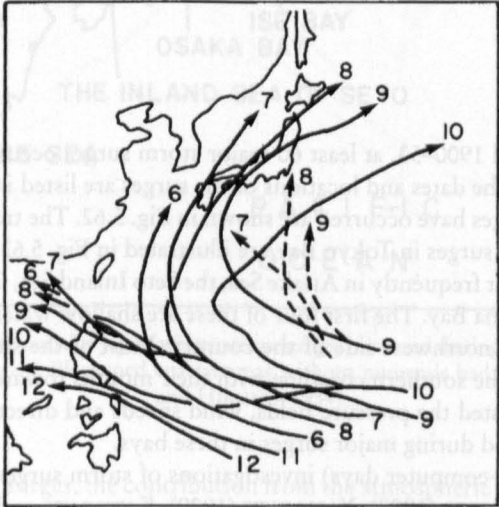


Fig. 5.60: Monthly mean tracks of tropical cyclones in the western North Pacific. Numbers refer to the months (AOKI, 1979)

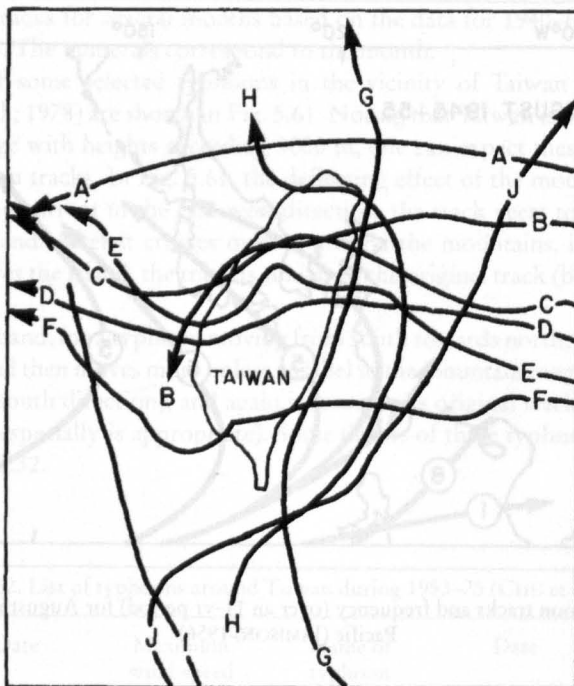


Fig. 5.61: Typical tracks of typhoons around Taiwan. A, Trix, 1960; B, Agnes, 1960; C, Pamela, 1961; D, Nora, 1967; E, Nina, 1975; F, Betty, 1975; G, Dinah, 1965; H, Wendy, 1974; I, Nora, 1973; J, Judy, 1953 (CHU et al., 1978)

Japan

During the period 1900–53, at least 60 major storm surges occurred in Japan (WADATI and HIRONO, 1954). The dates and locations of the surges are listed in Table 5.33. The locations where major surges have occurred are shown in Fig. 5.62. The tracks of some of the typhoons that generated surges in Tokyo Bay are illustrated in Fig. 5.63.

Storm surges occur frequently in Ariake Sea, the Seto Inland Sea, Osaka Bay, Tokyo Bay, Suruga Bay, and Toyama Bay. The first four of these are shallow water bodies; only Toyama Bay is situated on the northwest side of the country. Most of the shallow water bodies in Japan are situated on the southern coastline with their mouths towards southwest. WADATI and HIRONO (1954) listed the pressure fields, wind speeds and directions, damage, and the number of people killed during major surges in these bays.

For early (i.e. pre-computer days) investigations of storm surges in and around Japan, see TERADA and YAMAGUTI (1928), YAMAGUTI (1929), KAWABATA and FUJITO (1951), HON-SYŪ (1932), and UNOKI (1959). TERADA (1912) and NAKANO (1949) investigated the secondary undulations associated with storm surges in Japan. RABE and BRAND (1980) studied the extreme sea states associated with typhoons.

MIYAZAKI (1975) studied the characteristics of storm surges along the coast of Japan. Some of the major surges (that exceeded 2 m) during the period 1900–73 are listed in Table 5.33. The damage associated with some selected surges is listed in Table 5.34.

There were 15 major surges in Kobe harbour during the period 1926–54. The surge of September 21, 1934, had a peak value of 3.5 m (MIYAZAKI, 1975). These surges and pertinent meteorological data are listed in Table 5.33 of MIYAZAKI (1975). NOMITSU (1935) studied the surges in Lake Biwa due to the Muroto typhoon of September 21, 1934. OGURA (1925) studied the surges around the Tisima or Kurile Islands. TERADA (1939) used an analytical model to study the storm surges in Osaka Bay due to the Muroto typhoon.

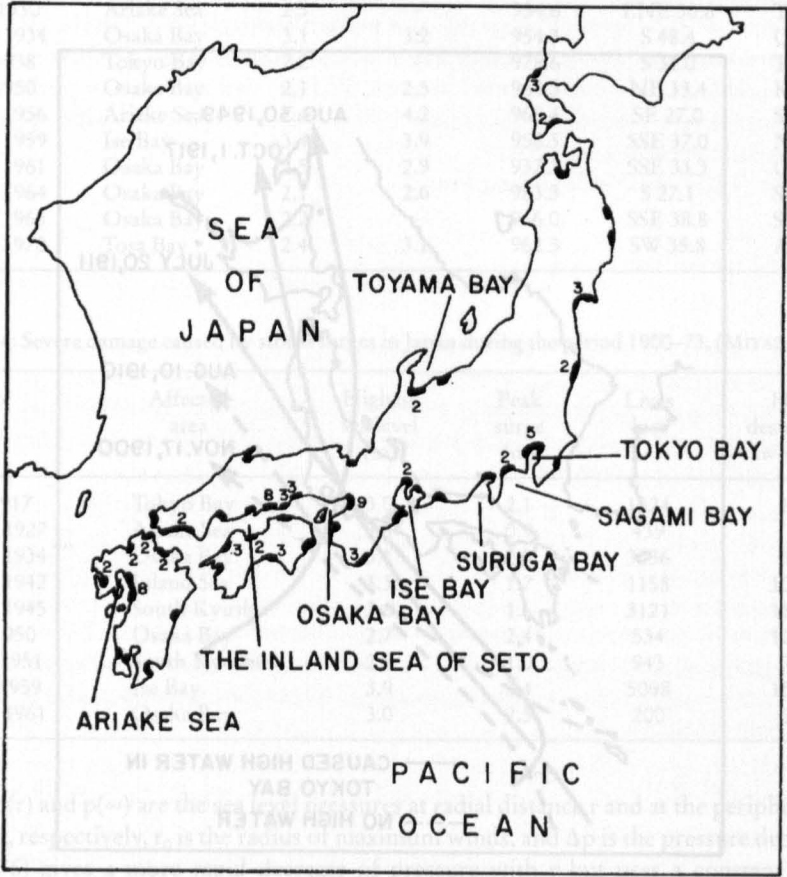


Fig. 5.62: Locations on the coast of Japan where storm surges occurred during 1900–53 (numerals indicate number of occurrences). Blackened coastal areas without numerals had one occurrence (WADATI and HIRONO, 1954)

In Japanese storm surges, the contribution from the atmospheric pressure gradients was at most 15 %. In the numerical model of ISOZAKI (1970a, 1970b, 1970c) the following pressure field distributions were specified:

$$p(r) = p(\infty) - \frac{\Delta p}{\left[1 + \left(\frac{r}{r_0}\right)^2\right]^{1/2}} \tag{5.75}$$

or

$$p(r) = 1010 - \frac{\Delta p}{\left(1 + \frac{r}{r_0}\right)^2} \quad (5.76)$$

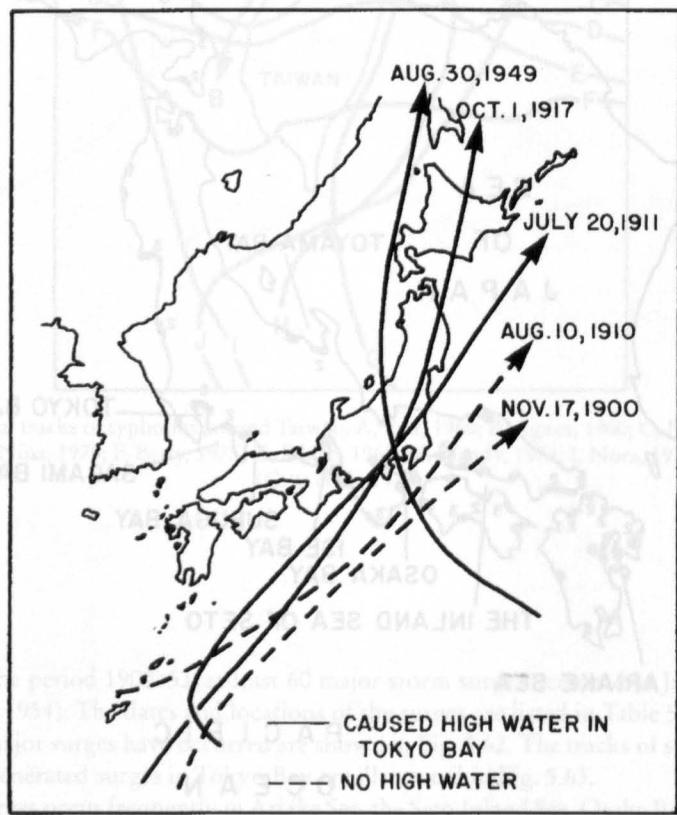


Fig. 5.63: Tracks of typhoons that passed near Tokyo Bay (WADATI and HIRONO, 1954)

Table 5.33: Storm surges in Japan during the period 1900–73 with maximum amplitudes in excess of 2 m; highest level includes surge and tide (MIYAZAKI, 1975)

Date	Affected area	Peak surge (m)	Highest level (m)	Meteorological extreme values		
				Central pressure (mb)	Wind (m · s ⁻¹)	Location
Oct. 1, 1917	Tokyo Bay	2.3	3.1	950.4	SSE 40.0	Tokyo
July 18, 1930	Ariake Sea	2.5	-	954.6	ENE 30.6	Tomie
Sept. 21, 1934	Osaka Bay	3.1	3.2	954.3	S 48.4	Osaka
Sept. 1, 1938	Tokyo Bay	2.2	-	978.6	S 31.0	Tokyo
Sept. 3, 1950	Osaka Bay	2.1	2.5	964.3	NE 33.4	Kobe
Aug. 17, 1956	Ariake Sea	2.4	4.2	968.4	SE 27.0	Saga
Sept. 26, 1959	Ise Bay	3.4	3.9	958.5	SSE 37.0	Nagoya
Sept. 16, 1961	Osaka Bay	2.5	2.9	937.3	SSE 33.3	Osaka
Sept. 25, 1964	Osaka Bay	2.1	2.6	983.5	S 27.1	Sumoto
Sept. 10, 1965	Osaka Bay	2.2	-	966.0	SSE 38.8	Sumoto
Aug. 21, 1970	Tosa Bay	2.4	3.1	962.3	SW 35.8	Ashizuri

Table 5.34: Severe damage caused by storm surges in Japan during the period 1900–73. (MIYAZAKI, 1975)

Date	Affected area	Highest sea level (m)	Peak surge (m)	Lives lost	Houses destroyed or swept away
Oct. 1, 1917	Tokyo Bay	3.0	2.1	1324	60 175
Sept. 13, 1927	Ariake Sea	3.8	0.9	439	2 211
Sept. 21, 1934	Osaka Bay	3.1	2.9	3036	92 323
Aug. 27, 1942	Inland Sea	3.3	1.7	1158	102 374
Sept. 17, 1945	South Kyushu	2.6	1.6	3121	115 984
Sept. 3, 1950	Osaka Bay	2.7	2.4	534	120 923
Oct. 14, 1951	South Kyushu	2.8	1.0	943	72 648
Sept. 27, 1959	Ise Bay	3.9	3.4	5098	156 676
Sept. 16, 1961	Osaka Bay	3.0	2.5	200	54 782

where, $p(r)$ and $p(\infty)$ are the sea level pressures at radial distance r and at the periphery of the typhoon, respectively, r_0 is the radius of maximum winds, and Δp is the pressure drop. Equation (5.76) gives a more rapid decrease of pressure with r but uses a constant value of 1010 mb at the typhoon periphery. The cyclostrophic wind corresponding to eq. (5.76) is

$$V^2 = 4V_m^2 \left[\frac{\mu^2}{(1 + \mu^2)^2} \right]$$

(5.77)

where, $\mu = r/r_0$ and V_m is the maximum wind at r_0 . The maximum wind and the pressure drop are related through

$$V_m = C(V_v)^{1/2}$$

(5.78)

where, C is a constant.

In other studies, the JELESNIANSKI (1972) model is used:

$$v(r) = v(r_0) \frac{2r_0}{r_0^2 + r^2} \tag{5.79}$$

where, again, r_0 is the radius of maximum winds. MYERS and MALKIN (1961) determined the angle of inflow for a stationary storm using the equations of motion. The angle varies from 0 at the center of the storm to about 30° at a radial distance of about $3r_0$ (where r_0 is the radius of maximum winds) and is roughly constant after that. Usually, within the region up to r_0 , the wind field computed from the pressure field (i.e. cyclostrophic or gradient winds) is reasonably correct. Outside r_0 , the angle of inflow (i.e. the angle of the wind vector across circular isobars) must be considered.

TAKAHASHI (1939) used the following form:

$$p(r) = p(\infty) - \frac{\Delta p}{\left(1 + \frac{r}{r_0}\right)} \tag{5.80}$$

This formula underestimates the pressure field at the center. KAWAHARA et al. (1980) used a finite-element model for storm surge propagation in Suragawa Bay. They used eq. (5.75) to specify the pressure field.

China

In China, storm surges mainly occur on the southeastern coast. In the 1970s, the biggest storm surge in China occurred at Shantou on August 2, 1979. The peak surge was over 2 m. In the dynamic models for surge prediction used in China (JIN-CHUAN and GUANG, 1979), MYERS (1954) formula is used:

$$\Delta p = \Delta p_0 (1 - e^{-R/r}) \tag{5.81}$$

where,

$$\Delta p_0 = p_\infty - p_c \text{ and } \Delta p = p_\infty - p \tag{5.82}$$

where, p_c is the central pressure, p_∞ is the peripheral pressure, p is the pressure at any point at distance r from the centre, and R is the radius of maximum winds.

The tangential component of the wind field is expressed as

$$V_\theta = \begin{cases} V_{\max} \frac{r}{R} \cos \alpha & \text{for } r \leq R \\ V_{\max} \frac{R}{r} \cos \alpha & \text{for } r > R \end{cases} \tag{5.83}$$

The radial component of the wind field is written as

$$V_r = \begin{cases} -V_{\max} \frac{r}{R} \sin \alpha & \text{for } r \leq R \\ -V_{\max} \frac{R}{r} \sin \alpha & \text{for } r > R \end{cases} \quad (5.84)$$

where, α is the angle measured inward between the wind direction and the isobars. In the surge computations for the Chinese coast, α was taken as 30° .

The tangential and radial components of the wind stress are computed from:

$$\begin{aligned} \tau_\theta &= K\rho_a |V| V_\theta \\ \tau_r &= K\rho_a |V| V_r \end{aligned} \quad (5.85)$$

where, $K = 2.5 \times 10^{-3}$ and $\rho_a = 1.2 \times 10^{-3} \text{ g} \cdot \text{cm}^{-3}$.

Storm surges are quite frequent in Hong Kong. About three to four occur per year in Hong Kong Harbour (WORLD METEOROLOGICAL ORGANIZATION, 1978). A total of 35 surges with amplitudes varying from 0.2 to 1.8 m occurred in Hong Kong during 1954–64 (CHENG, 1967). Typhoon Wanda caused one of the important surges in September 1962. The surge was 1.8 m at Hong Kong and 3.2 m at Taipo (farther inland in a narrow channel).

CHAN and WALKER (1979) mentioned that two of the most disastrous surges in Hong Kong occurred on September 2, 1937, and September 1, 1962, in the Tolo Harbour region. WATTS (1959) concluded that pronounced surges occur in Hong Kong when the center of a westward moving storm passes over Hong Kong within several tens of kilometres to the south.

If the storm track lies to the west of Hong Kong, the wind field at Hong Kong will be strong (east-northeast to east-southeast) and a major surge could be generated. On the other hand, if the track is to the east of Hong Kong, the winds will be weak (west-northwest to west-southwest) and surges, if generated, will be small. Most of the storms that affect Hong Kong originate in the Philippine Sea. A few, however, develop in the South China Sea, and in this case, the above criterion (track to the east or west of Hong Kong) does not apply. Also, those storms that make a landfall at Hong Kong usually are associated with weak local winds and would not generate significant surges. The major surges at Hong Kong are associated with storms that make a landfall within 60 nautical miles (111 km) either to the north or south of Hong Kong.

Based on storm surge data at North Point, the storm surges are classified into three categories by CHAN and WALKER (1979): type 0 refers to storms whose centers lie within a 60 nautical mile radius of Hong Kong, type W for storms whose centers are outside the 60 nautical mile radius and which travel to the west of Hong Kong over the land, and type E for storms with centers outside the radius and traveling over the land to the east of Hong Kong. For these three categories, the average values of the peak surges are 2.49 ± 0.25 , 1.71 ± 0.13 , and $1.31 \pm 0.18 \text{ ft}$ ($1 \text{ ft} = 0.3048 \text{ m}$).

For type 0 storms, the following empirical relation was deduced:

$$s = 0.102 (1009.1 - p) \quad (5.86)$$

where, s is the peak surge (feet) and p is the local minimum hourly sea level pressure (millibars). Note that in this relation, the local minimum hourly mean sea level pressure is used to represent the central pressure of the storm when it landfalls near Hong Kong. For type 0 storms, the coefficient of correlation between the central pressure and the peak surge was -0.89 . For type W and E storms the correlation was poor.

Again, for type 0 storms, the correlation coefficient between the peak surge s and the maximum hourly mean wind speed W_{60} was 0.84 and the following regression equation was derived:

$$s = 0.088 W_{60} - 0.75 \quad (5.87)$$

The local wind field appears to have more influence on the type W and E storm surges than type 0. For type W, maximum surges are associated with winds from east-northeast, east, or east-southeast. The following relation has been empirically deduced for type W storm surges:

$$s_w = 0.00217 W_{60}^2 + 0.43 \quad (5.88)$$

The correlation coefficient between s_w and W_{60}^2 was 0.88 . No correlation could be found for type E storm surges.

LAU (1980a, 1980b) adapted the SPLASH (JELESNIANSKI, 1972, 1974) model to predict storm surges in Hong Kong. Using 57 hypothetical storms, peak surge heights at various locations along the South China coast near Hong Kong were determined. In these calculations, a standard storm is chosen with the following six parameters: (a) a central pressure of 973 mb at nearest approach, (b) a movement on bearing 300° at nearest approach, (c) a speed of 10 knots at nearest approach, (d) a radius of maximum winds of 26 nautical miles at nearest approach, (e) a nearest approach of 26 nautical miles, and (f) landfalling to the west of Hong Kong. This standard storm will generate on an open coast a surge (using the SPLASH program) of 1.92 m at North Point.

5.4.4 Explosively developing tropical Cyclones and Superthypoons in the Pacific

CLARK (1978a, 1978b), using satellite imagery, studied rapidly developing tropical cyclones in the northeastern Pacific Ocean during the period 1973–76. In his analysis, he made use of the so-called T number (DVORAK 1975a, 1975b)¹. During this 4-yr period, of a total of 62 cyclones, 12 underwent a rapid development. The tracks of these rapidly developing tropical cyclones fall within a small area near Mexico (Fig. 5.64). CLARK (1978a, 1978b) cited persistent atmospheric conditions as contributing to the existence of a relatively small area of rapid development.

HOLLIDAY and THOMPSON (1979) made a study of rapidly deepening typhoons in the western part of the North Pacific Ocean using data from the period 1956–76. Their defini-

¹ The T number is based on the maximum wind speed. For example, T1 corresponds to 25 knots, T2 to 30 knots, T3 to 45 knots, T4 to 65 knots, etc., with T8 corresponding to 170 knots ($1 \text{ knot} = 1.852 \text{ km} \cdot \text{h}^{-1}$).

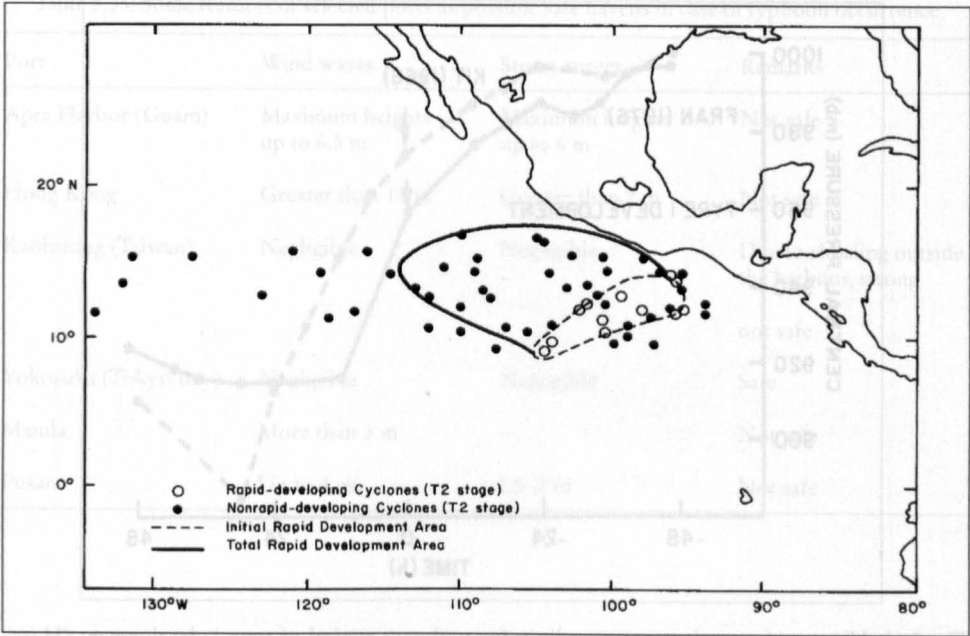


Fig. 5.64: Area of development of eastern North Pacific tropical cyclones, 1973–76 (CLARK, 1978b)

tion of rapid deepening is a fall in the central surface pressure by at least 42 mb in 24 h. In a total of 79 cases, rapid deepening (i.e. over an interval of 18 h with the steepest fall in the first 6 h) produced surface central pressures of 920 mb or less. For a tropical cyclone to mature into a typhoon, the underlying ocean temperature (up to a depth of 30 m) must be at least 28° C. This is a necessary condition for rapid deepening but not a sufficient condition.

Two basic types of deepening were noticed. In type 1 (Fig. 5.65) the central pressure falls at a moderate rate ($\geq 0.8 \text{ mb} \cdot \text{h}^{-1}$) at least over a period of 12–24 h. This is accompanied by accelerated development ($\geq 1.75 \text{ mb} \cdot \text{h}^{-1}$). This behaviour for Typhoons Kit of 1966 and Fran of 1976 is shown in Fig. 5.65. In type 2 behaviour, initially there is slower development ($< 0.8 \text{ mb} \cdot \text{h}^{-1}$) suddenly followed by explosive ($\geq 1.75 \text{ mb} \cdot \text{h}^{-1}$). This is shown for Typhoons Virginia of 1957 and Anita of 1970 in Fig. 5.66. In the 79 case studies, 36 % exhibited type 1 behaviour and the remainder showed type 2 behaviour.

About 36 % of the rapid deepening occurred during daytime and 64 % occurred during nighttime. SHEETS (1969) suggested that this might be related to the differences in the atmospheric stability during day and night. However, SHEETS' (1969) study of hurricanes and FRANK's (1978) study of typhoons on diurnal variations showed little evidence for diurnal changes except in the temperature field and other Crameters in the upper troposphere and stratosphere.

The time interval between the weak circulation stages to the commencement of rapid deepening varied from 72 to 172 h. The time interval between the tropical storm stages to the onset of rapid deepening varied from 12 to 108 h. The interval between the time of reaching typhoon stage and initiation of rapid deepening varied from 0 to 72 h.

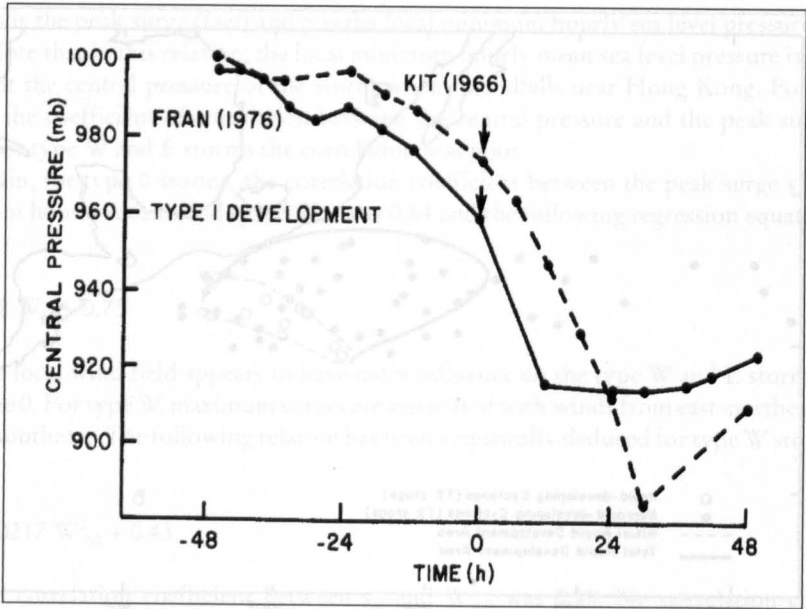


Fig. 5.65: History of central pressure readings for typhoons typical of type 1 development (Hurricanes Kit of June 1966 and Fran of September 1976). Arrow indicates onset of rapid deepening ($\geq 1.75 \text{ mb} \cdot \text{h}^{-1}$) (HOLLIDAY and THOMPSON, 1979)

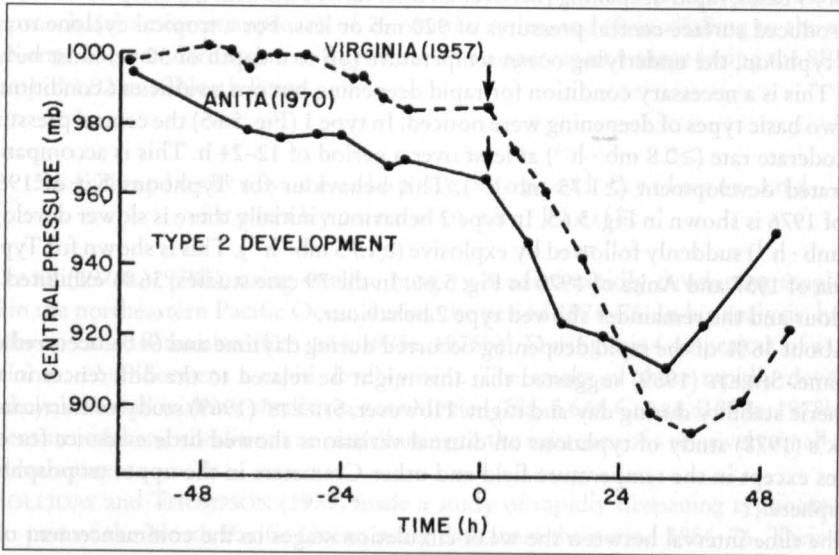


Fig. 5.66: History of central pressure readings for typhoons of type 2 development (Hurricanes Virginia of June 1957 and Anita of August 1970). Arrow indicates onset of rapid deepening ($\geq 1.75 \text{ mb} \cdot \text{h}^{-1}$) (HOLLIDAY and THOMPSON, 1979)

Table 5.35: Some features of selected ports as possible safe havens in case of typhoon occurrence

Port	Wind waves	Storm surges	Remarks
Apra Harbor (Guam)	Maximum heights up to 6.5 m	Maximum heights up to 6 m	Not safe
Hong Kong	Greater than 10 m	Greater than 2 m	Not safe
Kaohsiung (Taiwan)	Negligible	Negligible	Due to shoaling outside the harbour, strong not safe
Yokosuka (Tokyo Bay)	Negligible	Negligible	Safe
Manila	More than 3 m	–	Not safe
Pusan	Up to 4 m	1.5–2 m	Not safe

At the time of initiation of rapid deepening the eye diameters ranged from 29 to 37 km (average 33 km). Twelve hours after initiation of rapid deepening, the mean diameter of the eye decreased to 30 km, and 24 h after rapid deepening commencement, the average diameter was 26 km. Most of the rapid deepening occurred during the period July–November, with maximum activity in August and September. The area where rapid development began is shown in Fig. 5.67. The numerals show the number of cases during 1956–76.

Next, two interesting typhoons will be considered: Agnes of July 1978 and Tip of October 1979. The track of Typhoon Agnes is shown in Fig. 5.68. Because of the loop in the track, according to BELL (1979) it is the only tropical storm on record that caused gale signals to be hoisted twice at Hong Kong. Another unusual feature was that the so-called Fujiwara effect occurred between Typhoons Agnes and Wendy, although they were separated by 1000 mi (1600 km) apart. Another interesting feature from a public information point of view was that the American spacecraft *Apollo* ran into this with 60-knot ($111\text{ km} \cdot \text{h}^{-1}$) winds and 25-ft (8 m) waves when it splashed down into the Pacific Ocean.

Super typhoon Tip developed in the western part of the North Pacific Ocean in early October 1979. This had at least two unique features: it holds the world record for the lowest minimum sea level pressure (870 mb) ever measured in a tropical cyclone (see Fig. 5.69) and it possessed the largest surface circulation pattern ever observed for a tropical cyclone (about 2200 km in diameter). Finally, this was transformed into an extratropical cyclone around October 18, 1979. Although it caused great destruction in Japan, the destruction was minimal for its size because the maximum intensity was reached while the system was still far away from inhabited areas.

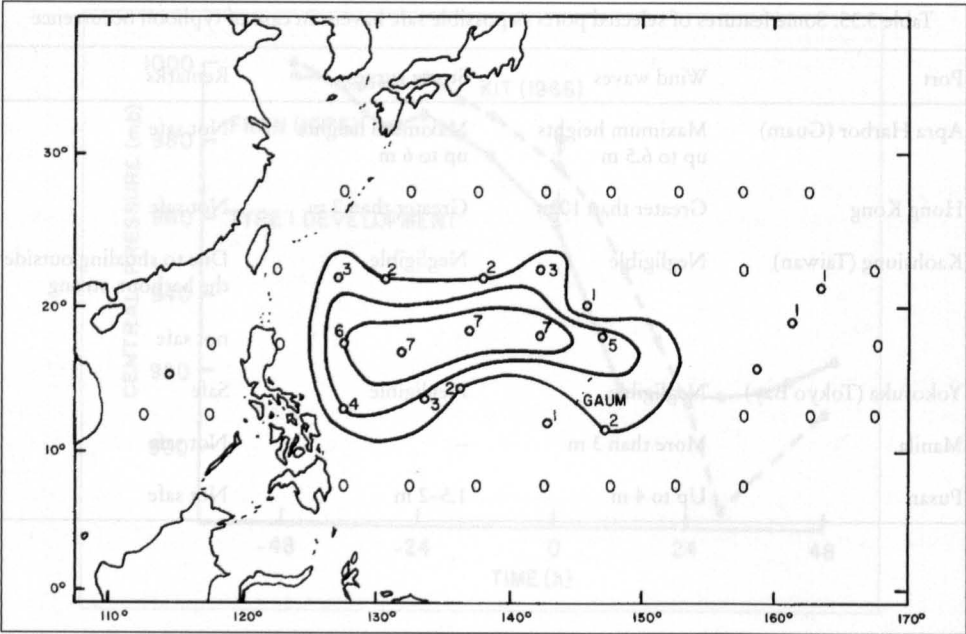


Fig. 5.67: Areas where typhoons intensified rapidly during summer and early fall (June 20–October 16). Numbers represent occurrences during 1956–76 (HOLLIDAY and THOMPSON, 1979)

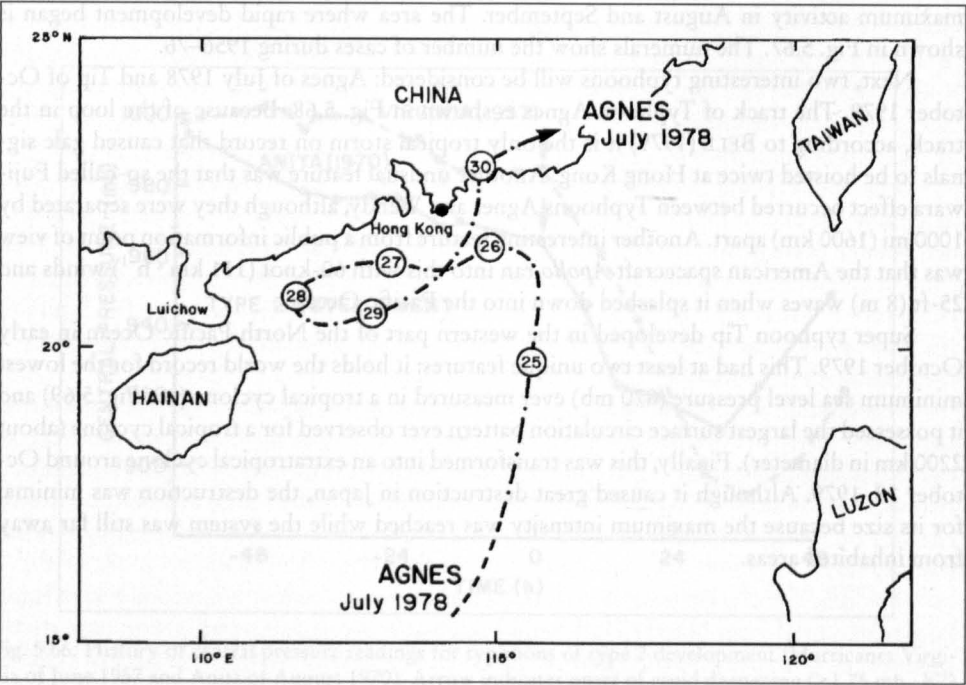


Fig. 5.68: Track of severe tropical storm Agnes from its formation on July 24, 1978, to its passage across the coast on July 30, 1978 (BELL, 1979)

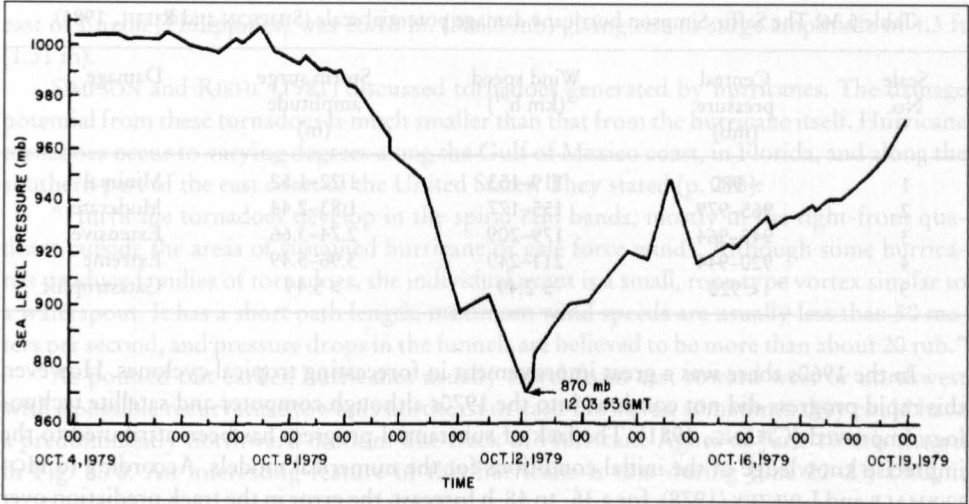


Fig. 5.69: Central pressure trace for Super typhoon Tip of October 1979 (DUNNAVAN and DIERCKS, 1980)

5.5 Tropical Cyclones of the Atlantic Ocean

Extratropical cyclones that affect North America are born in the western parts of the continent or in the Pacific Ocean and travel generally towards east (also east-northeast and north-east). Extratropical cyclones originating in the Atlantic generally do not affect North America but will travel towards Europe. Therefore this will be considered in chapter 5.1.3.

Here, basically, tropical cyclones originating in the Atlantic that affect mainly the North American continent will be considered.

5.5.1 Hurricanes Affecting the United States

The term “hurricane” comes from the Spanish word “huracon”, which probably originated from Maya and Carib Indian usage meaning evil spirit, storm god, or devil. A hurricane is an intense tropical storm with wind speeds in excess of 74 mi · h⁻¹ (64 knots or 33 m · s⁻¹). Hurricanes originating in the Atlantic Ocean, Caribbean Sea, and the Gulf of Mexico caused about thousands of deaths. About 90 % of the deaths were due to drowning in the storm surge. In the twentieth century, damage in the United States resulting from hurricanes exceeded more than \$ 12 billion.

There appears to be no definite periodic cycle for hurricanes. For example during the 1940’s Florida took the brunt, during the 1950s the east coast of the United States was mostly affected, and during the 1960s and 1970s most damage occurred along the coast of the Gulf of Mexico. There is some indication in the early 1980s that the same trend as in the 1940s and 1950s may occur (OWEN, 1980).

In the North Atlantic Ocean, from June through November, some 100 disturbances develop every year. Of these, about five to six intensify into hurricanes. About 70 % of these storms originate near the west coast of Africa and are referred to as Cape Verde storms. Locations were shown earlier (Fig. 1.19) at which Atlantic tropical storms reached hurricane intensity during the period 1901–63.

Table 5.36: The Saffir-Simpson hurricane damage potential scale (SIMPSON and RIEHL, 1981)

Scale No.	Central pressure (mb)	Wind speed (km h ⁻¹)	Storm surge amplitude (m)	Damage
1	~980	119–153	1.22–1.52	Minimal
2	965–979	155–177	1.83–2.44	Moderate
3	945–964	179–209	2.74–3.66	Extensive
4	920–944	211–249	3.96–5.49	Extreme
5	< 920	> 2.49	> 5.49	Catastrophic

In the 1960s there was a great improvement in forecasting tropical cyclones. However, this rapid progress did not continue into the 1970s although computer and satellite technology improved (CHANG, 1981). The lack of substantial progress has been attributed to the imprecise knowledge of the initial conditions for the numerical models. According to HÖVERMALE and LIVEZEY (1978), for a 36- to 48-h forecast, the error in the track prediction over the oceans (where data is scarce) is three times the error at coastal stations. Not everybody agrees with this evaluation. The EOS Bulletin (Vol. 61, No. 28, July 15, 1980, p. 538) mentioned that a NOAA satellite that is 22 300 mi (35 680 km) out in space is locating Atlantic Ocean hurricanes with an average accuracy of about 17 nautical miles and is pinpointing their intensity within an average of 10 knots. For a recent summary of the status of operational prediction of tropical cyclone motion over the North Atlantic Ocean, see NEUMANN and PELLISSIER (1981). These authors concluded that none of the seven models (five statistical and two dynamical) that are in use at the National Hurricane Center in Miami could be singled out as superior to the others in every respect. One disappointing aspect is that one cannot combine the good points from all these models into a single model.

Hurricanes are classified according to the Saffir-Simpson scale (named after Herbert Saffir, a consulting engineer, and Dr. R. H. Simpson, former director of the National Hurricane Center in Miami), which is an intensity scale based on the central pressure, wind speed, amplitude of the storm surge, and the resulting damage. This scale is illustrated in abbreviated form in Table 5.36. More details about this scale can be found in SIMPSON and RIEHL (1981). Note that in the twentieth century, only three storms affecting the United States are given the highest rank (5) on this scale. These are the Labour Day storm of 1935, Hurricane Camille of 1969, and Hurricane Allen of 1980.

Hurricane Statistics For The United States

Some of the most disastrous hurricanes of the twentieth century in the United States and the damage are listed in Table 1. 1. BRUUN et al. (1962) gave a list of major hurricanes affecting Florida during the period 1900–60. In this table there are 40 entries. The inverted barometer effect could be quite significant in the generation of storm surges here. For each inch (of mercury) of reduction of the central pressure of the hurricane (1 in. = 2.54 cm) the corresponding hydrostatic water head is 14 in. (BRETSCHNEIDER, 1967). For the storm of September 2, 1935, at Lower Matecumbe Key in Florida, the lowest central pressure was 26.35 in. Hg (892.3 mb). Taking the normal sea level pressure as 29.92 in. Hg (1013.2 mb) gives a 4.1-ft (1.3 m) rise in water level. Similar inverted barometer effects could be noticed in typhoons, also. For the typhoon of August 18, 1927, the central pressure some 460 mi (740 km)

east of Luzon (Philippines) was 26.18 in. (886.6 mb) giving rise to surge amplitude of 4.3 ft (1.31 m).

SIMPSON and RIEHL (1981) discussed tornadoes generated by hurricanes. The damage potential from these tornadoes is much smaller than that from the hurricane itself. Hurricane tornadoes occur to varying degrees along the Gulf of Mexico coast, in Florida, and along the southern part of the east coast of the United States. They stated (p. 218):

“Hurricane tornadoes develop in the spiral rain bands, mostly in the right-front quadrant outside the areas of sustained hurricane or gale force winds. Although some hurricanes produce families of tornadoes, the individual event is a small, rope type vortex similar to a waterspout. It has a short path length, maximum wind speeds are usually less than 50 meters per second, and pressure drops in the funnels are believed to be more than about 20 rub.”

As pointed out earlier, hurricanes usually travel from east toward west or northwest with a possible recurvature towards northeast or east. However, sometimes they could have a predominantly northward motion. The track of Hurricane Agnes of June 1972 is shown in Fig. 5.70. An interesting feature of this hurricane is that during June 22–23, 1972, it

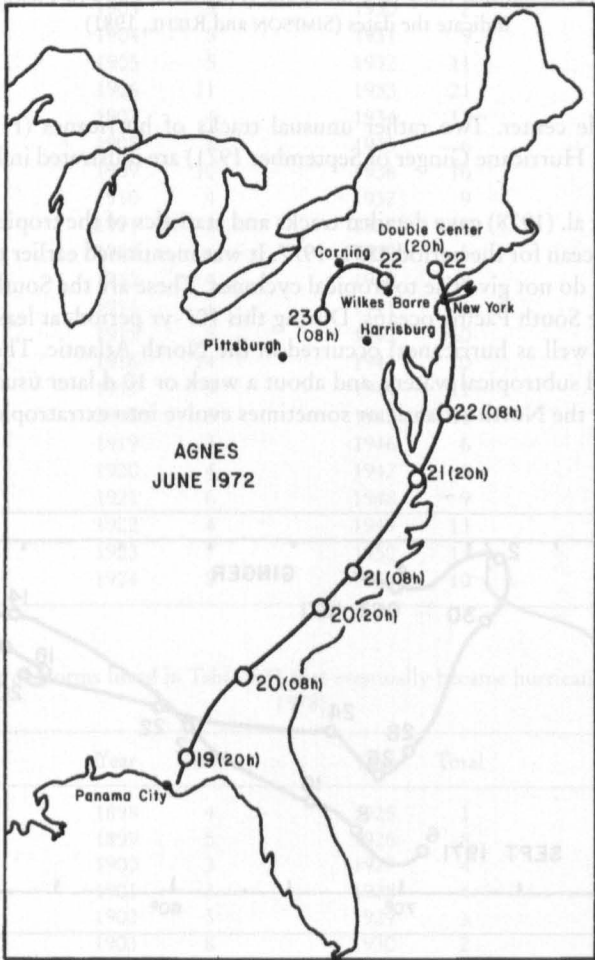


Fig. 5.70: Track of Hurricane Agnes of June 1972

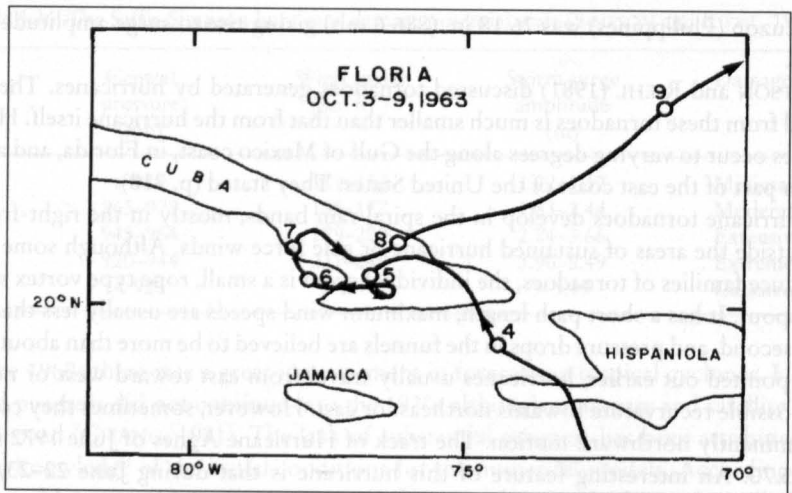


Fig. 5.71: Example of an unusual track of a hurricane (Hurricane Flora of October 1963). Numbers indicate the dates (SIMPSON and RIEHL, 1981)

exhibited a double center. Two rather unusual tracks of hurricanes (Hurricane Flora of October 1963 and Hurricane Ginger of September 1971) are illustrated in Fig. 5.71 and 5.72, respectively.

NEUMANN et al. (1978) gave detailed tracks and statistics of the tropical cyclones of the North Atlantic Ocean for the period 1871–1977. It was mentioned earlier that two large tropical ocean basins do not give rise to tropical cyclones. These are the South Atlantic and the eastern part of the South Pacific oceans. During this 107-yr period, at least 850 tropical cyclones (storms as well as hurricanes) occurred in the North Atlantic. These form over the warm tropical and subtropical waters, and about a week or 10 d later usually dissipate over the cold waters of the North Atlantic or sometimes evolve into extratropical cyclones.

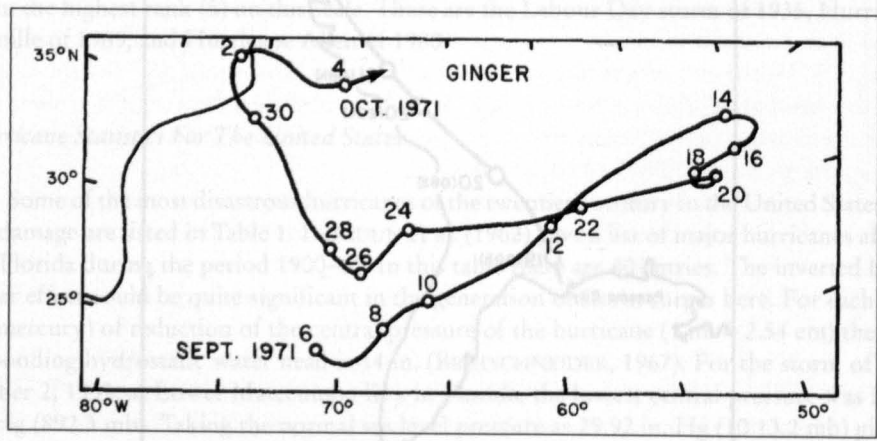


Fig. 5.72: Another example of an unusual hurricane track (Hurricane Ginger of October 1971). Numbers indicate the dates (SIMPSON and RIEHL, 1981)

These storms are listed in Table 5.37 for each of these years. Moreover the list of NEUMANN et al. (1978) encloses storms by month. It can be seen the dominance of storm events from August to October, which increase in number from May to August and decrease from October to December. Those that eventually became hurricanes are listed in Table 5.37. The distribution of the observed duration of hurricanes is given in Fig. 5.73.

Table 5.37: Number of recorded Atlantic tropical cyclones (excluding depressions and after 1967, including subtropical cyclones) that reached at least tropical storm intensity, 1871–1977 (NEUMANN et al., 1978)

Year	Total	Year	Total	Year	Total	Year	Total
1871	6	1898	9	1925	2	1952	7
1872	5	1899	6	1926	11	1953	14
1873	5	1900	7	1927	7	1954	11
1874	7	1901	10	1928	6	1955	12
1875	4	1902	5	1929	3	1956	8
1876	3	1903	9	1930	2	1957	8
1877	8	1904	5	1931	9	1958	10
1878	10	1905	5	1932	11	1959	11
1879	8	1906	11	1933	21	1960	7
1880	9	1907	4	1934	11	1961	11
1881	6	1908	8	1935	6	1962	5
1882	3	1909	10	1936	16	1963	9
1883	4	1910	4	1937	9	1964	12
1884	3	1911	4	1938	8	1965	6
1885	8	1912	6	1939	5	1966	11
1886	10	1913	4	1940	8	1967	8
1887	17	1914	1	1941	6	1968	8
1888	9	1915	5	1942	10	1969	18
1889	9	1916	14	1943	10	1970	10
1890	1	1917	3	1944	11	1971	13
1891	11	1918	5	1945	11	1972	7
1892	9	1919	3	1946	6	1973	8
1893	12	1920	4	1947	9	1974	11
1894	6	1921	6	1948	9	1975	9
1895	6	1922	4	1949	13	1976	10
1896	6	1923	7	1950	13	1977	6
1897	5	1924	8	1951	10		

Table 5.38: Number of storms listed in Table 5.37 that eventually became hurricanes (NEUMANN et al., 1978)

Year	Total	Year	Total	Year	Total	Year	Total
1871		1898	4	1925	1	1952	6
1872		1899	5	1926	8	1953	6
1873		1900	3	1927	4	1954	8
1874		1901	3	1928	4	1955	9
1875		1902	3	1929	3	1956	4
1876		1903	8	1930	2	1957	3
1877		1904	2	1931	2	1958	7
1878		1905	1	1932	6	1959	7

Table 5.38: (Continued)

Year	Total	Year	Total	Year	Total	Year	Total
1879		1906	6	1933	9	1960	4
1880		1907	0	1934	6	1961	8
1881		1908	5	1935	5	1962	3
1882		1909	4	1936	7	1963	7
1883		1910	3	1937	3	1964	6
1884		1911	3	1938	3	1965	4
1885		1912	4	1939	3	1966	7
1886	8	1913	3	1940	4	1967	6
1887	10	1914	0	1941	4	1968	5
1888	5	1915	4	1942	4	1969	12
1889	5	1916	11	1943	5	1970	5
1890	1	1917	2	1944	7	1971	6
1891	8	1918	3	1945	5	1972	3
1892	4	1919	1	1946	3	1973	4
1893	10	1920	4	1947	5	1974	4
1894	5	1921	4	1948	6	1975	6
1895	2	1922	2	1949	7	1976	6
1896	6	1923	3	1950	11	1977	5
1897	2	1924	5	1951	8		

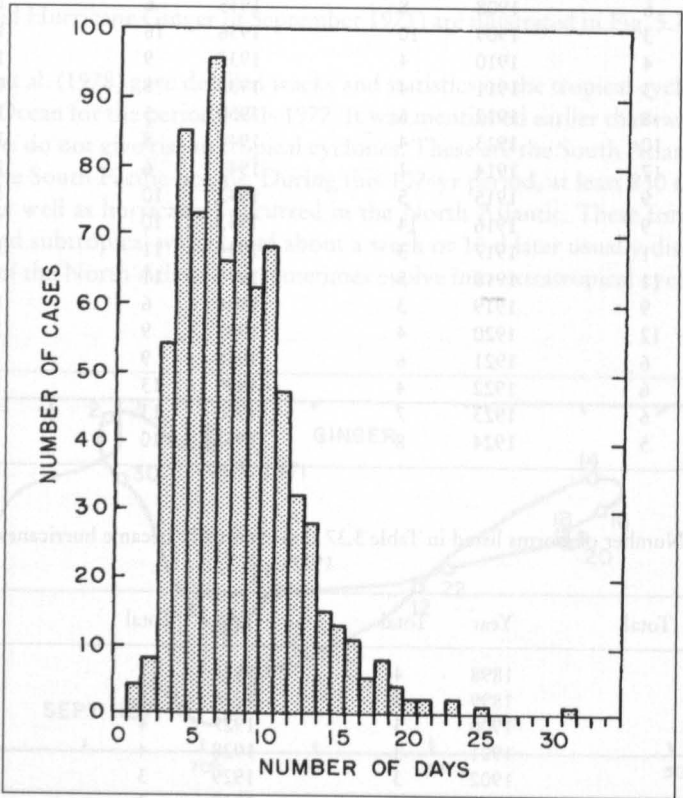


Fig. 5.73: Distribution of observed duration of Atlantic tropical cyclones, 1886–1977 (NEUMANN et al., 1979)

FRANK (1978) studied the geographical distribution of the generation areas and other characteristics of these Atlantic storms for the period 1968–77. During this 10-yr period, a total of 1044 systems appeared. Of these, 58 % originated near Dakar (Africa). Of the approximately 100 tropical weather systems developing in each hurricane season (June 1–November 30) about 25 % become depressions and about 10 % become storms.

NEUMANN and HILL (1976) described the computerized tropical cyclone climatological data at the National Hurricane Center in Miami. The tracks of the 680 recorded Atlantic tropical cyclones for the period 1886–1969 were plotted. Later, this number increased to 743 tracks up to the end of the 1975 hurricane season. Most of these data are based on ship reports, and in later years these data were supplemented by aircraft reconnaissance and satellite data. The storm track data are maintained at the National Climatic Center in Asheville, NC. Based on these computerized data. NEUMANN and CRY (1978) discussed the revised Atlantic tropical cyclone climatology.

Some Comparisons of the Tropical Cyclone Activity in the Atlantic and Pacific Oceans

NUNEZ and GRAY (1978) and GRAY (1978c) compared some meteorological parameters associated with Atlantic hurricanes and Pacific typhoons, and their findings are summarized in Table 5.39.

Table 5.39: Comparison of Atlantic hurricanes and Pacific typhoons

Parameter	Atlantic hurricanes (West Indies)	Pacific typhoons
Temperature anomaly. This is determined as follows. A mean temperature is calculated by averaging the temperature values at 9 and 15° to the east and west of the position of the cyclone. Deviation from this mean temperature is the anomaly	Warm core throughout most of the troposphere. Warmest temperature at about 300 mb. The anomaly is +4°C for the hurricane (at 300 mb) Cold core in the upper troposphere and lower stratosphere. This region occurs at a lower level than for typhoons and its radial extent is greater	Warm core throughout most of the troposphere. Warmest temperature at about 250 mb. The anomaly is +7° C for the typhoon (at 250 mb). Cold core in the upper troposphere and lower stratosphere
Relative humidity	About 10 % less than for typhoons at equivalent radii and heights Boundary layer relative humidity is about 15 % lower than for the West Pacific	Moister inner core with relative humidities greater than 90 % up to 400 mb whereas in the hurricane, such a high relative humidity cannot be found higher than at 575 mb
Radial winds	Maximum inflow at 950 mb with a wind of 8 ms ⁻¹ . At 150 mb there are two outflow jets: northeast and southwest. The northeast jet is about four times stronger	Maximum inflow at 950 mb with a wind of 6 ms ⁻¹ . At 150 mb there are two outflow jets: northeast and southwest. The southwest jet is somewhat greater

Table 5.39: (Continued)

Parameter	Atlantic hurricanes (West Indies)	Pacific typhoons
Tangential wind	<p>Maximum cyclonic flow is at the top of the frictional boundary layer at 850 mb</p> <p>The tangential wind is smaller than in typhoons</p> <p>The anticyclonic maximum occurs at 150 mb</p> <p>Generally the hurricane size is smaller than a typhoon's</p> <p>Vertical shear between 950 and 150 mb is 10–15 ms⁻¹</p>	<p>Maximum cyclonic flow is at the top of the frictional boundary layer at 850 mb</p> <p>The anticyclonic maximum occurs at 150 mb. The anticyclonic circulation is relevant also in determining the weather associated with the typhoon</p> <p>Vertical shear between 950 and 150 mb is 15–20 ms⁻¹</p>
Inflow angle	<p>The boundary layer inflow angle decreases from quadrant to quadrant in the following order: right, front, back, left</p>	<p>The boundary layer inflow angle decreases in the following order: front, right, left, back</p>
Steering current concept for predicting tracks	<p>Applies</p>	<p>Applies</p> <p>West Pacific typhoons move more to the left of the mean current than do West Atlantic hurricanes</p>

5.6 Tropical Cyclones of the Indian Ocean

There are no extratropical cyclones in the North Indian Ocean. The extratropical cyclones of the South Indian Ocean are not very relevant for storm surge studies and, in any case, these will be briefly considered. In this section will be considered mainly the tropical cyclones of the South and North Indian oceans with emphasis on the Bay of Bengal and to a lesser extent on the Arabian Sea. However, while discussing tropical cyclones, another type of cyclone (which is neither tropical nor extratropical) referred to as a subtropical cyclone will be considered.

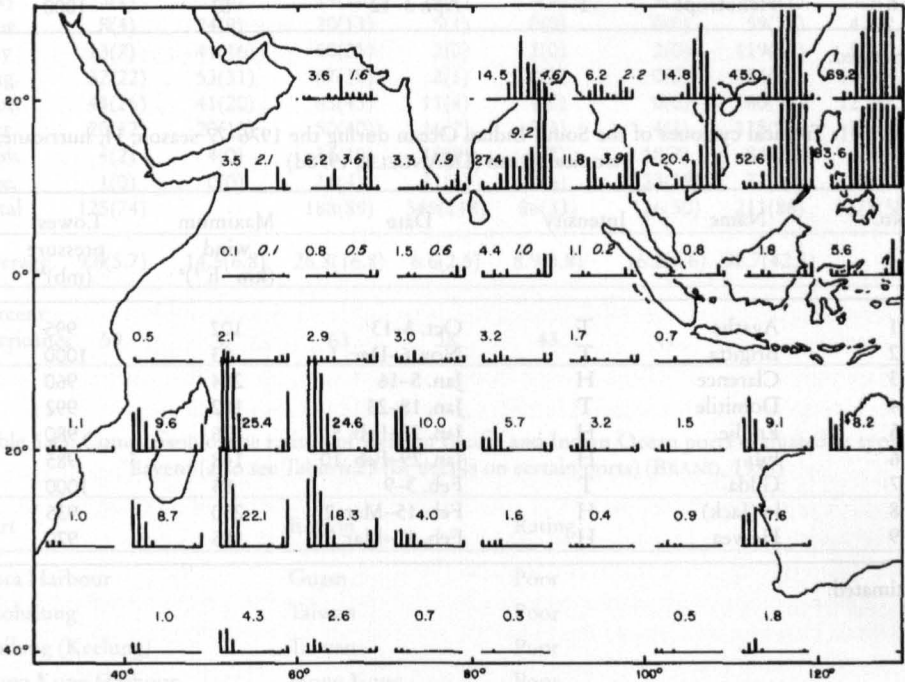


Fig. 5.74: Frequency of tropical cyclones in the Indian Ocean (average numbers of occurrences per 10 yr. for each 10° square by months). Roman-type numbers indicate average 10-yr totals over the northern Indian Ocean. The unblackened segments of the histograms and the italicized numbers given corresponding information for severe tropical storms (RAMAGE, 1971)

Tropical cyclones develop in all parts of the Indian Ocean. This is in contrast with the Atlantic and Pacific Oceans. There are no tropical cyclones in the South Atlantic and eastern part of the South Pacific. The average number of tropical cyclones during a 10-yr period for each 10° square by months is shown in Fig. 5.74. It can be seen that the highest frequencies occur north of Indonesia (not counting the Philippines area). In the Bay of Bengal and to the region east of the Malagasy Republic (Madagascar) high frequencies also occur. However, one difference is that whereas in the Bay of Bengal the highest frequencies are during September–December, in the region east of the Malagasy Republic (i.e. the western part of the South Indian Ocean) and in the region west of the west coast of Australia (i.e. the eastern part of the South Indian Ocean) the high frequencies occur during January–March.

Table 5.40: Tropical cyclones of the South Indian Ocean for the 1975–76 season. H, hurricane; T, tropical storm (DEANGELIS, 1977)

No.	Name	Intensity	Date	Maximum wind ($\text{km} \cdot \text{h}^{-1}$) ^a	Lowest pressure (mb) ^a
1	Audrey	T	Nov. 17–29	96	995
2	Barbara	H	Dec. 3–19	157	980
3	Clotilde	H	Jan. 7–20	250	980
4	Danae	H	Jan. 12–29	250	955
5	Gladys	T	Mar. 27–Apr. 10	111	998
6	Heliotrope	T	Apr. 3–12	83	1000

^aEstimated.

Table 5.41: Tropical cyclones of the South Indian Ocean during the 1976–77 season; H, hurricane; T, tropical storm (DEANGELIS, 1978d)

No.	Name	Intensity	Date	Maximum wind ($\text{km} \cdot \text{h}^{-1}$) ^a	Lowest pressure (mb) ^a
1	Agathe	T	Oct. 3–13	102	995
2	Brigitta	T	Nov. 6–Dec. 1	83	1000
3	Clarence	H	Jan. 5–16	204	960
4	Domitile	T	Jan. 18–23	102	992
5	Emilie	H	Jan. 26–Feb. 5	176	980
6	Fifi	H	Jan. 29–Feb. 10	148	985
7	Gilda	T	Feb. 3–9	83	1000
8	lo (Jack)	H	Feb. 15–Mar. 2	250	935
9	Hervea	H	Feb. 17–Mar. 3	185	970

^a Estimated.

5.6.1 Tropical Cyclones of the South Indian Ocean

Certain features of the tropical cyclones of the South Indian Ocean for the seasons 1975–76 and 1976–77 are summarised in Table 5.40 and 5.41, respectively. In the 1975–76 season there was a total of six tropical cyclones of which three reached hurricane strength. In the 1976–77 season, of a total of nine cyclones, five became hurricanes. The tropical cyclones for the period 1965–77 are summarised by month for various ocean basins in Table 5.42. Note that in terms of frequency, the North Indian Ocean has the lowest and the South Indian Ocean has the second lowest. However, this may be misleading when one considers the damage due to tropical cyclones (and storm surges generated by them). More than 60 % of the deaths and almost 40 % of the damage due to tropical cyclones occur on lands bordering the Bay of Bengal, which is only a small part of the North Indian Ocean.

Considered earlier were typhoon waves among harbours located around the Pacific Ocean. Some Indian Ocean harbours as well as some Pacific Ocean harbours (for comparison) are listed in Table 5.43. Among the Indian Ocean harbours, only Colombo is listed as “good” and Karachi as “marginal” (BRAND, 1978).

Table 5.42: Tropical cyclones in various ocean basins during the period 1965–77. Numbers in parentheses indicate tropical cyclones that reached hurricane intensity (i.e. winds $\geq 119 \text{ km} \cdot \text{h}^{-1}$) (DE-ANGELIS, 1979a)

Month	North Atlantic	Eastern North Pacific	Western North Pacific	North Indian	South Indian	Australia-South Pacific	Total	Average
Jan.	0(0)	0(0)	9(5)	2(1)	29(17)	52(20)	92(43)	7.1(3.3)
Feb.	0(0)	0(0)	4(1)	0(0)	30(16)	41(16)	75(33)	5.8(2.5)
Mar.	0(0)	0(0)	6(1)	0(0)	15(5)	39(18)	60(24)	4.6(1.8)
Apr.	0(0)	0(0)	11(9)	4(2)	6(1)	18(6)	39(18)	3.0(1.4)
May	3(1)	5(3)	14(10)	14(5)	3(0)	4(3)	42(22)	3.3(1.7)
June	8(4)	24(9)	20(13)	5(1)	0(0)	0(0)	59(27)	4.4(2.1)
July	13(7)	41(16)	60(35)	2(0)	1(0)	2(0)	119(58)	9.2(4.5)
Aug.	32(22)	53(31)	67(38)	2(1)	0(0)	0(0)	154(92)	11.8(7.1)
Sept.	44(26)	41(20)	63(43)	11(4)	1(0)	0(0)	160(93)	12.3(7.2)
Oct.	20(12)	20(10)	50(40)	16(7)	5(3)	4(1)	115(73)	8.8(5.6)
Nov.	4(2)	4(0)	34(19)	19(8)	5(2)	18(7)	84(38)	6.5(2.9)
Dec.	1(0)	0(0)	11(4)	11(4)	21(6)	33(15)	77(29)	5.9(2.2)
Total	125(74)		188(89)	349(218)	86(33)	116(50)	211(86)	1075(550)
Average	9.6(5.7)	14.5(6.8)	26.8(16.8)	6.6(2.5)	8.9(3.8)	16.2(6.6)	82.7(42.3)	
Percent hurricanes	59	47	63	38	43	41		

Table 5.43: Comparison of the ratings of western Pacific and Indian Ocean ports evaluated as typhoon havens (also see Table 6.29 for details on certain ports) (BRAND, 1978)

Port	Region	Rating
Apra Harbour	Guam	Poor
Kaohsiung	Taiwan	Poor
Chilung (Keelung)	Taiwan	Poor
Hong Kong Harbour	Hong Kong	Poor
Yokosuka	Japan	Good
Nunazu operating area	Japan	Poor
Lwakuni	Japan	Marginal (but has easily accessible anchorages close by that are good)
Kure	Japan	Good
Saskebo	Japan	Good (except for carriers)
Kagoshima	Japan	Poor
Buckner Bay (Okinawa)	Japan	Poor
Naha (Okinawa)	Japan	Poor
Subic Bay	Philippines	Marginal to poor
Manila	Philippines	Poor
Cebu	Philippines	Poor
Inchon	Korea	Poor (unless shelter is available in the tidal basin, then it would be considered a good haven)

Table 5.43: (Continued)

Port	Region	Rating
Pusan	Korea	Poor
Chinhae	Korea	Marginal (but has easily accessible anchorage's nearby that are considered good)
Colombo	Sri Lanka	Good
Karachi	Pakistan	Marginal
Auckland	New Zealand	Good to marginal
Freemantle	Australia	Marginal (unless shelter is available in Cockburn Sound or the inner harbour, then it would be considered good)
Diego Garcia Harbour	Diego Garcia	Poor

Australia and New Zealand

Although storm surges are not a serious problem in Australia and New Zealand, they do occur and cause damage. In Australia, the areas particularly susceptible to storm surges are the central north coast of eastern Queensland and parts of the Gulf of Carpentaria. HOPLEY and HARVEY (1979) studied the storm surges all along the coast of Australia. The cyclones in this study are listed in Table 5.44. Cyclones affect the northern parts of the east and west coasts of Australia, as well as its north coast. The frequency of cyclones (capable of generating storm surges) varies from 0.4 to 2.8 per year. Lowest central pressures occur on the east and west coasts between 20 and 25° S. The central pressures on the west coast are usually 3–4 mb lower than those on the coast of Queensland. Central pressures drop gradually towards the north but more drastically towards the south.

Intense cyclones with central pressures less than 960 mb occur on the central part of the west coast (Northwest Cape to Port Hedland), the region between Princess Charlotte Bay and Mackay on the Queensland coast. However, in the Gulf of Carpentaria, central pressures less than 960 mb rarely occur.

Cyclones in the Australian region usually travel with speeds between 6 and 11 knots although sometimes with a speed as high as 35 knots (particularly on the Queensland coast between 25 and 30° S). They travel with low speeds over the Gulf of Carpentaria and off Arnhemland (COLEMAN, 1972). The variability in the meteorological parameters associated with cyclones in the Australian region, based on data for 1960–72, is shown in Table 5.44 of HOPLEY and HARVEY (1979). This variability was determined for the following three parameters: (a) variability in the direction of movement by measuring the difference between the point on the coast for which the cyclone was heading 24 h prior to landfall and the observed landfall location, (b) variability in pressure by comparing changes in the pressure field during the 24 h prior to landfall, and (c) variability in the speed of movement by comparing the average speed in the 24 h prior to landfall with the mean speed in the previous 24 h.

NELSON (1975) listed 30 severe tropical cyclones in the Australian region during the period 1880–1970 that generated storm surges with amplitudes of at least 0.5 m along the north coast of Australia. One of the lowest central pressures ever recorded, a storm on

March 5, 1899, that travelled over Bathurst Bay and struck Barrow Point on the Queensland coast, was 914 mb. The storm and the storm surge together killed 300 people and the surge penetrated 5 km inland (WHITTINGHAM, 1958).

Table 5.44: Cyclones in and around Australia (HOPLEY and HARVEY, 1979)

Name	Date of landfall or nearest point to coast	Tidal station closest to cyclone	Lowest central pressure (mb)	Highest record of surge at any station (m)	Remarks
Adeline	Jan. 28, 1973	Centre Island	990	0.52	
Agnes	Mar. 6, 1956	Townsville	961	1.4	
Althea	Dec. 24, 1971	Townsville	952	2.85	3.6 m at Toolakea
Bridget	Jan. 27, 1969	Lucinda	1002	0.34	
Emily	Apr. 2, 1972	Gladstone	920	1.78	Filled rapidly before crossing
Eva	Dec. 4, 1970	Broome	970	0.16	1.2- to 13-m surge reported at Broome (Met. Bur. 1973)
Gertie	Feb. 16, 1971	Lucinda	983	0.52	
Glynis	Feb. 6, 1970	Perth	970	1.01	Surge incorrectly reported as 4.1 m above normal at Carnarvon (Met. Bureau, 1973). Record tides elsewhere
Ida	Feb. 16, 1971	Mourilyan	980	0.37	
Ingrid	Feb. 16, 1970	Carnarvon	970	1.32	Surge incorrectly reported as 2.3 m above normal at Carnarvon (Met. Bur. 1973)
Joan	Dec. 7, 1975	Port Hedland	-992	1.52	Port Hedland recorder malfunction during rising surge
Leah	Feb. 28, 1973	Milner Bay	990	0.45	
Madge	Mar. 4, 1973	Milner Bay	990	0.42	Affected east coast and Gulf
Pam	Feb. 6, 1974	Kirra	930	0.4	Came within 450 km of Queensland but very large cyclone
Sheila-Sophie	Feb. 3, 1971	Port Hedland	970	1.8	
Tracy	Dec. 24, 1974	Darwin	940	1.6	2.0-m surge reported to north of city
Una	Dec. 19, 1973	Townsville	988	0.72	
Wanda	Jan. 25, 1974	Noosa	990	0.6	Associated with Brisbane floods
Zoe	Mar. 13, 1974	Broadwater	975	0.56	

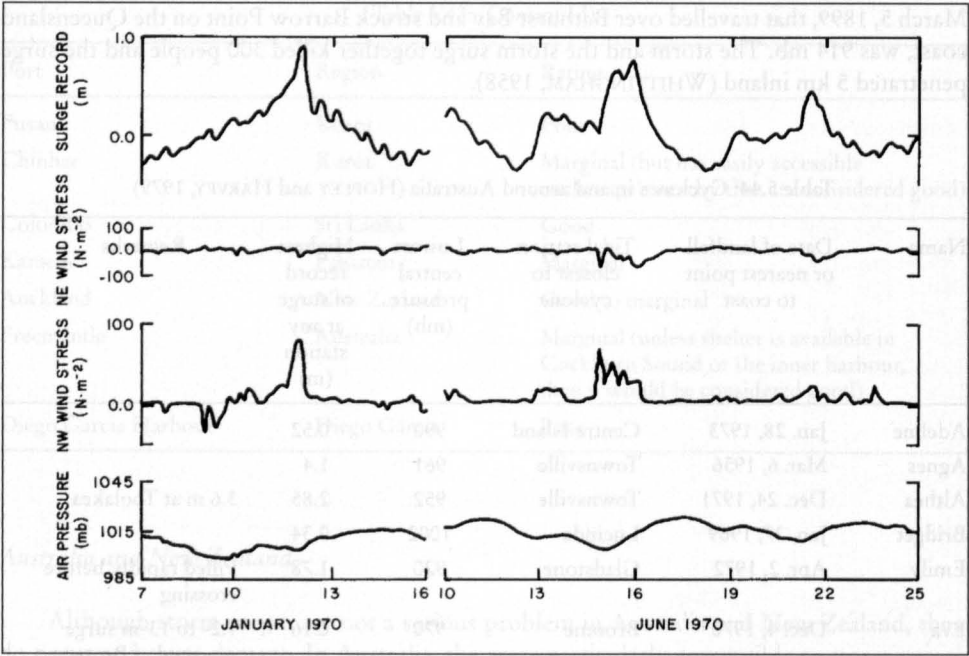


Fig. 5.75: Storm surges, atmospheric pressure, and wind stress at Adelaide, Australia (TRONSON and NOYE, 1973)

In the 1970s two storm surges did considerable damage in Australia. Cyclone Althea of December 24, 1971, made a landfall to the north of Townsville on the Queensland coast. Winds up to $196 \text{ km} \cdot \text{h}^{-1}$ and lowest central pressure of 971.5 mb generated a maximum surge of about 2.7 m at Townsville. Cyclone Tracy of December 25, 1974, hit Darwin; a central pressure of 955 mb and winds up to $200 \text{ km} \cdot \text{h}^{-1}$ generated a maximum surge of about 1.6 m.

TRONSON and NOYE (1973) developed statistical models to predict storm surges on the coast near Adelaide in South Australia. The storm surges in this region are particularly sensitive to the wind direction. On April 12, 1948, steady winds from the southwest with a speed of $90 \text{ km} \cdot \text{h}^{-1}$ caused a surge of about 1.2 m. On June 28, 1972, a surge with the same amplitude was generated by winds from the northwest, with a speed of about $45 \text{ km} \cdot \text{h}^{-1}$. Surges with amplitudes of up to 4 m can occur at Adelaide, e.g. on May 12, 1960, and June 28, 1972. The atmospheric pressure field, the wind stress, and the surges at Adelaide for two cases (January 7–16 and June 10–25, 1970) are shown in Fig. 5.75.

HEATH (1979) discussed the storm surges on the coasts of New Zealand. Storm surge amplitudes on the coasts of New Zealand are rather small and are usually less than 1 m (AGNEW, 1966; GILMOUR, 1963; PICKRILL, 1972). Even though the amplitudes may be small, they could cause severe erosion, especially on the west coast of the North Island, in the Bay of Plenty, and on the east coast of the North Island, north of Auckland.

HEATH (1979) studied the following three surges: April 9–11, 1968, on the east coast of the North Island, July 30–August 1, 1975, on the east coast of the South Island, and September 11–14, 1976, on the west coast of the North Island. The surface weather chart for the third case is given in Fig. 5.76.

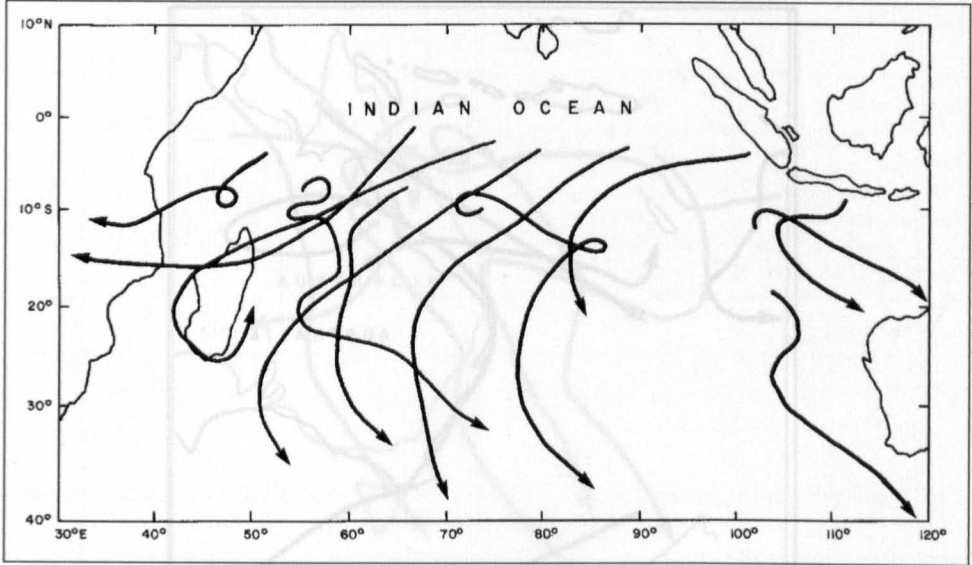


Fig. 5.76: Typical tropical cyclone tracks in the South Indian Ocean between the Malagasy Republic and the west coast of Australia

Australia is the only continent that is affected by tropical cyclones on both the east and west coasts. Certain features of the tropical cyclones of Australia are described in Tables 5.45–5.47. The average tropical cyclone frequencies for the west and east coasts of Australia for the months of December and January are given in Fig. 5.81 and 5.82, respectively. The frequency of cyclone days in Australia is given in Fig. 5.83 and the cyclone frequency change (i.e. trend) during the period 1905–55 is shown in Fig. 5.84.

Some typical tropical cyclone tracks in the region between the Malagasy Republic and the west coast of Australia are illustrated in Fig. 5.77 and typical tracks near the west coast of Australia in Fig. 5.78. For comparison, tropical cyclone tracks near the east coast of Australia and those affecting New Zealand are shown in Fig. 5.79 and 5.80, respectively.

Australia is the only continent that is affected by tropical cyclones on both the east and west coasts. Certain features of the tropical cyclones of Australia are described in Tables 5.45–5.47. The average tropical cyclone frequencies for the west and east coasts of Australia for the months of December and January are given in Fig. 5.77 and Fig. 5.78, respectively. The frequency of cyclone days in Australia is given in Fig. 5.79 and the cyclone frequency change (i.e. trend) during the period 1905–55 is shown in Fig. 5.80.

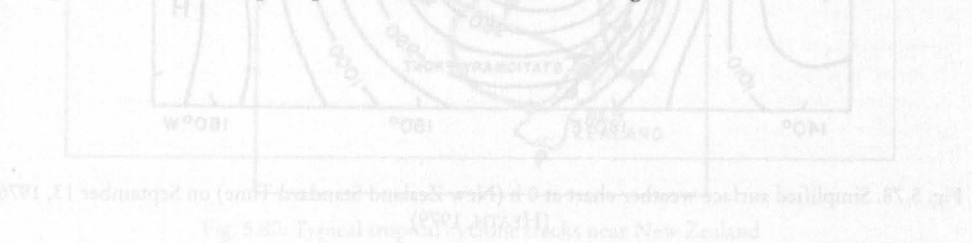


Fig. 5.80: Typical tropical cyclone tracks near New Zealand



Fig. 5.77: Typical tropical cyclone tracks near the west coast of Australia

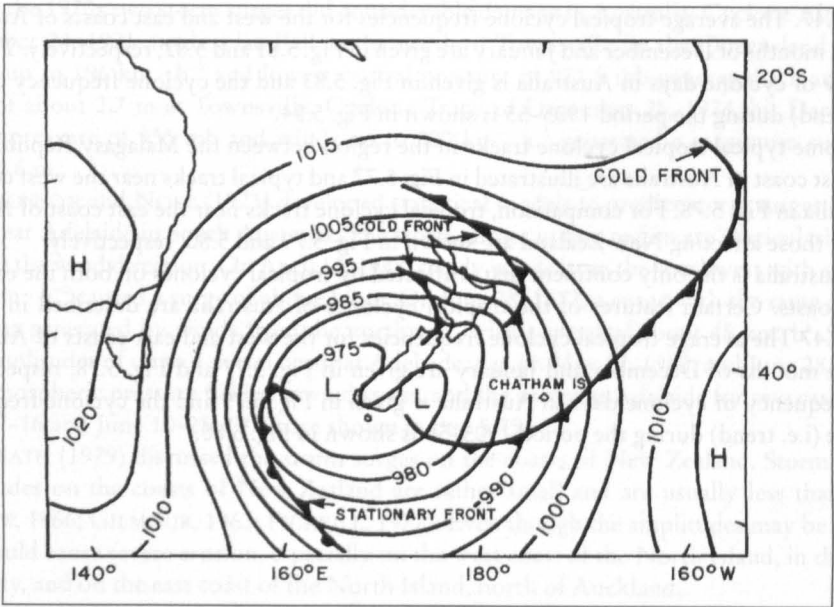


Fig. 5.78. Simplified surface weather chart at 0 h (New Zealand Standard Time) on September 13, 1976 (HEATH, 1979)

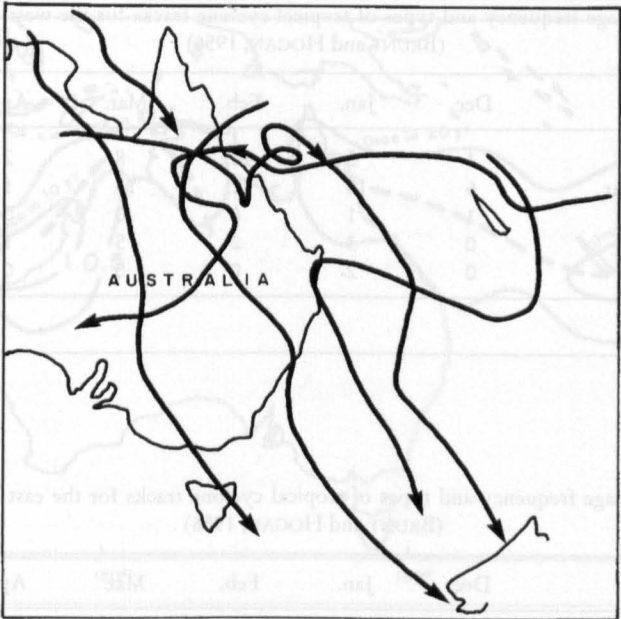


Fig. 5.79: Typical tropical cyclone tracks near the east coast of Australia

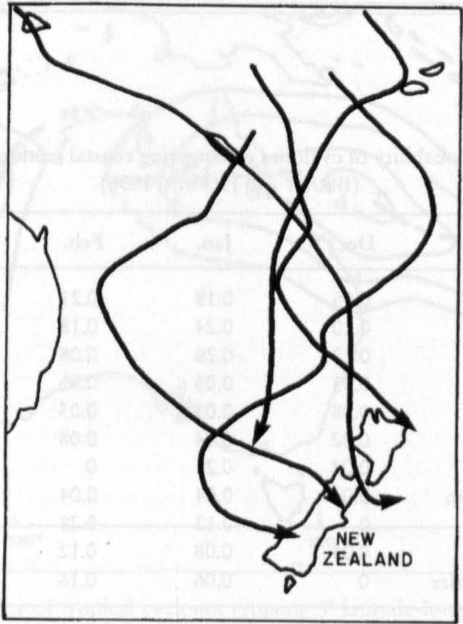


Fig. 5.80: Typical tropical cyclone tracks near New Zealand

Table 5.45: Percentage frequency and types of tropical cyclone tracks for the west coast of Australia (BRUNT and HOGAN, 1956)

Type of path	Dec.	Jan.	Feb.	Mar.	Apr.	Season
Parabolic	4	5	12	8	2	31
More or less straight	6	16	12	13	1	48
Reverse curvature	1	1	6	0	0	8
Cusp	0	3	2	5	1	11
Doubling of track	0	2	0	0	0	2
Total						100

Table 5.46: Percentage frequency and types of tropical cyclone tracks for the east coast of Australia (BRUNT and HOGAN, 1956)

Type of path	Dec.	Jan.	Feb.	Mar.	Apr.	Season
Parabolic	2	6	14	15	2	39
More or less straight	2	11	8	11	5	37
Reverse curvature	1	8	0	1	2	12
Cusp	0	2	7	1	0	10
Doubling of track	1	0	0	0	1	2
Total						100

Table 5.47: Probability of cyclones endangering coastal sections in Australia (BRUNT and HOGAN, 1956)

Section of coast	Dec.	Jan.	Feb.	Mar.	Apr.
Hamlin Pool-Roebourne	0.05	0.18	0.21	0.18	0
Roebourne-Broome	0.10	0.24	0.18	0.13	0.03
Broome-Wyndham	0.10	0.26	0.08	0.13	0.03
Wyndham-Darwin	0.03	0.03	0.05	0.03	0
Darwin-Melville Bay	0.08	0.03	0.03	0.03	0.03
N.T. Gulf coast	0.02	0.14	0.08	0.08	0
Queensland Gulf coast	0.02	0.21	0	0	0
Thursday Island-Cooktown	0.04	0.04	0.04	0.08	0.04
Cooktown-Townsville	0	0.12	0.28	0.12	0.04
Townsville-Rockhampton	0.04	0.08	0.12	0.16	0.06
Rockhampton-N.S.W. border	0	0.06	0.16	0.16	0.06

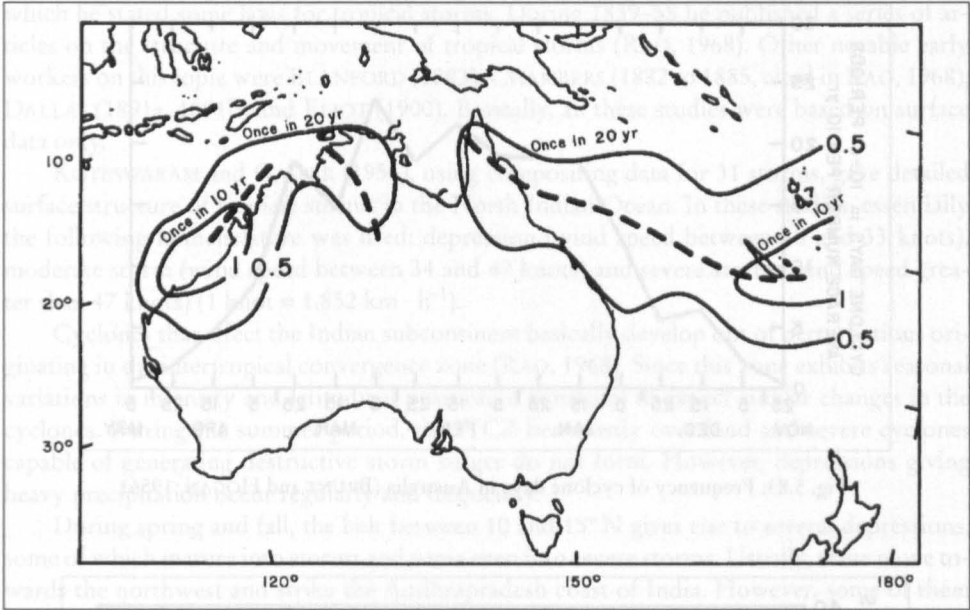


Fig. 5.81: Average frequency of tropical cyclones crossing 5' latitude-longitude squares per 10 yr. in December; heavier broken lines indicate the axes of maximum values (BRUNT and HOGAN, 1956)

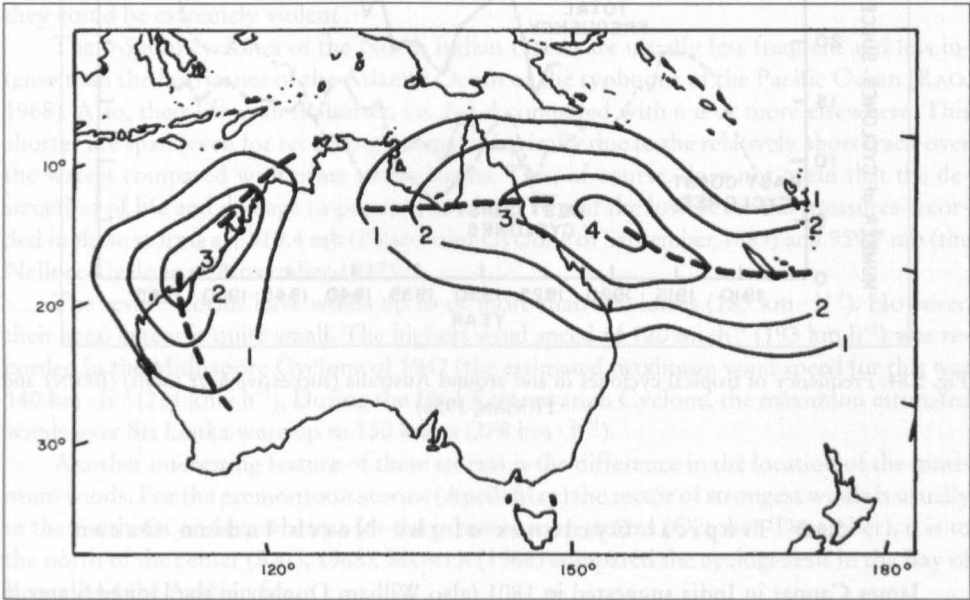


Fig. 5.82: Average frequency of tropical cyclones crossing 5' latitude-longitude squares per 10 yr. in January. Heavier broken lines indicate the axes of maximum values (BRUNT and HOGAN, 1956)

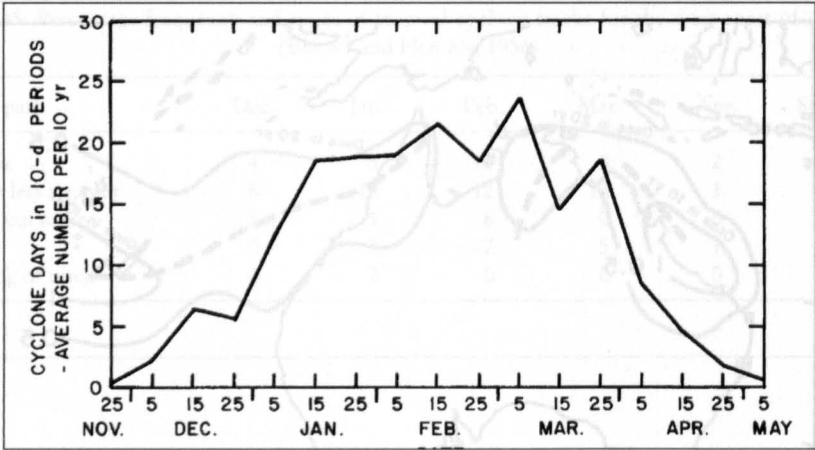


Fig. 5.83: Frequency of cyclone days in Australia (BRUNT and HOGAN, 1956)

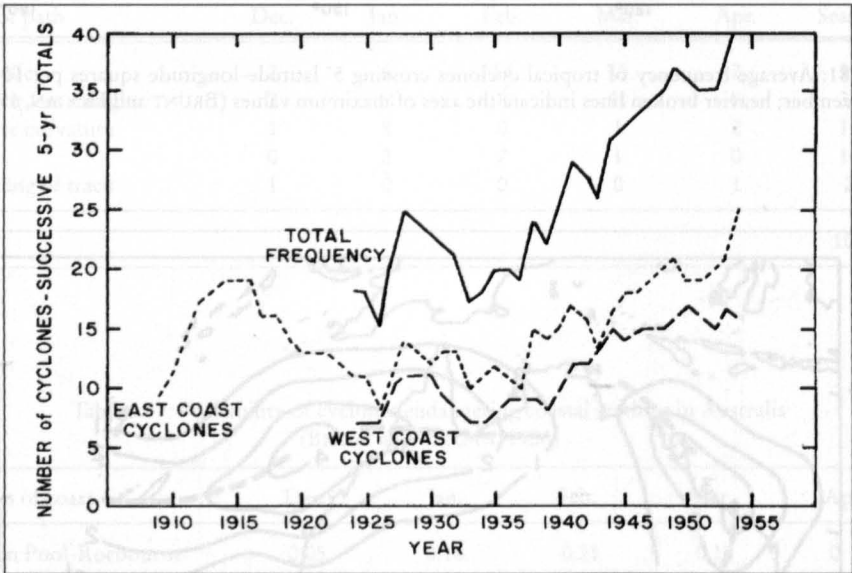


Fig. 5.84: Frequency of tropical cyclones in and around Australia (successive 5-yr totals) (BRUNT and HOGAN, 1956)

5.6.2 Tropical Cyclones of the North Indian Ocean

James Cappar in India suggested in 1801 (also William Dunbar in the United States in the same year) that there is a vortex in the center of a tropical cyclone (LUDLAM, 1963). However, it was Henry Piddington who, in 1851, coined the word “cyclone” from the Greek word „kyklon” meaning coil of snake to describe the rotary motion. Piddington was the president of the Marine Courts at Calcutta, India, and in 1851 he published a sailor’s handbook in

which he stated some laws for tropical storms. During 1839–58 he published a series of articles on the structure and movement of tropical storms (RAO, 1968). Other notable early workers on this topic were BLANFORD (1883), CHAMBERS (1882 to 1885, cited in RAO, 1968), DALLAS (1891a, 1891b) and ELIOT (1900). Basically, all these studies were based on surface data only.

KOTESWARAM and GASPER (1956), using compositing data for 31 storms, gave detailed surface structure of tropical storms in the North Indian Ocean. In these studies, essentially the following nomenclature was used: depression (wind speed between 18 and 33 knots), moderate storm (wind speed between 34 and 47 knots) and severe storm (wind speed greater than 47 knots) ($1 \text{ knot} = 1.852 \text{ km} \cdot \text{h}^{-1}$).

Cyclones that affect the Indian subcontinent basically develop out of perturbations originating in the intertropical convergence zone (RAO, 1968). Since this zone exhibits seasonal variations in intensity and latitudinal position, it is natural to expect similar changes in the cyclones. During the summer period, the ITCZ lies mostly over land and severe cyclones capable of generating destructive storm surges do not form. However, depressions giving heavy precipitation occur regularly and frequently.

During spring and fall, the belt between 10° and 15°N gives rise to several depressions, some of which mature into storms and some even into severe storms. Usually, these move towards the northwest and strike the Andhrapradesh coast of India. However, some of them recurve over the Bay of Bengal and hit the northern coast of the bay (the west Bengal state of India and the coast of Bangladesh). During autumn, the storms take a more southerly course and strike the peninsular part of India. Some of these storms recurve and strike the north coast of the bay (the Sunderban coast). Some cross the peninsula and redevelop over the Arabian Sea and travel west-north-west and strike the Arabian Sea coast of the subcontinent. Usually, there are no storms during winter. On the rare occasion when they occur, they could be extremely violent.

The tropical cyclones of the North Indian Ocean are usually less frequent and less intense than the hurricanes of the Atlantic Ocean or the typhoons of the Pacific Ocean (RAO, 1968). Also, their life span is shorter, i.e. 2–3 d compared with 6 d or more elsewhere. This shorter life span (even for recurving storms) is basically due to the relatively short track over the waters compared with other ocean basins. This, of course, does not mean that the destruction of life and damage to property are less. Two of the lowest central pressures recorded in these storms are 919.4 mb (False Point Cyclone of September 1885) and 959.7 mb (the Nellore Cyclone of November 1927).

The severe storms have winds up to or more than 100 knots ($185 \text{ km} \cdot \text{h}^{-1}$). However, their areal extent is quite small. The highest wind speed of $120 \text{ mi} \cdot \text{h}^{-1}$ ($193 \text{ km} \cdot \text{h}^{-1}$) was recorded in the Midnapore Cyclone of 1942 (the estimated maximum wind speed for this was $140 \text{ km} \cdot \text{h}^{-1}$ ($224 \text{ km} \cdot \text{h}^{-1}$)). During the 1964 Rameswaram Cyclone, the maximum estimated winds over Sri Lanka were up to 150 knots ($278 \text{ km} \cdot \text{h}^{-1}$).

Another interesting feature of these storms is the difference in the location of the maximum winds. For the premonsoon storms (April–May) the sector of strongest winds is usually in the southeast or east, whereas for the postmonsoon storms (October–December), it is to the north of the center (RAO, 1968). MOWLA (1968) compared the cyclogenesis in the Bay of Bengal and the Arabian Sea.

Table. 5.48: Number of cyclonic disturbances that originated over the Bay of Bengal and the Arabian Sea in different months for the period 1891–1960. Note that “storms” includes “severe storms” also, whereas „cyclonic disturbances“ include storms and severe storms in addition to cyclonic disturbances (RAO, 1968)

	Cyclonic disturbances	Storms	Severe storms
Jan.	13	4	1
Feb.	3	1	1
Mar.	5	4	2
Apr.	26	18	7
May	56	28	18
June	93	34	4
July	132	38	7
Aug.	145	25	1
Sept.	151	27	8
Oct.	132	53	19
Nov.	102	56	23
Dec.	52	26	9
Year	910	314	100

After the Second World War, using radiosonde data, the upper structure of these storms was studied, and several articles appeared in the *Indian Journal of Meteorology and Geophysics* (now called *Mausam*), especially on the tracks of cyclonic disturbances in various months with emphasis on the recurvature. These studies revealed that the areas of generation and the tracks in every month are closely related to the anticyclonic cell in the upper troposphere at a 10- to 12-km height. However, variations in the tracks could occur due to changes in the general circulation produced by troughs in the midlatitude westerlies.

Frequencies of Cyclonic Storms in the Bay of Bengal

The number of cyclonic disturbances over the Bay of Bengal for each month during the period 1891–1960 is given in Table 5.48. RAGHAVENDRA (1973) performed a statistical analysis of the number of tropical storms and depressions in the Bay of Bengal for the period 1890–1969. The average annual number of storms and depressions is 13. The monsoon season accounts for 56 % of these and the postmonsoon season accounts for 31 %. The highest number (20 storms) occurred in 1927. The frequency distribution of storms and depressions of monsoon and postmonsoon seasons is normal and that of the annual season is almost normal with slight kurtosis. The decade of 1920–29 had the highest mean and the decade of 1950–59 the lowest mean for the annual and monsoon seasons, thus indicating a cycle of 60 yr.

SADLER and GIDLEY (1973) gave tracks of the storms in the North Indian Ocean. CHAKRAVORTHY (1956) discussed the dimensions of the eye of the Bay of Bengal storms. He found that the eye diameter varied from 7 to 20 mi (11.5–32 km).

MOOLEY (1980a, 1980b) studied the severe cyclonic storms of the Bay of Bengal for the period 1877–1977. He found that during the period 1965–77, a higher percentage (than the average) of storms intensified into severe storms and a higher percentage of storms made landfall. Generally, the formation and landfall of these severe storms are random events and are consistent with the Poisson stochastic process.

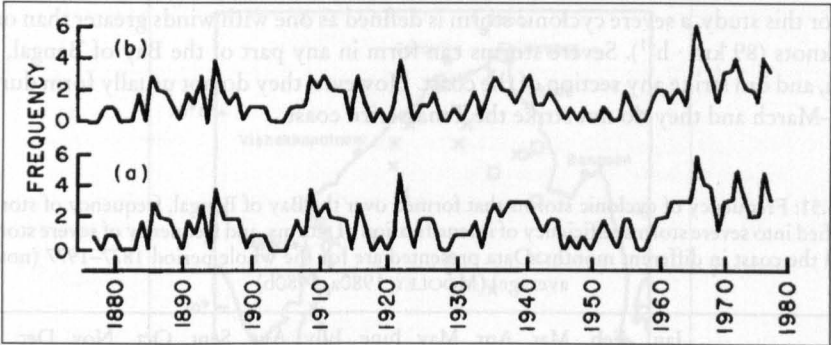


Fig. 5.85: Annual frequency of severe cyclonic storms that over the period 1877–1977 (a) formed over the Bay of Bengal and (b) struck the coast (MOOLEY, 1980a, 1980b)

Table 5.49: Mean and variance of the number of severe storms forming over the Bay of Bengal, and the number of severe storms striking the coast in a year (MOOLEY, 1980)

Period	Severe storms forming over the Bay of Bengal		Severe storms striking the coast	
	Mean	Variance	Mean	Variance
1891–1964	1.50	1.420	1.22	1.087
1877–1964	1.42	1.374	1.16	1.091
1877–1977	1.67	1.910	1.40	1.530
1965–1977	3.38	1.923	3.00	1.833

Table 5.50: Number of cyclonic storms that formed over the Bay of Bengal, number that intensified into severe storms over the bay, and number that struck the coast as severe storms in different 13-yr periods (MOOLEY, 1980a, 1980b)

Period	Number of storms that formed	Number of storms that intensified into severe storms	Number of severe storms that struck the coast	Intensification of storms into severe storms over the bay	Efficiency of Ratio of severe storms that struck the coast to storms that struck the coast
1877–99	49	13	12	0.26	0.31
1890–1902	56	19	18	0.34	0.36
1903–15	64	19	17	0.30	0.30
1916–28	61	19	16	0.31	0.36
1929–41	70	24	19	0.34	0.39
1942–54	46	13	8	0.28	0.28
1952–64	45	21	13	0.47	0.43
1965–77	70	44	39	0.63	0.66
1886–98	74	24	23	0.32	0.35
1924–36	74	16	13	0.22	0.25
1932–44	71	27	22	0.38	0.47

For this study, a severe cyclonic storm is defined as one with winds greater than or equal to 48 knots ($89 \text{ km} \cdot \text{h}^{-1}$). Severe storms can form in any part of the Bay of Bengal, in any month, and can strike any section of the coast. However, they do not usually form during January–March and they do not strike the Tenasserin coast.

Table 5.51: Frequency of cyclonic storms that formed over the Bay of Bengal, frequency of storms that intensified into severe storms, efficiency of intensification of storms, and frequency of severe storms that crossed the coast in different months. Data presented are for the whole period 1877–1977 (not annual average) (MOOLEY, 1980a, 1980b)

	Jan.	Feb.	Mar.	Apr.	May	June	July	Aug.	Sept.	Oct.	Nov.	Dec.	Annual
Frequency of storms	5	0	5	21	48	43	48	30	42	77	91	43	453
Frequency of storms that intensified into severe storms	2	0	3	9	32	6	8	3	14	30	44	18	169
Efficiency of intensification				0.43	0.67	0.14	0.17	0.10	0.33	0.39	0.49	0.42	0.37
Frequency of severe storms that crossed the coast	1	0	2	6	29	6	8	3	12	28	35	11	141

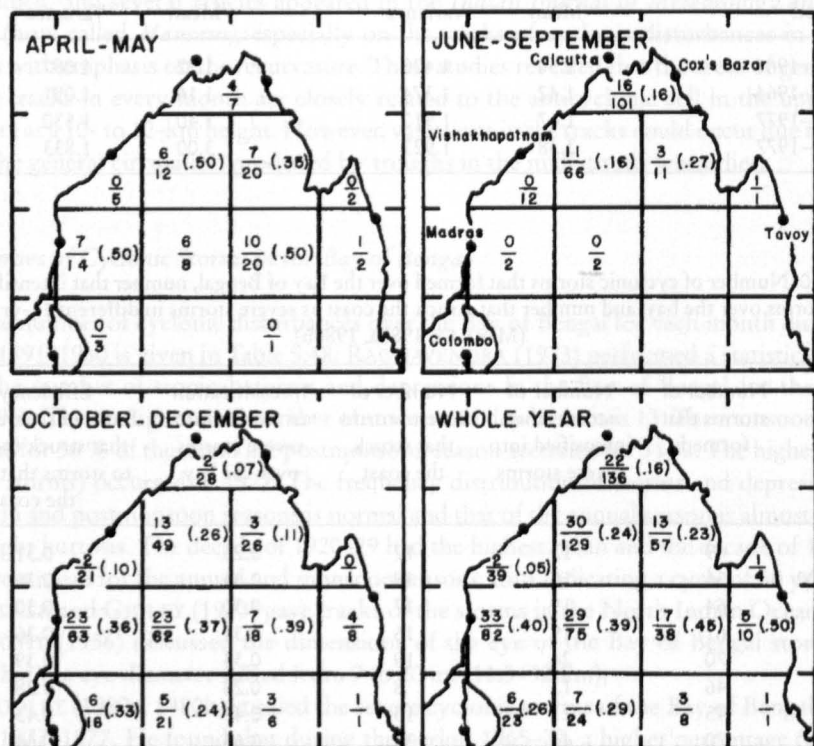


Fig. 5.86: Number of storms located (denominator), number of storms intensified into severe storms (numerator), and the efficiency of intensification (in parentheses) in the different sectors of the Bay of Bengal for the period 1877–1977 (MOOLEY, 1980a, 1980b)

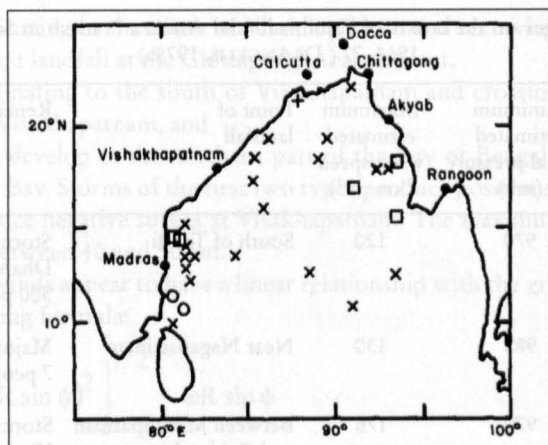


Fig. 5.87: Locations of severe storms just prior to their weakening into storms and depressions over the Bay of Bengal during the period 1877–1977. ○, January–March; □, April and May; June–September; ×, October–December (MOOLEY, 1980a, 1980b)

The annual frequency of severe cyclones that formed over the Bay of Bengal and those that struck the coast is shown in Fig. 5.85. The mean and variance of the number of severe storms forming over the Bay and those striking the coast are listed in Table 5.49. Further details are provided in Table 5.50 and 5.51. The efficiency of intensification (i.e. a cyclonic storm maturing into a severe storm) for different areas in the Bay of Bengal, for the periods April–May, June–September, October–December, and the whole year, is shown in Fig. 5.86. The locations of severe storms just prior to their weakening into storms or depressions are illustrated in Fig. 5.87.

In principle, the entire coast of the Bay of Bengal from Sri Lanka to Thailand is vulnerable to storm surges, although in practice, storm surges occur only on certain stretches. Storm surges are not frequent in Sri Lanka; however, in 1978 a major surge occurred that caused great devastation. Most of the storms developing in the Andaman Sea travel towards northwest and strike the coast of Tamilnadu or Andhrapradesh (south-east part of India), rather than travel towards the west and strike the coast of Sri Lanka. Certain storms have a more northerly component in their motion and these can landfall on the coast of Orissa. Those that recurve can hit the coasts of West Bengal, Bangladesh, and Burma.

On the coasts of Tamilnadu and Andhrapradesh, at least six storm surges occurred during the period 1964–77. These are listed in Table 5.52 along with the minimum central pressure and maximum wind speed. There appears to be some controversy regarding the intensity of the November 1977 cyclone (last entry in Table 5.52). PANT *et al.* (1980) suggested that the minimum central pressure was 943 mb and the maximum wind speed was 125 knots ($231 \text{ km} \cdot \text{h}^{-1}$). This cyclone intensified from T6 to T7 between November 17 and 19 (see Table 5.53 for the classification of T numbers in terms of pressure drop and wind speed). GHOSH (1980) suggested that the lowest pressure was 919 mb and not 943 mb. In intensity, this cyclone was comparable with that of the 1927 cyclone. However, the 1927 cyclone generated a surge smaller than the 1977 cyclone (in the storm surge of 1927, 300 people died compared with at least 10 000 in the 1977 surge). The 1927 cyclone made a landfall near Nellore where the topography was much steeper and hence the surge was smaller. Another cyclone that had a pressure drop in excess of 90 mb occurred in 1885 (ELIOT, 1890).

Table 5.52: Storm surges on the coasts of Tamilnadu and Andhra Pradesh in Southeast India during 1964-77 (DEANGELIS, 1978a)

Date	Minimum estimated central pressure (mb)	Maximum estimated wind speed ($\text{km} \cdot \text{h}^{-1}$)	Point of landfall	Remarks
Dec. 17-24, 1964	970	120	South of Tondi	Storm surge amplitude at Dhanushkodi about 5 m, 500 people died
Dec. 4-8, 1967	988	130	Near Nagapattinam	Major storm surge, 7 people died
Nov. 4-9, 1969	970	176	Between Masulipatnam and Kakinada	Storm surges at Visakhapatnam, 200 people died
Sept. 7-14, 1972	957	204	Near Baruva	Storm surges of 1-3 m between Baruva and Chandbali
Nov. 15-23, 1972	983	148	South of Nellore	Minor storm surge
Nov. 14-20, 1977	919	250	Chirala	Surges up to 6 m near Divi. At least 10 000 people died. Surges occurred on a coastal stretch 80 km long and penetrated 8-15 km inland

Table 5.53: Relationship between T number, maximum wind speed, and pressure drop in a cyclone (DVORAK, 1975a; MISHRA and GUPTA, 1976)

T	Maximum wind speed ($\text{km} \cdot \text{h}^{-1}$)	Pressure drop (mb)	T	Maximum wind speed ($\text{km} \cdot \text{h}^{-1}$)	Pressure drop (mb)
1	46	-	5	167	40
1.5	46	-	5.5	189	52
2	56	-	6	213	66
2.5	65	6	6.5	235	80
3	83	10	7	259	97
3.5	102	15	7.5	287	119
4	120	21	8	315	143
4.5	143	29			

At Visakhapatnam, on the east coast of India, the maximum (positive or negative) surge appears to occur usually about a day after the winds attain their maximum intensity. The amplitude of the surge depends more on the wind direction than on the wind speed (RAM-ANADHAM and VARADARAJULU, 1965). The storm surges at Visakhapatnam are usually associated with three types of storm tracks:

(a) storms originating to the south of Visakhapatnam and recurving near the east coast of India and making a landfall at the Chittagong-Arakan coast,

(b) storms originating to the south of Visakhapatnam and crossing the coast between Masulipatnam and Visakhapatnam, and

(c) storms that develop in the northern part of the Bay of Bengal and cross the coast near the head of the Bay. Storms of the first two types produce positive surges and storms of the third type produce negative surges at Visakhapatnam. The maximum amplitudes of the surges are usually between 40 and 50 cm.

The observed winds appear to have a linear relationship with the gradient wind calculated from the following formula:

$$V_g = \left[\frac{R}{\rho} \frac{\partial p}{\partial r} + (\omega R \sin \phi)^2 \right]^{1/2} - \omega R \sin \phi \quad (5.89)$$

where, V_g is the gradient wind, ω is the angular velocity of the earth's rotation, ϕ is the latitude, R is the radius of curvature of the isobars, and p is the density of air. It was found that

$$\frac{V}{V_g} = 0.6$$

where, V is the wind as measured from ships offshore.

Although storm surges may be of small amplitude at Visakhapatnam, south of it, storm surges could have very large amplitudes. The cyclone of October 28, 1949, made a landfall north of Masulipatnam (Fig. 5.88). Winds up to 90 knots ($167 \text{ km} \cdot \text{h}^{-1}$) produced storm surges with amplitudes of 3–4 m along a stretch of the coast shown in Fig. 5.88. The storm crossed the coast at the time of high tide (RAO, 1968).

Another severe storm struck the Coromandel Coast on November 30, 1952 (RAO, 1968). Again, winds up to 90 knots produced surges with amplitudes up to 2.5 m along a stretch of the coast shown in Fig. 5.89. Another severe cyclonic storm travelled towards the west over the northern boundary of the Palk Strait (between India and Sri Lanka) on November 30–December 1, 1955. Two different storm surges occurred (RAO, 1968). The first one was along the coast between Point Calimere and Vettaikaran Iruppu and had amplitudes up to 2 m. The second surge occurred between Thambkottai and Kattumavedi with amplitudes over 1 m.

One of the most destructive storm surges in southern India occurred on December 23, 1964 (Fig. 5.92). Winds up to 120 knots ($322 \text{ km} \cdot \text{h}^{-1}$) created storm surges over the islands of Mannar (Sir Lanka) and Rameswaram (India) and the maximum amplitudes of the surges were 5–6 m. This storm exhibited some interesting features: (a) the major surges occurred to the left of the storm track (at Pamban-Dhanushkodi Islands), (h) the surges preceded the arrival of the storm by approximately 3–4 h, (c) although winds up to 80 knots ($148 \text{ km} \cdot \text{h}^{-1}$) were recorded to the west of the Pamban Bridge, no surges occurred along this part of the coastline

It was mentioned that the amplitude of storm surges at Visakhapatnam, is not significant. Generally, north of Visakhapatnam, the storm surge activity is not severe, except on some stretches of the Orissa coast, until one arrives at the coast of Bangladesh. Saugor Island (India) is situated near the head of the Bay of Bengal where the Hoogly Estuary empties into the Bay. On this island, the surge heights usually range from 1/3 to 1 m (JANARDHAN, 1967).

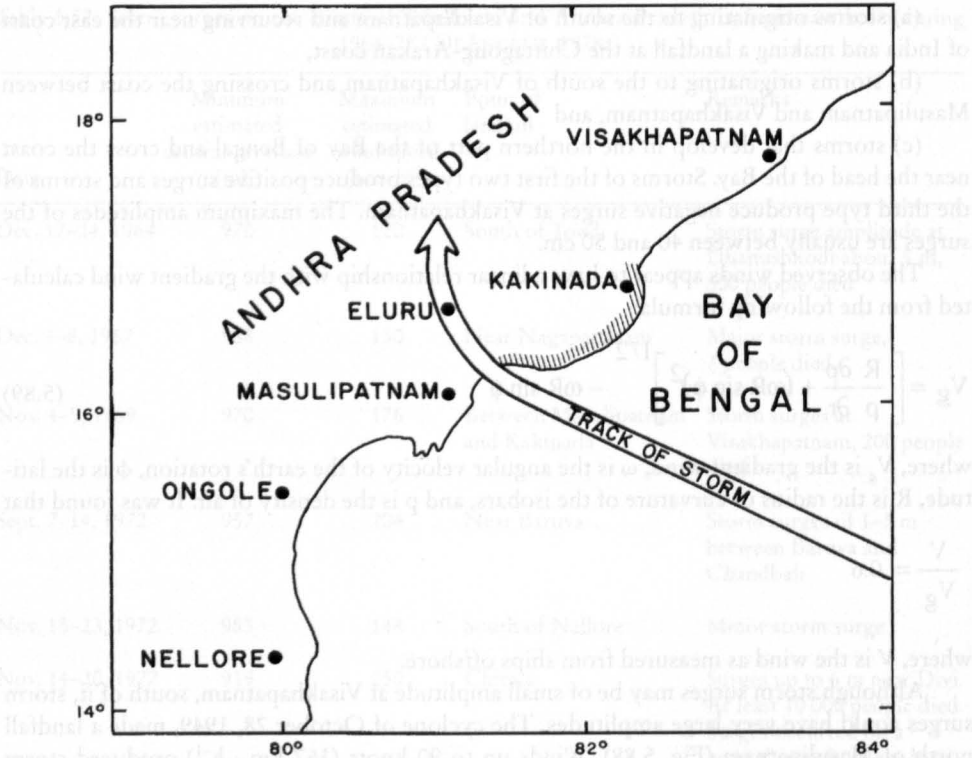


Fig. 5.88: Track of the storm of October 1949 on the southeast coast of India. Hatched area shows the coastline affected by the storm surge (RAO, 1968)

JOHNS and ALI (1980) used the following pressure distribution in their simulation of the November 1970 storm surge that caused great devastation in Bangladesh.

$$p = p_a - \Delta p \exp\left(-\frac{r}{R}\right) \tag{5.90}$$

where, p is the pressure field at radius r , p_a is the ambient pressure, Δp is the difference between the ambient and central pressures, and R is the e-folding radius of the pressure distribution.

A value of 350 km was given to HOLLAND (1980) pointed out that R should be the radius of maximum winds and that a typical value of R should be about 35 km.

The argument that R should be the radius of maximum winds was developed by HOLLAND (1981) as follows. For tropical cyclones, a typical Rossby number will be about 100, in the strongest wind region. One may assume a cyclostrophic balance and write

$$V_c = \left(\frac{r}{\rho} \frac{\partial p}{\partial r}\right)^{1/2} \tag{5.91}$$

where, V_c is the cyclostrophic tangential wind and ρ is the air density. Substituting eq. (5.90) into (5.91)

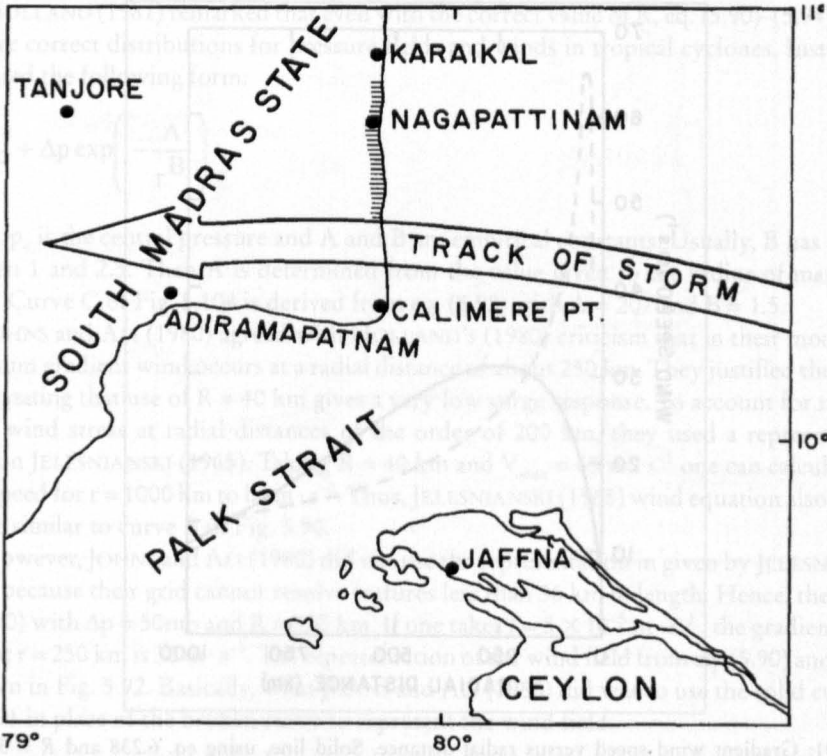


Fig. 5.89: Track of the storm of November 1952 on the southeast coast of India. Hatched area shows the coastline affected by the storm surge (RAO, 1968)

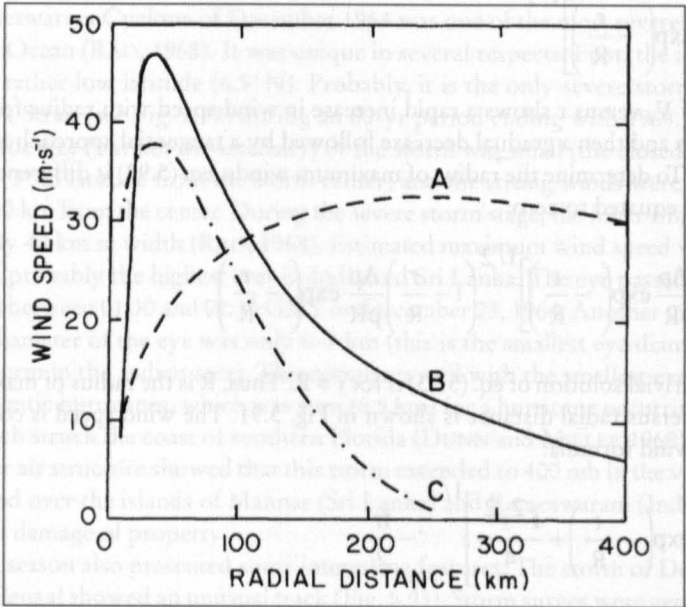


Fig. 5.90: Gradient wind speed versus radial distance. Curve A, $R = 350$ km; curve B, $R = 35$ km; curve C, from eq. 6.243 (HOLLAND, 1981)

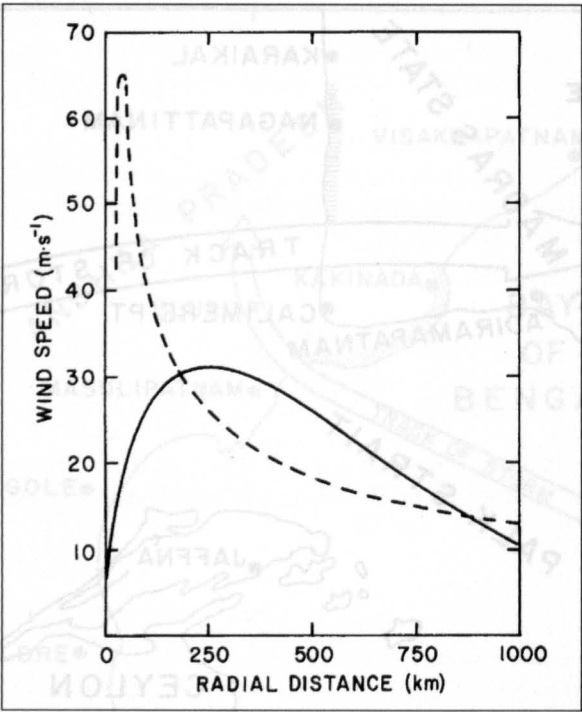


Fig. 5.91: Gradient wind speed versus radial distance. Solid line, using eq. 6.238 and $R = 350$ km; broken line, using eq. 6.143, $R = 40$ km, and $V_c = 65$ m. s⁻¹ (JOHNS and ALI, 1981)

$$V_c = \left[\frac{r \Delta p}{\rho R} \exp \left(-\frac{r}{R} \right) \right]^{1/2} \tag{5.92}$$

A plot of V_c versus r shows a rapid increase in wind speed with radius from the center to a maximum and then a gradual decrease followed by a tangential approach to zero at infinite distance. To determine the radius of maximum winds, eq. (5.92) is differentiated with respect to r and equated to zero:

$$\frac{\partial V_c}{\partial r} = \frac{1}{2} \left[\frac{r \Delta p}{\rho R} \exp \left(-\frac{r}{R} \right) \right]^{1/2} \left(1 - \frac{r}{R} \right) \frac{\Delta p}{\rho R} \exp \left(-\frac{r}{R} \right) \tag{5.93}$$

The nontrivial solution of eq. (5.93) is for $r = R$. Thus, R is the radius of maximum winds. Wind speed versus radial distance is shown in Fig. 5.91. The wind speed is computed from the gradient wind formula:

$$V_g = \left[\frac{r \Delta p}{\rho R} \exp \left(-\frac{r}{R} \right) + \frac{f^2 r^2}{4} \right]^{1/2} - \frac{fr}{2} \tag{5.94}$$

where, V_g is the gradient wind and f is the Coriolis parameter. The following values were used: $\Delta p = 50$ mb, $p = 1.2$ km · m⁻³, $f = 5 \times 10^{-5}$ · s⁻¹.

HOLLAND (1981) remarked that even with the correct value of R , eq. (5.90)–(5.94) might not give correct distributions for pressure fields and winds in tropical cyclones. Instead, he suggested the following form:

$$p = p_c + \Delta p \exp\left(-\frac{A}{r^B}\right) \quad (5.95)$$

where, p_c is the central pressure and A and B are empirical constants. Usually, B has a value between 1 and 2.5. Then A is determined from the value given to the radius of maximum winds. Curve C of Fig. 5.104 is derived from eq. (5.95) with $A = 207$ and $B = 1.5$.

JOHNS and ALI (1980) agreed with HOLLAND'S (1980) criticism that in their model, the maximum gradient wind occurs at a radial distance of about 250 km. They justified their model by stating that use of $R = 40$ km gives a very low surge response. To account for the role of the wind stress at radial distances of the order of 200 km, they used a representation based on JELESNIANSKI (1965). Taking $R = 40$ km and $V_{\max} = 65 \text{ m} \cdot \text{s}^{-1}$ one can calculate the wind speed for $r = 1000$ km to be $\text{m} \cdot \text{s}^{-1}$. Thus, JELESNIANSKI (1965) wind equation also shows a curve similar to curve B of Fig. 5.90.

However, JOHNS and ALI (1980) did not use the representation in given by JELESNIANSKI (1965) because their grid cannot resolve features less than 36 km in length. Hence, they used eq. (5.90) with $\Delta p = 50 \text{ mb}$ and $R = 350$ km. If one takes $f = 5 \times 10^{-5} \text{ m} \cdot \text{s}^{-1}$, the gradient wind speed at $r = 250$ km is $30 \text{ m} \cdot \text{s}^{-1}$. The representation of the wind field from eq. (5.90) and (5.95) is shown in Fig. 5.92. Basically, what JOHNS and ALI (1980) did was to use the solid curve of Fig. 5.91 in place of the broken curve to represent the wind field.

Case Studies of Cyclonic Storms in the Bay of Bengal During the Period 1964–99

The Rameswaram Cyclone of December 1964 was one of the most severe storms of the North Indian Ocean (RAO, 1968). It was unique in several respects. First, the intensification occurred at a rather low latitude (6.5°N). Probably, it is the only severe storm that moved across the Palk Strait (see Fig. 5.92) during an 80-yr period ending with 1964. Another feature was that the size (but not the intensity) of the storm was small (the closed isobaric field extended only 3° in latitude from the storm center) and the strong winds were confined to a region 100–150 km from the center. During the severe storm stage, the inner ring of hurricane winds was only 40 km in width (RAO, 1968). Estimated maximum wind speed was 175 knots ($324 \text{ km} \cdot \text{h}^{-1}$), probably the highest ever in India and Sri Lanka. The eye passed over Rameswaram (India) between 01:30 and 02:30 GMT on December 23, 1964. Another unusual feature was that the diameter of the eye was only 6–7 km (this is the smallest eye diameter reported for a severe storm in the Indian area). This compares well with the smallest eye diameter reported for Atlantic hurricanes, which was 4 mi (6.5 km) for a hurricane occurring on July 27, 1936, and which struck the coast of southern Florida (DUNN and MILLER 1960).

The upper air structure showed that this storm extended to 400 mb in the vertical. Storm surges occurred over the islands of Mannar (Sri Lanka) and Rameswaram (India) with great loss of life and damage of property.

The 1965 season also presented some interesting features. The storm of December 1965 in the Bay of Bengal showed an unusual track (Fig. 5.93). Storm surges were generated on the coast of Bangladesh and heavy casualties followed. Not only was the track unusual, but also the duration of the storm was 9 d compared with the usual 1–3 d. During a 70-yr period,

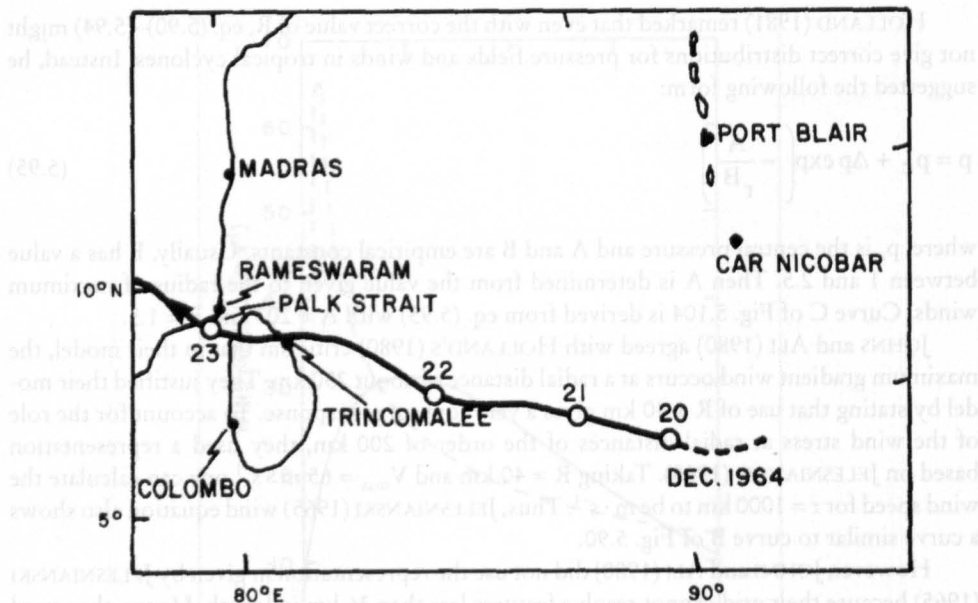


Fig. 5.92: Track of the severe storm of December 1964 over Sri Lanka (RAO, 1968)

about 77 % of the storms in the Bay of Bengal lasted only 1–4 d, 17 % lasted for 5–6 d, and only 7 % (i.e. three storms) lasted for 7 d. The average duration for the Bay of Bengal storms is 3.5 d (compared with the average life span of global tropical cyclones, which is 6.5 d according to RIEHL, 1954). Another unusual feature was that this storm hit Bangladesh and Burma in December. Note that in the 70-yr period only 13 storms did this. A final unusual feature was the simultaneous presence of another storm in the Arabian Sea (see Fig. 5.93). Only five times before has a similar situation existed (i.e. storms in the Bay of Bengal and the Arabian Sea at the same time). These cases are listed in Table 5.54 and their tracks are illustrated in Fig. 5.93.

The 1966 season produced a maximum number of storms in the postmonsoon season (RAMAN et al., 1967). The following deductions were made by RAMAN et al. (1967).

The thermodynamical conditions necessary for the development of cyclone storms, as discussed by PALMÉN (1955), are found in all the postmonsoon months. However, additional conditions must be satisfied. One of the reasons for the high cyclone activity in the 1966 season was the continued northward position of the equatorial trough. Even though the low latitude wind fields in 1959 and 1966 were similar, the absence of northward horizontal shear in the wind field of 1959 inhibited the development.

The required minimum energy for development is available at the air-sea interface during all postmonsoon months. However, for maturity into severe storms, the zones of maximum evaporation should also take place in preferred areas. During the 1966 season, the atmosphere gained the maximum heat over the southwest and west central parts of the Bay of Bengal. Generally, only in this region do all disturbances mature into cyclonic storms. On the other hand, in November 1954, maximum evaporation took place over the southwest part of the bay, south of 10° N. Finally, the origin, intensification and movement of cyclonic storms coincide with the zones of convergence of the total energy that is available in the atmosphere.

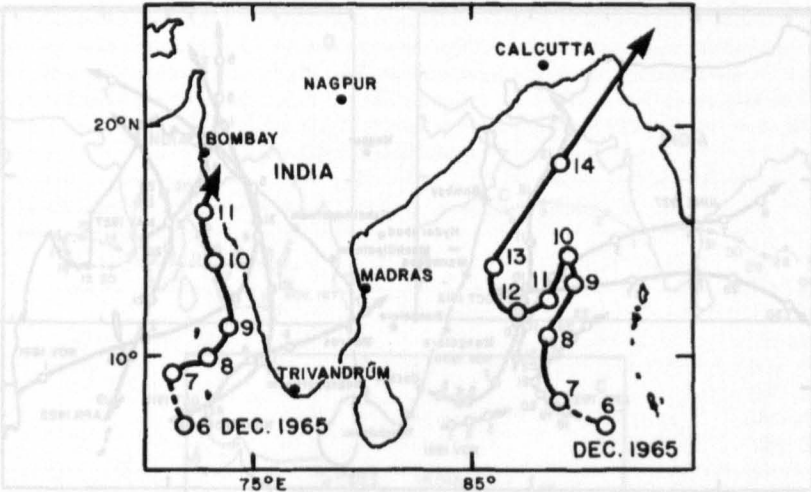


Fig. 5.93: Tracks of a storm pair in the Bay of Bengal (December 7–15, 1965) and Arabian Sea (December 7–12, 1965) (SWAMINATHAN, 1966)

Table 5.54: Details of storm pairs in the Bay of Bengal and the Arabian Sea during the period 1891–1960. Date indicated refers to the original date of the storm. In each pair, the top row is for the Bay of Bengal and the bottom row for the Arabian Sea (SWAMINATHAN, 1966)

Origin		
Date	Latitude (° N)	Longitude (° E)
Nov. 1, 1981	8.0	74.5
Nov. 1, 1891	9.5	98.5
Oct. 25, 1912	15.0	72.5
Oct. 28, 1912	8.5	89.0
Apr. 18, 1922	9.0	68.5
Apr. 19, 1922	9.5	93.0
May 31, 1927	11.5	71.0
May 31, 1927	17.5	91.5
Nov. 3, 1936	9.5	75.0
Nov. 4, 1936	9.0	88.0

However, the 1977 season was an especially bad one. On November 19, a cyclone hit the coast of Andhra Pradesh (India) and produced storm surges greater than 5 m in amplitude. The path of this storm is shown in Fig. 5.95 a (track A). Between November 21 and 22, another Bay of Bengal originated storm struck the west coast of India (Fig. 5.95 a, track B). This storm also caused great damage. On October 28, a storm originating in the Bay of Bengal struck the coast of Arabia between November 4 and 5 (Fig. 5.95 b, track C).

WINCHESTER (1979) provided the following details about the Andhra coast storm of November 19. The storm made a landfall near the mouth of the Krishna River with a speed of 12 mi · h⁻¹ (19.5 km · h⁻¹) with wind speeds of 75 mi · h⁻¹ (121 km · h⁻¹) and gusting to 120 mi · h⁻¹ (193 km · h⁻¹). The storm surge was 5 m in amplitude and penetrated at least 10 mi

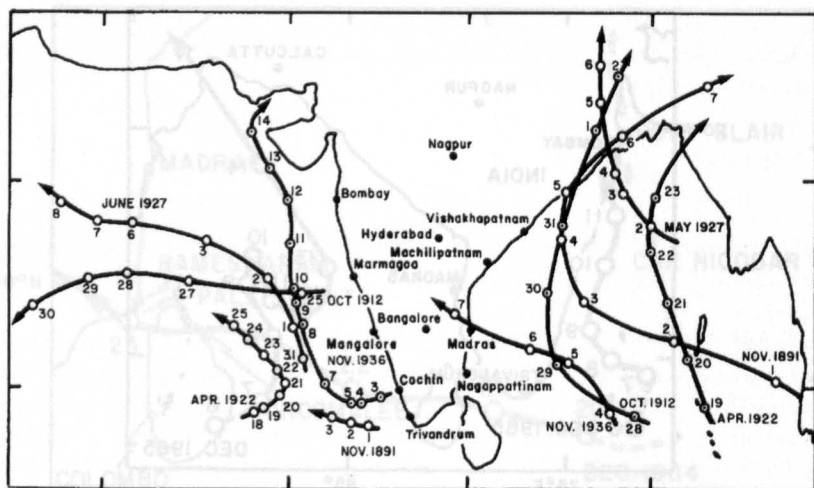


Fig. 5.94: Tracks of storm pairs in the Bay of Bengal and the Arabian Sea during 1891–1960 (SWAMINATHAN, 1966)

(16 km) inland with a speed of about $10 \text{ mi} \cdot \text{h}^{-1}$ ($16 \text{ km} \cdot \text{h}^{-1}$) over a coastal stretch of 35 mi (56 km). The high water due to the surge remained for about 10 h. The cyclone and the storm surge together totally damaged an area of about 7500 mi^2 ($195\,000 \text{ km}^2$). At least 20 000 people died and 2 million people were left homeless (DEANGELIS, 1978a, 1978b, 1978c, 1978d).

There was no significant storm surge activity in India during 1978. However, Sri Lanka experienced a very devastating storm surge during this year (damage of \$ 50 million). On November 21, 1978, a tropical storm generated near the Nicobar Islands matured to hurricane strength and on November 23 it struck the east coast of Sri Lanka (Fig. 5.95 c, track D). The resulting storm surge together with the cyclone and the resulting landslides that occurred killed 373 people and destroyed 80 000 houses. Wind gusts up to $204 \text{ km} \cdot \text{h}^{-1}$ occurred. The storm surge inundated rice fields up to 8 km inland. The storm then moved to India over the Gulf of Mannar where it killed 10 people (DEANGELIS, 1979a, 1979b, 1979c).

One humorous sidelight of this cyclone was that 160 convicts escaped when the roof blew off the jail in Batticaba (Sri Lanka). The fact that not everybody is inconvenienced by a natural disaster such as a storm surge can be seen from the fact that, invariably, after the disaster looters descend upon the scene and helped themselves. These are also good times for black marketeers and food hoarders, especially in the developing countries.

When one of the author of this book (T. S. Murty) visited his native village in Andhra Pradesh, India, in 1978 (1 yr after the disastrous storm surge of November 1977), tales of how village officers confiscated the emergency relief funds (provided by the federal government of India as well as by several international agencies) for their own use were mentioned to him. Although this author is not an expert on sociological aspects, his early background in developing countries convinced him that there is much truth to these tales. He was given to understand by the villagers that corruption is minimal to nonexistent with federal (central) government officers (due to the higher calibre of the federal civil service and also due to various built-in checks against corruption), and that corruption increases by an order of magnitude with the provincial (state) government officers, then by another order of magnitude with the district (county) level of government, and to absolute and total corruption at the municipal

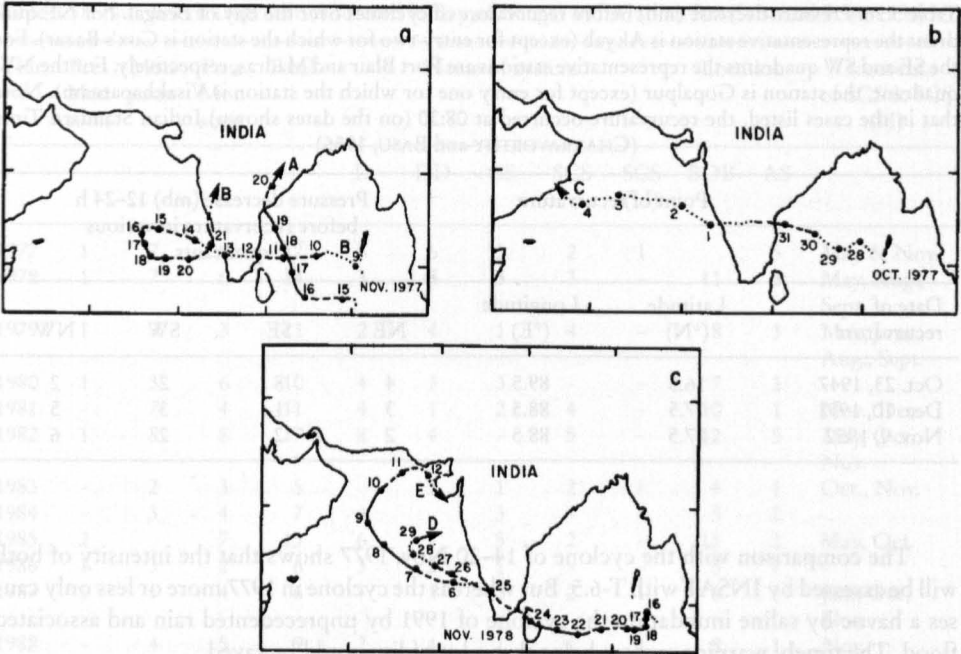


Fig. 5.95: (a) Track A: storm of November 1977 that caused great damage to the Andhra Pradesh Coast of India; track B: storm of November 1977 that did moderate damage to the west coast of India. (b) Track C: storm originating in the Bay of Bengal on October 28, 1977, that struck the coast of Arabia. (c) Track D: storm of November 1978 that did great damage on the east coast of Srilanka; track E: storm of November 1978 originating in the Arabian Sea and striking the Gujarat coast of India (DE ANGELIS, 1978a,1978b, 1978c, 1978d)

(city, town, village) level. We would like to recommend to the international agencies that provide emergency relief funds to any developing country that only the federal government officials be involved in the handling of the relief operations.

SOM and SOM (1995) describe the Machilipatnam cyclone on 9th May 1990, which hit the Andhra coast (eastern coast of India) with an estimated force reaching 200 to 250 kph. Over the coastal area heavy rainfall has been happened. 967 people died and 650,000 people were evacuated from 546 coastal villages. They pointed out that the storm affected a population of about 7.78 million in 5160 villages in Andhra Pradesh. It was one of the severest cyclones in the Bay of Bengal whereas in Andhra coast another earlier cyclone struck the coast with an equal intense.

Table 5.55: Storms and depressions in the Bay of Bengal, 1945–54. A, total number; B, number that recurved. Storms and depressions that recurved on land or while in the Arabian Sea have been excluded (CHAKRAVORTHY and BASU, 1956)

Type	Jan.	Feb.	Mar.	Apr.	May	June	July	Aug.	Sept.	Oct.	Nov.	Dec.
A	5	1	1	5	6	11	18	19	19	18	12	11
B	2	0	0	1	1	0	0	0	0	5	1	4

Table 5.56: Pressure decrease (mb) before recurvature of cyclones over the Bay of Bengal. For NE quadrant the representative station is Akyab (except for entry two for which the station is Cox's Bazar). For the SE and SW quadrants the representative stations are Port Blair and Madras, respectively. For the NW quadrant, the station is Gopalpur (except for entry one for which the station is Visakhapatnam). Note that in the cases listed, the recurvature occurred at 08:30 (on the dates shown) Indian Standard Time (CHAKRAVORTHY and BASU, 1956)

Date of recurvature	Point of recurvature		Pressure decrease (mb) 12–24 h before recurvature in various quadrants			
	Latitude (°N)	Longitude (°E)	NE	SE	SW	NW
Oct. 23, 1947	16.5	89.5	4	8	2	2
Dec. 10, 1951	17.5	88.5	3	1	3	5
Nov. 9, 1952	17.5	88.5	2	2	2	6

The comparison with the cyclone of 14–20 Nov. 1977 shows that the intensity of both will be assessed by INSAT with T-6.5. But whereas the cyclone in 1977 more or less only causes a havoc by saline inundation the cyclone of 1991 by unprecedented rain and associated flood. The timely warning system helps that a lot of live could be saved.

SOM and SOM (1995) although describe the cyclone on 29 April, 1991 which has been happened about 12 hours long and occurred a 5 meter high storm surge. 10 Million people were affected and the country had suffered incalculable economic damage. SOM and SOM (1995) described the situation as follows:

“Whether it was an island (like Sandwip or Kutubdia) or a place on the main land, one moment there were communities of ten thousands or more, three hours later there was absolutely nothing. Just enormous street of salt water dwarfing everything save the tall palm trees. It swept heavily populated areas several kilometres inland along a 240 km coastal stretch of Bangladesh and all the offshore islands. The seawater took merely 10 minutes to reach neck deep water levels at highest points of Sandwip islands. The official tally of the casualties was approximately 132,000. But exact number of deaths would never be known as no one knew how many people had been washed away in the Bay of Bengal. However, unofficial estimate of casualties was half a million.”

Arabian Sea

Compared with the Bay of Bengal, the storms of the Arabian Sea are less frequent, generally less intense, and the accompanying storm surges are usually less destructive (Table 5.57). The statistics by month for the period 1891–1960 are given in Table 5.58.

PEDGLEY (1969) mentioned that cyclones develop preferentially over the southeastern quadrant of the Arabian Sea and move in a west to northwest direction towards Arabia. However, sometimes they recurve to the north or northeast towards northwestern India and Pakistan (Fig. 5.96). About one storm in three passes over the western part of the Arabian Sea and strikes the coast of the Arabian peninsula.

Table 5.57: Number of Depressions formed in Bay of Bengal and Arabian Sea (SOM and SOM, 1995)

Year	Pre- Mon soon	Mon soon	Post Mon soon	Total	Name of system					Location		Occurrence of SCS & SCS (H)
					D	DD	CS	SCS	SCS (H)	BOB	AS	
1977	1	7	9	17	5	6	3	2	1		5	May & Nov.
1978	1	7	6	14	3	5	3	3	-	11	3	May, Aug., Sept.
1979	1	7	3	11	2	4	1	4	-	8	3	May, June, Aug., Sept.
1980	1	3	6	10	4	3	3	-	-	7	3	-
1981	-	7	4	11	4	1	2	4	-	10	1	Nov., Dec.
1982	1	8	8	17	8	4	-	5	-	12	5	May, Oct. Nov.
1983	-	2	3	5	-	2	1	2	-	4	1	Oct., Nov.
1984	-	3	4	7	4	-	3	-	-	5	2	-
1985	2		7	13	6	-	5	2	-	11	2	May, Oct.
1986	1	3	2	6	3	2	1	-	-	5	1	-
1987	1	1	4	6	-	1	2	2	1	6	-	Jan., Oct, Nov.
1988	-	4	5	9	2	4	1	1	1	8	1	Nov.
1989	1	5	4	10	3	4	1	-	2	9	1	May & Nov.
1990	1	3	5	9	4	3	-	1	1	8	1	May & Dec.
1991	2	3	3	8	4	1	2	-	1	8	-	April
1992	1	3	8	12	1	4	5	1	1	8	4	Nov.

D – Depression, DD – Deep Depression, CS – Cyclonic Storms, SCS – Severe Cyclonic Storms, SCS (II) – Severe Cyclonic Storms with Hurricane Wind, BOB – Bay of Bengal, AS – Arabian Sea.

Table 5.58: Data on the cyclonic storms of the Arabian Sea during the period 1891–1960 (RAO, 1968)

Type of storm	Jan.	Feb.	Mar.	Apr.	May	June	July	Aug.	Sept.	Oct.	Nov.	Dec.	Year
Total number of cyclonic disturbances	6	0	1	7	20	30	11	21	0	36	36	8	165
Total number that intensified into storms	2	0	0	5	13	13	3	1	4	17	21	3	82
Total number that intensified into severe storms	0	-	-	4	11	8	0	0	1	7	16	1	48

The frequency of cyclonic storms for the period 1891–1967 is given in Table 5.59. About one cyclonic storm in 3 yr strikes the coast and about half of these that strike have cyclone strength. Usually the cyclones make landfall near Salalah and they show a tendency to turn to the left at a distance of a few hundred kilometres from the coast. The 10 cyclones that hit the Arabian coast during 1943–67 are listed in Table 5.60.

Table 5.59: Number of occurrences of cyclones (Beaufort ≥ 12) and cyclonic storms (BF ≥ 8) over the whole Arabian Sea during the period 1890–1950 and number of occurrences along the Arabian coast during the period 1891–1967. For the Beaufort wind scale, see Tables 5–6–18 (PEDGLEY, 1969)

Type of storm	Jan.	Feb.	Mar.	Apr.	May	June	July	Aug.	Sept.	Oct.	Nov.	Dec.	Year
Cyclones and Cyclonic storms over the whole Arabian Sea	1	0	0	4	10	11	2	1	4	15	12	3	63
Cyclones and Cyclonic storms along the coast of Arabia	0	0	0	0	8	5	1	0	0	7	6	1	28
Cyclones along the coast of Arabia	0	0	0	0	6	2	0	0	0	2	2	1	13

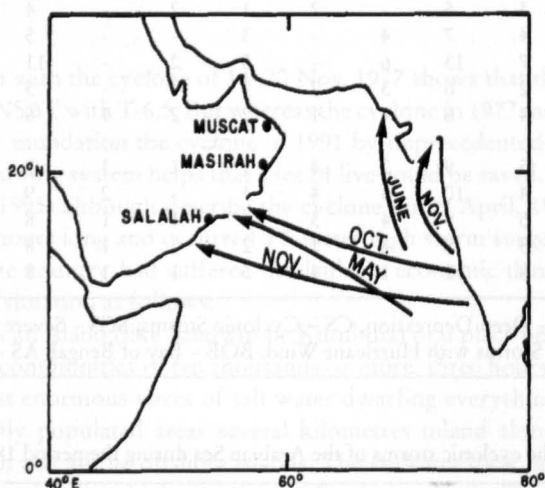


Fig. 5.96: Common tracks of Arabian Sea cyclones (PEDGLEY, 1969)

Table 5.60: Cyclones near the coast of the Arabian peninsula during 1943–1967 (PEDGLEY, 1969)

Date of approach or crossing the coast	Nature of the cyclone
June 6, 1946	Decaying before approaching Masirah from east-southeast
October 1, 1948	Decaying before approaching coast between Masirah and Ra's al Hadd from east
October 25, 1948	Cyclonic storm crossed Salalah, approaching from southeast
May 24, 1959	Severe cyclone crossed Salalah, approaching from east-southeast
October 18, 1959	Severe cyclone crossed near Ras Madraka, approaching from east
May 18, 1960	Severe cyclone crossed coast at Ras Fartak
November 23, 1960	Cyclonic storm approached entrance to Gulf of Aden from east
May 30, 1962	Decaying before crossing coast at Ras Madraka
May 26, 1963	Severe cyclone, passed just south of Salalah, approaching from east-southeast and then turning towards west-southwest
November 13, 1966	Severe cyclone with a track similar to that of May 1963

The following pressure distribution

$$p = 1008 - 1.64(v_r r)$$

(5.96)

appears to fit the central pressure of the Arabian Sea cyclones. Here, p is the central pressure (millibars) and v_r is the radial wind speed in knots at a distance from the center of r degrees latitude (KRUEGER, 1959). The maximum wind speed v_m can be estimated from MYERS (1957):

$$v_m = K\sqrt{p' - p}$$

(5.97)

where p' is the surrounding pressure and K is a constant (equal to 11). For example, taking $p = 960$ mb and $p' = 1010$ mb gives $v_m = 80$ knots ($148 \text{ km} \cdot \text{h}^{-1}$).

Although most of the Arabian Sea cyclones originate locally, some (6 of the 28 mentioned in Table 5.59) originated in the Bay of Bengal. Usually, cyclones with this distant origin occur towards the end of the cyclone season (i.e. towards November). Occasionally, the Arabian Sea cyclones cross the Gulf of Aden and even rarely the Gulf of Oman.

One difference between the cyclones of the Arabian Sea and the Bay of Bengal is that, whereas in the Bay of Bengal more cyclones occur in the postmonsoon season (September to December) than in the premonsoon season (April to May), in the Arabian Sea they are about equally distributed between the two cyclone seasons (i.e. May to June and October to November). Most of these originate over the southeastern Arabian Sea and move towards west-northwest. However, a few originate in the Bay of Bengal and cross southern Indian peninsula before emerging over the Arabian Sea.

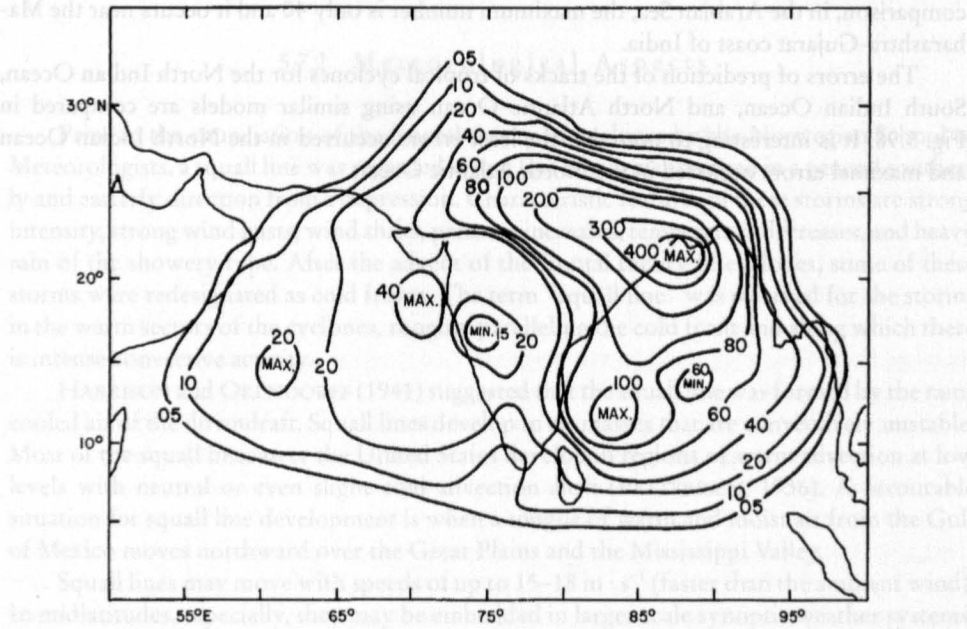


Fig. 5.97: Contours of a number of tropical cyclones (including depressions) passing through 2.5° latitude-longitude squares for the period 1877–1974 (NEUMANN and MANDAL, 1978)

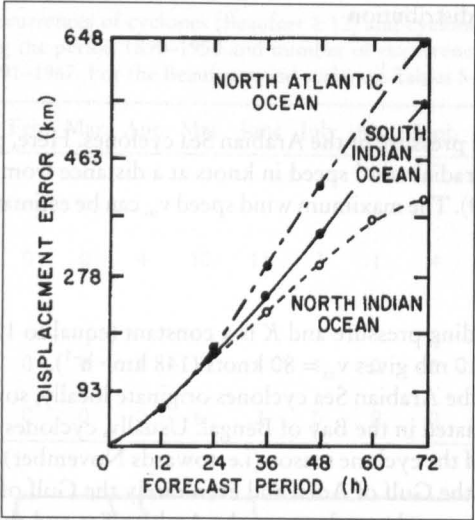


Fig. 5.98: Forecast errors in the tracks of tropical cyclones for three different ocean basins (NEUMANN and MANDAL, 1978)

NEUMANN and MANDAL (1978) used statistical techniques to predict the storm movement over the Arabian Sea and the Bay of Bengal. The number of tropical cyclones (including depressions) passing through 2.5° latitude-longitude squares for the period 1877–1974 is given in Fig. 5.97. It can be seen that maximum values of up to 400 cyclones and depressions occurred near the coasts of West Bengal (India) and Bangladesh in the Bay of Bengal. By comparison, in the Arabian Sea, the maximum number is only 40 and it occurs near the Maharashtra-Gujarat coast of India.

The errors of prediction of the tracks of tropical cyclones for the North Indian Ocean, South Indian Ocean, and North Atlantic Ocean using similar models are compared in Fig. 5.98. It is interesting to note that the least errors occurred in the North Indian Ocean and maximal errors occurred in the North Atlantic Ocean.

5.7 Mesoscale Weather Systems

HOBBS (1981) defined a mesoscale weather system as one with horizontal scales in the range of a few to 1000 km and time scales ranging from several hours to 1 d. Squall lines, thunderstorms, and tornadoes fall into the classification of mesoscale weather systems. Here, squall lines are specifically examined, since, as will be seen later, they can give rise to storm surges.

Squall lines are nonfrontal lines of active thunderstorms, several to some tens of kilometers wide and hundreds of kilometers long, which exist for a considerably longer period than the lifetime of the component cumulonimbus clouds (RAMAGE, 1971).

Stationary as well as traveling mesoscale weather systems such as those that occur over the Great Plains of the United States are classified further into the following: regional scale (200–2000 km), or meso-alpha; squall line scale (20–200 km), or meso-beta; cloud scale (2–20 km), or meso-gamma (ANONYMOUS, 1978).

5.7.1 Regions Where Squall Lines Occur

Squall lines occur in midlatitudes as well in the tropics. They occur mainly over the United States, Central, West, and South Africa, Venezuela, northern India, and northern Australia. In the United States they occur predominantly during spring and summer.

According to HAMILTON and ARCHBOLD (1945) and TSCHIRHART (1958), sub-Saharan Africa is a fertile ground for squall lines and, in fact, these account for most of the rainfall. Another area where squall lines occur is the Caribbean Sea. On rare occasions, squall lines can also be observed over the southern part of the North Sea.

5.7.2 Meteorological Aspects

Prior to the enunciation of the frontal theory of cyclones by the Norwegian School of Meteorologists, a squall line was regarded as any line of storms arranged in a general southerly and easterly direction from a depression. Characteristic features of these storms are strong intensity, strong wind gusts, wind shifts, pressure increases, temperature decreases, and heavy rain of the showery type. After the advent of the frontal theory of cyclones, some of these storms were redesignated as cold fronts. The term “squall line” was reserved for the storms in the warm sectors of the cyclones, roughly paralleling the cold front and along which there is intense convective activity.

HARRISON and ORENDORFF (1941) suggested that the squall line was formed by the rain-cooled air of the downdraft. Squall lines develop in air masses that are convectively unstable. Most of the squall lines over the United States develop in regions of warm advection at low levels with neutral or even slight cold advection aloft (PETTERSEN, 1956). A favourable situation for squall line development is when a tongue of warm and moist air from the Gulf of Mexico moves northward over the Great Plains and the Mississippi Valley.

Squall lines may move with speeds of up to $15\text{--}18\text{ m}\cdot\text{s}^{-1}$ (faster than the ambient wind). In midlatitudes, especially, they may be embedded in larger scale synoptic weather systems. In such situations, the intense part of the weather might be concentrated only in about 10% of the area of the synoptic system. The life span of a squall line is much shorter

than that of the synoptic scale system in which it is embedded (e.g. a few hours versus a few days).

Squall lines have low-level indraft along their forward edge due to rapid motion (RIEHL, 1979). Individual cumulonimbus clouds in a squall line have life times of at most a few hours. Hence, for a squall line to survive, new convective elements continually replace dissipating elements (RAMAGE, 1971). Squall lines usually become most intense during late afternoons when the convective activity is the highest.

NEWTON and NEWTON (1959) and NEWTON (1967) showed that the continuous exchange of mass between the storm and the surroundings leads to a nonhydrostatic pressure that aids the convection process. On the downshear side the convective elements continually develop whereas on the upshear side they dissipate. Hence, the storm moves in the direction of developing elements and away from dissipating elements.

Over the Central United States the squall lines move 25° to the right of and about $4 \text{ m} \cdot \text{s}^{-1}$ slower than the mean wind at the 700-mb level. Squall lines over the midwestern and northeastern parts of the United States deviate 50 and 70° , respectively, to the right of the wind direction at the 700-mb level.

Squall lines usually develop near topographic discontinuities (mountains and valleys). Generally, squall lines tend to dissipate when they cross a coast because cool and relatively stable surface air suppresses ascent due to buoyancy (RAMAGE, 1971).

In northern India, squall lines occur in spring and fall (DE, 1963). In northern Australia, squall lines occur mainly in spring. The West African squall lines resemble those over the United States in the following respects: they tend to develop and are most intense in the afternoon and are most frequent in spring. However, there are certain differences also. The West African squall lines are usually embedded in an environment possessing easterly vertical shear and they travel westward with velocities of up to $10 \text{ m} \cdot \text{s}^{-1}$. Although the life span of most squall lines is less than 24 h, some persist for several days and travel more than 3000 km. Although most squall lines weaken after crossing a coastline, some do not (e.g. over the warm Guinea current).

Probably the first systematic study of squall lines emerged from the U.S. thunderstorm project during 1946–48. WILLIAMS (1948) used the data from the automatic recording stations in Ohio operated by the U.S. Weather Service's cloud physics project to deduce the microstructure of squall lines.

TEPPER (1950a, 1950b) described the meteorological features associated with the arrival of an intense squall line at the ground. Initially there is an abrupt rise in the surface pressure, which he referred to as a "pressure jump". FUJITA (1955) called it the "pressure surge". Within 1 min after the pressure jump there is a sudden change in the wind direction, which was referred to as "wind shift." Then, the temperature begins to drop rapidly within 2 min after the wind shift. This drop of temperature was referred to as the "temperature break". The peak wind gust, the onset of rain, and the pressure maximum follow the temperature break.

On the other hand, FUJITA (1955) described the situation somewhat differently. Following the pressure surge, the thunderstorm high occurs and then the pressure decreases. The low pressure areas following the wake drop in pressure are called wake depressions.

BEDARD et al. (1977) and BEDARD and MEADE (1977) described an inexpensive instrument system that was deployed at the Dulles Airport in Washington, DC, to measure the gust fronts associated with squall lines. NOAA (ANONYMOUS, 1978) described the various modeling activities on squall lines that are being done at the National Severe Storms Laboratory (United States). A model being developed by Fritsch (ANONYMOUS, 1978) incorporates the effects of deep convection and shows how a series of thunderstorms can become organized

into groups and how they can influence the winds and pressures in the surroundings. Warm moist air accumulates in front of the squall line, and this leads to a low pressure system at the surface; colder air from the thunderstorm downdraft forms a high pressure area behind the squall line. Presently used weather forecast models cannot resolve the squall lines adequately because the grids used are of the order of 200 km in size.

The official U.S. Weather Service definition of pressure jump (associated with a squall line) is an increase of pressure of more than 0.17 mb min^{-1} with at least a total increase of 0.7 mb. TEPPER (1950) suggested that the detection of the pressure jump could be used as an indication of the movement of the squall line.

Time series data on pressure jumps were published by TEPPER (1950b), FUJITA (1959), and CHARBA (1974). These data show increases of several millibars in surface pressure during a period of a few minutes. TEPPER's (1950a,b) data showed pressure increases of 2.3 mb in 5 min. WILLIAMS' (1948) data showed a 2- to 5-mb rise in 5 min. GOFF (1975) found an average increase of 2.5 mb in 100 s. BLECKER and ANDRE (1950) found significant pressure increases in 10 min.

As for the speed of travel, WILLIAMS (1948) gave a value of 13.4 m s^{-1} , TEPPER (1950) found 20.4 m s^{-1} , and GOFF (1975) found 10 m s^{-1} . On the other hand, DE (1963), based on a study of 44 squall lines in northern India, found a value of $33 \text{ km} \cdot \text{h}^{-1}$. He quoted values from other authors ranging from 35 to $40 \text{ km} \cdot \text{h}^{-1}$. DE (1963) also found that the direction of movement of the squall lines is generally within 90° to the right (looking downwind) of the 700-mb wind. They occurred mainly during March–May and their life span varied from 3 to 10 h. Their lengths varied from 40 to 400 km and their speed of travel varied from 20 to $50 \text{ km} \cdot \text{h}^{-1}$. For comparison, some data on squall lines in Venezuela are listed in Table 5.61.

Table. 5.61: Squall lines over Venezuela (BETTS et al., 1976)

Major axis of squall line (km)	Minor axis of squall line (km)	Life span (min)	Observed track length (km)	Speed of travel ($\text{km} \cdot \text{h}^{-1}$)
96	32	200	136	51.1
90	46	240	131	38.5
120	27	211	170	55.0
95	20	215	161	59.4
100	30	140	154	52.4
100	31	195	150	52.0

The cross-section through a squall line system is shown schematically in Fig. 5.100. Important results on squall lines may be found in LILLY (1979), OGURA and LIOU (1980), BETTS et al. (1976), ZIPSER (1969, 1977), HOUZE (1977), MITCHELL and HOVERMALE (1977), CHARBA (1974), MONCRIEFF and MILLER (1976) and MILLER and BETTS (1977).

5.7.3 Squall Line Forcing Terms for Storm Surge Calculation

WILSON (1978) developed simplified pressure and wind profiles for a “historical maximum squall line” for use in estimating water levels near United States nuclear power plants. One very important point to be made is that, whereas with synoptic scale weather systems

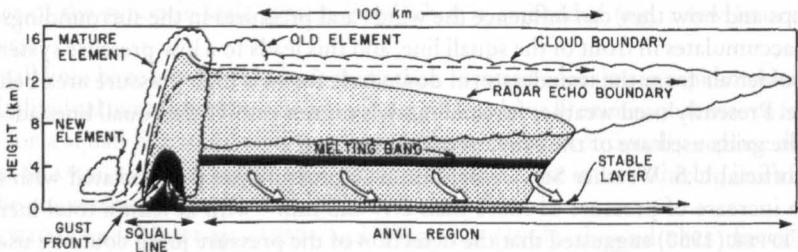


Fig. 5.99: Schematic cross-section through a squall line system. Streamlines show flow relative to the squall line. Broken lines show updraft circulation. Thin solid streamlines show mesoscale downdraft below the base of the anvil cloud. Dark shading shows strong radar echo in the melting band and in the heavy precipitation zone of the mature squall line element. Light shading shows weaker radar echoes. Scalloped line shows visible cloud boundaries (Houze, 1977)

(e.g. tropical and extratropical cyclones) usually the wind stress is much more important than the atmospheric pressure gradients, for squall lines, the pressure gradient terms are at least of equal importance and sometimes much bigger than the wind stress terms.

Following FUJITA (1955), WILSON (1978) developed a simple model for a squall line system, as shown in Fig. 5.100. He also made the following assumptions: (a) the squall line is in a steady state and is in the mature stage, (b) the leading edge of the pressure surge and the gust front move with the same speed (this is in contrast with FUJITA's [1955]) result that the pressure surge moves with a speed some 40 % greater than that of the gust front), and (c) the squall line moves perpendicular to the shoreline.

Making use of these assumptions and the model shown in Fig. 5.100, WILSON (1978) developed the pressure and wind profiles (Fig. 5.101) for a historical maximum squall line. For example, FUJITA et al. (1956) gave a value for the pressure gradient of 9 mb in 50 mi (80 km)

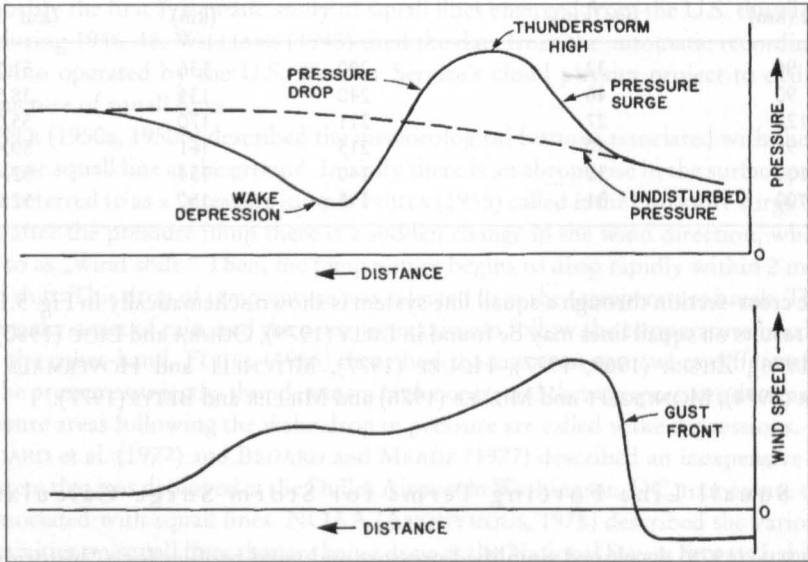


Fig. 5.100: Idealized pressure (top) and wind speed (bottom) field profiles for a squall line system. Negative wind speed denotes inflow into storm system (WILSON, 1978)

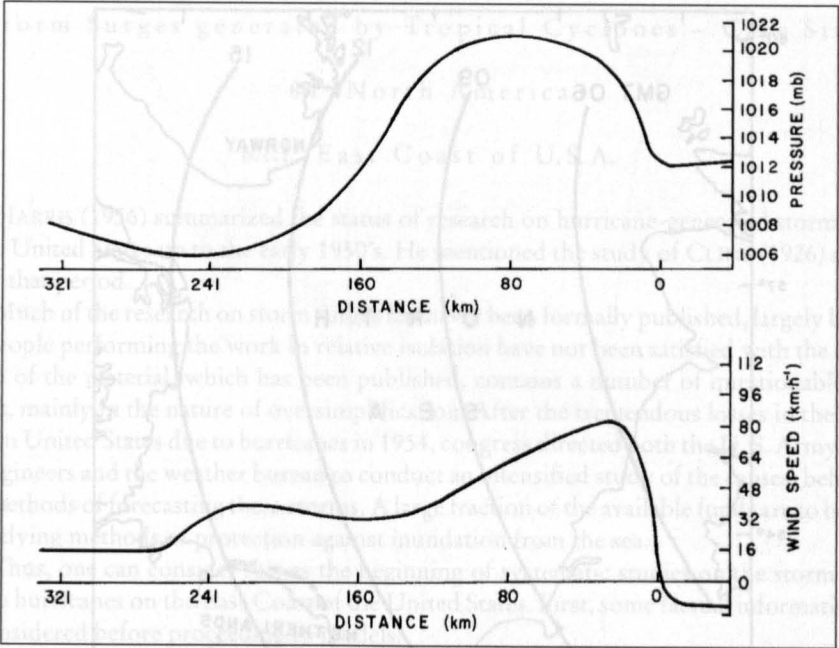


Fig. 5.101: Simplified pressure (top) and wind speed (bottom) profiles for historical maximum squall line system (WILSON, 1978)

for a squall line over Nebraska on June 25, 1953, with a sustained post-gust front wind speed of $45 \text{ mi} \cdot \text{h}^{-1}$ ($73 \text{ km} \cdot \text{h}^{-1}$). In this model Wilson used a value of $50 \text{ mi} \cdot \text{h}^{-1}$.

It was mentioned that for squall lines the pressure gradient terms are comparable in magnitude with wind stress terms. This is also borne out by the studies of FREEMAN and MURTY (1972) and MURTY and FREEMAN (1973) for the squall line of August 22, 1971, over Lake Huron. For the squall line, a sharp rise of pressure (δp_a) of 4.5 mb and wind (W) of $112.6 \text{ km} \cdot \text{h}^{-1}$ were deduced from the observations. Taking the average depth (D) of the southern part of Lake Huron as 54.7 m, a horizontal scale (δx) of 8 km, a time interval during which the pressure increased as 5 min, and the speed of travel of the squall line as $96.5 \text{ km} \cdot \text{h}^{-1}$, the pressure gradient term becomes

$$\frac{1}{\rho} D \frac{\delta p_a}{\delta x} = 34 \text{ cm}^2 \cdot \text{s}^{-2}$$

The wind stress term gives

$$\tau_s = 3 \times 10^{-6} W^2 = 30 \text{ cm}^2 \cdot \text{s}^{-2}$$

For the synoptic scale, the atmospheric pressure gradient as taken from the isobaric plot is a 4-mb change (δp_a) in a 161-km distance (δx). A wind speed (W) of $32 \text{ km} \cdot \text{h}^{-1}$ is used as a typical value. The pressure gradient term and the wind stress term become 1.5 and $2.4 \text{ cm} \cdot \text{s}^{-2}$, respectively.

Earlier, the storm surge calculations in idealized situations using the method of characteristics (e.g. RAO, 1967, 1969; MURTY, 1971) were discussed. The calculations of the storm

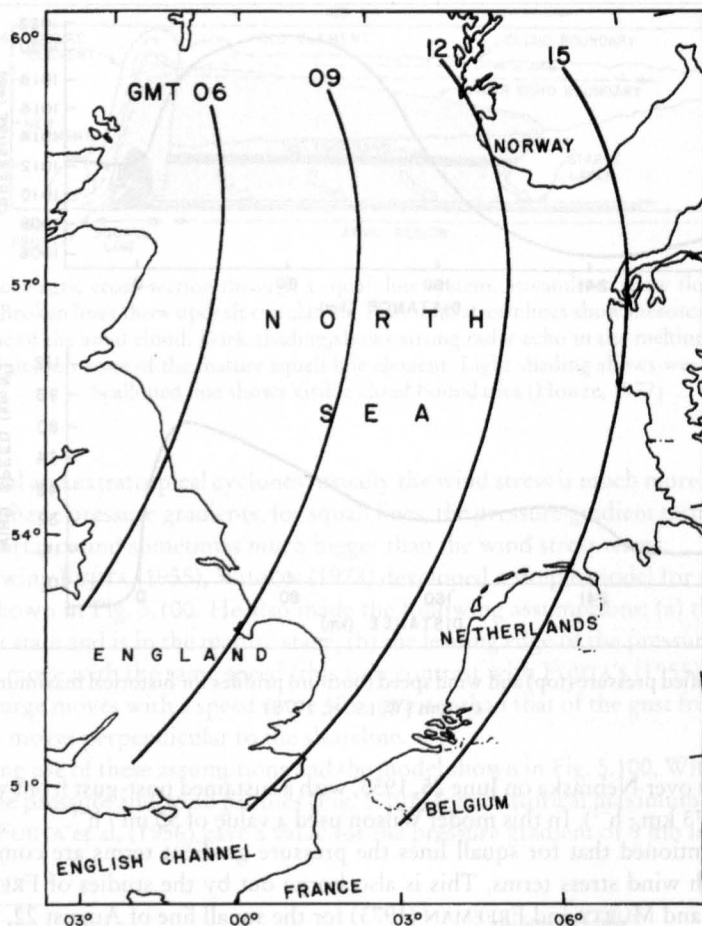


Fig. 5.102: Position of the leading edge of the squall line at four different times (GMT) on December 13, 1956 (TIMMERMANN, 1971)

surge in Lake Michigan due to a squall line on June 26, 1954 (PLATZMAN, 1958a, 1965; IRISH, 1965; HUGHES, 1965) are included elsewhere in the book. DONN and BALACHANDRIAN (1969) discussed the water level oscillations in Long Island Sound (east of New York City) due to a squall line on November 23, 1953. DONN (1959) studied the storm surges in Lake Huron and Erie due to a squall line on May 5, 1952. KRAUSS (1978) studied the response of a stratified sea to a moving squall line.

DOUGLAS (1929) made a simple calculation of the water level oscillations in the English Channel due to a squall line on July 20, 1929. TIMMERMANN (1971) studied the water level oscillations (he referred to them as "cold fronts") on the Dutch coast of the North Sea. When the speed of the squall line is between 29 and 36 knots, resonance occurs between the squall line and the long gravity waves in the North Sea, and this leads to water level oscillations. During the period December 13, 1956, to January 4, 1968, 20 squall lines with speeds ranging from 25 to 36 knots travelled over the southern part of the North Sea. The positions of the leading edge of the squall line at four different times on December 13, 1956, are shown in Fig. 5.102.

6. Storm Surges generated by Tropical Cyclones – Case Studies

6.1 North America

6.1.1 East Coast of U.S.A.

HARRIS (1956) summarized the status of research on hurricane-generated storm surges in the United States up to the early 1950's. He mentioned the study of CLINE (1926) as typical of that period.

Much of the research on storm surges has never been formally published, largely because the people performing the work in relative isolation have not been satisfied with the results. Much of the material, which has been published, contains a number of questionable statements, mainly in the nature of oversimplification. After the tremendous losses in the north-eastern United States due to hurricanes in 1954, congress directed both the U. S. Army Corps of Engineers and the weather bureau to conduct an intensified study of the causes, behaviour and methods of forecasting these storms. A large fraction of the available funds are to be spent in studying methods of protection against inundation from the sea.

Thus, one can consider this as the beginning of systematic studies on the storm surges due to hurricanes on the East Coast of the United States. First, some factual information will be considered before proceeding to models.

WIEGEL (1964) stated that during the period 1900–55 there was more than 11, 750 deaths caused by hurricanes in the United States. The worst storm surge (from the point of view of loss of life) in United States history occurred in September 1900 when more than 6000 people drowned, most of them at Galveston, Texas (Price 1956). During the 14-year period 1940–53, the loss of life due to hurricane-generated surges over the globe was 3744; 590 of those deaths occurred in the United States (WIEGEL, 1964).

DUNN (1958) mentioned the years and the locations of some of the greatest storm surges on the east coast of United States: Galveston (1900 and 1915), Tampa Bay (1921), Miami (1926), Palm Beach and Lake Okeechobee (1928 and 1949), Florida Keys (1953), and New England, particularly Narragansett Bay (1938 and 1954). The maximum storm surge from these was about 12.5 ft (3.8 m) above mean low water.

HARRIS (1956) and DUNN (1958) mentioned forerunners to storm surges and also resurgence. REDFIELD and MILLER (1957) studied these phenomena in detail and these will be considered now. Also, these authors provided a review of the literature up to 1957; some pertinent information will be extracted.

Between 1635 and 1938 there were at least six major hurricanes on the coast of New England (TANNEHILL, 1950) and between 1938 and 1957 there were at least another six. Since 1874 at least 40 hurricanes passed within 200 nautical miles (370 km) of Rhode Island. NAMIAS (1955) analyzed the tracks of hurricanes and showed that the region most frequently traversed during 1935–55 near the Gulf of Maine was at 40° N, 65° W. One important point made by REDFIELD and MILLER (1957) is that although more than three quarters of the deaths due to hurricanes are caused by the storm surge, until the mid-1950's little attention was paid to the water level problem and all the consideration was given to meteorological problem.

The database for the study by REDFIELD and MILLER (1957) is the following: (1) September 21, 1938, (2) September 14–15, 1944, (3) August 31, 1954 (Carol), (4) September 11, 1954 (Edna), (5) October 15–16, 1954 (Hazel). The tracks of these hurricanes are shown in Fig. 6.1. The three phenomena studied were forerunners, hurricane surge, and resurgence.

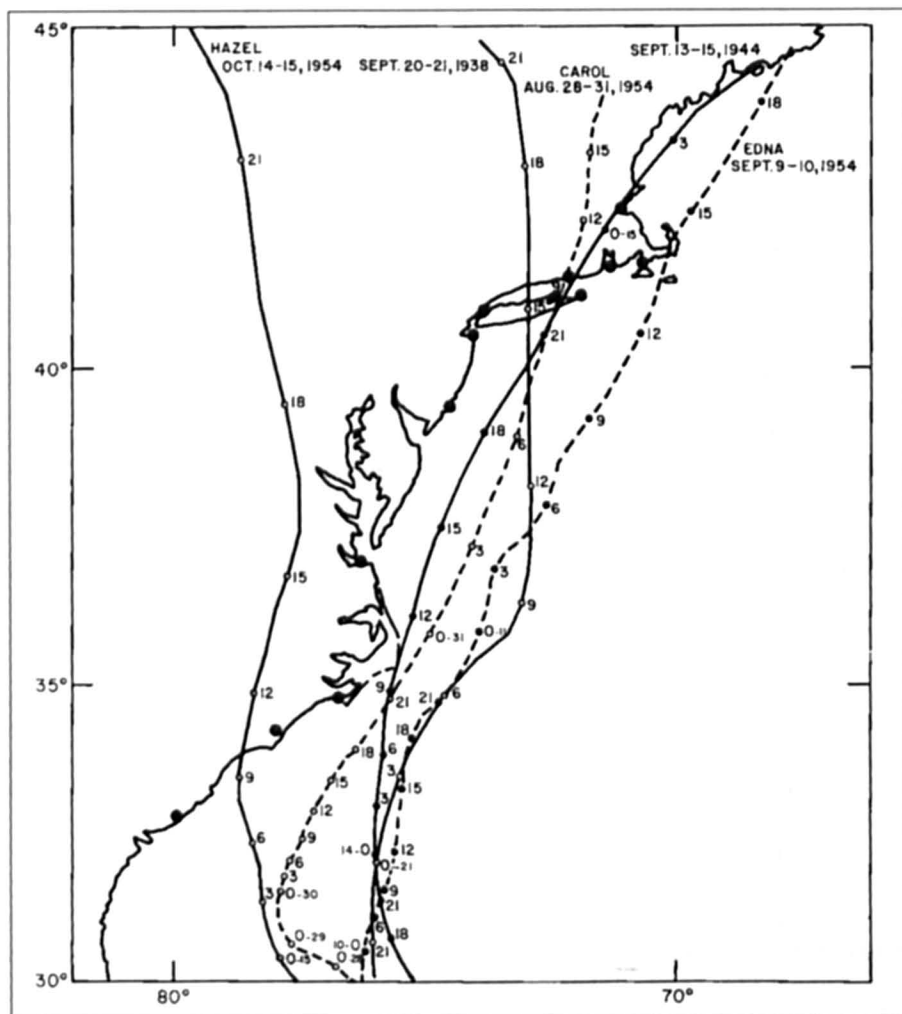


Fig. 6.1: Tracks of some of the hurricanes that affected the New England States. Solid circles show the locations of the tide gauges. Circles on the tracks represent the hours (GMT) and the small numbers denote the dates (REDFIELD and MILLER, 1957)

A forerunner is the gradual rise in sea level along the coast that precedes the arrival of the hurricane, and which may occur while the storm center is at a great distance from the coast regardless of whether or not it reaches the point of observation. The hurricane surge is the sudden and substantial rise in water level that accompanies the violent winds of the storm. Resurgences include a number of phenomena that occur after the passage of a storm center. They may be attributed in general to the free motion of water in returning to the normal level but are augmented in some cases by wind blowing in a changing direction.

CLINE (1920, 1926 and 1933) noticed forerunners in the Gulf of Mexico and called attention to their importance in the prediction of the storm arrival. The sea level began to rise (above the predicted tide) 1 or 2 d before the arrival of the storm. Elevations of several feet were noticed before the rapid rise due to the storm surge itself. Cline explained the forerunners as being due to transport of water by the swell that arrives in advance of the hurricanes.

Table 6.1: Relation of duration of surge to size and speed of storm (REDFIELD and MILLER, 1957)

Storm	Time (h) half level Preceded maximum Level	Speed at Coast (km·h ⁻¹)	Diameter of 980-mb Isobar (km)	Time (h) Pressure < 980 mb
1938	1.0–1.5	96	270	3.2
1944	2.1–2.2	67	241	4.2
1954 (Carol)	1.1–1.3	74	183	2.9
1954 (Edna)	2.0–2.3	63	261	4.8
1954 (Hazel)	3.0–5.0	46	261	6.5

Observations showed that if the tide gauge was within 50 nautical miles (93 km) to the left (in the Northern Hemisphere) of the storm track, or 100 nautical miles (185 km) to its right, the rate of rise of water level increased to more than 1 ft h⁻¹ beginning 3 or 4 h before the passage of the center. (This rapid rise is the surge whereas the slow gradual rise before this is the forerunner).

Examples of the forerunners can be found in the storm surge records at Atlantic City and Sandy Hook. At Atlantic City during Hurricane Carol of September 1954, the water level began to increase even before the storm passed Cape Hatteras (260 nautical miles or 481 km to the south). This rise continued for 8–12 h at which time the storm center passed over Atlantic City and the wind shifted. Then the water level dropped abruptly and this was followed by resurgences. The hurricane of September 14–15, 1944, traveled close to the coast and the forerunner was not significant. REDFIELD and MILLER (1957) discounted the fall in barometric pressure as the cause of the forerunners. They cited wind as the main agent responsible. The fact that the water levels decreased abruptly when the wind shifted is another piece of evidence, according to them.

After the storm surge itself, on the outer coast, surges up to 8–9 ft (2.4–2.7 m) occurred. At Long Island, and along the coasts of Rhode Island and Massachusetts, water level deviation up to 18-ft (5.5 m) occurred (but part of this were wind-generated waves). However in Buzzards Bay, Narragansett Bay, Long Island Sound, etc., surges up to 15-ft (4.6 m) have occurred many times. These authors introduced the term „half-level time“ to define the time required to develop from one half the maximum to the maximum water level achieved. For hurricanes crossing the coast of New England this time varied from 1.25 to more than 2 h (Table 6.1.). This half-level time that defines the sharpness of the surge varies in proportion with the storm speed at the time the storm crosses the coast, as can be seen from Table 6.1. This Table also lists the size of the storm as typified by the diameter of the 980-mb isobar and the time during which the pressure was less than 980 mb. This time is roughly twice the half-level time.

The storm surge amplitude (meters) along the ordinate versus distance (nautical miles) from the storm center along the abscissa is given in Fig. 6.2. It can be seen that maximum water levels occurred some 50–70 nautical miles (93–130 km) to the right of the storm center. However, REDFIELD and MILLER (1957) pointed out that the highest water levels following Hurricane Hazel of 1954 occurred close to the storm center, and 40 nautical miles (74 km) to

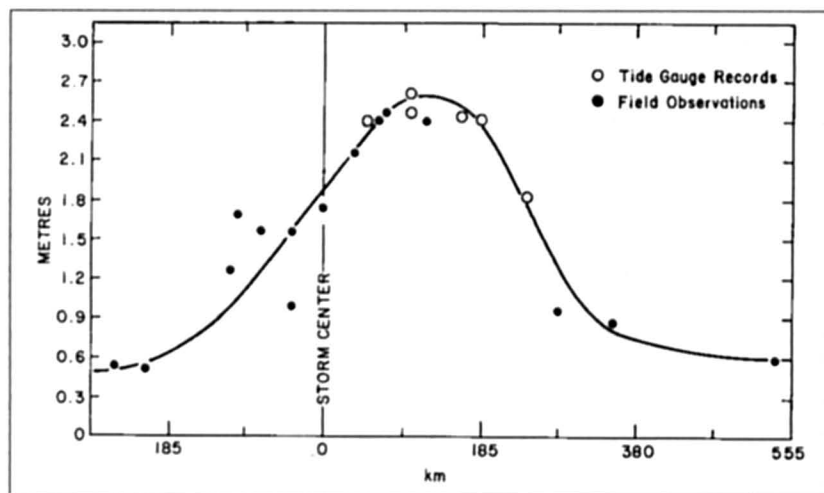


Fig. 6.2: Storm surge amplitude (ordinate) versus distance from storm center (abscissa) (REDFIELD and MILLER, 1957)

the right they were small. HUBERT and CLARK (1955) mentioned that for the coast of the Gulf of Mexico the maximum water levels occurred close to the storm center slightly to its right.

The time of occurrence of the maximum surges with reference to the passage of the storm center differed from one storm to another and from one location to another. If the storm center passed close to a tide gauge, usually, maximum surges occurred within 1 h before or after the storm passage. The differences in the time of occurrence of the maximum surges can be explained by differences in the exposure of the gauges and also by the fact that the wind and pressure centers of a hurricane need not coincide (MYERS, 1954).

The maximum surges on the southern New England Coast and their times of occurrence following the hurricane of September 21, 1938, are shown in Fig. 6.3 and 6.4 respectively. Similar information for Hurricane Carol of August 31, 1954, is given in Fig. 6.5 and 6.6. Large surges on the coast of southern New England might to some extent be accounted for by the presence of a wide and shallow shelf. This topographic effect is most noticeable between Montauk Point (at the eastern tip of Long Island) and Martha's Vineyard. However, greatest surges and most property damage occurred on the Narragansett Bay coast. Extreme surges

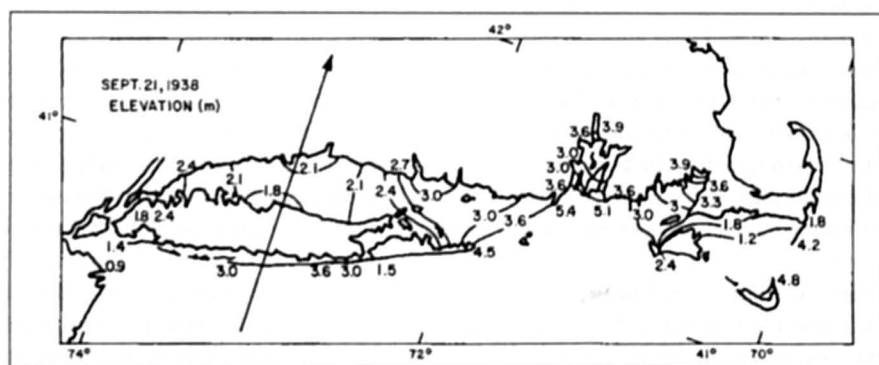


Fig. 6.3: Storm surge heights (meters) on the coast of the southern New England States. The arrow shows the track of the storm of September 21, 1938, that caused this surge (REDFIELD and MILLER, 1957)

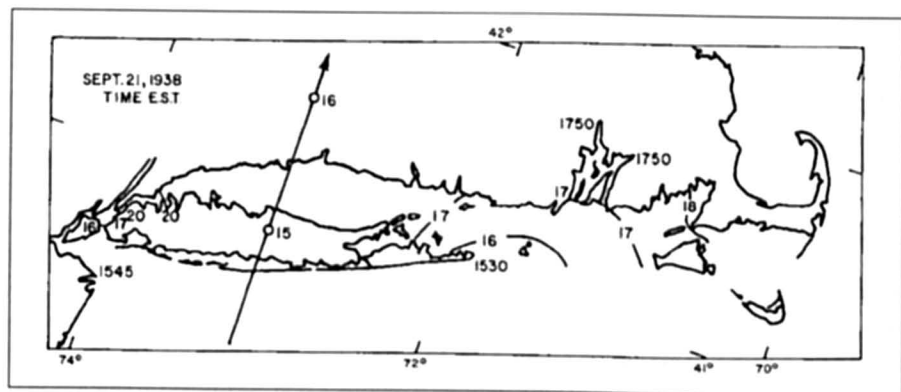


Fig. 6.4: Times of occurrence of maximum surge along the coast of the southern New England States on September 21, 1938 (REDFIELD and MILLER, 1957)

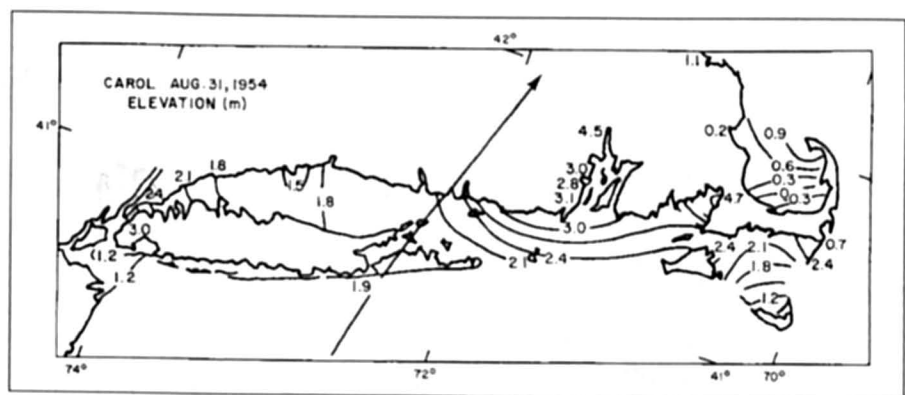


Fig. 6.5: Storm surge heights (meters) along the coast of the southern New England States following Hurricane Carol of August 31, 1954 (REDFIELD and MILLER, 1957)

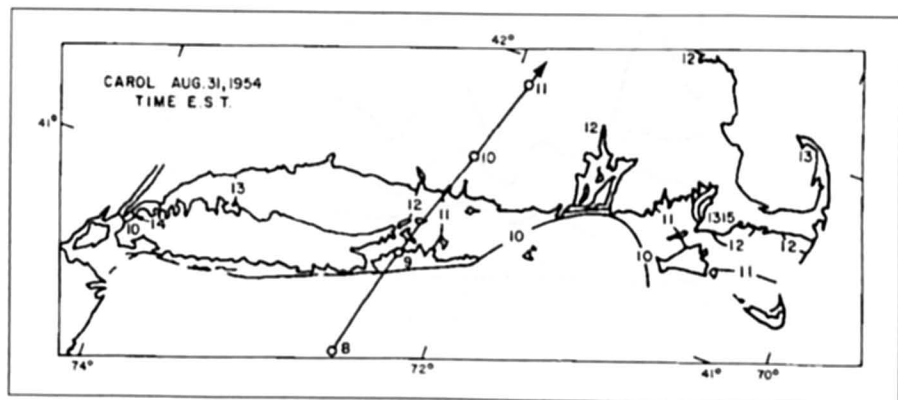


Fig. 6.6: Times of occurrence of maximum surge along the coast of the southern New England States following Hurricane Carol of August 31, 1954. The arrow shows the hurricane track (REDFIELD and MILLER, 1957)

up to 13 ft (4 m) were noted at Providence, Rhode Island, in water of depth less than 20 ft (6.1 m).

According to REDFIELD and MILLER (1957), Providence is among the most frequently flooded (due to surges) in the United States. Surges up to 11 ft (3.4 m) were observed in 1944 (but little damage occurred because the maximum surge coincided with low tide); 15 ft (4.6 m) surges were recorded on August 31, 1954, and there was evidence of 12 to 14 ft (3.7–4.3 m) surges in 1815. In Buzzards Bay, surges of 13 ft (4m) occurred in 1938 and 15 ft (4.6 m) surges were recorded following Hurricane Carol in 1954. A diary entry by Governor Bradford in 1635 (MORRISON, 1952) describes a 20 ft (6.1 m) surge on August 14–15 of that year. There is evidence of negative surges of 1–3 ft (0.3–0.9 m) in Cape Cod Bay and Nantucket Sound. Surges up to 4 ft (1.2 m) were noted at Boston and Portland. North of Cape Cod the amplitudes of surges become small and amount to about 1 ft at Eastport (Maine).

REDFIELD and MILLER (1957) paid particular attention to the resurgences, which are basically free oscillations of the water in trying to return to its normal level. Following Hurricane Carol of August 31, 1954, the damage at the Cape Cod area was a result of the resurgence. In Buzzards Bay, although the main surge had amplitudes of about 12 ft (3.7 m) along the western shore, resurgences with amplitudes up to 15 ft (4.6 m) occurred on the eastern shore. The resurgence following a 1938 hurricane in Buzzards Bay caused great damage and loss of life at Woodshole. In Long Island Sound, resurgences occurred following the hurri-

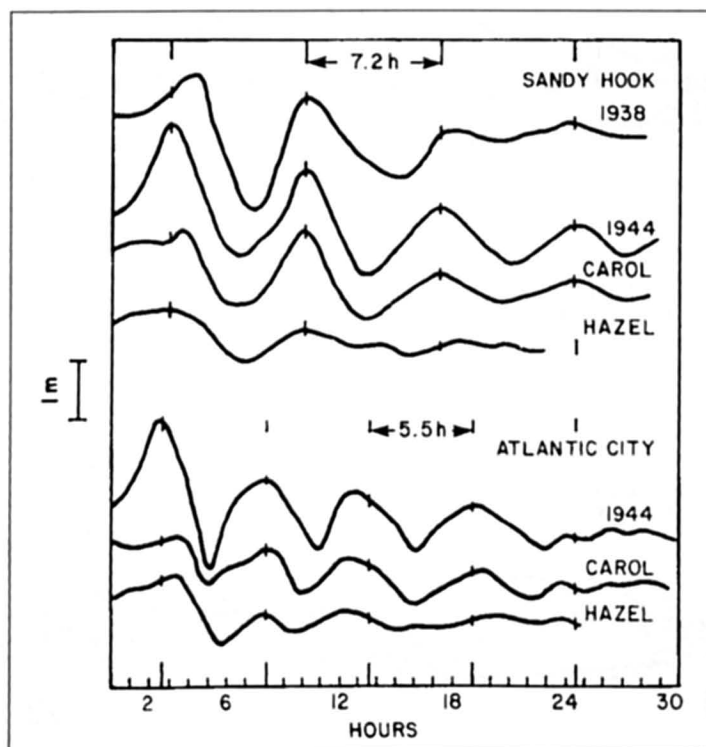


Fig. 6.7: Comparison of resurgences following the passage of several storms at Sandy Hook and Atlantic City. The times were adjusted (for each station) so that the time of occurrence of the first resurgence for the different storms coincide. Vertical ticks denote time separation of 7.2 h for Sandy Hook and 5.5 h for Atlantic City. Ordinate: water level (meters); abscissa: duration of surge (hours) (REDFIELD and MILLER, 1957)

canes of September 21, 1938, and August 31, 1954. Tide gauges at Atlantic City and Sandy Hook showed prominent resurgences (Fig. 6.7.). After the original surge reaches a maximum, the water level drops abruptly to low values and then increases again in a series of undulations with periods of several hours. These resurgences periods are about 5.5 h at Atlantic City and 7.2 h at Sandy Hook. The attenuation rate of the resurgences at Sandy Hook is about 0.07 h^{-1} . MUNK et al. (1956) explained these resurgences as due to edge waves.

Storm surges on the east Coast of the United States also occur as a result of extra-tropical cyclones. Some differences between storm surges due to tropical and extra-tropical storms on the east Coast of the United States are listed in Table 6.2.

Some models that were developed with the aim of hindcasting and eventually predicting storm surges will now be considered. The so-called bathystrophic storm surge (FREEMAN et al., 1957) was discussed earlier. PARARAS-CARAYANNIS (1975) used this approach to hind-

Table 6.2: Differences between hurricane-generated and extratropical storm generated surges

Parameter	Tropical system	Extratropical system
Size of storm	Small	Large
Representation on weather charts	Some times difficult to position on weather charts using ordinary weather reports. The vigorous portion of the storm may lie between two observing stations	Easier
Requirement of specialized observations such as satellite, weather, reconnaissance, radar, aircraft	Needed	Usually not required. Standard weather reports usually adequate unless mesoscale systems are embedded
Amplitude of surges	Greater The Maximum surge generated in the United States was at Gulfport, MS, following Hurricane Camille in August 1969: 7.5 m	Smaller surges of amplitudes up to 5 m can occur infrequently
Duration of surge	Short (Several hours to 1/2 d)	Long (usually 2-5 d). Severe erosion of coastline can occur
Inland inundation	Large	Little
Length of coastline affected by the surge	Less (usually < 160 km)	Several hundred kilometers
Geometry of the storm	Compact and nearly symmetrical	Ill-defined and sprawling geometry
Speed of movement of the storm	Variable	Slow motion generally along a regular track
Pressure gradients and wind stress associated with the storm	Easy to model the driving forces could be represented analytically	Difficult to model the driving fields

cast surges on the East Coast and Gulf of Mexico coast of the United States. The observed and computed surges at three locations are compared in Fig. 6.8. PARARAS-CARAYANNIS (1975) simulated surges due to the hurricanes listed in Table 6.3. Pertinent meteorological information is also listed in this table, which is used in the above calculations.

KAJIURA (1959) examined analytically, as well as empirically, hurricane-generated surges on continental shelves. Using dimensional analysis he showed that the surge is determined by the following two dimensionless ratios: V/c and L_2/L_1 where V is the speed of movement of the storm, c is the speed of long gravity waves on the shelf, L_2 is the scale of the storm and L_1 is the width of the shelf, the dynamic response of the water level is significantly influenced by the natural modes of oscillation on the shelf (the dynamic amplification for a one-dimensional case is between 1 and 2). The free oscillations again become important when one considers the transient aspects. Coriolis force becomes relevant if the scale of the disturbance is significant relative to c/f , where f is the Coriolis parameter. When the scale of the shelf is comparable with the scale of storm, the two-dimensional aspects of hurricanes must be considered.

Other important results from KUJIURA'S (1959) study are the following. If the storm moves perpendicular to the coastline from the sea, then the maximum surge always occurs a little later than the time of the nearest approach of the storm center to the water level station. For any other type of track, the maximum surge can occur either before or after the storm center approaches nearest to the observing station. When the storm moves inland from the sea, the maximum surge is found to the right of the track. The dynamic amplification of the surge is maximum when the track is parallel to the coast and the amplification depends on the duration of the storm as well as V/c .

Actual data of hurricane-generated surges along the Atlantic coast showed that significant surges (up to one third of the maximum surge) occur within 70 nautical miles (130 km) to the left and 110 nautical miles (204 km) to the right of storm track. The maximum surge usually occurs about 25 nautical miles (46 km) to the right of the track. Unless the storm center is very close to the station, usually the water levels are greater south of Sandy Hook than on the New England coast.

Table 6.3: Hurricane parameters in the bathystrophic storm surge study (PARARAS-CARAYANNIS, 1975)

Hurricane	Central pressure (mb)	Peripheral pressure (mb)	Radius of maximum winds (km)	Speed of movement (km · h ⁻¹)	Maximum gradient wind speed (km · h ⁻¹)
Hurricane of Oct. 3-4, 1949	963.4	1014.2	27.8	20.4	141.6
Carol of Aug. 30-31, 1954	971.6	1013.2	46.3	61.7	152.9
Audrey of June 26-27, 1957	946.5	1005.8	35.2	24.1	152.9
Carla of Sept. 7-12, 1961	936.0	1013.2	85.2	5.6	160.9
Camille of Aug. 15-16, 1969	905.2	1013.2	25.9	24.1	201.2

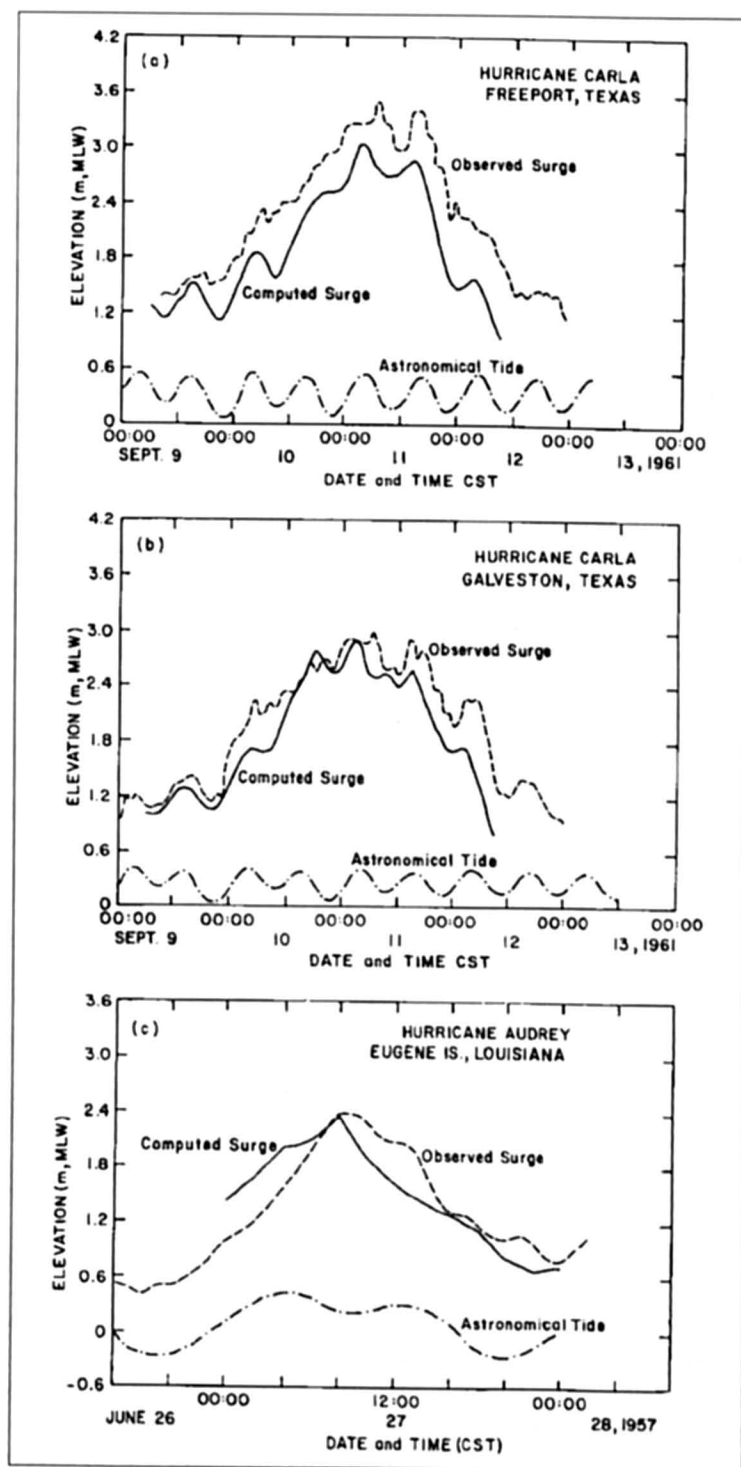


Fig. 6.8: Computed surge (using bathystrophic approach), observed surge, and tide due to (a) Hurricane Carla at Freeport, Texas, (b) Hurricane Carla at Galveston, Texas, and (c) Hurricane Audrey at Eugene Island, Louisiana (PARARAS-CARAYANNIS, 1975)

SPLASH Models

SPLASH is an acronym for "special program to list amplitudes of surges from hurricanes." SPLASH I deals with landfalling hurricanes and SPLASH II takes care of situations in which the hurricanes need not go over land. These models were developed at the Techniques Development Laboratory of the U.S. National Weather Service (JELESNIANSKI 1972, 1974, 1976; JELESNIANSKI and BARRIENTOS 1975; BARRIENTOS and JELESNIANSKI 1976, 1978). This computer program is operationally used at the National Hurricane Center in Miami and is applied to the Atlantic coast and the Gulf of Mexico coast of the United States. The stretch of coast for which these models are used extends about 3000 mi (4827 km) from Brownsville, Texas, to Long Island, New York. Along this coastal stretch, reference stations (for use in hurricane landfall determination) are established with an approximate spacing of 100 mi (161 km).

SPLASH is a numerical storm surge model that involves a linearized version of the transport equations. The geometry of the model is idealized into a rectangle with variable depth. One side of the rectangle is the coast and the other three sides are open boundaries. At the coast the normal transport is zero and at the deepwater open boundary static height is prescribed (this height is zero in the absence of an atmospheric pressure gradient). On the two lateral open boundaries the normal derivative of transport is prescribed to be zero. Depth contours are analysed on overlapping 600 mi \times 72 mi (965 km \times 116 km) basins. The basins are centered 50 mi apart.

In SPLASH I, which applies to landfalling hurricanes only, the following meteorological input is required: (1) pressure drop $\Delta p = p_{\infty} - p_0$ where p_{∞} is the ambient pressure outside the storm and p_0 is the central pressure of the hurricane, (2) the radius R of maximum winds, (3) the vector storm motion U_s/θ where U_s is the storm speed and θ is the storm direction of motion, and (4) point of landfall. This program assumes that the conditions are steady state, i. e., the size, intensity, and speed of movement are constants.

SPLASH II deals with an unsteady storm. The storm track could have any orientation and the storms need no landfall. The input data consist of (among other things) a 24-h track segment, which is defined by latitude and longitude for five points on the track staggered 6 h apart for a 24-h period. These latitude and longitude data not only define the track but also the speed of movement of the storm. Other input data are the radius of maximum winds and pressure drop, which can vary with time.

One very important component in SPLASH is a normalized shoaling correction, which is used to correct the computed surge along the coast if the landfall point is shifted. Shoaling corrections were prepared for the Atlantic and the Gulf coasts by using landfall storms normal to the coast at 16-mi (25.8 km) intervals using a storm speed of 15 mi \cdot h⁻¹ (24 km \cdot h⁻¹).

The SPLASH models were verified generally against data from 43 hurricanes during five hurricane seasons. These cases, the dates of occurrence, location of the peak surge, and computed and observed peak surges are listed in Table 6.4. The varying location of the peak surge, depending on the nature of the bathymetry, is shown quantitatively in Fig. 6.9.

Whereas SPLASH I can deal with landfalling hurricanes only, SPLASH II can be applied to a general storm track. Especially the following three types of tracks are considered: (1) landfall storm with its track perpendicular to a straight-line coast, (2) an alongshore moving storm (i.e. constant abeam distance of the track from the coast), and (3) a recurving storm (non-landfall). Slow-moving storms are treated as a special case and a hypothetical storm with the following properties is used: (1) the storm traverses the continental shelf with the speed of less than 8 mi \cdot h⁻¹ (12.9 km \cdot h⁻¹), (2) the storm's closest approach to the coast occurs

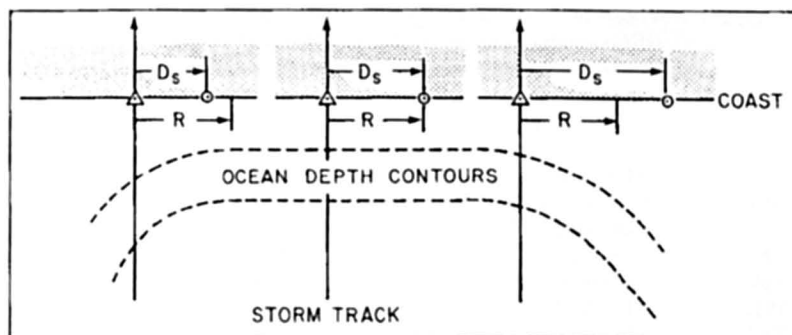


Fig. 6.9: Qualitative illustration showing the varying positions of peak surge on the coast as compared with two-dimensional bathymetry. \odot , location of peak surge; \triangle , landfall point; R, radius of maximum winds; D_s , distance to peak surge. (JELESNIANSKI, 1972)

near Miami where there is hardly any continental shelf, and (3) the storm's strength and size ($\Delta p = 100$ mb, $R = 15$ mi \cdot h $^{-1}$ [24 km \cdot h $^{-1}$]) do not change along the track.

Calculations using SPLASH II gave the following results. The maximum surge is not highly sensitive to storm size for landfall storms. However, for non-landfall storms, the storm size is important because the surge is a function of distance from the coast relative to storm size. When the storm is on the shelf, if the component of the track on the coast is large, the length of the coastline affected by the surge could be very long. For a storm travelling perpendicular to the coast, the component of the track on the coast degenerates to a point, and surges occur only along a small length of the coastline.

One of the main drawbacks of SPLASH II (although it is an improvement over SPLASH I) is that it treats the coast as a straight line and cannot include the curvature of the coastline. To remove this restriction, JELESNIANSKI (1976) developed a sheared coordinate system. In this model, a mildly curving coastline (which does not include bays, estuaries, sounds, deltas, capes, spits, etc.) is sheared into a straight-line. A surface plane, beginning at the ocean shelf and containing the curved coast as one of the boundaries, is fitted with a curve, nonorthogonal grid. The plane with curved boundaries is then transformed via a sheared coordinate system onto an image rectangle. In this transformed system, one deals with a Cartesian, orthogonal, equally spaced grid in which the coast coincides with grid lines. JELESNIANSKI (1976) used such a model incorporating the linearized storm surge equations for a 3000 mi (4827 km) coastline beginning at the United States-Mexico border in the Gulf of Mexico to the eastern tip of Long Island in New York. The storm tracks could be curved and the intensity, the size of the storms, and its speed of movement could be variable.

The somewhat idealized SPLASH models are being replaced with a new generation of models referred to as SLOSH (sea, lake and overland surges from hurricanes). These models are being developed for the east and gulf coasts of the United States. Specifically, the following coastal stretches are being modelled: New Orleans Area, Lake Okeechobee, Tampa Bay, Mobile Bay, Galveston area, Charlotte Harbour (Florida), Florida Bay, Biscayne Bay, Florida Keys, Long Island Sound, Chesapeake Bay, Charleston Harbour (South Carolina), Narragansett Bay, Buzzards Bay, Delaware Bay, Palmico Sound, Massachusetts Bay, Corpus Christi (Texas), Lower Laguna Madre (Texas), Matagorda Bay (Texas), Lake Sabine (Texas), and Pensacola (Florida). Some testing of the SLOSH model during Hurricane Bob in July 1979 showed that the results are quite satisfactory.

Table 6.4: Comparison of observed maximum surges (m) in the United States with those computed from the nomograms using SPLASH (JELESNIANSKI, 1972)

Date	Location of peak surge	Computed peak surge	Observed peak surge
Oct. 2, 1893	Mobile, AL	3.32	2.83
Sept. 27, 1894	Charleston, NC	1.59	1.62
Sept. 8, 1900	Galveston, TX	4.60	4.45
Aug. 14, 1901	Mobile, AL	2.07	2.26
July 21, 1909	Galveston, TX	3.54	3.05
Sept. 13, 1912	Mobile, AL	0.91	1.34
Aug. 16, 1915	High Island, TX	3.60	4.24
Sept. 29, 1915	Grand Isle, LA	3.41	2.74
Oct. 18, 1916	Pensacola, FL	1.59	0.91
Sept. 28, 1917	Fort Barrancas, FL	1.77	2.16
Sept. 9, 1919	Key West, FL	2.23	1.98
Oct. 25, 1921	Punta Rassa, FL	3.29	3.32
Aug. 26, 1926	Timbalier Island, LA	3.02	2.99
Sept. 18, 1926	Miami Beach, FL	3.57	3.17
Sept. 20, 1926	Pensacola, FL	2.19	2.74
Sept. 16, 1928	West Palm Beach, FL	2.74	2.96
Sept. 28, 1929	Key Largo, FL	2.23	2.68
Sept. 7, 1933	Brownsville, TX	3.02	3.96
July 25, 1934	Galveston, TX	2.07	1.80
Nov. 4, 1935	Miami Beach, FL	2.01	2.74
July 31, 1936	Panama City, FL	1.71	1.83
Aug. 7, 1940	Calcasieu Pass, LA	1.62	1.62
Aug. 11, 1940	Beaufort, SC	2.44	2.44
Sept. 23, 1941	Sargent, TX	2.35	2.59
Oct. 7, 1941	St. Marks, FL	3.08	1.86
Aug. 30, 1942	Matagorda, TX	2.90	4.27
July 27, 1943	Galveston, TX	1.77	1.10
Oct. 19, 1944	Naples, FL	3.26	3.23
Oct. 20, 1944	Charleston, FL	1.22	1.22
Aug. 27, 1945	Matagorda, TX	1.89	1.95
Aug. 24, 1947	Safine Pass, LA	0.87	0.76
Aug. 17, 1947	Hillsboro Beach, FL	1.95	2.90
Sept. 19, 1947	Biloxi, MS	3.41	3.32
Oct. 15, 1947	Quarantine Station, GA	2.13	1.77
Sept. 4, 1948	Biloxi, MS	1.59	1.55
Aug. 26, 1949	New Jupiter In., FL	1.65	1.25
Oct. 4, 1949	Freeport, TX	3.17	2.74
Aug. 30, 1950	Pensacola, FL	1.16	1.55
Sept. 5, 1950	St. Petersburg, FL	2.10	1.92
Oct. 15, 1954	Southport, NC	3.81	3.90
Aug. 17, 1955	Holden Beach, NC	1.62	1.65
Sept. 24, 1956	Laguna Beach, FL	1.43	2.16
June 27, 1957	Calcasieu Pass, LA	4.82	3.81

Earlier we referred to the SLOSH models of N.O.A.A., U.S.A. More recent information on these can be found in JELESNIANSKI et al., (1992). One of the strongest Hurricanes to make a landfall on the East Coast of U.S.A. was Hurricane Hugo of September 11–25, 1989 causing a total damage in excess of 7 billion US dollars. The track is shown in Fig. 6.10.

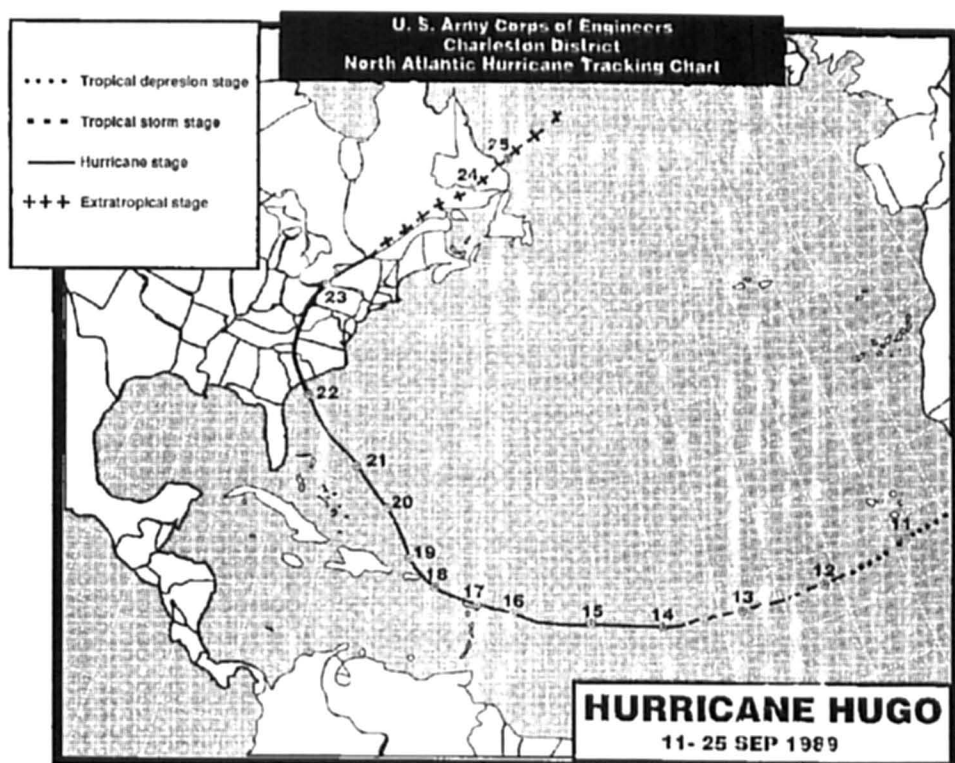


Fig. 6.10

6.1.2 Gulf of Mexico Coast (Excluding Florida Coast)

Up to this point, storm surges along the Atlantic Coast and the Gulf of Mexico have been studied. The gulf coast will now be considered in some detail. CLINE (1920) discussed the storm surges in the Gulf of Mexico due to hurricanes during the 20-yr period 1900–19. The pertinent information for these hurricanes and the storm surges generated are given in Table 6.5.

Following are some results of the study by CLINE (1920). During 1900–19, about 7225 people were killed and about \$ 106 million in property damage occurred as a result of hurricanes in the Gulf of Mexico. The storm surges need not be symmetric about the hurricane track because the wind velocities to the left side of the track are much smaller (and less persistent) than on the right side. Peak surges occur a few kilometers to the right and at about the time of the passage of the center of the hurricane. The high water extends for only a short distance to the left of the point where the center of the storm moves inland. High water, however, occurs to the right of the center for a distance of 100–200 mi (161–322 km).

CONNER et al. (1957) gave a table of hurricanes and associated surges during the period 1893–1950. This table is reproduced here as Table 6.6. Although this table bears some resemblance to an earlier table (Table 6.4), certain entries are different. Also, in Table 6.8 only the observed surge is included (there is no calculated surge). In addition, the lowest pressure in the hurricane is also listed. Two empirical relations best fit these data. One is

$$h_{\max} = 0.867(1005 - p_0)^{0.618} \quad (6.1)$$

where, h_{\max} is the surge height (feet) and p_0 is the lowest central pressure (millibars). The correlation coefficient between h_{\max} calculated and p_0 is 0.66. Another is

$$h_{\max} = 0.154(1019 - p_0) \quad (6.2)$$

In this case the correlation coefficient is 0.68. The difference in the values for the observed surges for the same storms listed in Tables 6.4 and 6.6 are mainly due to different sources.

Hurricane Audrey of 1957 was the first hurricane that caused major storm surges since the organization of the National Hurricane Research Project by the U.S. Weather Bureau. This hurricane crossed the shore near the Texas–Louisiana border on the morning of June 27, 1957. HARRIS (1958a, 1958b) studied the storm surges associated with this hurricane and gave detailed diagrams of the surge height distribution along the coast.

MARINOS and WOODWARD (1968) used the bathystrophic theory to compute storm surges on the Texas–Louisiana coast. They made use of three storms to calibrate their model and checked it against several other storms. Using several synthetic hurricanes, 100-yr surge hydrographs were also constructed.

MIYAZAKI (1965) computed the storm surge in Gulf of Mexico due to Hurricane Carla of September 7–11, 1961, using a time-dependent linearized two-dimensional model. He first used a coarse grid of 48 nautical miles (89 km) for the entire Gulf and then developed a fine-grid model (grid spacing of 9.6 nautical miles or 17.8 km) for the northwestern part where the storm surge was the most significant. In the coarse-mesh model, bottom friction was ignored whereas quadratic bottom friction was used in the fine-mesh model.

Hurricane Carla is an exceptional hurricane in the sense that it moved very slowly (about 7 knots or $13 \text{ km} \cdot \text{h}^{-1}$). The maximum wind speed was 85–95 knots ($137\text{--}176 \text{ km} \cdot \text{h}^{-1}$) and the radius of maximum winds was about 50 nautical miles (93 km). Another remarkable feature of this hurricane is in the generated surge. Along the Texas-Louisiana coast the storm surge occurred for almost a 6-d period (September 7–12, 1961). Maximum surge height of about 10ft. (3.1 m) was estimated on September 10 at Galveston. The calculated surge was compared with the observed surge by MIYAZAKI (1965) at the following stations: Port Isabel (Texas), Port Aransas (Texas), Freeport (Texas), Pier 21 and Pleasure Pier (both in the Galveston area), Fort Point (Texas), Sabine Pass (Texas), Bayou Rigaud (Louisiana), Humble Oil Platform A (Louisiana) and Pensacola (Florida).

Hurricane Betsy struck the southeastern Louisiana coast on September 9, 1965. It was the most destructive (economically) ever to hit the United States coast up to that time (GOUDEAU and CONNER, 1968). Winds reaching up to $125 \text{ mi} \cdot \text{h}^{-1}$ ($201 \text{ km} \cdot \text{h}^{-1}$) caused a great storm surge resulting in extensive flooding in the Metropolitan area of New Orleans. Goudeau and Conner 1968 also gave detailed diagrams for the storm surge height distribution and flooded areas on the Mississippi River and also in Lake Pontchartrain.

PEARCE (1972) developed a two-dimensional, time-dependent numerical model for studying storm surges in the Gulf of Mexico. He used two different mesh sizes: 16 nautical miles (29.6 km) and 6 nautical miles (11.1 km). These were applied to the surge generated by Hurricane Camille of August 17–22, 1969. There was no significant difference in the results between the smaller grid and larger grid models. Inclusion of the nonlinear advective terms made only a difference of 2 % in the surge heights. The model results were insensitive to bottom friction coefficients between 0.005 and 0.02. PEARCE (1972) also used a one-dimensional model as well as an analytical model. The distribution of surge heights computed for August 17 at 23:40 is shown in Fig. 6.11. Although in this subsection the Gulf of Mexico was considered as a whole, later subsections will consider parts of this system such as Galveston Bay, Mobile Bay, etc. in detail.

Howard Elgison made the following comments in ANNON (1992) on page 60. Hopefully there will never be another storm with the destructive power of Hurricane Andrew. Certainly, there will never be another hurricane named Andrew. Like the great athletes whose numbers have been retired, the great hurricanes, those that were particularly severe or destructive, have their names retired.

Currently, a total of 33 names are enshrined in the Hurricane Hall of Infamy. They are listed below in chronological order:

1954 Carol-Edna – Hazel	1970 Celia
1955 Connie – Diane – Ione – Janet	1972 Agnes
1957 Audrey	1974 Carmen
1959 Gracie	1975 Eloise
1960 Donna	1977 Anita
1961 Carla	1979 David - Frederic
1963 Flora	1980 Allen
1964 Cleo – Dora – Hilda	1983 Alicia
1965 Betsy	1985 Elena – Gloria
1967 Beulah	1988 Gilbert – Joan
1969 Camille	1989 Hugo
	1991 Bob

Table 6.5: Hurricanes and storm surges in the Gulf of Mexico during 1900-19.

Date(s) of hurricane	Hurricane	Storm surge
Sept. 1-12, 1900	Hurricane reached Florida Straits on Sept. 5 and moved in a north-westerly direction across the gulf a distance of about 1600 km. Maximum winds observed were 193 km-h ⁻¹ .	Surge of 4.6 m at Galveston on Sept. 8; over 6000 people killed; \$ 30 million damage (in 1920 currency)
July 5-10, 1901	Storm of small extent and moderate intensity moved through the Yucatan channel into the Gulf of Mexico on July 7 and reached the Texas coast west of Galveston on July 10.	Surge of 1.4 m at Galveston; no damage
Aug. 9-15, 1901	Hurricane first appeared to the north of Cuba on Aug. 9. It moved across southern Florida and into the Gulf of Mexico on the morning of Aug. 11, continued its course westward to 90° W when, during Aug. 14, it recurved and on the morning of Aug. 15 passed northeastward between New Orleans and Port Eads. Hurricane had small diameter but great intensity and its track was unusual.	Surge of 1.3 m at Port Eads, 1.7 m at New Orleans, and 2.5 m at Mobile; 10 persons killed; \$ 1 million damage
Sept. 23-27, 1906	Disturbance passed through the Yucatan channel on the morning of Sept. 24, travelled roughly in a straight line, and moved in on the Mississippi coast on the morning of Sept. 27. Hurricane was of large extent and of unusual intensity.	Surge of 1.2 m at Port Eads, 3.3 m at Pensacola. At Pensacola 32 people killed and near Mobile 31 killed (it is not known whether some of these deaths were due to hurricane and not the surge)
July 18-21, 1909	Hurricane moved from the Caribbean Sea though the Yucatan Channel on July 18 and moved inland on the Texas coast with its centre near Velasco.	Surges (amplitude not known) occurred to the right of the storm center up to Galveston; 4 people killed
Sept. 12-21, 1909	Storm of great extent and unusual intensity. Its effect was felt from east of Pensacola to the west of Galveston. Hurricane passed through the Yucatan channel during Sept. 17 and moved inland on the Louisiana coast on Sept. 20.	353 people killed; \$ 6.4 million damage
Oct. 13-18, 1910	Disturbance moved into the Florida Straits on Oct. 14, moved towards the northwest during Oct. 15, southward during Oct. 16, and then eastward to the Florida Straits by the morning of Oct. 17 after which it moved northward over Florida on Oct. 18.	Negative surge of 2 m at Tampa
Aug. 13-17, 1915	Storm moved across the western end of Cuba into the Gulf of Mexico during the morning of Aug. 14, travelled in a direct line, and passed inland on the Texas coast a short distance to the left of Galveston on the morning of Aug. 17.	\$ 21 million damage

- Sept. 2-4, 1915
Disturbance of considerable intensity crossed western Cuba, moved into the east Gulf, and receding slowly, moved inland near the mouth of the Apalachicola River during early morning of Sept. 4.
- Sept. 22-30, 1915
One of the most intense hurricanes in the history of the Gulf coast. Hurricane moved through the Yucatan channel during the night of Sept. 27 and, travelling northwestward, moved inland on the Louisiana coast to the left of and near Grand Isle during Sept. 29. Disturbance recurred slowly after crossing latitude 27° N and moved slowly northward.
- July 1-6, 1916
Disturbances first appeared in the Caribbean Sea on the afternoon of July 1, moved almost in a straight line through the Yucatan channel on July 3, and reached the Mississippi coast late in the afternoon of July 5. Storm covered considerable area and was of great intensity.
- Aug. 12-19, 1916
Disturbances passed through the Yucatan channel into the Gulf during the night of Aug. 16, advanced northwesterly in nearly a straight line, and moved inland on the Texas coast midway between Corpus Cristi and Brownsville during the afternoon of Aug. 19.
- Sept. 21-29, 1917
Disturbance moved through the Yucatan channel into the Gulf during the night of Sept. 25 and advanced in a direction a little west of north towards the mouth of the Mississippi river. When within about 80 km of Port Eads the storm began receding to the right and center, passing about 80 km to the right of Port Eads, and moved inland to the right of Pensacola.
- Aug. 1-6, 1918
Disturbances moved through the Yucatan channel into the Gulf of Mexico during the night of Aug. 4, travelled in a northwesterly direction, and passed inland over Lake Charles during Aug. 6. Hurricane was small but of marked intensity.
- Sept. 6-14, 1919
Storm moved through the Yucatan channel into the Gulf towards the mouth of the Mississippi River. Then it moved more or less parallel to the coast.
- Surge of at least 1.5 m at St. Petersburg
- 275 persons killed; \$ 13 million damage. Surge heights up to 3.7 m on the coast of Lake Pontchartrain and 3-3.4 m on the Louisiana and Mississippi coasts. Inside Lake Pontchartrain, surges up to 4 m
- Damage at Mobile and along the Alabama coast of \$ 2.5 million; 12 people killed. Damage at Pensacola of \$ 1 million. Maximum surge up to 3.5 m.
- 15 people killed; \$ 1.8 million damage. Surges greater than 2.1 m at Mobile.
- Surge of 0.86 m at Pensacola. Surge of 1.77 m at Fort Barancas. Negative surge of 1.52 at Mobile.
- \$ 5 million damage and 34 people killed due to the hurricane. Surge of 0.91 m at Morgan City. Surge of 0.86 at Johnson Bayou
- 284 people killed; more than \$ 20 million damage. Surges of up to 3.7 m occurred

Table 6.6: Lowest central pressures and highest surges of Gulf of Mexico hurricanes (CONNOR et al., 1957)

Date	Location of highest surge on open coast	Lowest Pressure (mb)	Peak Surge (m)
Oct. 2, 1983	Mobile, AL	956	2.56
Sept. 8, 1900	Galveston, TX	936	4.42
Aug. 14, 1901	Mobile, AL	973	2.26
Sept. 27, 1906	Fort Barrancas, FL	965	3.29
July, 21, 1909	Galveston, TX	959	3.05
Sept. 20, 1909	Mobile, AL	980	2.38
Sept. 13, 1912	Mobile, AL	993	1.34
Aug. 16, 1915	High Island, TX	953	4.24
Sept. 29, 1915	Grand Isle, LA	944	2.74
July 5, 1916	Fort Morgan, AL	961	1.43
Sept. 28, 1917	Fort Barrancas, FL	964	2.16
Sept. 14, 1919	Port Aransas, TX	948	3.38
Oct. 25, 1921	St. Petersburg, FL	958	2.38
Aug. 25, 1926	Timbalier Bay, LA	959	3.05
Sept. 20, 1926	Pensacola, FL	955	2.32
Sept. 5, 1933	Brownsville, TX	949	3.96
July 25, 1934	Galveston, TX	975	1.80
July 31, 1936	Panama City, FL	964	1.83
Aug. 7, 1940	Calcasieu Pass, LA	974	1.46
Sept. 23, 1941	Sargent, TX	959	3.02
Oct. 7, 1941	St. Marks, FL	981	2.44
Aug. 30, 1942	Matagorda, TX	951	4.51
July 27, 1943	Galveston, TX	975	1.22
Aug. 27, 1945	Matagorda, TX	968	2.23
Aug. 24, 1947	Sabine Pass, LA	992	1.10
Sept. 19, 1947	Biloxi, MS	968	3.38
Sept. 4, 1948	Biloxi, MS	987	1.71
Oct. 4, 1949	Freeport, TX	978	3.17
Aug. 30, 1950	Pensacola, FL	979	1.68
Sept. 5, 1950	Cedar Key, FL	958	1.55

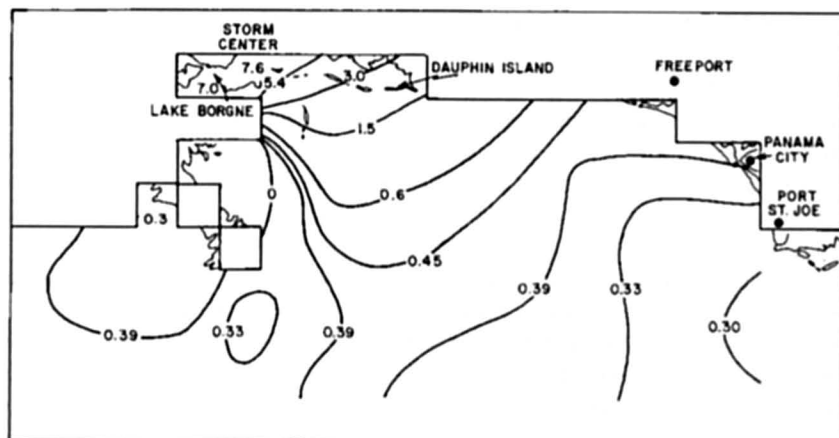


Fig. 6.11: Distribution of the water levels (storm surge with a 0.25 m tide superimposed) along parts of the coasts of Louisiana, Mississippi, and Alabama due to Hurricane Camille of 1969 (PEARCE, 1972)

There are many ways to measure the destructive power of hurricanes. The method chosen by the National Hurricane Center (NHC) is to calculate the total dollar value of property losses in the United States and adjust for inflation. Using this method, the top six hurricanes of all time are listed below. The damage Figs. are given in 1990 dollars. Needless to say, Hurricane Andrew sits atop the list with monetary damages greater than the combined total of the next three most costly storms. Table 6.7 lists the damage from some intense Hurricanes that affected the U.S.A.

Table 6.7: Damage in Billions of U.S. Dollars (at 1990 prices) by the Topio Hurricanes affecting the U.S.A. (ANON, 1993)

Rank	Hurricane	Year	Damage in Billions of US Dollars at 1990 price levels
1	Andrew	1992	30.0
2	Hugo	1989	7.0
3	Frederic	1979	2.3
4	Agnes	1972	2.1
5	Alicia	1983	2.0
6	Iniki	1992	1.8
7	Juan	1985	1.5
8	Camille	1969	1.427
9	Betsy	1965	1.425
10	Elena	1985	1.25

Even though only 53 people died in the wake of Hurricane Andrew, it is the single most natural disaster in U.S. history in terms of damage up to that time.

6.1.3. Storm Surges along the Coast of Florida

In this subsection, storm surges along the Gulf of Mexico coast and the Atlantic coast of Florida will be considered. Storm surges in Lake Okeechobee will be considered in the next subsection. DAMSGAARD and DINSMORE (1975) used a two-dimensional numerical model to study storm surges in Biscayne Bay, Florida. Their model allows for overtopping of low-lying barrier islands as well as inundation of flood plains. They tested their model against the storm surge generated by Hurricane Betsy of September 8, 1965.

VERMA and DEAN (1969) also used a two-dimensional model to study storm surges in Biscayne Bay. Their model allows for the inclusion of rainfall. ROSS and JERKINS (1977) used two different models to study storm surges in Tampa Bay, Florida. The first model (referred to as USF) was developed at the University of South Florida and is based on the explicit model by REID and BODINE (1968). The second model is based on the Rand model (LEENDERTSE, 1967) and makes use of an implicit-explicit scheme. Based on calculations for Tampa Bay, these authors concluded that the USF model provides a more accurate simulation than the Rand model.

By far the most comprehensive study of storm surges on the Florida coast (which this author could find) is one by BRUUN et al. (1962), in which they studied the storm surges in relation to coastal topography. Forty hurricanes during the period 1900-60 that caused significant storm surges along Florida coast are listed in Table 6.8.

Table 6.8: Major Hurricanes affecting Florida, 1903–65. The last four entries are taken from TETRA TECH INC. (1978) coastal flooding storm surge model, Part I. Methodology prepared by Tetra Tech Inc. for U.S. Dep. Of Insurance Administration, Washington, DC, May 1978 (BRUUN et al., 1962)

Index No.	Date of occurrence	Coastal area affected
1	Sept. 10–16, 1903	Fort Lauderdale and Tampa Bay
2	Oct. 10–23, 1904	West Palm Beach
3	Oct. 11–20, 1906	Florida Keys and Miami
4	Oct. 6–15, 1909	Florida Keys and Miami
5	Oct. 11–13, 1910	Key West to Tampa Bay and Jacksonville
6	Sept. 2–14, 1919	Florida Keys
7	Sept. 27–Oct. 1, 1920	Cedar Keys and St. Augustine
8	Oct. 21–23, 1921	Tampa Bay and Daytona Beach
9	July 22–Aug. 2, 1926	Entire east coast
10	Sept. 6–22, 1926	Miami and Everglades to Tampa Bay
11	Aug. 7–10, 1928	Fort Pierce and Cedar Key
12	Sept. 6–20, 1928	West Palm Beach to Jacksonville
13	Sept. 22–Oct. 4, 1929	Florida Keys to Tampa Bay
14	Aug. 31–Sept. 7, 1933	West Palm Beach to Cedar Key
15	Aug. 31–Sept. 8, 1935	Florida Keys to Cedar Key
16	Oct. 30–Nov. 8, 1935	West Palm Beach to Miami and Key West to Fort Myers
17	July 27–Aug. 1, 1936	Miami and Everglades to Tampa Bay
18	Oct. 4–12, 1941	Miami to Florida Keys and Everglades to Cedar Key
19	Oct. 13–21, 1944	Key West to Tampa Bay and Jacksonville
20	Sept. 12–19, 1945	Florida Keys to Miami and northeast coast
21	Oct. 7–9, 1946	Fort Myers to Cedar Key and Jacksonville
22	Sept. 11–19, 1947	Fort Lauderdale and Fort Myers
23	Oct. 9–15, 1947	Key West to Miami
24	Sept. 19–25, 1948	Key West to Fort Myers and Fort Pierce
25	Oct. 4–8, 1948	Florida Keys to Fort Lauderdale
26	Aug. 24–29, 1949	West Palm Beach and Cedar Key
27	Sept. 1–7, 1950	Key West to Cedar Key
28	Oct. 15–19, 1950	Entire east coast
29	Sept. 30–Oct. 7, 1951	Fort Myers and Fort Pierce
30	Oct. 8–10, 1953	Fort Myers and Fort Pierce <i>Florida Panhandle</i>
31	Sept. 10–30, 1906	Pensacola
32	Aug. 9–14, 1911	Key West to Pensacola
33	Sept. 11–23, 1912	Tampa Bay to Pensacola
34	Sept. 4, 1915	Key West to Apalachicola
35	July 5, 1916	Pensacola
36	Oct. 12–21, 1916	Pensacola
37	Sept. 21–29, 1917	Pensacola
38	Sept. 13–20, 1924	Panama City of Apalachicola
39	Sept. 24–26, 1953	Pensacola to Panama City
40	Sept. 9–12, 1960 (Donna)	Florida Keys and South Gulf Coast
41	Aug. 26–29, 1964 (Cleo)	Southeast Florida
42	Sept. 7–11, 1964 (Dora)	Northeast Florida
43	Oct. 8–16, 1964 (Isabell)	Southern Florida
44	Sept. 6–9, 1965 (Betsy)	Southern tip of Florida

6.1.4 Lake Okeechobee

In an earlier section a storm surge study by REID et al. (1977a, 1977b) was considered, which treated the extensive vegetation areas of Lake Okeechobee as a canopy. MYERS (1954) studied in detail the data from the hurricanes that were pertinent for levee design for this lake. Here, some studies on storm surges in this lake will be considered. KIVISILD (1954) made an extensive study of storm surges in shallow bodies of water and applied this to Lake Okeechobee storm surges.

During the period 1886–1950, the average number of hurricanes reaching Florida was 1.28 per year. The probability that the Okeechobee area would be subjected to winds greater than $75 \text{ mi} \cdot \text{h}^{-1}$ ($121 \text{ km} \cdot \text{h}^{-1}$) in any given year is 1 in 7. Several tide gauges were located during the Lake Okeechobee project that was organized during the early 1950s. The north-south extent (maximum) of the lake is 30 mi (48 km), the east-west extent (maximum) is 25 mi (40 km), and the total area is 730 mi^2 (1891 km^2). Extensive marsh and vegetation covers the western portion of the lake. The south shore of the lake from St. Lucie Canal to Fisheating Creek is enclosed by levees constructed to an average crown height of 32.5 ft (9.8 m) above mean sea level. On the north shore a levee of the same height extends from 2 mi (3.2 km) southeast of Taylor Creek to Kissimmee River, and this levee protects the town of Okeechobee. The northwest portion of the lake, bordering low, saw grass marshes, and the northeast shore, bordering comparatively high ground, are unprotected. Ritta, Kreamer, and Torry islands at the southern end of the lake are partially protected by levees but these are insufficient against storm surges such as the hurricane of August 26–27, 1949.

KIVISILD (1954) used simple analytical formulae to calculate the surges in Lake Okeechobee. However, for better resolution of the geometry of the lake, he divided it into triangular elements. The pertinent information of the five hurricanes studied by KIVISILD (1954) and the related surges is summarised in Table 6.9.

LANGHAAR (1951) calculated the storm surges in Lake Okeechobee using simple analytical formulae. These values agreed well with observed surges, which ranged from 3.5 to 10.2 ft (1.1–3.1 m). In this calculation, Langhaar considered the surge at the leeward end of the lake as a superposition of the surge due to seiches and a static surge that the wind would maintain if it persisted indefinitely. The surge due to seiche is referred to as the “dynamical surge” and the total surge is the sum of the dynamical and static surges. FARRER (1958) also used simple analytical formulae to compute storm surges in Lake Okeechobee for the hurricane of August 26, 1949. The water level distribution in the lake at three different times is shown in Fig. 6.12. The shaded area represents the marsh.

DANARD and MURTHY (1994) re-examined the work of REID and WHITAKER (1976) on the effect of vegetation in Lake Okeechobee on the storm surges.

Their assumptions on the equality of various drag coefficients are replaced by more realistic calculations. A new method for calculating wind stress on water is presented for the case when the vegetation extends above the water surface.

For the case of vanishingly small water-depth, it is shown that the horizontal stress is approximately constant in the vertical. This results in a diagnostic relationship for the water current as a function of the wind stress and bottom roughness.

A new expression for the vertically averaged frictional force per unit mass is derived on the assumption that the friction velocity varies linearly with height. The vertical rate of change of friction velocity depends on the mean water current, the wind stress, the bottom roughness, and the water depth.

For coastal defenses against storm surges, traditionally concrete sea walls have been in

Table 6.9. Five hurricanes and storm surges in Lake Okeechobee studied by KIVISILD (1954)

Date(s) of Hurricane	Meteorological information	Storm surge information
Sept. 15-16, 1945	Storm first noted east of the Leeward Islands on Sept. 11; it passed north of Puerto Rico on Sept. 13 and near Turks Island on the night of Sept. 13-14. It began a slow curvature over the great Bahamas Banks during the night of Sept. 14-15 and struck Florida with its center passing over the northern end of Key Largo. Highest measured wind velocity was $222 \text{ km} \cdot \text{h}^{-1}$ at Carysfort Reef, at the southern tip of Florida. Path of the hurricane-intensity winds was only 32-48 km wide, so that only the southwestern shores of Lake Okeechobee received winds of a velocity greater than $121 \text{ km} \cdot \text{h}^{-1}$. Storm was, in general, of moderate intensity.	Maximum surge recorded was about 1.8 m in range
Sept. 16-18, 1947	Hurricane center developed on Sept. 5 in the vicinity of Dakar (French West Africa). It moved about $27 \text{ km} \cdot \text{h}^{-1}$ on a west-northwest course to the Bahamas where on Sept. 15 it became almost stationary for about 24 h. Center reached the Florida coast at Fort Lauderdale on Sept. 17. Highest recorded wind velocity in Florida was $250 \text{ km} \cdot \text{h}^{-1}$ at Hillsboro Light near Pompano. Center moved westward across the state at about $16 \text{ km} \cdot \text{h}^{-1}$ and entered the Gulf of Mexico just north of Naples. Hurricane force winds were experienced along about 386 km of the Florida east coast, while winds of $160 \text{ km} \cdot \text{h}^{-1}$ were recorded in a 113-km stretch between Miami and Palm Beach. Hurricane was one of the great storms. Lowest barometric pressure recorded in the Lake Okeechobee area was about 985 mb at Moore Haven.	Maximum positive surge of about 2.13 m and a maximum negative surge of 1.22 m
Sept. 21-22, 1948	Hurricane center developed on Sept. 18 between Jamaica and Grand Cayman Islands and moved slowly in a northerly direction passing over Cuba on Sept. 20 with winds greater than $160 \text{ km} \cdot \text{h}^{-1}$. When the storm center passed over Florida on Sept. 21-22 there appeared to have been several centers, with lulls reported from 64 to 129 km apart normal to the path of the storm. Speed of movement of the storm was $13-16 \text{ km} \cdot \text{h}^{-1}$. Strongest wind recorded was in gusts of $196 \text{ km} \cdot \text{h}^{-1}$ at Boca airport near Key West. By the time the Lake Okeechobee region was reached, wind velocities diminished to gusts of about $145 \text{ km} \cdot \text{h}^{-1}$. Lowest barometric pressure recorded in the Lake Okeechobee area was 962.8 mb.	Calculated values much bigger because the bottom friction due to the marsh grass was not taken into account
Aug. 26-27, 1949	Storm was noticed on Aug. 23 in its formative stage, 201 km northeast of Leeward Islands. Center was well organized by the time it passed North Nassau on Aug. 26 and it intensified as it approached the Florida coast. Strongest winds occurred some distance to the right of the center near Jupiter, FL, where the anemometer failed after reaching an extreme of $246 \text{ km} \cdot \text{h}^{-1}$. Center passed the northern part of Lake Okeechobee during the early part of the evening of Aug. 26 with wind velocities ranging from 160 to $203 \text{ km} \cdot \text{h}^{-1}$. In the Lake Okeechobee section it was the worst hurricane felt since the great disastrous hurricane of September 1928.	Storm surges with ranges up to 4.27 m were recorded
Oct. 17-18, 1950	Storm formed over the northwestern Caribbean Sea on Oct. 15 and moved northeastward and then northward across Cuba as a small hurricane. Center of the hurricane, about 8 km in diameter passed directly over Miami on the midnight of Oct. 17-18. Highest recorded wind speed was $201 \text{ km} \cdot \text{h}^{-1}$. Center crossed northward over Lake Okeechobee during the morning of Oct. 18 with wind gust up to $153 \text{ km} \cdot \text{h}^{-1}$. In general, the diameter of this storm was smaller than that of most hurricanes, and sustained wind velocities were barely above the minimum hurricane	Surges with a maximum range of 2.74 m were recorded

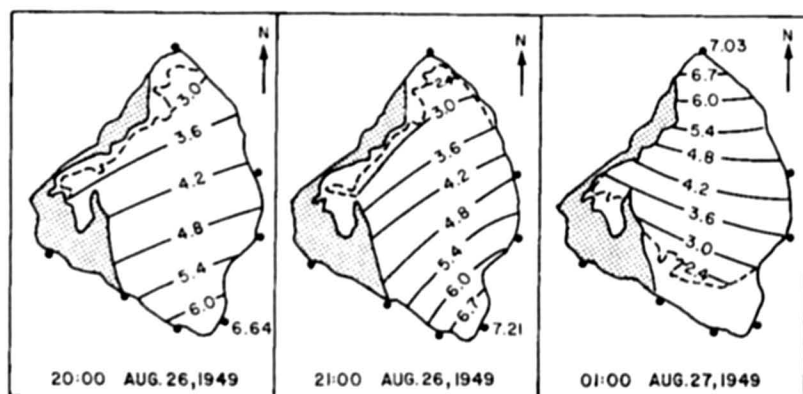


Fig. 6.12: Storm surge height (meters) distribution at three different times in Lake Okeechobee, Florida, due to the hurricane of August 26-27, 1949. (FARRER, 1958)

use. Even such prohibitively expensive structures might not be able to withstand the full force of impact from the incoming surge. Indeed during the 29 April 1991 storm surge in Bangladesh, two-foot thick concrete walls were taken out by the surge.

Earlier it was noticed (REID and WHITAKER, 1976) that surges were of smaller amplitude in those parts of Lake Okeechobee in Florida, wherever there was tall reed grass extending above the water surface. Thus there is observational evidence that a vegetation canopy can reduce storm surges significantly. However, it should be noted that this type of moderation by vegetation would occur more for the locally generated surge by a local wind field, than for that part of the surge that is generated outside and propagates into the region under discussion. This is because for a locally generated surge, the wind speed and therefore wind stress on the water surface are reduced by vegetation protruding above the water. Generally, the locally generated surge accounts for 50 to 80 % of the total surge; hence possible reduction of storm surges by vegetation canopies is of great practical interest.

The case where the water completely covers the canopy is shown in Fig. 6.13. D is the undisturbed total depth of the water and b is the height of the canopy. The velocity of the water above the canopy ($b \leq z \leq D$) is u_1 , τ_a is the stress (force per unit area) that the atmosphere exerts on the water surface, τ_c is the stress the upper layer exerts on the lower, and τ_b is the stress lower layer exerts on the bottom.

Ignoring atmospheric pressure gradients, the linearized, vertically integrated equation of motion for the lower (canopy) layer is

$$\rho \frac{\partial U_1}{\partial t} + \rho g b \nabla h = \hat{\sigma}_c - \hat{\sigma}_b - F_c - \rho f \mathbf{k} \times U_1 \quad (6.3)$$

Where

$$U_1 = bu_1$$

h is the perturbation height of the free surface and F_c is the resistance (force per unit horizontal area) due to the canopy elements. Since the fluid is hydrostatic and homogeneous, the horizontal pressure gradient force is independent of z and is proportional to the gradient of the perturbation height of the free surface even in the lower layer. Let N be the number of

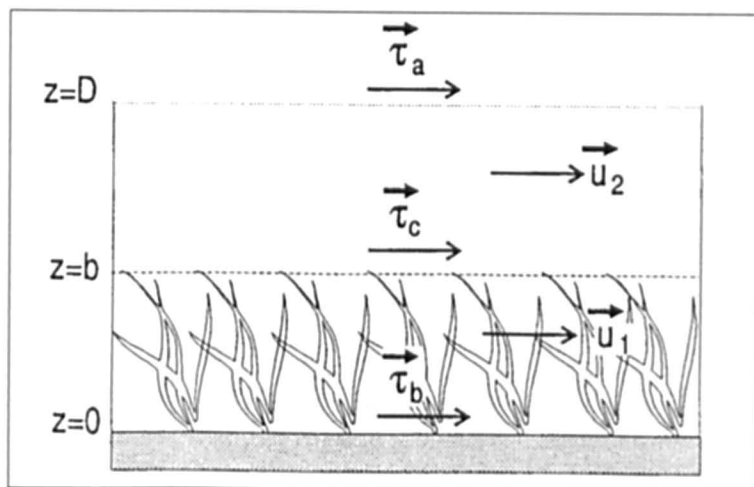


Fig. 6.13: Schematic diagram of stresses and water velocities in case where water completely covers the canopy (DANARD and MURTY, 1994)

canopy elements per unit horizontal area of width w . Then the vertical area obstructing the flow is bw for each canopy element, so the total obstructing area (per unit horizontal area) is Nbw . Thus

$$F_c = \rho C_d Nbw |u_1| u_1 \quad (6.4)$$

where, C_d is the drag coefficient for the vertical surface of the canopy elements. For rigid canopy elements presenting a flat surface perpendicular to the water flow, the velocity should be zero or nearly so immediately behind the canopy elements. The dynamic pressure force per unit horizontal area opposing u_1 is

$$F_c = \frac{1}{2} \rho u_1^2 Nbw \quad (6.5)$$

Equating (6.4) and (6.5) gives

$$C_d = 1/2 \quad (6.6)$$

This is of course an upper limit. In general, C_d will be smaller.

Reid and Whitaker write τ_c as

$$\hat{\sigma}_c = \rho f_1 |u_2 - u_1| (u_2 - u_1) \quad (6.7)$$

where, f_1 is a non-dimensional coefficient. An alternate expression to (6.7) may be derived using reasoning similar to that of CRESSMAN (1960). Let ϵ ($\perp b$) be the top part of canopy that u_2 senses. The vertical area of the canopy obstructing u_2 is Nwe per unit horizontal area. Assuming zero velocity immediately behind the canopy elements, the dynamic pressure force opposing u_2 is $Nwe < 1/2 \rho u_2^2$. Let k (< 1) be an efficiency factor representing the efficiency of the top of the canopy in blocking u_2 . Then

$$\hat{\sigma}_c = kNw \in \cdot \frac{1}{2} \rho |u_2| u_2 \quad (6.8)$$

We can write (6.8) as

$$\hat{\sigma}_c = \rho C |u_2| u_2 \quad (6.9)$$

where,

$$C = \frac{kNw \in}{2} \quad (6.10)$$

is the drag coefficient of the top of the canopy. CRESSMAN (1960) estimates $k \sim 1/4$ for air flowing over mountain ridges. For $k = 0.25$, $N = 100 \text{ m}^{-2}$, $w = 0.1 \text{ m}$ and $\epsilon = 0.1 \text{ m}$, (6.10) gives

$$C = 0.125 \quad (6.11)$$

The equation of motion for the upper layer is

$$\frac{\partial U_2}{\partial t} + \rho g(D-b)\nabla h = \hat{\sigma}_a - \hat{\sigma}_c - \rho f k \times U_2 \quad (6.12)$$

Where

$$U_2 = (D-b)u_2$$

Write τ_a as

$$\hat{\sigma}_a = \rho_a C_w |W| W \quad (6.13)$$

where, ρ_a is the air density, C_w is the drag coefficient of the water surface, and W is the anemometer level wind. A typical value for C_w is (ROLL, 1965)

$$C_w = 2 \times 10^3, \quad (6.14)$$

although SIMONS (1978) points out that storm surge modellers frequently must use higher values.

Now consider the case where the canopy extends above the water surface as shown in Fig. 6.14. τ_w is the stress the wind exerts on the top of the canopy, W_1 is the mean wind within canopy, and τ_s is the stress the wind (i.e., W_1) exerts on the water surface. Clearly, $|W_1| < |W|$ so $|\tau_s| < |\tau_a|$. Let R be the stress (force per unit horizontal area) exerted by W_1 on the vertical canopy elements. By analogy to equation (6.4),

$$R = \rho_a C_d N(b-D)w |W_1| W_1 \quad (6.15)$$

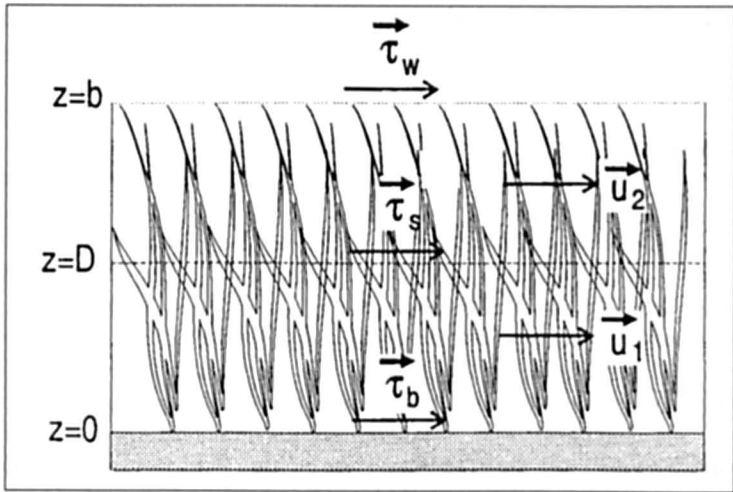


Fig. 6.14: Schematic diagram of stresses in case where canopy extends above the water surface (DANARD and MURTY, 1994)

The same drag coefficient is used in (6.4) and (6.15) since C_d is a function of the roughness of the surface and does not depend on the fluid (water or air) flowing over the surface. By analogy to (6.9),

$$\delta_w = \rho_a C |\mathbf{W}| \mathbf{W} \quad (6.16)$$

The same drag coefficient applies to (6.9) and (6.16) since they both represent fluid moving over the top of the canopy. By analogy to (6.13)

$$\delta_s = \rho_a C_w |\mathbf{W}_1| \mathbf{W}_1 \quad (6.17)$$

From the balance of forces in the layer $D \leq z \leq b$,

$$\delta_s = \delta_w \cdot \mathbf{R} \quad (6.18)$$

Each term in (6.18) is in the direction of \mathbf{W} . Substituting (6.15) – (6.17) in (6.18) gives

$$\mathbf{W}_1^2 = \left[\frac{C}{C_w + C_d N(b-D)} \right] \mathbf{W}^2 \quad (6.19)$$

This enables one to calculate τ_s from (6.17). Reid and Whitaker assume that $C = C_w = C_d$. However, C refers to flow over the top of the canopy whereas C_w refers to flow over a water surface. Clearly, then, $C \neq C_w$. Also, C_d refers to the obstruction to flow of the vertical surface of the canopy elements. Obviously between $C_w \neq C_d$ and $C \neq C_d$. The values given by (6.6), (6.11) and (6.14) show the differences between C_d , C and C_w . The equation of motion for the water layer is (6.3)

$$\rho \frac{\partial \mathbf{U}_1}{\partial t} + \rho g D \nabla h = \delta_s - \delta_b - \mathbf{R} - \rho f \mathbf{k} \times \mathbf{U}_1 \quad (6.20)$$

The magnitude of the wind stress on the water is

$$\hat{\sigma}_s = \rho_a C_w W^2 \quad (6.21)$$

where, W_1^2 is evaluated from (6.19). Substituting (6.19) in (6.21) yields

$$\hat{\sigma}_s = \left[\frac{\rho_a C_w C}{C_w + C_d N(b-D)w} \right] W^2 \quad (6.22)$$

Using Reid and Whitaker's assumption ($C_w = C = C_d$), $\rho_a = 1.2 \text{ kgm}^{-3}$, $C_w = 2 \times 10^{-3}$, $N = 100 \text{ m}^{-2}$, $b = 2 \text{ m}$, $D = 1 \text{ m}$ and $w = 0.1 \text{ m}$, (6.22) gives

$$\hat{\sigma}_s = 2.2 \times 10^{-4} W^2 \quad (6.23)$$

for τ_s on Pa and W in ms^{-1} . On the other hand if we employ (6.6), (6.11) and (6.14) in (6.1.50), we obtain

$$\hat{\sigma}_s = 6.0 \times 10^{-6} W^2 \quad (6.24)$$

There is clearly a significant difference between (6.23) and (6.24), due to the fact that Reid and Whitaker predict a much higher wind speed at the water surface.

Comparison of equations (6.23) derived by Reid and Whitaker and (6.24) derived here shows that for the situation where the vegetation extends above the water surface, the effective wind stress is an order of magnitude smaller. This explains why a vegetation canopy (especially in the situation where the vegetation extends above the water surface) can moderate storm surges quite significantly.

It is well known that most of damage to coastal structures during a storm surge occurs from water currents and wind waves and not from the high water levels themselves. Hence, it is important to compute the water currents and wind waves for building design purposes.

Consider now the case of wind-driven water flow without a canopy. The linearized equation of motion is

$$\frac{\partial \mathbf{u}}{\partial t} + g \nabla h + \frac{1}{\rho} \nabla \rho_a = \frac{1}{\rho} \frac{\partial \hat{\sigma}}{\partial z} - f \mathbf{k} \times \mathbf{u} \quad (6.25)$$

where, ρ_a is atmospheric pressure. Tides may be included in (6.25) by imposing boundary conditions on \mathbf{u} and h at the seaward boundary of the computational domain. The non-linear advective acceleration is omitted from (6.25) although this may be important. Take the vertical average of (6.25) to yield

$$\frac{\partial \bar{\mathbf{u}}}{\partial t} + g \nabla h + \frac{1}{\rho} \nabla \rho_a = \mathbf{F} - f \mathbf{k} \times \bar{\mathbf{u}} \quad (6.26)$$

where, ($\bar{\mathbf{u}}$ is the vertically averaged water velocity,

$$\mathbf{F} = \frac{(\hat{\sigma}_a - \hat{\sigma}_b)}{\rho H} \quad (6.27)$$

is the vertically averaged friction force per unit mass and $H = D + h$ is the total water depth. τ_a is usually calculated from (6.13). τ_b is frequently computed from a similar expression

$$\hat{\sigma}_b = \rho c |\bar{u}| \bar{u} \quad (6.28)$$

where, c is the drag coefficient of the bottom surface. FLATHER (1979) and GREENBERG (1977) use

$$c = 2.5 \times 10^{-3} \quad (6.29)$$

However, (6.13) and (6.28) are calculated essentially independently, (6.4) therefore has a singularity as the denominator approaches zero. FLATHER and HEAPS (1975) avoid this singularity by specifying a minimum depth $D_0 = 1\text{m}$ for use in (6.27). While this is preferable to having the model blow up, a better way is needed.

As the water depth becomes smaller, one would expect $\tau_b \rightarrow \tau_a$. Given the dimensionless number $\delta (\leq 0.1)$, there exists a depth $d(\delta)$ such that

$$\frac{|\hat{\sigma}_a - \hat{\sigma}_b|}{|\hat{\sigma}_a|} \leq \delta \quad (6.30)$$

for $H \leq d$. However, (6.30) simply implies a constant flux layer through which $\tau = \tau_a$. For a neutral stratification this means

$$u = \frac{u_{*w}}{k_v} \ln \left(\frac{z}{z_0} \right) \quad (6.31)$$

where u_{*w} is the (constant) water friction velocity, k_v is von Karman's constant, and z_0 is the roughness length of the bottom surface. The vertical average of (6.31) is

$$\bar{u} = \frac{1}{(H - z_0)} \int_{z_0}^H u dz \quad (6.32)$$

Substituting (6.31) in (6.32) gives

$$\bar{u} = \frac{u_{*w}}{(H - z_0)k_v} \left\{ H \left[\ln \left(\frac{H}{z_0} \right) - 1 \right] + z_0 \right\} \quad (6.33)$$

For $z_0 \leq H$, (6.33) simplifies to

$$\bar{u} = \frac{u_{*w}}{k_v} \left[\ln \left(\frac{H}{z_0} \right) - 1 \right] \quad (6.34)$$

Note that (6.33) and (6.34) are diagnostic expressions for the water current. The direction of \bar{u} is the same as τ_a or \mathbf{W} . This will be discussed further in the paragraph following equation (6.41).

To find u_{*w} , note that the stress the water surface exerts on the atmosphere is equal in magnitude and opposite in direction to the stress the atmosphere exerts on the water. This is:

$$\begin{aligned} \rho u^* w^2 &= \tau_a \\ \text{or} & \\ u^* w &= \left[\frac{\tau_a}{\rho} \right]^{1/2} \end{aligned} \quad (6.35)$$

An alternate to (6.33) and (6.34) may be obtained by setting $\tau_b = \tau_a$ in (6.28) and solving for \bar{u} to give

$$\bar{u} = \left(\frac{\tau_a}{c\rho} \right)^{1/2} \quad (6.36)$$

Let's obtain a numerical value for \bar{u} from (6.36). For $\rho_a = 1.2 \text{ kg m}^{-3}$, $C_w = 2 \times 10^{-3}$ and $W = 10 \text{ ms}^{-1}$, (6.13) gives $\tau_a = 0.24 \text{ Pa}$. Substitute this value in (6.36) along with $c = 2.5 \times 10^{-3}$ and $\rho = 10^3 \text{ kg m}^{-3}$ to obtain $(\bar{u} = 0.31 \text{ ms}^{-1})$.

An attempt will now be made to estimate the critical depth d following the method of DANARD (1981). Integrate (6.25) from $z = 0$ to $z = d$ and write as

$$\frac{|\hat{o}_a - \hat{o}_b|}{\hat{o}_a} = \frac{\rho d \left| \partial \mathbf{u} / \partial t + g \nabla h + \rho^{-1} \nabla \rho_a + f \mathbf{k} \times \bar{\mathbf{u}} \right|}{|\hat{o}_a|} \quad (6.37)$$

Equating the right side of (6.37) to (and solving for d gives

$$d = \frac{\delta |\hat{o}_a|}{\rho \left| \partial \mathbf{u} / \partial t + g \nabla h + \rho^{-1} \nabla \rho_a + f \mathbf{k} \times \bar{\mathbf{u}} \right|} \quad (6.38)$$

Suppose the water velocity decreases by 0.1 ms^{-1} in 10^3 s . Then for $\rho = 10^3 \text{ kg m}^{-3}$, $\rho |\partial \mathbf{u} / \partial t| \sim 0.1 \text{ Pa m}^{-1}$. The terms $g \nabla h$ and $f \mathbf{k} \times \bar{\mathbf{u}}$ frequently offset each other and do so exactly if the current is geostrophically balanced. The sum of these terms should be the same order of magnitude as $\partial \bar{\mathbf{u}} / \partial t$. Now

$$|\nabla \rho_a| = \rho_a f |\mathbf{W}_g| \quad (6.39)$$

where, \mathbf{W}_g is the geostrophic wind. For $\rho = 1.2 \text{ kg m}^{-3}$, $f = 10^{-4} \text{ s}^{-1}$ and $|\mathbf{W}_g| = 15 \text{ ms}^{-1}$, (6.39) gives $|\nabla \rho_a| = 1.8 \times 10^{-3} \text{ Pa m}^{-1}$. This is two orders of magnitude smaller than $\rho |\partial \bar{\mathbf{u}} / \partial t|$ so we will approximate (6.38) by

$$d = \frac{\delta |\hat{o}_a|}{\rho \left| \partial \bar{\mathbf{u}} / \partial t \right|} \quad (6.40)$$

In the previous paragraph we calculated $|\tau_a| = 0.24 \text{ Pa}$. Setting $\delta = 0.1$ in (6.40) yields Larger accelerations attainable in small mesh models would result in smaller values of d .

$$d = 0.24 \text{ m} \quad (6.41)$$

To show that $\bar{\mathbf{u}}$ is in the same direction as τ_a or \mathbf{W} , it has just been demonstrated that if $H \leq d$, then τ_a and τ_b are approximately parallel. One would expect $\bar{\mathbf{u}}(H)$ to be parallel to τ_a .

For small z , one would expect $\bar{\mathbf{u}}(z)$ to be parallel to τ_b (6.28). It follows that the direction of $\bar{\mathbf{u}}(z)$ is approximately constant for all z and therefore $\bar{\mathbf{u}}$ is parallel to τ_a .

It is proposed that the prognostic calculation of $\bar{\mathbf{u}}$ using equation (6.26) be replaced by a diagnostic calculation using equation (6.36), when the total water depth falls below a critical value d . Here d may be estimated from (6.38) or (6.10) using the nearest available data, or replaced by a constant which varies directly with grid size.

One shortcoming of the diagnostic approach is that the water current is always in the direction of the wind. Thus an ebbing tide with an onshore wind of any magnitude would result in onshore water current. Similarly, an incoming tide with zero wind stress would have zero water velocity. However, this is only for points nearest the shore whose depths are less than d .

Next we describe a new method for calculating \mathbf{F} , which may be used for smaller depths than equation (6.37). Consider 2-dimensional flow (u, w) in the vertical x - z plane. The following derivation in this paragraph [equations (6.42)–(6.49)] is similar to classical boundary layer theory (see e.g., HALTINER and MARTIN, 1957). However, the rest of the derivation is new. The horizontal stress is

$$\tau = -\rho u'w' \quad (6.42)$$

where, the primes denote perturbation velocities (departures from time-average values) and the carat signifies a time average. Assume that

$$u' = \ell \left(\frac{\partial u}{\partial z} \right) \quad (6.43)$$

where, ℓ is the mixing length. Assume also that

$$w' = -w' \text{sign} \left(\frac{\partial u}{\partial z} \right) \quad (6.44)$$

where, $\text{sign}(\partial u / \partial z)$ has the sign of $\partial u / \partial z$ and a unit magnitude. Substituting (6.43) and (6.44) in (6.42) yields

$$\tau = \rho \ell \left(\frac{\partial u}{\partial z} \right)^2 \text{sign} \left(\frac{\partial u}{\partial z} \right) \quad (6.45)$$

A negative sign ($\partial u / \partial z$) means that τ is in the $-x$ direction. Now assume that

$$\ell = k_v z \quad (6.46)$$

Substituting (6.46) in (6.45) gives

$$\tau = \rho \left(k_v z \frac{\partial u}{\partial z} \right)^2 \text{sign} \left(\frac{\partial u}{\partial z} \right) \quad (6.47)$$

Define the friction velocity u_* from the equation

$$\tau = \rho u_*^2 \text{sign}(u_*) \quad (6.48)$$

where, $\text{sign}(u_*) = \text{sign}(\partial u / \partial z)$. Then from (6.47) and (6.48),

$$u(z) = k_v z \frac{\partial u}{\partial z} \quad (6.49)$$

If

$$u_* = u_{*w} = \text{constant}, \quad (6.50)$$

where, u_{*w} is given by (6.35), then (6.31) is obtained. However, to obtain a more general result, instead of (6.50) it will be assumed that the friction velocity varies linearly with height, i.e.,

$$u_* = u_{*w} - a(H - z) \quad (6.51)$$

where, a is a constant, which may be positive or negative. Substituting (6.51) in (6.49) yields

$$u = \frac{(u_{*w} - aH)}{k_v} \ln \left(\frac{z}{z_0} \right) + \frac{b(z - z_0)}{k_v} \quad (6.52)$$

Note that (6.52) is similar to the 'log-linear' profile of stable flows (see, e.g. DEARDROFF, 1972, eq. [13]). The mean velocity is obtained by substituting (6.52) in (6.32), assuming $z_0 \perp H$, and integrating to give

$$\bar{u} = \frac{(u_{*w} - aH)}{k_v} \left[\ln \left(\frac{H}{z_0} \right) - 1 \right] + \left(\frac{aH}{2K_v} \right) \quad (6.53)$$

Since aH is unknown, (6.53) is not a diagnostic equation for \bar{u} . However, (6.34) and (6.36) are diagnostic equations.

The vertically averaged frictional force per unit mass is

$$F = \frac{u_{*w}^2 \text{sign}(u_{*w}) - u_{*0}^2 \text{sign}(u_{*0})}{H} \quad (6.54)$$

where, from (6.51),

$$u_{*0} = u_{*w} - aH \quad (6.55)$$

The quantity aH is obtained diagnostically from the mean water velocity using (6.53):

$$aH = \frac{u_{*w} \left[\ln \left(\frac{H}{z_0} \right) - 1 \right] - k_v \bar{u}}{\left[\ln \left(\frac{H}{z_0} \right) - \frac{3}{2} \right]} \quad (6.56)$$

This expression has a singularity for

$$\ln \left(\frac{H}{z_0} \right) = \frac{3}{2}$$

or

$$\frac{H}{z_0} = 4.5 \quad (6.57)$$

In deriving (6.56) it was assumed that $H/z_0 \gg 1$, although if this assumption were not made, all that would result would be the appearance of additional terms. If use of (6.56) is limited to cases where $H > d$ (see eq. [6.38]) or $H > 10z_0$, whichever is larger, then the singularity (6.57) will pose no problem. This limitation on H will also help avoid the singularity in (6.54) for $H = 0$. The numerator of the right side of (6.56) won't necessarily become small for small H , nor will the numerator of (6.54).

Equations (6.54)–(6.56) provide a diagnostic procedure for evaluating F given u_{*w} , H , z_0 and \bar{u} . If tides are included, they will affect \bar{u} .

It was shown above that a vegetation canopy, especially one that projects above the water surface can significantly dissipate storm surges. This has practical importance because instead of erecting prohibitively expensive sea walls, one can use reed grass whose expense will be orders of magnitude less. A method has been proposed to compute the horizontal currents, which account for most of the damage. A prior knowledge of the possible maximum value of such currents for each surge prone location can help in the design of coastal engineering structures.

6.1.5 Galveston Bay

REID and BODINE (1968) developed a two-dimensional numerical model for computing storm surges in Galveston Bay. They also allowed for rainfall by including it in the continuity equation. The observed and computed surges at different locations for two different hurricanes are compared in Fig. 6.15 and 6.16. BUTLER (1979) also developed a two-dimensional numerical model for storm surge computations in Galveston bay. The time dependence is treated implicitly in this model. Spatially varying and time-dependent wind fields and rainfall are included. Flooding of low-lying areas is simulated by treating the location of land-water boundary as a function of the time-varying local water depth. Subgrid barrier effects are also included. Exposed, submerged, and overtopping barriers can be represented in the mesh system; thus, one can allow for the surge waters breaching narrow barriers such as elevated highway, control structures, etc.

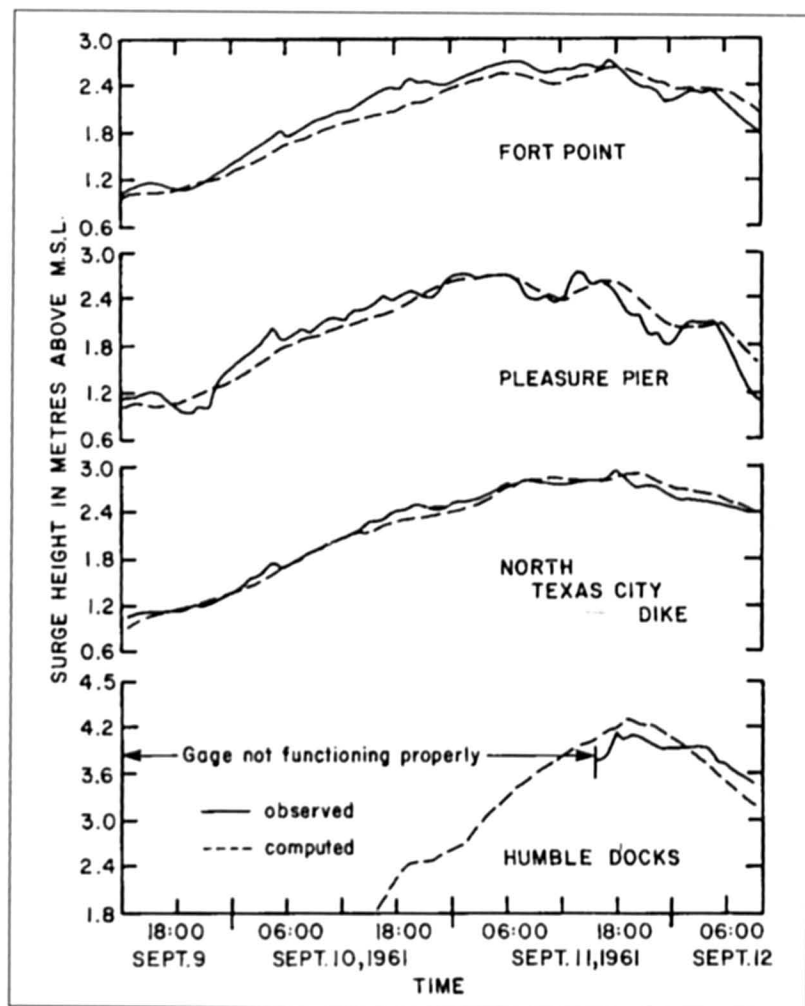


Fig. 6.15: Comparison of observed and computed surges at four locations in Galveston Bay due to Hurricane Carla of September 9-12, 1961 (REID and BODINE, 1968)

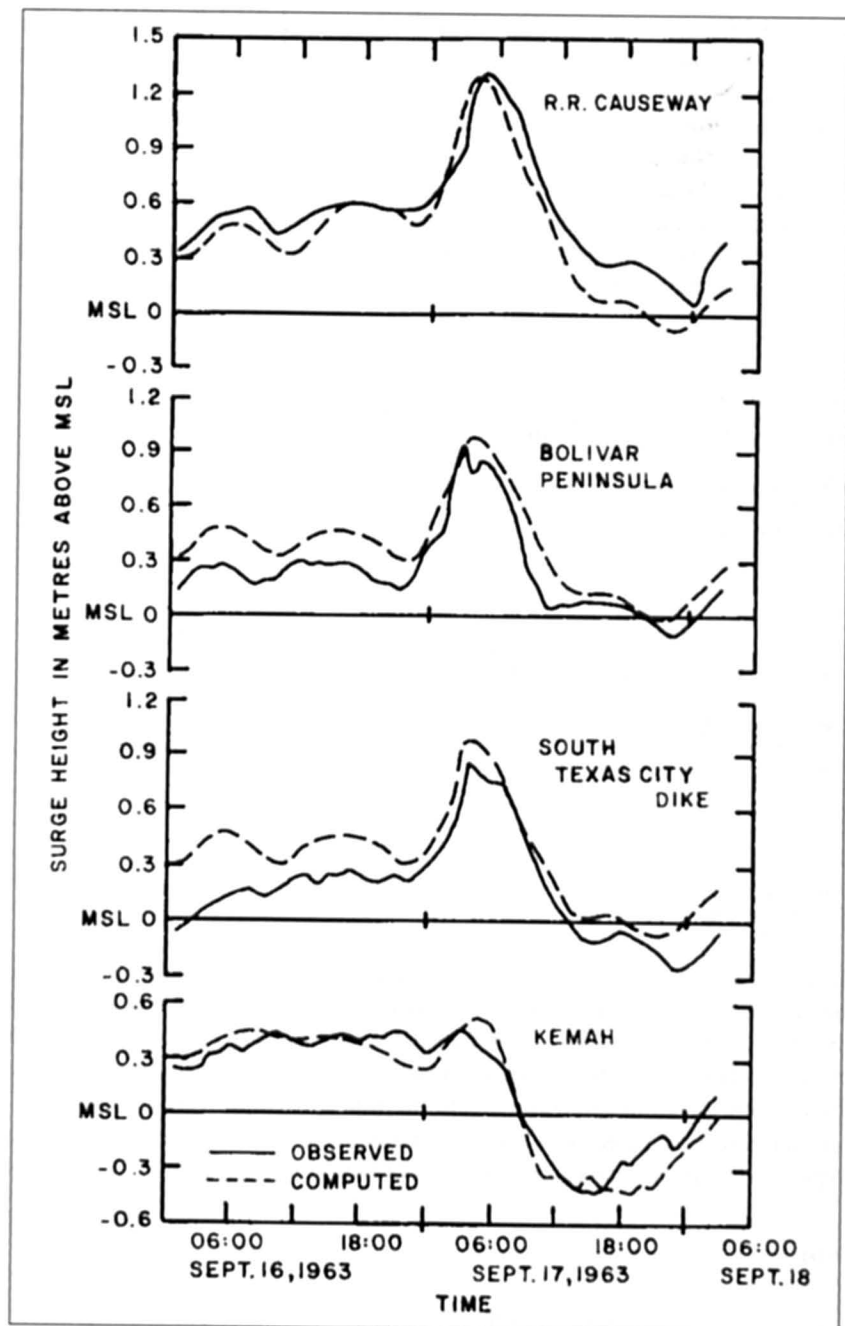


Fig. 6.16: Comparison of computed and observed surges at four locations in Galveston Bay due to Hurricane Cindy of September 16–18, 1963 (REID and BODINE, 1968)

One special feature of this model is the employment of a coordinate transformation in the form of a piecewise exponential stretch. This transformation maps prototype space, discretized with a smoothly varying grid, into computational space with a regularly spaced grid, and in the computational space all the derivatives are centered. Through this transformation one can simulate a complex domain by locally increasing grid resolution and also by aligning coordinates along physical boundaries. A smoothly varying grid with continuous first derivatives eliminates the problem usually associated with variable grids. Indeed, BUTLER (1979) used expansions of grid length in prototype space by a factor of 10. BUTLER (1979) wrote the vertically integrated two-dimensional equations of motion and continuity as follows:

$$\frac{\partial U}{\partial t} + \frac{\partial}{\partial x} \left(\frac{U^2}{d} \right) + \frac{\partial}{\partial y} \left(\frac{UV}{d} \right) - fV + gd \frac{\partial}{\partial x} (\eta - \eta_a) + F_x + \frac{gU}{c^2 d^2} (U^2 + V^2)^{1/2} - dc \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} \right) = 0 \quad (6.58)$$

$$\frac{\partial V}{\partial t} + \frac{\partial}{\partial x} \left(\frac{UV}{d} \right) + \frac{\partial}{\partial y} \left(\frac{V^2}{d} \right) + fU + gd \frac{\partial}{\partial y} (\eta - \eta_a) + F_y + \frac{gV}{c^2 d^2} (U^2 + V^2)^{1/2} - dc \left(\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} \right) = 0 \quad (6.59)$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} = 0 \quad (6.60)$$

Here, h is the still-water elevation, $d = h + \eta$ is the total water depth, c is the Chezy friction coefficient, e is a generalized eddy viscosity coefficient, R is the rate at which additional water is introduced into or taken out of the water body (rainfall, evaporation), F_x and F_y represent external forcing functions such as wind stress, η is the water surface elevation, and η_a is the hydrostatic elevation corresponding to the atmospheric pressure anomaly.

For each direction a piecewise reversible transformation is independently used to map prototype into computational space. The transformation is of the form

$$x = a + b\alpha^c \quad (6.61)$$

where, a , b , and c are arbitrary constants. The equations of motion in the α -space are

$$\frac{\partial U}{\partial t} + \frac{1}{\mu_1} \frac{\partial}{\partial \alpha_1} \left(\frac{U^2}{d} \right) + \frac{1}{\mu_2} \frac{\partial}{\partial \alpha_2} \left(\frac{UV}{d} \right) - fV + \frac{gd}{\mu_1} \frac{\partial}{\partial \alpha_1} (\eta - \eta_a) + F_{\alpha_1} + \frac{gU}{C^2 d^2} (U^2 + V^2)^{1/2} - T_1 = 0 \quad (6.62)$$

$$\frac{\partial V}{\partial t} + \frac{1}{\mu_1} \frac{\partial}{\partial x_1} \left(\frac{UV}{d} \right) + \frac{1}{\mu_2} \left(\frac{V^2}{d} \right) + fU + \frac{gd}{\mu_2} \frac{\partial}{\partial x_2} (\eta - \eta_a) + F_{\alpha_2} + \frac{gV}{C^2 d^2} (U^2 + V^2)^{1/2} - T_2 = 0 \quad (6.63)$$

$$\frac{\partial \eta}{\partial t} + \frac{1}{\mu_1} \frac{\partial U}{\partial x_1} + \frac{1}{\mu_2} \frac{\partial V}{\partial x_2} = R \quad (6.64)$$

where,

$$\mu_1 = \frac{\partial x}{\partial \alpha_1} = b_1 c_1 \alpha_1^{c_1-1} \quad (6.65)$$

$$\mu_2 = \frac{\partial y}{\partial \alpha_2} = b_2 c_2 \alpha_2^{c_2-1} \quad (6.66)$$

Table 6.10: Comparison of computed and observed surges (m) at several locations in Galveston Bay due to Hurricane Carla of 1961 (mean absolute error = 0.18 m). (BUTLER, 1979)

Gauge Location	Observed	Computed	Difference
Oyster Creek	3.11	3.29	+0.18
San Luis Pass	3.29	3.05	-0.24
Sea Isle Beach	3.69	3.05	-0.64
Bermuda Beach	3.20	2.99	-0.21
Scholes Field	2.59	2.93	+0.33
Bolivar Beach	2.83	2.83	+0.00
Crystal Beach	2.68	2.87	+0.18
Rollover Beach	2.93	2.83	-0.09
Halls Bayou	4.36	4.30	-0.06
Highway Six	3.84	3.87	+0.03
Sievers Cove	3.23	2.83	-0.39
Dickinson Bayou	3.47	3.60	+0.12
Carbide Docks	3.35	3.17	-0.18
Kemah	4.33	3.90	-0.43
Smith Point	2.99	3.17	+0.18
Oyster Bayou	3.20	3.35	+0.15
Scott Bay	4.33	4.30	-0.03
Humble Docks	4.18	3.84	-0.34
Ananua	3.78	3.87	+0.09
Wallisville	4.27	4.26	+0.00
Pleasure Pier	2.83	2.87	+0.03
Fort Point	2.74	2.90	+0.15
Pier 21	2.68	2.90	+0.21
Pelican Bridge	2.74	2.87	+0.12
Texas City Dyke (south)	2.90	3.05	+0.15
Texas City Dyke (north)	2.96	3.05	+0.09

The parameters μ_1 and μ_2 define stretching of the regular grid into α -space to approximate the study area of real space. The terms T_1 and T_2 represent the transformed flux terms (which are not included in the application to Galveston Bay).

The above model is applied to storm surge computation in Galveston Bay (which is a large shallow bay of area greater than 1000 km²) due to Hurricane Carla of 1961. The model was calibrated by reproducing the tides. The observed and computed surges at 26 different locations are compared in Table 6.10.

6.1.6 Pamlico Sound and Cape Fear Estuary

Two important water bodies along the coast of North Carolina are Pamlico Sound in the north and Cape Fear Estuary in the south. In Pamlico sound the astronomical tides are small (5-cm range) but storm surges could be significant. ROELOFS and BUMPUS (1953) calculated the surges in this water body using the following simple relation of KEULEGAN (1951):

$$\frac{S}{L} = 3.3 \times 10^{-6} \left[1 + 63 \left(\frac{H}{L} \right)^{1/2} \right] \frac{V^2}{gH} \quad (6.67)$$

where, S is the setup (i.e. $h_2 - h_1$, where h_2 and h_1 are the windward and leeward displacements of water level), L is the length of the water body, V is the wind velocity, and H is the mean depth of the water body. From this formula it was calculated that a southwest wind of about 13 knots (24 km · h⁻¹) is needed to generate a setup of about 1 foot (0.3 m) and a 40-knot (74 km · h⁻¹) wind could produce a surge of 9.8 ft (3 m). This result does not include the funnelling effect due to the geometry of the sound. Northeasterly winds will cause a similar rise along the southwest shore.

MYERS (1975) used a one-dimensional numerical model to calculate the storm surges in Cape Fear Estuary. Some recent dredging operations increased the tidal range at Wilmington, North Carolina. Hence, they used two different depth profiles: the first corresponding to the early 1950's and the second corresponding to the present depths. They generated time histories of the open coast surge from the SPLASH II model for an ensemble of hurricanes, each storm being related to a frequency of occurrence. These time histories are linearly combined with appropriate phases of the astronomical tide at the entrance to Cape Fear River. Three hurricanes were selected: Hazel of 1954, Diane of 1955, and Helene of 1958. The pertinent information for these hurricanes is listed in Table 6.11.

Table 6.11: Meteorological data for Hurricanes Hazel of 1954, Diane of 1955, and Helene of 1958 (MYERS, 1975)

Hurricane	Central pressure depression (mb)	Radius of maximum winds (km)	Speed of movement (km·h ⁻¹)	Maximum wind speed (km·h ⁻¹)
Hazel	66	38.9	53.2	166.7
Diane	30	31.5	22.8	110.4
Helene	65	38.9	24.1	165.9

Table 6.12: Pertinent information about selected hurricanes affecting Chesapeake Bay. (BRETSCHNEIDER, 1959)

Parameter	Hurricane of Aug. 22-24, 1933	Connie of Aug. 11-13, 1955	Diane of Aug. 15-18, 1955	Hazel of Oct. 14-17, 1957
Track	Just west of Chesapeake Bay's west coast	Just west of Chesapeake Bay's east coast	About 160 km west of Chesapeake Bay's west coast	About 160 km west of Chesapeake Bay's west coast
Radius of maximum winds ($\text{km} \cdot \text{h}^{-1}$)	86.9	72.4	72.4	57.9
Central pressure anomaly (mb)	28.8	46.4	24.0	56.2
Speed of movement over ocean ($\text{km} \cdot \text{h}^{-1}$)	46.2	22.2	38.9	101.9
Speed of movement over Chesapeake Bay ($\text{km} \cdot \text{h}^{-1}$)	24.1	18.5	22.2	66.6
Maximum wind speed over ocean ($\text{km} \cdot \text{h}^{-1}$)	98.2	115.9	86.9	148.1
Maximum wind speed over Chesapeake Bay ($\text{km} \cdot \text{h}^{-1}$)	80.5	72.4	56.3	112.7
Peak surge (m) at Hampton Roads, VA	2.01	1.34	0.18	0.55
Peak surge (m) at Gloucester Point, VA	—	1.37	0.70	0.88
Peak surge (m) at Solomon's Island, MD	—	1.28	0.67	0.85
Peak surge (m) at Annapolis, MD	1.77	1.49	0.98	1.28
Peak surge (m) at Baltimore, MD	2.20	1.59	1.13	1.46

6.1.7 Chesapeake Bay

Hurricane-generated storm surges in this water body were studied by BRETSCHNEIDER (1959). Of all the hurricanes that generated surges in Chesapeake Bay up to 1959, only four are sufficiently well documented: August 22-24, 1933, August 11-13, 1955 (Connie), August 15-18, 1955 (Diane), and October 14-17, 1954 (Hazel).

The pertinent information for the meteorological aspects of these hurricanes as well as the storm surges recorded is given in Table 6.12. Some typical surge profiles in Chesapeake Bay are illustrated in Fig. 6.17 and 6.18.

For computing the surges outside Chesapeake Bay on the open coast, two model hurricanes were selected. The first (referred to as A) is the September 14, 1944, hurricane transposed to the Chesapeake Bay area but not adjusted for filling. For this hurricane, the radius R of maximum winds is 33.5 nautical miles (62 km); the atmospheric pressure anomaly at the center is 2.2 in. Hg (74.5 mb), and the maximum sustained wind speed at R is $105 \text{ mi} \cdot \text{h}^{-1}$ ($169 \text{ km} \cdot \text{h}^{-1}$). The path of movement over the open ocean was assumed to be perpendicular to the coast and the speed of travel was $15\text{--}25 \text{ mi} \cdot \text{h}^{-1}$ ($24\text{--}40 \text{ km} \cdot \text{h}^{-1}$). After crossing the coast, the path of movement curves and proceeds northward along the west side of Chesapeake Bay, and the speed of movement reduces to $12\text{--}15 \text{ mi} \cdot \text{h}^{-1}$ ($19\text{--}24 \text{ km} \cdot \text{h}^{-1}$). The second storm (referred to as B) is exactly the same as A, except that all wind speeds are $5 \text{ mi} \cdot \text{h}^{-1}$ ($8 \text{ km} \cdot \text{h}^{-1}$) larger. The results for the surges due to hurricanes A and B are summarized in Table 6.13. The prediction curves for hurricane surges at Washington, DC, are given in Fig. 6.19.

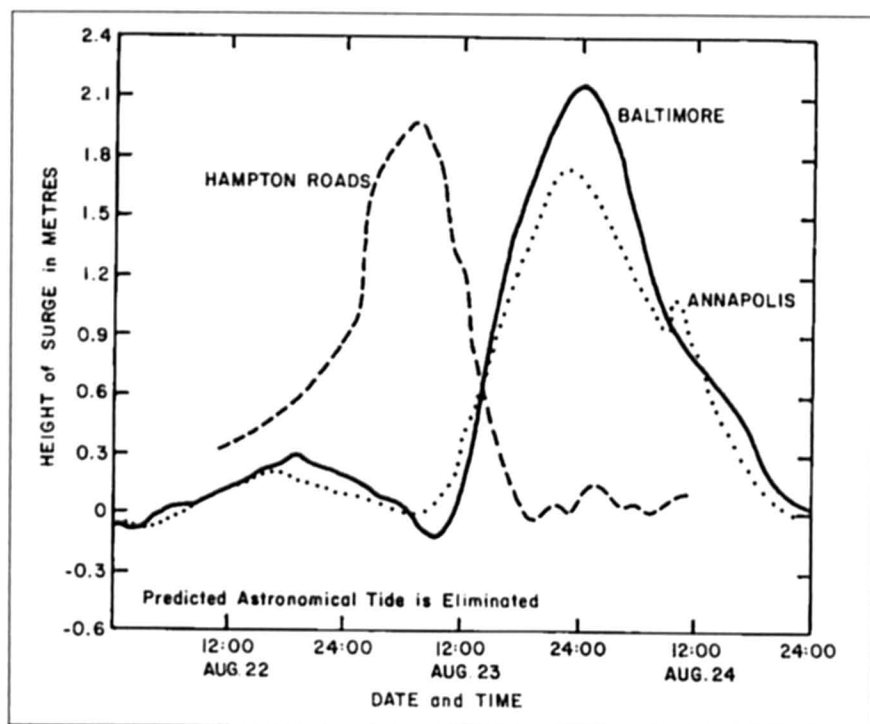


Fig. 6.17: Storm surges at three locations in Chesapeake Bay due to the hurricane of August 22-24, 1933 (BRETSCHNEIDER, 1959)

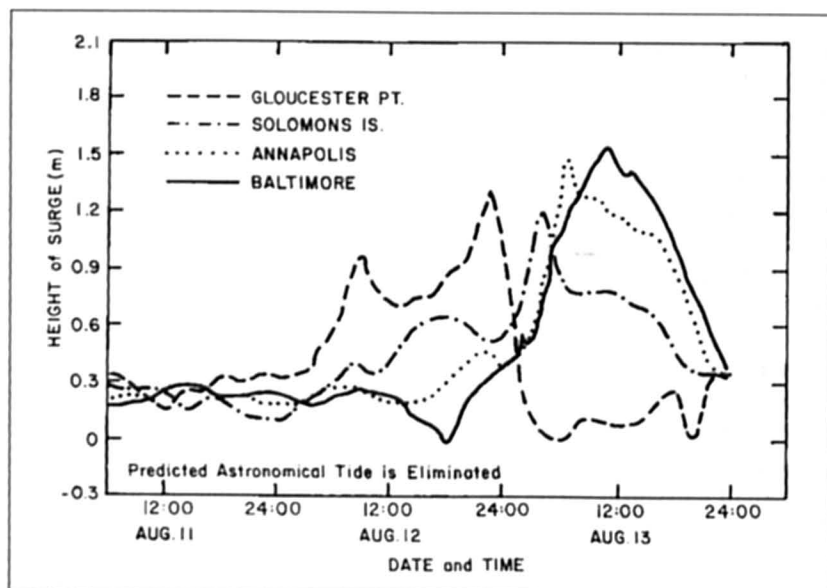


Fig. 6.18: Storm surges at four locations in Chesapeake Bay due to Hurricane Connie of August 11-13, 1955 (BRETSCHNEIDER, 1959)

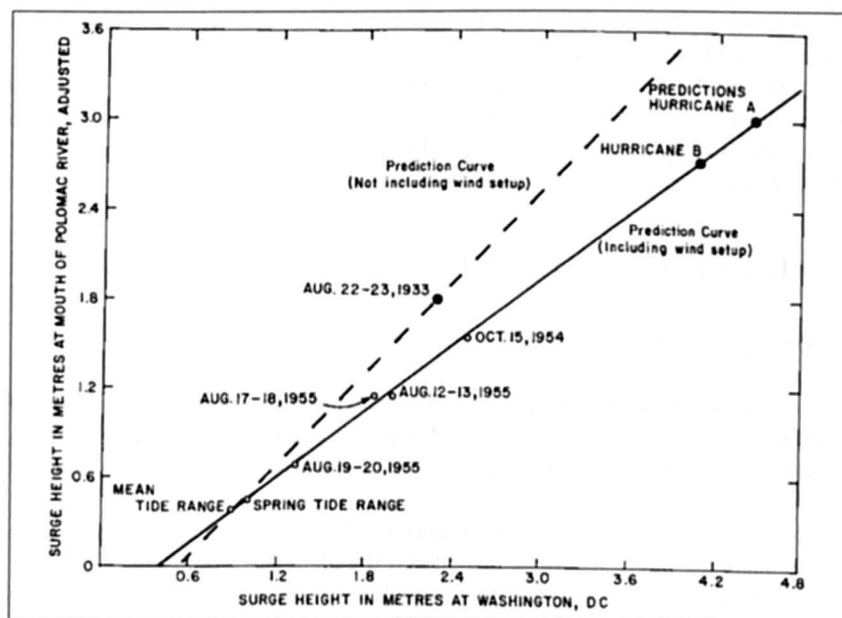


Fig. 6.19: Storm surges prediction curves for hurricane generated storm surges at Washington D.C. (BRETSCHNEIDER, 1959)

BODINE (1971) used the bathystrophic theory to compute storm surges on an open coast and applied this to the Chesapeake Bay area. In this connection, he pointed to the important effect of interaction between tide and surge, especially when it is recognized that the tidal range can vary from 18.2 ft (5.5 m) at East Port, Maine, to 1.3 ft (0.4 m) at Key West, Florida, and that, generally, the tides along the Atlantic coast of the United States are semi-diurnal whereas along the Gulf of Mexico coast they are mainly diurnal.

Table 6.13: Computed storm surges in Chesapeake Bay due to hurricanes A and B. These values have an uncertainty of 0.12 m (BRETSCHNEIDER, 1959)

Location	Maximum surge (m) due to	
	Hurricane A	Hurricane B
Hampton Roads, VA	3.29	3.57
Mouth of York River	3.14	3.44
Mouth of Rappahannock River	2.99	3.26
Mouth of Potomac River	2.77	3.05
Mouth of Severn River	2.53	2.77
Mouth of Patapaco River	2.87	3.11

To give the most probable degree of protection required for any given area, the standard practice is to select a hurricane with a given set of characteristics for the particular geographical location. This will be called a "hypothetical" or "hypohurricane". Also, for such a hurricane the characteristics are taken as invariant and the track is assumed to follow a prescribed path. The U.S. Weather Bureau and the U.S. Army Corps of Engineers jointly established two design storms (which depend on the geographical location) for practical use for

coastal engineering purposes. These are the Standard Project Hurricane (SPH) and the Probable Maximum Hurricane (PMH).

GRAHAM and NUNN (1959) defined the SPH as a hypohurricane that is intended to represent the most severe combination of hurricane parameters that is reasonably characteristic of a region, excluding extremely rare combinations. The maximum gradient wind speed in the belt of maximum winds (miles per hour) was determined by the following formulae:

$$V_{gx} = K(p_n - p_0)^{1/2} - R(0.575f) \quad (6.68)$$

$$V_x = 0.865V_{gx} + 0.5V_F \quad (6.69)$$

where $K = 73$, p_n and p_0 are the peripheral and central pressures in inches of mercury, R is the radius of maximum winds in nautical miles, f is the Coriolis parameter in units per hour, V_F is the speed of movement of the hurricane in miles per hour, and V_x is the maximum wind speed 30 ft (9.1 m) above the water.

For protection of the nuclear power plants, the U. S. Atomic Energy Commission concluded that adequate safety would be provided if the plant site would not be flooded by the surge and surface waves associated with a probable maximum hurricane (PMH). The U. S. Weather Bureau developed the characteristics of the PMH, which is much more severe than the SPH. The PMH was defined as a hypothetical hurricane having that combination of characteristics that will make it the most severe storm that can probably occur in the particular region involved. The hurricane should approach the point under study along a critical path and at an optimum rate of movement. Development of the isovel fields is basically the same for the PMH as for the SPH. The difference essentially is that whereas p_n is taken as the standard sea level pressure of 29.92 in. Hg. (1013.2 mb) for the SPH, it is treated as a function of the latitude for the PMH. Also, K is treated as a function of latitude for the PMH whereas it is a constant for SPH. At times it may be desirable to select a design storm other than the SPH or PMH based on the risk or economy factors for a particular location or coastal structure. Using bathystrophic theory, BRETSCHNEIDER (1959) estimated the peak surge (for a selected storm) at the mouth of Chesapeake Bay to be 13.4-ft (4.1 m).

PORE (1965) studied hurricane-generated storm surges in Chesapeake Bay. He made a distinction between western-type (i.e. hurricanes passing west of the bay) and eastern-type (hurricane travelling east of the bay) storms. His study showed that the western-type storms create greater surges in the northern part of the bay whereas the eastern-type storms generate greater surges in the southern portion of the bay. The storm surges resulting from these two types of hurricanes are listed in Tables 6.14 and 6.15.

Table 6.14: Storm surges data for western type storms in the Chesapeake Bay region (PORE, 1965)

Date	Baltimore	Annapolis	Cambridge	Surge amplitudes (m) at Solomon's point	Gloucester point	Hampton Roads	Time lag (h) from Norfolk to Baltimore	Storm movement (km) northward in 12 h
Oct. 2, 1929	1.19	1.10	-	-	-	0.73	18	352
Aug. 23, 1933	2.13	1.68	-	-	-	1.86	18	315
June 19, 1934	-	-	-	-	-	0.24	-	148
Sept. 18, 1945	0.82	0.73	0.70	0.64	-	0.73	17	389
Aug. 29, 1949	0.52	0.43	0.46	0.24	-	-0.06	-	519
Sept. 1, 1952	1.04	0.88	-	0.49	0.15	0.12	13	241
Oct. 15, 1954	1.40	1.19	-	0.85	0.34	0.46	14	945
Aug. 18, 1955	1.88	0.73	-	0.52	0.52	0.30	21	241

Table 6.15: Storm surge amplitudes (m) for eastern type storms in the Chesapeake Bay region. For certain cases, maximum positive and negative surges are listed (PORE, 1965)

Date	Baltimore	Annapolis	Cambridge	Solomon's point	Gloucester point	Hampton Roads	Portsmouth
Sept. 16, 1933	0.27	0.30	-	-	-	1.55	-
Sept. 8, 1934	-	-	-	-	-	0.24	-
Sept. 18, 1936	-1.74, 0.40	-1.28, 0.37	-	-	-	1.49	-
Sept. 21, 1938	-0.98, 0.06	-0.67, 0.03	-	-0.43	-	-	0.55
Oct. 24, 1938	0.21	0.21	-	1.8	-	-	0.21
Sept. 1, 1940	0.06	0.06	-	0.06	-	-	0.09
Sept. 14, 1944	-0.64, 0.27	-0.49, 0.21	-0.27, 0.24	-0.18, 0.18	-	1.13	-
June 26, 1945	-0.34, 0.18	-0.24, 0.24	-0.18, 0.27	0.15	-	0.79	-
Aug. 20, 1950	0.21	0.21	0.15	0.18	-	0.24	-
Aug. 14, 1953	-0.79, 0.40	-0.73, 0.34	-	-0.46, 0.34	0.94	1.13	-
Aug. 31, 1954	-0.18, 0.21	0.24	-	0.24	0.49	0.79	-
Sept. 11, 1954	-0.43, 0.15	-0.30, 0.12	-	-0.12, 0.15	0.67	0.88	-
Sept. 27, 1956	0.34	0.58	-	0.64	-	1.13	-
Aug. 28, 1958	-0.37, 0.18	-	-	0.18	-	0.34	-

6.1.8 Coast of New Jersey

The greatest loss of life and property, damage on the coast of New England occurred during September 21–22, 1938, as a result of storm surge generated by a West Indian hurricane coupled with river flooding (due to excessive rainfall). The storm surge amplitude was maximum in Rhode Island with values exceeding 17-ft. (5.2) m, and the amplitudes reached record levels all along the coast between New York City and Cape Cod. More than 500 people died (PAULSEN et al., 1940) and the property damage exceeded \$ 0.3 billion (at 1938 prices).

The storm surge amplitudes at Sandy Hook on the coast of New Jersey and at three other locations are listed as a function of time in Table 6.16. The surge profiles at Forest Hills and Rockway Park, both in New York State, are shown in Fig. 1.2 and 1.3.

Table 6.16: Storm surge amplitudes (m) as a function of time on the Massachusetts-New York-New Jersey coast during Sept. 21–22, 1938. Time is local time. (PAULSEN et al., 1940)

Hour	Sandy Hook, NJ		The Battery, NY		Boston, MA		Mill Neck, NY
	Sept. 21	Sept. 22	Sept. 21	Sept. 22	Sept. 21	Sept. 22	Sept. 21
01	0.40	-0.49	0.27	-0.21	0.30	0.85	-
02	0.85	-0.37	0.73	-0.18	-0.18	-0.03	-
03	1.19	-0.03	1.13	-0.12	-0.03	-0.49	-
04	1.55	0.58	1.46	0.64	0.49	-0.12	-
05	1.71	1.52	1.59	1.34	1.16	0.24	-
06	1.62	1.74	1.62	1.71	1.92	0.91	-
07	1.34	1.59	1.46	1.71	2.65	1.89	-
08	1.04	1.16	1.22	1.43	3.14	2.80	-
09	0.76	0.76	0.88	1.10	3.20	3.23	-
10	0.49	0.34	0.61	0.61	2.80	2.23	-
11	0.30	0.09	0.37	0.34	2.19	2.80	-
12	0.30	0	0.15	0.09	1.55	2.16	-
13	0.55	-0.03	0.18	0	0.79	1.34	-
14	1.07	0.12	0.55	0	0.21	0.43	-
15	1.80	0.55	1.34	0.30	0.18	-0.24	-
16	2.38	1.01	2.47	0.91	0.91	-0.37	-
17	1.55	1.46	2.04	1.37	1.62	0.15	-
18	0.91	1.74	1.16	1.65	2.13	0.82	-
19	0.24	1.77	1.01	1.74	2.68	1.71	3.54
20	0.09	1.43	0.73	1.65	3.23	2.53	4.60
21	0.76	0.98	0.70	1.34	3.35	3.17	4.02
22	0.79	0.58	1.22	0.91	3.05	3.35	3.78
23	0.24	0.24	0.49	0.52	2.50	3.05	3.69
24	-0.37	0	-0.03	0.21	1.86	2.44	3.66

PAGENKOPF and PEARCE (1975) developed several storm models and applied these to the New Jersey coast. In particular, these authors compared two-dimensional finite-difference and finite-element methods and concluded that, at least for storm surge calculations, there is no particular advantage to preferring one to the other. They also compared their results with bathystrophic storm surge calculations. All these calculations were made for the hurricane of

September 14, 1974. The results from bathystrophic calculations are not satisfactory in certain circumstances. The horizontal distributions of storm surge heights computed by the finite-difference and finite-element models are compared in Fig. 6.20.

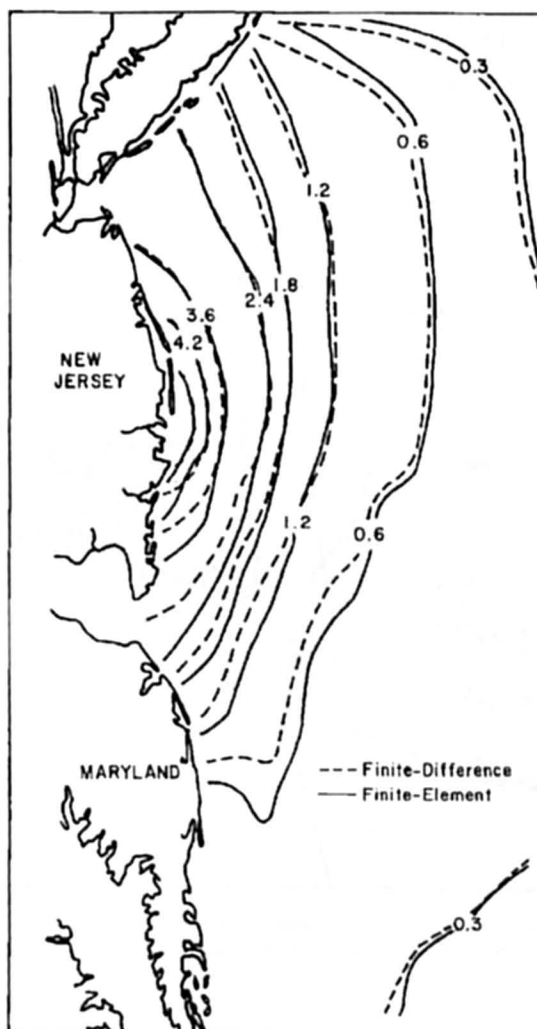


Fig. 6.20: Calculated storm surge heights (meters) along the coast of New Jersey (PAGENKOPF and PEARCE, 1975)

6.1.9 Storm Surges in the New York Bight

PORE and BARRIENTOS (1976) studied storm surges in the New York Bight due to hurricanes and extra-tropical cyclones. This subsection will be confined to only hurricane-generated storm surges (extratropical cyclone generated surges will be discussed later). PORE and BARRIENTOS (1976) selected five major hurricanes that affected the New York Bight area: September 21–22, 1938, September 13–15, 1955, August 30–31, 1954 (Carol), September 10–12, 1954 (Edna), and September 12, 1960 (Donna). The storm surge height distributions for the third and fifth hurricanes are given in Fig 6.21 and 6.22, respectively.

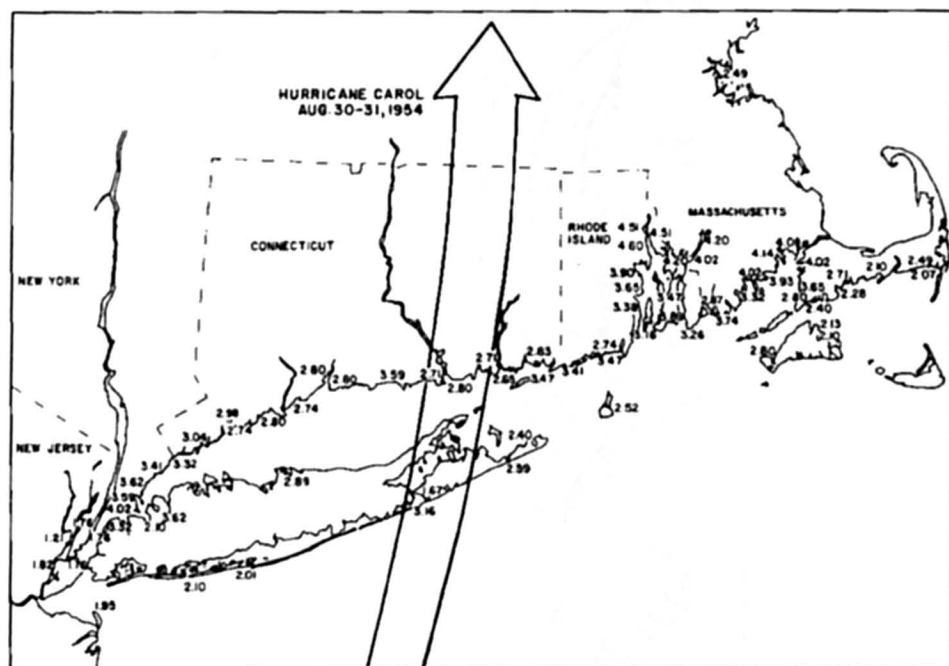


Fig. 6.21: Distribution of storm surge heights (meters) in the New York Bight due to Hurricane Carol of August 30–31, 1954. The arrow shows the hurricane track (PORE and BARRIENTOS, 1976)

SETHURAMAN (1979) studied the storm surge due to Hurricane Belle of August 8–10, 1976. The surge at Shinnecock Inlet (Long Island) is shown in Fig. 6.23. This surge occurred near the time of low tide; hence damage was minimal.

6.1.10 Storm Surges in New York Bay

KUSSMAN (1957) examined the storm surge problem for New York City and surrounding area. The storm amplitudes at several locations due to nine hurricanes are listed in Table 6.17.

The arrow shows the hurricane track. (PORE and BARRIENTOS, 1976)

WILSON (1959, 1961) did a comprehensive study of the hurricane generated storm surge problem in New York Bay. The technique of this study was as follows (WILSON, 1961, p. 548):

A recursion formula is evolved, using the method of finite differences for time increments of $\frac{1}{3}$ hour, which relates tide elevation at the bay-mouth with two values of the elevation at $\frac{1}{3}$ and $\frac{2}{3}$ hour earlier and with values of wind-stress and pressure-gradient driving force components (directed towards New York Bay from several remote two dimensionally spaced off-shore-stations on the continental shelf) at times earlier by the periods taken for free long gravity waves to travel from the stations to the bay-mouth. The formula includes a cumulative forcing function term, which allows for the geostrophic influence of the earth's rotation and also for an "edge wave" effect northward along the eastern seaboard. Moreover it takes into account the observed tendencies of hurricane storm tides in New York Bay to develop resurgences at periods of 7 hours with decay rates of 50 % amplitude decrease per cycle. The coefficients of the "forcing functions", determined by correlation, tend to represent the storm size and speed and also the dynamic augmentation of the forced wave.

The predicted surge curves at selected locations for a design storm moving with a speed of 35 knots ($65 \text{ km} \cdot \text{h}^{-1}$) are shown in Fig. 6.24. The maximum storm surge amplitude and resurgence amplitude at several locations, due to a designed hurricane, are given in Table 6.18.

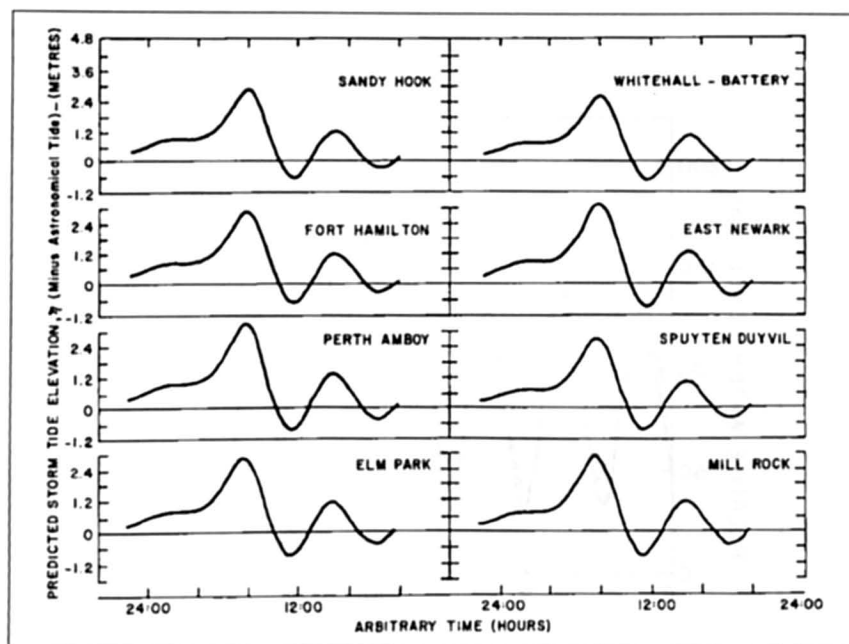


Fig. 6.24: Predicted storm surge heights at various locations in New York Bay for a design hurricane moving with a speed of $65 \text{ km} \cdot \text{h}^{-1}$. (WILSON, 1959)

Table 6.17: Maximum storm surge amplitudes (m) in the New York City area and vicinity due to hurricanes during the period 1938–55 (KUSSMAN, 1957)

Location	Sept. 21, 1938	Sept. 15, 1944	Nov. 25, 1950	Nov. 7, 1953	Aug. 31, 1954	Sept. 11, 1954	Oct. 15, 1954	Aug 12–13 1955	Oct. 14–16 1955
Fort Hamilton, NY	1.95	2.04	2.29	2.35	1.80	1.31	–	1.37	1.95
Perth Amboy, NJ	2.01	2.26	2.90	2.68	1.77	1.46	1.68	1.62	2.35
Spuyten Duyvil, NY	1.62	1.83	2.13	2.04	1.59	1.22	1.28	1.34	1.80
Lawrence Point, NY	–	–	3.05	3.17	3.32	1.89	1.80	1.59	2.26
The Battery, NY	1.95	1.95	2.26	2.32	1.71	1.16	1.37	1.28	1.80
Sandy Hook, NJ	1.80	2.56	–	2.41	1.86	1.34	1.40	1.25	1.89
Willeys Point, NY	3.66	–	–	2.65	3.47	1.95	1.86	1.62	2.38
Montauk (Fort Pond Bay), NY	4.82	2.41	–	1.65	2.41	1.10	0.94	0.64	1.19
New London, CT	2.99	1.86	2.19	1.80	2.65	0.91	1.22	0.76	1.28

Table 6.18: Predicted maximum storm surge heights due to hurricanes in New York Bay (WILSON, 1959)

Station	Maximum storm surge height (m)		Maximum first resurgence height (m)	
	Surge	Probable error (90 %) confidence limits	Resurgence	Probable error (90 %) confidence limits
Sandy Hook	2.71	± 0.21	1.04	± 0.21
Fort Hamilton	2.68	± 0.21	1.04	± 0.21
Perth Amboy	3.20	± 0.30	1.25	± 0.30
Elm Park	2.87	± 0.46	1.16	± 0.46
Whitehall (Battery)	2.53	± 0.18	1.01	± 0.18
		– 0.24		– 0.24
East Newark	3.11	± 0.49	1.25	± 0.49
Spuyten Duyvil	2.65	± 0.30	1.04	± 0.30
Mill Rock	2.99	± 1.37 ^a	1.19	± 1.37 ^a
		– 0.91 ^a		– 0.91 ^a

^a The 90 % confidence limits are probably better than these for the main surge.

6.1.11 Narragansett Bay

McALEER (1964) studied hurricane-generated storm surges in Narragansett Bay and particularly examined the role of barriers in reducing storm surge levels. The results were arrived at through hydraulic model investigations. Storm surges of up to 10–14 ft (3.0–4.3 m) in amplitude have been observed in Narragansett Bay. A hurricane storm surge in September of 1938 caused \$ 100 million damage and killed 110 people. Ten people were killed in another storm surge during 1954. For some of the major hurricane tracks, Narragansett Bay lies in the dangerous northeast quadrant of the storm.

While some of the major hurricanes move relatively slowly along the southern part of the east coast of the United States, they may move faster when they approach the northern part of the coast. Hence, some storms that were reported as having stalled (or as moving

slowly) along the southern east coast suddenly accelerated and caused surges in Narragansett Bay some 8–10 h later.

Numerical and hydraulic models have been used to study the effects of barriers on storm surge amplitudes. The barriers are envisaged as rock fill barriers with large ungated navigation openings across the three entrances to Narragansett Bay. The results indicated that the barriers would reduce the surge amplitudes by 6–7 ft (1.83–2.13 m) over the 120-mi² (311 km²) bay. These barriers will also decrease the mean tidal range somewhat.

PARARAS-CARAYANNIS (1975) used the bathystrophic model to compute the surges at Narragansett Pier, Rhode Island, generated by Hurricane Carol of 1954. This hurricane had a radius of maximum winds of 25 nautical miles (46.3 km) and moved with an average speed of over 33 knots (61 km·h⁻¹). Hurricane Carol arrived over Rhode Island at about 10:30 EST on August 31, 1954, with sustained wind speeds up to 90 mi·h⁻¹ (145 km·h⁻¹) and gusts up to 105 mi·h⁻¹ (169 km·h⁻¹). At Block Island, gusts up to 130 mi·h⁻¹ (209 km·h⁻¹) were measured.

Because of its intensity, speed of movement, and arrival at the time of high tide, exceptionally large surges and great destruction occurred. About a third of the city of Providence was under 8–10 ft (2.4–3.0 m) of water for several hours. PARARAS-CARAYANNIS (1975) mentioned waves up to 40-ft (12.2 m) in height. Maximum surge at Narragansett Pier was about 12.8-ft (3.9 m). Observed and computed surge profiles at Narragansett Pier are compared in Fig. 6.25.

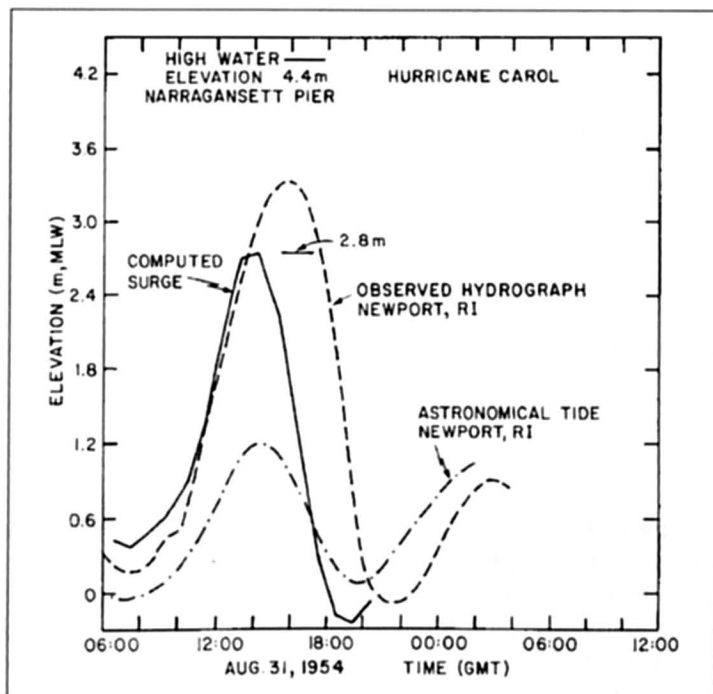


Fig. 6.25: Computed and observed surges at Narragansett Pier due to Hurricane Carol of 1954 (PARARAS-CARAYANNIS, 1975)

6.1.12 Hawaii

The Hawaiian Islands are not frequently subjected to storm surges. However, in November 1982 the storm surge caused by Hurricane Eva resulted in extensive damage to the islands of Kauai and Oahu and a few people died. Another major surge occurred in February 1983. Prior to these two surges, major surges occurred in the mid-1950s and some minor ones occurred in the 1970's.

Even though hurricanes are common over the eastern pacific and annually are seen in parts of central pacific, they are not found over Hawaii only. Four hurricanes impacted Hawaii during 1950 to 1992. Hurricane Iniki of September 6–13, 1992 with winds up to 160 mph (258 kph) was by far the strongest and most destructive. Fig. 6.26 shows the track of Hurricane Iniki and Fig. 6.27 shows that the passage of the eye over Kauai. Fig. 6.28 shows the wind field.

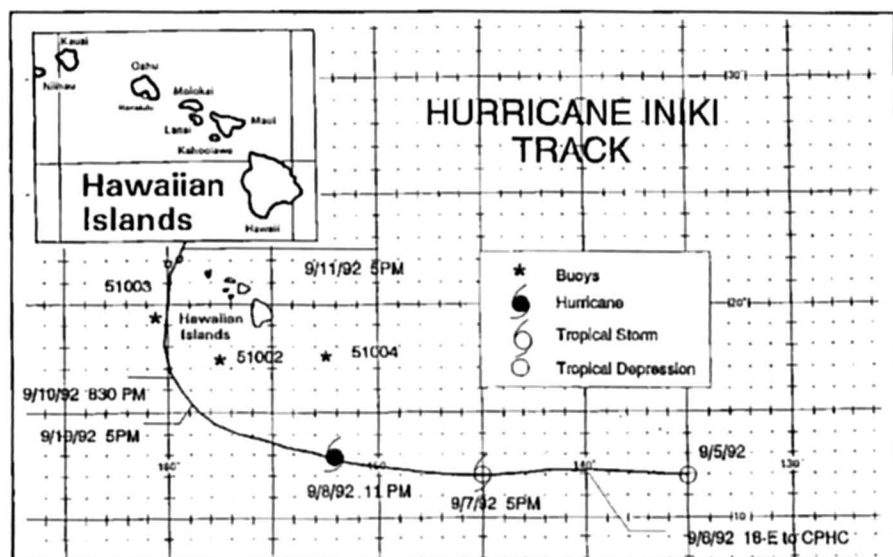


Fig. 6.26: Track of hurricane Iniki (ANON, 1993)

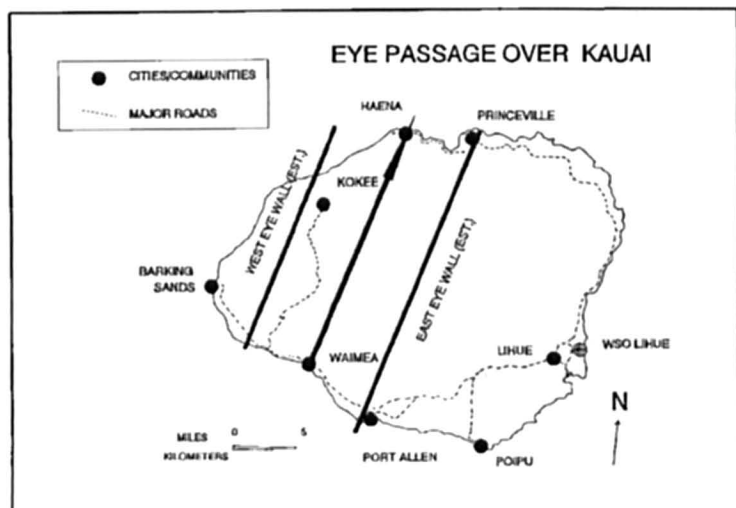


Fig. 6.27: Estimated Iniki Eye Passage over Kauai (ANON, 1993)

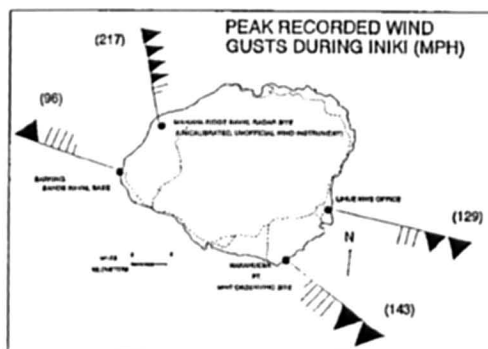
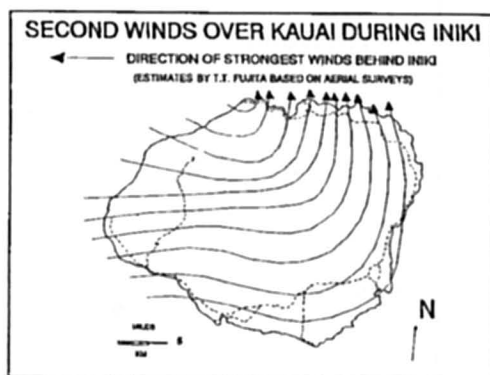
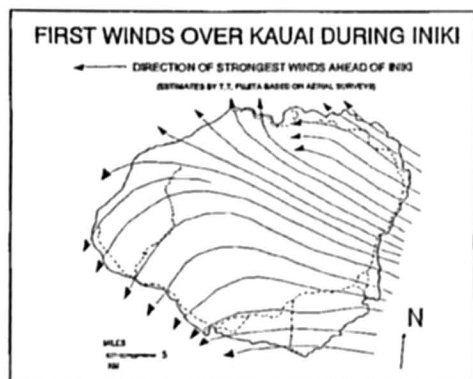


Fig. 6.28: Winds on Kauai from Iniki (ANON, 1993)

6.1.13 Mexico

Mexico is affected by storm surges on its Gulf of Mexico coast. Usually, the hurricane tracks over the Gulf of Mexico are such that they strike the United States rather than Mexico. However, on rare occasions, storm surges do occur on the Mexican coast also. On the Pacific coast of Mexico, also, storm surges occur rather infrequently. The storm surge due to Hurricane Paul of September 30, 1982 killed 24 people and caused considerable damage on the Baja California coast. In this hurricane, winds up to $240 \text{ km} \cdot \text{h}^{-1}$ were reported.

6.2 Central and South America Including the Caribbean

6.2.1 Caribbean Sea Region

Hurricanes and storm surges cause significant death and damage in the nations of the Caribbean Sea region. Of the four nations Haiti, Cuba, The Dominican Republic, and Honduras, maximum effects occurred in Haiti (FUNK, 1980) where about 8400 people were killed in the twentieth century. In 1963 alone, Hurricane Flora caused 5000 deaths. Hurricane David of August 29, 1979, killed 56 people in Dominica.

Hurricanes originating in the Caribbean Sea south of 15°N , especially in the month of August, are a potential threat to Jamaica (BLAKE, 1981). Winds of up to $45 \text{ m} \cdot \text{s}^{-1}$ generated storm surges with amplitudes up to 12 m at Manchioneal and Galina. Most of the northern coast of Jamaica was struck by surges of amplitudes between 4 and 8 m. There is evidence that the surge penetrated several kilometres inland. The damage was estimated to be about \$126 million. About 75 % of the banana crop, 95 % of the fishing industry equipment on the north coast, and more than 800 houses were destroyed.

The storm surge of June 12, 1979, made people aware of what to expect and this helped in the safe evacuation of people during the 1980 surge.

6.2.2 Barbados

Barbados and other island of the Lesser Antilles are not usually subjected to storm surges, but they do have severe problems from swell and wind waves. There is a broad reef shelf surrounding Barbados and this makes the problem worse. The swell action is not associated with local storms from the Caribbean Sea but is due to intense extratropical cyclones in the North Atlantic Ocean (DONN and MCGUINNESS, 1959).

Swell with amplitudes up to 20 ft (6.1 m) can occur quite frequently. Between December 1957 and October 1958, at least four occasions of major swell activity occurred.

READING (1990) analysed the annual and decadal frequency of cyclones throughout the Caribbean region. For the "Historical Period" (i.e. period before weather charts were made) the Caribbean has been divided into ten sub-regions as shown in Fig. 6.29 for the modern period (i.e. charted period) a 5° latitude-longitude grid were used as shown in Fig. 6.30. Fig. 6.31 show the mean decadal frequency. Here cyclones are defined as warm cored systems of storm force or above while hurricanes are similar systems of hurricane intensity as defined by the U.S. Weather Bureau.

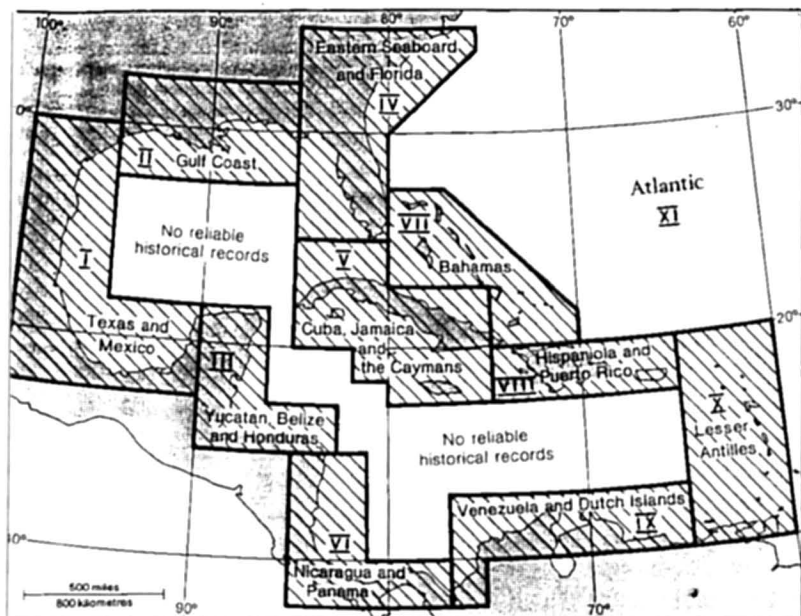


Fig. 6.29: Subregions of the Caribbean: historical data analysis (READING, 1990)

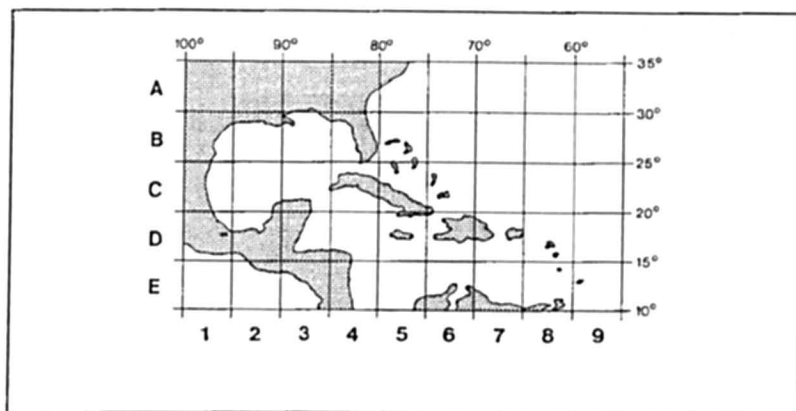


Fig. 6.30: Grid map of Caribbean area: modern data analysis (READING, 1990)

Fig. 6.31 shows that cyclone frequencies are greatest around the Western Bahamas, Eastern Seaboard of U.S and adjacent Atlantic. This can be explained by the fact that this area is within the favoured path of the two types of cyclones that affect this region; the Capeverde (CV) type systems, which recurve around the periphery of the sub-tropical high pressure cell to the north and the western Caribbean (WC) type which, after developing in the warm waters of the western Caribbean, almost immediately become affected by the westerly mid-latitude circulation and move steeply towards higher latitudes. Cyclone frequencies decrease from this northeastern core-region in roughly concentric circles. Areas of anomalously high frequencies between 15° N and 20° N east of 70° W reflect the strong preference of CV

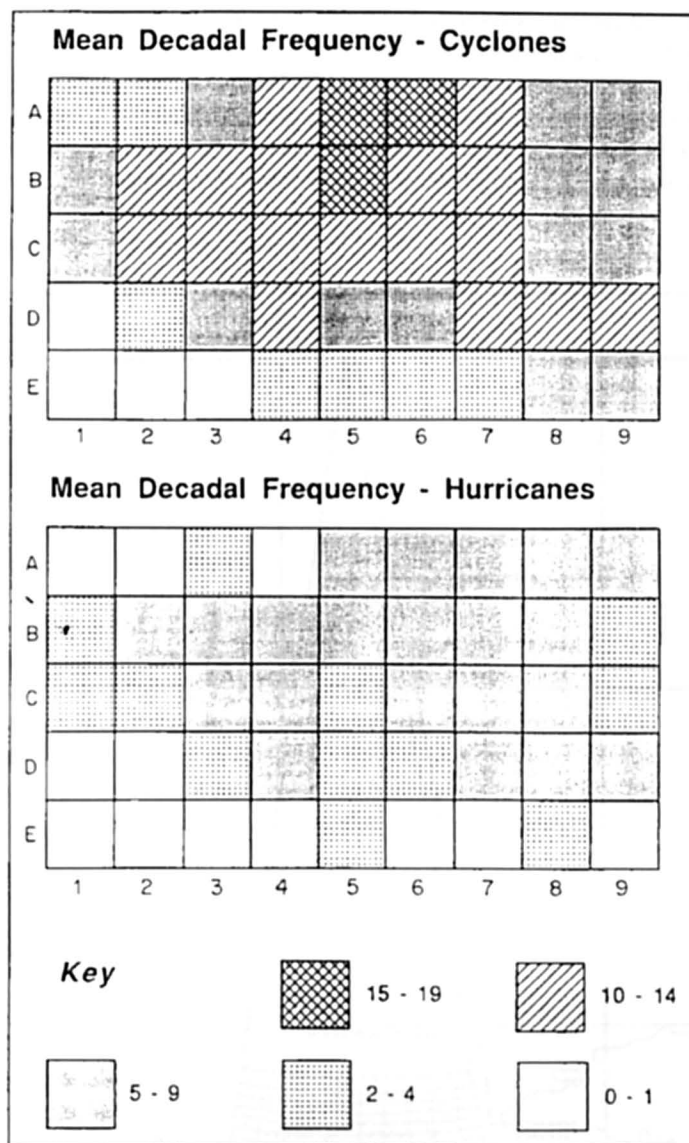


Fig. 6.31: Mean decadal frequency of cyclones and hurricanes: per 5° grid square (READING, 1990)

systems to enter the Caribbean at this latitude. Square D4 represents the major area of intensification for WC type systems.

Areas of relatively high hurricane frequencies (5–9 per decade) occur as two distinct bands. The western band represents the favoured track of WC type systems and the eastern band that of recurring CV type systems. These bands join over the north-central Caribbean, representing an area where both types of system frequently pass.

There is a strong latitudinal and longitudinal preference by the cyclones that develop, possibly a reflection of changes in the relative positions and intensity of the subtropical high pressure cell and the inter-tropical convergence zone. Another important result is that the

proportion of cyclones intensifying to hurricane status within the Caribbean has risen from 45 % in the 1970's to about 63 % in the 1990's.

MERCADO (1994) modelled storm surges in Puerto Rico using the SLOSH model. Fig. 6.32 shows the grid for the SLOSH basin. The grid on which the surge computations and inundation are made has a resolution of approximately 2 x 2 miles (3.2 x 3.2 km). The model was tested against hurricane Hugo storm surge with amplitudes up to 3.5 m.

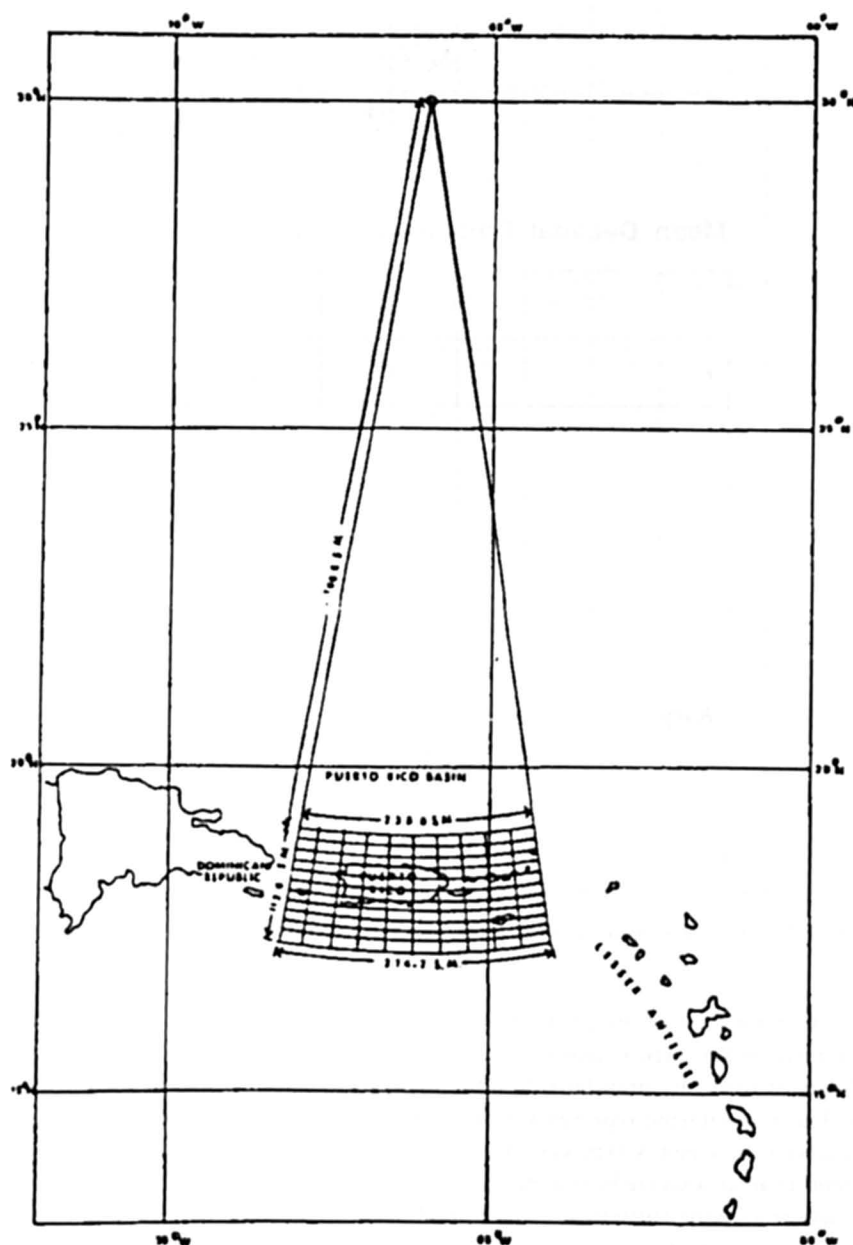


Fig. 6.32: Puerto Rico SLOSH Basin and grid system used (MERCADO, 1994)

6.3 North Indian Ocean

Discussion in this section will mainly concentrate on the storm surges in the Bay of Bengal and Arabian Sea. Although the frequency of the tropical cyclones in the North Indian Ocean is not quite high, the coastal regions of India, Bangladesh and Myanmar suffer most in terms of loss of life and property caused by the surges. The reason besides the inadequate accurate prediction, are the low lands all along the coasts and considerably low-lying huge deltas, such as, Gangetic delta and Ayeyarwady delta.

6.3.1 Bay of Bengal

Storm surges are extremely serious hazards along the east coast of India, Bangladesh, Myanmar and Sri Lanka. Although Sri Lanka is affected only occasionally by the storm surge, however tropical cyclones of November 1964, November 1978 and the recent cyclone of November 1992 have caused extensive loss of life and property in the region. Storm surges affecting Myanmar are also to much less extent in comparison with Bangladesh and India. Notable storm surges, which have affected Myanmar, have been during May 1967, May 1968, May 1970 and May 1975, of which May 1975 was the worst cyclone. The storm surge due to the May 1975 event penetrated at least 100 km into the Ayeyarwady river system and caused serious inland flooding (LWIN, 1980)

A detailed review of the problem of storm surges in the Bay of Bengal is given by RAO (1982), ROY (1984), MURTY (1984), MURTY et al. (1986), DAS (1994 a, b), DUBE (1998a), DUBE et al. (1997, 1999b, 2000c) and CHITTIBABU (1999). In this section, a brief account of the problem of storm surges in Bangladesh, east coast of India, Myanmar and Sri Lanka would be given. Of all the countries surrounding the Bay of Bengal, Bangladesh suffers most from storm surges.

(a) Bangladesh

It is probably not incorrect to say that Bangladesh suffered more from storm surges than any other country. ALI (1979) summarized the main factors contributing to the disastrous storm surges on the coast of Bangladesh: (1) shallow water, (2) convergence of the bay, (3) high astronomical tide, (4) thickly populated low-lying islands, (5) favorable cyclone track, and (6) innumerable number of inlets and few large estuaries and rivers. Except in the eastern and southeastern parts of the country (where there are hills) most of the land is flat. Many places, although 160 km from the sea are not more than 9.1 m above sea level. A rise of a few meters in sea level can bring large areas of land under water (GILL, 1975).

Another peculiar problem is the topographical changes that appear to occur in decadal periods in the courses of the rivers and tributaries. The storm surge problem became worse after the Assam earthquake of August 1950 because millions of tons of material from the mountains was dislodged by the earthquake, which ultimately found its way into the river system and caused raising of the bottom by as much as 4.3 m in certain locations.

The approximate number of people killed in Bangladesh because of storm surges is listed in Table 6.19. For comparison, a storm surge in 1881 in China supposedly killed 300,000 people. A surge in Japan in 1923 killed 250 000 people. Another surge in Japan in 1960 killed

Table 6.19: Number of people killed in Bangladesh due to storm surges. Only those cases in which the number is more than 5000 are included

Year	Estimated approximate No. of deaths
1822	40,000
1876	1,00,000
1897	1,75,000
1912	40,000
1919	40,000
1960	15,000
1963	11,520
1965	19,279
1970	3,00,000
1985	11,069
1991	1,40,000

Table 6.20: Damage in Bangladesh (in addition to human death toll) due to the November 1970 cyclone and storm surge (FRANK and HUSSAIN, 1971)

Damage	Toll
Population affected	4.7 million
Crop loss	U.S.\$ 63 million
Loss of cattle	280 000
Loss of Poultry	500 000
Houses damaged	400 000
School damaged	3 500
Fishing boats (marine) destroyed	9 000
Fishing boats (inland waters) destroyed	90 000

5000 people. A surge in 1780 in the Antilles killed 22 000 people and one in the Cuba-Haiti area in 1963 killed 7196 people (FRANK and HUSSAIN, 1971).

The November 13, 1970, storm surge was supposed to be the worst on record in Bangladesh. The death toll was initially estimated to be over a million people. Later estimates brought it down to 500,000, then 300,000, and finally 200,000. Whatever the correct toll may be, this storm surge event created a new awareness of tropical cyclones in general and of storm surges in particular, not only in Bangladesh but all over the world. In a storm surge event of this magnitude, there is not only the human death toll but there are other damages as well. The damage in Bangladesh due to this storm surge is listed in Table 6.20. The salt water from the sea flooded the land during the surge event, leaving much salt on the land, which for 4-5 years after the event affected crops until rains finally washed away the salt.

There are more than 40 known cases of storm surges in Bangladesh during the period 1800-1999. A partial list is given in Table 6.21 for the period 1876-1999. It is quite probable that some of the entries in the table are wrong. Also, sometimes the total water level (i.e. tide + surge) is reported as surge. The observed water levels during storm surge events at six different locations in Bangladesh during the period 1965-76 are listed in Table 6.22. The storm surge and the pertinent meteorological and tidal information at Chittagong for the period 1960-70 are given in Table 6.23. ALI (1980b) summarized the numerical models that have

Table 6.21: List of storm surges in Bangladesh (1582-1999)

No.	Date	Location	Damage
1	1582	Near Backergunge, Bangladesh	200,000 deaths, Destruction reported due to surge
2	1699	Sundarban coast, Bangladesh	50,000 deaths
3	1760	Sundarban coast, Bangladesh	Extensive damage
4	1765	Chittagong coast, Bangladesh	Extensive damage
5	1767	Barisal, Bangladesh	13.03 m surge, 30,000 deaths
6	May-June, 1797	Chittagong, Bangladesh	2 ships sank. No estimate of deaths
7	6 June, 1822	Barisal/Backergunge, Bangladesh	50,000 deaths, storm wave swept the region
8	16 May, 1869	Khulna	Surge entered through the Pussur and Haringhata Rivers and inundated a vast area causing damage of life and property. 250 people died in Moreganj
9	31 October, 1876	Backergunge, Bangladesh	This was the infamous Backergunge cyclone. Peak water levels in Bangladesh varied from 3 to 13.6 m, including tide and wind waves. 100,000 deaths in Bangladesh (then part of India). This India Meteorological Department was expanded following this surge. GILL (1975), but this could be an over-estimate lot of destruction. Inundation subsided in 2 hours
10	27 October, 1893	Noakhali	Damage estimates not available
11	October, 1895	Sunderban/Bagerhat, Subdivision, Bangladesh	175,000 deaths. Thousands died in the epidemic which followed the calamity
12	24 October, 1897	Chittagong, Kutubdia Island, Bangladesh	Surge caused huge damage
13	May, 1898	Taknaf, Bangladesh	Damage estimate not available
14	November, 1901	Western Sunderbans, Bangladesh	172 deaths, extensive damage
15	15-18 October, 1909	Backerganj, Bangladesh	Storm surge caused heavy damage
16	2-6, December, 1909	Cox's Bazar, Bangladesh	Damage estimate not available
17	April, 1911	Teknaf, Bangladesh	Damage estimate not available
18	May, 1917	Sunderbans, Bangladesh	3,500 deaths in Bangladesh
19	20-25 September, 1919	Barisal, Bangladesh	Damage estimate not available
20	19-24 April, 1922	Cox Bazar, Bangladesh	Damage to ships, No deaths
21	3-7 May, 1923	Teknaf, Bangladesh	25000 houses damaged
22	19-23 May, 1926	Cox's Bazar, Bangladesh	2700 deaths
23	22-26 May, 1941	Between Barisal and Noakhali, Bangladesh	3.03-3.64 m surge. 5000 deaths due to storm surge
24	21-24 October, 1947	Between Chittagong and Barisal, Bangladesh	500 deaths
25	17-19 May, 1948	Between Chittagong and Noakhali, Bangladesh	Damage estimate not available
26	15-20 November, 1950	Patuakhali, Bangladesh	Damage estimate not available
27	16-19 May, 1958	East Meghna Estuary, Bangladesh	Cargo and country boats capsized, Sandwip island badly affected
28	21-24 October, 1958	Noakhali and West Meghna Estuary, Bangladesh	Up to 2 m surges in Bangladesh and West Bengal State of India, 500 deaths
29	29 May, 1960	Sunderbans, Bangladesh	3.2 m surge, extensive damage

Table 6.21 (continued)

No.	Date	Location	Damage
30	8-10 October, 1960	Noakhali, Meghna Estuary, Bangladesh	6 m surge. 6,000 deaths in offshore island of Noakhali, Barisal, Chittagong.
31	30-31 October, 1960	Nathalie, Chittagong, Bangladesh	6.6 m surge. 5,149 deaths
32	9 May, 1961	Noakhali West Meghna Estuary, Bangladesh	3 m surges. 11,468 deaths
33	29-30 May, 1961	Chittagong, Cox's Bazaar, Noakhali, offshore islands, Bangladesh	2.6-4.5 m surge. Peak water levels up to 9 m.
34	26-30 October, 1962	Feni, Bangladesh	Damage estimate not available
35	28-29 May, 1963	Noakhali, Chittagong, Bangladesh	Peak water levels up to 8.1 m. 11,520 deaths
36	5-8 June, 1963	Jessore, Bangladesh	Peak surge 3.1 m
37	25-27 October, 1963	Teknaf, Bangladesh	Damage estimate not available
38	11 April, 1964	Bangladesh	196 deaths
39	9-12 May, 1965	Barisal and Noakhali, Bangladesh	3-6 m surge. 19,279 deaths
40	26 April - 1 May, 1965	Hatia, Bangladesh	Up to 7.6 surges. 12,000 deaths
41	5 November, 1965	Bangladesh	Up to 3.7 m surges
42	11-15 December, 1965	Cox's Bazaar, Bangladesh	2.4-3.6 m surge. 873 deaths
43	23 September-1 October, 1966	Noakhali, Bangladesh	6.0-6.7 m surge. 850 deaths
44	1 November, 1966	Bangladesh	Peak water levels up to 10 m
45	7-12 December, 1966	Cox's Bazaar, Bangladesh	Damage estimate not available
46	8-11 October, 1967	Khulna, Bangladesh	Peak water levels up to 9.3 m
47	20-24 October, 1967	Cox's Bazaar, Bangladesh	Up to 7.6 m surge, 51 deaths
48	17 April, 1969	Bangladesh	75 deaths
49	10 October, 1969	Khulna, Bangladesh	Peak water levels up to 8 m.
50	2-7 May, 1970	Cox's Bazaar, Bangladesh	Up to 5 m surge
51	18-23 October, 1970	Chandpur, Bangladesh	4.7 m surge. 300 deaths
52	8-13 November, 1970	Between Noakhali and Chittagong, Bangladesh	3-10 m surge. 300,000 deaths. 2,80,000 cattle killed, 44,00,000 houses destroyed, 18,000 boats destroyed, unofficial estimation of deaths more than 500,000
53	8 May, 1971	Khulna to Chittagong and offshore islands, Bangladesh	2.4-4.2 m surge. Other information not available
54	28-30 September, 1971	Chandpur, Bangladesh	Surge plus tide of 5 m
55	5-6 November, 1971	Chittagong, Bangladesh	Water levels up to 5.5 m
56	28-30 November, 1971	Sunderban coast, Khulna, Bangladesh	1 m surge
57	14-18 November, 1973	Barisal, Bangladesh	1.0 m surge. Peak water level including wind waves 3.8 m
58	5-9 December, 1973	Patuakhali coast and offshore islands, Bangladesh	Peak water level 6.2 m. Peak surge 4.5 m. 183 deaths

59	13-15 August, 1974	Khulna, Bangladesh	6.7 m surge	
60	24-28 November, 1974	Chittagong, Bangladesh	3.0-5.1 m surge. 20 deaths, 50 injured, 280 persons missing, 1,000 cattle killed, 2,300 house destroyed	
61	9-12 May, 1975	Bhola, Cox's Bazaar, Khulna, Bangladesh	5 deaths. 4 injured. 36 fishermen missing	
62	4-8 June, 1975	Chittagong, Bangladesh	Peak surge 4.0 m, 50 deaths	
63	24-28 June, 1975	Bangladesh	Tide and surge 4.8 m	
64	7-11 Nov, 1975	Barisal, Noakhali, Bangladesh	Maximum surge 3.1 m	
65	15-21 October, 1976	Meghna Estuary, Bangladesh	Tide plus surge 5.0 m at Comapaniganj	
66	20 November, 1976	Chittagong, Bangladesh	1.0 m surge. 2.1 m tide	
67	9-13 May, 1977	Noakhali, Bangladesh	0.6 m surge. 0.7 m tide	
68	1-3 October, 1978	Khulna and Sunderban coast, Bangladesh	Damage estimate not available	
69	6-10 December, 1981	Khulna, Bangladesh	2-4.5 m surge 72 deaths and 200 deaths in India.	
70	14-15 October, 1983	Chittagong coast near the Feni River, Bangladesh	43 deaths. Substantial damage	
71	5-9 November, 1983	Chittagong, Cox's Bazaar, Bangladesh	1.5 m surge, 300 deaths. Substantial damage	
72	20-25 May, 1985	Cox's Bazaar, Chittagong, Sandwip, Bangladesh	4.55 m surge. 11,069 deaths. 94,000 houses destroyed	
73	7-9 November, 1986	Chittagong, Bangladesh	0.61 m surge, 50 deaths. Substantial damage	
74	January 30- Februar-4, 1987	Chittagong, Bangladesh	Damage estimate not available	
75	24-30 November, 1988	Khulna coast near Raimangal river, Bangladesh	4.4 m surge. 11,683 deaths in Bangladesh, 532 deaths in India 6,000 missing. 65,000 cattle killed. 15,000 deer killed. 9 royal Bengal tigers killed. Substantial crop damage.	
76	7-8 October, 1990	Barisal, Bangladesh	150 fishermen missing. Substantial damage	
77	16-18 December, 1990	Khulna coast, Bangladesh	4.4 m surge, 5683 deaths, 15,000 and 9 tigers killed, 65,000 cattle killed	
78	25-30 April, 1991	Chittagong, Cox's Bazaar, Bangladesh	6-7.6 m surge. 140,000 deaths. 70,000 cattle killed. Great damage	
79	31 May-2 June, 1991	Noakhali-Patakhali, Bangladesh	2.5 m surge, 300 deaths	
80	16-21, Nov 1992	Teknoff, Bangladesh Coast	Damage estimation not available	
81	21-25 Nov 1995	Coxbazar, Bangladesh	Damage estimation not available	
82	26-29 October, 1996	Sundarban coast, Bangladesh	1.52-2.12 m surge, 9 deaths, 2000 fishermen missing, 15,000 cattle killed, 10,000 houses damaged	
83	15-20 May, 1997	Chittagong, Bangladesh	4.55 m surge, 155 deaths	
84	24-27 September, 1997	Noakhali-Chittagong coast, Bangladesh	3.03-4.55 m surge at Bhola, 1.52-2.12 m surge at Barguna, 2.42-3.03 m surge at Galachipa, 67 deaths. At Khagrachhari, 16 villages and a part of the district town went under 1.82-2.42 m surge.	
85	4-9 Nov 1997	Bangladesh coast	3.0 m surge, substantial damage	
86	17-21 May 1998	Bangladesh coast	16 deaths	

Table 6.22: Observed water levels (tide + surge) in meters at six locations in Bangladesh (ALI, 1980b)

Date	Khulna	Barisal	Sandwip	Chittagong	Chandpur	Companigonj
May 12. 1965	—	2.84	2.90	—	2.53	2.21
May 31. 1965	2.25	2.44	3.73	—	3.80	7.13
Oct 11. 1967	2.59	—	—	2.92	—	8.75
Oct 24. 1967	2.44	—	—	1.89	—	7.61
May 10. 1968	—	—	2.78	3.38	—	4.74
Oct 10. 1969	2.61	—	7.21	3.20	4.27	4.63
Oct 23. 1970	3.02	3.47	—	—	4.74	4.21
Nov. 12. 1970	—	2.67	3.86	5.58	4.09	5.58
Sep. 30. 1967	3.08	3.04	—	—	5.03	4.21
Oct. 20. 1976	—	4.64	3.00	3.17	3.54	5.02

Table 6.23. Some pertinent details for storm surges at Chittagong, Bangladesh (FLIERL and ROBINSON, 1972)

Date	Storm speed ($\text{km}\cdot\text{h}^{-1}$)	Maximum observed wind speed ($\text{km}\cdot\text{h}^{-1}$)	Astronomical tide (m)	Observed sea level (m)	Maximum surge (m)
Oct 11, 1960	20	161	1.5	6.0	4.5
Oct 31, 1960	38	193	0.0	6.6	6.6
May 9, 1960	38	161	1.2	4.8	3.6
May 30, 1960	22	161	0.6	—	—
May 29, 1960	40	209	0.3	—	—
Nov. 9, 1965	42	161	1.2	—	—
Dec. 15, 1965	32	161	0.3	—	—
Nov. 13, 1970	20	161	1	6.0–9.0	4.2–7.2

been developed for storm surges on the coast of Bangladesh. Probably the first model is by DAS (1972) for the coasts of India and Bangladesh, and he simulated the surge due to the November 1970 cyclone. This was extended by DAS et al. (1974). They investigated the effect of the central pressure drop and the speed of movement of the cyclone. Nomograms were given for the peak surge for three different tracks. This work will be considered under the subsection Storm Surges in India. FLIERL and ROBINSON (1972) also developed a linear model specifically for the coast of Bangladesh. A nomogram for practical purpose was also prepared.

ISLAM (1971) discussed the storm surge protection problem in Bangladesh. He mentioned the construction of various types of raised platforms (Machan, Killa, etc.) for people and animals. KIBRIA (1980) discussed the planned delta works to protect the Bangladesh coast from storm surges.

DUBE et al. (1984b, 1985b, 1985c, 1986a, 1986b) and SINHA et al. (1983, 1985, 1986) developed several models to simulate the surges associated with severe cyclonic storms hitting the coast of Bangladesh. Their models are confined to the northern shelf of the head Bay region with southern open Sea boundary at 19°N . Curvilinear coastal boundary treatment analogous to that used by Johns et al. (1981) was utilized by them. Experiments were carried out to determine the optimum grid resolution, which turned out to be 30 km in the E-W and

8–20.5 km in the N–S directions (varying because of the coordinate transformation). Authors attempted several problems including the computation of inland inundation using continuously deforming shoreline model and the impact of Meghna river discharge on storm surges. In the absence of the observed reliable data on storm surges it was difficult to compare the results, however limited comparisons with observed peak surge were given.

Fig. 6.33 and 6.34 show respectively the computed peak surge along the Bangladesh associated with November 1970 Chittagong cyclone and the temporal variation of predicted sea surface elevation at Maijdi. The impact of inclusion of the river and its discharge on the peak surge and on the temporal evolution of surge is clearly seen from these experiments.

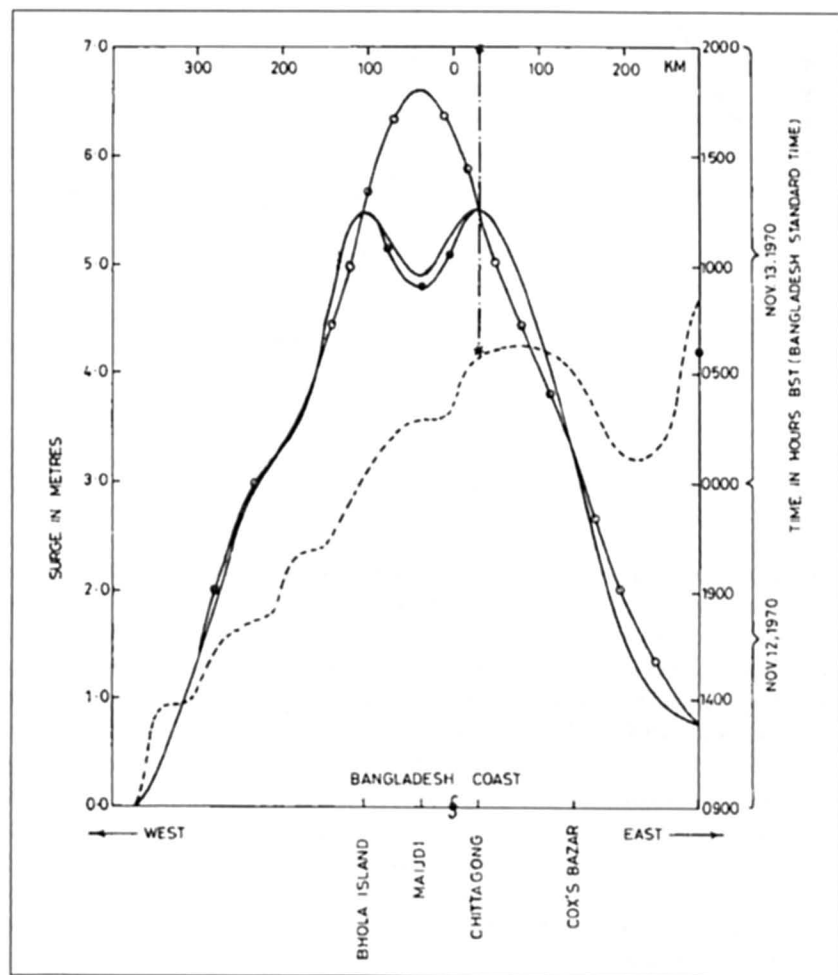


Fig. 6.33: Maximum predicted sea - surface elevation and its time of occurrence along the Bangladesh coast. § = place of landfall; • = time of landfall (on the time axis); - = peak surge envelope (BRM1) with discharge; --- = time of occurrence (BRM1); -•-•- = peak surge envelop (BRM2) without discharge; -o-o- = peak surge envelope (MWR) without river; *--* = observed range of sea - surface elevation in excess of predicted tide (DUBE et al., 1986b)

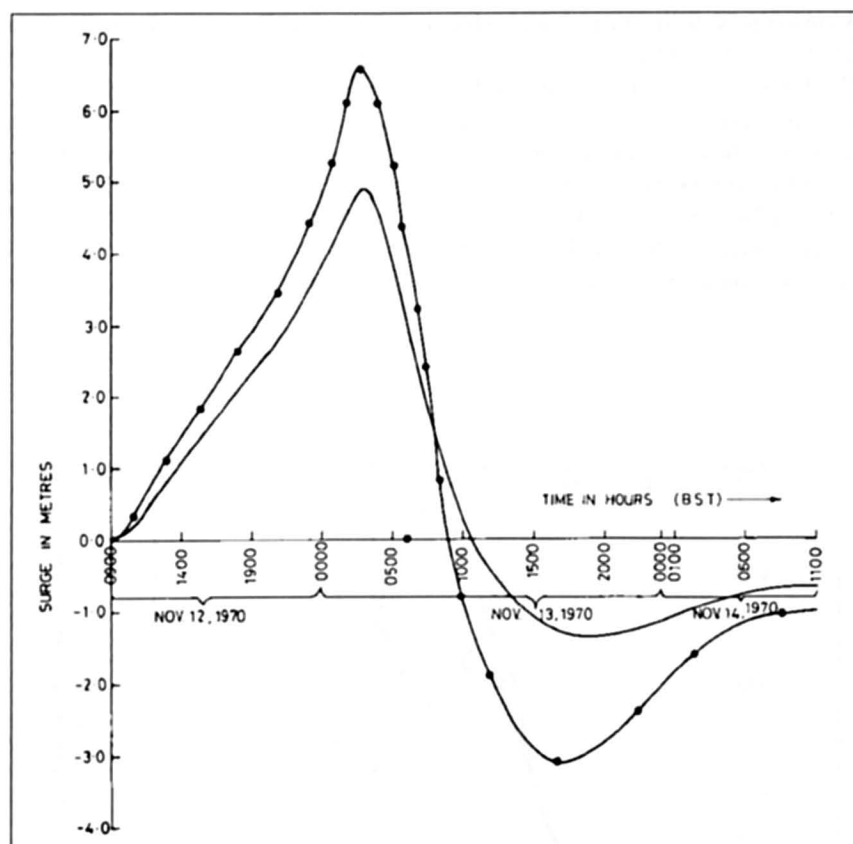


Fig. 6.34: Time variation of the predicted sea-surface elevation at Maijdi. • = time of landfall (on time axis); — = BRM1 (with discharge); -•-•- = MWR (without river). (DUBE et al., 1986b)

Considering the complexities of the Bangladesh coastline with numerous inlets, offshore islands and chars, the smooth curves of the model coast resulting from the curvilinear coordinate transformation appear to be a quite limitation of these models. Recognizing this shortcoming, JOHNS et al. (1985) developed a model for the Head Bay region using rectangular Cartesian coordinates. The southern open boundary of the model was at $19^{\circ}33' \text{ N}$, the grid size 17.6 km E-W by 19.8 km N-S, and five idealized river models, each of uniform depth and width and length 200 km were included to represent the main channels in the Ganges Delta. The model was nested within a large curvilinear model of the whole Bay (JOHNS et al., 1981), which provided boundary input of tide and surge. The model was used to study the tide-surge interaction in the Bay of Bengal for details refer to section 4.5.2.

A detailed numerical storm surge prediction model for the Bangladesh region was developed by FLATHER (1994). The formulation used by the author allows the delta to be included in a much more complete and realistic manner. This was achieved by a modification in the standard depth-averaged equations with a numerical scheme in which the solution of one-dimensional equations for narrow channels and two-dimensional equations for the open sea are combined within a unified computational framework. In this manner author was able to realistically model the complex coastal area and the Gangetic Delta. Using the scheme earlier designed by FLATHER and HEAPS (1975), the model also allows the inland inundation.

The model was used to investigate the storm surges generated by November 1970 and April 1991 cyclones. Hindcast and "forecast" simulations of April 1991 event was described using forcing derived from a semi analytical cyclone model with data supplied by the Joint model with data supplied by the Joint. Typhoon Warning Center (JTWC). The results show that the timing of cyclone landfall and its coincidence with high tide determine the areas worst affected by flooding.

ALI et al. (1997b) studied the backwater effect of tides and storm surges on fresh water discharge through the Meghna estuary. In another study ALI et al. (1997a) used a two-dimensional model to study in detail the interactions between river discharge, storm surges and tidal interactions in the Meghna river mouth in the Bangladesh. The study considers the interactions mostly in terms of flow across the river mouth under the three forcing, individually and in different combinations of them. The model has been able to produce some interesting features of the interaction between three forcing in the mouth of Meghna estuary. It is shown by the authors that river discharge and tidal flow across the river mouth act both positively and negatively depending on the tidal phase, positively during the high tide and negatively during low tide. The result is also found true for the combination of all three forces. In most of the cases, river discharge is found to act in opposition to the storm surges. The interaction between river discharge and storm surges is shown to be dependent on their relative magnitudes. However, in respect of the total elevation in the estuarial region, river discharge tends to increase the surge height.

Recently HENRY et al. (1997) used a finite element model to study the tides and storm surges in offshore waters of the Meghna estuary. The model reproduced tidal elevations well at the four coastal sites used for model verification and simulated surge elevations at the coast with acceptable accuracy.

(b) East Coast of India

India is prone to storm surges on both its east and west coast although the frequency and severity of surges is greater on the east coast. Some important storm surges (form the point of view of loss of life) on the Bay of Bengal coast of India are listed in Table 6.24. List, which is based on various sources, might not be totally correct. Also, in this list, several minor surges in which less than 100 people were killed are excluded.

Some pertinent information on six storm surges at Saugor Island (in the northwestern part of the Bay of Bengal) during the period 1948-55 is given in Table 6.25. This table also compares the observed surges with those computed using simple empirical formulae (JANARDHAN, 1967).

RAO and MAZUMDAR (1966) and RAO (1968) used empirical relations to calculate storm surges on the east coast of India, south of 17° N. Topography near the shore and wind waves were also included in the calculations. Based on these calculations, RAO (1968) classified the east coast of India (and the coasts of Bangladesh and Burma for comparison into three types. These results are summarized in Table 6.26. In this table, the values listed under "storm surge amplitude" pertain to a storm with winds up to $40\text{ m} \cdot \text{s}^{-1}$. The values listed under "total water level" include the peak surge plus the wind waves.

Classification of types A, B, and C is as follows. For a type A coastline, the maximum total water level is less than or equal to 2 m during storm surge events, for type B the amplitude is between 2 and 5 m, and for type C the amplitude is greater than 5 m. This classification is shown in Fig 6.35, for the east and west coasts of India (the west coast of India will be

Table 6.24: List of storm surges along east coast of India (1681-1999)

No.	Date	Location	Damage
1	10 November, 1681	Nagapattinam, Tamilnadu, India	14,000 deaths
2	18 April, 1700	Visakhapatnam, Andhra Pradesh, India	Several ships lost at sea. No estimate of number of deaths available
3	December, 1706	Coringa, Andhra Pradesh, India	No exact estimate of the number of deaths, except a statement that people in great number were lost
4	18 December, 1709	Coastal Ramnad, Tamilnadu, India	Extensive inundation of coastal Ramnad. Major surge. Deaths in thousands
5	7-12 October, 1737	Mouth of Hoogly River, West Bengal, India	12 m surge (probably includes tide and wind waves). Surge penetrated 100 km inland through the Hoogly River. 300,000 deaths in India and Bangladesh (could be a slight exaggeration)
6	2 October, 1747	Madras, Tamilnadu, India	Extensive damage, no estimate of deaths
7	31 October, 1752	Madras, Tamilnadu, India	Extensive damage, no estimate of deaths
8	30 December, 1760	Pondicherry, Tamilnadu, India	Several ships destroyed. 11,000 deaths
9	31 October, 1763	Madras, Tamilnadu, India	Extensive damage, no estimate of deaths
10	13 October, 1779	Masulipatnam, Andhra Pradesh, India	3.63 surge, 20,000 deaths
11	20 May, 1787	Coringa, Andhra Pradesh, India	20,000 deaths. Coastal inundation due to storm surges
12	December, 1789	Near Coringa, Andhra Pradesh, India	3 major waves in the surge. Several ships lost. 20,000 deaths. Inundation of the whole city of Coringa of 1 to 2 m.
13	10 December, 1807	Madras, Tamilnadu, India	Extensive destruction in Madras, no estimate of deaths
14	11 May, 1811	Madras, Tamilnadu, India	Extensive destruction in Madras, no estimate of deaths
15	2 May, 1820	Near Madras, Tamilnadu, India	No estimate of deaths
16	8 May, 1820	Nellore District, Andhra Pradesh, India	Inundation. No estimate of deaths
17	27 May, 1823	Balasore, Orissa, India	Inundation up to 10 km inland. Several ships and whole villages disappeared
18	31 October, 1831	Balasore, Orissa, India	2.112-4.5 m surges. Extensive inundation. 22,000 deaths. 50,000 cattle lost. This might have been the same storm that also generated at surge at Barisal, Bangladesh.
19	10 May, 1832	Coringa, Andhra Pradesh, India	Extensive damage at Coringa
20	October, 1832	Balasore, Orissa, India	More violent storm than in 1823 (No. 16) but the surge was less destructive
21	21 May, 1833	Sagar Island/24 Paraganas, West Bengal, India	3 m surge. 50,000 deaths. 100,000 cattle lost
22	16 November, 1839	Between Visakhapatnam and Narsapur/Coringa, Injaram, Andhra Pradesh, India	Over 6 m surge. 20,000 deaths
23	22 May, 1843	Masulipatnam, Andhra Pradesh, India	Extensive damage
24	October, 1854	Mouth of Hoogly River, West Bengal, India	Up to 12 m water level increase near Calcutta and environs. 50,000 deaths
25	21-27 April, 1859	Near Nagapatnam, Tamilnadu, India	No estimation of deaths.

Table 6.24 (continued)

No.	Date	Location	Damage
26	2-5 October, 1864	Near Contai, West Bengal, India	Up to 12 m surge. Flooded up to 13 km on either side of the Hoogly River. 80,000 deaths.
27	1-2 November, 1864	Masulipatnam, Andhra Pradesh, India	About 130 km long stretch was subjected to surges up to 3.93 m. Surge penetrated up to 27 km inland. 30,000 deaths
28	1 November, 1867	East of Calcutta, West Bengal, India	1.8 m surge. Damage at Port Canning. 13 m surge at Hatia, Bhola Islands
29	4 November, 1870	Visakhapatnam, Andhra Pradesh, India	Lower parts of the town flooded. Also whole of Anakapalle town flooded. 7 deaths
30	1 July 1872	Near Cuttack, Orissa, India	Extensive damage, no estimate of deaths
31	13-16 October, 1874	Mouth of Hoogly, West Bengal, India	3049 deaths
32	7-8 October, 1876	Near Bhimilipatnam, Andhra Pradesh, India	Extensive damage, 30 deaths
33	6-8 December, 1878	Kakinada, Andhra Pradesh, India	Local storm surge and inundation
34	19-23 September, 1885	Cuttack (False Point) Orissa, India	7 m surge. 5,000 deaths by drowning. 300 deaths by falling trees. 50,000 houses destroyed. 10,000 cattle lost
35	6-15 September, 1882	South Orissa coast, India	Extensive damage
36	2-16 November, 1886	Madras coast, India	No estimation of deaths.
37	21-28 May, 1887	False Point, Orissa, India	Major surges
38	21-26 September, 1887	Calcutta, West Bengal, India	No estimation of deaths.
39	13-20 September, 1888	False Point, Orissa	No estimation of deaths.
40	21 November, 1888	Madras, Tamilnadu, India	No estimation of deaths.
41	24-27 October, 1909	Near Gopalpur, Orissa, India	Extensive damage, no estimation of deaths.
42	20-24 September, 1911	Kanigapatnam, Andhra Pradesh, India	Extensive damage, no estimation of deaths
43	18-29 September, 1916	West Bengal coast, India	Extensive damage, no estimation of deaths
44	21-23 November, 1916	Near Cuddalore, Tamilnadu, India	Extensive damage, 300 deaths
45	12-20 May, 1925	Masulipatnam, Andhra Pradesh, India	The surge penetrated up to 6 km inland, 80 deaths.
46	29 Oct-1 Nov, 1927	Nellore, Andhra Pradesh, India	629 deaths. Considerable damage due to surge
47	14-19 Nov, 1933	Ongole, Andhra Pradesh, India	Moderate surge inundated low-lying areas
48	25-28 October, 1936	Masulipatnam, Andhra Pradesh, India	Surge penetrated up to 6 km inland. Destruction of agriculture due to saline water intrusion
49	21-25 Nov, 1938	Machilipatnam, Andhra Pradesh, India	2 m surge. Railway bridge washed away. Extensive damage to waterworks due to saline water intrusion
50	14-16 October, 1942	Contai, West Bengal, India	5 m surge at Midnapore (64 km upstream in Hoogly River) 15,000 deaths
51	13-23, May 1943	South of Madras, Tamilnadu, India	Extensive damage, low-lying areas inundated

Table 6.24 (continued)

No.	Date	Location	Damage
52	29-31 October, 1943	Kalingapatnam, Andhra Pradesh, India	Surge combined with floods in River Vamsadhara caused great damage
53	15-21 October, 1945	Masulipatnam, Andhra Pradesh, India	Up to 3.03-4.54 m surges penetrated 24 km inland
54	30 November, 1952	South of Nagapattinam, Tamilnadu, India	1.21 m surge penetrated 8 km inland. 400 deaths
55	6-14 October, 1955	Kalingapatnam, Andhra Pradesh, India	Surge up to 1.7 m
56	28 Nov-2 Dec, 1955	Tanjavore District, Tamilnadu, India	Surges up to 5 m penetrated 16 km inland. 500 deaths
57	29 May-1 June, 1956	Near Calcutta, West Bengal, India	Inundation in Midnapore District. Damage to agriculture due to saline water intrusion
58	21 October, 1963	Cuddalore, Tamilnadu, India	Almost 7 m surge
59	3-8 November, 1964	Madras coast, India	Low-lying areas of Madras city flooded
60	20-23 Dec, 1964	Tondi (Rameswaram Island), Tamilnadu, India	3-6 m Surge. 1,000 deaths
61	1-3 November, 1966	North Madras coast, India	Tidal bore flooded a large area of Madras city, 30 deaths, 3 ships grounded
62	8-11 October, 1967	Puri, Orissa, India	Water levels up to 9 m. 1000 deaths. 25 km inland inundation.
63	2-8 December, 1967	Nagapattinam, Tamilnadu, India	Moderate surges. 7 deaths
64	7 November, 1969	Kakinada, Andhra Pradesh, India	3.1 m surge. 900 deaths
65	26-30 October, 1971	Paradip, Orissa, India	4-5 m surge. The surge penetrated 25 km inland. 10,000 deaths
66	10 September, 1972	Barua, Orissa, India	3.4 m surge. 0.8 m tide
67	22 September, 1972	Gopalpur, Orissa, India	Inundation in Puri District
68	15-23 November, 1972	South of Nellore, Andhra Pradesh, India	Minor Surge
69	6-12 October, 1973	Chandbali, Orissa, India	Mild surge in river estuaries caused saline water intrusion in the coastal areas of north Orissa and West Bengal. 100 deaths
70	3-9 November, 1973	Near Paradip, Orissa, India	3-4.5 surge. Saline water inundation in Basudevpur and Uttara Sumiti
71	12-23 December 1968	Near Nagapattinam, Tamilnadu, India	7 deaths, Tidal waves caused severe damage in coastal districts of Ramapattinam
72	13-20 August, 1974	Contai, West Bengal, India	3 m surge. Inundation of low-lying areas of Digha and Juneput. 7 deaths
73	11 September, 1976	Contai, West Bengal, India	2.5 m surge. 1.4 m tide. 40 deaths.
74	14-20 Nov, 1977	Chirala, Andhra Pradesh, India	Peak surge 5.0 m, Tide 0.3 m. Divi and surroundings totally inundated. 10,000 deaths
75	24 November, 1978	Between Kilakkarai and Rochemary Island, Tamilnadu, India	3-5 m surges on the coasts of Tamilnadu and Sri Lanka. Extensive damage on the northeast coast of Sri Lanka. 1000 deaths in Sri Lanka. 10 deaths in India
76	12 May, 1979	Kavali, Andhra Pradesh, India	3 m surge. 0.6 m tide. 700 deaths
77	1-4 June, 1982	Between Paradip and Chandbali, Orissa, India	2 m surge along the Orissa and West Bengal coasts. Peak surge of 4.8 m 35 km north of Dhamra harbour. 245 deaths.

Table 6.24 (continued)

No.	Date	Location	Damage
78	9-14 November, 1984	Near Sriharikota, Andhra Pradesh, India	524 deaths, extensive damage
79	20 September, 1985	Close of Puri, Orissa, India	2 m surge. Inundation lasted for 3 days. Substantial damage
80	16 October, 1985	Near Balasore, Orissa, India	Up to 4 m surge. Damage due to saline water inundation
81	13-19 October, 1987	North of Ongole, Andhra Pradesh, India	Moderate surge. 17 deaths. Substantial damage
82	31 October - 3 November, 1987	Nellore, Andhra Pradesh, India	50 deaths. 26,000 cattle killed. Substantial damage
83	23-27 May, 1989	Near Balasore, Orissa, India	3-6 m surge, 71 deaths, 2625 cattle killed, extensive damage in West Bengal and Orissa
84	4-7 November, 1989	Kavali, Andhra Pradesh, India	3-4 m surge caused destruction in Nellore and Kavali. 69 deaths
85	4-11 May, 1990	Mouth of Krishna River, Andhra Pradesh, India	4-5 m surge. 967 deaths. 600,000 houses destroyed. 21,600 cattle killed. 3,500,000 poultry killed. 42,700 goats and sheep killed. Substantial damage to agriculture
86	11-17 Nov, 1992	Sri Lanka, and Tutikorin, India	1-2 m surge at Tuticorin, 170 killed, 160 missing
87	1-4 December, 1993	Near Karaikal	1-1.5 m surge, 111 killed
88	29-31 Oct, 1994	Madras, India	1-2 m surge, 304 killed, 100,000 huts damaged, 60,000 hectares crops damaged
ged			
89	6-10 Nov, 1995	Gopalpur, Orissa, India	1.5 m, 96 killed, 2,84,253 hectares crops damaged
90	12-16 Jun, 1996	Visakhapatnam, India	179 killed, 13,378 hectares of crops damaged
91	5-7 Nov, 1996	Kakinada, India	2-3 m surge, 978 killed, 1375 missing, 647554 houses damaged, 1.74 lakh hectares crops damaged
92	17-21 Nov, 1998	Visakhapatnam, India	16 deaths. Damage estimation not available

Table 6.25. Storm surge at Saugor Island, India, during 1948–55 (JANARDHAN, 1967)

Date	Distance of storm center to Saugor Island (km)	Observed peak surge (m)	Computed peak surge (m)	State of tide at time of peak surge
Aug. 14, 1948	306	0.34	0.43	High
Aug. 15, 1948	402	0.43	0.40	Low
July 25, 1951	306	0.85	0.98	Low
Aug. 05, 1952	418	0.34	0.34	High
Aug. 03, 1953	306	0.46	0.46	High
Aug. 30, 1955	217	0.46	0.46	High

considered in the next subsection). The storm surge considered here is the piling up of the water due to wind stress. The inverse barometer effect is not included here, since according to RAO (1968), it does not exceed 0.5 m anywhere on the east coast of India.

Table 6.26: Maximum possible storm amplitudes and total water levels (surge + wind waves) at selected locations on the east coast of India. The hypothetical storm has a wind speed of $40 \text{ m} \cdot \text{s}^{-1}$. A, total water level <2 m; B, 2–5 m; C, >5 m. A few locations in Bangladesh and one in Burma are included for comparison (RAO, 1968)

Location	Favorable Wind direction	Storm surge amplitude (m)	Storm surge + Wind wave (total water level) (m)	Classification
Dhanushkodi	NNE	4.8	8.2	C
Rameswaram	SE	6.8	11.3	C
Pamban	NNW	4.4	7.3	C
Devipatnam	E	4.5	7.5	C
Adirampatnam	SSE	5.1	8.5	C
Point Calimere	SSE	4.2	7.0	C
Nagapattinam	E	1.5	2.5	B
Karikal	E	0.3	1.3	A
Madras	ENE	1.5	2.5	B
Nizampatnam	SW	4.5	7.4	C
Mouth of Krishna River	SE	1.6	2.7	B
Narasapur	S	1.7	2.9	B
Sacramento Shoals (outer sand banks)	SSE	1.4	2.3	B
Kakinada (outer sand banks)	E	0.6	1.0	A
Visakhapatnam	SE	0.7	1.2	A
Kalingapatnam	E	1.1	1.8	A
Gopalpur	SE	0.9	1.5	A
Mouth of Devi River	SE	0.8	1.3	A
False point	SE	1.9	3.2	B
Balasore	SE	3.0	5.0	C
Mouth of Hoogly River	S	6.5	10.8	C
Mouth of Matla River	S	5.0	8.4	C
Mouth of Baleswar River (Bangladesh)	S	6.9	11.5	C
Mouth of meghna river (Lakhichar Island, Bangladesh)	SSE	8.0	13.4	C
Cox Bazaar (Bangladesh)	WSW	3.2	6.3	C
Moth of Faaf River (Burma)	SW	3.2	5.3	C

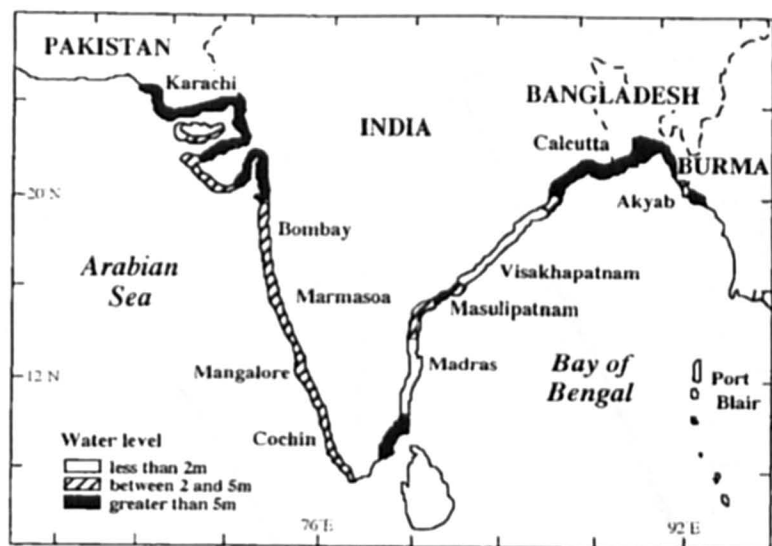


Fig. 6.35: Classification of the Bay of Bengal and the Arabian Sea coasts of India (RAO, 1968)

This classification into types A, B, and C has been verified to certain extent by comparison with actual data (Table 6.27). Thus, type C belts are the most prone to major storm surges. It can be seen from Fig 6.35 that there are four such belts on the coasts of the Indian subcontinent (RAO, 1968). Two are as follows.

- 1) The coastal belt around the head of the Bay Bengal, approximately to the north of 20° N. The frequency of cyclones is high here and the storm tracks are usually favorable for generating maximum surges, especially in the Sunderbans.
- 2) South Coromandel coast around the Palk Bay. Although the frequency of storms striking this region is somewhat smaller than for the first belt, the major storms that strike this coast usually produce major surges.

The other two belts are on the west coast of the subcontinent and will be considered in the next subsection.

There is a short, type C belt near Nizampatnam Bay. The Andhra cyclone of November 1977 produced major surges in this general area and killed several thousand people. The east coast of India, between 14 and 16.5° N, is in the type B category. Also, the Coromandel coast between point Calimere and Karikal falls into this category.

GHOSH (1977) used the SPLASH model (JELESNIANSKI, 1972) for the east coast of India. He prepared nomograms for calculating peak surges based on pressure drop, radius of maximum winds, vector motion of the storm, and bathymetry offshore. The nomograms were prepared separately for the northern part (where the slope of the shelf is small) and for the remaining part of the coast (where the slope is large). A separate nomogram is presented to include the tidal effects on the northern part of the coast where the tidal range is large. Two typical nomograms prepared in this manner are shown in Fig. 6.36.

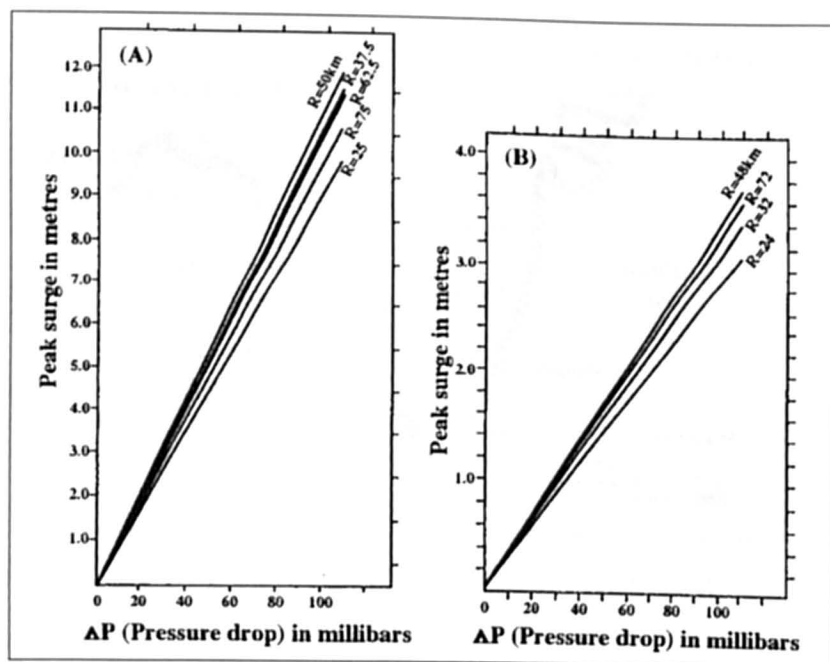


Fig. 6.36: Nomogram of peak storm surge as a function of pressure drop and radius of maximum winds for the (A) northern part and the (B) southern part of the east coast of India (GHOSH, 1977)

Table 6.27: Relationship between type of coastline and occurrence of storm surges on the coast of India. A, surge + wind wave amplitudes <2 m; B, 2–5 m; c, >5 m. Data are mainly for the period 1949–66. (RAO, 1968)

Type of coast	Intensity of storm	No. of storms that affected the coast	No. of storms that caused major storm surges
A	Moderate	13	—
	Severe	12	—
B	Moderate	19	—
	Severe	6	4
C	Moderate	1	—
	Severe	3	3

DAS (1972) used a numerical model to compute storm surges in the Bay of Bengal, which is probably the first numerical model developed for this area. DAS et al. (1974) extended this model to simulate the storm surge due to the cyclone of November 13, 1970, which caused great loss of life and destruction in Bangladesh. They used a two-dimensional linear model and telescoping grids. The grid scheme used for three different types of tracks is illustrated in Fig. 6.37. Nomograms for the storm surge as a function of the storm intensity and speed of movement of the storm are given (for the three tracks shown in Fig. 6.37, in Fig. 6.38).

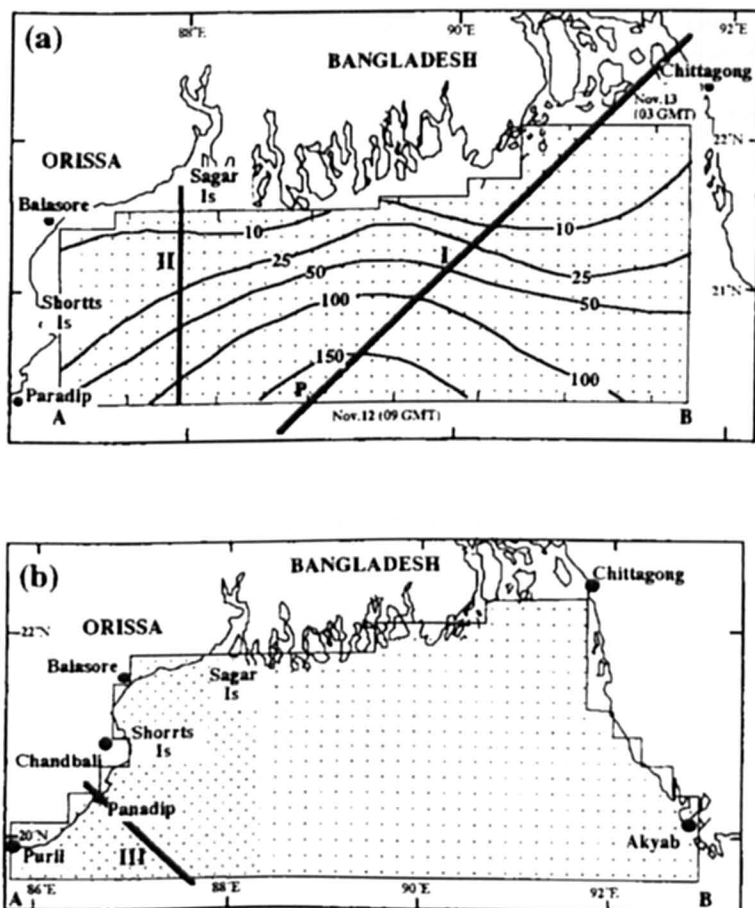


Fig. 6.37: (a) Grids for storms moving northeast (I) and north (II). Contours represent water depth (meters). (b) Grid for storms moving northwest (III) (DAS et al., 1974)

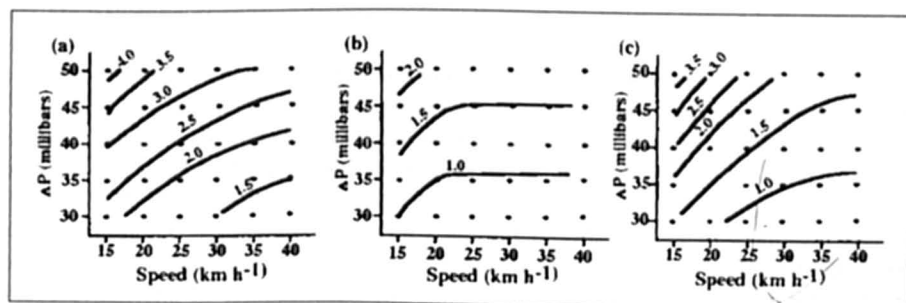


Fig. 6.38: Storm surge amplitude (meters) as a function of storm intensity (millibars) and speed 'c' of storm movement for the (a) northeast track (I), (b) northward track (II) and (c) northwest track (III) of Fig. 6.37 (DAS et al., 1974)

The relationship between the storm surge amplitude η and the storm intensity Δp and speed of movement of storm c was expressed as

$$\eta = A_0 \Delta p + A_1 (\Delta p)^2 + A_2 c \quad (6.69)$$

Table 6.28. Numerical values of the constants A_0 , A_1 , and A_2 of eq. 6.69 for the three different tracks shown in Fig. 6.37 (DAS et al., 1974)

Track	A_0 ($\times 10^2$)	A_1 ($\times 10^4$)	A_2 ($\times 10^2$)
Northeast	9.59	-0.91	-4.60
North	2.88	3.08	-1.20
Northwest	8.24	-1.60	-5.15

The numerical values of the constants A_0 , A_1 , and A_2 are listed for the three different tracks (shown in Fig. 6.37) in Table 6.28. These authors concluded that linear superposition of tide and surge would overestimate the water level by about 1 m.

DAS (1980) included nonlinear advective terms and improved the model of DAS et al. (1974), and the computational area was also enlarged. This model, which includes the tide-surge interaction in a more realistic manner, gave water levels that agreed better with observed levels. NATARAJAN and RAMANATHAN (1980) developed a nonlinear finite-element model and used the same computational area and storm tracks as in DAS et al. (1974)

In a series of papers JOHNS et al. (1981, 1982, 1983a, 1983b, 1985); DUBE et al. (1981, 1982); DAS et al. (1983); DUBE and SINHA (1982) and SINHA et al. (1993) have studied various aspects of storm surge modelling and prediction along the east coast of India. In all these modelling studies the treatment of the coastal boundaries involve a procedure leading to realistic curvilinear representation of the east coast of India, the details of which are described in Chapter 2.

In an attempt to simulate the surge generated by the devastating 1977 Andhra cyclone (Fig. 6.39) JOHNS et al. (1981) used three different numerical models. All the three models considered by the author's are fully nonlinear and based on the vertically integrated equations. The analysis area in the first model (designated M_1) includes the entire Bay of Bengal north of 6°N and utilizes a curvilinear boundary treatment to represent both western and eastern sides of the Bay. The second model (M_2) is a coastal zone model extending along the east coast of India with curvilinear treatment of the coastline. The third model (M_3) that again covers the entire Bay of Bengal uses conventional techniques based on the orthogonal straight-line segments to represent the coastline. Each of these models predict a maximum surge elevation along the Andhra coast in the range of 4–5 m. This compares well with the available observation. However, M_1 produced the surge elevation in excess of 6 m at the head of the Bay, which was unrealistic and is not seen in the results of M_2 . Interesting analysis of the differences in the response obtained from each model has been made. The difference between responses of M_1 and M_2 in the head Bay is attributed by the author's to the funnelling effect of the converging coastline towards the north. Subsequently DUBE et al. (1981) performed numerical experiments, using M_1 with number of alternative cyclone models, to further investigate the phenomenon of large sea surface elevations in the head Bay. Contrary to the earlier explanation given by JOHNS et al. (1981), the authors attribute the anomalous surge produced at Contai in the head Bay to the choice of the cyclone

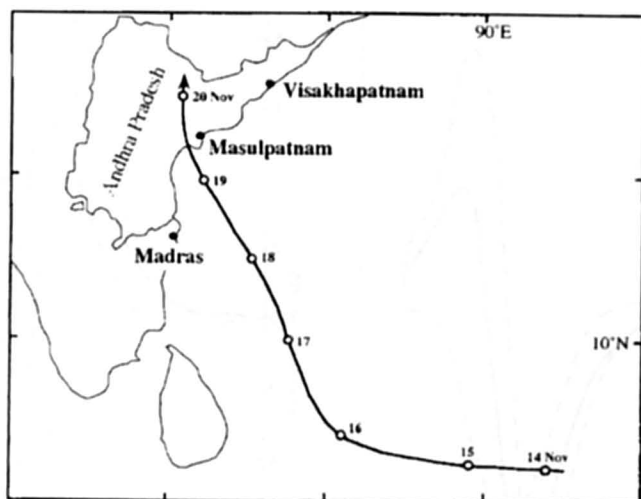


Fig. 6.39: Track of Andhra cyclone: 14–20 November 1977 (JOHNS et al., 1981)

model which gives significantly strong winds at greater distances from the centre of the cyclone.

Frequently, the lateral boundaries in numerical storm surge prediction models are taken to be vertical sidewalls through which no flux of water is allowed. In actuality, however, the water will usually move continuously inland and the use of idealized vertical sidewalls may lead to misrepresentation of the surge development. Recognizing this short coming of earlier models, JOHNS et al. (1982) developed a model which used a continuously deforming lateral fluid boundary instead of using the conventional solid wall boundary at the coast. The model is an extension of the earlier transformed coordinate coastal zone model wherein the coastal topography is included to route the storm surges over the land. As a result of the movement of the coastal boundary with changing water level the horizontal grid deforms with time and the undisturbed water depth at each grid point is recomputed at every time step. Numerical experiments were performed by the authors with different sea-floor slopes and with a fixed boundary version of the model. A comparison of the results show that the moving boundary model gives a reduced surge response at the initial coastline position than that in fixed boundary model. Further, fixed boundary model yields a significantly greater maximum inland intrusion as compared with deforming coastline model. Calculations based on fixed boundary model also show that the predicted maximum inland inundation occurs some 5 hours earlier than in moving boundary model. The differences decrease as the seabed slope at the coast is increased. Seaward recession of the coastline, following the peak surge is also simulated. Fig. 6.40 gives the variation of the coastline displacement and sea surface elevation at initial position of coastline along two stations of Andhra Coast with seabed slope of 2×10^{-4} .

JOHNS et al (1983 a) developed a fully three-dimensional coastal zone storm surge model and applied it to the 1977 Andhra cyclone. The model employed a highly sophisticated turbulent energy closure scheme due to JOHNS (1978). The model was developed with the surmise that the shallow water evolution of the surge response may be significantly different in three-dimensional model because of the full representation of the vertical current structure. It was also thought that the sea-surface surge response would be critically dependent on

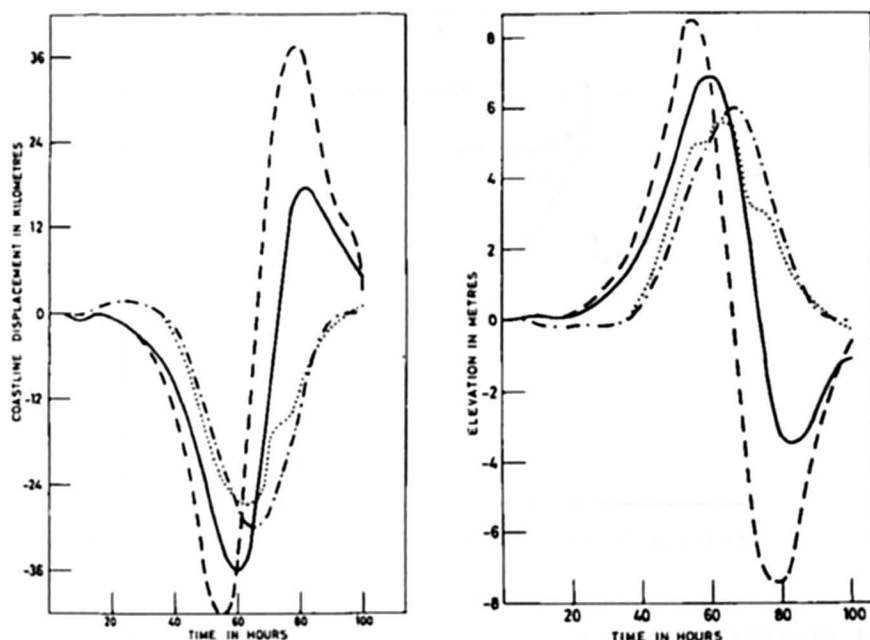


Fig. 6.40:(a) Variation of coastline displacement with $S = 2 \times 10^{-4}$ calculated from MD and MF. Kavali (MD) -; Kavali (MF) - - -; Divi (MD) - - - -; Divi (MF) (b) Variation of sea surface at initial position of coastline with $S = 2 \times 10^{-4}$ calculated from MD and MF. Kavali (MD) -; Kavali (MF) - - -; Divi (MD) - - - -; Divi (MF)

the value chosen for the bottom roughness parameter in the three-dimensional model. Simulations of the Andhra cyclone using two- and three-dimensional models were carried out. The results of their experiment are illuminating.

They found a remarkable qualitative and quantitative similarity between the two simulations, suggesting that details of the dissipative mechanism and vertical current structure were unimportant. They further conclude that if the vertical current structure is not a primary concern, it does not appear worthwhile replacing the depth-averaged procedure by a more complicated three-dimensional model.

Since the coastal surge elevations are effectively dependent upon the near coastal bathymetry, a desirable feature of storm surge simulation schemes is the ability to incorporate increased resolution adjacent to the coastline. This was achieved by JOHNS et al. (1983 b) by introducing an additional transformation of the offshore coordinates in their earlier coastal zone model (JOHNS et al., 1981). This version of the model was used to determine the influence of model resolution and nearshore bathymetry on the computed surge proper resolution of the near shore bathymetry was found to be crucial in determining the storm induced sea surface elevation, one of the interesting results identified by the authors pertain to a northward propagating component of the computed surge response which is found to have the characteristics of a coastally trapped wave. Thus the total response is determined by the contribution from direct wind stress together with the northward propagating component.

For the east coast of India, the phenomenon of alongshore propagation was further identified in a model developed to investigate tide-surge interaction in the Bay of Bengal (JOHNS

et al., 1985). Clear evidence is shown by the authors to the northeasterly propagation in the case of both the 1982 Orissa surge and the 1977 Andhra surge.

Coastal trapping of the energy is implied and the locally shallow water suggests that nonlinear aspects of the propagation process are important. Moreover, the trapped waves cannot have the form of a Kelvin wave, since this is necessarily right bounded, and must, instead, have the form of a topographically trapped edge waves. These findings were further illuminated by JOHNS and LIGHTHILL (1993). They used a simple theoretical model with uniform shelf slope to investigate the formation of anomalous sea-surface elevations remote from the position of landfall of the generating cyclone.

DAS et al. (1983) used the stretched coordinate model of JOHNS et al. (1983b) to simulate the surge generated by the 1982 Orissa cyclone. JARREL et al. (1982) made one of the most comprehensive studies of storm surges in the Bay of Bengal. They developed five models for the Sri Lanka/ India/ Bangladesh coastlines, two models for the Myanmar /Thailand coastline and one for the Andaman Islands region. The analysis areas of the models cover the coastline and the water area up to and slightly beyond the continental shelf. Based on population centers, a total of 16 tropical cyclone impact points were chosen (Table 6.29). The maximum wind speed in the calculations varies from 55 to 130 knots. The directions from which the cyclones could realistically approach the impact points are given in Table 6.29. A total of 258 runs were made for the 16 impact points. Tidal constituents M_2 , S_2 , N_2 , K_1 , O_1 and S_a were included in the models. Model provided surge heights in the case of 1977 Andhra cyclone are shown in Fig. 6.41. These model-simulated surges along the Andhra coast are in good agreement with limited available observations. GHOSH et al. (1983) applied the "SPLASH" model to compute the surge associated with 1977 Andhra and two other cyclones. They obtained a peak surge elevation of 5.7 m about 50 km to the right of the landfall. This is in good agreement with earlier calculation of JARREL et al. (1982).

Table 6.29: Angles of cyclone approach (with respect to the coast line) to be modelled for the individual impact points (JARREL, LEWIS and WHITAKER, 1982)

Impact Point	Direction from which storm approaches
Trincomalee (Sri Lanka)	SE through NE
Jaffna (Sri Lanka)	SE through NE
Negapatam (India)	SE through NE
Pondicherry (India)	SE through NE
Madras (India)	SSE through ENE
Masulipatnam (India)	SSE through ENE
Coconada (India)	S through ENE
Vishakhapatanam (India)	SSW through ESE
Berhampur (India)	SSW through ESE
Puri (India)	SSW through SE
Calcutta (India)	SW through SE
Port Blair (Andaman Is.)	S
Chittagong (Bangladesh)	SW through S
Bassein (Burma)	S through W
Rangoon (Burma)	SSE through SSW
Phuket (Thailand)	Only ESE

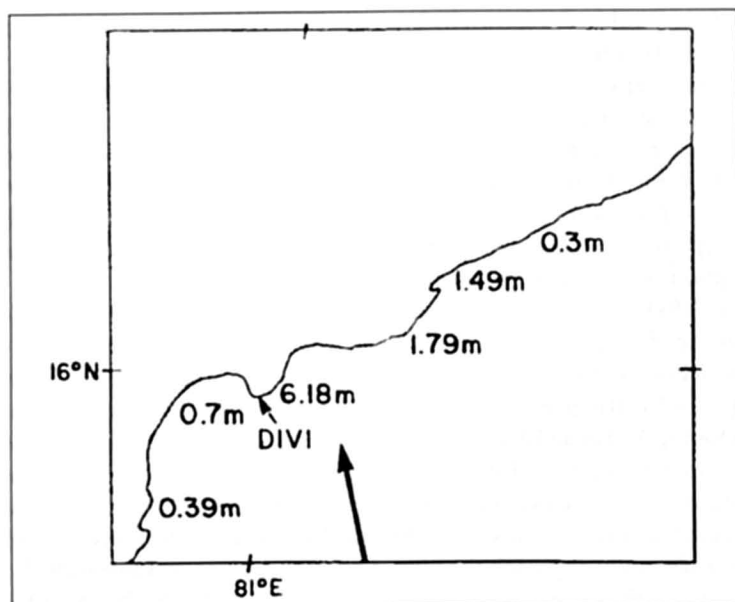


Fig. 6.41: Storm surge height distribution along the east coast of India for the November 1977 Andhra cyclone (JARREL, LEWIS and WHITAKER, 1982)

Advent of powerful personal computers has set up a trend to run storm surge models in real time on PC-based workstations in an operational office. Recognizing this DUBE et al. (1994) describe a real time storm surge prediction system for the east coast of India. The forecasting system proposed by the authors is based on the vertically integrated numerical storm surge models that were developed earlier by the group (JOHNS et al., 1981; 1983 b; DUBE et al., 1985 b). Surface winds associated with a tropical cyclone are derived from a dynamic storm model (JELESNIANSKI and TAYLOR, 1973). The only meteorological inputs required for the model are the positions of the cyclone, pressure drop and radii of maximum winds at any fixed interval of times. The model can be run in a few minutes on a PC in an operational office. The system is operated via a terminal menu and the output consists of the two-dimensional and three-dimensional views of peak sea surface elevations with the facility of zooming the region of interest. One of the significant features of this storm surge prediction system is its ability to investigate multiple forecast scenarios to be made in real time. This has an advantage because the meteorological input needed for surge prediction can be periodically updated with the inflow of data on fast telecommunication links. The model has extensively been tested with severe cyclonic storms, which struck the east coast of India during the period 1960–1990. The model results reported for three case studies (June 1982 Orissa cyclone; November 1977 Andhra Cyclone and May 1990 Andhra Cyclone) are in very good agreement with the available observations and estimates of the surge. In Figs. 6.42 and 6.43 we show respectively the track of May 1990 Andhra cyclone and model computed peak surge envelope along the east coast of India. Detailed case studies by using this model may be seen in DUBE and GAUR (1995). This version of the model was tested in near real time during the cyclone periods of 1992–1993 (DUBE and GAUR, 1995). Operational feasibility test of the model is presently undergoing at India Meteorological Department.

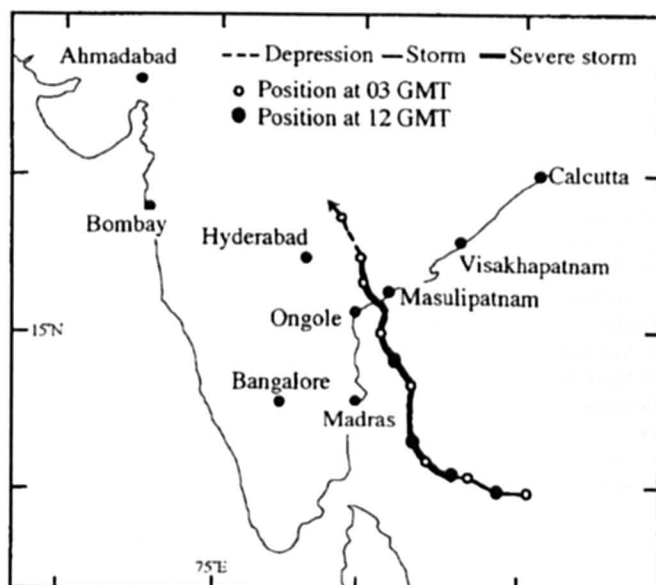


Fig. 6.42: Track of Andhra cyclone; 5–11 May 1990 (DUBE et al., 1994)

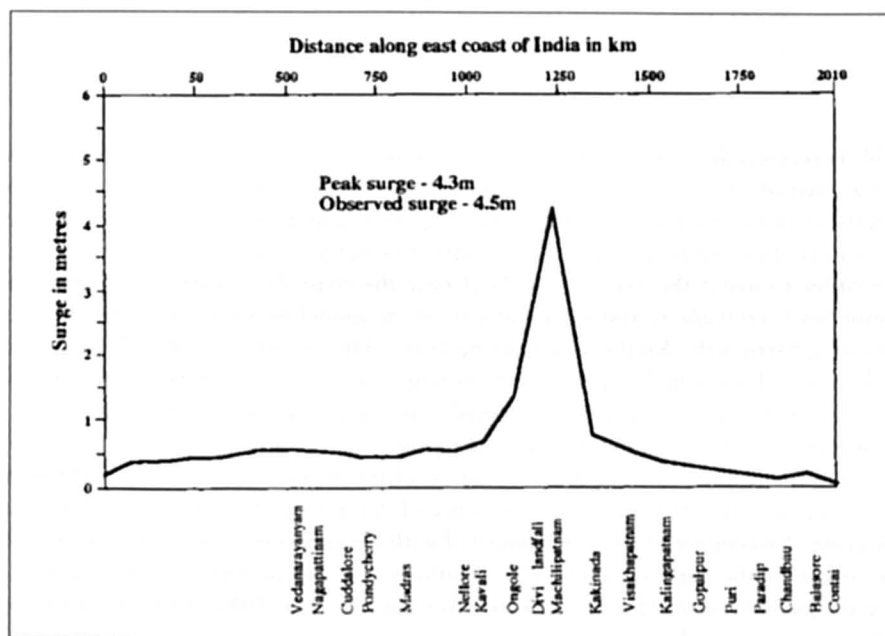


Fig. 6.43: Peak surge envelope associated with 1990 Andhra cyclone (DUBE et al., 1994)

Table 6.30: Severe cyclonic storms having potential of producing significant surges along the Andhra coast during 1895 to 1996

No.	Cyclone	ΔP (mb)	R (km)	Landfall Lat (N)	Maximum Wind Speed (knots)
1	1895 Kakinada	35	18	17.2	70
2	1906 Vizag	25	15	17.9	60
3	1921 Nellore	30	15	14.3	60
4	1925 Machili	60	20	16.1	108
5	1927 Nellore*	80	25	14.3	100
6	1940 SH	30	22	14.0	60
7	1945 Machili	50	19	16.3	90
8	1949 Machili*	60	25	16.3	110
9	1965 Vizag	30	15	17.9	62
10	1969	45	25	16.7	96
11	Kakinada*	30	15	13.8	80
12	1972 SH*	30	15	16.1	70
13	1976 Machili	28	15	14.8	60
14	1976 Kavali	80	40	15.8	135
15	1977 Divi*	26	15	14.8	55
16	1977 Kavali	60	35	14.8	100
17	1979 Kavali*	60	25	14.0	102
18	1984 SH*	26	15	14.4	50
19	1987 Nellore	26	15	15.9	50
20	1987 Machili	70	20	14.8	110
21	1989 Kavali*	80	40	15.7	136
22	1990 Divi*	30	25	13.0	75
23	1994 Madras*	35	20	16.7	90
	1996 Kakinada*				

More recently RAO et al., (1997) developed a location specific high-resolution model for Andhra coast of India, on the lines similar to that of DUBE et al. (1994). One of the important features of the model is that it uses more accurate and detailed bathymetry for the offshore waters of the Andhra Coast. A simple drying scheme has also been included in the model in order to avoid the exposure of land near the coast due to strong negative surges. Attempt has been made to test the reliability of the model by validating it for various cyclones, which struck the Andhra coast during 1891–1996. Table 6.30 list the 23 cyclones identified by the authors, which appear to have potential of producing a peak surge of more than 1m. In Table 6.31, the computed and observed peak surges and their locations of landfall have been listed for eleven cyclones for which post-storm survey surge information could be procured from the records of India Meteorological Department. Authors have used the model results to calculate the frequency of occurrence of storm surge heights at different locations of the coast. Assessment of the risk associated with a major storm surge for a given location is also made by the authors (Table 6.32). Authors also use an empirical formula given by FREEMAN and MEHAUTE (1964) and latter also used by ALI (1996), to estimate the inland flooding associated with storm surges.

Table 6.31: Comparison of observed and computed peak surge amplitude and their locations

Cyclone	Surge (m)		Location of peak surge	
	Observed/ Reported	Computed	Observed	Computed
1927 Nellore	3.0	3.07	North of Nellore	Nellore
1949 Machili	2.5	2.093	Machilipatnam	10 km N of Machilipatnam
1969 Kakinada	2.6	2.82	Kakinada	Kakinada
1972 SH	0.8-1	1.23	Sriharikota	Sriharikota
1977 Divi	5.0	4.93	Divi	Divi
1979 Kavali	3.0	3.3	Kavali	10 km North of Kavali
1984 SH	2.0	2.4	Sriharikota	Sriharikota
1989 Kaval	3-4	3.8	40 km N of Kavali	48 km N of Kavali
1990 Divi	4.5	4.41	Divi	Divi
1994 Madras	1-1.5	0.83	Madras	20 km North of Madras
1996 Kakinada	1.5	1.6	Kakinada	Kakinada

Table 6.32: Risk (%) of exceedence of storm surge heights at Divi (Zone 'G')

Years	Surge height (m)				
	≥ 1	≥ 2	≥ 3	≥ 4	≥ 5
10	50	22	20	18	8
20	75	40	36	34	16
50	97	92	67	65	36
160	99.9	99.4	89	87	59
200	99.99	99.99	98.8	98.5	83.9

Before ending this subsection we may like to refer few other storm surge studies, which have been carried out for the east coast of India. Interested readers may refer to the works of KUMAR et al. (1995), MATHEW et al. (1996), HENRY et al. (1997), MURTY and DUBE (2000), and DUBE et al. (1998, 1999a, 2000a, 2000b).

(c) Myanmar

Storm surges affecting Myanmar are to much less extent in comparison with Bangladesh and India. However, whenever a severe cyclone struck the coast of Myanmar it leaves severe damage and casualties mostly due to strong winds and storm surge floods. During the period 1884 to 1999 the Myanmar coast was affected by eleven severe cyclonic storms of which seven were associated with significant surges. Table 6.33 lists the impact of these cyclones (THAW, 1998).

During April 22-26, 1936, a severe storm struck the Kyaukpyu area and killed about 2000 people and over 7,000 cattle. Another cyclone that caused heavy loss of life and pro-

Table 6.33: Losses of lives and properties due to severe cyclone during 1884-1998

Sr. No.	Year	Month	Day	Wind Speed in m.p.h.	Damage to crop	Lives	Loss of Cattle	No. Of homes damaged	Total loss in Kyats	Point of landfall
1	1884	May	14-17	100	-	100	-	-	200,000,000	Sittwe
2	1936	April	22-26	80-100	-	2000	7000	-	200,000,000	Kyaukpyu
3	1948	October	5-8	80-100	-	-	-	-	100,000,000	Sittwe
4	1952	October	22-24	60-80	-	4	-	-	10,000,000	Sittwe
5	1967	May	7-10	80-100	-	-	-	-	30,000,000	Kyaukpyu
6	1967	October	22-24	80	-	172	656	-	100,000,000	Sittwe
7	1968	May	4-7	130	-	1037	17537	57663	800,000,000	Sittwe
8	1975	May	5-7	80-100	-	304	10191	246700	776,500,000	Parthein
9	1978	May	14-17	80-100	-	-	-	-	20,000,000	Kyaukpyu
10	1982	May	2-5	80-100	-	31	63	-	38,000,000	Gwa
11	1994	May	1-2	100-120	787 acres	10	150	2874	78,000,000	Maungdaw

erty cross the Myanmar coast near Sittwe on May 7, 1968. The cyclone generated a surge of more than 4 m with loss of more than 1000 human lives. The storm surge due to the May 1975 cyclone killed 304 people and more than 10,000 cattle and destroyed about 28,000 houses (LWIN, 1994a). In recent past a severe cyclonic storm crossed the coast of Myanmar near Maungdaw on 2 May 1994. Storm surge of 3.26 m and loss of 10 lives in addition to some damages were reported (THAW, 1998). The peak surge envelope for May 1994 cyclone is shown in Fig. 6.44.

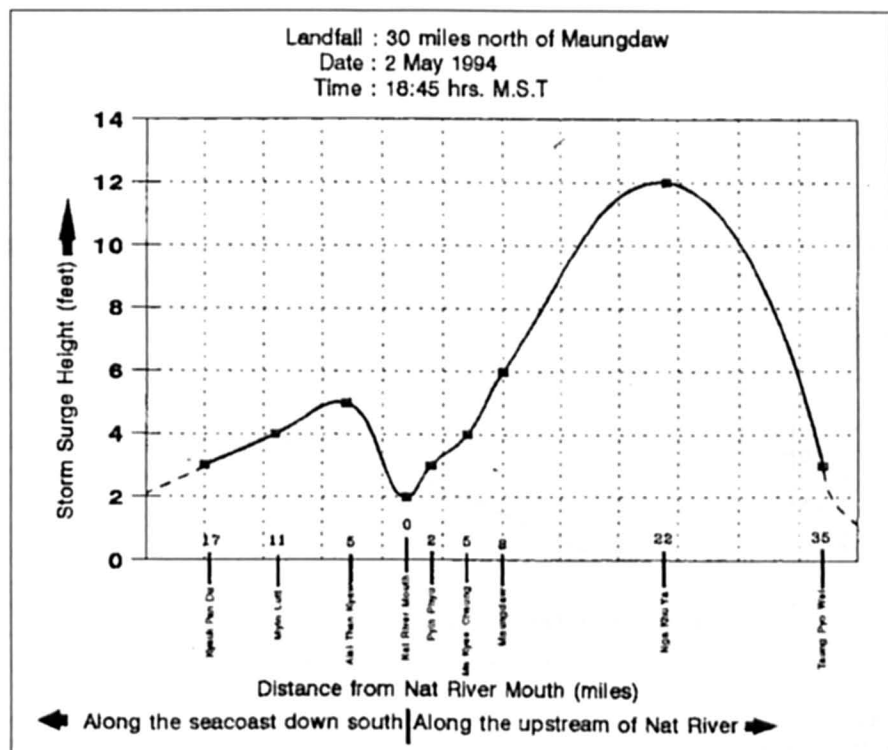


Fig. 6.44: Storm surge envelope of May 1994 severe cyclone storm in Myanmar (LWIN, 1994 a)

In Myanmar, tidal and storm surge data are available at about 10 stations beginning with 1966. The list of the tide gauges available along the coast of Myanmar is shown in Table 6.34. Rakhine coast and Deltaic region are the most favorable places for storm surge inundation. The available surge data during the last 35 years are shown in Table 6.35(a, b). Based on the available data THAW (1998) points out following salient features of storm surges affecting the Myanmar coast

- (i) For narrow coastal areas where there is no estuary, storm surge occurred on both sides of the point of landfall. But it was higher and more extensive on the onshore wind region.
- (ii) For coastal strip close to Deltaic region, the storm surge entered through estuaries over the delta, which is not directly struck by the high onshore winds of cyclone. The Patheingyi cyclone of May 1975 and Maungdaw cyclone of May 1994 are the examples. The storm surge due to the May 1975 event penetrated at least 100 km into the river system and

Table 6.34: List of available observed tidal data along the coast of Myanmar

Name of Station	Latitude	Longitude	Data available since
Kyaukpyu	19.25	93.33	1973
Thandwe	18.28	94.21	1968
Patheingyi	16.46	94.56	1973
Yangon	16.46	96.10	1953
Yangon River Mouth (Elephant Point)	16.35	96.12	1968
Mawlamyine	16.30	97.37	1965
Amherst	16.05	97.34	1967
Dawei	14.06	98.13	1972
Myeik	12.26	98.36	1966
Kawthoung	09.58	98.35	1966

caused inland flooding (LWIN, 1980). The distribution of the maximum surge along the Ayeyarwady River for the cyclone of May 1975 is given in Fig. 6.45 (CHO, 1980). The highest surge was recorded 80–90 kilometers inland. Duration of storm surge was longest where water logged. It was about 25–30 km inland (Fig. 6.46).

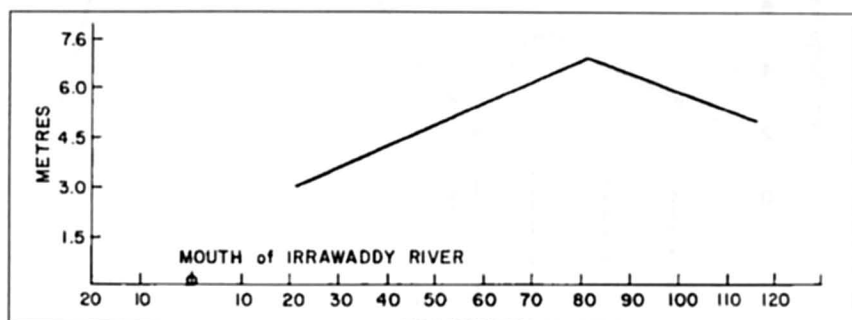


Fig. 6.45: Distribution of the maximum surge along the Ayeyarwady River for the storm of May 5–8, 1975. The ordinate is the surge amplitude and the abscissa is the distance along the river (CHO, 1980)

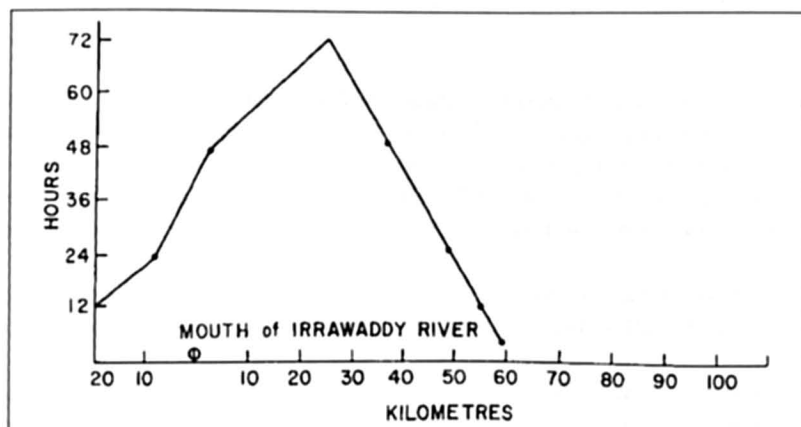


Fig. 6.46: Surge duration versus distance along the Ayeyarwady River for the storm of May 5–8, 1975 (CHO, 1980)

- (iii) For deltaic coastal strip covered by many estuaries and islands, storm surge occur with winds, which may be offshore to the general coastline. In the case of 1968 Sittwe cyclone the strong offshore easterly winds have brought in water mass from the underlying surface and inundated the whole of the area.

ODD (1980) studied the storm surges generated by May 1975 cyclone in the Ayeyarwady Delta Area of Myanmar making use of hydraulic and numerical models. He concluded that the surge amplitudes as well as the amplitude of the semidiurnal tide increase rapidly east of China Bakir because of the shallowness and funnel shape of the Gulf of Martaban.

Table 6.35 (a): List of computed and observed surge heights for rakhine coast

Year	Station	ΔP (mb)	C ($\text{km} \cdot \text{hr}^{-1}$)	Computed Surge (m)	Observed Surge (m)	E
1967	Sittwe	25	10	1.85	1.80	+0.08
1967	Sittwe	22	10	1.66	NA	NA
1968	Sittwe (Kyaukpyu)	50	11	4.05	4.25	-0.20
1976	Thandwe	20	10	1.42	NA	NA
1978	Kyaukpyu (Myabon)	34	8	2.78	NA	NA
1994	Maungdaw	43	36	3.26	3.08	+0.18

NA = Not Available

Table 6.35 (b): List of computed and observed surge heights for deltaic coast

Year	Station	V_{\max} (kt)	H_c (m)	H_o (m)	E
1975	Pathein	140	2.75	3.00	-0.25
1982	Latputta	60	0.48	0.60	-0.12
1982	Gwa	120	3.75	3.70	+0.05

LWIN (1980) developed an analytical and empirical prediction model, which is based on the combination of Miyazak's and Fletcher's equations. The empirical formula developed by LWIN (1980) relates the peak surge h (cm) with the maximum sustained wind V_m (ms^{-1}) and the angle between the normal to the coast and the direction of the moment of the storm θ . The relation is

$$h = (A + B \cos \theta) V_m^2$$

where A and B are numerical constants, whose values are determined from the historical records. The values of A and B are:

- (i) For Rakhine coast; $A = 0.0563$, $B = 0.0744$
- (ii) For the Deltaic coast; $A = 0.1264$, $B = 0.0864$.

Two precomputed nomograms, one for shallow water corresponding to deltaic coast and the other for deep water corresponding to Rakhine coast were also constructed by the author. These nomograms are given in Fig. 6.47a and 6.47b.

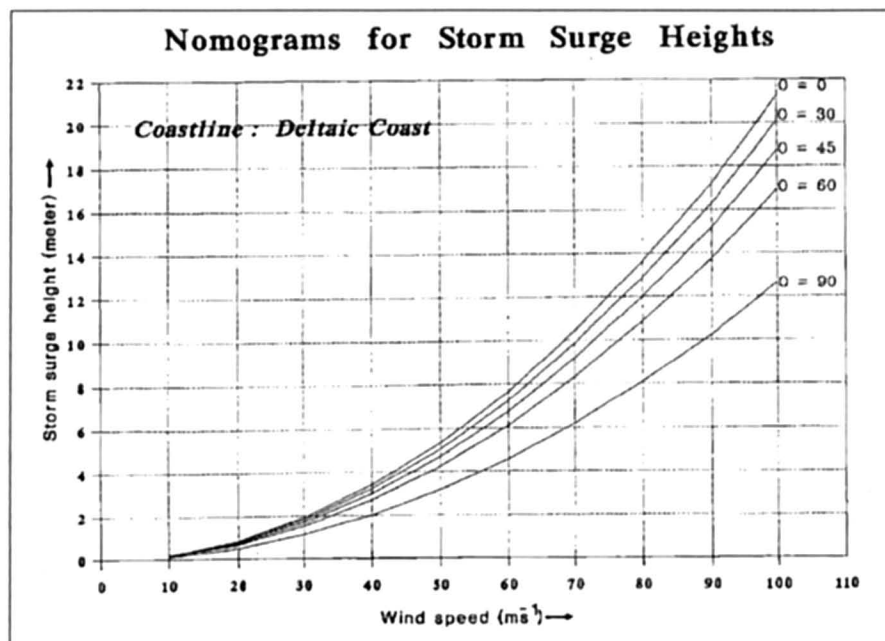


Fig. 6.47a: Nomograms for storm surge heights (deltaic coast) (Lwin, 1994b)

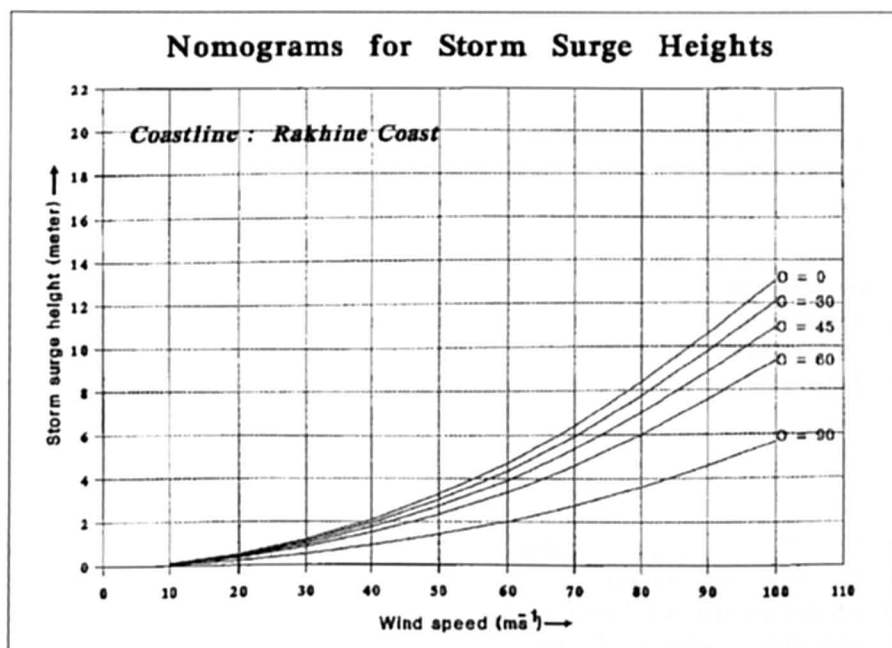


Fig. 6.47b: Nomograms for storm surge heights (Rakhine coast) (Lwin, 1994b)

As already maintained JARREL et al. (1982) developed two models for the Myanmar/Thailand coastlines. Analysis area of the models included the coastline and offshore region up to and slightly beyond the continental shelf. Three tropical cyclone impact points based on the population were chosen: Two in Myanmar (Patheingyi and Yangon) and one in Thailand (Phuket). Authors performed several runs for these impact points to assess the storm surge threat in the coastal regions of Myanmar and Thailand.

DUBE et al. (1984a) used a vertically integrated storm surge model to simulate the surge generated by May 1975 Pathain cyclone. Their model is based on fully nonlinear equations and cover the whole Bay of Bengal extending from 6° N to 22.5° N and the western and eastern sides of the analysis area are the east coast of India and Myanmar-Malaya coasts respectively. Their model produced the maximum surge in the range of 3 to 5 m in the deltaic region of Myanmar right from the mouth of Ayeyarwady to the extreme northern regions of the Gulf of Martaban. This is good agreement with the available observations.

Attempts have also been made to predict storm surges in Myanmar using different empirical and statistical techniques. The detailed review of these methods is given by LWIN (1994b). LWIN (1994a) and THAW (1998) give the detailed review of the present status of storm surge forecasting in Myanmar.

DUBE (1998b) applied a coastal zone vertically integrated numerical storm surge model to Myanmar. He performed several simulation experiments by using the data of severe cyclonic storms hitting the coastal regions of the Myanmar. He compared the simulated sea surface elevation with observations from local tide gauges where ever possible or with post storm survey estimates. The results of the experiments are in general in good agreement with reported values along the deltaic region of Myanmar. The computed peak surge envelope for May 1982 Gwa cyclone is shown in Fig. 6.48.

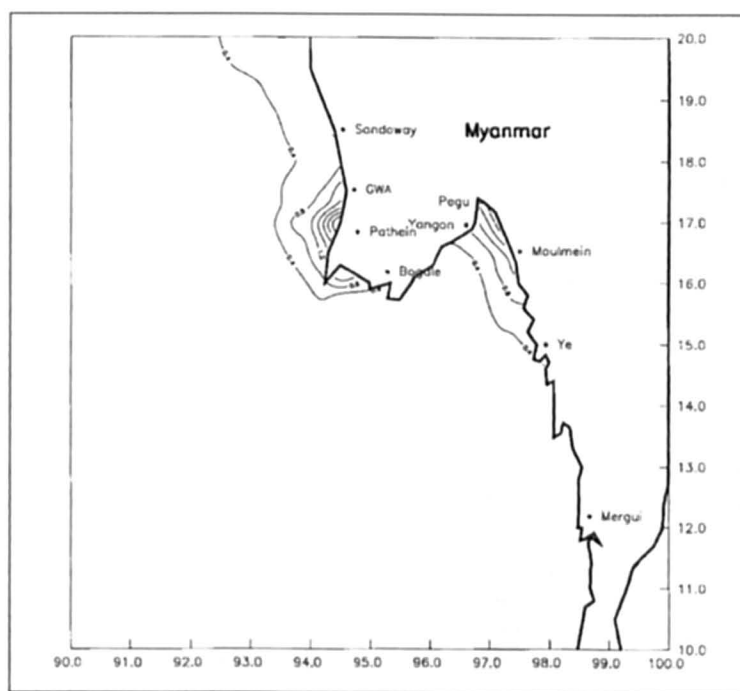


Fig. 6.48: Computed peak surge for May 1982 Gwa cyclone (DUBE, 1998b)

(d) *Sri Lanka*

Storm surges are not frequent in Sri Lanka; however major surges occurred in association with December 1964 and November 1978 cyclone. December 1964 Trincomalee/Rameswaram cyclone was one of the severest storm that affected Sri Lanka and extreme southern India peninsula. Batticaloa cyclone of November 1978 also affected southeast coast of India besides causing extensive loss of life and property in the coastal regions of east coast of Sri Lanka Table 6.36 lists the severe cyclonic storms, which formed in the Bay of Bengal during 184–1999 and crossed Sri Lanka coast. It may be seen from the table that east and north Sri Lanka coast are the most vulnerable coast for the landfall of tropical cyclones.

Table 6.36: Severe cyclonic storms of Sri Lanka

No.	Date	Location	Damage
1	8–10 March, 1907	Eastern coast of Sri Lanka	Damage estimation not available
2	17–24 December, 1964	Near Trincomalee	Damage estimation not available
3	17–24 November, 1978	Near Batticaloa	2 m surge, 915 deaths 100,000 houses damaged, At Kalkudah, the sea had entered land to distance of about 1.5 km.
4	11–17 November, 1992	Eastern coast of Sri Lanka	4 deaths, 29,116 houses damaged

Study of the storm surges in Sri Lanka has not attracted many workers. Only studies that came to our notice are by JARREL et al. (1982), RAO et al. (1994), DHARAMRATNA (1996) and CHITTIBABU (1999).

JARREL et al. (1982) developed models for Sri Lanka as a part of their major study to evaluate storm surge threat in the Bay of Bengal. They selected Trincomalee and Jaffna as the tropical cyclone impact points on the northeast coast of Sri Lanka. Several numerical experiments were performed by the authors for the cyclones of varying wind speeds approaching Trincomalee and Jaffna from SE through NE. This study may probably be considered as one of the most comprehensive study to assess the impact of storm surges on the coast of Sri Lanka.

RAO et al. (1994) developed a coastal zone numerical model to simulate storm surges and currents arriving Sri Lanka and Southern Indian Peninsula. The model is based on the conventional depth averaged equations and cover an analysis area extending from 2° N to 20° N and 72° E to 86° E. Experiments are carried out to simulate the surges generated by the December 1964 and November 1992 cyclones. The 1964 Rameswaram cyclone crossed the Sri Lanka coast about 50 km north of Trincomalee on 22 December at about 0600 UTC, Moving north westward it crossed the Sri Lanka and struck the Indian coast about 30 km to the south of Tondi on December 23 at 0600 UTC. Surges therefore occurred both on the northeast coast of Sri Lanka and southeast coast of India in association with this cyclone.

The track of the cyclone is shown in Fig. 6.49 computed maximum sea surface elevations for the landfall of the cyclone in Sri Lanka and later in India are shown in Fig. 6.50. A peak surge of 3.7 m is predicted at about 50 km north of Trincomalee (Sri Lanka) while near Tondi (India) a peak surge of 5.6 m is predicted. This is in agreement with the reported flooding and surge in the region (RAO and MAZUMDAR 1966). Very recently CHITTIBABU (1999) used the model developed by RAO et al. (1994) to simulate the surge generated by November 1978

Batticaloa cyclone. Model computed contours of peak surge elevations for the east coast of Sri Lanka and southeast coast of India are given in Fig. 6.51. The simulated surges are in good agreement with the reported maximum surge values (SRINIVASAN et al., 1978).

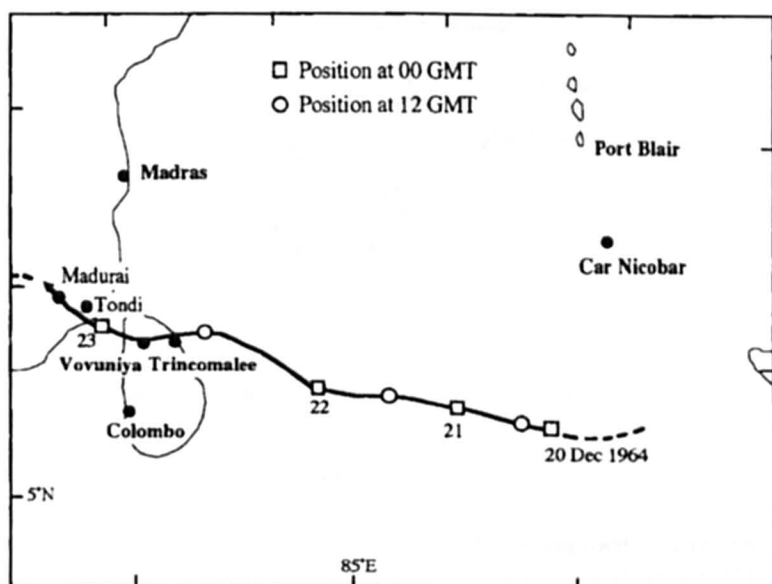


Fig. 6.49: Track of December 1964 Rameshwaram cyclone (RAO et al., 1994)

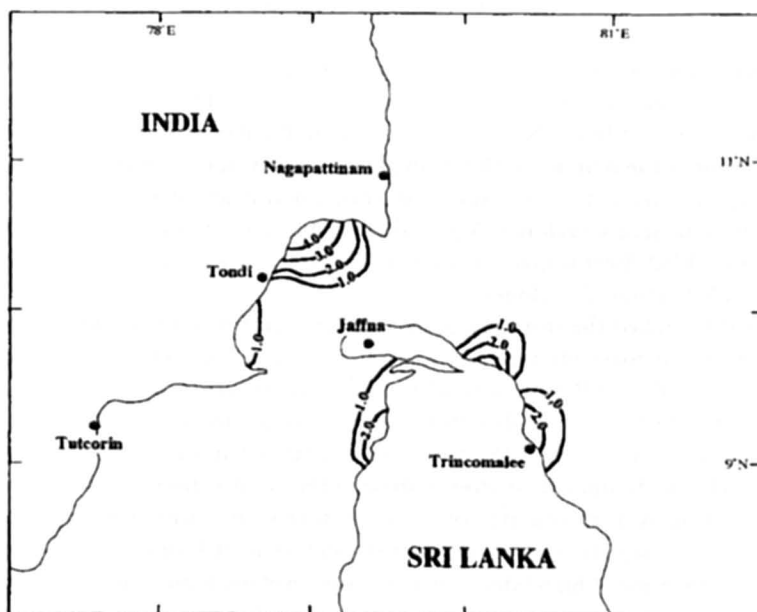


Fig. 6.50: Computed maximum sea surface elevations for the landfall of the cyclone in Sri Lanka and later in India (RAO et al., 1994)

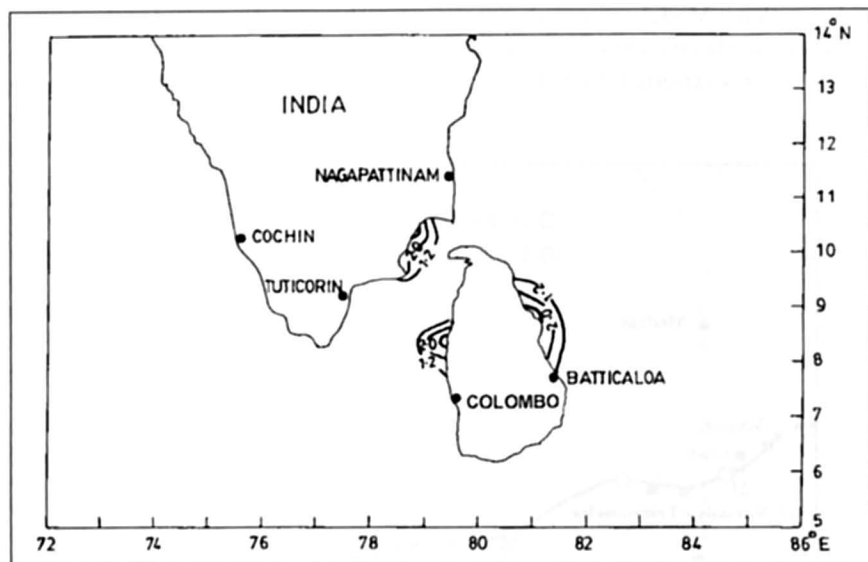


Fig. 6.51: Computed peak surge associated with November 1978 Batticaloa cyclone of Sri Lanka (CHITTIBABU, 1999)

DHARMARATNA (1996) presented the nomograms based on the model output of JELESNIANSKI (1972) for predication of the storm surges on the entire east coast of Sri Lanka. He applied these nomograms to successfully compute the surge associated with 1978 Batticaloa cyclone.

6.3.2 Arabian Sea

Although more cyclones occur in the Bay of Bengal than the Arabian Sea, there are several records of severe cyclonic storms hitting the Gujarat and the North Maharashtra regions of the west coast of India. Number of cyclones in the Bay of Bengal over a given period is about four times the number in the Arabian Sea; however, only about one quarter of the Bay of Bengal storms mature into severe storms, whereas about 40 % of the Arabian Sea storms can become severe cyclones. A partial list of major storm surges on the Arabian coast of India during 1782–1999 is given in Table 6.37. Table shows that the Gujarat coast is the most vulnerable to tropical cyclones.

RAO (1968) studied the storm surges on the Arabian Sea coast of India (and Pakistan). Classification of this coast into types A, B, and C is given in Fig 6.35. Previously, it was mentioned that on the Bay of Bengal coast of the subcontinent, there are two dangerous zones (type C). On the Arabian coast, also, there are two dangerous zones. The first one includes the Konkan coast to the north of 18° N and the coastal belt around the Gulf of Cambay.

In this belt, the frequency of storms striking the coast is low. This may be seen from Fig. 6.52, which provide the landfall of cyclonic storms on a district-wise basis. Here, the tidal range is quite large (e. g., 8 m at Mumbai. and 11 m at Cambay). Unless peak surge occurs close to the time of high tide, no major water level oscillations may occur in this belt. It should be emphasized that, even though the Arabian Sea coast experiences major storm surges much less frequently than the Bay of Bengal coast, the reason there are two dangerous belts in the manner of the classification into types A, B, and C. This classification does not

Table 6.37: List of Storm surges along west coast of India (1618-1999)

No.	Date	Location	Damage
1	May 15, 1618	Mumbai coast Maharashtra, India	2000 deaths, many vessels lost in Bombay port
2	20-21 April, 1782	Near Surat, Gujarat coast, India	Major storm surge in Gulf of Cambay, several Thousands killed, several ships grounded
3	April 18, 1847	Laccadive islands, India	1000 deaths, huge storm wave swept over several of the Laccadive islands
4	May, 1851	32 km west of Karachi	Major storm surge Karachi and environs
5	30 October-2 November, 1854	Bombay coast, India	1000 deaths
6	6-14 June, 1920	Veeraval, India	Major storm surge in Gulf of Cambay
7	9-13 June, 1964	Naliya, India	2 m storm surge at Kandla, 1.5 m at Okha, 1 m at Navlakhi, 27 killed, extensive damage
8	19-24 October, 1975	Porbandar, Saurashtra, India	85 deaths, several thousand houses damaged
9	31 May-5 June, 1976	Mahua, India	87 deaths, 4500 cattle died, extensive damage
10	13-23 November, 1977	Karwar, India	72 deaths, major storm surge Karwar and environs
11	4-9 November, 1982	Veeraval, Gulf of Cambay	542 deaths, 1,50,332 cattle killed, 12624 pucca houses and 54549 kutcha buildings destroyed. Storm surge - 3.5 m at Mangral, 2 m at Diu, 2 m at Veraval, 3 m at Jafarabad
12	12-15 Nov., 1993	North Gujarat and Sindh coast	50 fishermen missing
13	17-20 June, 1996	Between Kodiar and Diu, India	5-6 m storm surge near Bharuch. Gulf of Cambay are affected by storm surge of height 3-5 m. 47 killed. 30,000 houses destroyed
14	8-11 June, 1998	Kandla, Gulf of Kutch	550 killed, 150 kmph winds, great destruction

include the frequency of occurrence. It only deals with the maximum water level to be expected in the event of major storms, however infrequently they may occur.

The second dangerous belt stretches from Dwarka (India) to Karachi (Pakistan). This region includes the extensive marshy areas (mostly unpopulated) known as the "Rann of Kutch." In this belt, also, the frequency of storm is low and the tracks are not usually favorable for major surge development. However, on rare occasion when they do occur, storm surges several meters in amplitude could result.

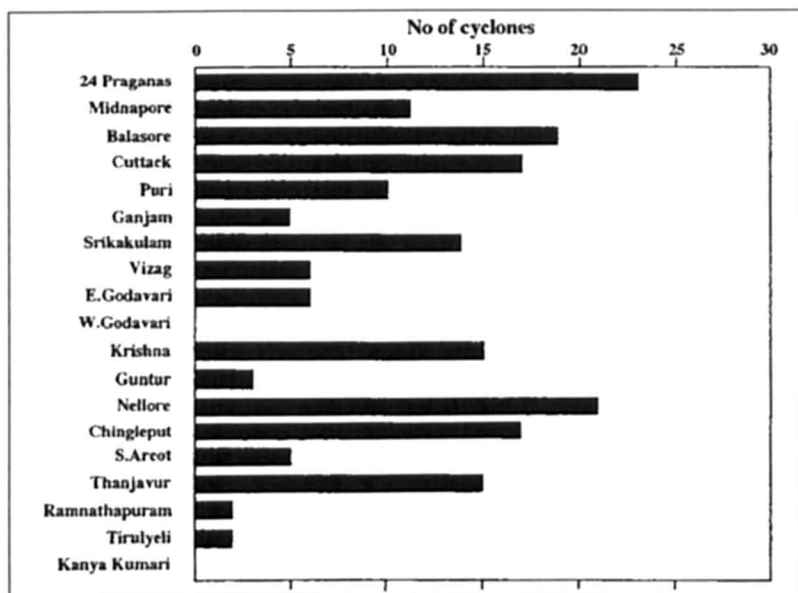


Fig. 6.52: The frequency of storms striking the west coast of India (DUBE et al., 1997)

RAO (1968) mentioned that the extensive marshlands of the Rann of Kutch are subject to large storm surges with the onset of the strong westerlies of the southwest monsoon season. The entire west coast of India south of 18° N falls into the type B category. In this area, also, the frequency of storms is low (Fig. 6.52). Also, the tracks are not generally favorable for major surge development. The coast around the Kathiawar Peninsula between Diu and Dwarak belongs to the type B category. The major surge amplitudes that can occur here are about 1.5 m and are about half the tidal range here. In this area the frequency of storms is high, but usually they are not intense (not of hurricane strength).

The peak storm surge amplitudes, maximum total water level (surge + wind waves), and the classification (into type A, B, or C) at several locations on the west coast of India and the coast of Pakistan are listed in Table 6.38. The track of the Kutch cyclone of June 1964 and the areas where surges occurred are shown in Fig. 6.53 Modeling of storm surges in the North Indian Ocean has attracted more attention to the Bay of Bengal, very few modelling studies have been carried out for the west coast of India.

GHOSH et al. (1983) have run the "SPLASH" model of JELESNIANSKI (1972) to determine storm surge envelope for the November 1982 cyclone. The peak surge computed by them is in good agreement with available estimates from observations. DUBE et al. (1985a) appears to be the among the first to use a two-dimensional fully nonlinear coastal zone numerical model to study the storm surges on the west coast of India. Their model covers an analysis area lying between 10° N and 23.2° N and between 67.8° E and 76° E. Orthogonal straight-line segments represent the coastal boundary of the west coast of India, which has the advantage of representing the Gulf of Cambay. This model has been used to simulate the surge generated by the 1975 Porbandar cyclone (Fig. 6.54a). The predicted maximum surge elevation at Porbandar compares well with the actual observations. The distribution of the predicted maximum sea surface elevations (peak surge envelope), observed surge and the time of occurrence along the Gujarat coast are given in Fig. 6.54b. It is interesting to note from the figure that the predicted peak surge of 2.2 m at Porbandar is in good agreement with the post storm

Table 6.38: Peak surge amplitude and maximum water level; (surge + wind wave) that can occur for storm with maximum winds of $40 \text{ m}\cdot\text{s}^{-1}$ on the Arabian Sea coast of the Indian subcontinent. Classification: B, total water level 2–5 m; C, > 5 m. (RAO, 1968)

Location	Favorable wind direction	Peak surge amplitude (m)	Maximum value of total water level (m)	Classification
Muthan Point (Nagercoil)	SW	1.4	2.3	B
Cochin	W	1.6	2.7	B
Calicut	WSW	2.1	3.5	B
Mangalore	WSW	1.8	3.0	B
Bhatkal	WSW	2.7	4.5	B
Panjim	WSW	1.7	2.8	B
Devgad	WSW	1.5	2.5	B
Ratnagiri	W	1.8	3.0	B
Harnaf	WSW	1.7	2.8	B
Mouth of Rajpuri River (Murud)	W	3.1	5.2	C
Mouth of Patel Ganga River	W	4.3	7.2	C
Bombay	W	1.5	4.5	B
Agashi Bay	W	4.2	7.0	C
Dahapu	W	4.0	6.7	C
Bulasar Kheri	W	4.5	7.5	C
Suvali Point	WSW	3.3	5.5	C
Mindola	WSW	5.2	8.7	C
Mal Bank	S	4.3	7.2	C
Mahuva Road	SE	2.0	3.4	B
Jafarabad	SSE	3.1	5.2	C
Diu	SSE	2.2	3.7	B
Veeraval	SW	1.5	2.5	B
Porbandar	SSW	1.6	2.7	B
Dwarka	SW	1.6	2.7	B
Balachin	W	5.1	8.5	C
Rann of Kutch	WSW	3.9	6.5	C
Wair Creek	SSW	4.0	6.7	C
Mouth of Indus River	S	3.0	5.0	C
Karachi	S	3.5	5.8	C

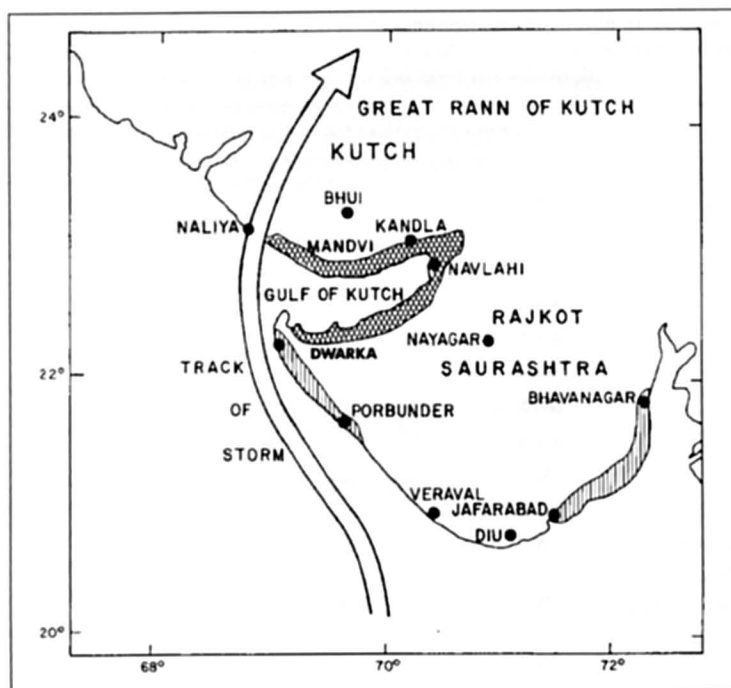


Fig. 6.53: Track of the Kutch cyclone of June 1964 on the west coast of India. Single – hatched area is affected by minor surges; double – hatched areas are affected by major surges (RAO, 1968)

survey estimated sea-surface elevation of 2.7 m (GHOSH 1981). A slightly lower elevation produced by the model has been attributed by the authors to the contribution due to astronomical tides, which was not accounted in the model. At approximately the time of the land-fall of the cyclone, the predicted value of astronomical tides was 63 cm. No other observation on the sea surface elevation was, however, available to make a comparison of the observed and predicted surge along this part of the Gujarat coast.

SINHA et al. (1984) used the numerical model developed DUBE et al. (1985 a) to simulate the surge induced by November 1982 Gujarat cyclone. During the period of this event, the estimated heights of water level above normal tide was collected during the post storm survey at certain ports (RAMA SASTRY et al., 1984). Model computed maximum surge height was found to be in good agreement with the estimated values at Veral, Diu and Jafarabad (Fig. 6.55). However, at Mangral, which is about 80 km to the left of the landfall, the predicted value is much lower than the estimated one, for which the authors could give no satisfactory explanation.

More recently CHITTIBABU et al. (2000) developed a high-resolution location specific model for Gujarat coast. Model has been used to simulate surges associated with recent cyclones hitting the coast of Gujarat.

The coastal area of Pakistan is occasionally affected by severe cyclonic storms, which form in the Arabian Sea. A partial list of severe cyclonic storms during the period 1891–1999 which made landfall on Pakistan coast is given in Table 6.39. Data on storm surges associated with these tropical cyclones are not available. However numerical simulation experiment performed by CHITTIBABU (1999) using the information available for June 1999 cyclone shows that the cyclone could have generated a minor surge on the Sind coast of Pakistan.

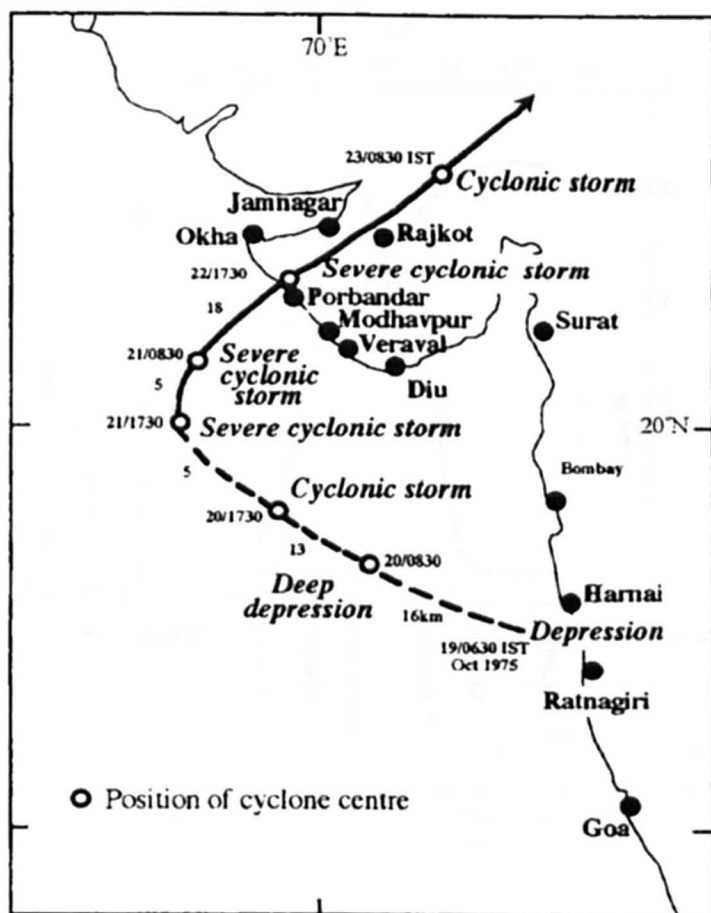


Fig. 6.54a: Path of Porbandar cyclone (DUBE et al., 1985a)

Table 6.39: List of severe cyclonic storms in Pakistan and rest of the Arabian Sea

No.	Date	Location	Damage
1	May 1851	32 km west of Karachi	Major storm surge Karachi and environs
2	25 April-5 May 1901	Makran coast	Damage estimation not available
3	7-14 May 1902	Near Karachi	Damage estimation not available
4	11-16 June 1902	Near Karachi	Damage estimation not available
5	4-6 June 1907	Near Karachi	Damage estimation not available
6	18-20 June 1920	South of Karachi	Damage estimation not available
7	5-9 June 1994	Saudi Arabian Coast	Damage estimation not available
8	15-20 Nov. 1994	Somali coast	Damage estimation not available

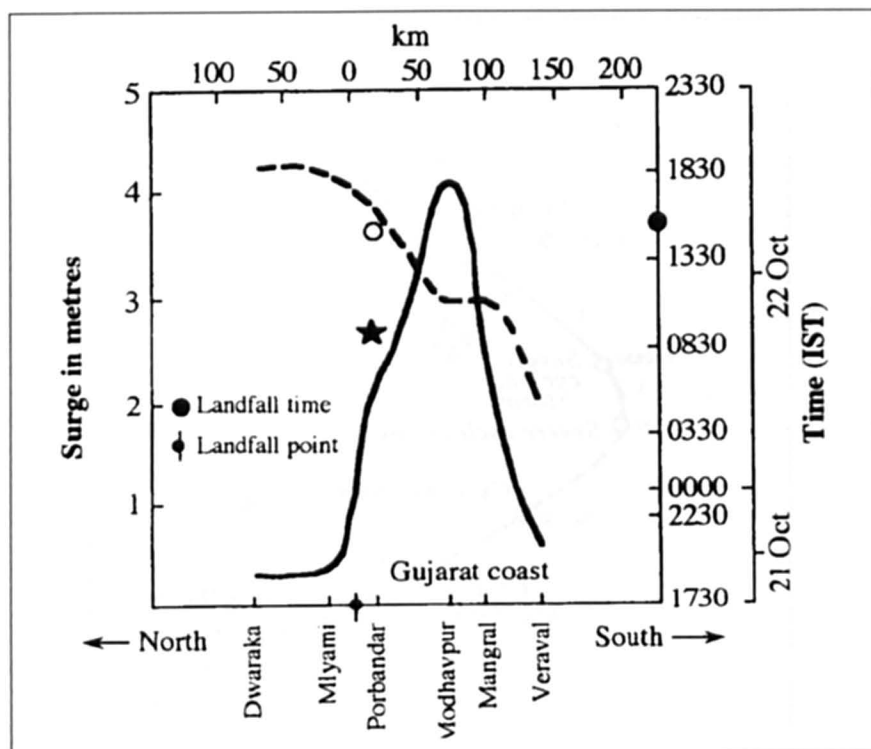


Fig. 6.54b: Maximum sea – surface elevation and time of occurrence along Gujarat coast: —, peak surge envelope; ---, time of occurrence of peak surge; *, observed storm generated surge; °, observed time of occurrence of peak surge (DUBE et al., 1985)

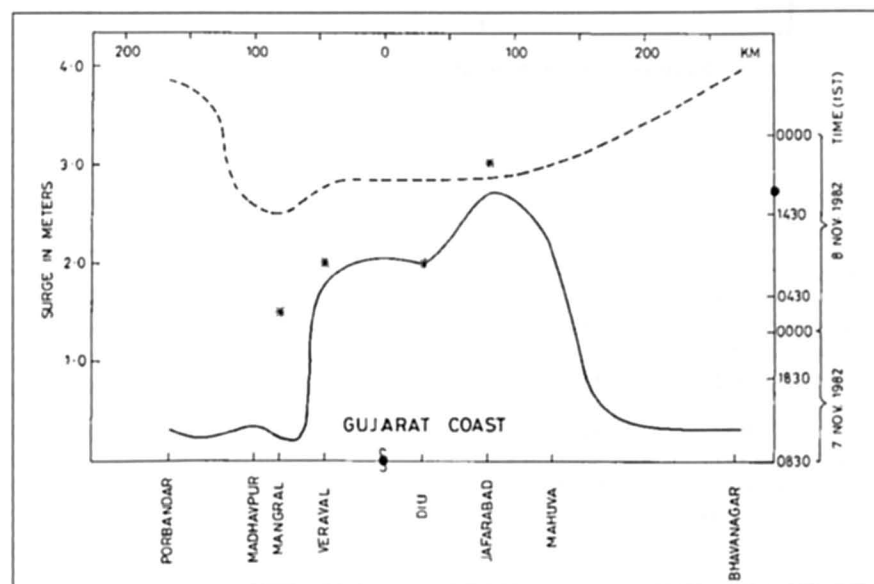


Fig. 6.55: Maximum sea surface elevation and time of occurrence along Saurashtra coast (SINHA et al., 1984)

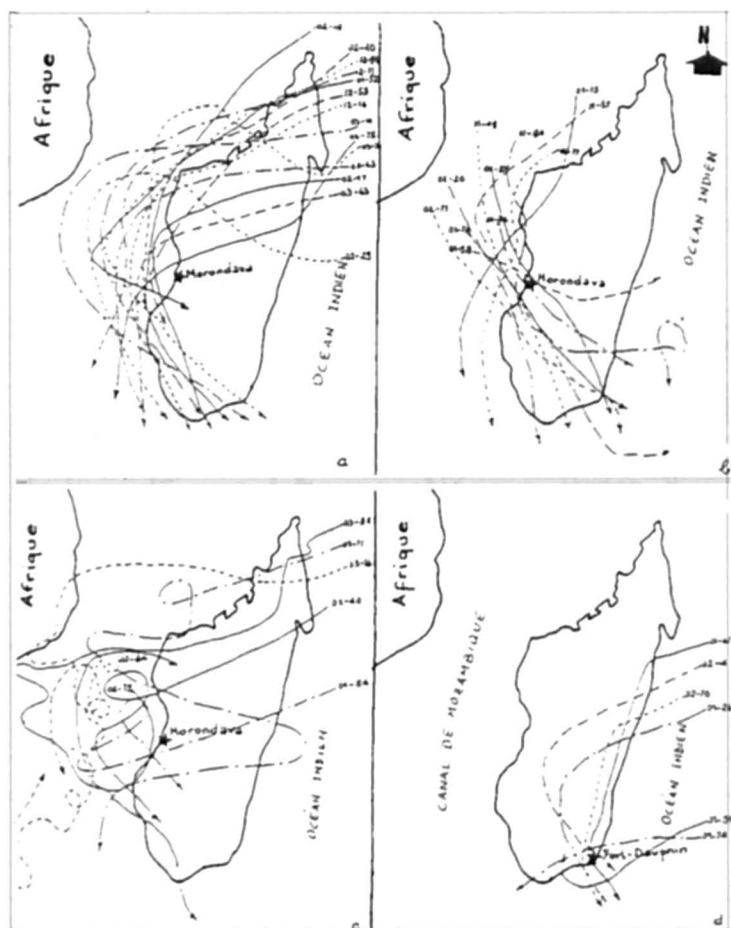


Fig. 6.57: Track of cyclones that influence Morondava and Fort-Dauphin, (a) cyclones from the Indian ocean influencing Morondava, (b) cyclones from the Mozambique channel influencing Morondava, (c) cyclones with complex trajectories influencing Morondava, (d) cyclones influencing Fort-Dauphin (BATTISTINI, 1964).

Earlier, it was mentioned that tropical cyclones travel nearby and sometimes traverse Malagasy Republic. The only study this author could find on the storm surges in this region is by LACOUR (1935). In principle, storm surges could occur along the long east and west coasts of this island (about 1500 km in length). However, favourable cyclone tracks usually generate surges on the east coast of this island, where the tidal range is small (less than 80 cm).

Storm surges appear to be more frequent on the east coast than on the west coast. Also, surges on the east coast are more important south of Tamtave than north of it. Although surges are more frequent on the east coast the amplitudes usually are rather small (20 cm or less). However, the March 1927 event near Tamtave was a major surge and caused some destruction. Major surges could occur at Tuléar on the southern part of the west coast (e.g., the event of January 1933). DAS et al. (1978) stated that cyclonic storms in the Island of La Réunion in the South Indian Ocean often produced exceptionally heavy rain accompanied by surges of 4.6 m have been reported from this island.

Table 6.40: Cyclones affecting Madagascar (RASOANILANA, 1997)

Date	Name	Wind Speed (KPH)	Central Pressure (hPa)
23-24 Dec 1974	Adele		
2-21 Jan 1975	Camille	200	-
1 Feb	Fernande	200	-
12-29 Jan 1976	Danae	240	965
27 Mar-10 April 1976	Gladys	100	-
23 Jan 1977	Domitile	120	992
28 Jan-5 Feb 1977	Emilie	130	980
17 Feb-3 Mar 1977	Herves	108	986
23-25 Jan 1978	Georgia	96	992
10-13 Feb 1978	Irena	200	985
16-31 Dec 1978	Angele	194	958
4-12 Feb 1979	Dora	-	-
10-13 Jan 1980	Gudule	68	1002
28 Dec 1980	Edwige	-	998
1st Jan 1981			
17-25 Feb 1981	Iadine	180	991
31 Jan-5 Feb 1982	Electre	95	997
16-27 Mar 1982	Justine	135	957
9-16 Jan 1984	Elinah	-	-
5-10 Jan 1984	Caboto	43	-
18 Jan-2 Feb 1984	Domoins	100	-
1985-1986	Alifredy	58	-
	Berobia	58	-
	Gista	120	-
	Honorine	120	-
1987-1988	Calidera	-	-
	Doaza	-	-
9-17 Jan 1989	Calasanjy	133	980
1989	Iana	150	-
16-19 Feb 1991	Cynthia	113	979
25 Dec 1991	Bryna	65	1002
10 Jan 1992			

6.5 South East Indian Ocean

By South East Indian Ocean, we mean the northern part of the West Coast of Australia, which is subjected to storm surges generated by tropical cyclones, HUBBERT et al. (1991) numerically modelled. Tropical cyclone generated storm surges on the northern part of the Australian coastline. Fig. 6.58 shows the tracks of four hurricanes that made a landfall in the study area. Out of these hurricanes Jason Winifred and Aivu struck the Pacific coast of Australia (these will be considered in section 6.6) and Hazel made landfall on the Indian Ocean coast of Australia. In this section, we will consider only the Indian Ocean coast.

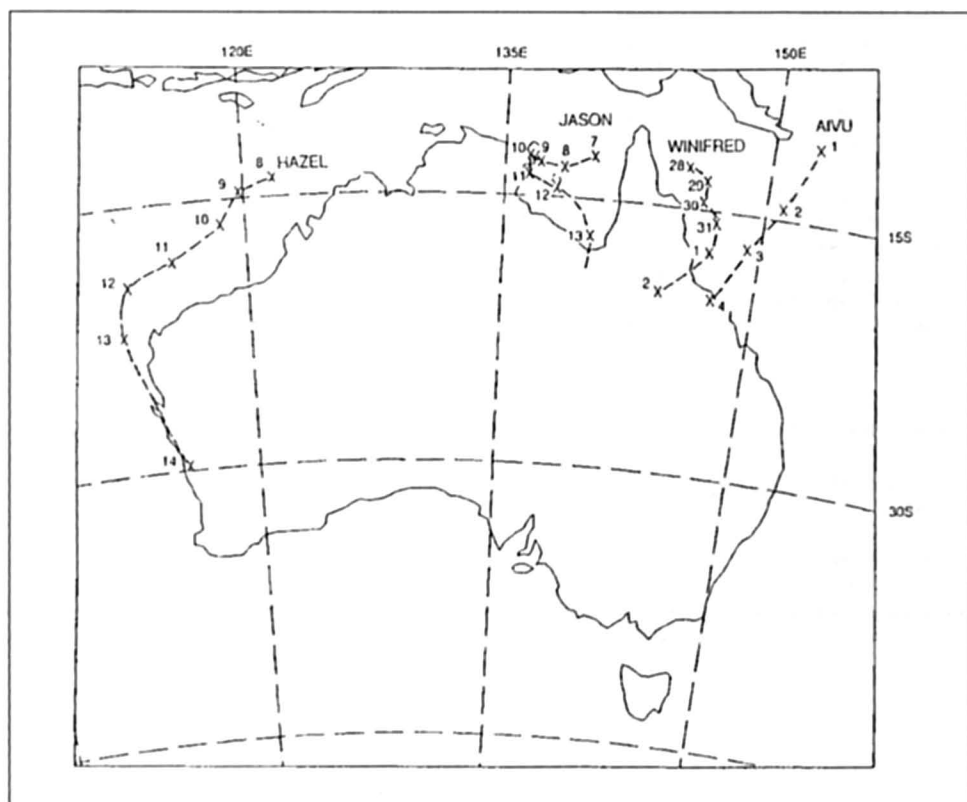


Fig. 6.58: Tracks of the four tropical cyclones (Winifred, Aivu, Jason and Hazel) used in this study. 00 UTC times and dates are shown (HUBBERT et al., 1991)

6.5.1 Numerical Model and Results

The two-dimensional depth-averaged model of HUBBERT et al. (1990) was used in conjunction with HOLLAND'S (1980) analytical-empirical model to derive the atmospheric pressure and wind fields at sea level. This model requires only the positions of the hurricane centre, the cyclone intensity and the radius of maximum winds (RMW).

The error in the numerical model for the prediction of surge elevations is 0.1 m to 0.2 m and the arrival times of the surge waves on the coast have atmost an error of one hour. The model includes such second order effects as coastally trapped edge waves.

When a tropical cyclone moves with the coast on the left (Southern Hemisphere) near to the propagation speed of a coastally trapped wave, resonant amplification of the sea surface elevation can occur, which is referred to by JELESNIANSKI (1967) as "Resurgence". This is a particular problem for the West Coast of Australia, where conditions for such resonant amplification are met. FANDRY et al. (1984) showed that the resulting surface elevation could propagate for thousands of kilometres and can cause inundation even at vast distances.

Hurricane Hazel attained a lowest central pressure of 936 hPa as it approached Carnarvon with an RMW of 30 km. As Hazel moved obliquely towards the coast, a region of positive surge developed first. A region of negative surge then formed and moved ahead of the amplifying positive surge wave, with the zero line staying slightly ahead of the cyclone position.

Fig 6.59 shows the contours of the water level at time of maximum surge at the Carnarvon. Significant amplification of the surge wave occurred in Shark Bay with amplitudes greater than 3 m. A second branch continued to propagate down the coast, resonating with the

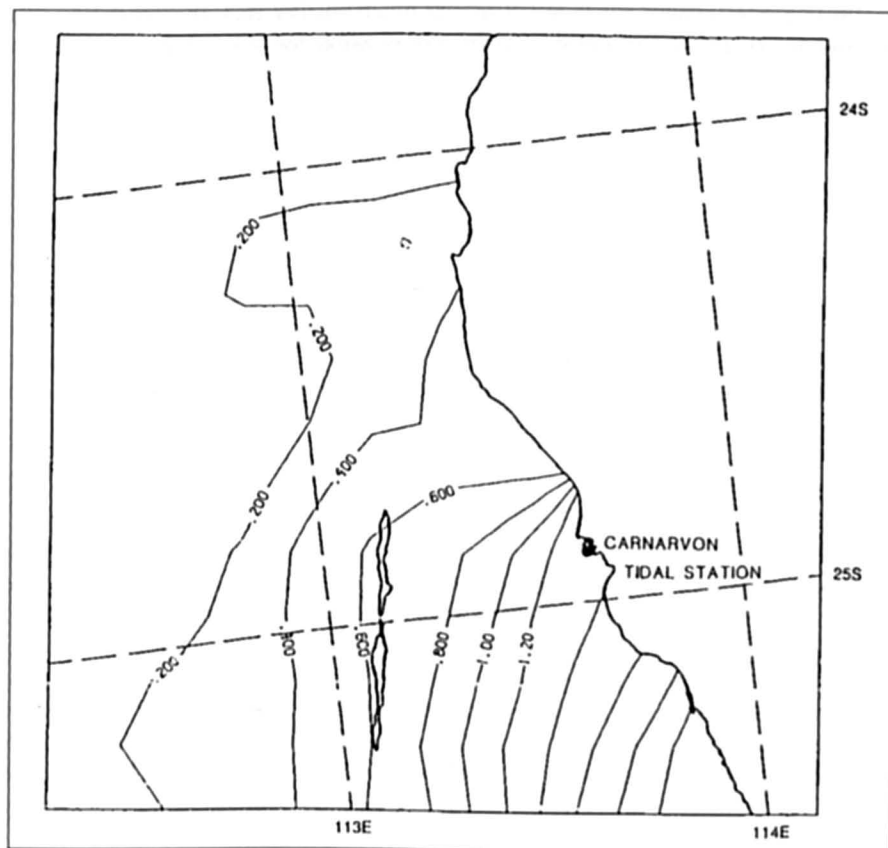


Fig. 6.59: Model results at the time of peak Carnarvon surge for tropical cyclone Hazel (14 UTC, 13 March 1979): (a) Sea surface elevations (m), and (b) depth - integrated currents (cm s⁻¹) (HUBBERT et. al., 1991)

developing Hazel. After the cyclone rapidly weakened after landfall, the second branch evolved into a freely propagating coastally trapped wave, with amplitude of about 10 cm. Table 6.41 summarises the errors.

Table 6.41: Errors in the results of the numerical model for hurricane Hazel

	Surge amplitude (m)		Time of Max. Surge			
	Observed	Computed	Error	Observed	Computed	Error
Carnarvon	1.3	1.3	0.0	1400	1400	0.0
Geraldton	0.7	0.6	-0.1	2100	2100	0.0

Table 6.41 shows that model results are quite accurate. However, the amplitude of the negative surge computed for Carnarvon was much greater than the observed value. Next, the authors made another simulation with a cyclone similar to Hazel but approaching the coast in a perpendicular direction near Carnarvon. Consistent with the analytical study of FANDRY et al. (1984), the maximum surge of 0.8 m was much smaller than the observed surge of 1.3 m, implying that resonant amplification was responsible for some of the surge at Carnarvon.

6.6 South West Pacific Ocean

By southwest Pacific, we mean the east coast of Australia and the coastlines of New Zealand.

6.6.1 New Zealand

Severe storm surges generally do not occur on the coasts of New Zealand. GILMOUR (1963) reported a surge of 0.78 m at Bluff Harbour; AGNEW (1966) found surges of up to 0.8 m on the west coast of the North Island during July 1965. Two cyclones in April 1972 produced surges up to 0.3 m on the east coast of New Zealand (PICKRILL, 1972). HEATH (1979) mentioned that due to the windy climate of New Zealand, departures from isostatic equilibrium are quite common.

Although storm surge amplitudes are small on the New Zealand coast, they cause considerable erosion (GIBB, 1976, 1977), e.g. in the Bay of Plenty on the west coast of the North Island and all along the east coast of the North Island (north of Auckland).

HEATH (1979) studied three storm surges: April 9–10, 1968, on the east coast of the North Island, July 30–August 1, 1975, on the east coast of the South Island, and September 11–13, 1976, on the west coast of the North Island. These three are the major storm surge events in New Zealand during the period 1968–78. The maximum surge in these events was about 0.6 m.

6.6.2 Australia

HOPLEY and HARVEY (1979) studied storm surges in Australia. They questioned the accuracy of the 12.2 m surge in Bathurst Bay in 1899 (WHITTINGHAM, 1958) and the 7.01 m surge at Groote Eylandt in 1923 (WHITTINGHAM, 1958). However, they mentioned that several surges with amplitudes greater than 3 m occur in eastern Queensland, Gulf of Carpentaria, and western Australia. These authors used the JELESNIANSKI (1972) scheme to compute the amplitudes of the surges. The maximum surge height h_c was calculated from

$$h_c = h_s \frac{V_p}{87} F_D \quad (6.70)$$

where, h_s is the precomputed surge height based on cyclone parameters (see the SPLASH model of JELESNIANSKI 1972), V_p is a correction factor based on maximum wind field and pressure drop, and F_D is a depth correction factor for local bathymetry.

Surge amplitudes are generally small on the Australian coastline, with the highest levels usually occurring on the Queensland coast, particularly south of Fraser Island. Storms moving parallel to the west and east coasts of Australia produce edge waves. It is observed that these edge waves tend to amplify the crest of the surge waves on the west coast of Australia, whereas on the coast of Queensland, they tend to amplify the trough. Negative surges also predominantly occur on the Queensland coast.

Storm surge profiles at several locations along the Australian coast are shown in Fig. 6.60. The maximum surge (3 m) in this diagram was at Townsville due to Cyclone Althea during December 22–25, 1976. HOPLEY and HARVEY (1979) analysed the contributions from the forerunner, effects of wind stress and pressure gradients, and semi-diurnal tides to the total

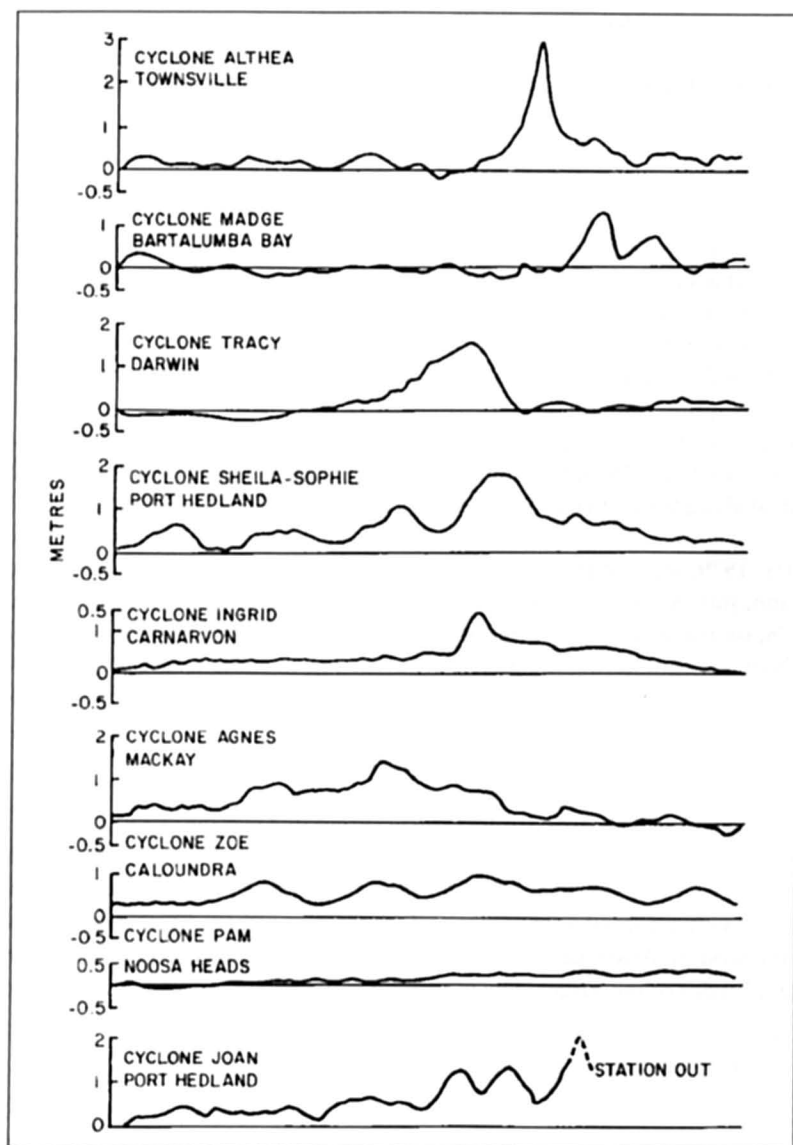


Fig. 6.60: Storm surge profiles at some locations due to selected hurricanes on the coast of Australia. Total length of the abscissa is 72 h, with the exception of cyclone Tracey, for which it is only 18 h. (HOPLEY and HARVEY, 1979)

water level during storm surge events for six regions of Australia. These results are summarised in Table 6.42.

These authors also calculated the peak surge occurrence probability curves for 19 locations around the northern coast of Australia. Brisbane and Noosa have the lowest surge risk. Two locations with the greatest surge risk are Townsville and Karumba. These results, however, change somewhat when one superimposes the tide on the surge. The greatest risk will then be at Miller Bay, followed by Carnarvon, Townsville, and Centre Island. These surge risk results are summarized in Table 6.43.

Table 6.42: Percentage contribution of various factors to the total water during storm surge events in Australia (HOPLEY and HARVEY 1979)

Region	No. of surges analyzed	Forerunner	Wind and pressure	Semidiurnal	24-h diurnal tide	Other sources
South Queensland	22	40.4	31.5	14.1	10.0	4.0
North Queensland	28	27.1	29.1	23.8	10.9	9.1
Gulf of Carpentaria	15	29.1	44.1	3.9	23.8	—
Northwest (Broome-Darwin)	4	15.7	31.4	37.2	4.7	9.0
Central Western Australia (Port Hedland Carnarvon)	8	50.3	25.5	9.7	5.8	8.7
Southwest Australia	7	74.5	14.7	1.3	3.2	6.3

* Without Melville Bay.

Table 6.43: Maximum surge heights (m) that can occur in 10,100, and 1000 yr at any point along a 100-km coastline centered at specific locations on the coast of Australia (HOPLEY and HARVEY, 1979).

Station	10 yr	100 yr	1000 yr
Brisbane	0.15	0.43	0.73
Noosa	0.20	0.50	0.83
Bundaberg	1.40	2.80	4.15
Gladstone	1.30	2.50	3.78
Mackay	1.40	2.40	3.40
Townsville	1.45	3.25	4.90
Cairns	1.03	1.78	2.55
Thursday Island	1.25	2.50	3.70
Weipa	0.60	1.30	2.00
Karumba	2.25	3.20	4.15
Center island	1.41	2.22	3.00
Milner Bay	1.40	2.25	3.15
Melville Bay	1.50	2.40	3.30
Darwin	1.65	2.30	2.90
Wyndham	1.50	2.73	3.60
Broome	1.10	1.75	2.38
Port Hedland	1.50	2.78	3.70
Carnarvon	0.80	1.46	2.10
Geraldton	0.60	1.15	1.64

NELSON (1975) listed 30 major tropical cyclones that caused surges of amplitudes of at least 0.5 m on the north coast of Australia during the period 1880–1970. Hurricane Tracey of December 25, 1974, did great damage near Darwin. DAS et al. (1978) pointed out that although the central pressure was as low as 955 mb and wind gusts attained $200 \text{ km} \cdot \text{h}^{-1}$, the peak surge was only 1.6 m. RUSSEL (1898) reported that storm surges passing over the Bass Strait. These surges contained waves with periods of about 26 min. Similar phenomena occurred in Lake George. TRONSON and NOYE (1973) developed the statistical models for the Adelaide area were considered.

MACKEY and WHITTINGHAM (1956) studied the storm surges at Port Hedland on the northwest coast of Australia for the events of November 14–20, 1955, and February 24–March 2, 1956. The observed and predicted tides and the observed surge for the latter case are shown in Fig. 6.61.

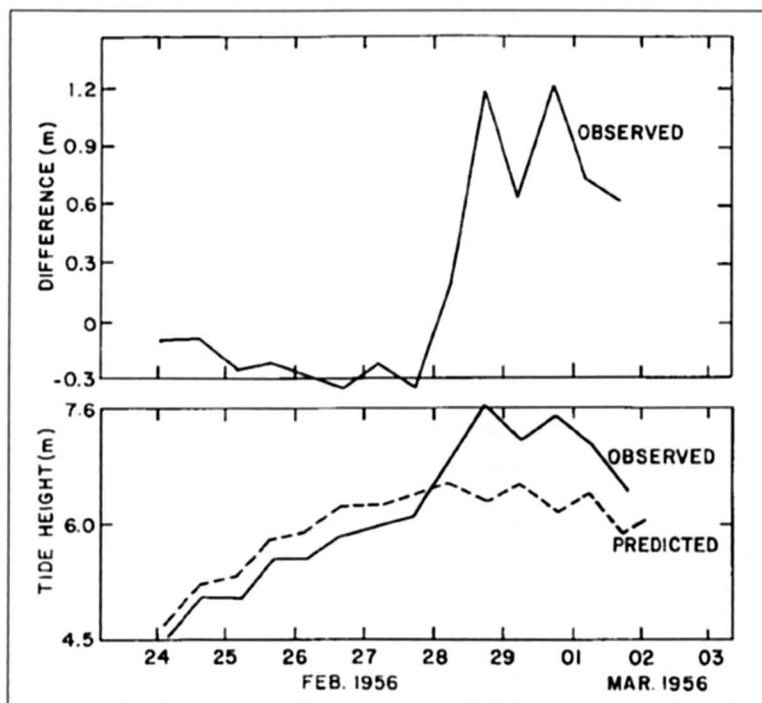


Fig. 6.61: Observed surge (top) and observed and predicted tides (bottom) at Port Hedland on the northwest coast of Australia during February 24–March 2, 1956 (MACKEY and WHITTINGHAM, 1956)

HUBBERT et al. (1991) numerically modelled the storm surges from three tropical cyclones on the East Coast of Australia. The tracks of Jason, Winifred and Aivu have been shown in Fig. 6.58.

Fig. 6.62 shows the surface pressure field for Winifred derived from the HOLLAND's (1980) model and Fig. 6.63 shows the surface wind field computed from the same model. Fig. 6.64 shows the surge amplitude for hurricane Winifred. Fig. 6.65 shows the surge amplitude for hurricane Aivu, whereas Fig. 6.66 similar results for hurricane Jason. Table 6.44 lists the errors in the results of the numerical model.

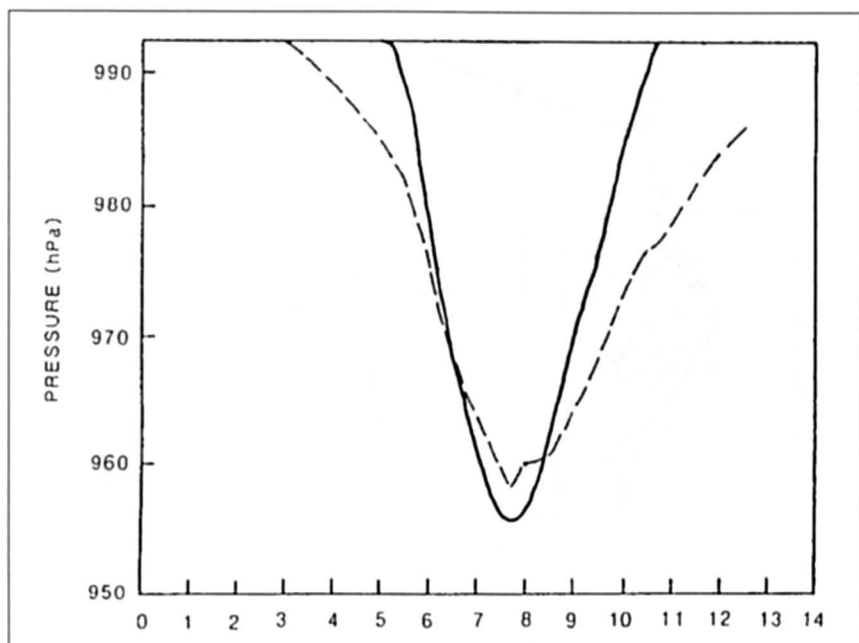


Fig. 6.62: Surface pressures and wind speeds for tropical cyclone Winifred (solid lines) compared with observations (broken lines) at Cowley Beach (just north of the cyclone landfall point) (HUBBERT et al., 1991)

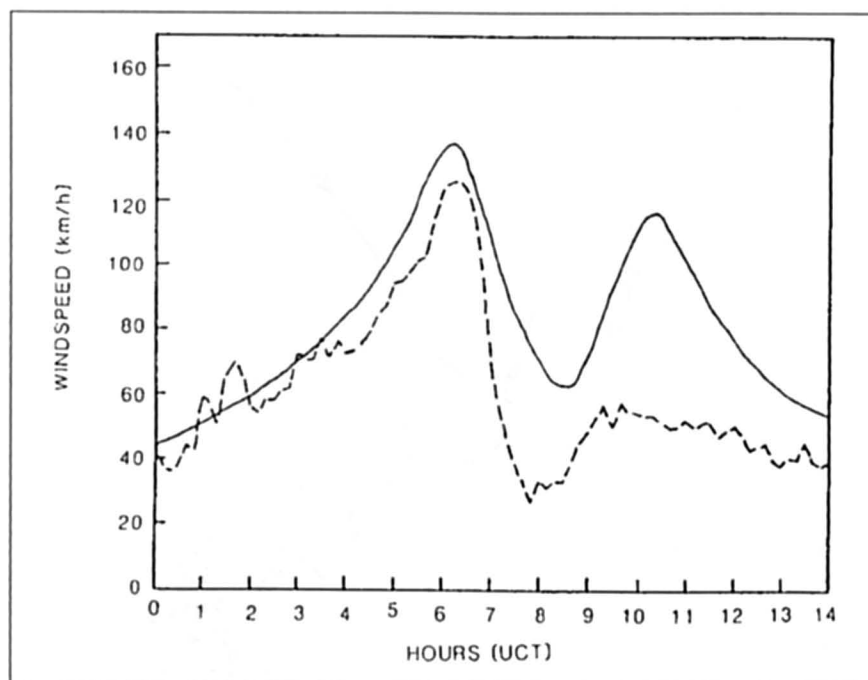


Fig. 6.63: Surface pressures derived from the Holland model for tropical cyclone Winifred (solid lines) compared with observations (broken line) at Cowley Beach (just north of the cyclone landfall point) (HUBBERT et al., 1991)

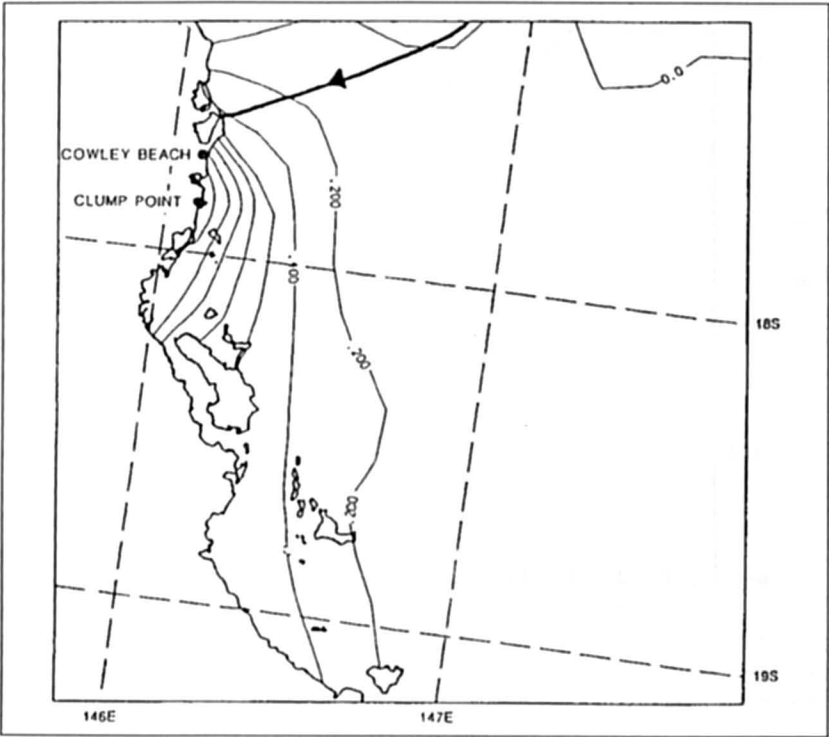


Fig. 6.64: Surge amplitude for hurricane Winifred (HUBBERT et al., 1991)

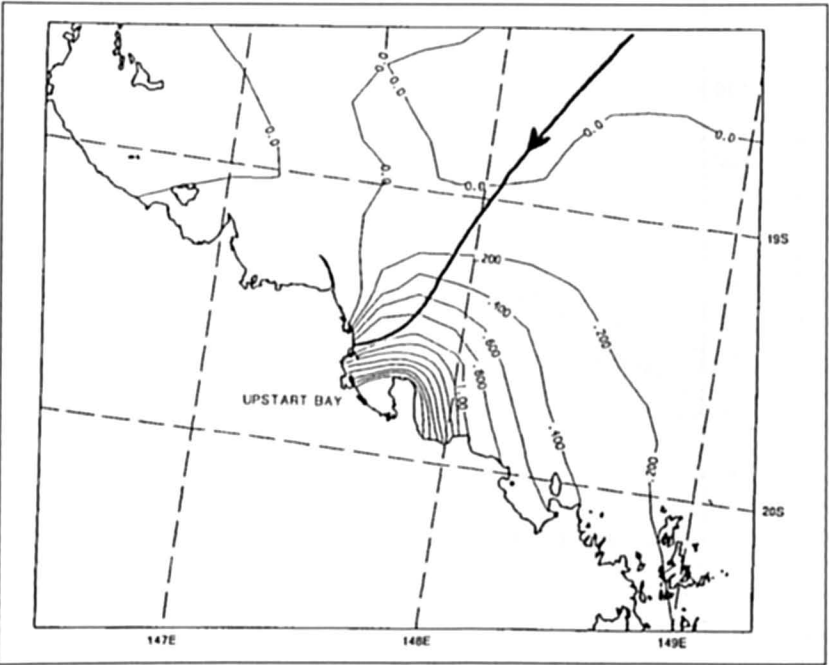


Fig. 6.65: Model results at landfall of tropical cyclone Aivu (00 UTC, April 3, 1989): Sea surface elevation (m) together with Aivu's track (HUBBERT et al., 1991)

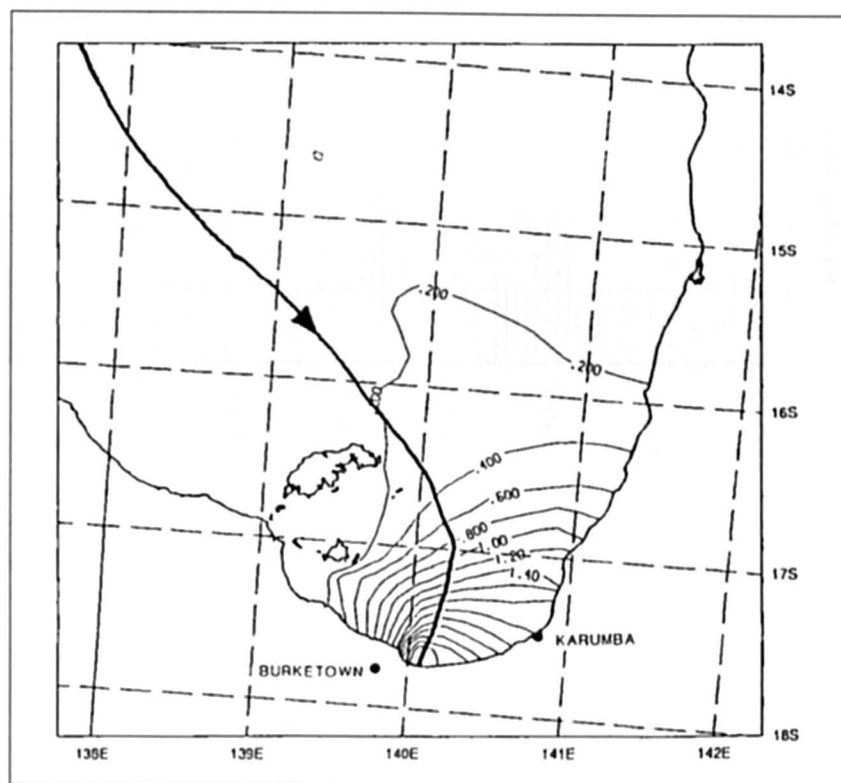


Fig. 6.66: Surge amplitude for hurricane Jason (HUBBERT et al., 1991)

Table 6.44: Errors in the results of the numerical model

Cyclone	Location	<----- Surge Amplitude (m) ----->			Arrival Time of Peak Surge		
		Observed	Computed	Error (m)	Observed	Computed	Error (H)
Winifred	Clumppoint	1.6	1.5	-0.1	0900	0900	0
Aivu	Upstart Bay	2.8	2.5	-0.3	0000	0100	1
Jason	Karumba	2.0	1.9	-0.1	0500	0400	-1
Jason	Burketown	3.5	3.3	-0.2	0500	0500	0

Fig. 6.67 shows the histogram of the number of cyclones in the southwest Pacific for the period 1920 to 1994 (BLONG, 1997) while it appears that there might have been a slight increase during 1970–1980, since then the numbers have decreased.

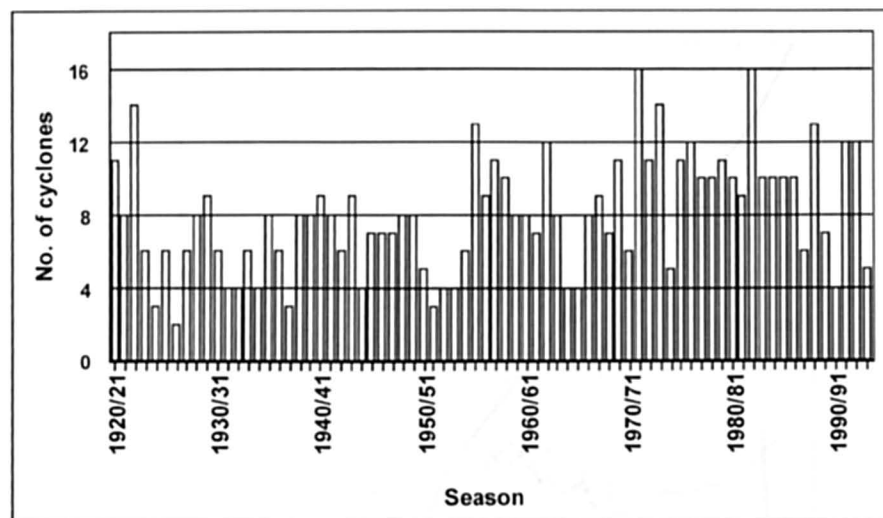


Fig. 6.67: Tropical cyclones in the South West Pacific seasonal occurrence – 1920/21 to 1993/94 (BLONG, 1997)

6.7 Western Tropical Pacific

6.7.1 Marianas, American Samoa, Solomon Islands, and Tonga

REDFIELD and MILLER (1957) mentioned that near the island of Mille in the Marianas, a storm surge of 12–15 m occurred in 1905 due to a build up of the surge in a lagoon 25 nautical miles (46 km) long.

GALLAGHER (1973) studied the nonlinear distortion produced to the tidal regime due to openings of restricted depth. He showed that the tides in the Pala Lagoon in American Samoa and the Main Lagoon on Christmas Island (in the latter case, very severely) are distorted. Similar behaviour is expected for other long waves such as storm surges and tsunamis.

GROVER (1967) studied storm surges in the Solomon Islands, which is a rare phenomenon there. Cyclones forming in the Coral Sea region and intensifying in the area south and east of the Solomons could cause surges occasionally. The storm surge of January 1952 caused some destruction on the west coast of Guadalcanal and at Malaita. The amplitude of the surge (at the time of low tide) at Honiara was about 3.5 ft (1.07 m). Winds greater than $85 \text{ mi} \cdot \text{h}^{-1}$ ($137 \text{ km} \cdot \text{h}^{-1}$) were recorded there during this event.

The surge caused serious erosion in a swath 60 m wide. Interesting topographic changes took place in the coastal waters. GROVER (1967) mentioned that some villages that withstood severe tsunamis during a half-century period were obliterated by this surge.

A major storm surge occurred during March 3–4, 1982, in Tonga Island in the South Pacific (which is located about 4025 km northeast of Sydney, Australia), and the surge amplitude was at least 1.3 m (The Citizen, March 4, 1982, Ottawa, Ont.). Winds up to $276 \text{ km} \cdot \text{h}^{-1}$ coupled with the surge caused great devastation and killed several people.

LUICK et al. (1997) studied storm surges in the so-called Pacific forum region. Fig. 6.68 shows a geographical and climatological map of the area (MCLEAN, 1995). The South Pacific region consists of the following island, nations: Cook Islands, Federated States of Micronesia, Fiji, Kingdom of Tonga, Marshall Islands, Niue, Papua New Guinea, Republic of Kiribati, Republic of Nauru, Solomon Islands, Tuvalu, Vanuatu, Western Samoa.

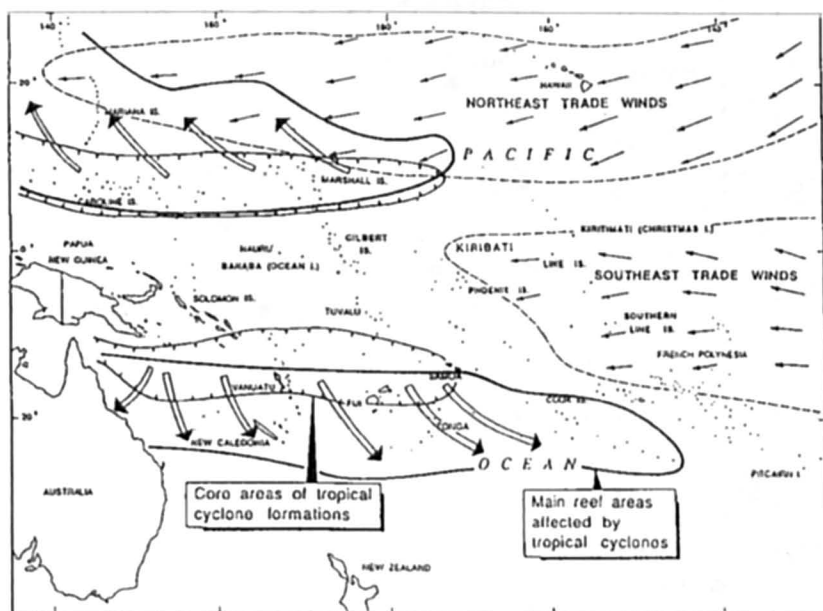


Fig. 6.68: Geographical and climatological map of the Western tropical Pacific area (MCLEAN, 1995)

The nations mainly in the western part e.g. Federated States of Micronesia (FSM) and Fiji, are subject at periodic intervals to tropical cyclones and the storm surges that are produced by them. Even though the lack of extensive continental shelves precludes the development of large amplitude surges such as those that occur in the Bay of Bengal and the Gulf of Mexico, nevertheless, moderate surges are generated. The inundation from such surges could cause problems in small islands with increased coastal erosion and salt-water intrusion into coastal aquifers.

Because of the complex topography (several small islands interspersed over a large area), traditional finite-difference models are not very applicable. Instead more sophisticated irregular triangular grid models are being developed to include not only realistic bathymetry but also the state of the tide. These finite element models were discussed earlier in chapter 3.

A map of the South Pacific Forum region (Fig. 6.69) gives the locations of the eleven SEAFRAME gauges in the region operated by National Tidal Facility (NTF) of Australia. These gauges use acoustic signals and have a precision of about 1 mm as compared to an accuracy of about 1 cm for the more traditional gauges. These gauges were placed to monitor the relative sea level changes that may be caused by the Green house warming.

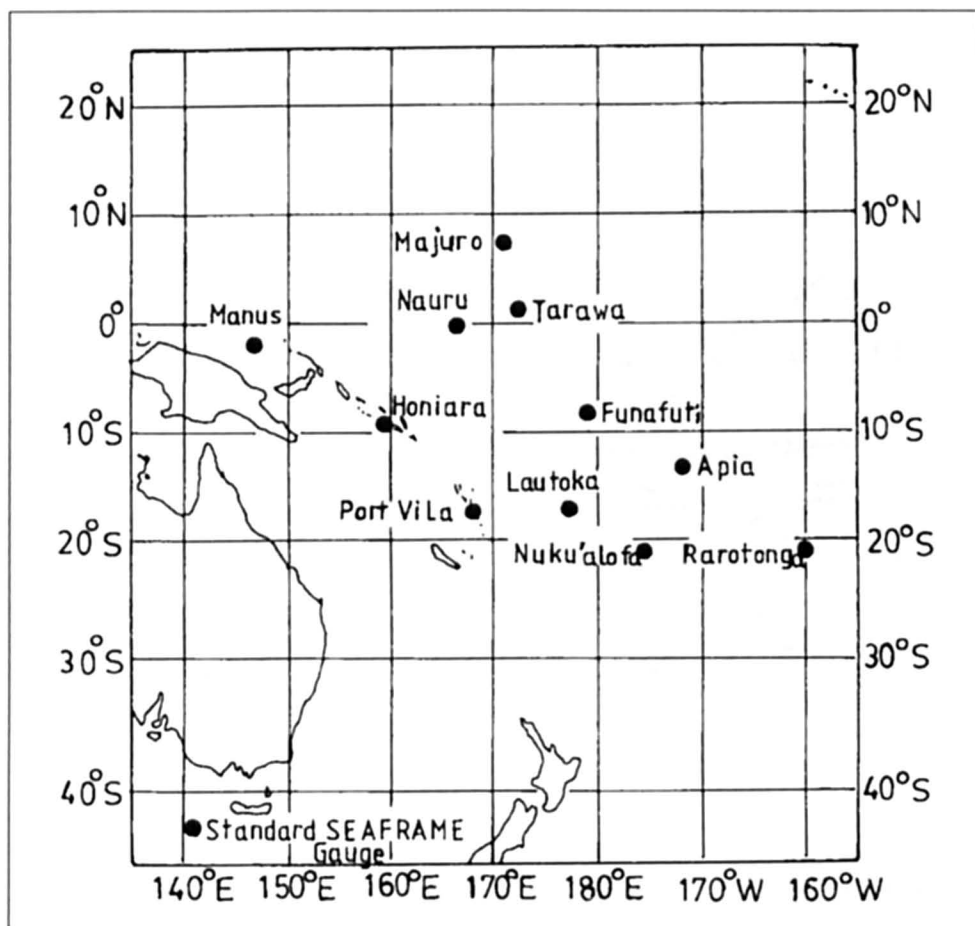


Fig. 6.69: Location of the SEAFRAME gauges in the Pacific operated by the National Tidal Facility of Australia (source: National Tidal Facility)

However, these gauges record all forms of long gravity waves, such as tides, storm surges and tsunamis. Storm surges up to one metre have been noticed occasionally in the residuals of these tide gauge records.

Fig. 6.70 shows the areas north and south of the equator where the tropical cyclones form. There is a clear break at the equator where there are none due to the absence of the Coriolis force.

Tropical cyclones in the South Pacific tend to form in the “monsoon trough” between 10°–15°S in the western South Pacific. During El Nino years the monsoon trough shifts to the east onto the Central Pacific. Very few cyclones intensify south of 20°S (due primarily to increasing westerlies in the upper troposphere).

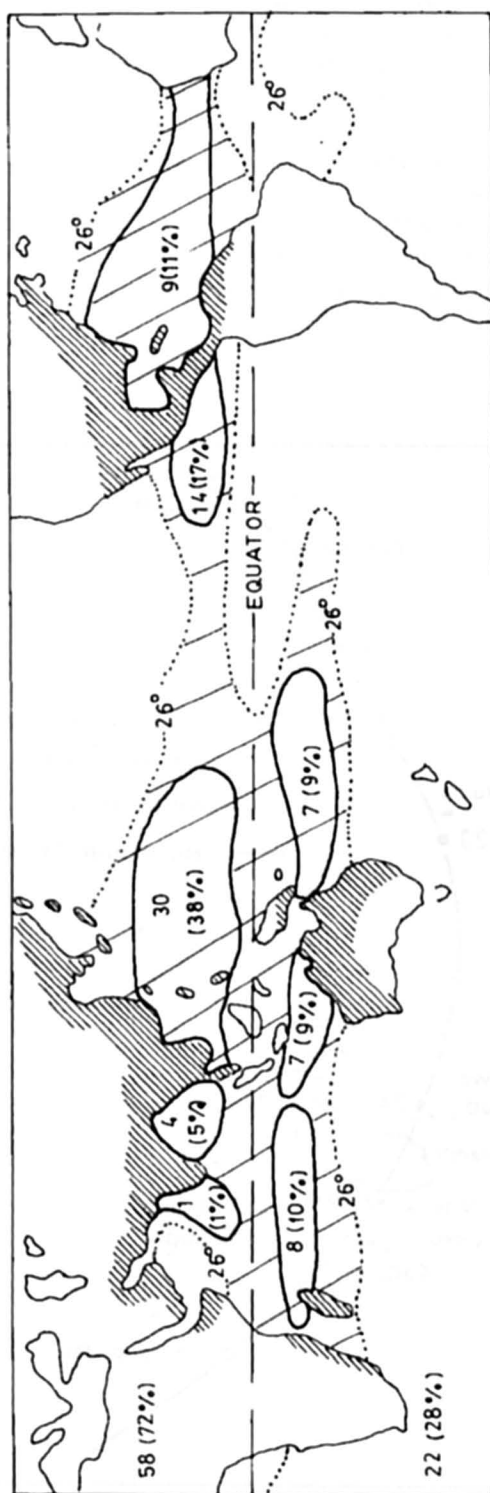


Fig. 6.70: Areas of tropical cyclone occurrence (GRAY, 1975). Land areas affected by cyclone are shown hatched (LUIJCK et al., 1997)

In the Southwest Pacific, tropical cyclones typically continue to intensify as they move southwards from their points of origin, decaying over cooler subtropical water. More than half however decay prior to reaching 30°S, while a third of tropical cyclones in the southwest Pacific eventually become extra-tropical depressions.

It is known (MURTY, 1984) that looking down the track of movement of a tropical cyclone, peak surges occur to the right of the track in the northern hemisphere and to the left in the southern hemisphere.

Fig. 6.71 shows the track of Hurricane Bebe of 1972. Even though the track is over Viti Levu, there is no coast against which the tangential wind stress can push water to the left of the track and pile it up. On the other hand, depending upon the strength of the wind field a surge could occur on the island, Vanua Levu.

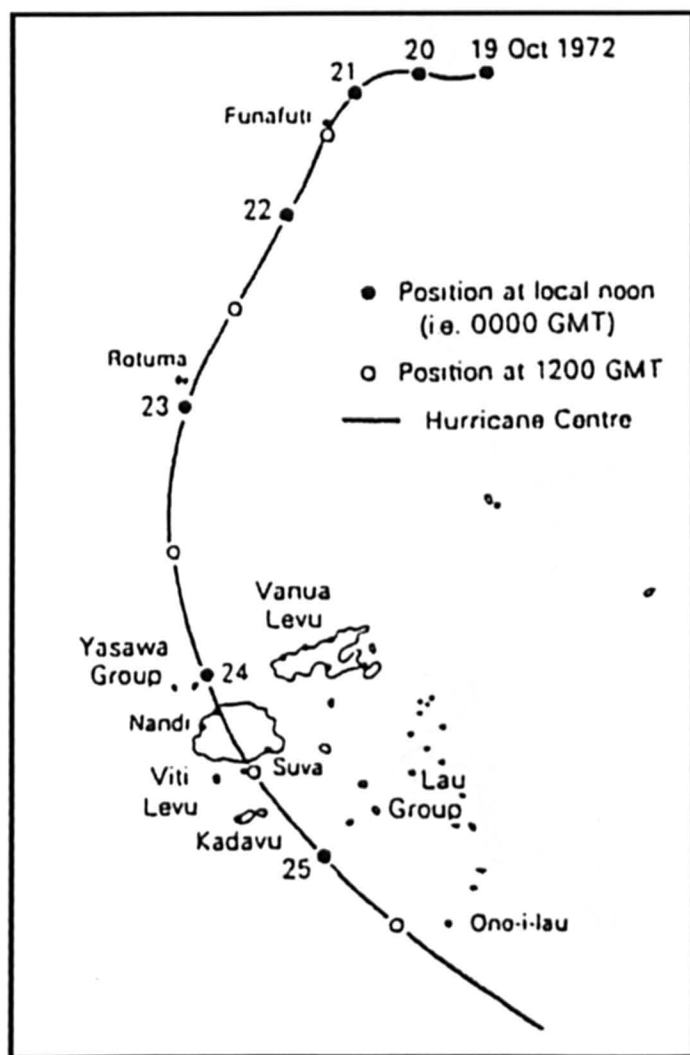


Fig. 6.71: Track of Hurricane Bebe October 1972 (from New Zealand Meteorological Service)

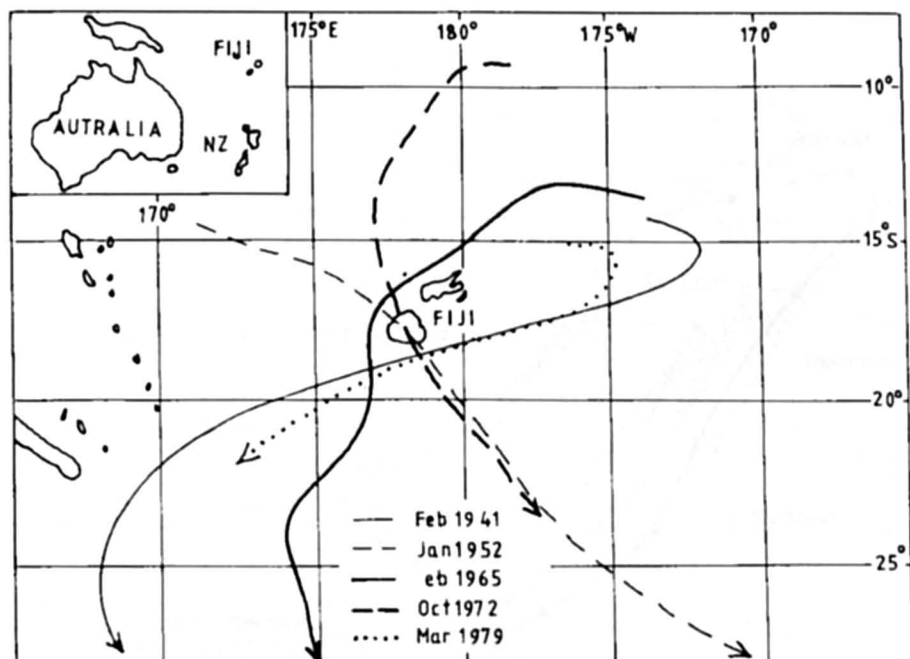


Fig. 6.72: Tracks of severe hurricanes in the Fiji area between 1940 and 1979
(from Fiji Meteorological Service)

The tracks of five hurricanes near Viti Levu are shown in Fig. 6.72. Again using the above rule of thumb, only the track for February 1965 should generate a peak surge on Viti Levu, depending upon the strength of the wind field.

Figs. 6.73 and 6.74 respectively show the tracks of hurricanes, Oscar (24th February to 2nd March 1983) and Meli (24th to 28th March 1979) impinging on the coastlines of Fiji.

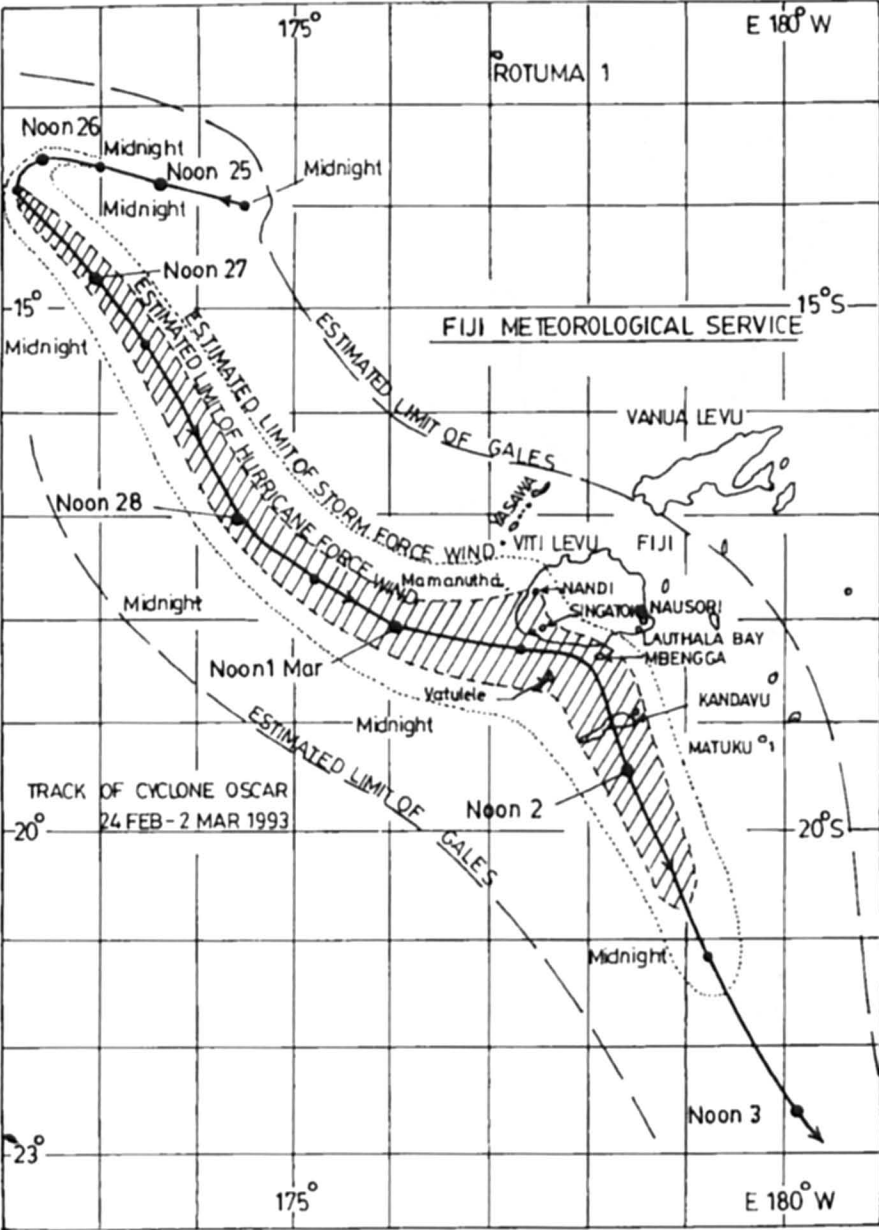


Fig. 6.73: Track of tropical cyclone Oscar, 24 February–2 March 1983 (Fiji Meteorological Service)

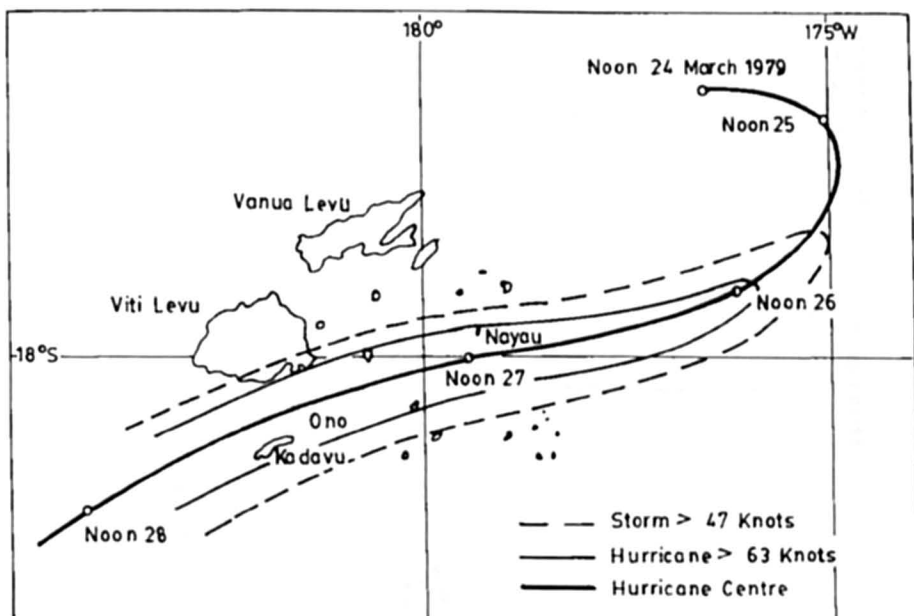


Fig. 6.74: Track of hurricane Meli and associated winds, March 1979 (Fiji Meteorological Service)

During 15–16 January 1996, a minor storm surge occurred in Tonga and was recorded on the SEAFRAME as shown in Fig. 6.75. The following information can be deduced from an examination of this figure.

Total residual or storm surge ~ 0.33 m.

Wind set-up (residual adjusted for the atmosphere pressure effect) ~ 0.18 m.

Inverse barometer effect = $0.33 - 0.18$ m = 0.15 m. Pressure drop ~ 15 hPa (hecto Pascals).

The wind set-up can be estimated roughly from the following simple calculation.

$$\frac{\partial \eta}{\partial x} = \frac{\rho_a}{\rho} \frac{C_D W^2}{gD} \quad (6.71)$$

η = amplitude of the surge (m)

x = coordinate perpendicular to the shoreline

ρ_a = density of air = 1.25 kg/m^3

ρ = density of sea water = $1.026 \times 10^3 \text{ kg/m}^3$

C_D = drag coefficient = 2.8×10^{-3} (dimensionless)

g = gravity = 9.8 m/s^2

D = average depth of the water = 10 m

W = wind speed = 35 m/s

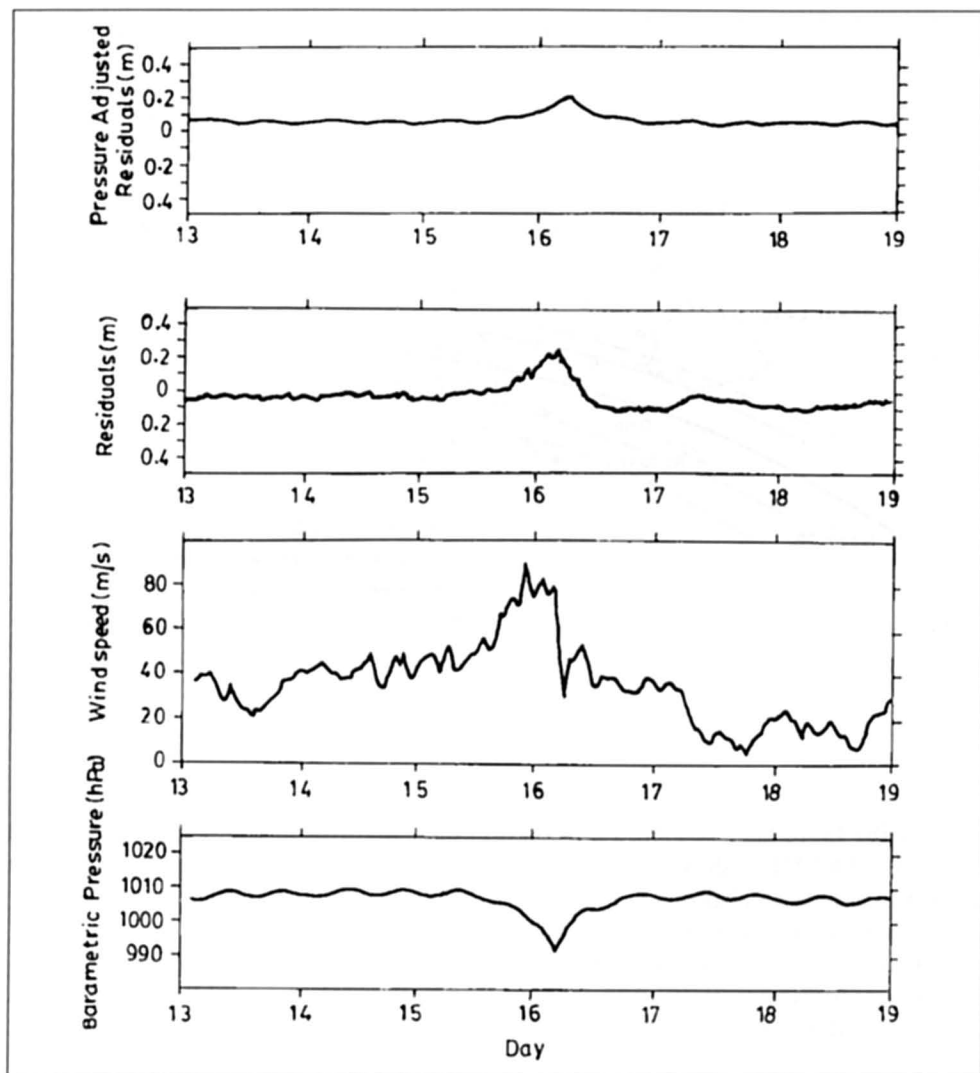


Fig. 6.75: Wind gust, barometric pressure, adjusted residual and residual at Tonga SEAFRAME gauge for January 1996

Using these values, we get

$$\frac{\partial \eta}{\partial x} = 0.42 \times 10^{-4} \quad (6.72)$$

Assuming a fetch of 5 km, one can write.

$$\eta = \frac{\partial \eta}{\partial x} \times 5 \times 10^3 \text{ m} = 0.21 \text{ m} \quad (6.73)$$

The amplitude of the wind set-up computed from the simple formula is 0.21 m, which compares reasonably well with the observed wind set-up of 0.18 m. A numerical model will yield a better agreement. Fig. 6.76 shows the incidence of tropical cyclones for the study area and surroundings (CARTER et al., 1991). Table 6.45 lists the general level of threat from various hazards in the study area whereas Table 6.46 gives the incidence of tropical cyclones in the South Pacific.

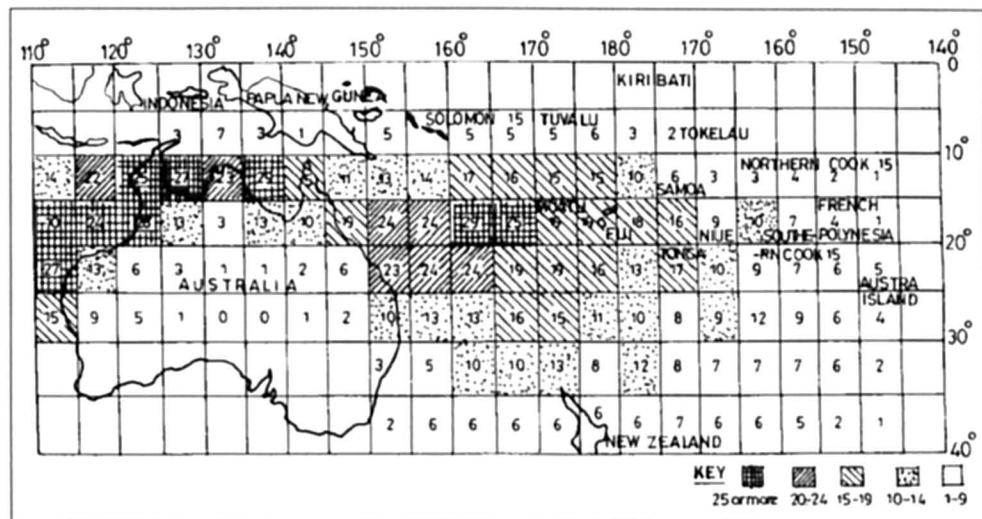


Fig. 6.76: Average decadal incidence of Tropical cyclones in 5-degree latitude – longitude squares. West of 150°E based on data for 1959–1975, East of the Longitude on data for 1969–1979 (CARTER et al., 1991)

Table 6.45: General level of threat (CARTER et al., 1991)

	Cook	Fiji	Solomons	Tonga	Vanuatu	W. Samoa	Kiribati	PNG
Cyclone	M	H	H	H	H	M	L	L
Drought	H	M	L	M	L	L	H	M
Earthquake	L	M	H	H	H	M	L	H
Flood	L	H	H	M	H	H	L	H
Landslide	L	H	H	L	H	H	L	H
Tsunami	M	H	H	H	H	H	L	H
Volcanic Eruption	–	–	H	H	H	L	–	H

L = Low M = Medium H = High

Table 6.46: Incidence of Tropical Cyclones in the South Pacific (CARTER et al., 1991)

Year	Cooks	Fiji	Solomons	Tonga	Vanuatu	W. Samoa	PNG
1960	1	–	–	2	1	–	–
1961	–	–	–	1	1	1	–
1962	1	–	–	–	–	–	–
1963	2	–	–	1	2	–	–
1964	–	3	–	1	1	1	–
1965	–	1	–	–	–	–	–
1966	–	1	2	–	–	1	–
1967	1	1	1	–	–	–	–
1968	–	–	1	–	2	1	–
1969	–	–	1	1	–	–	–
1970	–	3	–	1	–	–	–
1971	–	–	1	1	1	–	–
1972	1	1	1	1	4	–	–
1973	–	3	2	1	–	–	–
1974	–	1	–	1	1	1	–
1975	–	2	–	–	1	1	–
1976	1	–	–	–	1	2	–
1977	–	1	–	1	3	–	1
1978	–	3	1	1	1	–	–
1979	–	1	1	1	1	–	–
1980	–	3	–	–	–	–	–
1981	1	1	–	–	2	–	–
1982	–	1	1	1	1	–	–
1983	2	2	–	–	–	–	–
1984	–	–	–	–	–	1	–
1985	–	3	–	–	3	–	1
1986	2	2	1	–	1	–	–
1987	1	1	–	–	1	–	–
1988	1	–	1	–	3	–	–
1989	1	–	–	–	1	1	–
Total	15	34	14	15	32	10	2

6.8 Western Pacific Ocean

Under this heading we will include: China, Japan, South Korea, Philippines, Vietnam and Thailand.

6.8.1 China

Storm surges up to 6 m can occur occasionally on the coast of China, with surges up to 2–3 m occurring quite frequently. TSENG-HAO and SHIH-ZAO (1975) used a numerical model to compute storm surges in the Po Hai Sea. JIN-CHUAN and GUANG (1979) developed empirical techniques for hourly predictions of surges due to typhoons on the southeastern coast of China. Their study involved predictions for the following tidal stations: Shacheng, Sansha, Xiamen, Dongshan, Shantou, and Shanwei. The total number of surges considered by them was more than 1000. They used the empirical formulae thus developed operationally since 1977. The hourly predicted and observed surges at three locations due to typhoon 7908 of August 2, 1979 are compared in Table 6.47. JIN-CHUAN and GUANG (1979) gave surge profiles for the 24 most important storm surges on the southeastern coast of China during the 1970's. Five of these profiles are given in Fig. 6.77–6.81. C. Tseng-Hao and F. Shih-Zao (unpublished data) developed numerical models for storm surge prediction on the east coast of China.

Table 6.47: Predicted and observed storm surges at three locations in China due to Typhoon 7908 of August 2, 1979 (JIN-CHUAN and GUANG, 1979)

Time (h) GMT	Storm surges (cm) at					
	Shantou		Xiamen		Chongwu	
	Observed	Predicted	Observed	Predicted	Observed	Predicted
05	95	106	84	105	78	99
08	158	163	88	107	61	75
10	201	223	91	95	47	65
11	187	199	92	87	35	60
14	66	100	27	43	21	40

KENTANG (2000) studied the damage from storm surges in China since 1990. He mentions that storm surges are the number one marine hazard in China. Since 1990, 62 typhoons made a landfall on the coast of China. Three events, one in 1992, the second one in 1994 and the third one in 1997 were particularly disastrous. The direct economic losses from these events were about 1.7, 2.6 and 3.8 billion US Dollars. In average year between 1989–1991 the economic loss is much less and is about 0.7 billion US Dollars.

Fig. 6.82 shows the tracks of these three typhoons and Table 6.48 lists the damage. The author suggests the following counter measures:

1. Raise the society's awareness and public education about storm surge hazard
2. Work out a plan for building new sea walls
3. Improve and perfect the available warning and disaster relief command system and
4. Develop an insurance service in order to promptly mitigate the loss caused by severe storm surge disaster events.

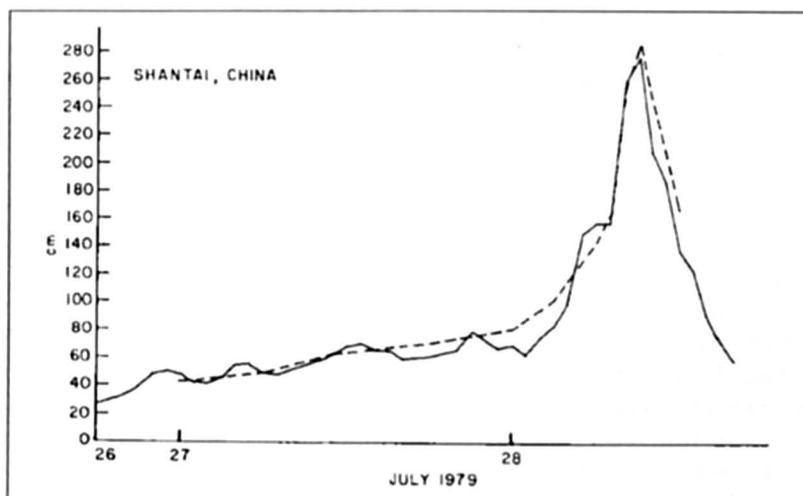


Fig. 6.77: Observed (solid line) and computed (broken line) surges at Shantow, China during July 26-29, 1979 (JIN-CHUAN and GUANG, 1979)

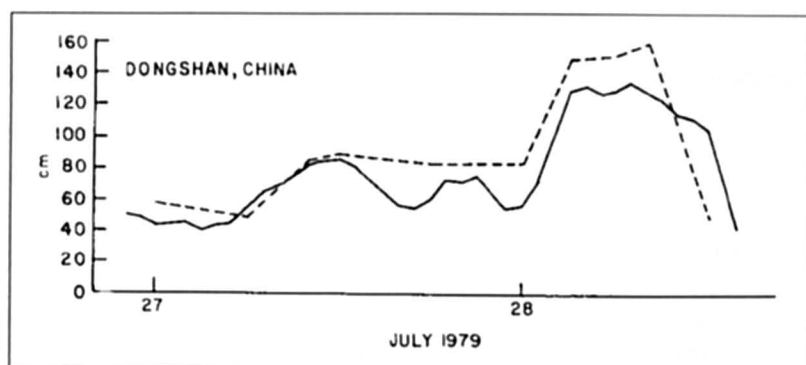


Fig. 6.78: Observed (solid line) and computed (broken line) surges at Dongshan, China during July 27-28, 1979 (JIN-CHUAN and GUANG, 1979)

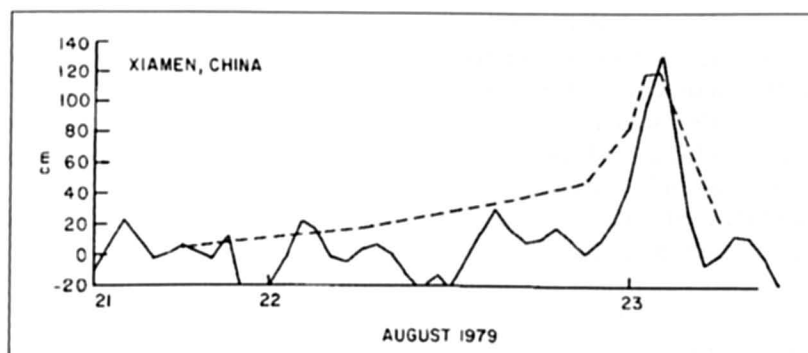


Fig. 6.79: Observed (solid line) and computed (broken line) surges at Xiamen, China during August 21-23, 1979 (JIN-CHUAN and GUANG, 1979)

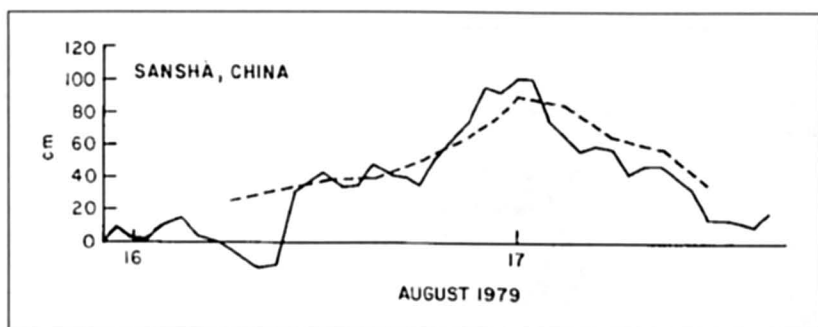


Fig. 6.80: Observed (solid line) and computed (broken line) surges at Sansha, China during August 16-17, 1979 (JIN-CHUAN and GUANG, 1979)

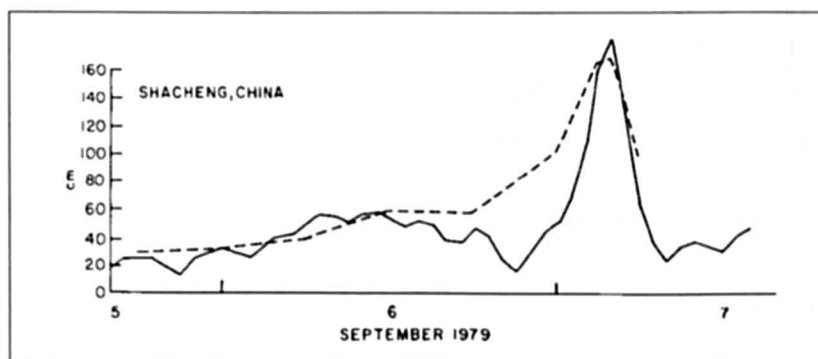


Fig. 6.81: Observed (solid line) and computed (broken line) surges at Shacheng, China during September 5-7, 1979 (JIN-CHUAN and GUANG, 1979)

Table 6.48: Damages of three severe storm surge disaster events (KENTANG, 2000)

	destroyed wall and bank (km)			killed and missing people (number)			direct economic loss (billion yuan, RMB)		
	Polly	Fred	Winnie	Polly	Fred	Winnie	Polly	Fred	Winnie
Name of typhoon	Polly	Fred	Winnie	Polly	Fred	Winnie	Polly	Fred	Winnie
Name of disaster	9216SSD	9417SSD	9711SSD	9216SSD	9417SSD	9711SSD	9216SSD	9417SSD	9711SSD
Province									
or city									
Fujian	203.3		*	12		0	0.92		*
Zhejiang	546.3	520.7	922	114	1216	46	3.15	17.76	18.6
Shanghai	*		~15	0		7	*		0.6
Jiangsu	77.7		260	10		17	0.32		3.0
Shandong	299		85	57		159	4.15		11.5
Hebei							0.32		
Tianjin	44.4			0			0.40		
Total	1170.0	520.7	1282	193	1216	229	9.26	17.76	33.7

(Note: * stands for the much less damage of the item and is not counted in the total)

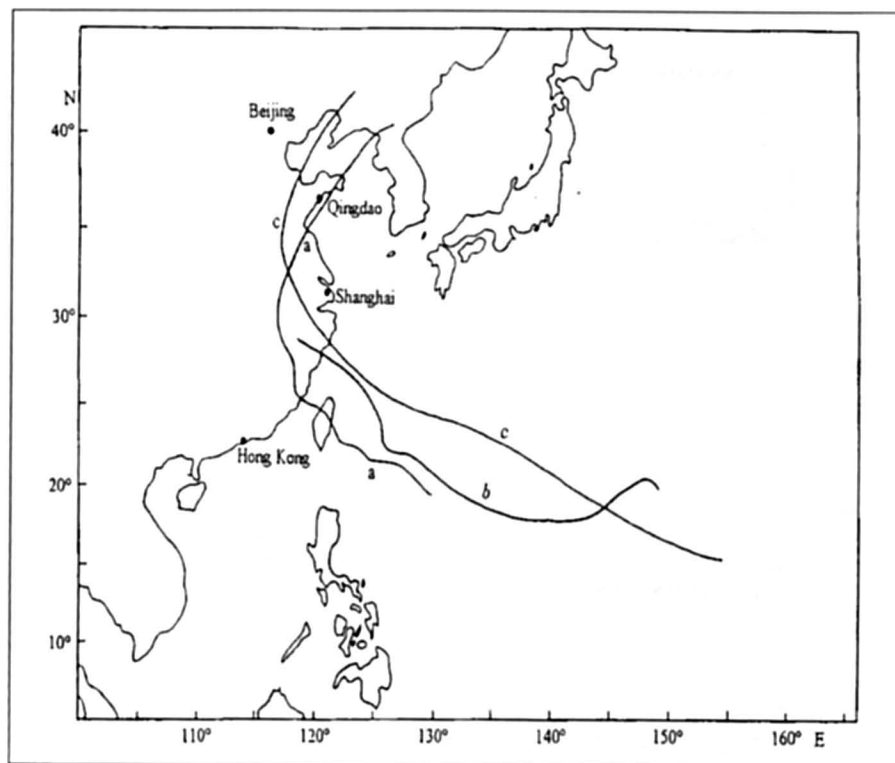


Fig. 6.82: Tracks of the three typhoons in the text (a) Polly, (b) Fred, (c) Winnie (KENTANG, 2000)

Surges in Shanghai Harbour

QIN et al. (1994) numerically simulated tides and storm surges in Shanghai harbour and vicinity by including non-linear tide-surge interaction, as opposed to the traditional method in which tides and surges are linearly super-imposed. They simulated the surges from 16 tropical cyclones hitting Shanghai during the period 1949 to 1990. For the tidal simulations, 63 tidal constituents were included.

Fig 6.83 shows the computational domain. Figs 6.84 to 6.86 respectively show the typhoon tracks for 1949–1959, 1960–1979 and 1980–1990. Fig 6.87 compares the computed water levels for Gloria (1949) and Marge (1951). For results for all the other typhoons, we refer the reader to the original paper. Table 6.49 lists the relative errors for all the simulations. Even though the method used here is not necessarily better in every single simulation; in an overall sense the method used here yielded better results than the traditional method.

Table 6.49: Root-mean-square-errors in the neighbouring high water level using the traditional method and the proposed method incorporating nonlinear surge-tide coupling (QIN et al., 1994)

TC No.	TC Name	Traditional method (cm)	Proposed method (cm)
4906	Gloria	9.0	46.5
5116	Marge	24.7	21.0
5410	Grace	42.5	34.6
5612	Wanda	44.5	20.5
5907	Sarah	29.5	29.5
6014	Carmen	48.5	38.8
6207	Nora	37.6	22.4
7008	Billie	45.0	37.6
7308	Iris	40.0	14.5
7413	Mary	33.0	21.1
7910	Judy	40.2	28.7
8114	Anges	39.2	28.1
8310	Forrest	29.9	23.5
8615	Vera	26.7	22.2
8913	Lola	33.9	25.9
9015	Abe	8.7	17.8

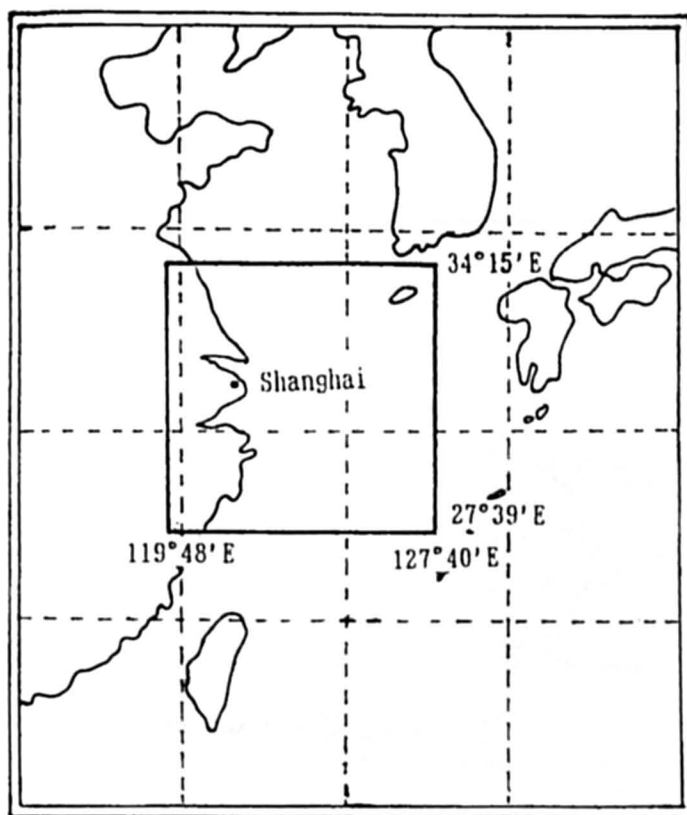


Fig. 6.83: Computational domain (QIN et al., 1994)

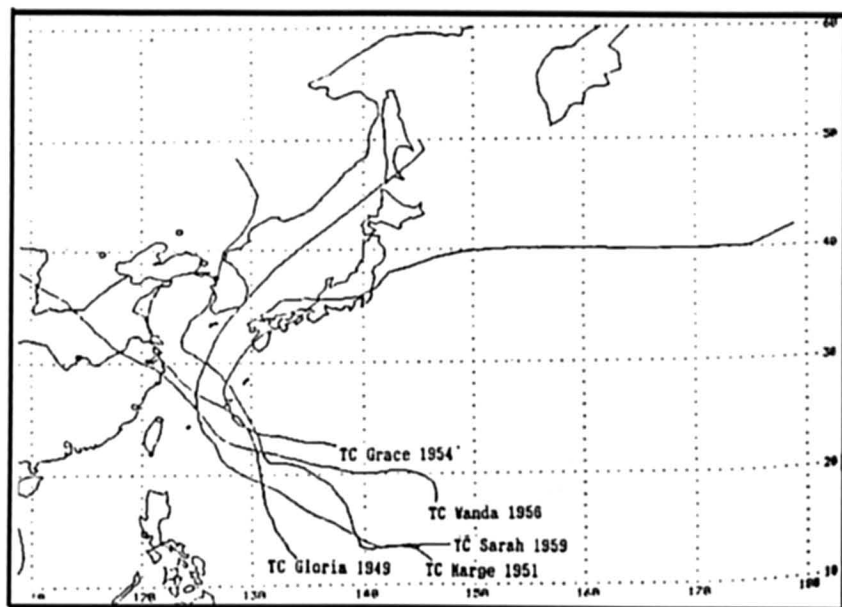


Fig. 6.84: Tracks of tropical cyclones for 1949-1959 (QIN et al., 1994)

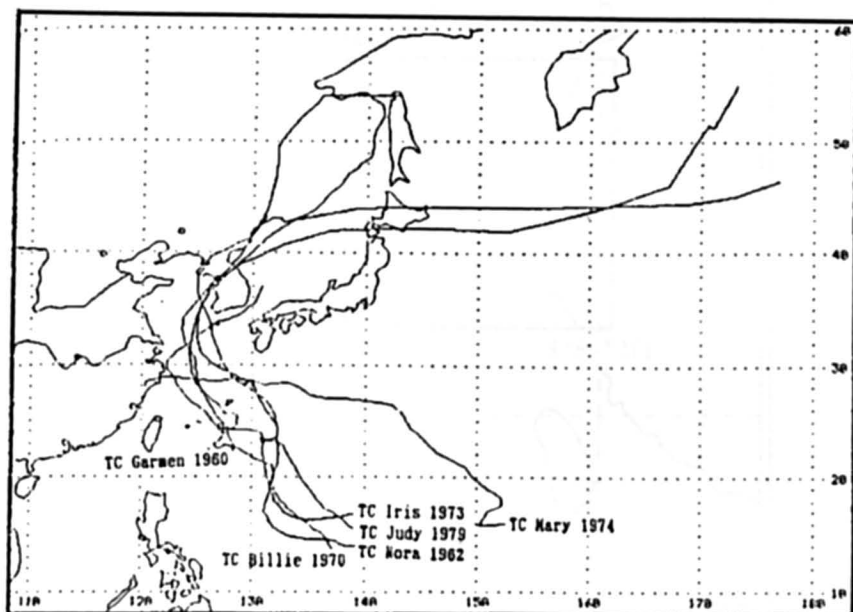


Fig. 6.85: Tracks of tropical cyclones for 1960-1979 (QIN et al., 1994)

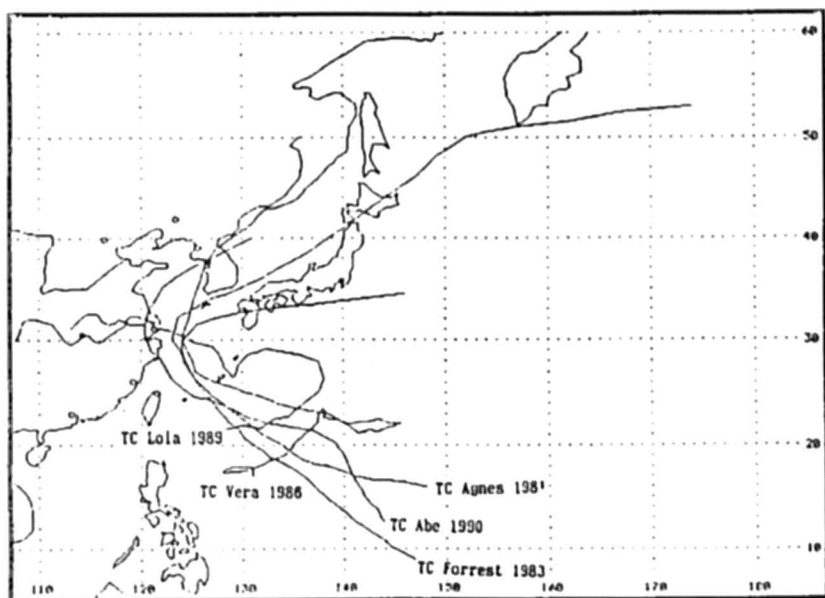


Fig. 6.86: Tracks of tropical cyclones for 1980-1990 (QIN et al., 1994)

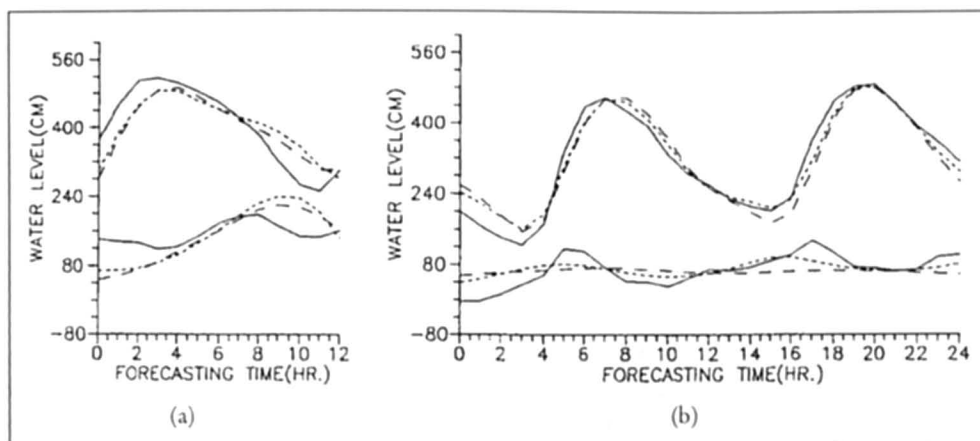


Fig. 6.87: (a) Surge and water level process curves caused by TC Gloria 1949 for Wuson. Legend: solid line – observed, dashed lines – simulated (longer for the traditional method, shorter for the proposed method); top case for total water-level, bottom case for storm surges (b) same as above except those caused by TC Morge 1951 (QIN et al., 1994)

Surges in Hong Kong

Storm surges are reasonably severe in Hong Kong (CHAN and WALKER, 1979) have described three different types of surges and the empirical formulae for predicting them. The return periods for surges of different amplitudes (BELL, 1961), computed using Gumbel's methods and using data from maximum hourly winds, are listed in Table 6.50. SILVESTER (1971) studied storm surges in Hong Kong and developed empirical relations. The pressure deficits and observed storm surges at North Point, Hong Kong Harbour, for seven different typhoons are listed in Table 6.51.

Table 6.50: Return periods for extreme storm surges in Hong Kong (BELL, 1961)

Surge amplitude (m)	Return period (Yr)	Surge amplitude (m)	Return period (Yr)
1.6	10	2.4	200
1.8	20	2.7	500
2.0	50	2.9	1000
2.2	100		

Table 6.51: Observed storm surge amplitudes and pressure deficits in typhoons that affected Hong Kong (North Point) (SILVESTER, 1971)

Typhoon	Date	Pressure deficit (mb)	Observed surge amplitude (m)
Wanda	Sept. 1962	61	0.62
Faye	Sept. 1963	17	0.17
Viola	May 1964	21	0.21
Ida	Aug. 1964	38	0.39
Ruby	Sept. 1964	45	0.46
Sally	Sept. 1964	24	0.24
Shirley	Aug. 1968	44	0.45

LAU (1980b) used the SPLASH model to compute storm surges at North Point and in Tolo Harbour for events of tropical cyclone passages across the northern part of the South China Sea. This study used 93 historical storms during the period September 1906–June 1976 that generated storm surges in Hong Kong. The standard storm of the SPLASH model gives an open-coast peak surge of 1.92 m at North Point. Nomograms for the surge height at North Point are given in Fig. 6.88–6.92, respectively, as a function of the central pressure of the storm, storm direction, storm speed, radius of maximum winds, and distance of nearest approach of storm.

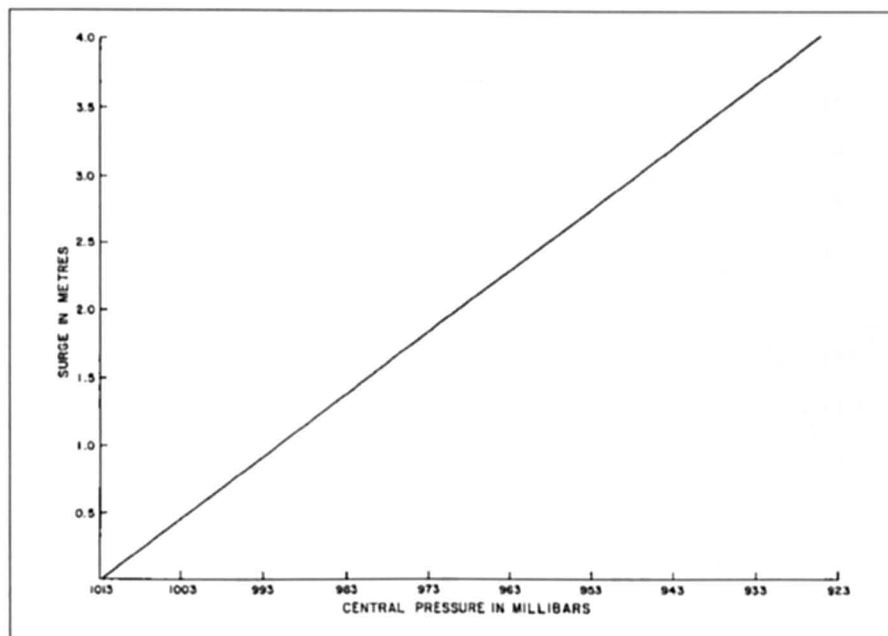


Fig. 6.88: Surge amplitude versus central pressure of storm for North point in Hong Kong harbour (LAU, 1980b)

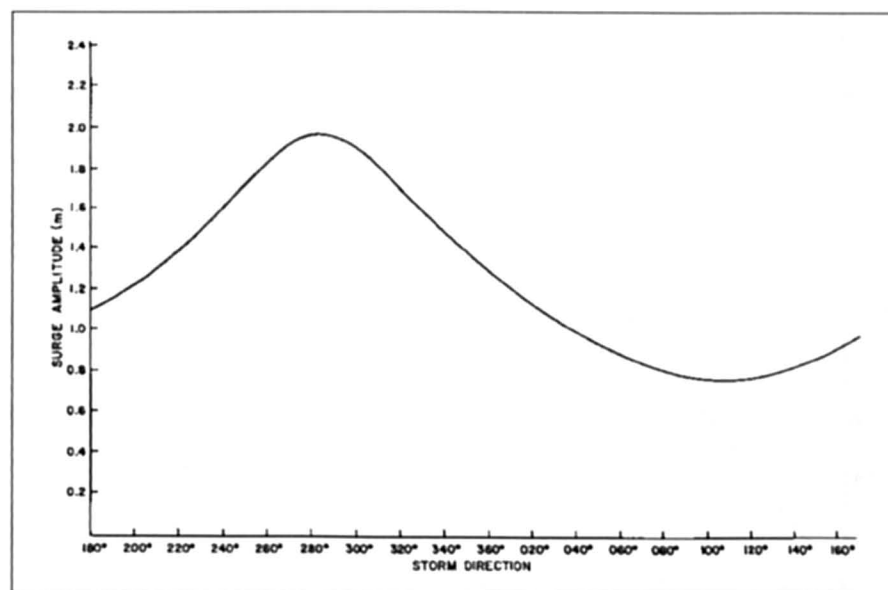


Fig. 6.89: Surge amplitude versus storm direction in 360° compass bearing for North point in Hong Kong harbour (LAU, 1980b)

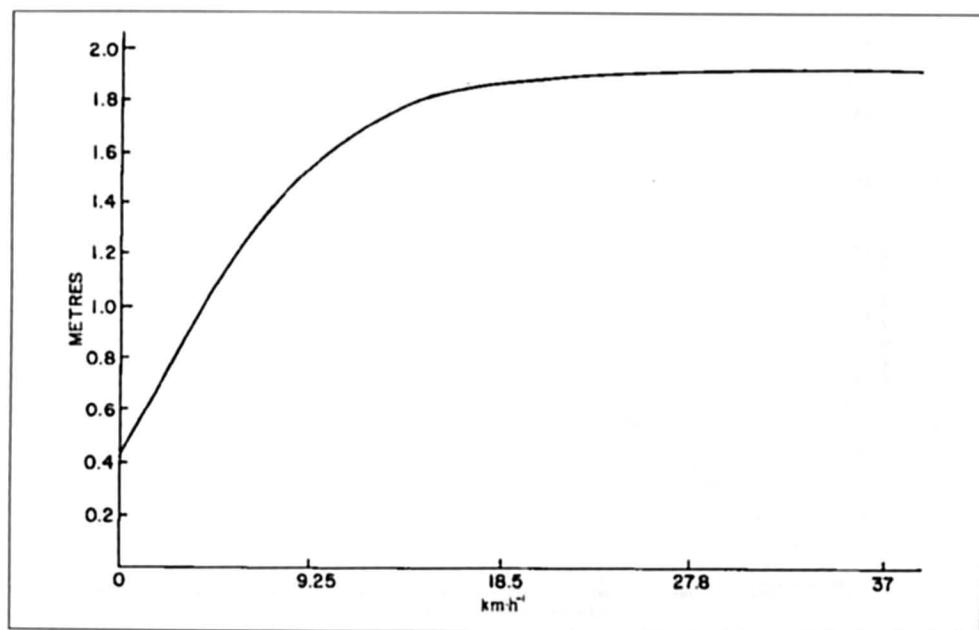


Fig. 6.90: Storm surge amplitude versus storm speed for North point in Hong Kong harbour (LAU, 1980b)

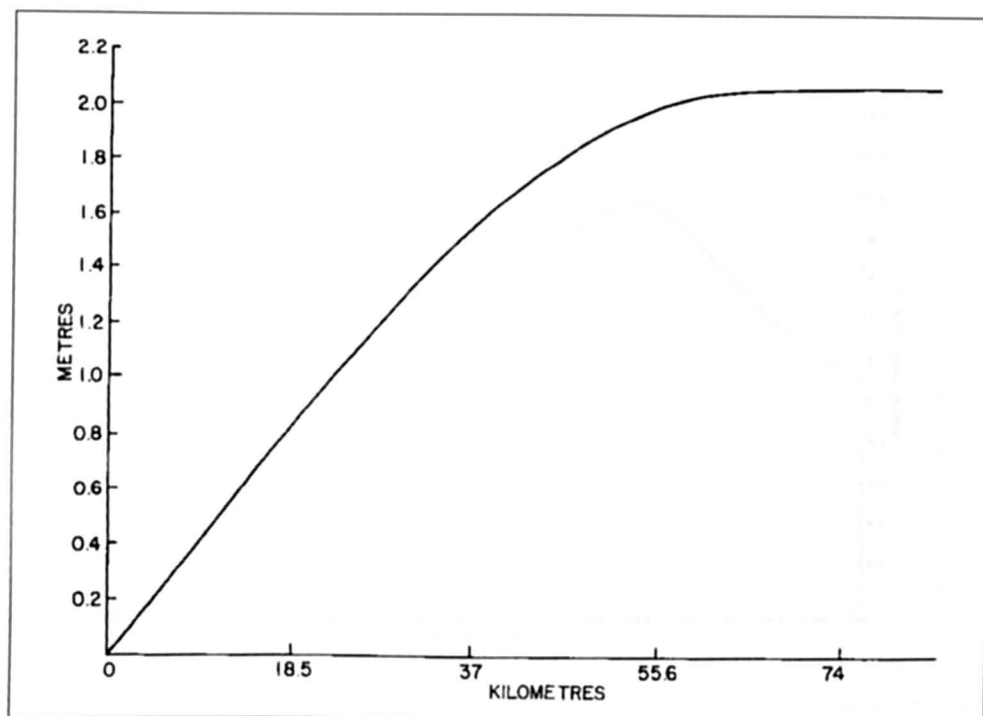


Fig. 6.91: Storm surge amplitude (ordinate) versus radius of maximum winds (abscissa) for North point in Hong Kong harbour (LAU, 1980b)

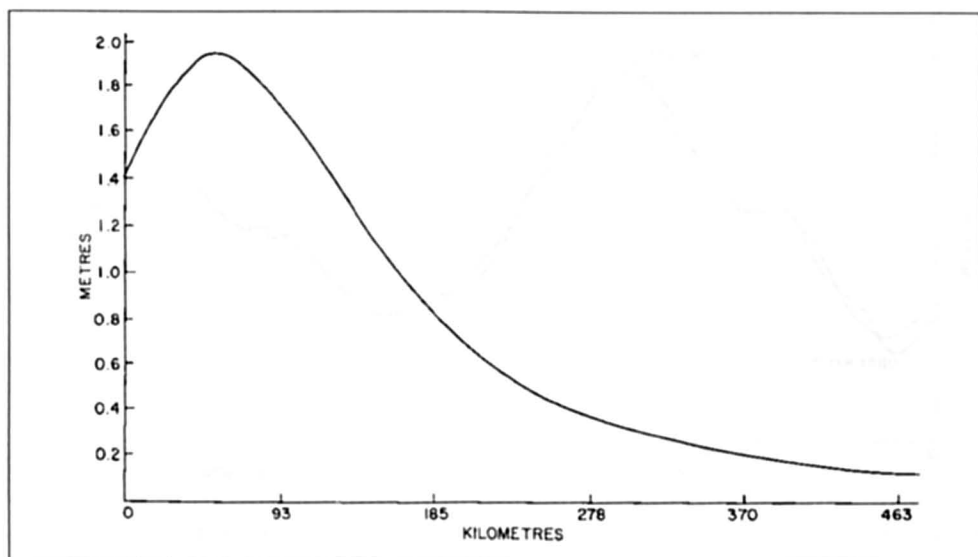


Fig. 6.92: Storm surge amplitude (ordinate) versus distance from the nearest approach of storm for North point in Hong Kong harbour (LAU, 1980b)

LAU (1980a) mentioned that the storm surge problem is getting worse in Hong Kong with more and more people crammed into reclaimed low-lying areas. A typhoon surge on September 2, 1937, killed 11000 people, and several villages around Tolo Harbour were destroyed. Typhoon Wanda of September 1, 1962, killed 127 people. LAU (1980a, 1980b) summarised the empirical relations developed by CHENG (1967) and CHAN (1976). He also included a table from PETERSON (1975) in which joint probabilities for certain combinations of tides and surges at Tolo Harbour and North Point were listed. Finally, LAU (1980a) developed a series of numerical models for computing surges in different areas of Hong Kong and environs. Observed and computed water levels at Tai Po Kau due to Typhoon Elaine of October 29–30, 1974, are compared in Fig. 6.93. Computed and observed water levels at Tai Po Kau due to Typhoon Elsie of October 14–15, 1975, are compared in Fig. 6.94.

DAS et al. (1978) mentioned that storm surges occur at the rate of three to four per year in Hong Kong Harbour. Thirty-five surges with amplitudes from 0.2 to 1.8 m occurred there during 1954–64 (CHENG, 1967). Typhoon Wanda of September 1962 produced a surge of about 3.2 m at Tai Po Kau (farther inland from Hong Kong Harbour), whereas the peak surge in Hong Kong Harbour was 1.8 m.

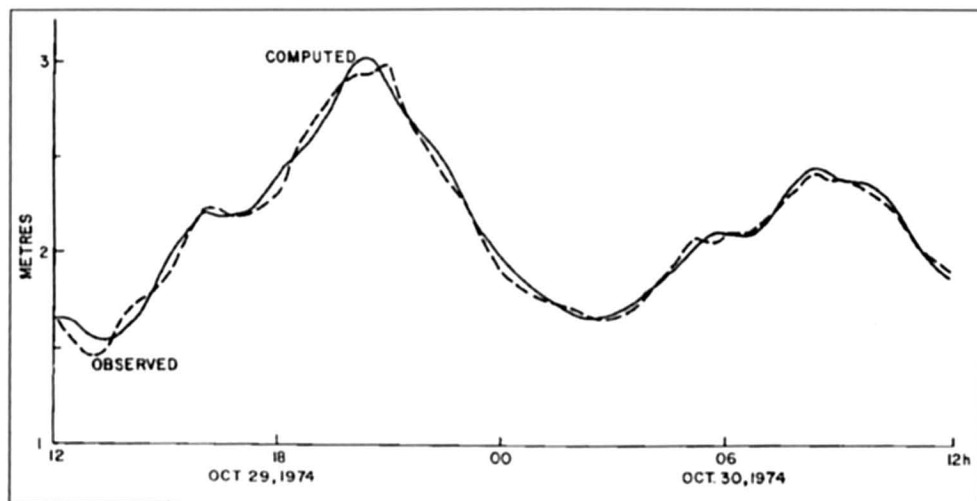


Fig. 6.93: Computed (solid line) and observed (broken line) water levels at Tai Po Kau due to Typhoon Elaine of October 29-30, 1974. Time is Hong Kong Standard Time (LAU, 1980a)

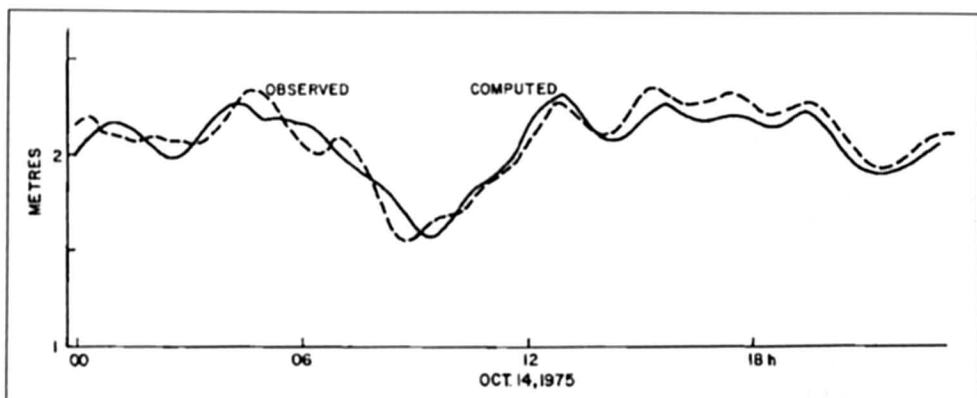


Fig. 6.94: Compared (solid line) and observed (broken line) water levels at Tai Po Kau due to Typhoon Elsie of October 14-15, 1975. Time is Hong Kong Standard Time (LAU, 1980a)

6.8.2 Japan

Storm surges in the bays on the coast of Japan are slightly less severe than, for example, in the Bay of Bengal and the Gulf of Mexico but they cause great damage and loss of life when they strike the densely populated coasts of Tokyo Bay, Osaka Bay, Ise Bay, etc. Table 6.52 and 6.53 list the important storm surges in Japan. MIYAZAKI (1975) mentioned that storm surge records in Japan generally exhibit three features: the forerunner, the main surge, and the resurgence. The surge profiles at Nagoya and Toba along the coast of Ise Bay due to the typhoon of September 26-27, 1959, are given in Fig. 6.95. Forerunners with amplitudes of 20-30 cm can be seen. Resurgences with periods of about 7 h can also be seen. MIYAZAKI (1975) also estimated the return periods of surges with different maximum amplitudes at six locations in Japan. These results are summarised in Table 6.54.

Table 6.52: Storm surges in Japan during the period 1900–73 with maximum amplitudes in excess of 2 m. Highest level includes surge and tide (MIYAZAKI, 1975)

Date	Affected Area	Peak surge (m)	Highest level (m)	Meteorological extreme values		
				Central pressure (mb)	Wind ($\text{m} \cdot \text{s}^{-1}$)	Location
Oct. 1, 1917	Tokyo Bay	2.3	3.1	950.4	SSE 40.0	Tokyo
July 18, 1930	Ariake Sea	2.5	—	954.6	ENE 30.6	Tomic
Sept. 21, 1934	Osaka Bay	3.1	3.2	954.3	S 48.4	Osaka
Sept. 1, 1938	Tokyo Bay	2.2	—	978.6	S 31.0	Tokyo
Sept. 3, 1950	Osaka Bay	2.1	2.5	964.3	NE 33.4	Kobe
Aug. 17, 1956	Ariake Sea	2.4	4.2	968.4	SE 27.0	Saga
Sept. 26, 1959	Ise Bay	3.4	3.9	958.5	SSE 37.0	Nagoya
Sept. 16, 1961	Osaka Bay	2.5	2.9	937.3	SSE 33.3	Osaka
Sept. 25, 1964	Osaka Bay	2.1	2.6	983.5	S 27.1	Sumoto
Sept. 10, 1965	Osaka Bay	2.2	—	966.0	SSE 38.8	Sumoto
Aug. 21, 1970	Tosa Bay	2.4	3.1	962.3	SW 35.8	Ashizuri

Table 6.53: Severe damage caused by storm surges in Japan during the period 1900–73 (MIYAZAKI, 1975)

Date	Affected Area	Highest sea level (m)	Peak surge (m)	Lives Lost	Houses destroyed or swept away
Oct. 1, 1917	Tokyo Bay	3.0	2.1	1324	60 175
Sept. 13, 1927	Ariake Sea	3.8	0.9	439	2211
Sept. 21, 1934	Osaka Bay	3.1	2.9	3036	92 323
Aug. 27, 1942	Inland Sea	3.3	1.7	1158	102 374
Sept. 17, 1945	South Kyushu	2.6	1.6	3121	115 984
Sept. 3, 1950	Osaka Bay	2.7	2.4	534	120 923
Oct. 14, 1951	South Kyushu	2.8	1.0	943	72 648
Sept. 27, 1959	Ise Bay	3.9	3.4	5098	156 676
Sept. 16, 1961	Osaka Bay	3.0	2.5	200	54 782

Table 6.54: Return periods of storm surges in Japan (MIYAZAKI, 1975).

Location	Maximum Surge observed (m)	Return period (yr) for surges with peak amplitude of at least		
		0.5 m	1.0 m	2.0 m
Tokyo	2.1	1.0	8	35
Yokohama	1.1	1.4	19	—
Nagoya	3.4	0.6	3	15
Osaka	3.1	0.7	3	10
Kobe	2.2	1.0	6	30
Beniya (on the Ariake Sea)	2.5	—	7	17

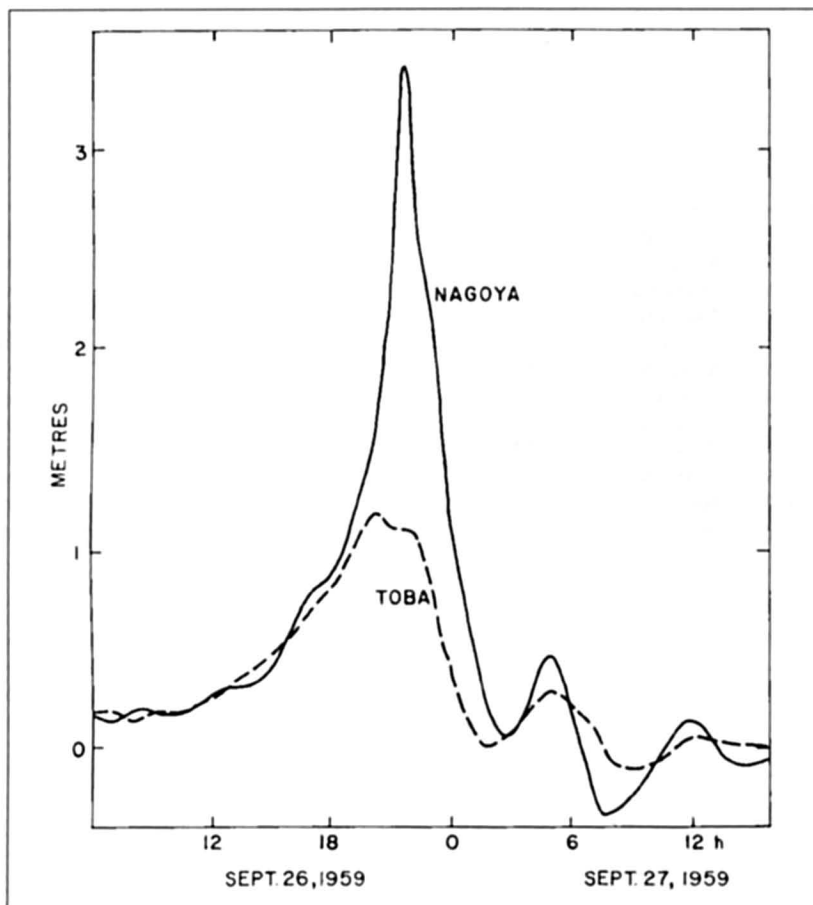


Fig. 6.95: Storm surges at Nagoya and Toba on Ise Bay, Japan, due to the typhoon of September 26–27, 1959. Note the forerunners and the resurgences in addition to the main surge (MIYAZAKI, 1975)

Unusual storm tracks can occur in the Japan area. The track of typhoon Orchid of September 1980 is illustrated in Fig. 6.96. This track is remarkable because it shows three loops. NAKAYAMA (1972) described the telemeter system for the tsunami and storm surge warning service provided by the Japan Meteorological Agency. As of 1972 there were a total of 60 coastal tide gauge stations in this system. Next, storm surge events will be considered in several different bays along the coast of Japan, beginning with Tokyo Bay and proceeding southwest. Note that the storm surge problem on the west coast of Japan (facing the Sea of Japan) is less severe than along the Pacific coast of Japan.

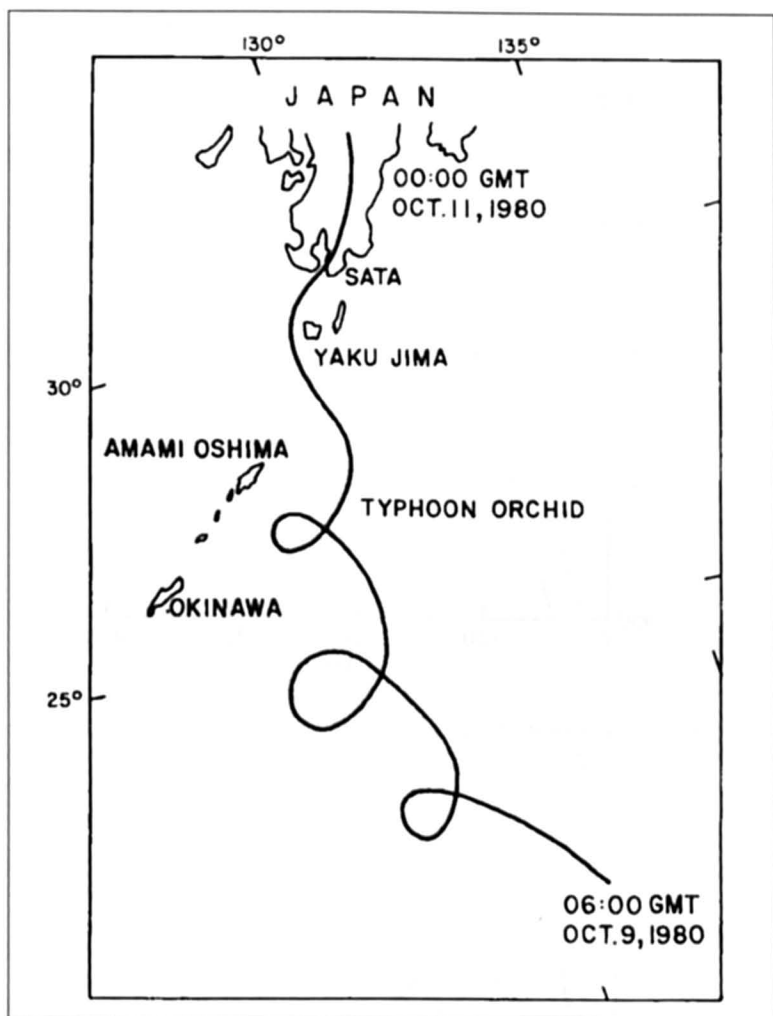


Fig. 6.96: Track of typhoon Orchid during October 9-10, 1980
(JOINT TYPHOON WARNING CENTER, 1981)

MIYAZAKI et al. (1961) used numerical models to compute the storm surges in Tokyo Bay, Ise Bay, and Osaka Bay. They reconstructed the meteorological forcing terms for the Ise Bay typhoon of September 1959. The pressure-distance and wind-distance relations are shown in Fig. 6.97 and 6.98, respectively.

Simulations were made for the following cases: (1) surge in Ise Bay due to the Ise Bay typhoon of September 1959, (2) surges in Tokyo Bay due to the typhoon of October 1, 1917, and Typhoon Kitty of September 1949, and (3) surges in Osaka Bay due to the Muroto typhoon of September 1934 and Typhoon Jane of September 1950.

The horizontal distribution of the storm surge amplitudes in Tokyo Bay due to the typhoon of October 1917 is given in Fig. 6.99. Computed and observed surges at Kishiwada and Osaka due to Typhoon Jane are compared in Fig. 6.100. The spectrum of the storm surge at Kobe due to Typhoon Jane is shown in Fig. 6.101.

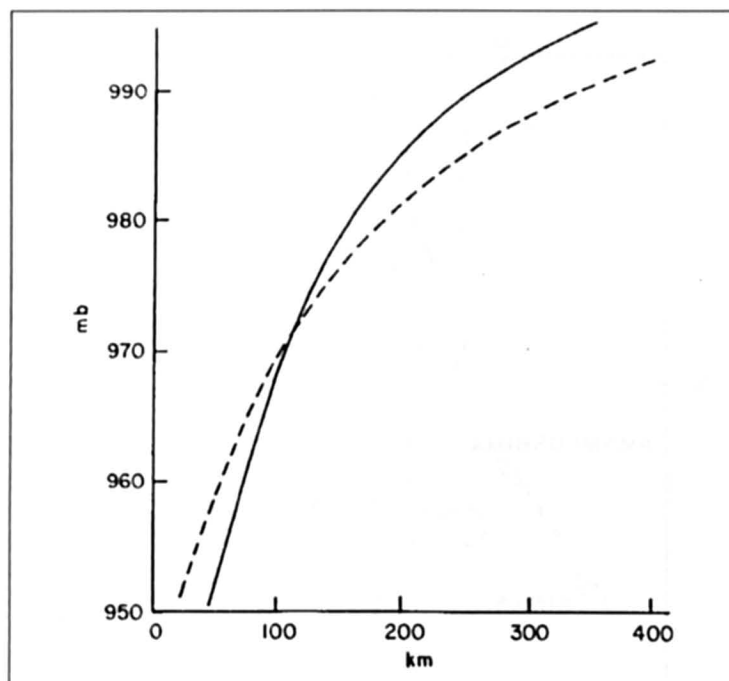


Fig. 6.97: Atmospheric pressure versus distance from the typhoon center for the Ise Bay typhoon of September 1959. Solid curve is obtained using Fujita's formula and the broken curve is from Takahasi's formula (MIYAZAKI et al., 1961)

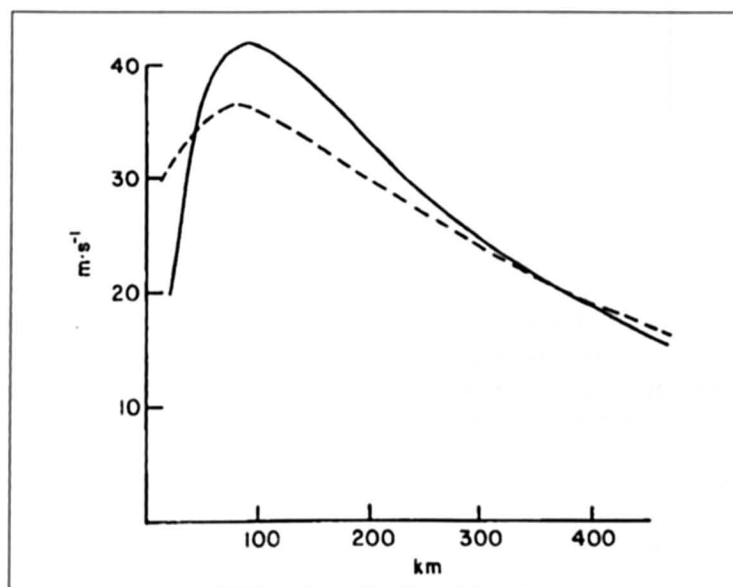


Fig. 6.98: Wind speed versus distance from the typhoon center for the Ise Bay typhoon of September 1959. Solid curve is from Fujita's formula and the broken curve is from Takahasi's formula (MIYAZAKI et al., 1961)

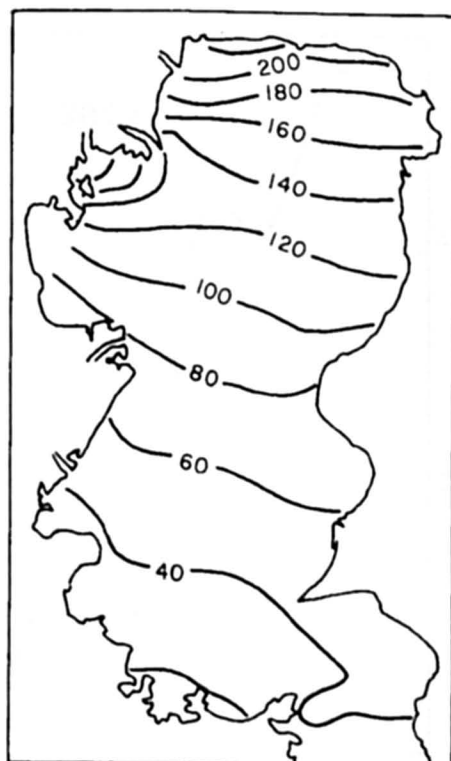


Fig. 6.99: Distribution of storm surge heights (centimeters) in Tokyo Bay at 04:00 on October 1, 1917 (MIYAZAKI et al., 1961)

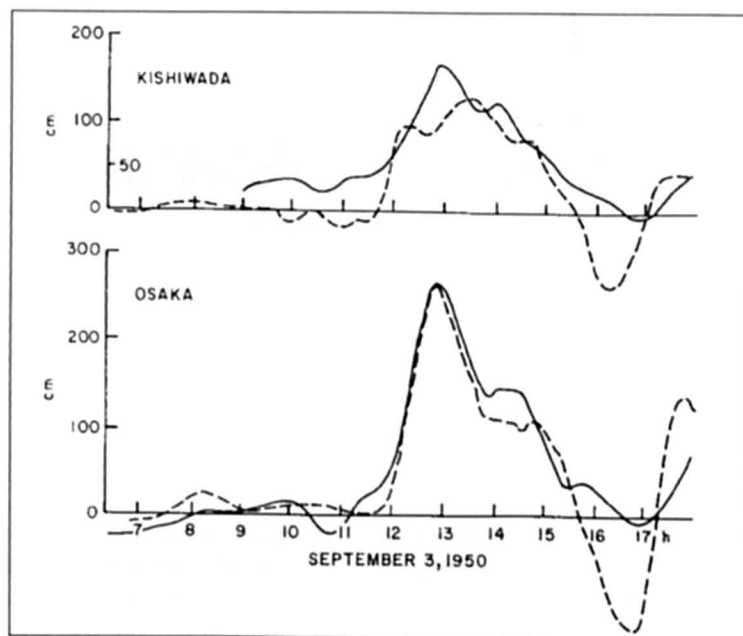


Fig. 6.100: Observed (solid line) and computed (broken line) storm surges at Kishiwada and Osaka due to typhoon Jane of September 1950 (MIYAZAKI et al., 1962)

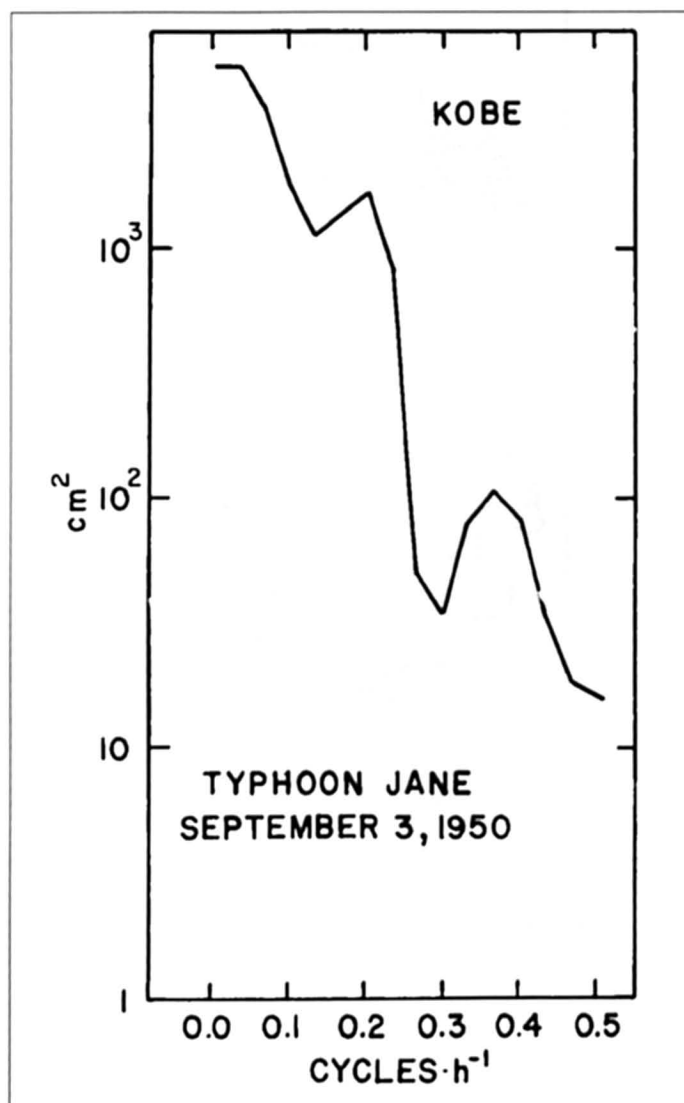


Fig. 6.101: Power spectrum of the storm surge at Kobe due to Typhoon Jane of September 3, 1950 (DAS et al., 1978)

ITO et al. (1965) developed a two-dimensional numerical model for storm surges in Tokyo Bay and the outer shelf using multiple grids. They also studied the problem of tide-surge interaction and the influence of a dyke (with an opening) in Tokyo Bay (north of a line connecting Kawasaki and Kisarazu) on the storm surges in the bay. They simulated the surges due to the October 1, 1917, typhoon and also due to the Ise Bay typhoon of September 1959.

They found the following empirical relation for the maximum water level max in that part of the bay protected by the dyke:

$$\eta_{\max} = a + m \log A \quad (6.74)$$

where, A is the cross-sectional area of the opening, a is a constant that depends on the point of observation, and m is another constant almost independent of location.

Runs were made with the numerical model for openings with widths of 20 m to 2 km and also for a case of two openings, each 0.5 km wide. The results tend to show that the maximum surge amplitudes in the inner bay (i.e. protected by the dyke) decrease when a dyke is present. Also, the maximum surge amplitude decreases for smaller widths of the opening (Fig. 6.102). The problem of tide-surge interaction has already been discussed in section 4.5.8.

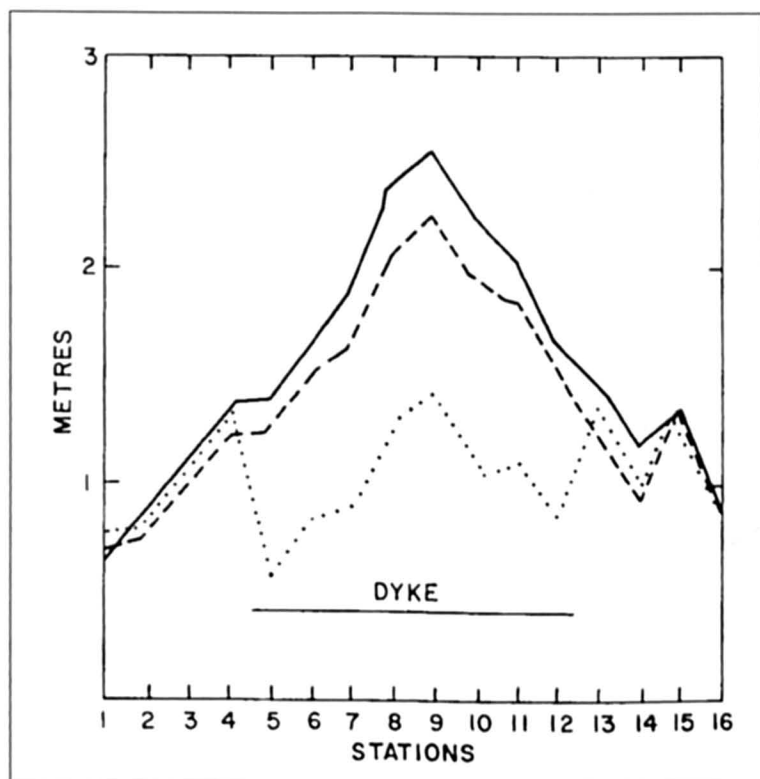


Fig. 6.102: Computed envelope of peak storm surge in Tokyo bay after the construction of a dyke. Solid line: without dyke; broken line: with dyke having an opening of 2 km dotted line with dyke having an opening of 0.5 km width, Stations: 1. Kurihama; 2. Yokosuka; 3. Yokohama; 4. Kawasaki South; 5. Kawasaki North; 6. Tokyo; 7. Urayasu; 8. Funabashi; 9. Chiba; 10. Goi; 11. Anegasaki; 12. Narawa; 13. Kisarazu; 14. Futtusu; 15. Isonoe; 16. Kaiho II (ITO et al., 1965)

KAWAHARA et al. (1980) used a finite-element model to compute storm surges in the Surugawan Bay due to the typhoon (No. 6626) of September 24, 1966. The maximum surge produced was about 1 m. After the disastrous storm surge of September 1959 in Ise Bay, a breakwater was constructed in the inner part of the bay to protect the Nagoya district.

(NAKAMURA et al. 1964). These authors also performed hydraulic model tests. The tests showed that the breakwater will not significantly alter the tide but will reduce the surge considerably in the inner part of the bay.

The Muroto typhoon of September 21, 1934, caused major storm surges in Lake Biwa (northeast of Osaka). The southern portion of this lake is very shallow with an average depth of only 3.4 m. Surges up to 2.4 m in amplitude were generated (NOMITSU, 1935).

MIYAZAKI (1955) studied storm surge in the Kobe Harbour. During the period 1925-54, a total of at least 34 storm surges occurred in this harbour. The Muroto typhoon of September 21, 1934, produced a surge of amplitude 2.2 m. Typhoon Jane of September 3, 1950, produced a surge of 1.7 m; the Makurazaki typhoon of September 18, 1945, as well as another typhoon on September 26, 1954, produced surges up to 1.5 m.

MIYAZAKI (1955) gave the following return periods for surges of amplitude 1.0, 1.5, 2.0, and 2.0 m in Kobe harbour: 5, 24, 105, and 455 yr. Of a total of 32 storm surges studied, 22 were caused by tropical cyclones and the remaining 10 were caused by extratropical cyclones. Further, any surges with amplitudes greater than 0.8 m were exclusively produced by tropical cyclones.

Osaka bay is frequently subjected to severe storm surges. The Muroto typhoon of September 21, 1934, killed 2593 people and 110,000 houses were destroyed in Osaka alone. The central pressure of this typhoon was the lowest ever recorded at a land station (912 mb). Wind velocities of up to $60 \text{ m} \cdot \text{s}^{-1}$ created maximum water level of 4.6 m, and surges with amplitudes of up to 2.3 m inundated large areas (MATSUO, 1934). Osaka Harbour (and several others) was heavily damaged and individual ships of up to 3145 t in weight were carried ashore by the surge. The total weight of the ships carried ashore in Osaka Harbour was about 23,000 t. The envelope of maximum surge amplitude at several locations along Osaka Bay due to Typhoon Nancy of 1961 is shown in Fig. 6.103.

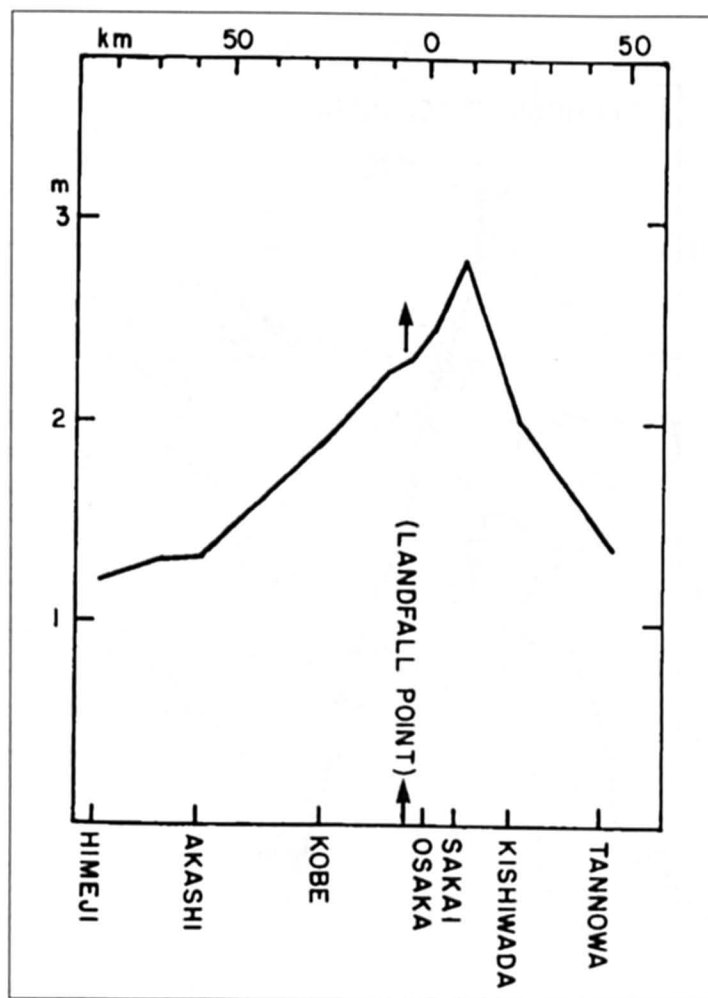


Fig. 6.103: Peak surge envelope at stations along Osaka Bay due to Typhoon Nancy of 1961 (DAS et al., 1978)

HAYAMI et al. (1955) performed hydraulic model experiments to study the propagation of a storm surge as a bore in the rivers and canals near Osaka City and concluded that the embankment under construction (1955) would provide some protection but not total protection from storm surges. MUROTA (1963) also performed hydraulic model studies for Osaka bay and concluded that construction of breakwater would actually increase the amplitudes of storm surges due to increased seiche action. UNEO (1981) used SPLASH and also a numerical model to simulate the storm surge of August 21, 1970, in Tosa Bay, which produced surges up to 2 m in amplitude. He also used a two-layer model to include the effect of stratification.

MINATO (1998) numerically simulated storm surges in Tosa (Fig. 6.104) making use of the three-dimensional terrain following Princeton Ocean Model (POM) with horizontally uniform stratification in the area of Tosa bay. Finer Resolution in the vertical direction and stronger stratification generates slightly greater peak surges.

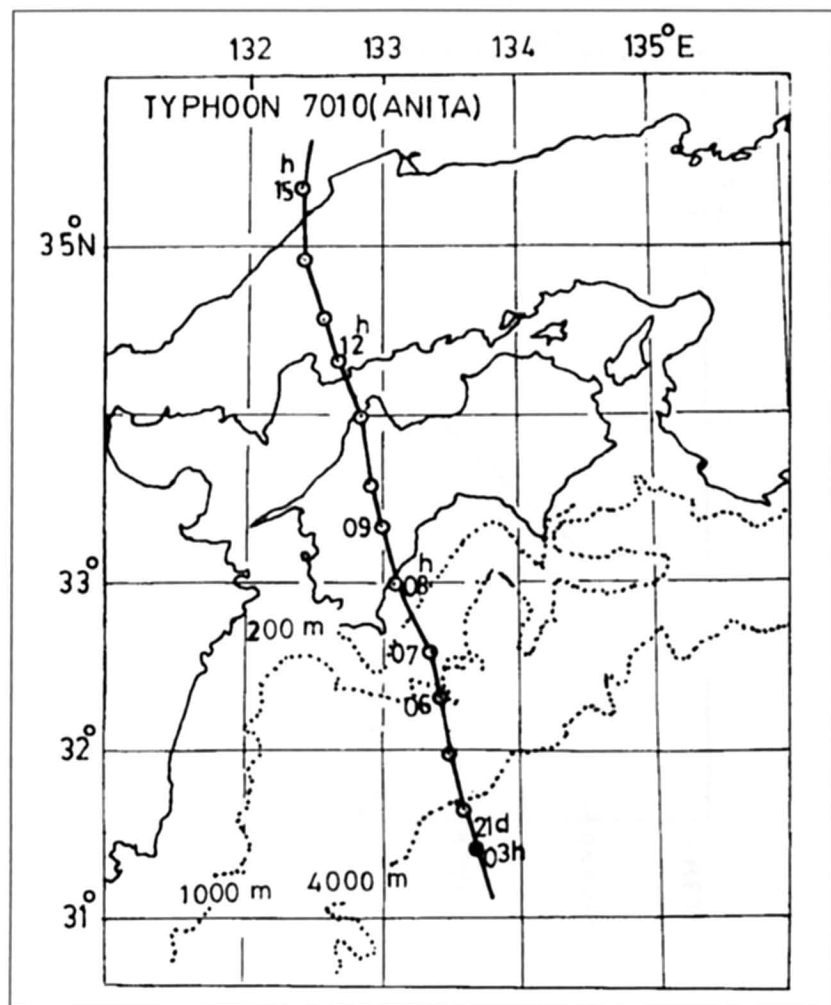


Fig. 6.104: Typhoon 7010 track (MINATO, 1998)

6.8.3 South Korea

Storm surges are not a serious problem in the Sea of Japan. Hence, the west coast of Japan and the east coast of Korea are not prone to major storm surges. However, storm surges occur in the Yellow Sea and the Po Hai Sea. Thus, storm surges on the west coast of Korea deserve attention.

On the southern part of the Korean peninsula, the tidal range in the Yellow Sea is about 4 m and it increases to about 10 m in the northern part (AN, 1980). The typhoons that pass over Korea are usually less severe than those that affect Japan.

The observed storm surge at Incheon (tidal range here is about 7 m) during August 30–31, 1979, due to Typhoon Billie is shown in Fig. 6.105. The track of this typhoon is shown in Fig. 6.106. AN (1980) used a two-dimensional numerical model to simulate this storm surge. The range (trough to crest) of the storm surge at Incheon was about 1.4 m. At Mokpo and Kunsan;

the range was only about 0.4 m. On July 29, 1965, a storm that struck the west coast of Korea generated an unusually large surge of 5.2 m (DAS et al., 1978).

CHOI (1987) developed numerical models for tides and surges in the Yellow Sea with application to South Korea. OH et al. (1988) studied storm surges due to typhoons passing through the south sea of Korea. Making use of data from eight tidal stations, they showed that surges have greater amplitudes generally for the western stations as compared to eastern stations also negative surges are more predominant for the western area.

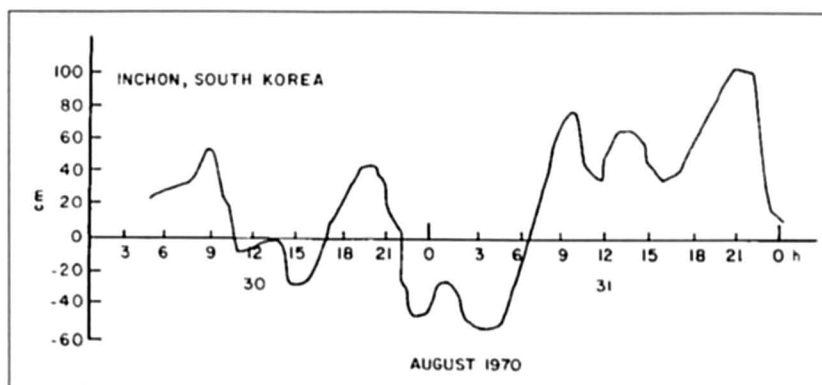


Fig. 6.105: Storm surge at Incheon, South Korea during August 30–31, 1970, due to Typhoon Billie. Time is Korean Standard Time (AN, 1980)

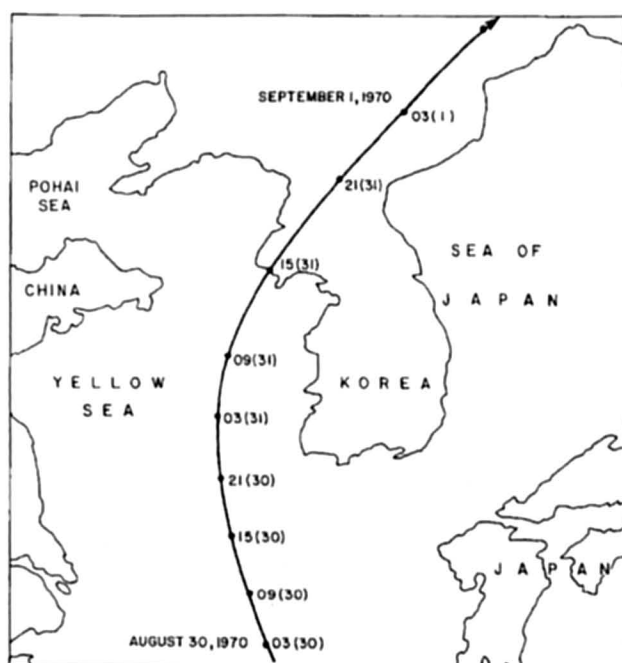


Fig. 6.106: Track of Typhoon Billie during August 30–September 1, 1970. Time is Korean Standard Time. Numbers in the parentheses are the dates (AN, 1980)

SHIN (1994) studied storm surges on the coast of South Korea. Table 6.55 lists the typhoons for the period 1904 to 1983. Fig. 6.107 shows the tracks of the typhoons coming from various directions. Table 6.56 lists the frequency and percentage of typhoon approach from different directions. Table 6.57 lists the peak surge amplitudes at various locations.

Table 6.55: The temporal distribution of the major storms around the Korean Peninsular during the years 1904–1983

Year	May	Jun.	Jul.	Aug.	Sep.	Oct.	Total	Year	May	Jun.	Jul.	Aug.	Sep.	Oct.	Total
1904				2			2	1945			1	2	1		4
1905			1	1	1		3	1946			1	2			3
1906				1	1	1	3	1947							0
1907			2		1		3	1948			1	1	2		4
1908				1			1	1949		1	2	1			4
1909				2			2	1950		2	1	3	2		8
1910			1				1	1951				1	1	1	3
1911			2	1	1	1	5	1952		1	1	1	1		4
1912			1				1	1953		1	1	1			3
1913			1				1	1954				1	2		3
1914		1	2	1	2		6	1955			2		1		3
1915			1	1	1		3	1956				1	3		4
1916				1	1		2	1957		1		1			2
1917				1	2		3	1958					1		1
1918			1	2			3	1959			2	1	4		7
1919				3	1		4	1960			1	2			3
1920							0	1961	1		1	1	1	1	5
1921					2		2	1962			1	2	1		4
1922					2	1	5	1963		1	1	1			3
1923		1	1	2			4	1964			3	1			4
1924			1	3			4	1965			1	2			3
1925			3	1	1		5	1966				2	1		3
1926			1	2			3	1967			1				1
1927				1	1		2	1968			1	1	1		3
1928					2		2	1969					1		1
1929				1			1	1970			2	2			4
1930			2	1			3	1971				2	1		3
1931			2	1			3	1972			2	1	1		4
1932				2			2	1973			2	1			3
1933			3	1	2		6	1974			2	1	1		4
1934			1	1	1		3	1975			1	1			2
1935				1	1		2	1976			3	2	1		6
1936			1	2	1		4	1977				1	1		2
1937			1		1		2	1978		1		2	1		4
1938				1	1		2	1979				2			2
1939			1	1			2	1980			1	1	1		3
1940			2	1	2		5	1981		2	1		2		5
1941			1	2			3	1982				3	1		4
1942			1	3			4	1983					1		1
1943			3	1			4	Total	1	12	72	94	63	5	247
1944				1			1								

Table 6.56: The frequency and percentage of storms, which were grouped by their routes

Group	Frequency	Percentage (%)
S	58	23
W	48	17
E	34	14
WE	27	11
CWEN	27	11
CWES	21	9
CWN	17	7
Others	20	8
Total	247	100

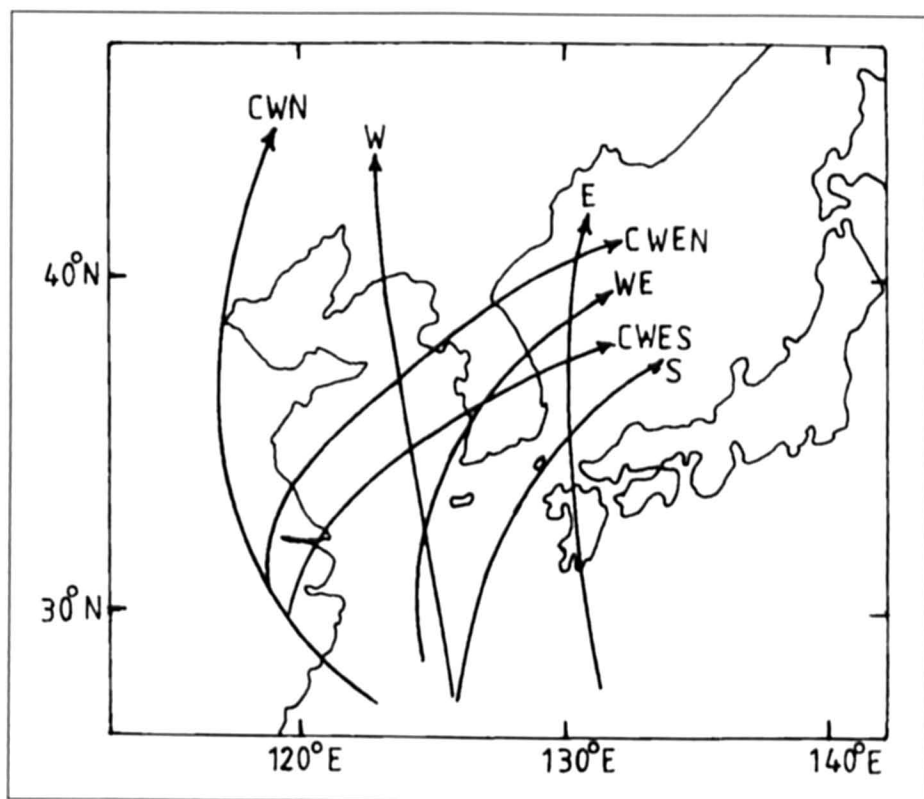


Fig. 6.107: Schematic representation of typhoon tracks (SHIN, 1994)

Table 6.57: Maximum tidal deviation at each station during the years 1957–1970 (SHIN, 1994)

[illegible]^a Tidal deviation caused by typhoon. ____ Same month

6.8.4 Philippines

Philippines is an archipelago of about 7,100 islands located between the South China Sea and the Pacific Ocean and the Southeast Asian continental shelf (BROWN et al., 1991). Its coastline of 17,460 km makes it particularly vulnerable to storm surges as it lies in the path of destructive typhoons.

During the period 1907–31, there were 43 significant storm surges in the Philippines (DAS et al., 1978). A storm of October 15–16, 1912, struck the towns of Leyte and Cebu and apparently caused 9-m surges at Sogod Norte in the Lisayan Islands. Typhoon Irma of October 24–26, 1981, caused major surges and destroyed one village.

Storm surges occur in the Sulu Sea, which is a water body on the southeastern corner of the South China Sea. Surges up to 1.22 m in amplitude and with periods of up to 75 min occur in this water body (HAIGHT, 1928).

Fig. 6.108 shows the various regions of Philippines considered in the study by BROWN et al. (1991). Fig. 6.109 shows the intensity map of strongest typhoons in Philippines. The intensity shown is the maximum wind speed in meters per second (mps) from any typhoon during this thirty year period. The historical distribution of storm surges around Philippines is shown in Fig. 6.110.

Table 6.58 lists the annual average landfall of typhoons in the regions shown in Fig. 6.108 whereas Tables 6.59 and 6.60 respectively show the probability of landfall of typhoons per year (in percent) and probability of at least one typhoon-crossing region. The average monthly frequency of typhoons for the period 1980 to 1989 is shown in Table 6.61. Tables 6.62 and 6.63 respectively list the vulnerability levels by region of typhoon hazards and annual typhoon damage and casualties.

Table 6.58: Annual average landfall of typhoons per region (BROWN et al., 1991)

Region	Latitude	Annual Average
Batanes (Region II)	19–22N	1.7
Northern Luzon (Regions I & II)	16–19N	2.7
Bicol and Quezon (Regions IV & V)	13–16N	1.9
Visayas (Regions VI & VII)	10–13N	1.9
Mindanao (Regions X, XI & XII)	7–10N	1.0
Total		9.2

Source: Philippine Atmospheric, Geophysical and Astronomical Services Administration (PAGASA)

Table 6.59: Probability of landfall of typhoons per year (in percent) (BROWN et al., 1991)

At least one	100
2 or more	100
3 or more	100
4 or more	100
5 or more	94
6 or more	77
7 or more	71
8 or more	64
9 or more	48
10 or more	39

Source: PAGASA

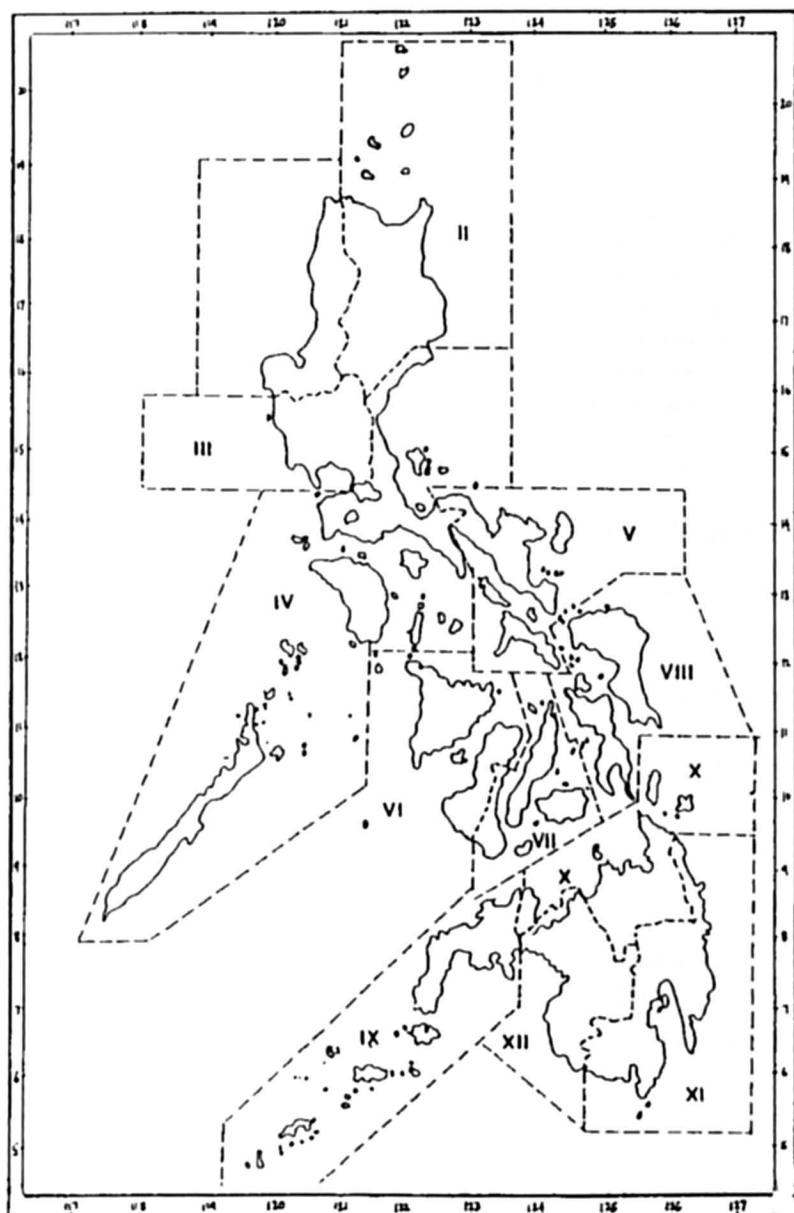


Fig: 6.108: Various regions of Philippines from the point of view of typhoons (BROWN et al., 1991)

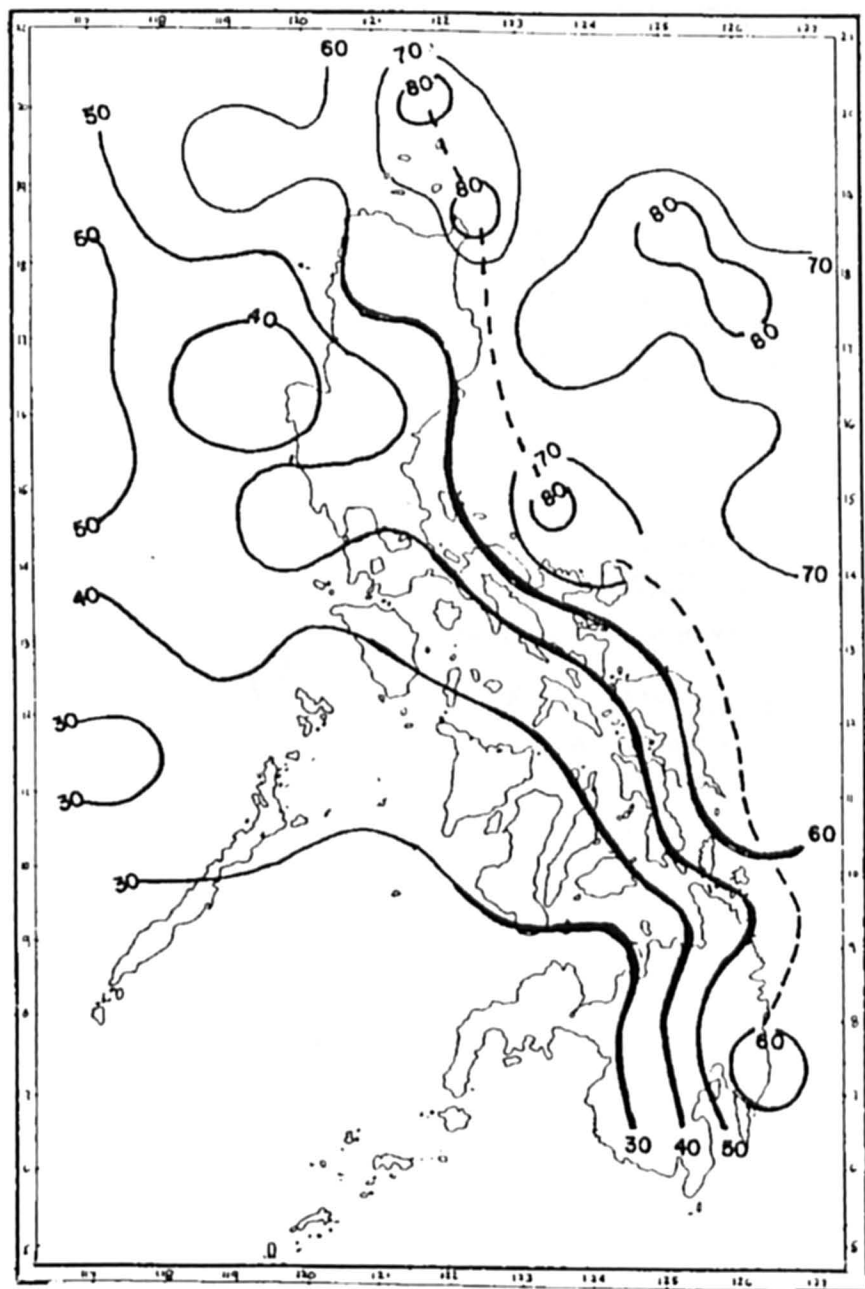


Fig. 6.109: Intensity (mps) of strongest typhoon, which passed every degree latitude – longitude square from 1960–1989 (BROWN et al, 1991)

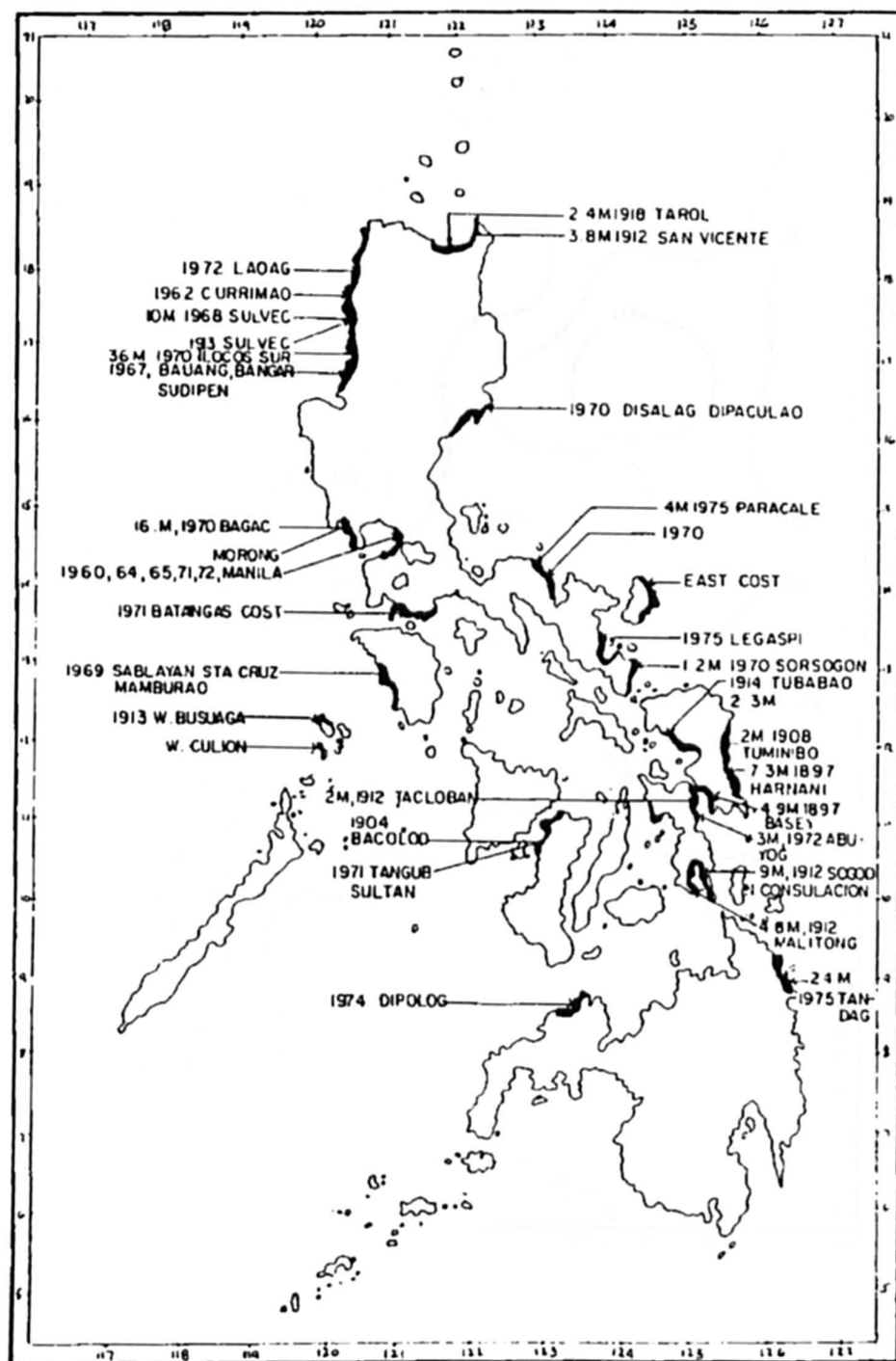


Fig. 6.110: Historical storm surges in the Philippines (BROWN et al., 1991)

Table 6.60: Probability of at least one typhoon crossing a region (BROWN et al., 1991)

Region	Probability (%)
Batanes (Region II)	90
Northern Luzon (Regions I & II)	87
Bicol and Quezon (Regions IV & V)	74
Visayas (Regions VI & VII)	87
Mindanao (Regions X, XI & XII)	58

Source: PAGASA

Table 6.61: Average monthly frequency of typhoons (1980–1989) (BROWN et al., 1991)

Months	Average frequency of typhoons	Probability of at least one typhoon making landfall (in percent)	Average frequency of making landfall
January	0.4	23	0.4
February	0.3	3	0.1
March	0.3	10	0.3
April	0.2	5	0.2
May	0.8	20	0.3
June	1.7	48	0.6
July	3.6	58	1.1
August	3.1	74	1.2
September	2.6	74	1.4
October	3.4	55	1.3
November	2.2	84	1.7
December	1.6	48	0.6
Total	20.2	100	9.2

Source: PAGASA

Table 6.62: Vulnerability levels by region for typhoons hazards (BROWN et al., 1991)

Region	High Winds	Floods	Storm Surge
National Capital	H	H	L
I	H	M	M
II	M	H	M
III	H	H	M
IV	H	M	H
V	H	H	H
VI	M	M	M
VII	M	L	M
VIII	H	M	H
IX	L	L	L
X	H	H	H
XI	M	M	L
XII	n.a	H	n.a
Cordillera ^{A/}	H	n.a	n.a

n.a. Not Applicable

A/ Prior to 1989, CAR was part of Region I

Source: Table composed by consultants

Table 6.63: Annual typhoon damage and casualties (BROWN et al., 1991)

	Billions of Pesos	(in Lives Lost current Prices)
1980	1.4	143
1981	1.3	484
1982	1.6	337
1983	0.5	126
1984	5.8	1979
1985	2.7	211
1986	1.7	171
1987	4.0	1020
1988	8.7	429
1989	4.5	382
Total	32.2	5282
Average	3.2	528

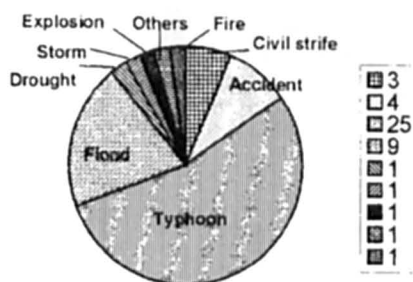
Source: Office of Civil Defense (OCD)

6.8.5 Vietnam

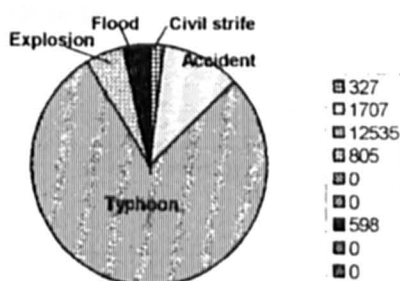
Storm surges occur on the east coast of North Vietnam and on the east and south coasts of South Vietnam. NICKERSON (1971) used SPLASH models to study these surges. One of the worst storm surges in human history occurred in 1881 in which about 300,000 people were killed in the area surrounding Haiphong (LACOUR, 1917c).

IMAMURA and TO (1997) studied storm surges and other natural disasters in Vietnam for the period subsequent to 1997. Fig. 6.111 shows the cost of natural and human made disasters in Vietnam for this period whereas Fig. 6.112 shows the damage due to typhoons. Fig. 6.113 shows the areas affected by floods and storm surges. Fig. 6.114 shows the tracks of typhoons Andy and Cecil in 1995, which devastated Central Vietnam. Fig. 6.115 shows the dyke system of Vietnam for protection against storm surge inundation and floods.

Disaster events (1953-1991)



Killed/missing people(1953-1991)



Damage(K\$)(1953-1991)

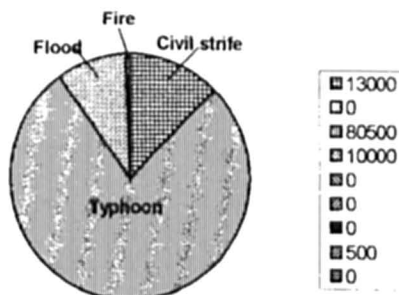


Fig. 6.111: Estimated damage caused by man-induced and natural disasters in Vietnam (1953-1991) (IMAMURA and TO, 1997)

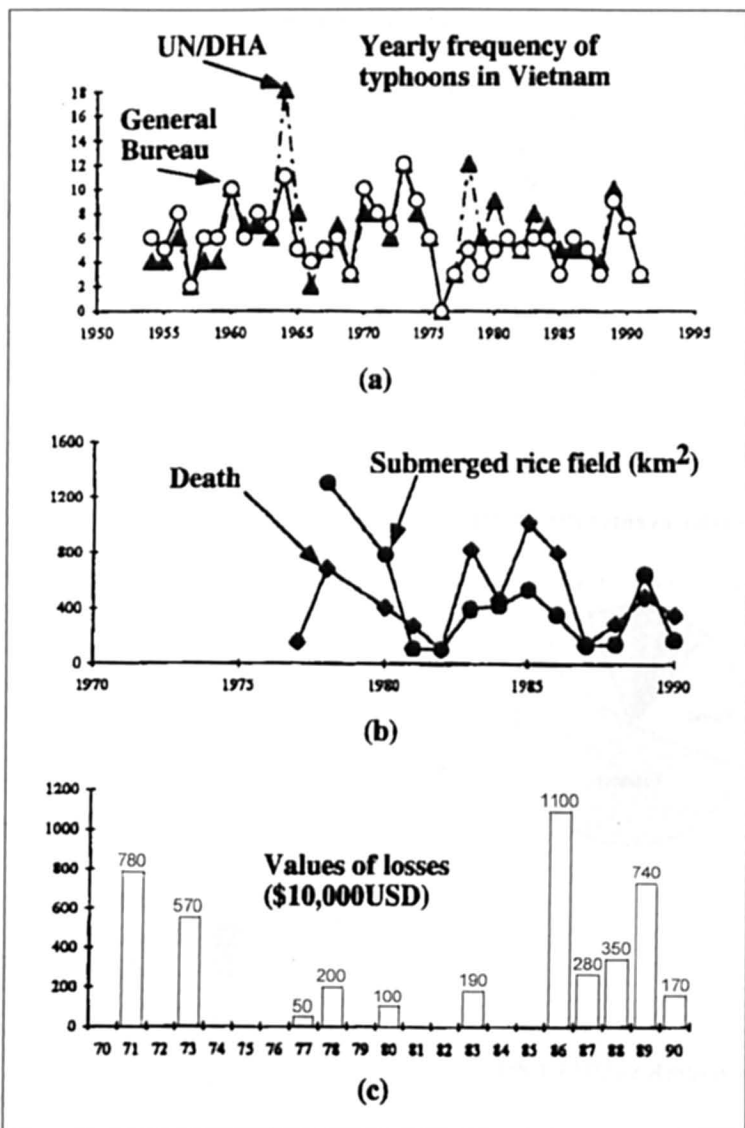


Fig. 6.112: (a) Frequency of typhoons and (b) flood damage death, submerged rice field, and (c) value of losses (IMAMURA and T_O, 1997)

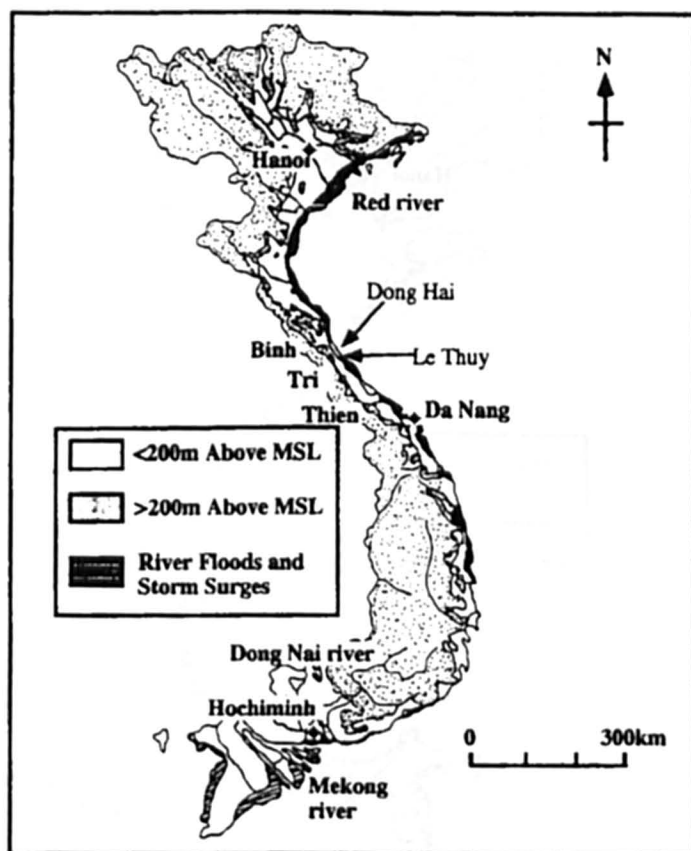


Fig. 6.113: Topography of Vietnam with elevation above sea level and areas damaged by river floods and storm surges shown by the horizontal shades (IMAMURA and TO, 1997)

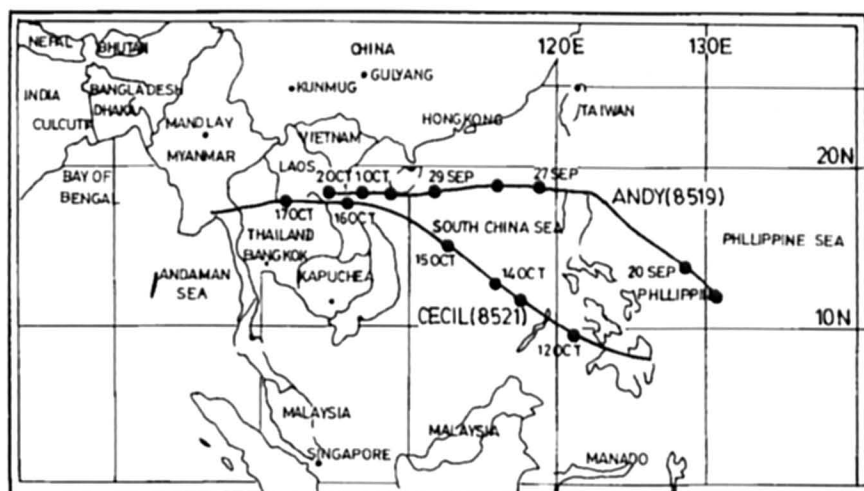


Fig. 6.114: Map of Vietnam, located in eastern Indo-China and the route of typhoons, Andy and Cecil in 1985, which devastated central Vietnam (IMAMURA and TO, 1997)

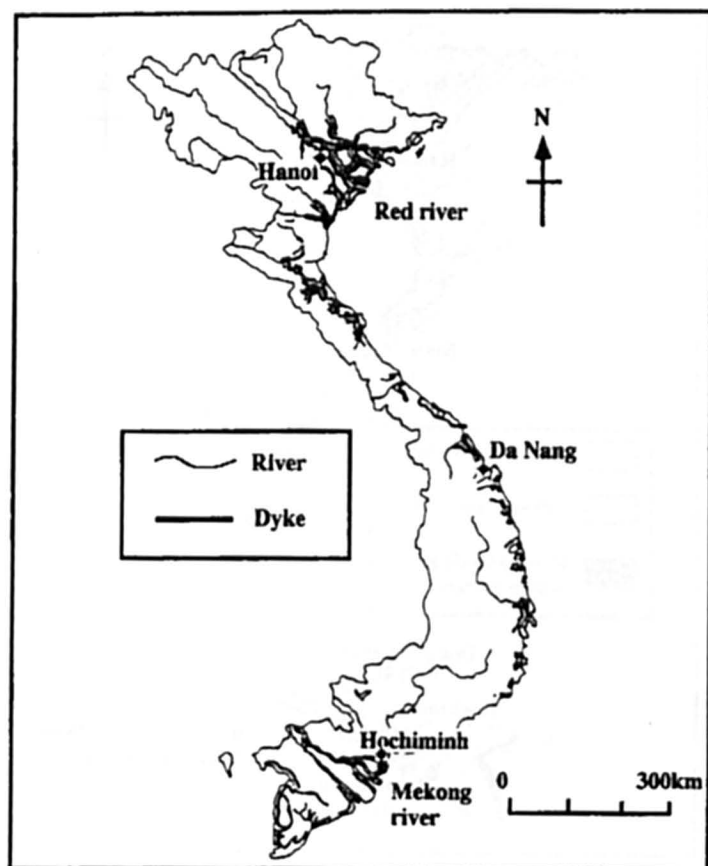


Fig. 6.115: Dike system in Vietnam along river and coasts. The system started more than 2000 years ago (IMAMURA and TO, 1997)

Table 6.64 compares the frequency of typhoons in various Southeast Asian countries. Table 6.65 and 6.66 respectively show the monthly frequency of typhoons during the period 1954 to 1991 and those that struck various districts.

Table 6.64: Frequency of typhoons in the Southeast Asian countries in 1985–1989 (IMAMURA and TO, 1997)

Country	1985	1986	1987	1988	1989	Total
China	8	6	4	4	11	33
Philippines	4	6	5	5	7	27
Japan	10	2	3	4	4	23
Rep. Of Korea	8	3	2	0	1	14
Vietnam	2	1	3	2	4	12
Hong Kong	2	3	1	3	2	11
Thailand	1	1	2	0	1	5
Malaysia	0	1	0	2	0	3
Total	17	11	12	12	19	71

Table 6.65: Monthly frequency of typhoons in Vietnam in 1954–1991 (IMAURA and TO, 1997)

Period	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec	Total	Average
1954–59	0	0	0	1	1	4	3	9	7	5	2	1	33	5.5/yr.
1960–69	0	0	0	0	1	6	8	15	17	9	8	1	65	6.5/yr.
1970–79	0	0	0	0	–	6	7	11	15	10	10	4	63	6.3/yr.
1980–89	0	0	2	1	1	6	5	5	9	21	5	0	54	5.4/yr.
1990–91	0	0	1	0	0	0	1	2	1	3	2	0	10	5.0/yr.
Total	0	0	3	2	3	22	24	42	48	48	27	6	225	5.9/yr.

Table 6.66: Monthly frequency of typhoons, which struck the district regions of Vietnam (1954–1991) (IMAMURA and TO, 1997)

Region	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec	Total
Northern	0	0	0	0	0	15	24	28	22	7	1	0	97
Central	0	0	0	1	2	0	0	14	23	35	6	0	81
Southern	0	0	3	1	1	7	0	0	3	6	20	6	47
Total	0	0	3	2	3	22	24	42	48	48	27	6	225

6.8.6 Thailand

VONGVISESSOMJAI (1994) studied storm surges in the upper Gulf of Thailand. Table 6.67 lists the characteristics of historic cyclones for this region. Fig. 6.116 shows the position of the inter tropical convergence zone (ITCZ) at three different times in the year and typhoon approach directions. Fig. 6.117 shows the typhoon tracks for the month of October for the period 1961 to 1970 whereas Fig. 6.118 shows the tracks of tropical cyclones for the period 1952 to 1974. The recurrence interval of maximum wind velocity and central pressure index for cyclones affecting the Gulf of Thailand is shown in Fig. 6.119.

Table 6.67: Historical cyclone characteristics (VONGVISESSOMJAI, 1994)

No.	Year, Month, Date	Name	CPI or P_0 (millibars)	Max. Velocity U_{\max} (mph)	Forward Speed, V_F (miles/hr)	Radius, R (nautical miles)
1	1952 Oct 21-22	VAE	990	53	14.97	6.7
2	Oct 24-25	TRIX	998	44	17.27	60
3	1960 Oct 3-4	-	992	52	3.45	8.4
4	1962 Jul 12-13	-	990	53	18.45	10.6
5	1966 Jun 17-18	-	-	-	12.67	-
6	Oct 25-26	-	990	48	9.21	49
7	1967 Jun 16-27	-	978	62	12.67	140
8	Oct 5-6	-	996	49	11.52	16
9	Oct 9-10	-	998	44	17.27	90
10	Nov 10-11	-	-	-	12.67	-
11	1968 Sep 5-6	BESS	992	44	2.3	115
12	Oct 21-22	HESTER	998	46	11.52	10
13	Jun 24-25	-	998	46	6.91	7.5
14	Sep 20-21	-	992	51	12.67	57
15	Nov 2-3	-	1000	45	16.12	10
16	1970 Sep 20-21	-	994	52	13.82	20
17	Oct 25-26	KATE	1000	27	13.82	314
18	Nov 29-30	RUTH	1000	42	11.52	32
19	1972 Jun 3-4	NAMIE	990	48	6.91	123
20	Sep 6-7	-	990	49	4.61	16
21	Sep 18-19	-	-	-	-	-
22	Dec 4-5	SALLY	994	50	5.76	5
23	1973 Nov 12-13	-	1002	38	5.76	4
24	Nov 17-18	THELMA	998	45	5.76	39
25	1974 Oct 9-10	-	1002	34	6.91	15
26	Nov 5-6	-	998	45	13.82	60

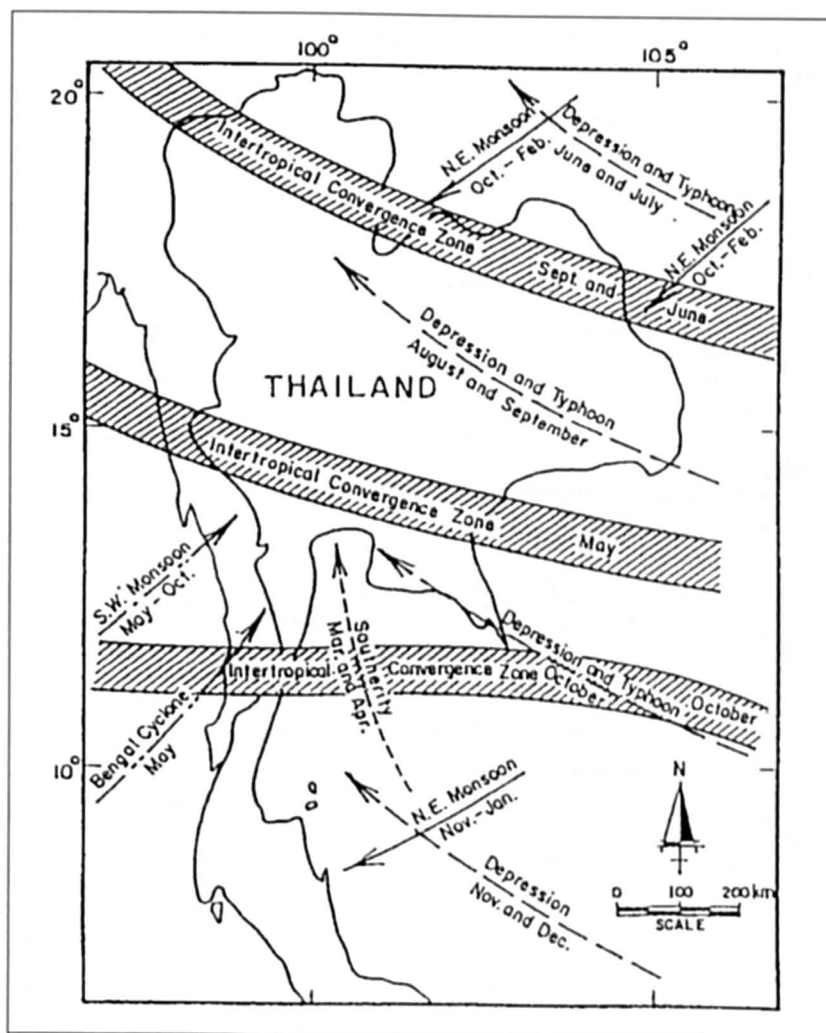


Fig. 6.116: Monsoon and storm tracks in Thailand (VONGVISESSOMJAI, 1994)

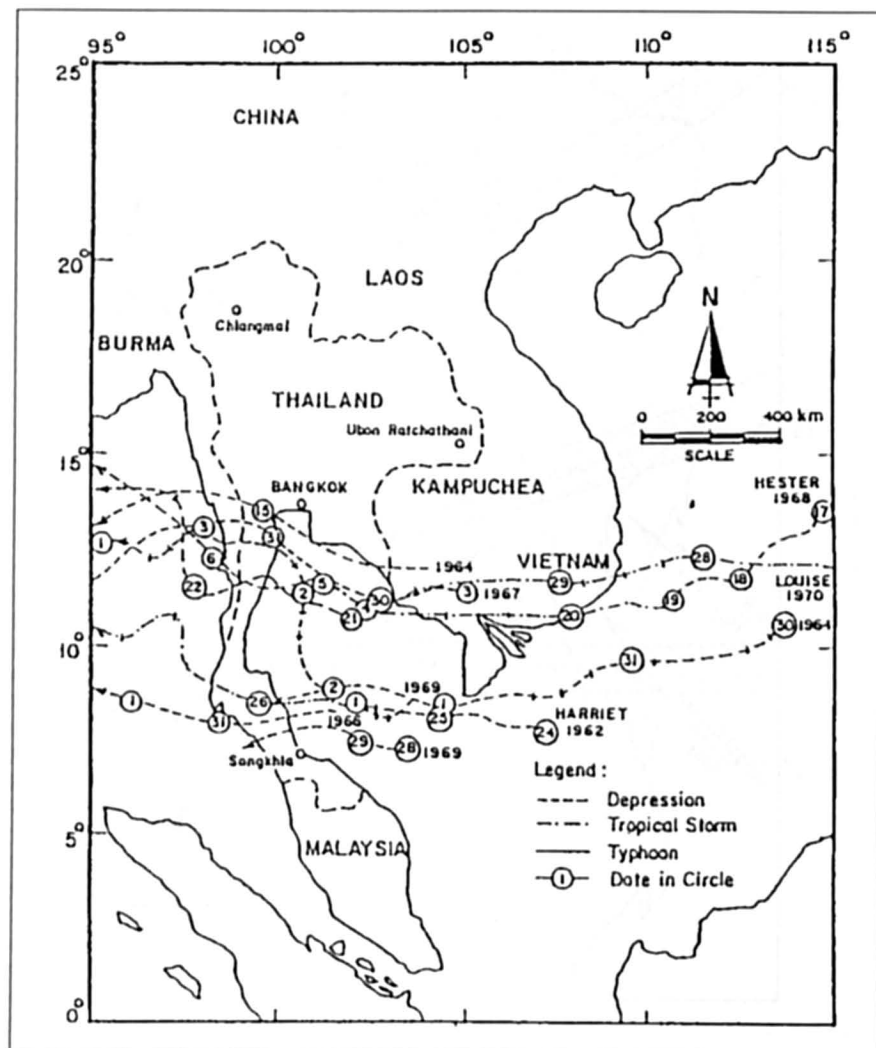


Fig. 6.117: Tracks of cyclones over the Gulf of Thailand in October 1961 to 1970
(VONGVIESSOMJAI, 1994)

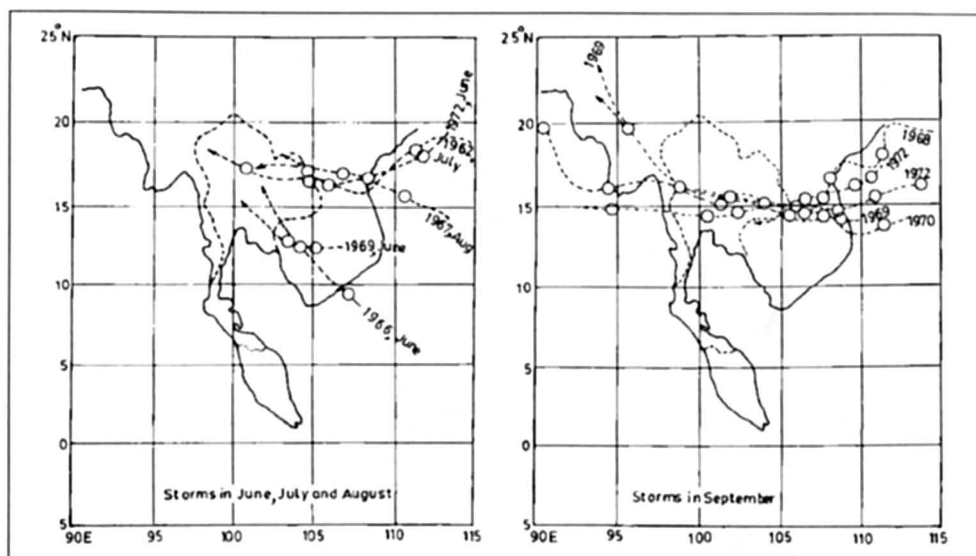


Fig. 6.118: Tracks of tropical cyclones over the Gulf of Thailand and its vicinity between 1952–1974 A. D. Encircled numbers are the positions of storm centers at 7 am on the days shown (VONGVISES-SOMJAI, 1994)

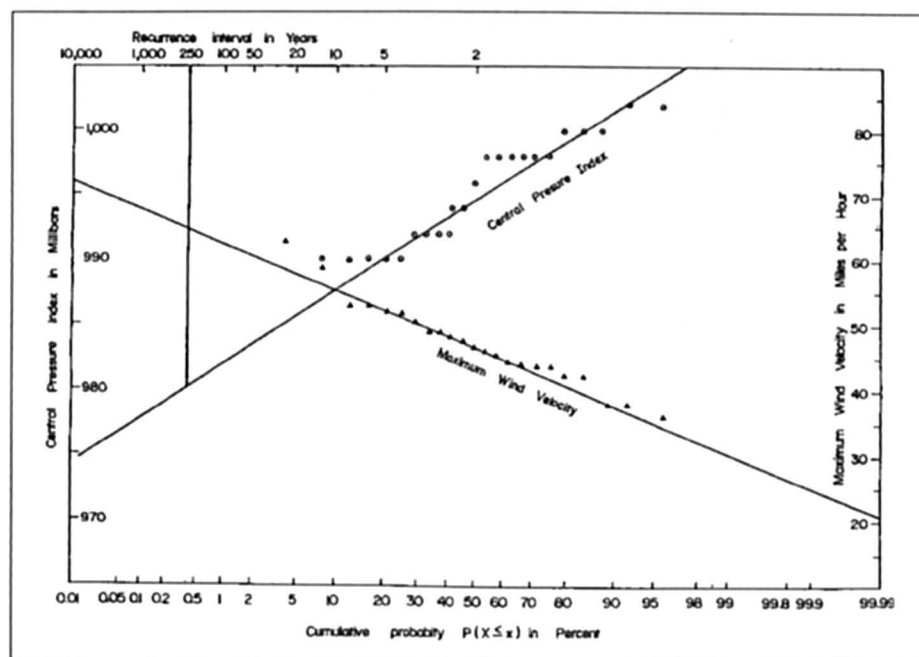


Fig. 6.119: Recurrence interval of cyclone characteristics for the Gulf of Thailand (VONGVISES-SOMJAI, 1994)

Fig. 6.120 shows the wind field for the probable maximum cyclone (PMC) for the Gulf of Thailand. Figs. 6.121 and 6.122 respectively show the peak surge and maximum wind wave at Aophai for the PMC and a 250 year typhoon.

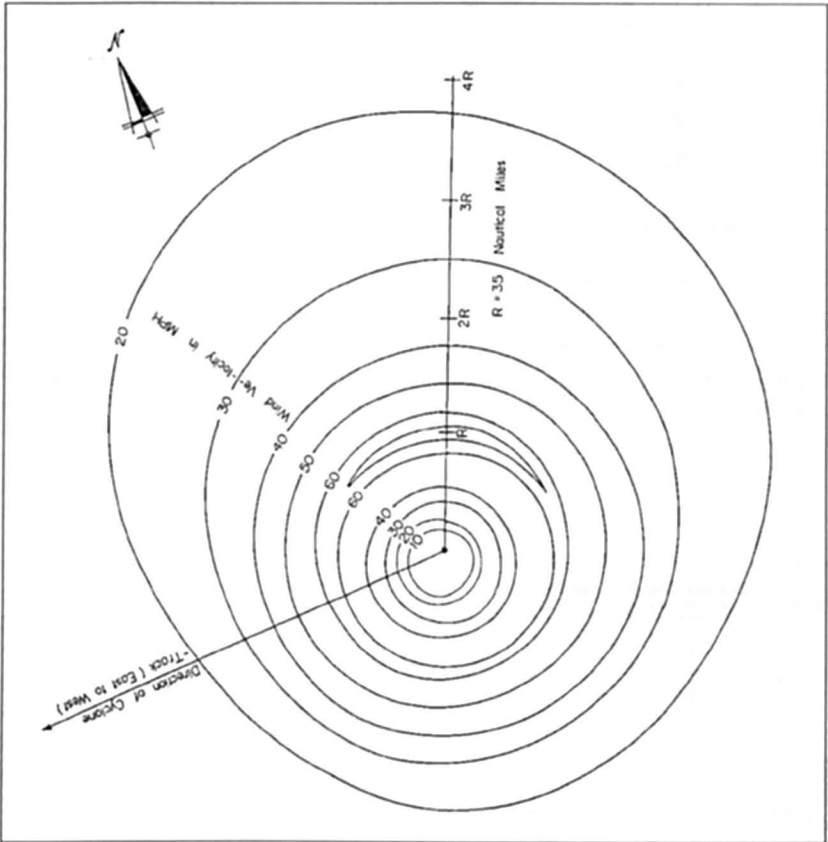


Fig. 6.120: Wind field of the probable maximum cyclone for the Gulf of Thailand (VONGVISESSOMJAI, 1994)

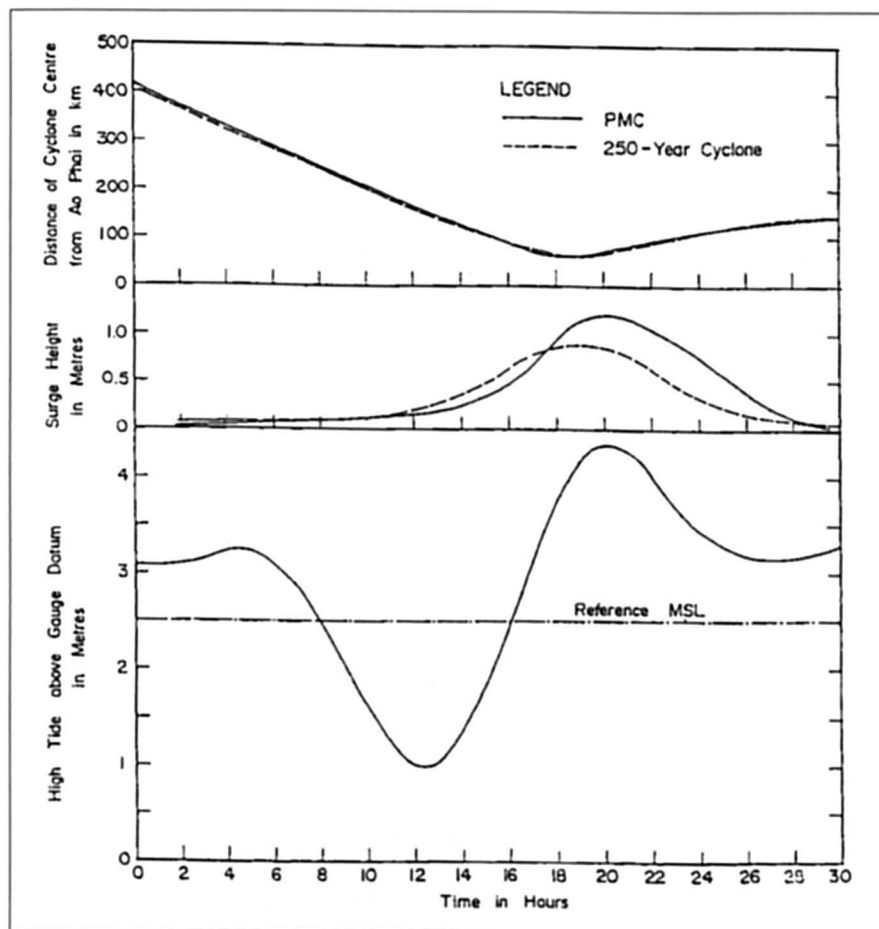


Fig. 6.121: Probable maximum cyclonic surge (PMC & 250 year) and high tide at Ao Phai (VONGVIESSOMJAI, 1994)

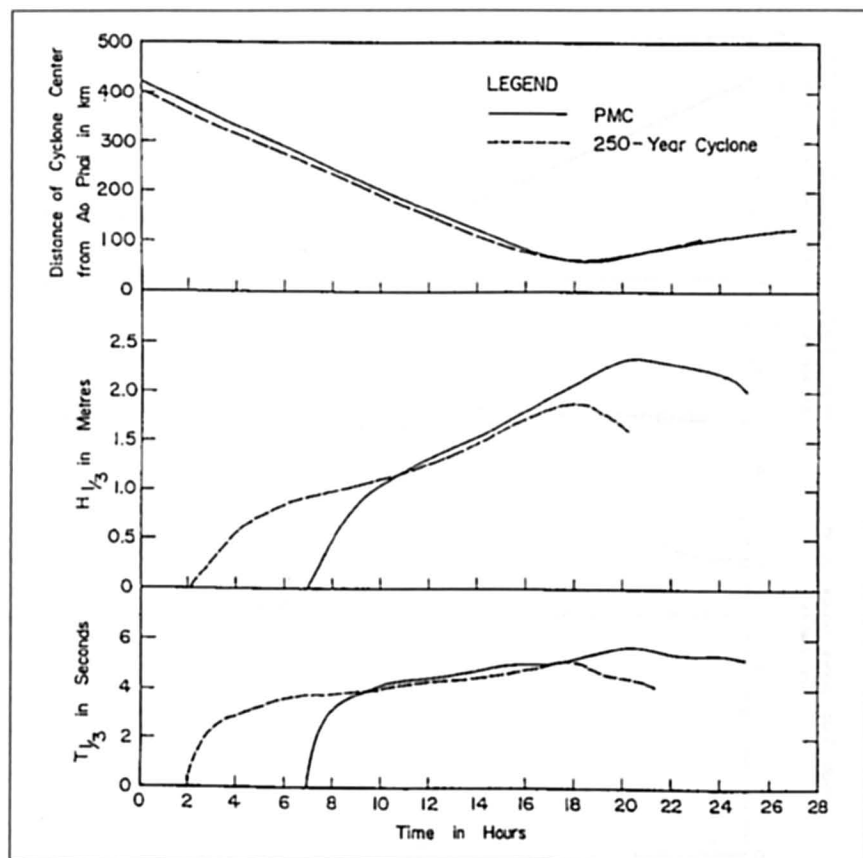


Fig. 6.122: Probable maximum wind wave (PMC & 250 year) at Ao Phai (VONGVISESSOMJAI, 1994)

7. Storm Surges Generated by Extra-Tropical Cyclones – Case Studies

7.1 North America

Earlier we mentioned that there appears to have been a decrease in the frequency of tropical cyclones (TC's) during the second half of the 20th century. For the frequency of extra-tropical cyclones (ETC's) the opposite might be true as can be seen from Fig. 7.1.

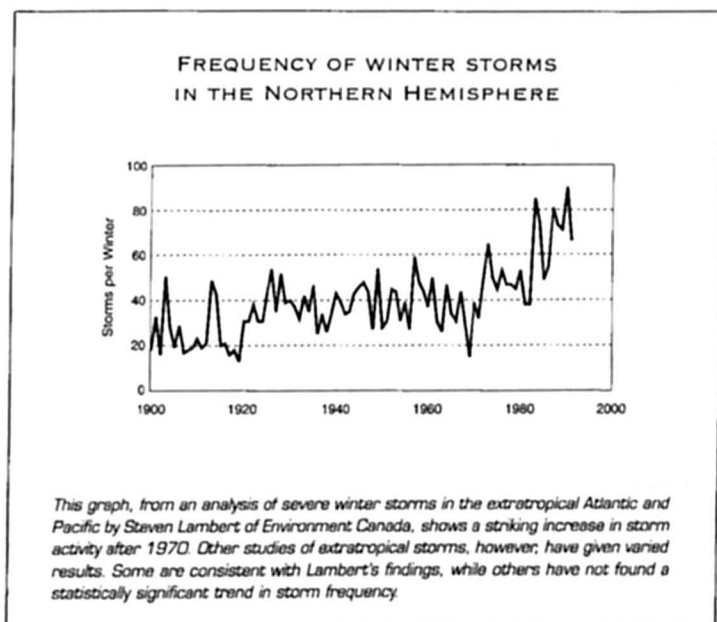


Fig. 7.1: Frequency of winter storms in the Northern Hemisphere (LAMBERT, 1995)

BODE and HARDY (1997) made some interesting observations on the development of research in storm surge modelling (SSM). We quote a few sentences below from their work.

"The storm surge phenomenon has long been characterised by a geographic divide. Surges tend to be associated either with mid-latitude storms or, often more disastrously with tropical cyclones. This divide has also extended, somewhat artificially into the modelling area. The efforts of various modelling groups are usually concentrated in one geographic region or the other. This separation of effort is reflected in recent research, in which many of the noteworthy developments have occurred in Europe, leading to the development of operational mid-latitude operational storm surge warning systems.

However, little corresponding development appears to have been supported in recent times for hurricane surge prediction. Presumably, this is a reflection of the magnitude and difficulty of the problem, but also of relative funding levels allocated for such purposes. A logical starting point is the review of HEAPS (1983), which concentrated on midlatitude storm surges. At that stage, European models have advanced to the point where NWP (Numerical

Weather Prediction) models of National Meteorological Services were being coupled to storm surges models to provide routine operational storm surge forecasts.

The foremost requirement for SSM is an accurate wind field model and the divide between the midlatitude and tropical cases is most pronounced here. Midlatitude models take their wind (and pressure) fields from operational NWP models, which generally perform well. (Although exceptions arise, such as the great storm of 1987 in U. K. for which forecasts largely failed.

7.1.1 Errors in the Specification of Wind Fields

CARDONE et al. (1980) discussed errors in the techniques, which are generally in use for the specification of wind fields for ETC's. They make the important point that the accuracy of specifications of extrapolated marine surface winds is limited basically by the sparsity of observations of surface wind and sea-level pressure from ships rather than by intrinsic shortcomings in the technique of analysis. However, it should be noted that during these past two decades subsequent to 1980 when CARDONE et al. (1980), published their paper, there is progressively less reliance on ships for marine winds and more reliance on ocean buoys and remote sensing through satellites.

According to these authors, three basic methods are available for elaborating surface marine wind fields in historical storms: (a) Use of parametric wind models (b) Objective analysis and (c) Direct Kinematic analysis. Parametric wind models have been successfully applied for tropical cyclones, but are not appropriate for the complex patterns of surface winds associated with ETC's.

Objective analysis methods were developed in the 1960's to satisfy the need for fast production, in real time, of fields of meteorological variables on grids for use in numerical forecast models. Objective analysis schemes for surface marine wind fields usually include (1) an initial guess at the surface wind on a regular grid, (2) a method for automatically screening a collection of wind reports from ships to eliminate highly discrepant and presumably erroneous winds, and (3) a method for blending the ship reports into the initial guess. Such schemes usually exploit the relation between the surface marine wind and the local pressure gradient by calculating the initial-guess winds from a marine sea-level pressure field, which in turn derives from an objective analysis of surface pressure measurements on land and sea.

CARDONE (1969) described an objective analysis scheme that included the application of a model of the wind profile in the planetary boundary layer (PBL) that related the surface marine wind velocity to the local pressure gradient, the air/sea temperature difference, and the atmospheric thermal advection. Winds derived from the PBL model, and reduced to a standard height of 19.5 m, are blended with winds from ship reports after the latter are ranked in order of presumed accuracy.

Kinematic analysis is a tedious, time-consuming, entirely manual procedure that only experienced analysts can execute successfully. The basic steps involved are (1) plot all synoptic ship reports on suitable meteorological base maps for the entire storm event, (2) standardize wind measurements to 19.5 m, using a marine-wind-profile model for measured winds where the ship's anemometer height is on file, and using the Beaufort conversion procedure described earlier for estimated winds, (3) identify and reject erroneous and unrepresentative reports so far as possible, (4) construct a continuity chart containing the "solution" for the storm event in terms of the movement of major discontinuities, singularities and other features of the surface wind field, and (5) construct streamlines and isotachs.

7.1.2 Great Lakes

Several finite element models are now available which have been referred to in chapter three. Here we will give a few more general references for the application of the impulse response method for storm surge computation, see SIMONS and SCHERTZER (1989). This method will be successful for those situations where there is linear dynamics for storm surge generation.

SCHWAB (1982) showed that this method could be inverted to provide an estimate of Overlake wind fields from observations of water level fluctuations around the shore of the lake. HAMBLIN (1987) provided a review of lake Erie storm surge computation techniques.

SCHWAB and LYNN (1987) developed a simple computer program for estimating the maximum and minimum storm surge amplitudes for the Great Lakes. The user has to provide a mean lakewater level, a wind speed and a wind direction. The program then lists maximum and minimum expected water level at several points on the shoreline of the selected area. The program covers the U. S. Shoreline only, (not Canadian) separately for the following water bodies: Lake Ontario, Central and Eastern Lake Erie, Western Lake Erie, Lake St. Clair, Lake Huron, Saginaw Bay, the Eastern Shore of Lake Michigan, the western shore of Lake Michigan, Green Bay and Lake Superior.

7.1.3 East Coast of Canada

PARKES et al. (1997) discussed storm surge events in the Maritime (eastern) provinces of Canada. MURTY et al. (1994) reviewed storm surges in Canadian waters. GRAY et al. (1984) used numerical models to simulate storm surges on the Nova Scotia Coast (Table 7.1). Fig. 7.2 shows the area of study. Here CMC refers to the Canadian Meteorological Center Fig. 7.3 shows the grid used in the numerical model.

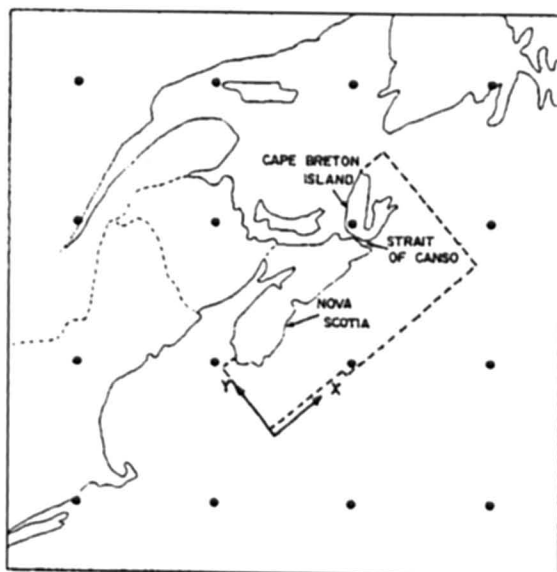


Fig. 7.2: Orientation of CMC and storm surge model grids showing the array of 4×4 CMC grid points (dots), and the computational domain of the storm surge model (dashed line) (GRAY et al., 1984)

Table 7.1: Comparison between computed and observed amplitudes (cm) and phases (deg.) of the M_2 tide (observed values taken from the Admiralty Tide Tables, except where indicated) (GRAY et al., 1984)

Grid Numbers*	Port	Observed		Computed	
		Amp.	Phase	Amp.	Phase
1	Yarmouth	163	63	163	63
2	Lower E. Pubnico	127	39	134	38
3	Sea Island	120	52	127	43
4	Clark Harbour	106	27	110	22
5	Lockeport	70	359	71	357
6	Liverpool	65	353	64	355
7	Lunenburg	60	353	64	354
8	Boutilier Point	64	352	66	353
9	Halifax	62	352	64	353
10	Jeddore Harbour	65	352	64	352
11	Sheet Harbour	62	347	64	351
12	Sonora	62	351	64	349
13	Isaac's Harbour	56	352	65	348
14	White Head	54	347	63	347
15	Canso Harbour	59	347	62	346
16	Point Tupper	59	344	66	345
17	Cannes	56	351	62	344
18	Loudibourg	50	344	52	344
19	North Sydney	38	355	43	350
20	Dingwall	27	11	32	354
21	St. Paul Island	31	6	31	6
22	Sable Island	52	352	57	350
23	T1**	48	351	48	353
24	1.2.23	49	350	50	354
25	T21**	49	357	48	355

* See Fig. 7.21

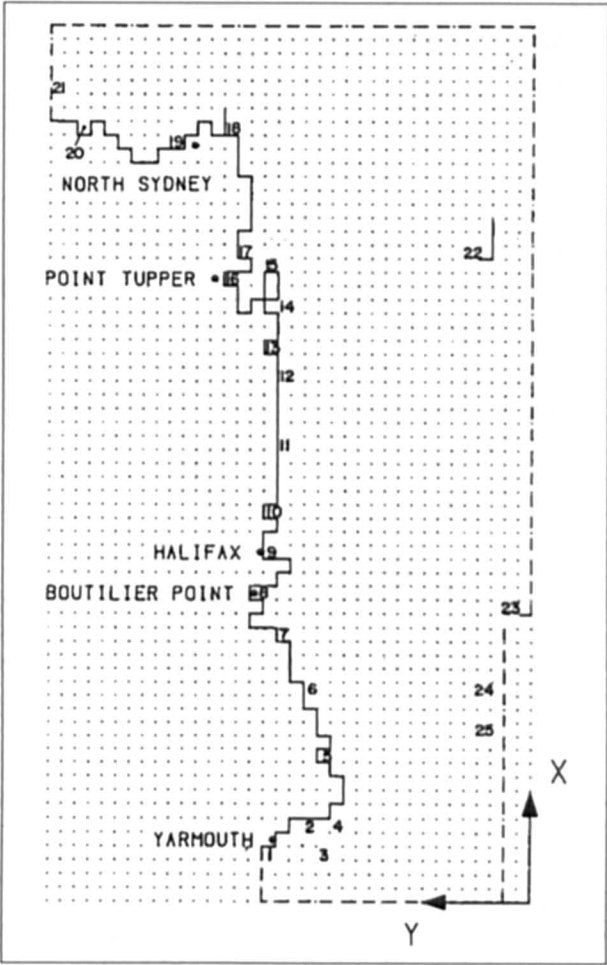


Fig. 7.3: Nova Scotia storm surge grid showing the coastline (solid line) and open – sea radiating boundary (dashed line). Numbers indicate the tidal stations listed in Table 7.1 (GRAY et al., 1984)

Fig. 7.4 shows the track of the Ground Hog Day storm of February 1976. The sea-level pressure map for 2nd February 1976 is shown in Fig. 7.5. Figs. 7.6 and 7.7 respectively show the wind stress computed on two grid spacings.

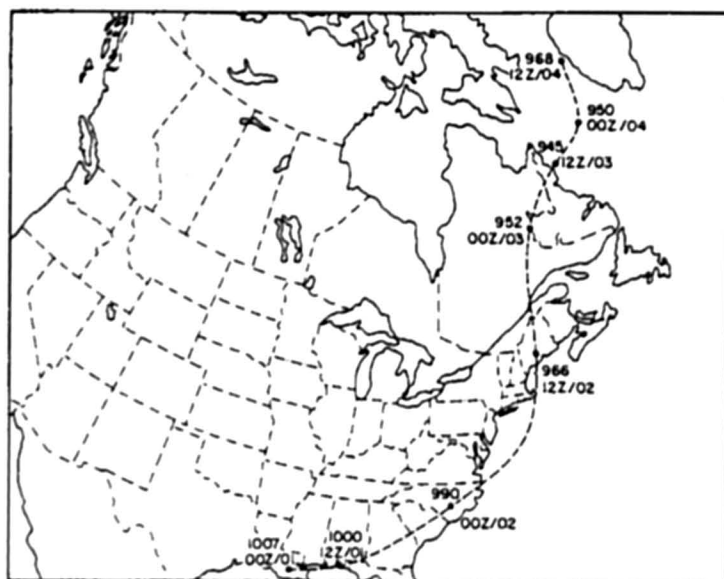


Fig. 7.4: Observed track and central sea-level pressures (mb) of the low center from 0000 GMT 1 February (00Z/01) to 1200 GMT 4 February (12 Z/04) 1976 (GRAY et al., 1984)

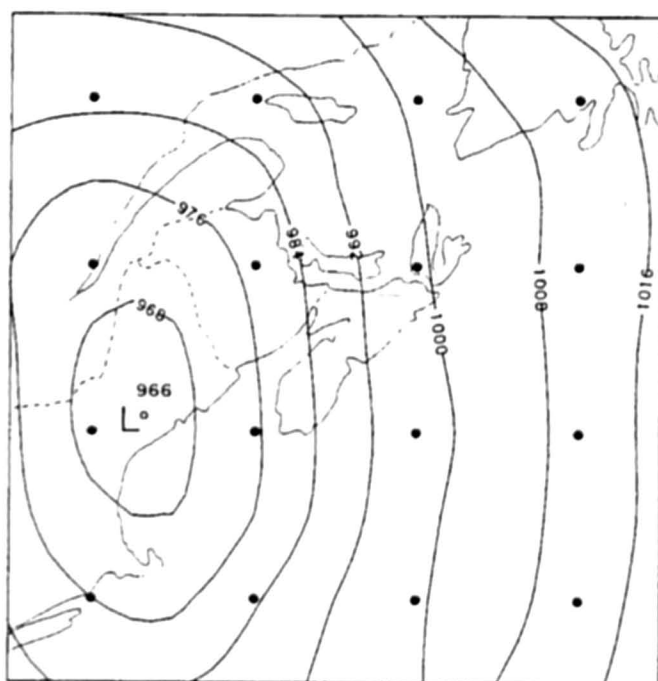


Fig. 7.5: Sea-level pressures (mb) at 1200 GMT 2 February 1976 (GRAY et al., 1984)

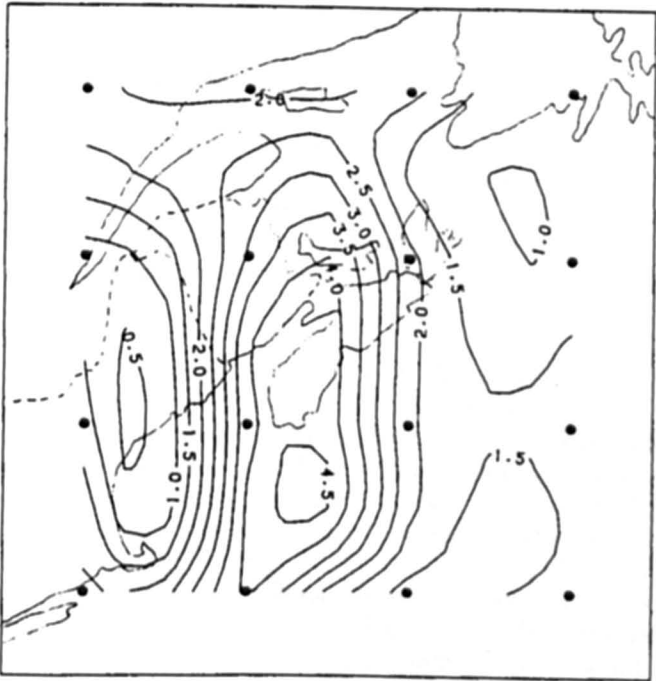


Fig. 7.6: Wind stress (Pa) at 1200 GMT 2 February 1976 computed from subjectively analysed sea-level pressures (190-km grid spacing) (GRAY et al., 1984)

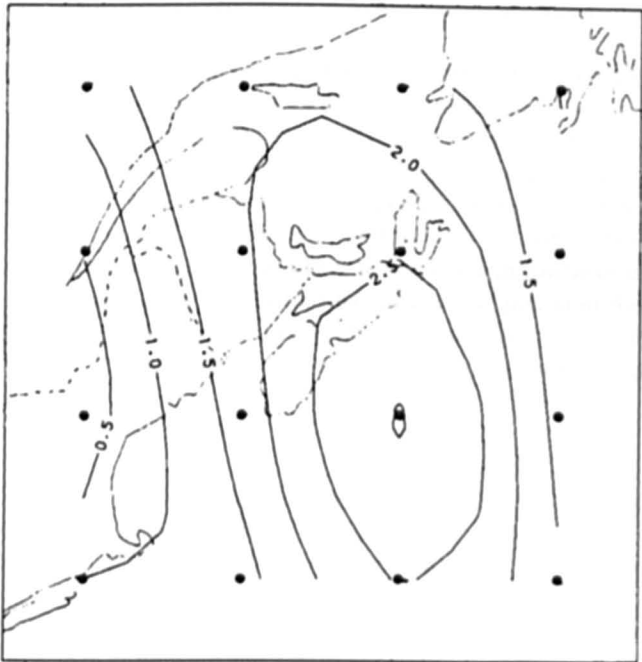


Fig. 7.7: Wind stress (Pa) at 1200 GMT 2 February 1976 computed from CMC analyzed 1000-mb heights (38-km grid spacing) (GRAY et al., 1984)

The model is designed to be run, using CMC (Canadian Meteorological Center) prognostic data. The model incorporates a quadratic bottom friction term and is capable of including advective, topographic and tidal effects. It can simulate a moving land-sea boundary approximately.

The model is applied to the East Coast of Nova Scotia for the "Ground Hog Day" storm of February 1976. Meteorological forcing is calculated using subjectively analysed sea-level pressures. Away from open boundaries, the agreement with observed surge residuals is generally good. However, the results are less satisfactory near the boundaries. CMC meteorological data are found to underestimate the surface wind stress during this period.

7.2 South America

The Rio de la Plata estuary is located on the Atlantic Coast of South America, with the cities of Buenos Aires (Argentina) and Montevideo (Uruguay) along its shores (O'CONNOR, 1991). The length of the estuary is about 270 km and its width varies from about 230 km at its mouth to 25 km at its head where the Parana and Uruguay rivers meet. The depth of the estuary at its mouth is 20 m.

GAGLIARDINI et al. (1984) divided the estuary into three regions: (a) Upper region (Playahonda) leads from the river delta and is less than 5 m deep (b) Intermediate region stretches from Buenos Aires to Montevideo and has several shallow banks (c) the outer region is wide and extends to the ocean. Here the continental shelf has a width of about 200 km.

The tidal range in the estuary is about 2 m. Storm surges due to south easterly winds from a stationary cyclone over the estuary can generate storm surges with amplitudes greater than 3 m. Historically, surges up to 4 m in amplitude have occurred over periods of several hours to several days.

The largest surges are along the coast of Argentina near Buenos Aires. This is due to the shallowing and narrowing of the estuary, the long fetch over which the wind acts on the water surface and the effect of the Coriolis Force (O'CONNOR, 1991). According to BALAY (1959) surges with amplitudes greater than 3 m have occurred in the years - 1914, 1922, 1923, 1940, 1958 and 1959. During the 27-28 July 1958 event, the flood depths were 3 to 4 m along the Buenos Aires shore for 100 km, but there was little flooding along the coast of Uruguay.

On the other hand during the storm of 10-12 July 1923, southerly winds lasted two days and surges up to 6 m in amplitude occurred on the coast of Uruguay, east of Montevideo. O'CONNOR (1991) numerically simulated the tides and storm surges in Rio de la Plata estuary and his results agreed reasonably well with those shown in Fig. 7.8.

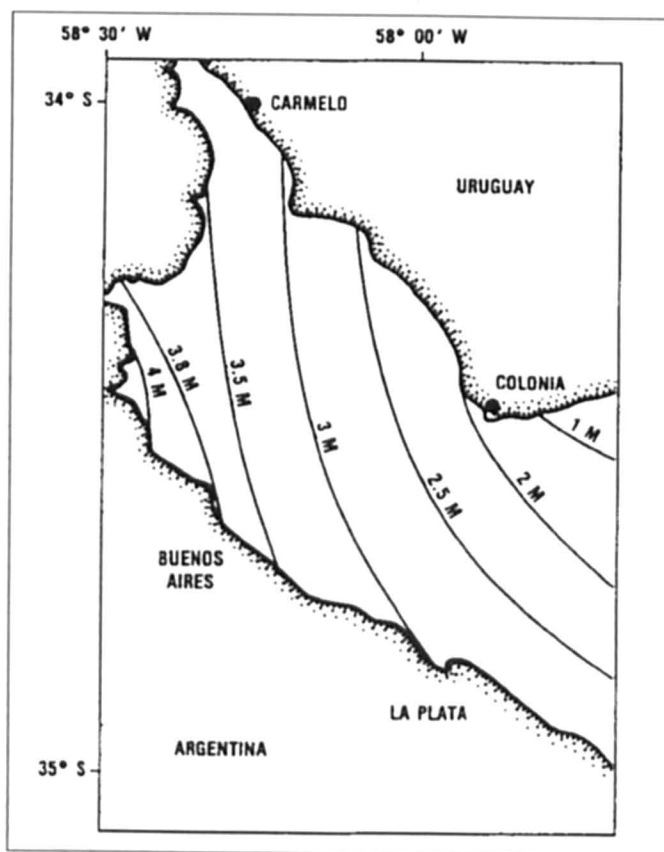


Fig. 7.8: The sea level in meters at the time of maximum surge, 27 July 1958 (BALAY, 1959)

7.3 Storm Surges in Europe

In section 5.1.2 the meteorological problems associated with storm surges in European waters were introduced. Here, case studies of storm surges in several water bodies in Europe and environs will be considered.

7.3.1 North Sea

The North Sea is a border sea of the Atlantic. The oscillation of the Atlantic effects the North Sea from the north through the channel. The shape of the basin, the depth and coriolis force influence the tide. The tide runs along the Scottish and English coastline with a mean tidal range of 4.20 m at Aberdeen and 7.20 m at Immingham and reaches the Dutch coast after crossing the Strait of Dover. There the tidal range increases from 1.50 m at Den Helder (135 cm at Texel) to 2.28 m at Borkum and 3.00 m at Cuxhaven, is the same till Pellworm and decreases from there to the Danish coast with 1.83 m at Sylt and 1.70 m at Rømø. The tidal range increases again from the islands to the continental coast.

The counterclockwise rotation of the tide can be seen in the progression of a storm surge from Aberdeen over Southend, Dover, Newhaven Hoek van Holland, Cuxhaven to Bergen. Fig. 7.9A shows the surge profiles along the western side of the North Sea during January 6–10, 1949, beginning at Aberdeen and ending at Newhaven. The surge profiles along the eastern boundary of the North Sea during the same period are given in Fig 7.9B. One can see first a counterclockwise progression of the disturbance with about the same propagation velocity as that of the diurnal tide (Fig. 7.10). The interaction between the tide and surge appears to be small (note that in the Thames Estuary the tide-surge interaction is significant). Second, one can see the progression of the surge height, which rises from Aberdeen to Southend and falls in the Strait of Dover from Dover to Newhaven. The increase of water level height at Grimsby, Kings Lynn and London Bridge is influenced by the topography of the locations of these gauges in an estuary or small basin like the Wash. But in general it can be stated that there is a level increase, because at Felixstowe and Dover it is higher than at Hartlepool. In this storm event at the eastern boundary of the North Sea the water level increases a little from the Dutch coast to the German coast till Cuxhaven and decreases from there to Norway (Bergen). As the storm surge of April 2–6, 1973, DAVIES and FLATHER (1977) compared the calculated and observed surges at five locations along the south and west coasts of the North Sea, which confirm this. A change of the wind direction can modify this development at the eastern boundary of the North Sea.

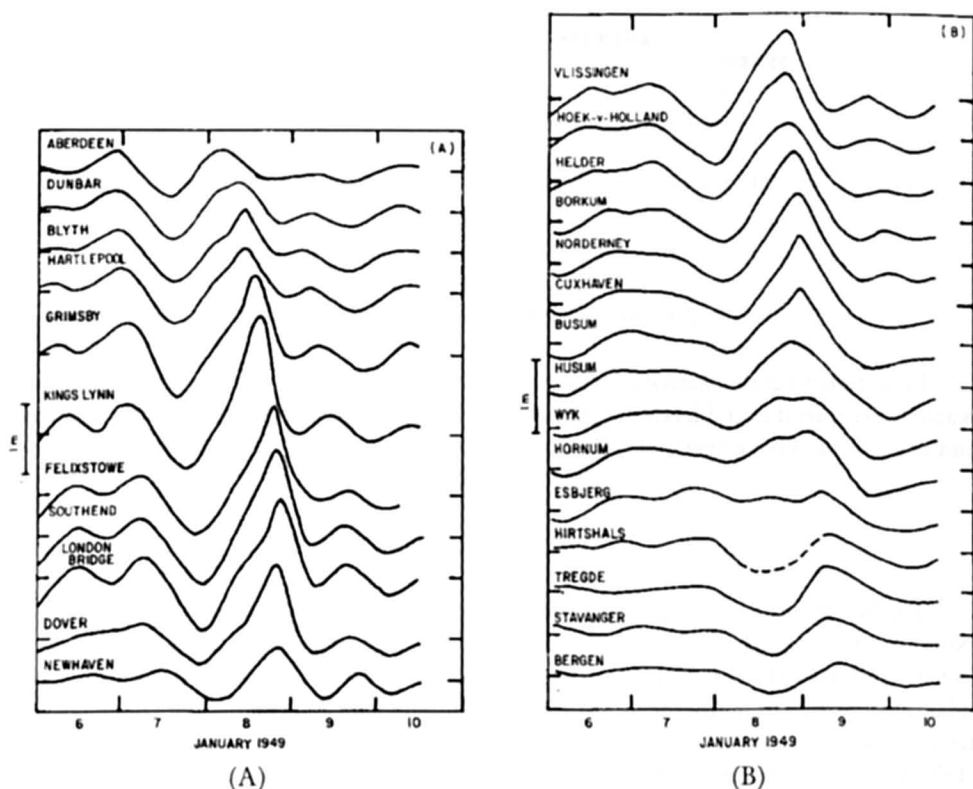


Fig. 7.9: Storm surge profiles at stations along the (A) western boundary of the North Sea and the (B) eastern boundary of the North Sea during January 6–10, 1949 (CHARNOCK and CREASE, 1957)

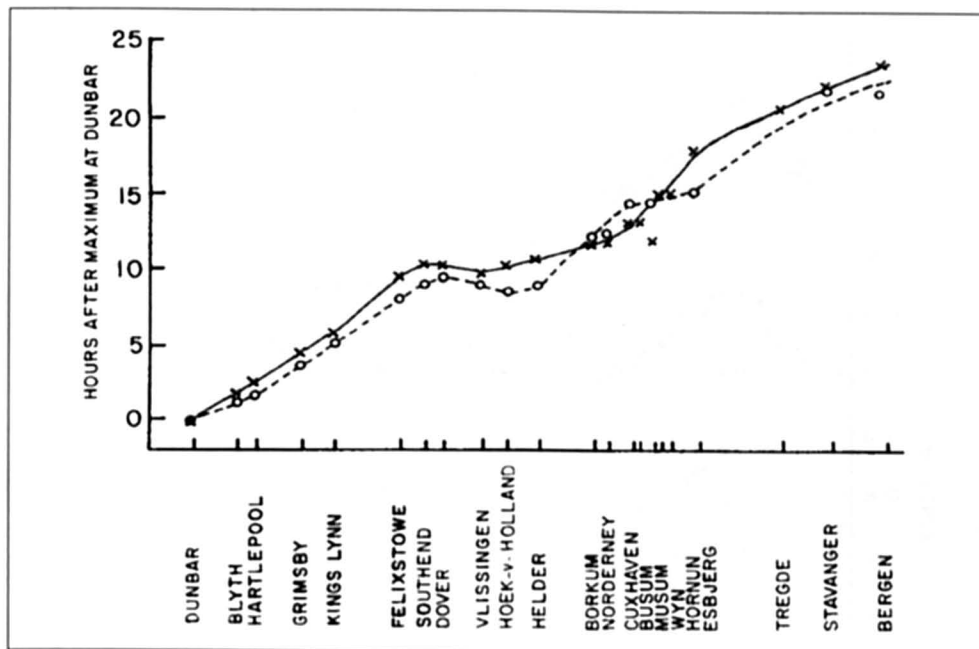


Fig. 7.10: Progression of storm surge and diurnal tide around the North Sea (CHARNOCK and CREASE, 1957)

During the storm surge on January 31–February 1, 1953 the situation at the southeastern and eastern boundary of the North sea was different to the situation on January 6–10, 1949. The track of the storm that produced this major surge is shown in chapter 5, Fig. 5.28. This depression caused a wind situation over the North Sea that produced very high storm surge levels at the British coast with rising level from Tyne over Immingham and Southend to London Bridge and falling levels to Dover and Newhaven (Fig. 7.12a & b.). Afterwards however, the surge reaches Ostende not with a lower level than in Dover; the level increased and reached a level there which was higher than at the British coast. At the German coast the high water level has become lower. A clear decrease of the water level can be seen from Esbjerg to Hornstholm (Denmark).

The horizontal distribution of the storm surge amplitudes during three different periods is summarized in Fig. 7.13. Maximum amplitudes up to 3 m occurred at the Belgian and Netherlands coasts. Amplitudes up to 2.5 m occurred at the coast of France, whereas amplitudes up to 2 m were found in the German Bight. At the Danish coast the maximum amplitudes were about 1 m. So the general principle has been lost since the wind direction and the surge do not increase anymore from the Dutch to the German coast. It must be stated that each location has its special wind direction in which the maximum surge can occur.

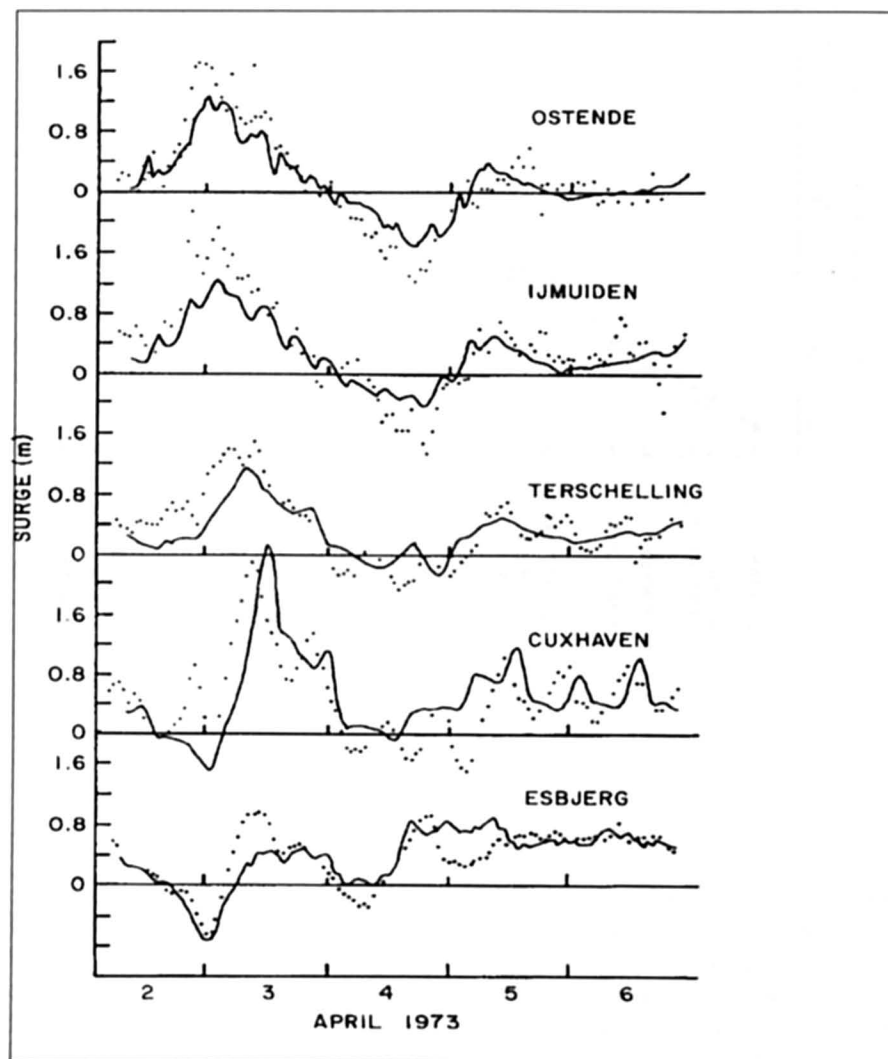


Fig. 7.11: Computed (solid line) and observed (dotted line) storm surges at five locations on the south and west coasts of the North Sea during April 2–6, 1973 (DAVIES and FLATHER, 1977)

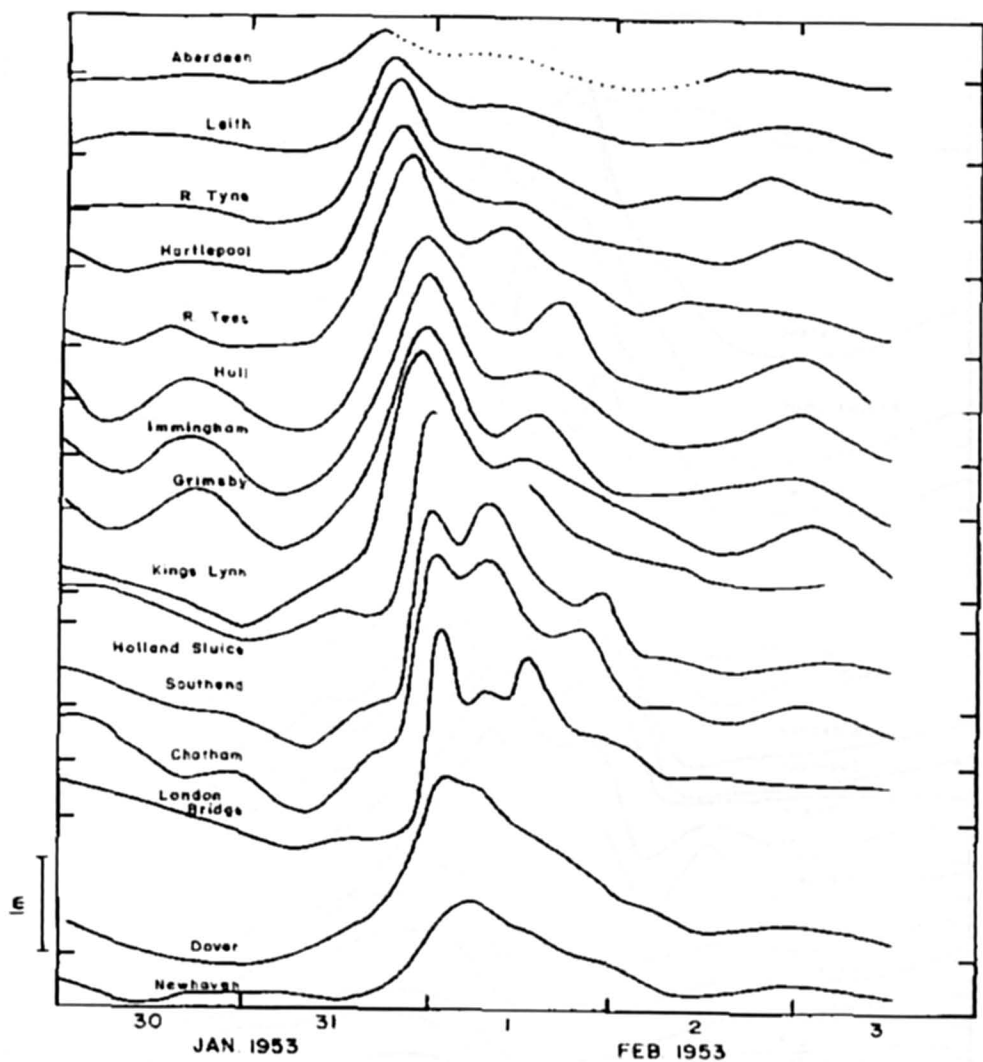


Fig. 7.12a: Storm surges at various locations around the North Sea during January 30–February 3, 1953 (ROSSITER, 1954)

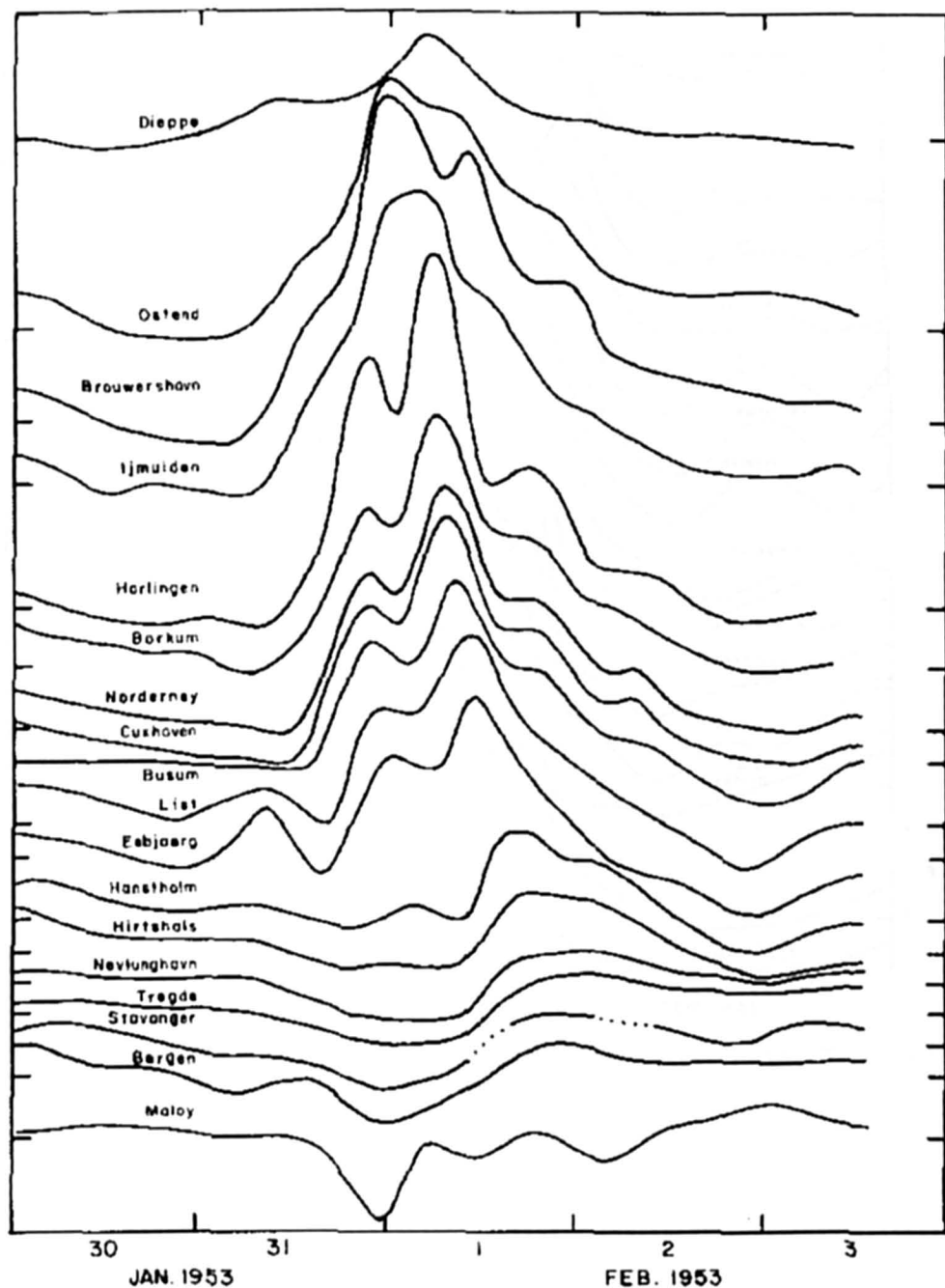


Fig. 7.12b: Storm surges at various locations around the North Sea during January 30–February 3, 1953 (ROSSITER, 1954)

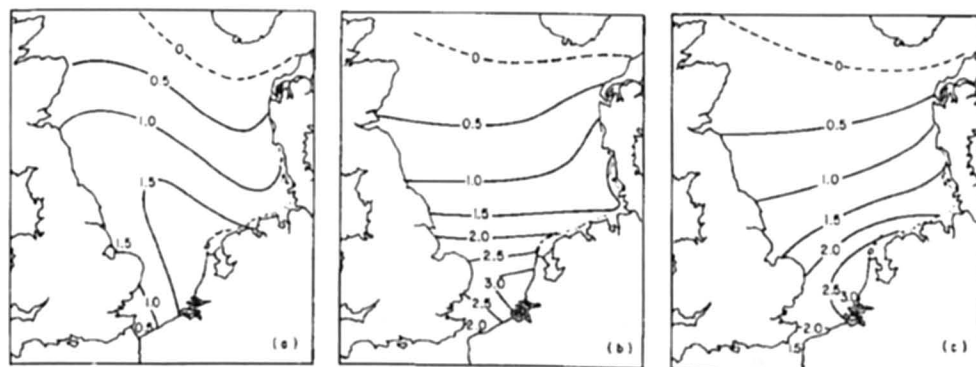


Fig. 7.13: Distribution of storm surge amplitudes (meters) in the North Sea during January 31–February 1, 1953, at (a) 18:00 (GMT) on January 31, (b) 00:00 (GMT) on February 1, and (c) 06:00 (GMT) on February 1

As described before in the English Channel the storm surge heights become smaller. The propagation of the surge through the English Channel from the North Sea is shown in Fig. 7.14.

BOWDEN (1957) mentioned that, in the southern part of the North Sea, the greatest elevation tends to occur along a line from Harwich to Flushing. The surface then slopes downward towards the Strait of Dover due to the flow of water into the English Channel.

LUNDBAK (1956) studied the storm surge of January 31–February 2, 1953, on the west coast of Denmark. He mentioned that one of the worst storm surges on the Danish coast occurred November 12–14, 1872, in which there was great damage and loss of life on the island of Lolland. The storm surge of October 10–11, 1634, was supposed to have killed more than 6000 people. This surge cut the German island, Nordstrand, into two separate islands, which were later named Pellworm and Nordstrand.

The question if the storm surge is the highest at any given instant or not depends first on the location and second on the time scale that one considers. For the coast of the United Kingdom, PETERS (1954) mentioned that a series of surges occurred during the period between 1086–99. A surge in the year 1099 killed 100 000 people. During the twelfth century, there were more surges. Another period of great surges was 1218–23. Other periods when the death toll exceeded 100,000 were in the years 1421 and 1446. Great surges also occurred (though the death toll was much smaller) on November 15, 1875, January 2, 1877, January 18, 1881, and November 29, 1897. After this period, the next comparable surge occurred in 1928 and then in 1953.

For the Netherlands VAN MALDE (1995) used the highest water level as the storm surge level. According to the official storm surge table of the Rijkswaterstaat; starting in 1825, the highest tidal-water levels recorded were those of the storm surge of February 4, 1825. But the question is, whether higher storm surge levels occurred in the past. VAN MALDE (1995) named the surges of 1421, 1446, 1468 and those from 1539 and 1552 as large, but shows that the conversion of such deceptive levels to centimeters is not a simple matter. He shows that the oldest reliable storm surge event was the All Saints Flood of 1570, one of the most disastrous floods that ever ravaged the Netherlands and summarizes that "the storm surges caused along the Dutch coast between Scheveningen and Den Helder were among the highest storm surge levels ever known". Off the northern provinces and the adjacent German coast the storm surge levels were very close to the highest ones having occurred ever

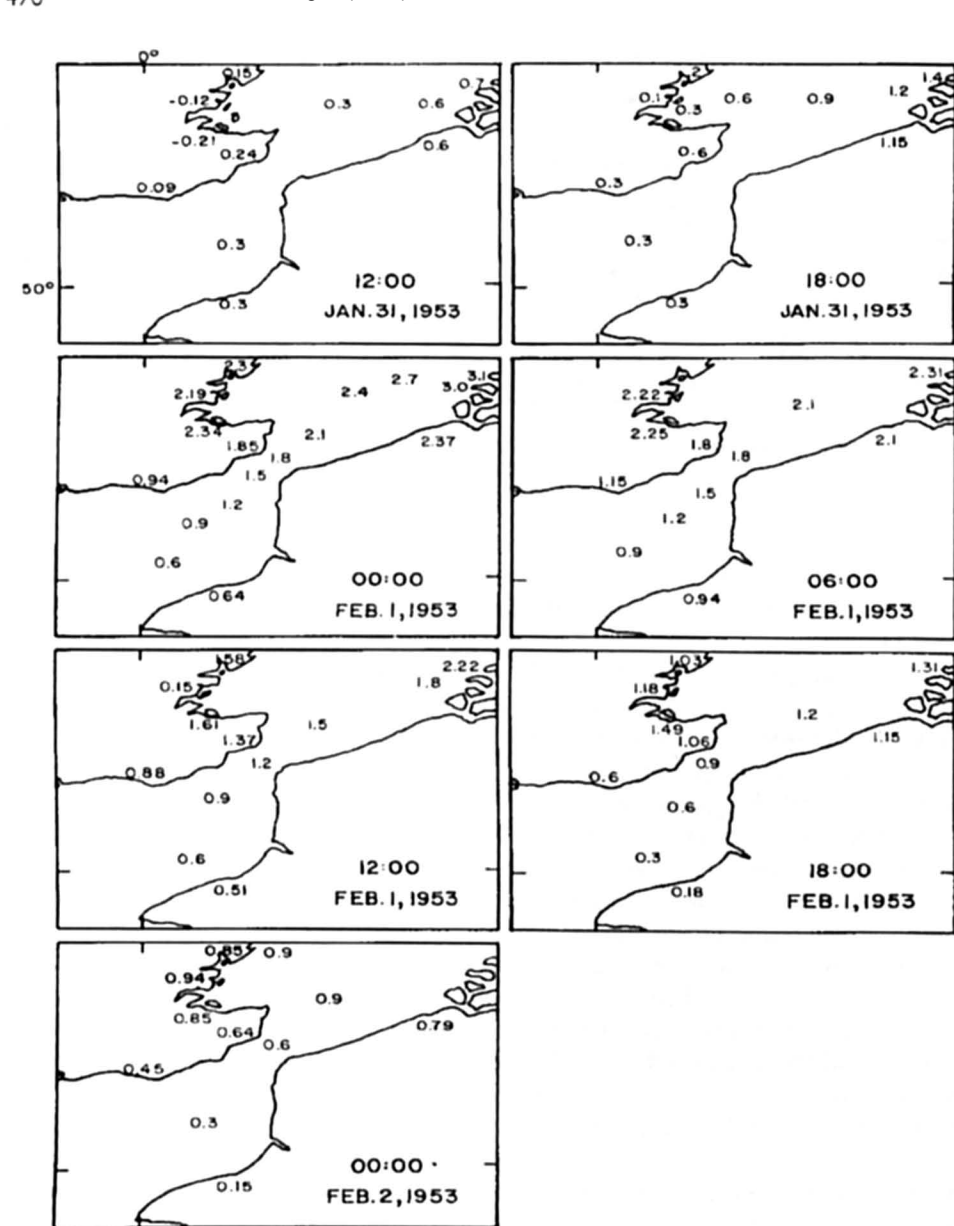


Fig. 7.14: Storm surge heights (meters) in the English Channel during January 31–Feb 2, 1953 (ROSSITER 1954)

since...” (meaning the storm surges of 1570, 1717, 1775, 1776, 1825 and 1953). The conclusion about the German coast is based on the research of ROHDE (1977), who did derive four historical storm surge levels at Emden with the following result:

November 1, 1570:	≥ NN + 470 cm	NN = Normal Null = mean sea level
December 14, 1717:	NN + 475 cm	
November 15, 1775:	NN + 388 cm	
November 21, 1776:	NN + 451 cm	
February 3–4, 1825:	NN + 465 cm	

To these results the following storm surge levels in the German Bight can be added. The highest storm surge level in the German Bight was reached in 1976 with a level of 370 cm over mean high tide level and 1010 cm NN. The storm surge of February 16–17, 1962, when a lot of people died was 355 cm over mean high tide level at Cuxhaven. This level has been reached during the flood of February 3–4, 1825, with 355 cm at Cuxhaven (GÖNNERT, 1999a). Therefore it can be stated that in recent years cause the storm surge level in the German Bight only a little increased and is compared to mean high tide level increase.

While the flood of 1825 caused high water levels along the Dutch and German Coast, the storm surge of 1962 was very high only in the German Bight and especially along the rivers Ems, Weser and Elbe within the cities of Emden, Bremen and Hamburg. The reason is the character of the storm and the location of the island in the deep water area of the North Sea. After the storm surge of 1962 coastal protection has been developed so that the higher storm surge of 1976 did not cause much damage.

A major storm surge occurred in the southern part of the North Sea and in the Thames Estuary during January 31–February 1, 1983, exactly 30 years after the surge of 1953. The meteorological conditions were somewhat different in these two cases. The surge of 1983 was potentially as destructive as the one of 1953. However, because of considerable improvement in storm surge warning services and the development of coastal protection works and the Thames Estuary barrier, loss of life and damage to property were considerably less than in 1953.

Negative Surges in the North Sea

ROSSITER (1971) drew attention to the navigational hazard posed to large ships in the southern North Sea due to negative storm surges. DOODSON (1947) mentioned that negative surges occurred at Dunbar and Southend during the storms of November 10–13, 1929, January 1–3, 1928, and October 17–21, 1935.

Table 7.2: Frequency of negative storm surges in the southern part of the North Sea (GEELHOED, 1973)

Location	Amplitude (cm) of negative surge that can occur (at the time of low water) with the frequency per year of			Amplitude (cm) of negative surge that can occur (at the time of high water) with the frequency per year of		
	10	1	10^{-1}	10	1	10^{-1}
Hook of Holland	50	83	117	50	80	111
Flushing	46	75	103	47	80	113
Dunkerque	44	68	92	46	75	105
Dover	43	69	96	47	79	111

GEELHOED (1973) studied negative storm surges in the southern part of the North Sea, with particular attention to the Sandettie Bank and the Brand Ridge areas because of the shallow water depths there. The data source consisted of 50 years of data for the stations of Hook of Holland and Flushing, 4.7 years of data for Dunkerque, and 20.1 years of data for Dover. The results of a frequency analysis are summarized in Table 7.2. This table must be interpreted as follows. For example, at Hook of Holland, negative surges of amplitudes up to

50 cm occur on the average about 10 times per year; negative surges with amplitudes up to 83 cm occur once a year and negative surges of amplitudes up to 117 cm occur only once in 10 years. The differences between the negative surges at low and at high waters are not significant.

Negative surges predominantly occur in winter. Southerly to westerly winds produce negative surges at Dover whereas at Hook of Holland, southerly to easterly winds cause negative surges. Largest negative surges occur at Southend (up to 2.3 m) and at Tilbury (up to 2.8 m). At other stations, negative surges with amplitudes of 1.0–1.5 m occur. GEELHOED (1973) attributed the differences in the amplitudes of the negative surges at various locations to topographic differences.

Table 7.3: Calculated amplitudes (m) of storm surges at three locations in the southern part of the North Sea for three different wind fields. (GEELHOED, 1973)

Type of wind field (83 km·h ⁻¹)	Amplitude (m) of surge at		
	Sandettie	Brown Ridge	Hook of Holland
Easterly	-0.8	-0.7	-1.3
Westerly	+0.8	+0.7	-
Southerly	-1.9	-1.8	-2.1

Westerly winds appear to cause negative surges exclusively on the east coast of the United Kingdom whereas easterly winds could cause negative surges exclusively on the coast of the Netherlands. On the other hand, southerly winds can cause negative surges on both coasts simultaneously (and indeed in the whole southern part of the North Sea). The calculated negative surges at three locations for three different wind fields are summarized in Table 7.3.

Negative surges in rivers are a special problem for navigation for the example of the Elbe river (German Bight) this has been investigated by RUDOLPH (1999). The following is based on RUDOLPH (1999) and also on personal communication.

The estuaries along the German Bight are well exposed to storms coming over the North Sea from westerly direction. In the Elbe estuary which is orientated from West to East, high water levels at the mouth in combination with strong westerly winds can result in high water levels along the whole estuary, which reaches inland more than 100 km. Even the harbor of Hamburg, which is situated about 120 km upstream of the mouth of the Elbe estuary is endangered by storm surges coming from the North Sea.

There are indeed situations too, where strong winds cause a decrease in water level. This might be called a negative storm surge. In the Elbe estuary for example strong easterly winds blowing for several days can lower high as well as low water levels significantly.

An example of a negative storm surge is found in the first week of October 1992. This period was preceded by a low fresh water discharge of only appr. 200 m³/s while the mean fresh water discharge of the last 50 years was 712 m³/s. During the end of September 1992 the wind over the Elbe estuary had easterly direction with wind speeds between 5 m/s and 10 m/s (Bft 4 to 5). In the first week of October 1992 the wind speed increased and reached up to 15 m/s (Bft 7) from April 10, 1992 until June 10, 1992.

For the period January 10, 1992 until July 10, 1992 the astronomical tide for Cuxhaven at the mouth of the Elbe estuary was calculated from harmonic tidal constants. Fig. 7.15a

shows the comparison between observed and predicted water levels at Cuxhaven. In addition the measured wind speed and wind direction in this area is given.

The difference between these water levels can be interpreted as surge. Fig. 7.15b shows the observed water level, the predicted astronomical tide and the surge during the period of strong easterly wind. In fact, a negative storm surge of up to one meter can be found.

Inside the estuary e.g. close to the harbour of Hamburg the difference between predicted and observed water levels is even higher. In this part of the estuary the effects of the low fresh water discharge and the strong easterly winds add up to differences in the high water level of 110 cm and in the low water level of 80 cm (Table 7.4).

Table 7.4: Measured and predicted water levels in [mNN] as well as the differences at Cuxhaven and Hamburg St. Pauli in the Elbe estuary during negative storm surges

Date		Cuxhaven			Hamburg St. Pauli		
		measured	predicted	difference	measured	predicted	difference
10/03/1992	HW	+ 1.13 m	+ 1.15 m	- 2 m	+ 1.49 m	- 2.00 m	- 51 cm
	LW	- 1.79 m	- 1.40 m	- 39 cm	- 2.01 m	- 1.40 m	- 61 cm
	HW	+ 0.70 m	+ 1.30 m	- 60 cm	+ 1.07 m	+ 1.80 m	- 73 cm
	LW	- 1.64 m	- 1.20 m	- 44 cm	- 1.97 m	- 1.30 m	- 67 cm
10/04/1992	HW	+ 1.71 m	+ 1.40 m	- 31 cm	+ 1.05 m	+ 1.90 m	- 85 cm
	LW	- 1.80 m	- 1.30 m	- 50 cm	- 2.13 m	- 1.40 m	- 73 cm
	HW	+ 0.09 m	+ 1.10 m	+ 101 cm	+ 0.43 m	+ 1.60 m	- 117 cm
10/05/1992	LW	- 1.67 m	- 1.10 m	- 57 cm	- 2.11 m	- 1.30 m	- 81 cm
	HW	+ 0.40 m	+ 1.20 m	- 80 cm	+ 0.77 m	+ 1.80 m	- 103 cm
	LW	- 1.61 m	- 1.20 m	- 41 cm	- 2.08 m	- 1.40 m	- 68 cm
	HW	- 0.02 m	+ 0.90 m	- 92 cm	+ 0.44 m	+ 1.50 m	- 106 cm
10/06/1992	LW	- 1.26 m	- 1.00 m	- 26 cm	- 1.72 m	- 1.30 m	- 42 cm
	HW	+ 0.37 m	+ 1.20 m	- 83 cm	+ 0.83 m	+ 1.80 m	- 97 cm
	LW	- 1.40 m	- 1.20 m	- 20 cm	- 1.84 m	- 1.40 m	- 44 cm
	HW	+ 0.26 m	+ 0.90 m	- 64 cm	+ 0.77 m	+ 1.50 m	- 73 cm

Investigations with a numerical model of the Elbe estuary showed, that not only the low water levels at the mouth of the Elbe caused the low water levels inside the estuary, but also the strong local wind over the Elbe estuary helped to lower the water level along the Elbe estuary during ebb tide (increasing ebb current) and to keep the water levels low during flood (decreasing flood current).

The processes described here, low fresh water discharge and continuous high easterly winds, resulted in a decrease in low and high water levels along the whole Elbe estuary. This negative storm surge lasted for more than four days. On July 10, 1992, the wind direction changed to North, the wind speed decreased and so the water levels finally reached their normal height again.

In contrast to storm surges these negative storm surges do not endanger the life of the inhabitants of the coastal areas. Nevertheless they are a problem for the traffic on e.g. the navigation channel Elbe, as the navigable depth is reduced significantly in comparison to the usually occurring tide.

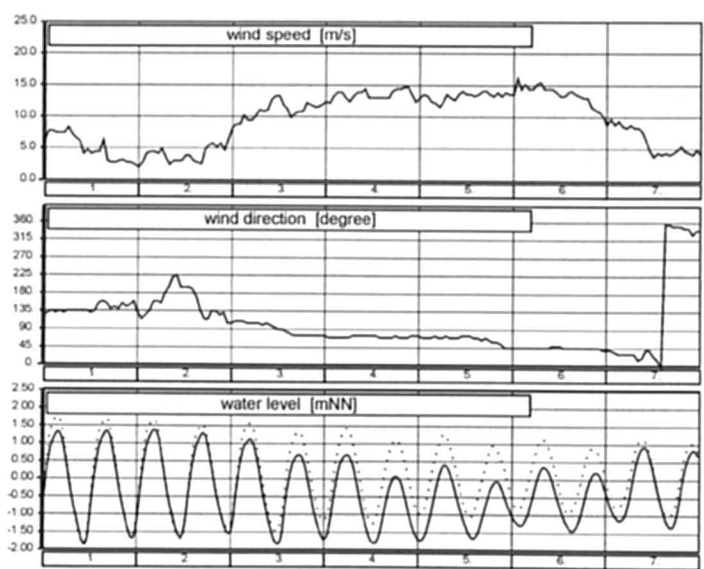


Fig. 7.15a: Negative Surge Elbe: Wind speed and wind direction at the island of Scharhörn in the mouth of the Elbe estuary and measured (dotted) and predicted (solid) water levels at Cuxhaven for the period 10/01/1992 until 10/07/1992. With increasing wind speed the difference between observed and predicted water level also increases

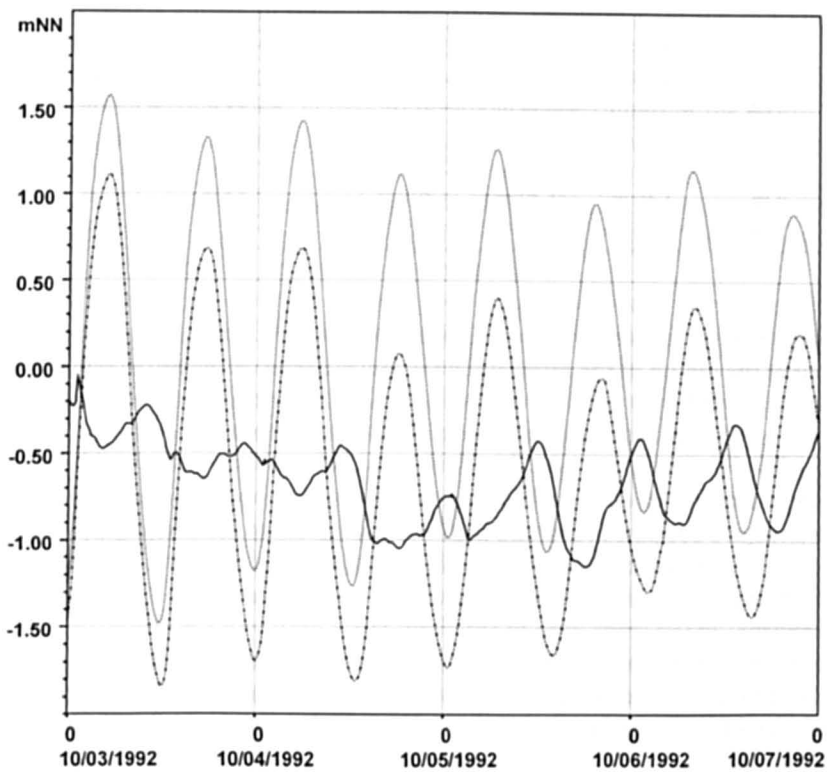


Fig. 7.15b: Negative Surge Elbe: Measured water level (dashed), astronomical tide (dotted) and surge (solid) at Cuxhaven during October 1992

The Netherlands

Earlier, the works of GALLÉ (1915) and SCHALKWIJF (1947) were discussed. The storm surge amplitudes along the coast of the Netherlands during the major storm surge of January 31–February 1, 1953, were greater than those at the east coast of the United Kingdom (UFFORD, 1953). Surge amplitudes up to 9 ft (2.74 m) occurred along the coasts of the provinces of Zeeland and Zuid-Holland, with a peak surge of 9.6 ft (2.93 m) occurring at Hellevoetsluis. In the Scheldt Estuary the amplitudes were even greater. At Berger op Zoom the amplitude was about 11 ft (3.35 m).

The water level rose above the dykes, and about 50 dykes collapsed and at least 1800 people died. The damage exceeded £ 100 million (at 1953 prices). UFFORD (1953) mentioned that this was the biggest surge since the one on November 18, 1421, when at least 10 000 people died. Since the time tide gauges were set up in 1890, the surge of 1953 was 2 ft higher on the average than any other surge during the period 1890–1953. The extent of the flooding on the coast of the Netherlands is shown in Fig. 7.16.

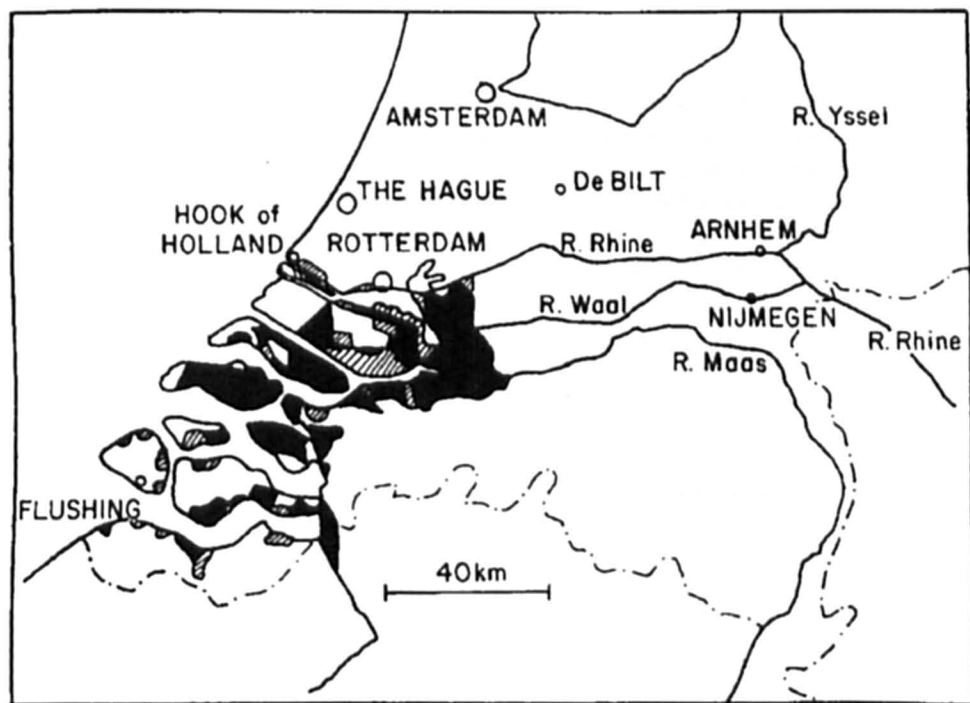


Fig. 7.16: Extent of flooding on the coast of the Netherlands due to the storm surge of January 31–February 1, 1953. Dark areas show regions that were flooded until March 1953. Hatched areas are those that were reclaimed after the flooding (UFFORD, 1953)

WEENINK (1956) studied the so-called twin storm surges that occurred on December 21 and 24, 1954. The observed surge and that computed through an equilibrium wind assumption are shown in Fig. 7.17.

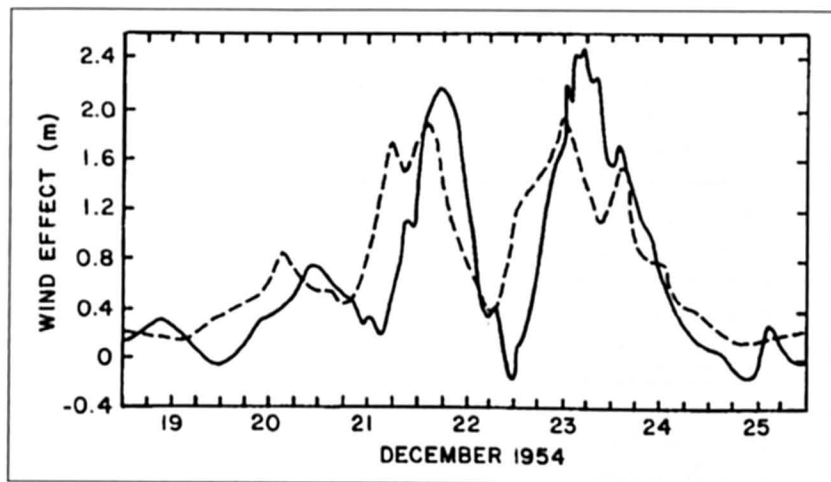


Fig. 7.17: Twin surges of the North Sea in December 1954 as recorded at the Hook of Holland (solid line). Broken line shows the computed surge using the equilibrium wind effect (WEENINK, 1956)

TIMMERMAN (1971) showed that moving cold fronts over the southern part of the North Sea could produce a sudden increase of water levels at the Netherlands coast (he uses the rather inappropriate term “gust bump” to refer to these water level increases). These increases in the water level occur only when the speed of propagation of the cold front lies between 29 and 36 knots (54–67 km/h). This suggests resonance between the traveling atmospheric disturbance and the long surface gravity waves in the water body. He numerically simulated the event of December 13, 1956. One can obtain some idea of the time scale and amplitudes of the gust bumps from Fig. 7.18. One can clearly see the bump at Katwijk at 11 a.m. on March 27, 1966. The locations of these stations can be seen in Fig. 7.19. Similar sudden water level increases for the event of December 13, 1956, are shown in Fig. 7.20.

After the storm surge of 1953 in the Netherlands it was decided to set new safety standards and perform extreme value statistics. It was agreed that the central, and most important, part of Netherlands was given a safety standard with a return period of 10,000 years (...) (RONDE et al., 1995). The wadden islands have a return period of 2000 years and the remaining coastal areas have a return period of 4000 years. With respect to the central coastal part, this gives a reduction of about 40 cm for most coastal areas.

RONDE et al. (1995) describe the extreme value water level as follows. At first the storm surge data were selected by use of depression storm tracks to obtain a homogeneous data set. Only one value per storm was taken to get un-correlated data. This is comparable with the method to calculate a storm surge curve and take only the highest water level. A so called “Peak over Threshold Method” was fitted to choose the extreme value distribution. “Finally a design level of about 5 m + NAP was designated for the Hook of Holland as the event with a return period of 10,000 years.” RONDE et al. (1995) described the method to calculate the design level of other stations with help of the design level of Hook van Holland.

Using statistical methods, RONDE et al. (1995) took into account a sea level rise of about 15 to 20 cm and the return period was re-calculated.

For real time forecasting of storm surges the CSM model with a grid size of 8 km is used at the KNMI (Royal Netherlands Meteorological Institute).

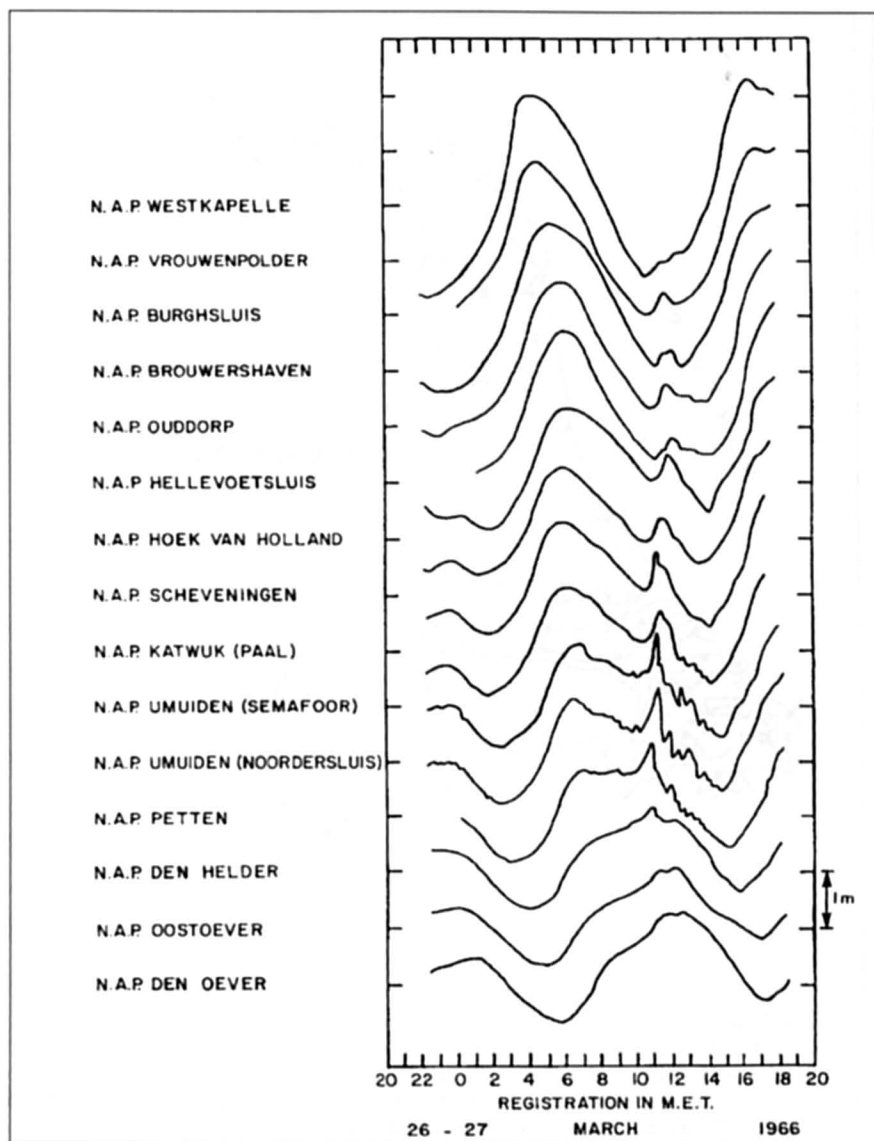


Fig. 7.18: Sudden water level changes (gust bumps) during March 27, 1966, at several locations on the Netherlands coast (TIMMERMAN, 1971)



Fig. 7.19: Netherlands coast showing the locations of the tide gauge stations used in the storm surge study, 1, Den Helder; 2, Oostoever; 3, Den Oever; 4, Petten; 5, Urnuiden; 6, Katwuk aan Zee; 7, Scheveningen; 8, Hoek van Holland; 9, Maassluis; 10, Vlaardingen; 11, Rotterdam; 12, Krimpen aan den Lek; 13, Spukenisse; 14, Ouddorp; 15, Hellevoetsluis; 16, Dordrecht; 17, Brouwershaven; 18, Burghsluis; 19, Vrouwenpolder; 20, Westkapelle; 21, Wemeldinge; 22, Vlissingen; 23, Hansweert; 24, Temeuzen (TIMMERMAN, 1971)

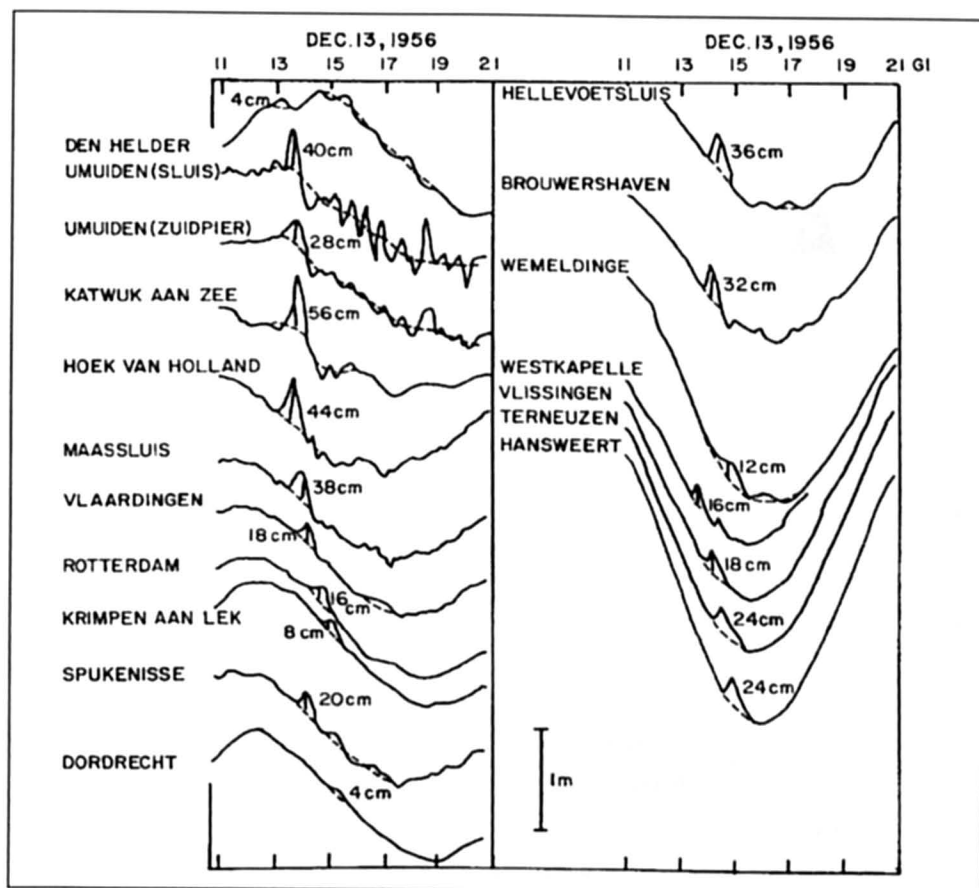


Fig. 7.20: Sudden water level changes (gust bumps) at several locations on the Netherlands coast on December 13, 1956 (TIMMERMAN, 1971)

German Bight

Storm surges occur in the German Bight when wind blows over the North Sea from N to NW. To reach a very high water level the duration of a high wind speed must be a minimum of 3 h. The so called critical wind direction for each location is different. For example the critical wind direction for Cuxhaven for very high storm surges lies between 280° – 310° , for Helgoland between 265° – 280° and for Norderney between 255° – 290° (GÖNNERT, 1999b).

In the North Sea near the Amphidromic point the water levels rise only slightly and increase towards the coast.

TOMCZAK (1950) discussed the storm surge of February 9–10, 1949, in the North Sea. The greatest effect of the surge was on the coast of Northern Friesland. One interesting feature was that the storm center remained almost stationary off the island of Sylt on February 9th and blocked the outflow of water from the German Bight northwards. The maximum amplitudes of the water level at several locations are listed in Table 7.5.

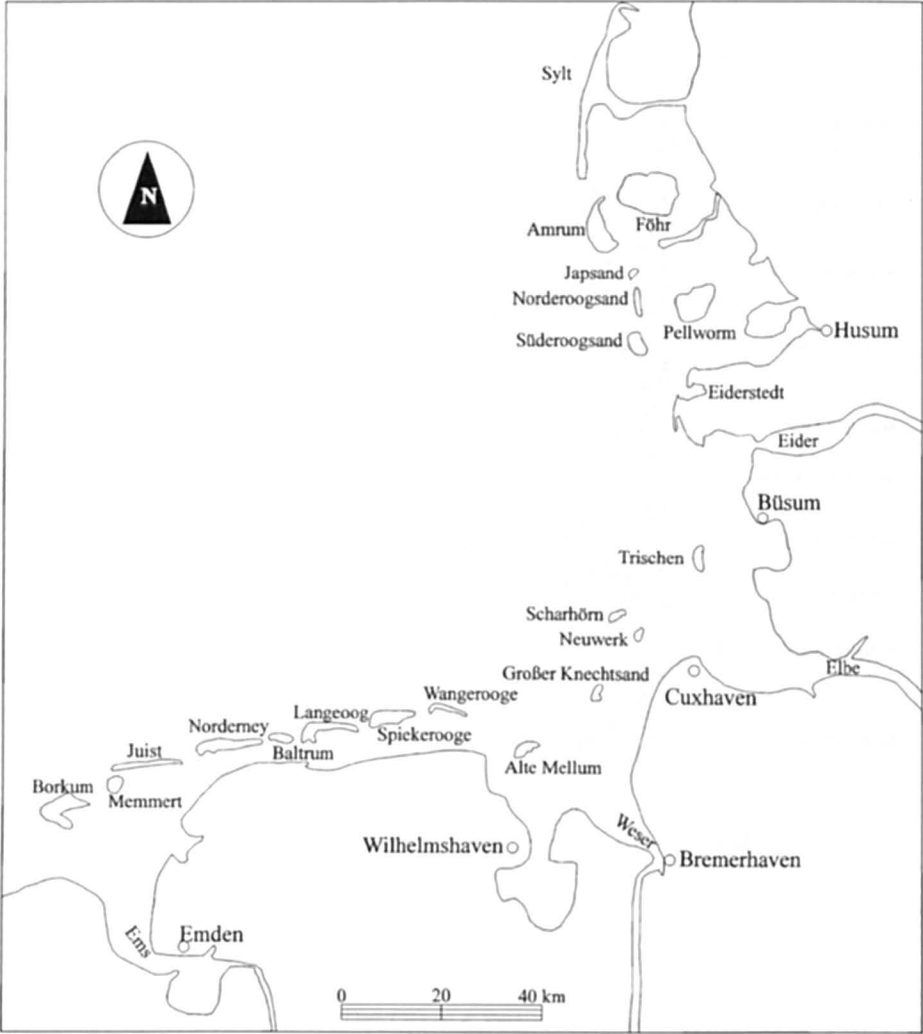


Fig. 7.21: The German Bight

Table 7.5: Maximum water levels during the storm surge of Feb. 9–10, 1949, at the German North Sea Coast (TOMCZAK, 1950)

Station	Amplitude (m)	Station	Amplitude (m)
Borkum	2.4	Bremerhaven	3.9
Norderney	3.0	Cuxhaven	4.2
Emden	3.3	Büsum	4.8
Wilhelmshaven	3.4	Husum	5.6

Other examples are shown in Table 7.6, indicating that the level depends on wind direction and location with each special topography.

Table 7.6: Storm surge level over NN (Normal Zero) in the German Bight

Storm surge	Feb. 16, 1962	Jan. 3, 1976	Feb. 26–28, 1990	Jan. 10, 1995
Cuxhaven	495 cm NN	5010 cm NN	434 cm NN	448 cm NN
Norderney	410 cm NN	386 cm NN	366 cm NN	346 cm NN
Wittddün	360 cm NN	327 cm NN	324 cm NN	266 cm NN
Helgoland	414 cm NN	405 cm NN	384 cm NN	301 cm NN

SIEFERT (1968, 1978, 1982, 1988a, 1988b, 1990), SIEFERT and LASSEN (1985) and GÖNNERT and SIEFERT (1997) studied storm surges in Cuxhaven and the Elbe River. The studies involved a total of 153 storm surges, which included 192 high tide water levels for the period of 1901–1995 (GÖNNERT and SIEFERT, 1998). Only events that generated a surge of 2 m or more between low water time and four hours after high water time are considered for the analysis (SIEFERT and LASSEN, 1985). During low tide the surge reaches a higher level than during high tide. Therefore the data record is restricted to storm tides with a surge level lower than 1.50 m at high tide. To analyze the change of storm tides in the last century utilization of the surge curve (Fig. 7.23) – which is the difference between the storm tide and the astronomical or mean tide curve – is the best approach, because it includes the meteorological factors. With this approach GÖNNERT (1999a & b) studied the 20th century storm tides (level, number, duration and character) in the German Bight (Fig. 7.21). The results showed an increase in the number of storm surges, but no significant increase in the level. The increase in frequency is mainly true for the small events, but the average storm surge curve is longer and there are more events with long duration (GÖNNERT, 1999a & b). For example, during the storm surge of February 26–28, 1990 one storm surge curve includes five height water peaks for Cuxhaven (Fig. 7.22).

In the German Bight the character of very high storm surges is different. At the coast very high crests are associated with a fast increase of wind speed. Since wind fields cannot be reliably predicted too far ahead, storm surges also cannot be predicted reliably for more than 12 hours ahead. But at the islands very high crests are associated with the slow increase of wind speed.

Investigations into the change of storm surge level and frequency by focusing on the tidal crest have been done for example by LÜDERS (1974), PETTERSON and ROHDE (1991), NASNER and PARTENSCKY (1977), FÜHRBÖTER et al. (1988), FÜHRBÖTER (1989), FÜHRBÖTER and TÖPPE (1991), JENSEN (1987), NIEMEYER et al. (1995) and STORCH et al. (1998).

GÖHREN (1976) studied currents on the tidal flats in the German Bight. Note that these tidal flats could be as wide as 20 km. He showed that the currents can increase from an average 30 cm/s to as much as 120 cm/s during storm surges. The destructive storm surges at the North Sea coast of Germany during February 16–17, 1962, December 6–7, 1973, and January 3, 1976, prompted ZSCHAU et al. (1978) to develop a storm surge forecasting technique by measuring the inland crustal tilt and the deflection of the local vertical due to the buildup of the surge. These authors, using a vertical pendulum, measured such tilts with precision. According to them there is advance information about the storm surge in these tilt measurements. The rationale for this is explained below.

There is an indirect effect of tides on tidal gravity, tilt, and strain measurements. Since this effect depends on the elasticity of the crust and the upper mantle, this effect has been used to determine their elastic properties. However, in the regions where the elastic properties are known better than the tides, the inverse problem of determining the tides from measurements



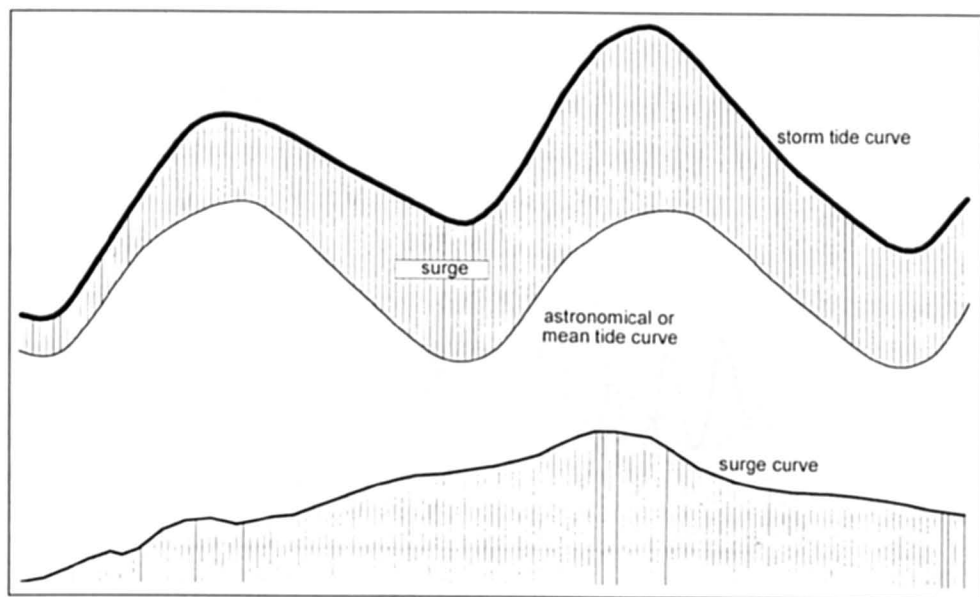


Fig. 7.23: The storm surge curve

of tidal gravity on the land has been used. ZSCHAU et al. (1978) used this inverse approach of determining the storm surge from tilt measurements made inland. According to them, the additional water mass of the surge has three different effects on these measurements: (1) the deflection of the vertical due to the gravitational attraction of the water mass, called the Newtonian tilt; (2) the tilt of the surface due to the loading and unloading of the sea floor, called the primary loading tilt; (3) the secondary deflection of the vertical due to the redistributions of mass caused by the loading and unloading, called the secondary loading tilt.

The secondary loading tilt, generally, is small compared with the primary tilt and it can be combined with the loading tilt. Note that the Newtonian tilt and the primary tilt cause a deflection of a vertical pendulum tilt meter and also tilt its casing.

The storm surge at Büsum on the west coast of Schleswig Holstein of December 6–7, 1973, is shown in Fig. 7.24. A maximum amplitude of about 3 m was attained. The measured tilt at Kiel-Rehmsberg and also the astronomical tide are shown. It can be seen that the tilt curve matches the storm surge curve except for a 12-h phase advance. This phase advance is explained as due to the amphidromic component of the North Sea surge, which takes roughly a day to propagate in a counterclockwise direction from Scotland along the coasts of the United Kingdom, Belgium, the Netherlands, Germany, and Denmark to Norway.

This same technique was used to simulate four major, two moderate, and three minor surges during November–December 1973. The predictions (Fig. 7.25) 9, 6, and 3 h ahead had average errors of 29, 18, and 11 cm, respectively, in the maximum storm surge amplitudes.

FÜHRBÖTER (1979), JENSEN (1985), FÜHRBÖTER and TÖPPE (1991) studied the frequencies of extreme storm surges on the North Sea coast of Germany. They suggested that the classical extrapolation techniques for return periods might not be applicable in this situation because the time series (representing the storm surge data) are not stationary but changing with time continuing. JENSEN (1999) summarized their work:

The current approaches for estimating a storm surge defence level can be classified into empirical and statistical methods. Statistical methods are mostly based on the consideration

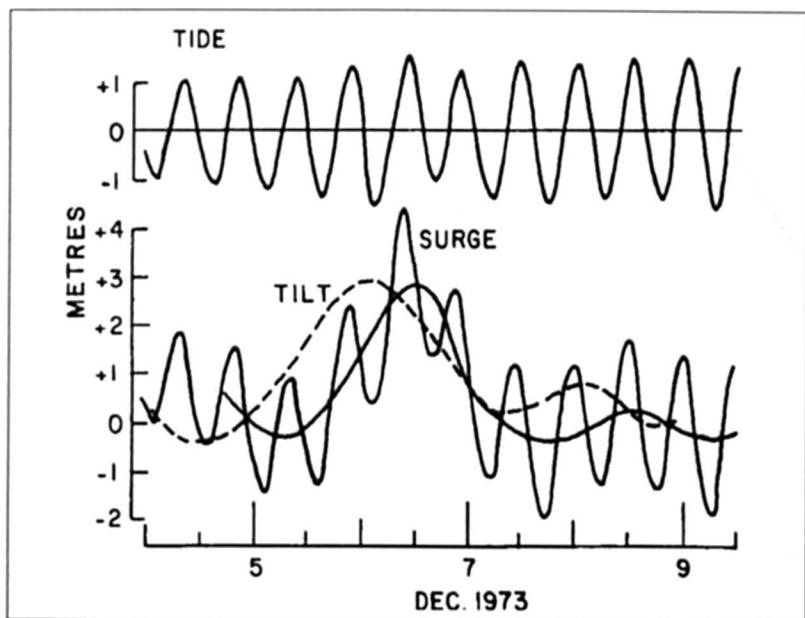


Fig. 7.24: Tide and surge at the coast of Germany during December 6-7, 1973. Top: tide at Büsum; bottom: solid curve shows the surge at Büsum and the broken curve shows the tilt at Kiel-Rehmsberg (ZSCHAU, 1977)

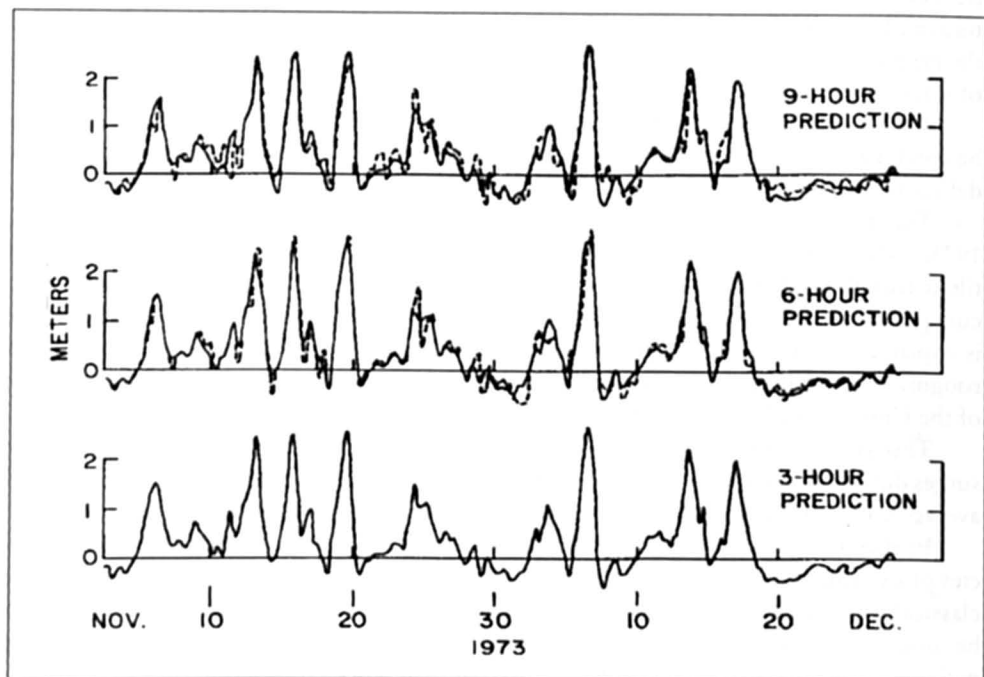


Fig. 7.25: Hindcast of storm surges for Büsum from tilt measurements at Kiel-Rehmsberg 9, 6, and 3 h in advance. Solid line: observed surge; broken line: hindcasted surge (ZSCHAU and KUMPEL, 1979)

of high water levels (HW) of an equidistant period (e.g. yearly maximum). The basic requirements of any data set are consistency, homogeneity and stationarity of the data.

Before further processing, time series should be checked and analysed very carefully for observation errors and inherent defectiveness. If mean values (mean tidal high water) are available, extreme values HW of the gauge should be homogenized using the linear trend s_T of the respective mean values as follows (if the year 2000 is the reference year):

$$BHW_i = HW + (2000 - i) \cdot s_T.$$

For the German Bight, a rise s_T of 25 cm to 50 cm for the mean tidal high water (MHW) has to be used for homogenisation of the extreme water levels. In order to estimate water levels that occur with a given probability or return period, usually some distribution functions are fitted to the observed values and a best-fitting function is selected. The most commonly used distribution functions for extreme water levels in the German Bight are: (LOG) Pearson III, Jenkinson (several procedures) and a linear regression procedure based on empirical return periods. In such an approach, the physical conditions that lead to an extreme water level are ignored.

A more reliable method of estimating extreme water levels is based on the separation of as many as possible single components from the total water level.

Examples of such components are wind set up, external surges, other astronomical influences, local wind set up, oscillations and others. Such a concept requires a continuous record of water levels as well a continuous computation of astronomical tides.

In general, as many components as possible should be regarded separately, but since such data is not yet available for the gauges in the German Bight, the only way of considering single components of the total water level is to analyse storm surge curves has done in SIEFERT (1999) and GÖNNERT (1999).

In doing so, the probabilities of a storm surge of a given level and the probability of that wind set up to occur during a high water period can be combined. Hence, the estimation of storm surge levels with a very low probability of exceedance is more reliable than of those obtained with a "classical statistical method", in particular for extreme water levels.

BARTHEL (1979) showed that significant wind wave activity could occur in the German Bight. One must include this in predicting the total water level.

Norway

GJEVIK and ROED (1974) mentioned that catastrophic surges occurred at the island of Grip (a small island on the west coast of Norway) and were discussed by HELLAND (1911). Major surges occur also at the Island of Ona. JOHANSEN (1959) studied the surge along the southeast coast of Norway. GJEVIK and ROED (1974) studied the following three surges on the Norwegian west coast: November 2, 1971, December 30, 1972, and December 31, 1972. The surge curves at three locations for the three cases together are shown in Fig. 7.26 and 7.27, respectively. The peak surge amplitudes at six locations for the first case are given in Table 7.65.

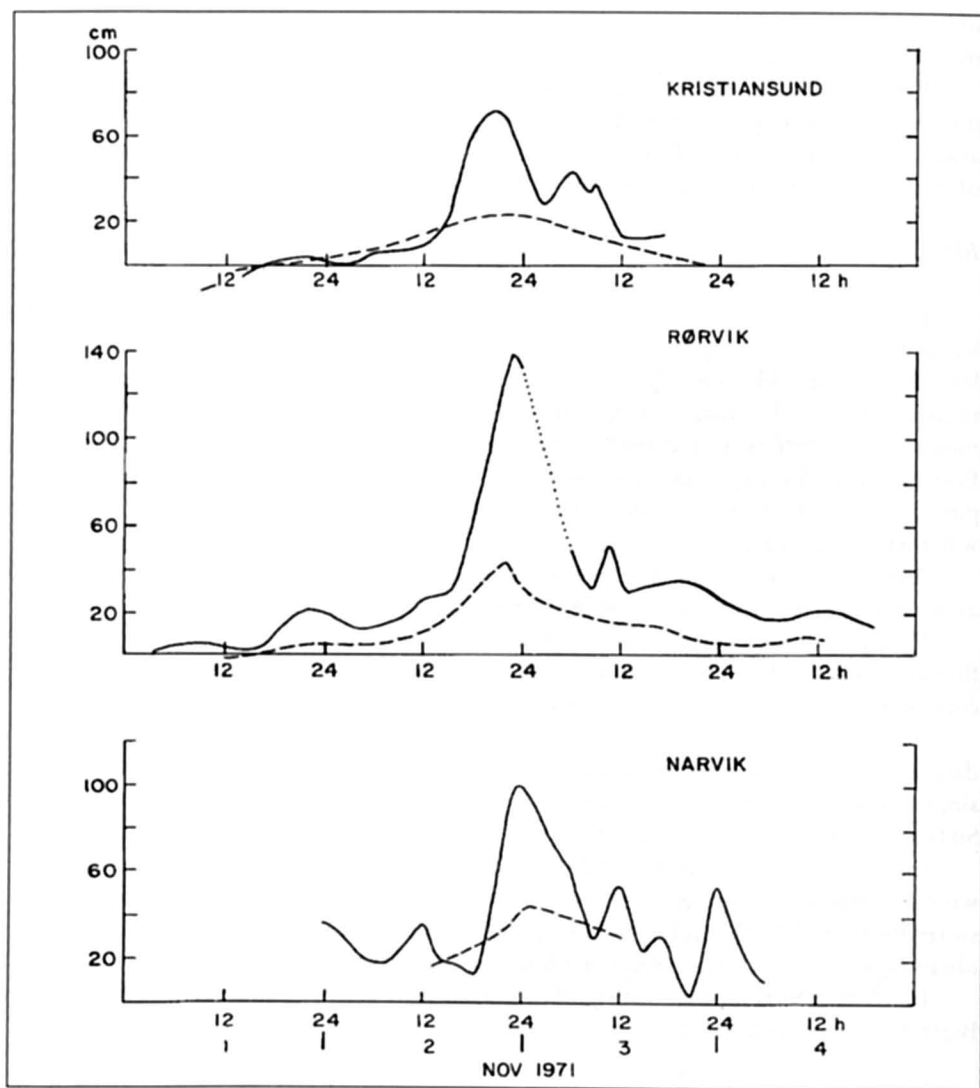


Fig. 7.26: Observed storm surges on the west coast of Norway during November 1–4, 1971. Dots denote missing observations. Broken curve represents the theoretical surge due to the atmospheric pressure gradient only (GJEVIK and ROED, 1974)

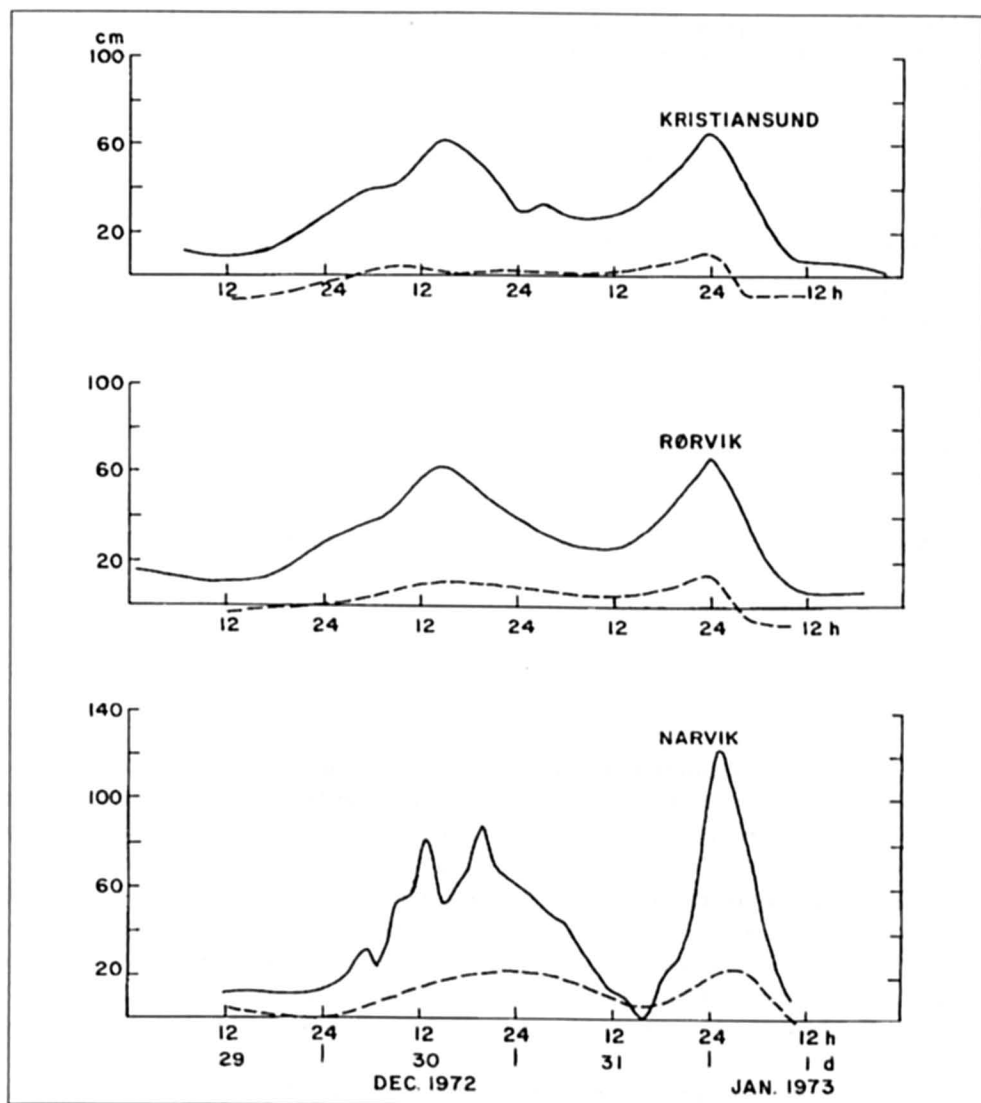


Fig. 7.27: Observed storm surges on the west coast of Norway during December 29, 1972–January 1, 1973 (solid line). Broken line shows the theoretical surge due to the atmospheric pressure gradient only (GJEVIK and ROED, 1974)

Table 7.7: Peak storm surge amplitudes at certain locations on the West coast of Norway for the surge of Nov. 2, 1971 (GJEVIK and ROED, 1974)

Location	Observed peak surge (m)
Alesund	0.40
Heimsjø	0.75*
Trondheim	1.00
Sandnessjøen	1.20
Hammerfest	0.40
Tromsø	0.50

* This value does not agree with that given by MARTINSEN et al. (1979). See Table 7.8.

Table 7.8: Comparison of observed and calculated peak surge amplitudes on the west coast of Norway for the surge of Nov. 2, 1971 (MARTINSEN et al., 1979)

Location	Observed	Computed
Kristiansund	0.7	0.98
Heimsjø	1.0	1.08
Rorvik	1.4	1.40
Sandnessjøen	1.2	1.47
Tromsø	0.5	0.65

MARTINSEN et al. (1979) developed a numerical model to simulate storm surges along the west coast of Norway. The observed surges at five locations and those calculated from the numerical model including bottom stress are compared in Table 7.8.

7.3.2 Baltic Sea

Storm surge investigations in the Baltic Sea are numerous. They extend from the early part of the 20th century by KRÜGER (1910) to BAERENS and HUPFER (1994). Therefore not all available references can be summarized here. The following discussions follows closely STIGGE (1999).

Special hydrodynamic conditions: The Baltic Sea extends between latitudes 54 and 66 in the central area of the circumpolar low pressure zone of the northern hemisphere. Relative to the surface area of this marginal sea, the entrances to the North Sea have very small cross sections, so that only long-period oscillations of North Sea water levels propagate undamped into the Baltic. In its southwestern parts, the semi-diurnal tides are reduced to amplitudes of just 10 cm, and towards the central Baltic they disappear almost completely. Because of its enclosed geographical situation and elongated basin shape, the Baltic Sea tends to produce surface seiches with periods ranging from 26 to 39 hours, depending on the type of forcing of all contributing sea areas. Storm surges are triggered by changes in the wind fields above these areas. Strong southwesterly winds cause high water levels on its northern, and low levels on its southern coasts, with water flowing in through the Straits of Denmark increasing the water volume. A change in the wind direction to north/north-east causes high water levels in the southern Baltic, in which case the potential energy of water masses, which had been pushed north, may produce an additional impact. Both at the northeastern and southwestern end points of the Baltic Sea's longitudinal axis, peak high water values exceeding 3 m above MSL may occur. Storm surges may cause considerable damage along the coastlines, so that adequate coastal protection has to be provided. On the other hand, both storm surges and preventive protection measures may impair the functionality of technical structures. Under environmental protection and landscape preservation aspects, regular flooding of land areas is even indispensable to create a habitat for the highly specific, vulnerable flora and fauna of the salt marshes, which deserve special protection.

Sustainable coastal development: Sustainable coastal development in this context means to create a balance between coastal defence and environmental protection. Since 1974, the 9 countries bordering the Baltic have been co-operating within the framework of the Convention on the Protection of the Marine Environment of the Baltic Sea (or Helsinki Convention, according to its venue). Owing to the Baltic Sea's economic and ecological relevance to Northern Europe, it is one of the most intensively investigated marginal seas of the world. In Germany alone, 251 coastal research projects were officially recorded between 1990 and 1996, and the trend is upward. Internet search leads to a large number of national marine research institutes, shipping and environmental authorities, storm surge forecasting services, and to almost all universities in the area. Water level and storm surge forecasting for the Baltic Sea today is based mostly on operational hydrodynamic models using output data of the meteorological Europe model, but also statistical methods are used. HELCOM recommendations may be interpreted and implemented differently depending on local conditions. Both climate and sea level fluctuations as well as people's traditional ways of coping with nature's forces play a role in this respect. Near the oscillation nodes, i.e. near the center of the Baltic's longitudinal axis, storm surges of course do not reach the same high levels as at the end points. Since local coastal defence measures are based on past experience, the dykes built in such areas are generally lower. The problem that has to be dealt with in the different areas thus is identical: local and temporary aspects must be considered in the investigation of storm surge scenarios. The secular coastal dynamics of the Baltic (land gain in the north, land losses in the south) and the different local impacts of land/sea interactions (abrasion and accumulation coasts) require primarily the acceptance of natural processes, and human intervention should only come second.

Climate and sea level fluctuations: Since the last ice age, after the melting of glacial ice on Fennoscandia, the North Scandinavian landmasses have risen 80–90 cm per century. At the same time, a tilting motion of the Earth's crust has caused a 10–20 cm subsidence of the German Baltic coast per century. However, this fact only partly explains the increasing number of storm surges observed in the 20th century. Detailed investigations of storm surge occurrences have revealed correlation with characteristic atmospheric circulation patterns and certain parameters of the circumpolar low pressure zone (North Atlantic oscillation). Storm surges in the Baltic Sea thus also serve as an interesting indicator of climate developments in Central and Northern Europe. Numerous astronomical tides, primarily those having very long periods, have been identified in the mean sea levels of the Baltic. A significant cycle of 10–11 years has been found which is related to solar activity. However, as the changes observed in the parameters of the circumpolar low-pressure zone are extremely small, this causal relationship is still considered to be an unsatisfactorily proven despite the informative studies of CURRIE (1981) and LABITZKE and VAN LOON (1988). A different interpretation is rather unlikely, though, considering the fact that the phases of the 10–11 a signal measured at all Baltic gauges differ by about 130° between the northern and southern Baltic areas. The climate signal even exhibits a phase difference of about 170° in this respect. A counter-running trend like this, which could also be interpreted as a variable longitudinal tilt in the water surface, can only mean that the cause is an internal phenomenon of the Baltic region, which is not based primarily on hydrodynamic characteristics of the North Atlantic. Periods attributable to the latter (e.g. the Saros period, or half-period of moon apse-line cycle) only exhibit minor phase differences between the northern and southern Baltic Sea levels. The high correlation between wind fields in the Baltic and water levels in the time window of high and low water occurrences confirms this interpretation.

Scenarios and statistics: The physical processes and causes of storm surges in the Baltic will continue unchanged also in the future. The travel time of gravity waves is bound to a mean Baltic Sea depth of some 55 meters, so that even a hypothetical rise or fall of the mean sea level by one meter would not cause major changes in the natural periods of the Baltic. Forcing of storm surges depends, among other factors, on changes in wind direction and speed per space or time unit. For example, higher increase rates in a scenario of rapidly tracking low-pressure zones would be compensated partly by the shorter period available for integration of the water levels until high water stand. A preferred method for predicting regional trends during storm surges does not exist presently. Flood protection measures are based generally on the highest water levels on record and take into account regional sea level trends. In this context, the climate scenarios developed by the IPCC are undoubtedly relevant. However, with regard to the functionality of port facilities or initiatives of environmental protection organisations to protect salt marshes in the area, i.e. wherever a certain acceptance of storm surge events may be assumed, statistical methods are preferred in assessing the probability of flooding. Although they clearly indicate an increase in the number of small and medium-size flood events in the 20th century, they do not show significant increases in the high water crest values. Also statistically significant data beyond the scatter of measurements, which might confirm an acceleration of sea level rise in the 20th century, have not been found. Because of the Baltic's own dynamics, an analysis of its storm surge climate should be based rather on weather scenarios than on water level data.

Sweden

BERGSTEN (1955) studied the relationship between winds and the water levels on the coasts of Sweden. He stated (p. 32-133):

Generally, the water level in the South Baltic rises when the winds are northerly, and falls when they are southerly ... The consequence is that on the south coasts of Skane and Blekinge offshore winds will raise the water level, and winds from the sea will reduce it ... Another consequence is that the water level in the Sound and the Belts will be greatly changed in height; e.g., SW gales are blowing, as these will lower the water level in the South Baltic, and raise it on the west coast. The difference between the levels in the South Baltic and the west coast may in extreme cases be as much as a couple of meters. As far as the Sound is concerned, the difference is concentrated on the very short distance from Limhamn to Klagshamn, where a submarine bank runs from the Swedish to the Danish side, constituting the boundary between the Baltic and the western seas. North-easterly gales reverse these conditions.

The surges at five locations on the Baltic coast of Sweden for the storm surge of January 2-5, 1954, are shown in 7.28. This surge was generated by a northerly gale. The surge at Björn on January 3 is particularly interesting because it shows that the Åland archipelago acts as a strong barrier to the southward flow of water.

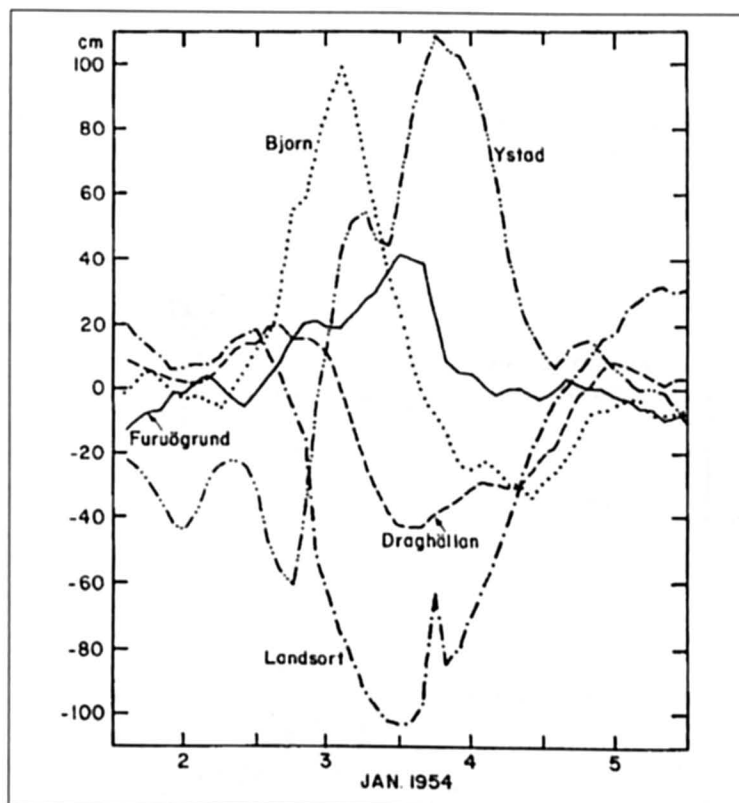


Fig. 7.28: Observed storm surges on the Baltic Sea coast of Sweden during January 2–5, 1954 (BERGSTEN, 1955)

Denmark

Denmark is attacked by storm surges at both the east and west coasts, i.e. from the Baltic Sea and the North Sea.

EGEDAL (1957) examined the storm surges at Randers on the east coast of Jutland. Depressions traveling over Jutland from the west cause north-northeasterly winds, which generate surges on the east coast of Jutland. Another area where surges are generated by such a weather system is the Island of Funen (Fyn). EGEDAL remarked that as far as storm surges are concerned, there are similarities between the east coast of Jutland and the east coast of the United Kingdom.

RINGE-JORGENSEN (1958) studied the storm surges along the North Sea coast of Denmark. The tidal amplitude varies from about 1.5 m near the Danish-German boundary to about 0.4 m at Thyboron. This study suggested that a meteorological situation similar to that of January 31–February 2, 1953, event could cause surges with amplitudes up to 3.4 m at Harlingen (Holland) and only about 1 m at Hanstholm (50 km north of Thyboron). The influence of the Norwegian Ditch appears to prevent the occurrence of very large amplitude surges at Thyboron but permits the occurrence of a large number of moderate surges.

LACOUR (1917a) studied the storm surge of January 15–16, 1916. He presented tables of the surge amplitudes at 46 locations at every hour from 12:00 on the 15th to 00:00 on the 17th. He also showed several diagrams of winds, currents and the water level at various times. Peak surges up to 1.9 m occurred. The distribution of the storm surge heights at 06:00 January 16, 1916, is given in Fig. 7.29.

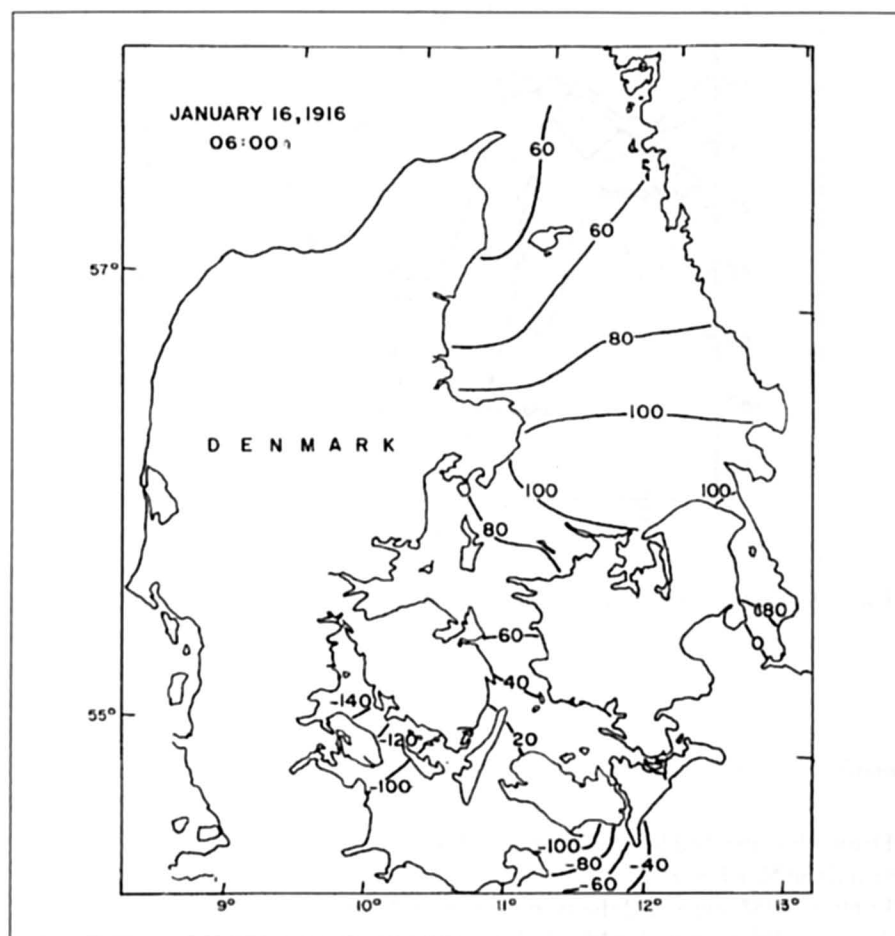


Fig. 7.29: Storm surge amplitudes along the east coast of Denmark at 06:00 on January 16, 1916 (LACOUR, 1932)

7.3.3 Irish Sea

In section 5.1.2 the meteorological situations leading to storm surges in the Irish Sea were discussed. The storm surge at Liverpool during December 29, 1921, to January 2, 1922, and the pressure data are shown in Fig. 7.30. CRESWELL (1929) presented storm surge amplitudes at Holyhead, Belfast, Fleetwood and Preston for the surge of October 20–24, 1928. These range from 1 ft 7 in. (48 cm) to 4 ft 7 in. (140 cm). However, a surge on October 29, 1927, had amplitudes of 7 ft 8 in. (2.34 m) at Fleetwood and 10 ft 2 in. (3.1 m) at Preston. For this event, the amplitudes at Holyhead and Belfast were 3 ft 4 in. (1.04 m) and 3 ft 2 in. (0.97 m), respectively.

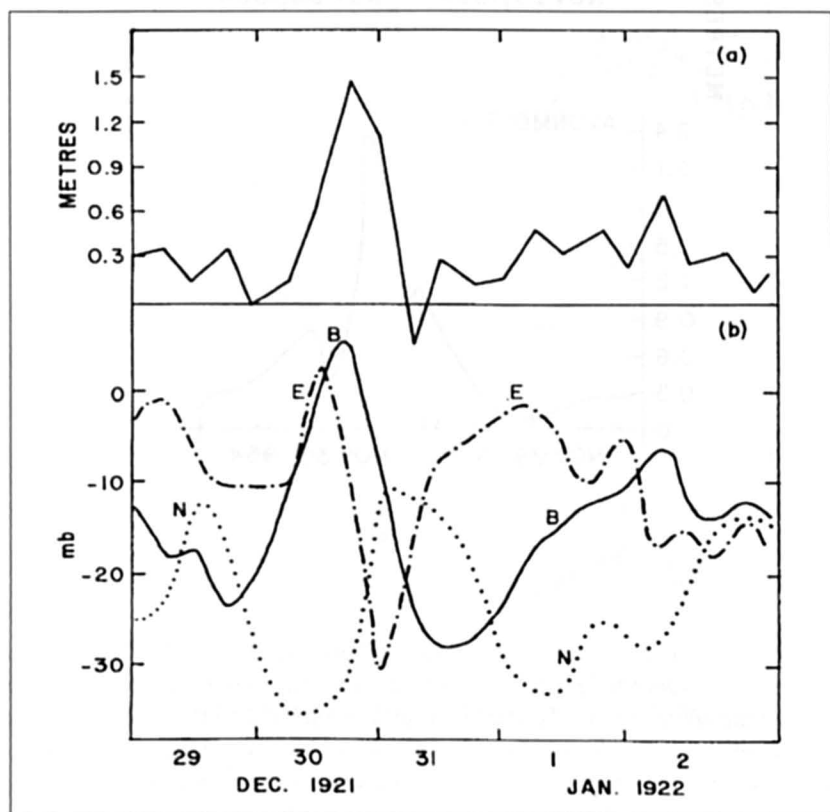


Fig. 7.30: (a) Storm surge at Liverpool, U.K., during December 29, 1921–January 2, 1922. (b) Curve B shows the fall of the atmospheric pressure at Liverpool; curves E and N, respectively, denote the east and north pressure gradients (millibars per 800 km) (DOODSON and DINES, 1929)

During the storm surge event of January 31, 1957, the surge amplitude at Liverpool reached a peak value of 3 ft whereas another event on February 4, 1957, produced a surge with amplitude of 5.8 ft (1.76 m). Another surge event of January 11–12, 1962, produced surges up to 5.5 ft (1.68 m) at Liverpool and up to 6.5 ft (1.98 m) at Avonmouth. The surges at Milfordhaven and Avonmouth during November 29–30, 1954, are shown in Fig. 7.31.

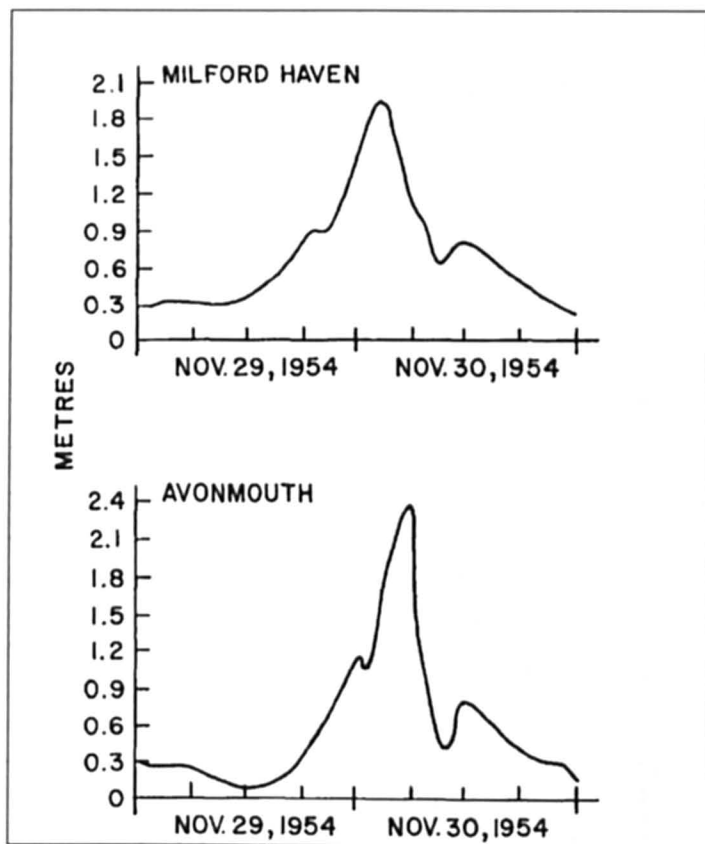


Fig. 7.31: Storm surges at Milford Haven and Avonmouth, U.K., during November 29–30, 1954 (HEAPS, 1967)

CORKAN (1952) mentioned that localized northerly winds over the Irish Sea would lower the water level everywhere in this water body, with the minimum decrease occurring at Liverpool. Strong southerly winds near the southern entrance to the Georges Channel will produce only small surges at locations such as Cork and Newlyn. After several hours, the general level rises in the Irish Sea. On the other hand, when a depression exists south of Ireland (with strong southerly winds blowing steadily) over the Bay of Biscay, surges up to 1–2 ft (0.3–0.6 m) could occur inside the region bordered by a hypothetical line joining Cork to Newlyn.

HEAPS and JONES (1975) simulated the storm surge in the Irish Sea for the event of January 10–18, 1965, using a two-and-a-half-dimensional model. The surge profiles at several locations in the Irish Sea (observed and computed) are shown in Fig. 7.32. The horizontal distribution of the storm surge heights at two different times is given in Fig. 7.33.

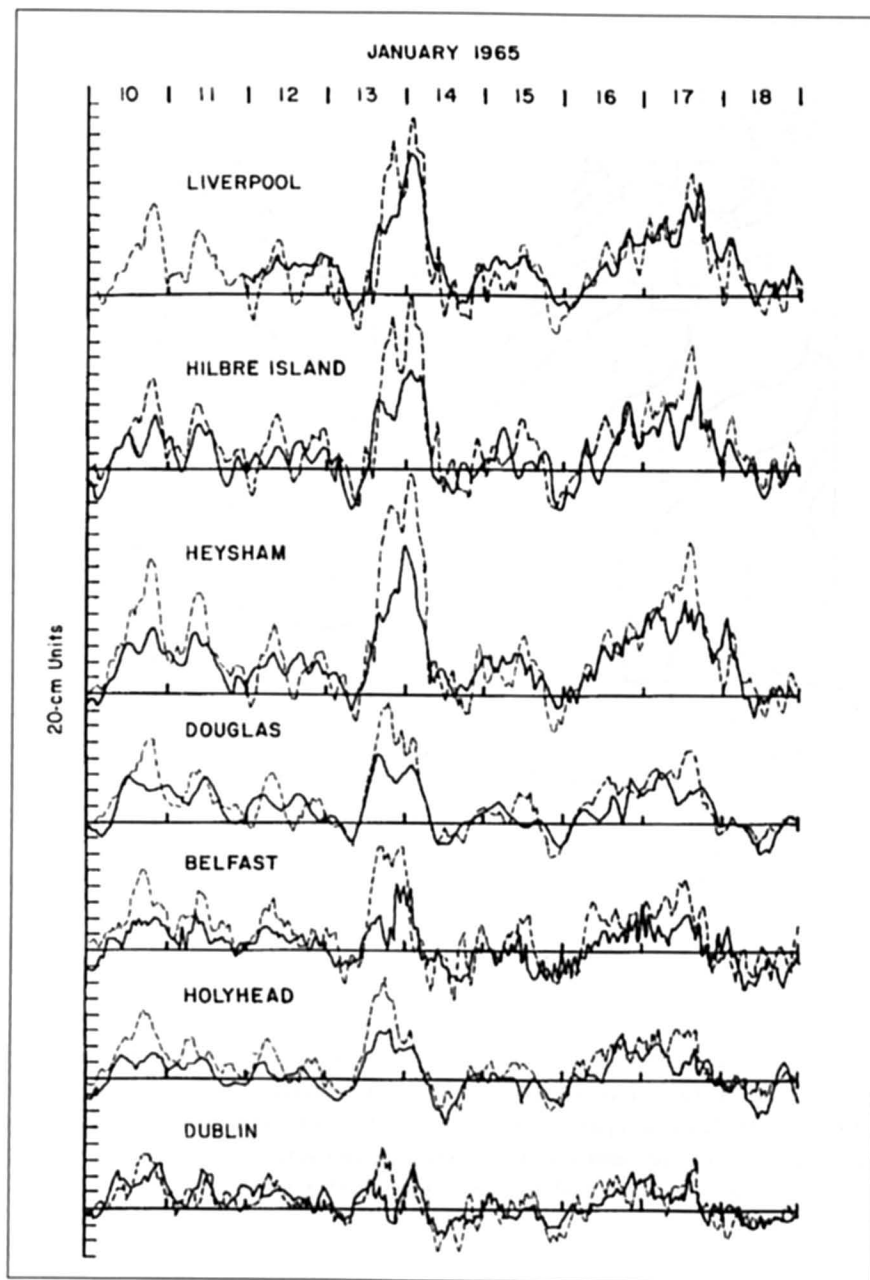


Fig. 7.32: Storm surges at various locations around the Irish Sea during January 10-19, 1965 (One unit = 20 cm along the ordinate) (HEAPS and JONES, 1975)

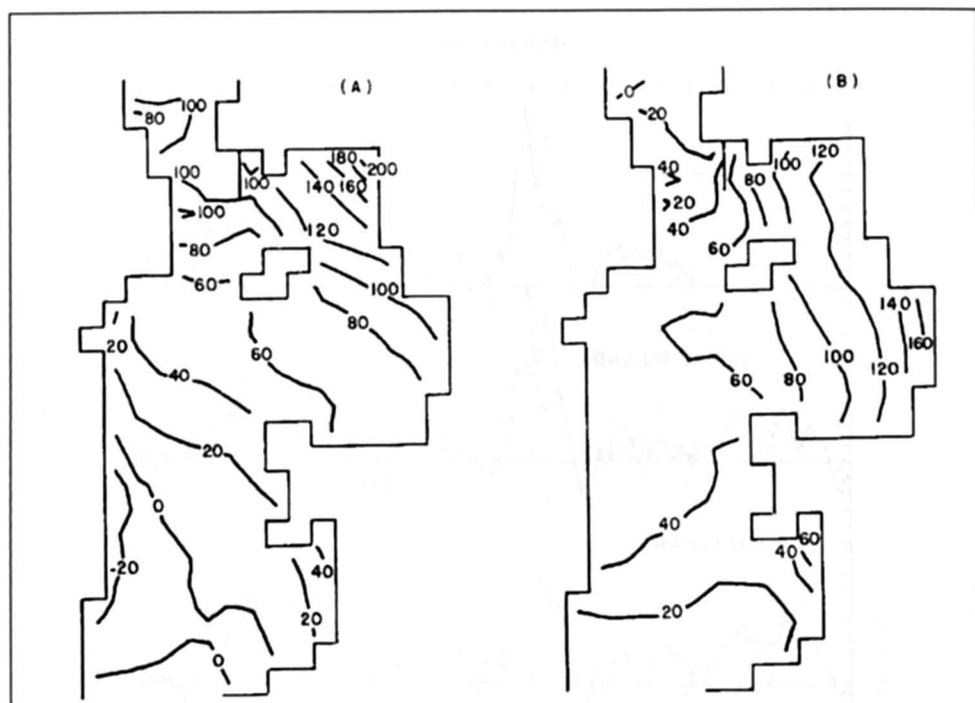


Fig. 7.33: Distribution of storm surge heights (centimeters) in the Irish Sea on January 14, 1965, at (A) 00:00 and (B) 04:00 (HEAPS and JONES, 1975)

HEAPS and JONES (1979) also simulated the storm surges in the Irish Sea for the events of November 11–15, 1977, and January 2–3, 1976, and compared these with the event of January 13–17, 1965. They paid particular attention to the time of occurrence of the peak surge relative to the times of high and low water. The tide and surge (computed and observed) at Liverpool and at Workington are shown in 7.34 and 7.35, respectively.

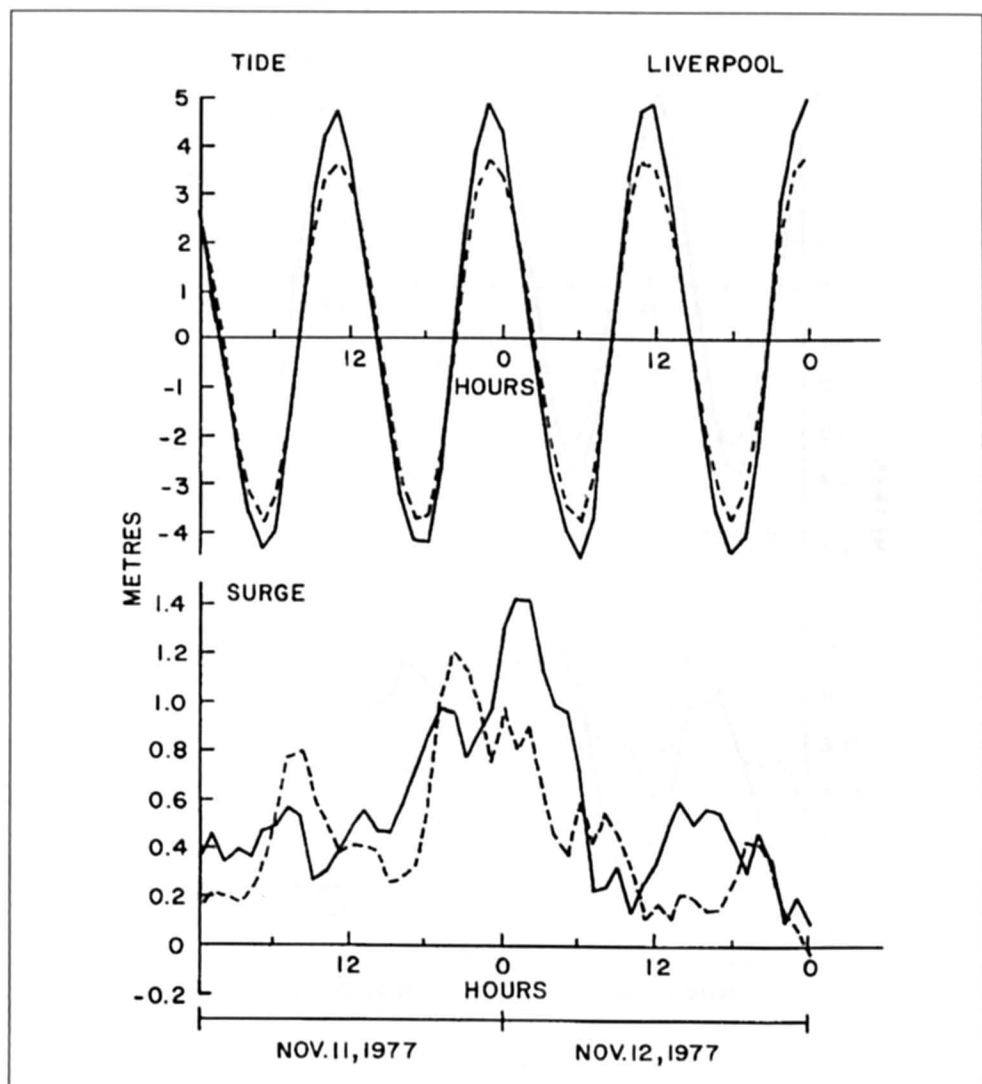


Fig. 7.34: Top: observed (solid line) and computed (broken line) tide at Liverpool during November 11–12, 1977. Bottom: observed (solid line) and computed (broken line) surge at Liverpool for the same period (HEAPS and JONES, 1979)

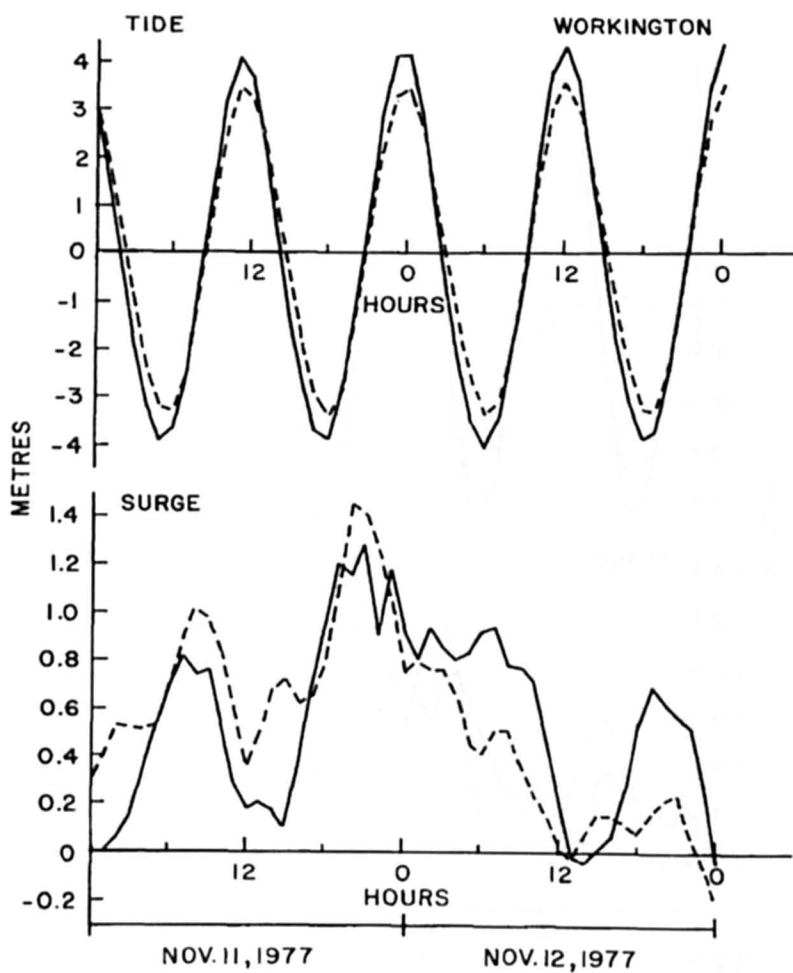


Fig. 7.35: Tide and storm surge at Workington, U.K. See Fig. 7.34 for explanation (HEAPS and JONES, 1979)

7.3.4 Mediterranean Sea

France

The North Sea coast of France was discussed earlier. Here, the Atlantic and Mediterranean Sea coasts of France will be considered.

FABRY (1909) studied the surge near Marseille (on the Mediterranean Sea coast of France) of June 15, 1909. The surge amplitude was between 0.4 and 0.8 m and an earthquake might have caused this, making this water level oscillation a tsunami rather than a storm surge. Some water level oscillations can occur in this region due to landslides.

CREPON (1974) studied water level oscillations on the Mediterranean coast of France. Note that in this area the tidal range is rather small (less than 1 m). Crepon applied his analytical theory to study the water levels at Sète located at the Mediterranean coast of France. Here, the continental shelf is about 100 km wide with a water depth of 90 m and there are no significant orographic influences on the wind field. The observed and computed water levels at this location for the period January–March 1969 are compared in 7.36. Some storm surge effects can be seen around the following dates: January 3–4, February 17–22, February 27, and March 21–23. It is interesting to note that the calculated water levels are systematically lower than the observed values. Also, the observed maximum values were about 0.5 m.

LACOUR (1917b) studied the storm surges at Brest (on the Atlantic coast of France) for the period 1861–1905. It appears that no significant surges occurred. One may conclude that storm surges are probably not significant in France except on the North Sea coast.

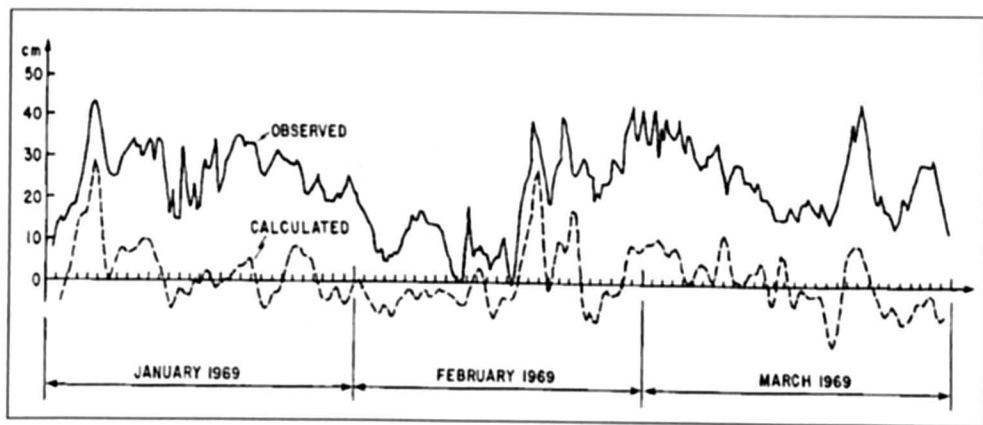


Fig. 7.36: Observed and calculated water levels at Sète (on the Mediterranean coast of France) for the period January–March 1969 (CREPON, 1974)

Israel

STRIEM (1974) studied the storm surges at Ashdod at the Mediterranean coast of Israel using the data for a 6yr period (1965–70). The tide here is mainly semidiurnal with a range of less than 1 m. The data for this study were selected whenever the daily mean sea level exceeded the average level by at least 20 cm and when there was a storm present.

STRIEM (1974) used the term “storm surge” to denote the changes in sea level at Ashdod during a period of several days due to storms in the eastern part of the Mediterranean Sea and

the term "storm set-up" to denote the rapid changes in the water level during a few hours. Three examples of these storm set-ups are shown in 7.37.

The six largest positive storm surges at Ashdod during the period of this study are summarized in Table 7.9a. The six largest negative storm surges at Ashdod are listed in Table 7.9b. The factors that cause the sea level to rise and fall at Ashdod are summarized in Tables 7.10 and 7.11, respectively. It was found that the storm surges at Ashdod basically are gradual changes in the daily mean sea level and that these changes could be linearly correlated with daily mean values of wind wave heights and wind velocities at the shore.

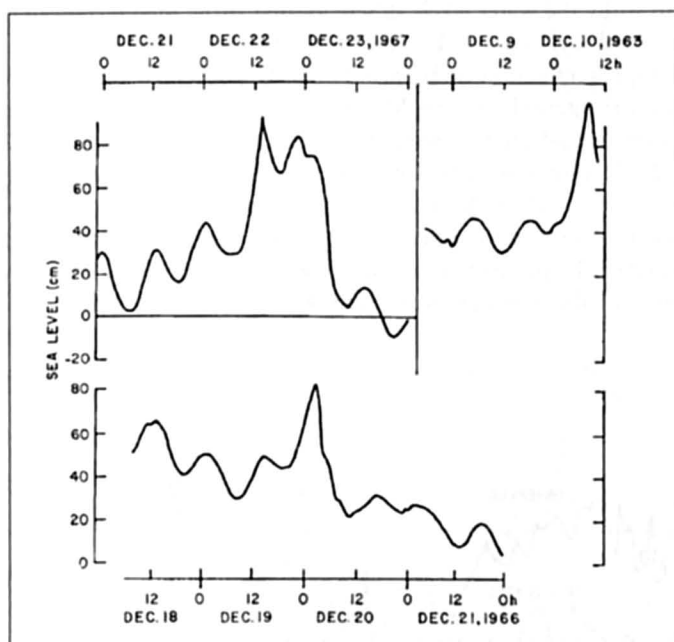


Fig. 7.37: Storm surges at Ashdod, Israel. Examples are shown of rapid changes. Top left: December 21–23, 1967; top right: December 9–10, 1963; bottom: December 19–21, 1966 (STRIEM, 1974)

Table 7.9a: Six largest positive storms surges at Ashdod, Israel, during 1965–70 (STRIEM, 1974)

Date	Amplitude of surge (cm)
Dec. 10, 1963	100
Dec. 22, 1967	93
Dec. 20, 1966	83
Feb. 5, 1965	63
Mar. 26, 1967	63
Jan. 14, 1968	63

Table 7.9b: Six largest negative storm surges at Ashdod, Israel, during 1965–70 (STRIEM, 1974)

Date	Amplitude of surge (cm)
Jan. 29, 1964	51
Mar. 24, 1966	46
Mar. 26, 1968	45
Feb. 12, 1968	42
Oct. 16, 1970	41
Apr. 12, 1968	40

Table 7.10: Factors contributing to the rise of sea level at Ashdod, Israel (STRIEM, 1974)

Factor	Time of occurrence	Approx. maximum rise of sea level (cm)
(a) High of spring tides	Vernal equinox	+ 26
(b) High of the seasonal fluctuation	Midsummer	+ 10
(c) High annual mean sea level		+ 7
(d) Rise due to daily inequality of the tides		+ 5
Total of effects not due to wind		+ 48
(e) Storm surges	Winter	+ 40
(f) Storm set-up	Winter	+ 40

Table 7.11: Factors contributing to the lowering of sea level at Ashdod, Israel (STRIEM, 1974)

Factor	Time of occurrence	Approx. maximum fall in sea level (cm)
(a) Extreme low of spring tides	Vernal equinox	- 26
(b) Low of the seasonal fluctuation	End of spring	- 10
(c) Low of annual levels		- 6
(d) Lowering due to daily inequality of the tides		- 5
Total of effects not due to wind		- 47
(e) Lowering due to eastern (offshore) winds (or down-surge after onshore storms)		- 15 (or - 30)
Possible lowering due to occurrence of all factors		- 62 (or -77)

Egypt

Storm surges occur in the Suez Canal and also at the Mediterranean coast of Egypt. MURTY and ELSABH (1981) studied the storm surges at Port Said at the northern end of the Suez Canal and at Port Suez at the southern end of the canal using the data for 1966.

Table 7.12: Number of occasions (treating each hourly value as one case) when positive and negative storm surges at Port Said, Egypt, exceeded prescribed amplitudes in 1966

State of tide	Surge height (cm)									
	10	20	30	40	50	60	70	80	90	100
Positive surges										
Low tide	253	189	90	28	9	5	1	1	1	1
Rising tide	236	137	51	10	1	0	0	0	0	0
High tide	237	131	44	2	0	0	0	0	0	0
Falling tide	246	175	82	26	6	2	1	0	0	0
Negative surges										
Low tide	19	7	3	2	0	0	0	0	0	0
Rising tide	16	9	3	2	1	1	0	0	0	0
High tide	12	5	1	1	1	1	1	1	1	1
Falling tide	13	5	0	0	0	0	0	0	0	0

The length of the Suez Canal is about 175 km and the average depth is 15 m. At Port Said the tide is co-oscillating with the eastern part of the Mediterranean Sea and has an amplitude of 25 cm. At Port Suez the Red Sea tidal influence is felt and has an amplitude of 75 cm. Based on these features the Suez Canal can be classified into a long estuary, in the Proudman sense (discussed earlier under Tide-Surge Interaction in the North Sea and in the St. Lawrence Estuary).

Treating each hourly surge value as one case, the number of occasions when positive and negative surges exceeded prescribed values at Port Said and Port Suez is given in Tables 7.12 and 7.13, respectively. Earlier, it was seen that PROUDMAN's theory (1957) suggested that for a long estuary, for a tide of progressive wave type, maximum surges are associated predominantly with low tide (or rising tide), and for a tide of standing wave type, maximum surges are associated predominantly with high tide (or falling tide). Observations for 1966 showed that the theoretical results of PROUDMAN, when interpreted for the Suez Canal, agreed with the observations at Port Said but not with those at Port Suez.

Table 7.13: Number of occasions (treating each hourly value as one case) when positive and negative storm surges at Port Suez, Egypt, exceeded prescribed amplitudes for positive surges and 10–90 cm for negative surges in 1966

State of tide	Surge height (cm)													
	10	20	30	40	50	60	70	80	90	100	110	120	130	140
Positive surges														
Low tide	172	111	75	44	32	16	8	3	3	3	3	3	2	1
Rising tide	191	110	76	38	13	7	6	6	3	1	0	0	0	0
High tide	121	57	18	5	2	1	1	1	1	0	0	0	0	0
Falling tide	174	107	50	34	27	23	10	3	0	0	0	0	0	0
Negative surges														
Low tide	84	66	46	32	16	11	3	0	0					
Rising tide	104	69	45	45	14	21	1	0	0					
High tide	117	69	59	49	40	24	6	0	0					
Falling tide	113	84	55	27	38	9	9	2	1					

7.3.5 European Part of the Atlantic Ocean

Storm surges at the Atlantic coast of France have been described before. Storm surges can also occur at the northern part of the Atlantic coast of Portugal (MORAIS and ABECASIS, 1975). The tidal range in this area is about 3–8 m and wind waves up to 13 m can occur here. A surge during January 16–17, 1973, did considerable damage in the Leixoes Harbour. The damage was severe because the surge occurred at the time of spring tide. The center of a low pressure system passed over Leixoes and its exceptionally long duration of 24 h generated very large wind waves.

In the surge record, waves with periods between 4 and 40 min attained significant amplitudes. Leixoes Harbour exhibits a seiche with a 4-min period, which was amplified by resonance. There is evidence of the occurrence of a Helmholtz mode type motion also.

Storm surges occurred again in January and February 1974 but the damage was minimal.

7.3.6 Adriatic Sea

In Italy, storm surges occur along the Ligurian Sea coast, the Tyrrhenian Sea coast, and the Adriatic Sea coast. On February 18, 1955, a cyclone caused great damage to the breakwater in Genoa Harbour (GRIMALDI, 1955; D'ARRIGO, 1955). Strong winds from the southwest-generated wind waves with greater than 7-m amplitudes and possibly also a storm surge. Some of the water level problems in the Ligurian Sea associated with weather systems were discussed in section 5.1.2. Northeastern Italy is a region where storm surges occur. BONDESAN et al. (1995) investigated the effect of global change on sea surges and stated that the frequency would increase.

The city of Venice is located at a lagoon off the Adriatic Sea and less than 1 m above the mean sea level. Hence, storm surges with amplitudes less than even 1 m cause serious flooding problems in Venice. To add to the problem, the openings between the sea and the lagoon are more extensive now (due to dredging) than before, which allows the storm surge from the sea to travel unimpeded. In addition, in the twentieth century the city subsided by 20 cm.

Storm surges occur quite frequently in this area (TOMASIN and FRASETTO, 1979), for example, in the years 1966, 1967 and 1972. The storm surge season lasts from November to February and occasionally to April. The first two normal modes of the Adriatic Sea have periods quite close to the diurnal and semidiurnal tides. The tidal range is 25–80 cm, the tide being forced by the Mediterranean Sea. There appears to be no interaction between the tide and the surge.

TOMASIN and FRASETTO (1979) studied the surge of April 21–22, 1967 (Fig. 7.38). What makes the problem more complicated is a seiche with a period of about 1 d that can be excited by weather systems. Such a seiche during February 16–20, 1967, is shown in Fig. 7.39. Observed and computed surges at Venice for February 12, 1972, are shown in Fig. 7.40. In the fall of 1982, major storm surges occurred at Venice and Trieste causing considerable damage.

In 1975 the Italian government devised a plan to reduce the effects of tides and storm surges at Venice by constructing barriers to narrow the entrances to the Venice lagoon (VITTORI and TAMPIERI, 1979).

The commune of Venice operates a statistical forecast model. ADAMI and NOLI (1992) describe this model and present an alternative modelling tool, which has been tested by the Danish Hydraulic Institute. "It was found that the existence of reliable air pressure predictions could increase the forecast horizon of reliable storm surge prediction from 3 to 24 hours."

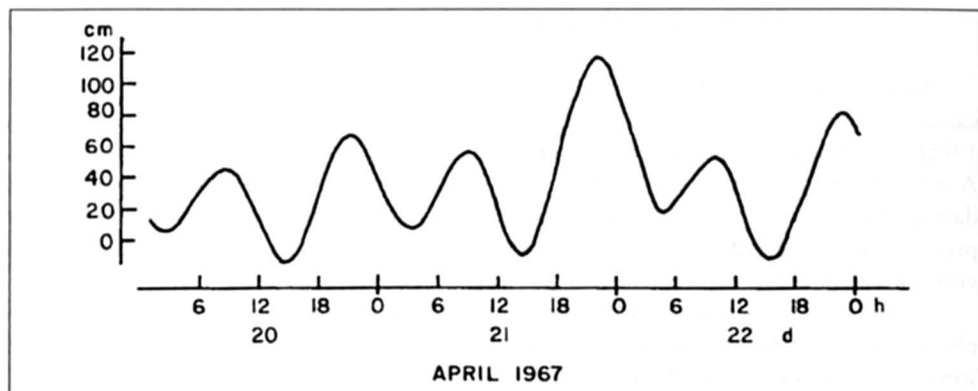


Fig. 7.38: Recorded water level (tide plus surge) at Venice, Italy, during April 20-22, 1967. Time is GMT - 1 (TOMASIN and FRASETTO, 1980)

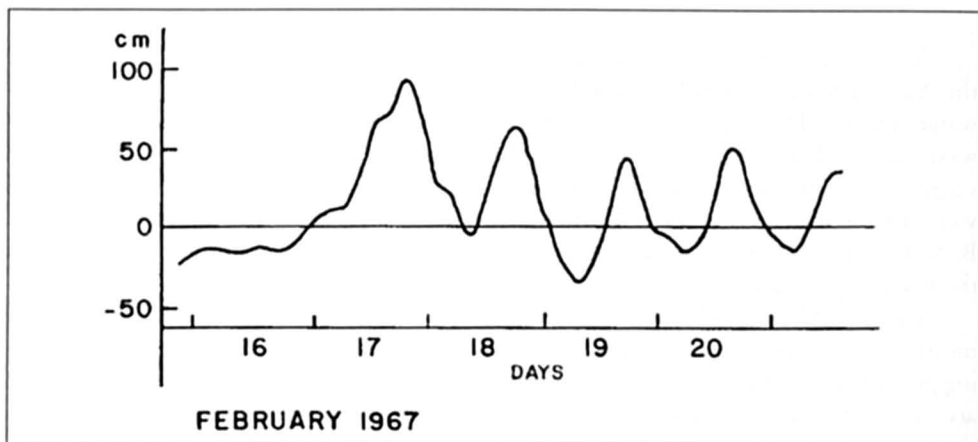


Fig. 7.39: Seiche at Venice, Italy, with a period of approximately 24 h (TOMASIN and FRASETTO, 1979)

STRAVISI (1972) used a one-dimensional numerical model to simulate hypothetical storm surges in the Adriatic Sea. Storm surge amplitudes at two different times are shown in Fig. 41. ADAMI and NOLI (1992) also carried out research on a forecasting system with a hydrodynamic model for the Adriatic. The Danish Hydraulic Institute calibrated a 2D model to reproduce tidal phenomena and seiching. To calibrate the storm surges at least seven historical surge events were simulated with storm winds and air pressures. With good meteorological data storm surge prognosis was very good for forecast up to 5 days.

For the Northern Adriatic Sea MAZARELLA and PALUMBO (1991) took into consideration the seasonal, 11-yr. and secular signals, which are more significant and several times larger than those in the mean sea level for the computation of the storm surge development and mean sea level rise. They stated that analyses of sea level maxima adjusted for such time variations, gives a more adequate and realistic basis for making predictions on the occurrence of damaging storm surges. Data from the gauges at Venice (1924-1970) and Trieste (1944-1988) have been investigated. After using the extension of the annual maxima approach from earlier work for calculation of the occurrence of extreme events calculated non-cycle

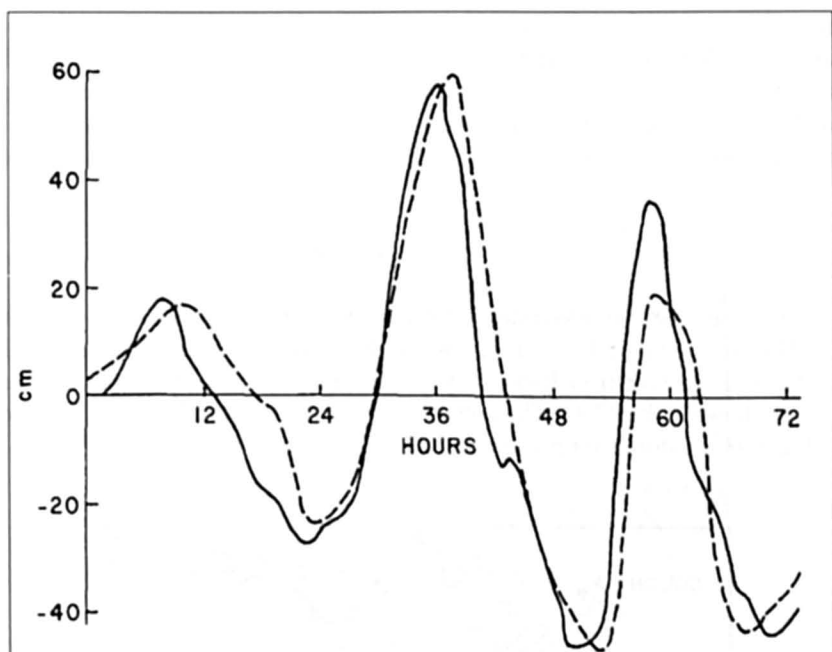


Fig. 7.40: Computed (broken line) and observed (solid line) surges at Venice during February 12-15, 1972. Time is hours from the starting time of 03:00 (GMT) on February 12, 1972 (TOMASIN and FRASETTO, 1979)

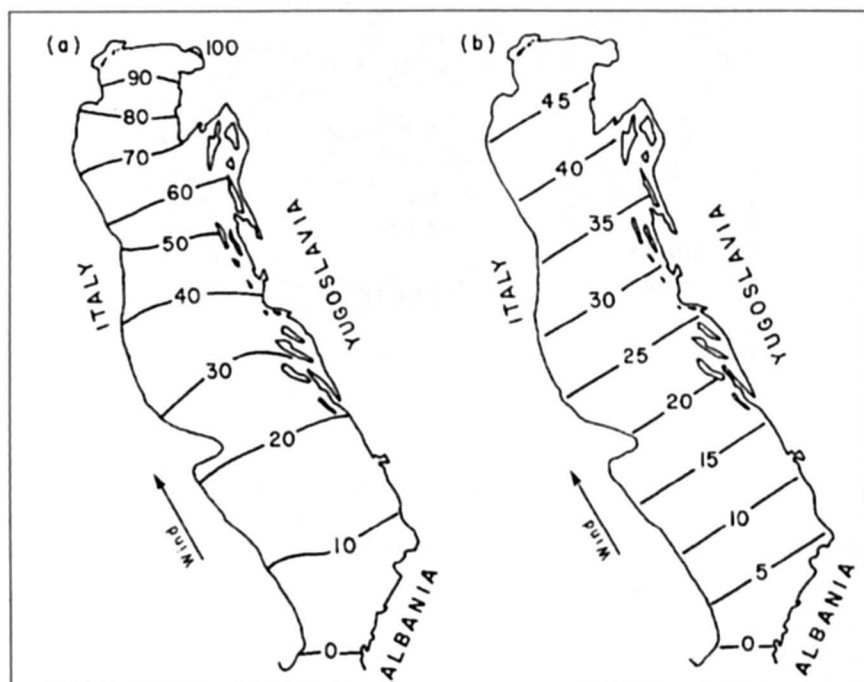


Fig. 7.41: Distribution of the amplitudes (centimeters) of a hypothetical storm surge in the Adriatic Sea at (a) 10 h and (b) 11 h after the start of wind stress application (STRAVISI, 1972)

variations of yearly SL mean and SL max, cycle variations seasonal and 11 yr. Waves have been carried out. MAZARELLA and PALUMBO (1991) summarised their results by stating that "the estimate of the return period obtained by means of the monthly maxima (filtered from seasonal, biennial and longer term non-stationary) is more robust against historical outliers than the analysis of annual maxima."

7.3.7 Aegean Sea

WILDING et al. (1980) studied tides and storm surges in the northwestern part of the Aegean Sea. The geography of this area is shown in Fig. 7.42. The tides are rather small in this water body, as can be seen from Table 7.13. The surges during August 20–23, 1975, at three locations are shown in Fig. 7.43. The power spectrum of half-hourly water level records is given in Fig. 7.44. Predominant periods of 2.68 and 2.40 h can be seen.



Fig. 7.42: Geography of the Aegean Sea (WILDING et al., 1980)

Table 7.14: Tides in the Aegean Sea (WILDING et al., 1980)

Location	Mean spring range (cm)	Mean neap range (cm)
Port Salonica	32.4	9.6
Saint Trias	29.0	6.6
Krini	29.6	4.4
Whaniona	29.4	5.0
Kayoura	29.0	4.6

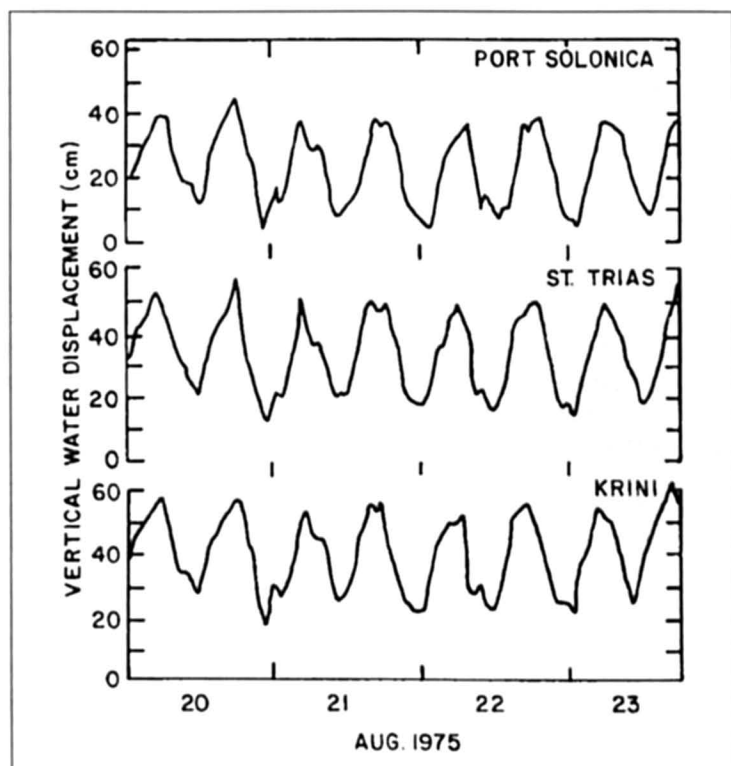


Fig. 7.43: Water level oscillations during August 20–23, 1975, at three locations in the Aegean Sea (WILDING et al., 1980)

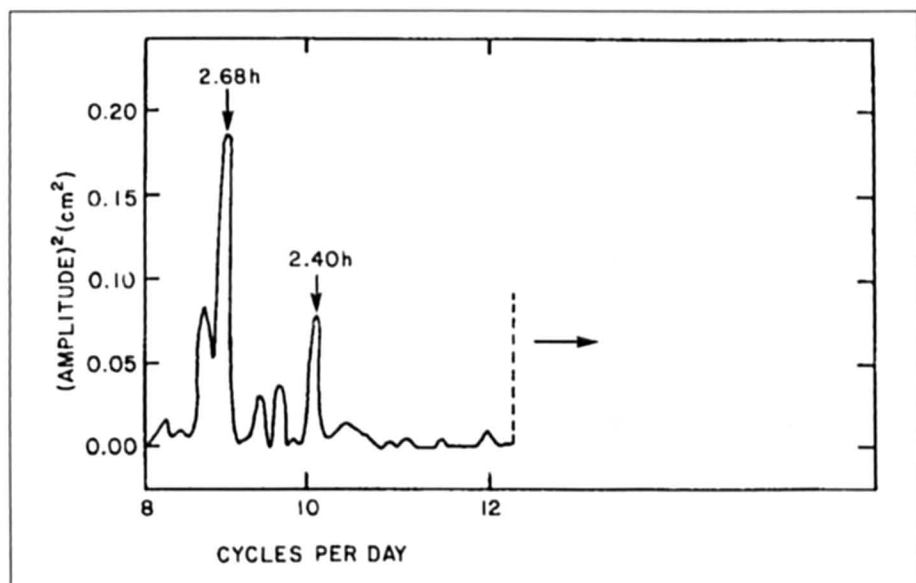


Fig. 7.44: Power spectrum of half-hourly water level data at Port Solonica (Aegean Sea) (WILDING et al., 1980)

7.3.8 Black Sea, the Okhotsk Sea and the Pacific

Moderate storm surges occur in the Black Sea, the Okhotsk Sea, the Pacific coast of Russia, the East Siberian Sea, and the Chukchi Sea. Large surges (up to 6 m in amplitude) can occur in Lake Baikal. Winds from north of this lake can produce surges that sometimes take only a few minutes to develop.

Earlier, the work of LAPPO and ROZHDESTVENSKIY (1977, 1979) was discussed in which they considered the lag of storm surges with reference to the atmospheric systems. Their work covered the northwest part of the Pacific Ocean in general and the Pacific coast of Russia near the Kurile Islands in particular. They considered the contribution of the static surge to the total water level deviation and developed the important concept of the hysteresis loop (Fig. 6.123). The lag between the atmospheric forcing and the storm surge could be anywhere between 5 and 18 h on this part of the Russia coast.

KOWALIK and POLYAKOV (1998) studied the tides in the Sea of Okhotsk. This is a region of large tidal sea level oscillations and strong tidal currents. The oscillation reaches 13 m in Penzhinskaya Guba. GORDAY et al. (1991) investigated extreme parameters of tsunamis in the region of Kuril-Kamchatka Trench and the Sea of Okhotsk using numerical simulation results.

MUSTAFIN (1969) studied the storm surges in the East Siberian and Chukchi seas with the particular aim of predicting the surges at Cape Schmidt. Based on 192 cases during the summer period (July–October) for 1951–55, in which the surges at Cape Schmidt and in Ambarchik Inlet exceeded 30 cm (both positive and negative surges), he prepared the following regression relationships:

$$\Delta h_{\text{Schm}} = a_1 \Delta p_1 \cos \alpha_1 + a_2 \Delta p_2 \cos \alpha_2 + a_3 \Delta h_{\text{Amp}} \quad (7.1)$$

$$R = 0.94 \pm 0.001, \quad \Sigma = 21$$

$$\Delta h_{\text{Schm}} = a_4 \Delta h_{\text{Amp}} \quad (7.2)$$

$$R = 0.90 \pm 0.01, \quad \Sigma = 26$$

$$\Delta h_{\text{Schm}} = a_5 \Delta p_1 \cos \alpha_1 + a_6 \Delta h_{\text{Amp}} b_1 \quad (7.3)$$

$$R = 0.93 \pm 0.004, \quad \Sigma = 23$$

$$\Delta h_{\text{Schm}} = a_7 \Delta p_2 \cos \alpha_2 + a_8 \Delta h_{\text{Amp}} b_3 \quad (7.4)$$

$$R = 0.92 \pm 0.007, \quad \Sigma = 24$$

$$\Delta h_{\text{Schm}} = a_9 \Delta p_1 \cos \alpha_1 + a_{10} \Delta p_2 \cos \alpha_2 + b_4 \quad (7.5)$$

$$R = 0.88 \pm 0.01, \quad \Sigma = 29 \quad (7.6)$$

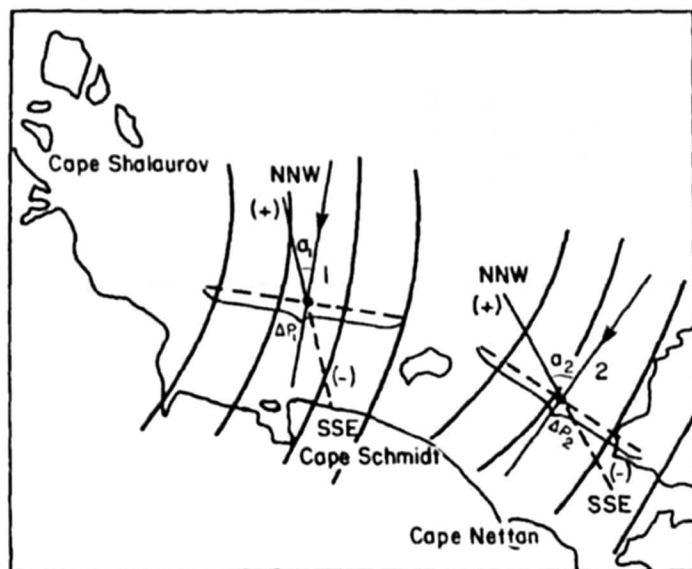


Fig. 7.45. Determination of the quantities Δp_1 and Δp_2 and the wind current direction from the isobars at points 1 and 2 (see eq. 7.1–7.6). a_1 and a_2 are the angles between the wind current direction (arrows) and the effective refluxing-fluxing direction north-northwest to south-southeast. The angles are acute and determine positive components (+) of Δp_1 and Δp_2 at the time of sea level fluxing motions and negative components (–) at the time of sea level refluxing wind directions (MUSTAFAIN, 1969)

where, Δh_{Schm} is the deviation (centimeters) of the no periodic factor in the sea level at Cape Schmidt from the mean annual navigational level, precalculated with an average forewarning period of 12–13 h upward (+) and downward (–); Δh_{Abm} is the deviation (centimeters) of the actual sea level in Ambarchik Bay from the mean annual navigational level upward (+) and downward (–); Δp_1 and Δp_2 are the respective pressure differences (millibars) at points 1 and 2 at a distance of 600 km (6 cm on a 1 : 10,000,000 scale map) along lines perpendicular to the isobaric trend (Fig. 7.45 of this chapter and Fig. 7 of MUSTAFIN, 1969); a_1 and a_2 are the angles between the wind direction along the isobars and the line running north-northwest and south-southeast (Fig. 7.45 of this chapter and Fig. 7 of MUSTAFIN (1969)); a_1, \dots, a_{10} are constants; b_1, \dots, b_4 are free terms; R and r are multiple and partial correlation coefficients and their probable errors; and Σ is the mean square root error (centimeters) of the regression equation.

Parameters Δp_1 , Δp_2 , a_1 , a_2 , etc., needed here are determined as shown in Fig. 7.45. One of the interesting features of this study is that, in contrast with the universally used technique of determining the atmospheric pressure gradients along constant directions, here, these gradients are calculated along variable directions but at pre-selected locations in the water body.

MUSTAFAIN's (1969) study was done for nine locations on the Siberian coast. Since knowing the water level at one location in advance might help the prediction at other locations, MUSTAFIN (1969) tabulated the correlation coefficients for the water levels between these stations. These are shown in Table 7.15. On this coast, the surges appear to lag the meteorological forcing by about 12 or 13 h.

Table 7.15: Correlation coefficients between the storm surges at various locations on the East Siberian Sea and Chuckchi Sea coasts (MUSTAFIN, 1969)

	Cape Shalau-Rov	Ambar-chik Inlet	Rau-Chua	Pevek	Cape Billings	Cape Schmidt	Cape Vankarem	Kolyuchin Island	Cape Nettan
Cape Shalaurov	1	0.86	0.83	0.85	0.82	0.75	0.70	0.84	0.77
Ambarchik Inlet		1	0.95	0.97	0.79	0.80	0.74	0.83	0.70
Rau-Chua			1	0.97	0.88	0.87	0.86	0.80	0.74
Pevek				1	0.85	0.90	0.67	0.81	0.85
Cape Billings					1	0.86	0.83	0.71	0.77
Cape Schmidt						1	0.84	0.84	0.91
Cape Vankarem							1	0.78	0.81
Kolyuchin Island								1	0.85
Cape Nettan									1

7.3.9 Storm Surge Forecasting

Storm surge forecasting and quick dissemination of warnings are of high importance for people living at coastlines and tidal rivers behind the dykes. This addresses the demand, that a storm tide forecasting method must satisfy the highest level of scientific standards that can be reached. Methods that are developed by hindcasting 5 to 10 special storm tides are not serious enough. Investigations show that we have to consider many more different surge types. The description follows closely IHP-OHP (IHP-OHP, SIEFERT and MURTY, 1991), and also based on CHRISTIANSEN and SIEFERT (1979), SIEFERT (1980).

The following examples are designed to give a survey of the state of present-day practice-orientated storm surge research and its application. Regional and supraregional systems will be mentioned in this connection.

The English East Coast

Following the storm surge of Jan. 31/Feb. 1, 1953, leaving behind on the English east coast 300 victims and 24.000 destroyed homes, a research group came to the decision that a warning system for high storm surges between Northhumerland and Kent should be established and investigations be made simultaneously as to whether such system should also cover the Channel, the Bristol Channel and the Irish Sea. Assuming that surges during the neap tide might be neglected, the warning service decided that storm surge prediction will be made only during spring tide. But since at certain locations on the east coast the height differences between spring and neap tides are insignificant so that a surge during neap tide can cause damage, the warning service must operate independent of the type of surge prevailing.

Storm surges on the English east coast develop from the North to the South. First indications as to potential storm surges can be obtained at the first arrival of tidal waves in the North Sea in the region of the Shetland Islands, partly even near the Hebrides. The forecasting system has been set up accordingly. One tries to recognize the storm surges, if possible, already far away in the north and to determine the height at the reference gauges using wind forecasts. Reference gauges are Stornoway/Hebrides, Wick, and Aberdeen.

From the northern tip of Scotland (John o'Groats) the tidal wave needs about 4 h to reach the English border and then another 9 h to reach the Thames. It is, of course, an advantage that such storm surges at the early stage of inaccurate forecasts first reach almost unpopulated coasts in less need of protection. Actual forecasts are being made only for the English east coast, which is subdivided into 5 divisions with one reference gauge, each Fig. 7.46.

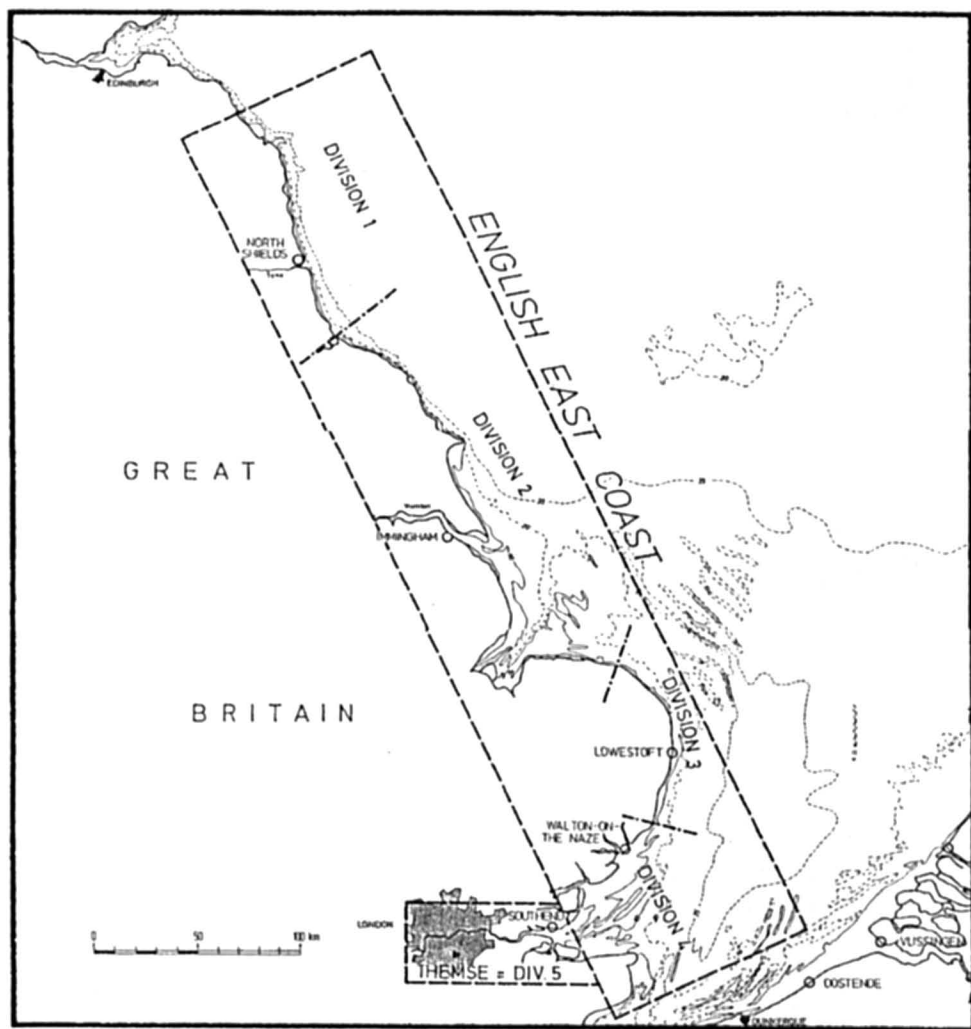


Fig. 7.46: Forecast area English east coast

Whether in the future more attention must also be given to the adjacent Scottish east coast in the north, will be decided in the course of further development in the field of oil exploration. For each reference gauge a "critical level", was fixed. If it is exceeded, certain areas will be flooded. If there is danger that this level will be reached, a warning is issued.

A first early warning (alert) can be given 12 h before HW. The second bulletin i. e. confirmation or withdrawal of the warning, is given 4 h prior to HW. Then, if required, the expected HHW level is pronounced. In the case of warnings for Div. 5 (Thames), a "London Flood Room" is taken over by the Greater London Council. There, the HHW for London is determined using the HHW forecast for Southend and the Q_0 discharge. To set off in time such a procedure in London, the 2nd warning is given as early as 6 h prior to HHW Southend.

The "storm surge season" on the English east coast extends from the end of August to 30 April. On average, that means 100 "alerts", 20 real warnings and 5 critical level reports.

There is a number of empirical correlations based on statistically secured regressions between the water levels at the reference gauges (see above), the wind and the water levels at the Stornoway, Wick and Aberdeen gauges, among which the best suited are selected in each case. The mean error is ± 0.2 m, individual deviations reaching 0.6 m. For Division 1 e. (Fig. 7.46), the equation reads as follows:

0.75.	(11 HW - MHW Wick)	4 h earlier
+ 0.003.	(320° comp. of the surface wind Fair Isle)	11 h earlier
+ 0.002.	(30° comp. of the geostrophic wind between Scotland and Southern Norway)	6 h earlier
+ 0.14 m		
<hr/>		
= HHW - MHW North Shields		

The main problems are at present:

- empiric approaches are based on only a few major storm surges (as these occur only seldom),
- dynamic wind effects are not taken into consideration,
- the interactions of tidal waves and waves due to wind stress are not taken into account, astronomical tide forecasts are inaccurate.

The Western Schelde

Storm surge forecasts for the Western Schelde are of great importance in particular for the port of Antwerp (about 80 km upstream of the mouth) with its numerous exposed installations. Therefore, extensive analyses were also made for this region after the storm surge of Feb. 1, 1953. It was thus found, inter alia, that northwest winds are the most dangerous winds. As a result of investigations made over many years a forecasting method was presented which, in principle, is based on a correlation of the HHW at Oostende and that at Antwerp (Fig. 7.47).

HWs occur at Oostende little less than 3 h earlier than at Antwerp. As this time period is too short for a reasonable forecast the Oostende HHWs are calculated about 2 h in advance.

These calculations are based, just as those for the Oostende-Antwerp correlations, on empirical estimates. The method is as follows:

$$\begin{aligned}
 & \text{extrapolation wind stress Oostende by 2 h} \rightarrow \text{HHW}_{\text{Oos}} \\
 & + \text{difference } \text{MHW}_{\text{Ant}} - \text{MHW}_{\text{Oos}} \\
 & + \text{wind according to direction and force off the coast} \\
 & \hline
 & = \text{HHW Antwerp}
 \end{aligned}$$

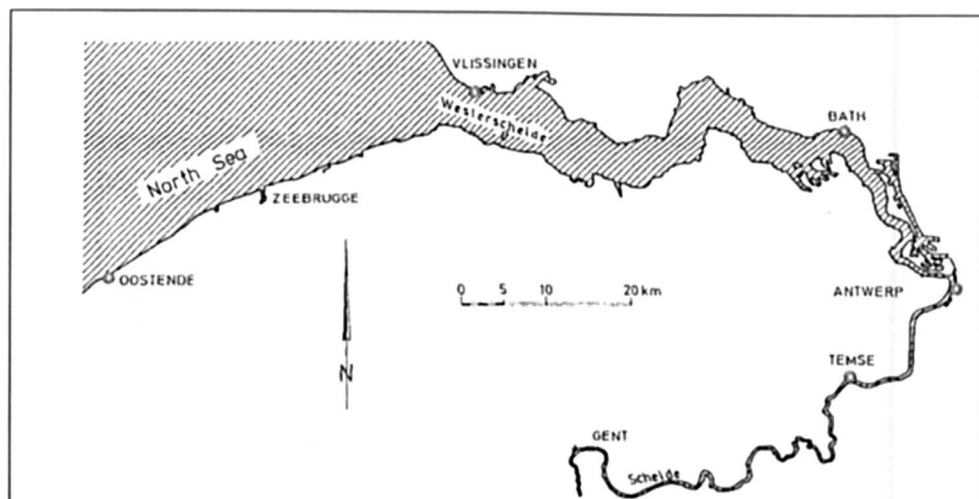


Fig. 7.47: Forecast area Western Schelde

The Dutch Coast

The theoretical principles for the methods applied in the Netherlands originated in the 1950s WEENINK and GROEN (1958). Their results have been tested in many practical applications.

For the stations of Vlissingen, Hoek van Holland, Den Helder, Harlingen, and Delfzijl (Fig. 7.48), the Koninklijk Nederlands Meteorologisch Instituut, (KNMI), publishes prognoses for the high water level due to meteorological causes. During a storm surge the "Stormvloedwaarschuwingsdienst" in The Hague determines the exact heights at the above stations and decides based on Q_0 and the predicted values whether warnings should be issued.

For the forecasting of water levels, correlations between HHWs of various places are needed. For this purpose, reference curves have been put together. Where the prevailing volumes of discharge have an influence on the rise, they have been covered by the statistical correlations.

As a supplement to this forecasting service, regional water level forecasts are also carried. Such forecasts are made on the basis of surge curves. For this purpose, data from a network of gauges, which have been in operation for several years for other purposes, are also relied upon. They are recorded via remote transmission in a central recording room. Every 5 minutes the water levels are recorded on punched tapes, analog recorders and a printer.

On the Dutch coast, too, one tries to use the possibilities offered by mathematical models for storm surge forecasts.

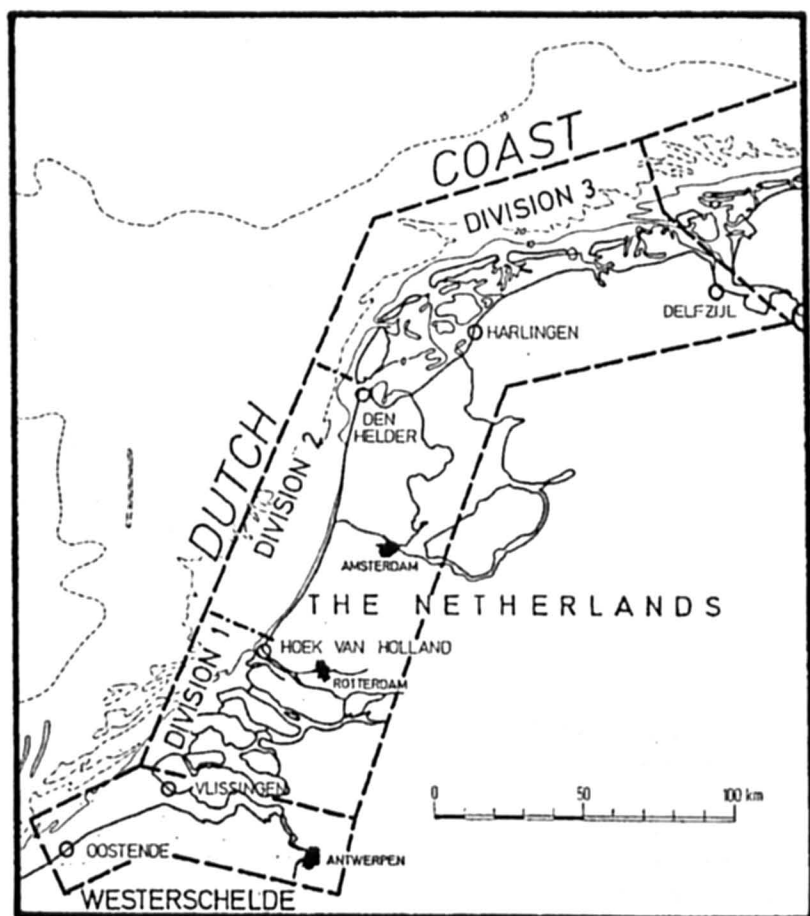


Fig. 7.48: Forecast area Dutch coast

Inner German Bight

Many forecasting methods often yield unsatisfactory results as they are based on weather forecasts and these weather forecasts – mainly wind speed and wind direction evolution – are not accurate enough.

The other reason for unsatisfactory predictions are the methods themselves. Usually only the peaks of storm tides are taken into consideration, representing only single points on a curve. Characteristics of tide and surge curves are not developed, and tide/surge interactions are not evaluated.

To exclude such difficulties a storm tide forecasting method should be developed

1. by analysing storm surge curves of storm tides over the last 50 years at several tide gauges on the coastline. A storm surge is defined as the difference between storm and mean tidal water level.
2. by taking into consideration as many wind data as are available;
3. by using only exact (not predicted) tide and wind data.

Fig. 7.49 shows the situation at the German North Sea coast.

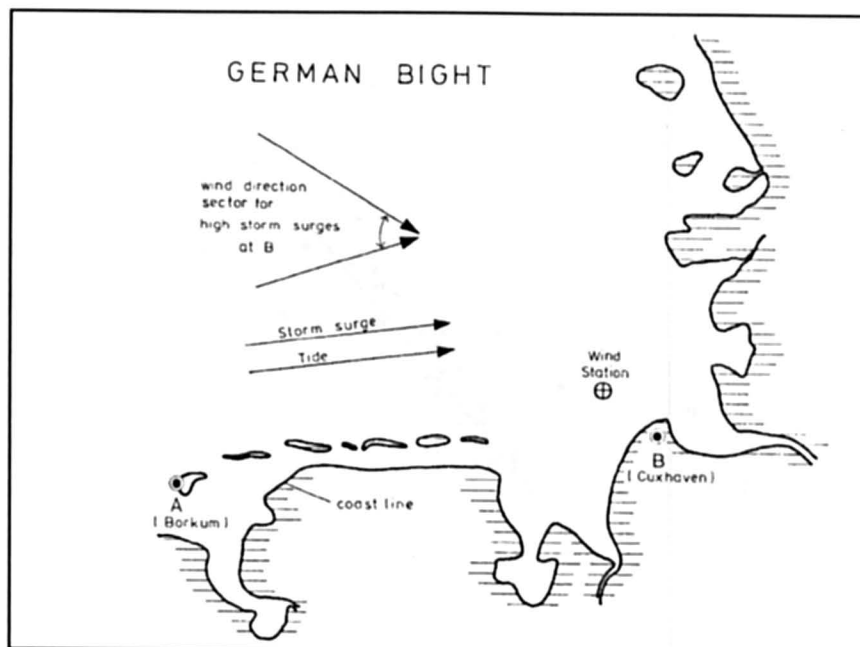


Fig. 7.49: Tide gauge locations A and B in the German Bight

In the German Bight the astronomical tide progresses in an anticlockwise direction. The winds during storm surge events come from west, as does the storm surge. Therefore, a forecast for a point B on this coastline needs information from a location westward of it (gauge A at the island of Borkum). This gauge A is the so-called input gauge for the forecast gauge B. However water level information merely from an input gauge is not sufficient.

Further investigations showed that an explanation for the outliers 7.50 can be given if wind speed and wind direction development within the last 3 hours before high tide at A (Borkum) are taken into account. The wind development in this 3-hour interval (about 3 hours before the expected high water level at B) is the best indicator for what will happen with water level changes in the following 3 hours after high tide at A. So about 3 hours before high tide at B no further wind information is needed to forecast the highest level at B. These conditions are in agreement with results at the Dutch and British coasts.

The high water level at B (H_B) can be roughly calculated by a simple linear formula:

$$H_B = 1.2 H_A + \Delta V + \Delta R - 80 \text{ cm} \quad (7.7)$$

where, $1.2 \cdot H_A - 80 \text{ cm}$ gives the trend of HW level comparison at A and Fig. 7.49 and ΔV (Fig. 7.51) and ΔR (Fig. 7.52) are the partial contributions to wind speed and wind direction developments respectively within 3 hours before forecasting time.

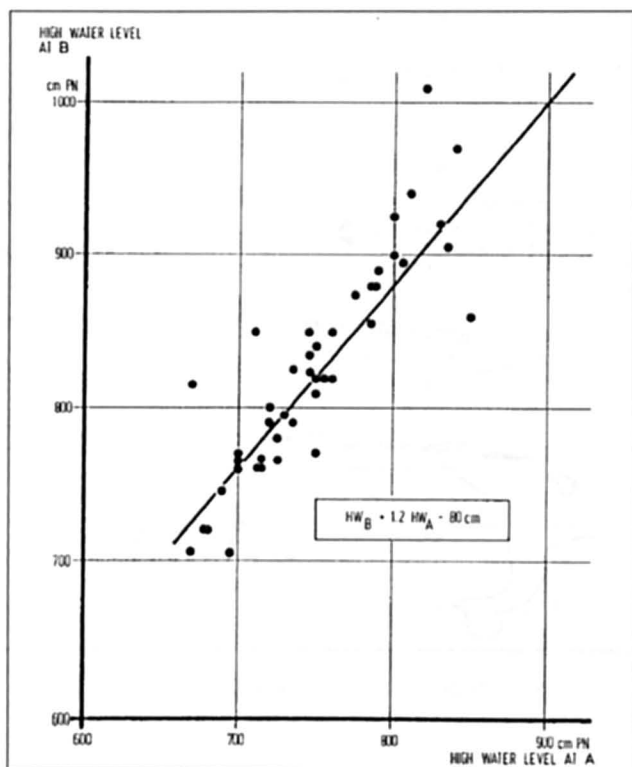
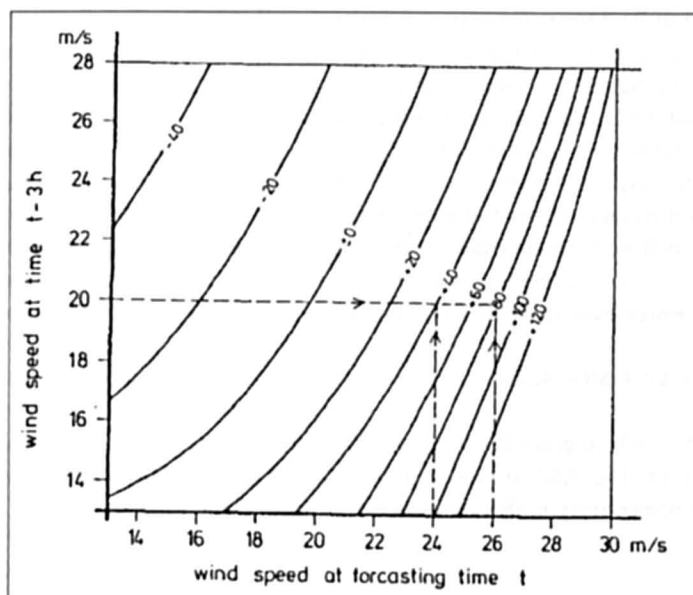


Fig. 7.50: Comparison of high water levels at A and B

Fig. 7.51: Wind speed development value ΔV in cm

This prediction method has been used for the calculation of the high water level in Hamburg using the predicted water level at Cuxhaven + a constant 110 cm. Long-term monitoring shows that this amount must be differentiated more accurately, because fairway and embankments improvement measures at the Elbe River have changed storm surge issue in the Elbe estuary. Since 1996 high water level differences • HTHW between Cuxhaven and Hamburg have been attributed to a class of high surges with • H 0130 cm (FERK, 1999).

The German Hydrographic Service (formerly DHO now BSH) in Hamburg has been charged by a law mandated with the task to inform traffic in the German Bight on anticipated water levels. The empirical-statistical method used is applied in a more simple form for about 50 years.

For the computed surge a distinction is made between local effects (i.e. German Bight) and distant effects. The value of greatest influence is unquestionably the wind (surge approximately proportional to the square of the wind velocity; the greatest surge value is reached after a 3 h influence). Then follow the static atmospheric pressure (the effect is practically spontaneous), the change of atmospheric pressure with time (in case of rapid changes in the pressure free waves up to 1 m height are generated), water temperature and temperature difference air-water (the colder it is and the greater the difference, the stronger the wind effect). In the BSH a mathematical model is being developed covering the influences in their entirety in an overall approach.

Water level forecasts are broadcast twice a day and cover the entire German North Sea coast (Fig. 7.50). Neither the tidal curves nor the times of the onset of peak levels are determined by only rises in such levels (as a measure between anticipated HHW and precalculated astronomical HW). Meteorological details obtained from the German Weather Service.

Because of the uncertainty of the forecasts, water levels are indicated at 25 cm intervals up to a surge height of 1.2 m and thereafter at 50 cm intervals. In the case of a storm surge, the warnings are of use not only for navigation but also for agencies and administrative offices along the coast and tidal rivers.

In the case of anticipated high wind velocities, the BSH needs forecasts on the direction, speed and time of onset of the wind over the North Sea. On the basis of the method applied by the BSH forecasts of sufficient accuracy are possible only if, in addition, the forecast and occurrence of meteorological input data are accurate and external surges are recognized early enough off the English east coast. Only then the first 12 hour forecasts are usable, otherwise only later data are more accurate. But even then there is room for improvements since wind forecasts are made only roughly in units on the Beaufort scale.

Danish Southwest Coast

Although the land behind the Danish tidal flats south of Esbjerg (Fig. 7.54), as the northernmost part of the Dutch-German tidal flat, is only relatively sparsely populated, attempts have been made during the last few years to increase the safety of the population in addition to reinforcing the old dykes by applying storm tide forecasting procedures.

The procedure was developed following the statistical evaluation of water levels measured over six years and allows computation at any time of the tidal cycle of the water levels for the forthcoming 1, 2, and 3 h. Forecasts for a maximum period of 3 h are sufficient to find out in time when an endangered dyke might break at the earliest and then perhaps to evacuate the population concerned which takes at most 2 h.

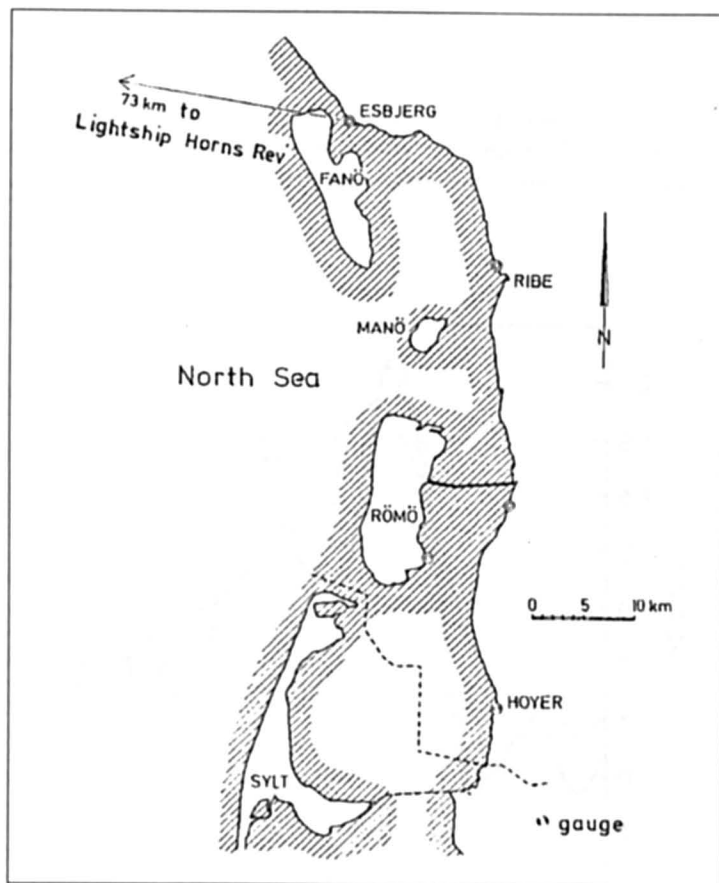


Fig. 7.54: Forecast area Danish Southwest coast

The programmed procedure has been in practice since 1970. It is based on hourly water level data from the Esbjerg and Hoyer gauges for which it was developed (Fig. 7.54) and on 3-hourly data of wind velocity, wind direction, and atmospheric pressure from a lightship off the coast. The 95 % confidence intervals are

- ± 20 cm for a forecast period of 1 h.
- ± 35 cm for a forecast period of 2 h.
- ± 45 cm for a forecast period of 3 h.

As during the storm surge of Jan. 03, 1976, the data flow was interrupted because the public telephone system was blocked, independent systems were rented in the meantime. Although the accuracy mentioned meets the requirements, it is planned to supplement the 3 h model in the next few years by a hydrodynamic 12 h model for the North Sea.

7.3.10 Modeling

North Sea

Following the 1953 disastrous storm surge, several numerical models for the North Sea and Thames Estuary were developed. Results from a linear model and a nonlinear model are compared with the observed surge at Southend of February 16–17, 1962, in Fig. 7.55.

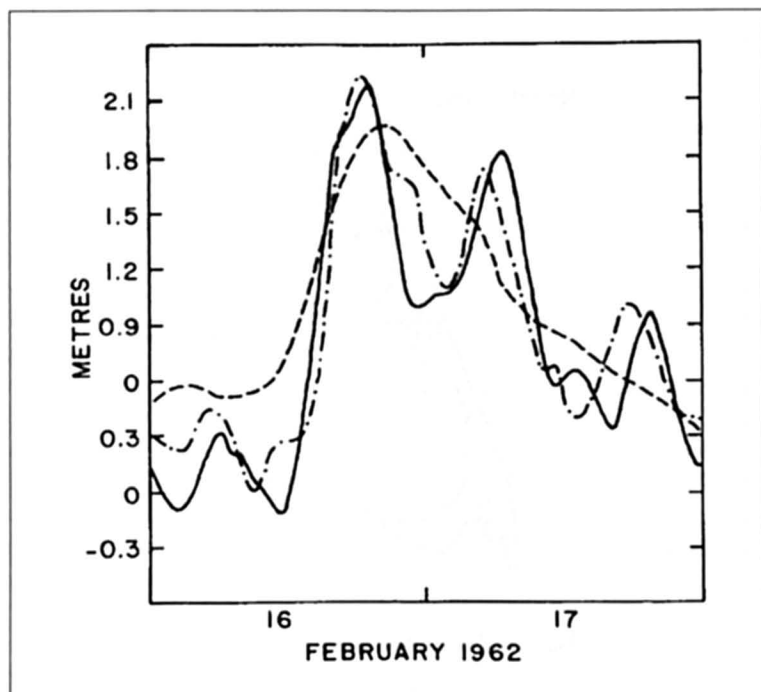


Fig. 7.55: Comparison of observed and computed surges at Southend, U.K., during February 16–17, 1962. Solid line, observed surge; broken line, computed surge using a linear model; dashed-dotted line, computed surge using a nonlinear model (ROSSITER, 1971)

Certain models have already been considered for the North Sea in different sections. ISHIGURO (1976a) showed through electronic analog models that atmospheric pressure gradient generated surges are important in the North Sea (Table 7.16). ISHIGURO (1976b) gave diagrams of estimated peak surges for different wind speeds. Contours of surge height for a wind speed of 36 m/s are illustrated in Fig. 7.56.

DAVIES and FLATHER (1977) computed the storm surge in the North Sea for the case of April 1–6, 1973, using several different numerical models. The features of these models are summarized in Table 7.17 and terms errors at various locations for these models are listed in Table 7.18.

Table 7.16: Comparison of the amplitudes of pressure gradient generated and wind stress generated surges in the North Sea. (ISHIGURO, 1976a)

Wind direction (degrees)	Wind duration (h)	Wind speed (m s^{-1})	Pressure-gradient ($\text{mb } 100 \text{ km}^{-1}$)	Pressure generated surge Y_p (cm)	Wind generated surge Y_w (cm)	Y_p / Y_w (%)
22	30	10	2.3	8	33	24
		20	4.5	16	130	12
		30	6.7	23	293	8
		40	9.0	32	520	6
112	10	10	2.3	10	15	67
		20	4.5	20	60	33
		30	6.4	30	135	22
		40	9.0	40	240	17

Table 7.17: Features of the different models for the North Sea used in the simulation of the storm surge of Apr. 1-6, 1973. (DAVIES and FLATHER, 1977)

Calculation	Model	Open boundary condition Surge input	Tidal input
a	Shelf	Radiation Hydrostatic	None
b	North Sea	Elevation specified Hydrostatic	None
c	Shelf	Radiation Hydrostatic	$M_2 + S_2$
d	North Sea	Elevation specified Hydrostatic	$M_2 + S_2$
e	North Sea	Elevation specified from calculation c + observations from Wick	$M_2 + S_2$

Table 7.18: Root-mean-square errors (cm) for calculations using models a to e (see Table 7.17) for the storm surge of Apr. 2-6, 1973. (DAVIES and FLATHER, 1977)

Port	a	b	c	d	e
Wick	18.1	12.6	13.5	12.6	0.0
Aberdeen	20.3	13.7	15.9	13.3	10.9
North Shields	22.5	17.7	17.0	16.6	16.3
Inner Dowsing	26.9	27.5	21.2	27.1	25.2
Immingham	26.6	25.6	19.5	20.8	18.2
Lowestoft	29.8	28.5	25.0	27.5	25.3
Walton-on-Naze	34.3	31.2	27.2	29.0	26.8
Southend	42.9	38.6	33.9	35.1	33.0
Ostende	36.1	34.0	25.1	30.3	26.7
IJmuiden	42.3	40.6	34.6	35.4	33.3
Terschelling	32.3	31.8	27.2	27.3	26.4
Cuxhaven	48.0	45.0	37.4	40.2	38.4
Esbjerg	32.6	29.0	23.3	24.11	21.2

PRANDLE and WOLF (1978a, 1978b) used parallel numerical models to study the modification of the tide due to surge and vice versa in the southern part of the North Sea. The tide and the surge before and after interaction for the case of October 19, 1970, are shown in Fig. 7.57. The interactions at Lowestoft and Southend for the event of January 31–February 1, 1953, are presented in Fig. 7.58 and 7.59, respectively. The contours of the interaction in the southern part of the North Sea are displayed in Fig. 7.60.

FLATHER (1980) summarized the status of a real-time storm surge prediction scheme for the North Sea. In this scheme, the meteorological forcing terms are obtained in real time as output of a 10-level primitive equation atmospheric model. In the storm surge model, a coarse model covers the whole of the Northwest European continental shelf. Models with finer resolution for the southern bight, eastern part of the English Channel, and the Thames Estuary are being developed. The contours of the surge at 03:00 GMT on January 12, 1978, are shown in Fig. 7.61.

VRIES et. al. (1995) compares 2D storm surge models applied to North Sea, Aegean and the Adriatic. They stated that the differences between the North Sea models are less than 10 cm, storm surges are underestimated by up to 50 cm, which indicates that improvement has to be found in the surface drag relations and not in the difference between the models. For the Mediterranean Sea the comparison shows differences of 35 cm with the observed level, which is due to the meteorological input inaccuracies.

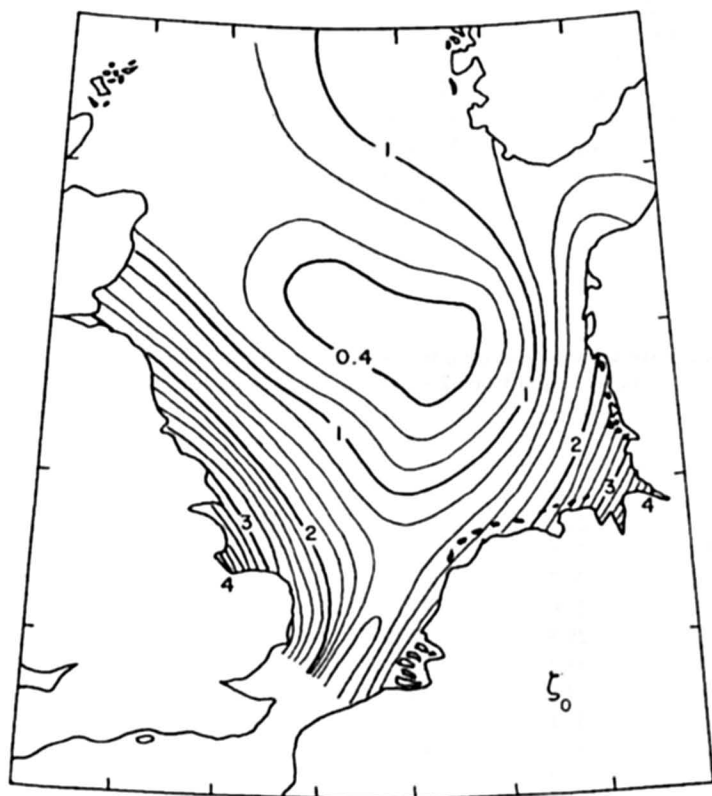


Fig. 7.56: Storm surge heights in the North Sea for a wind speed of 36 m·s⁻¹ blowing for 10 h. (ISHIGURO, 1976b)

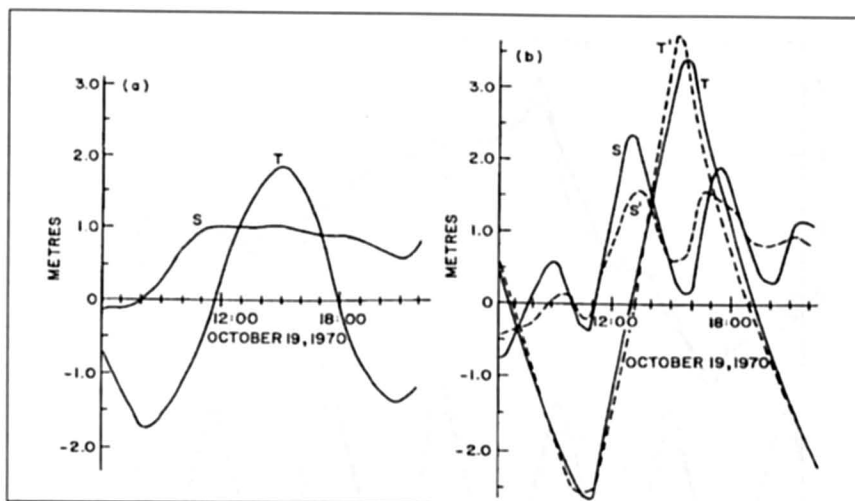


Fig. 7.57: Tide-surge interaction at (a) Walton-Margate (mouth of the model) and (b) Tower Pier. T, tide; S, surge; T', tide modified due to interaction with surge. S', surge modified due to interaction with tide. (PRANDLE and WOLF, 1978b)

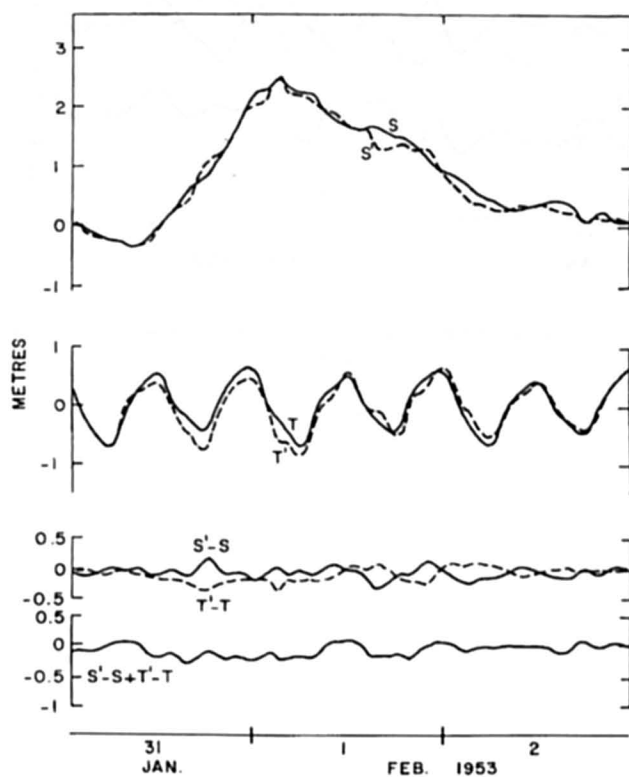


Fig. 7.58: Tide-surge interaction at Lowestoft, U.K. See Fig. 7.47 for explanation. (PRANDLE and WOLF, 1978b)

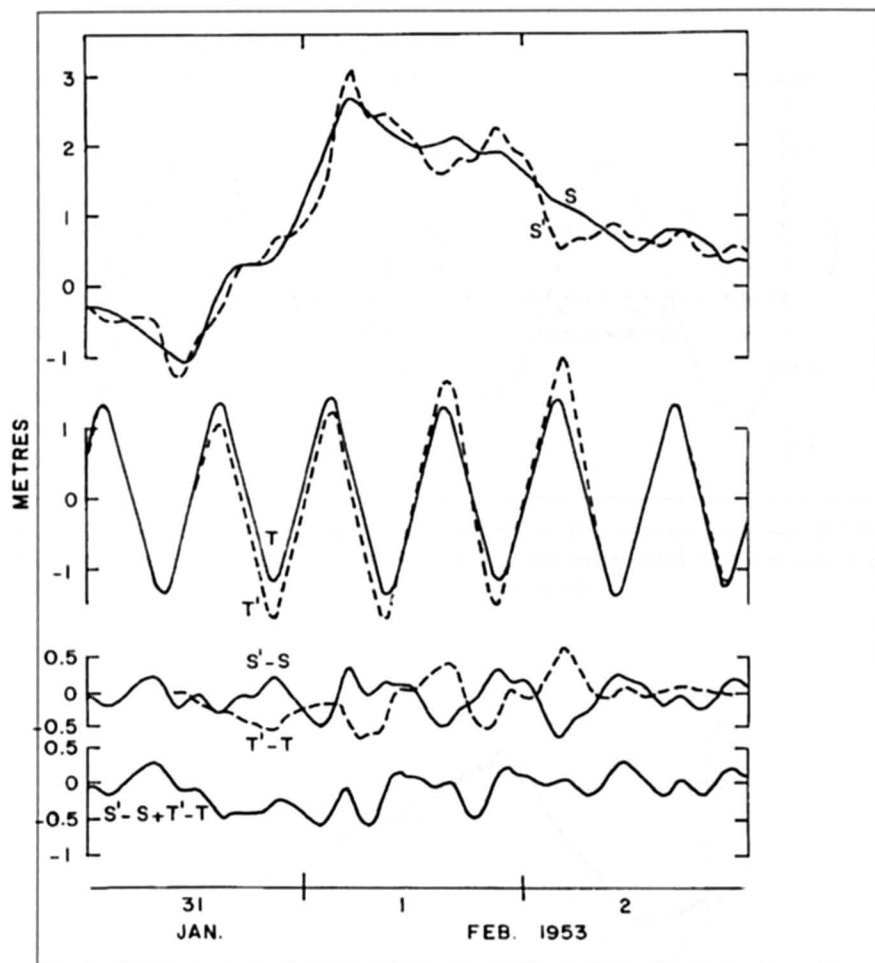


Fig. 7.59: Tide-surge interaction at Southend, U.K. See Fig. 7.57 for explanation.
(PRANDLE and WOLF, 1978b)

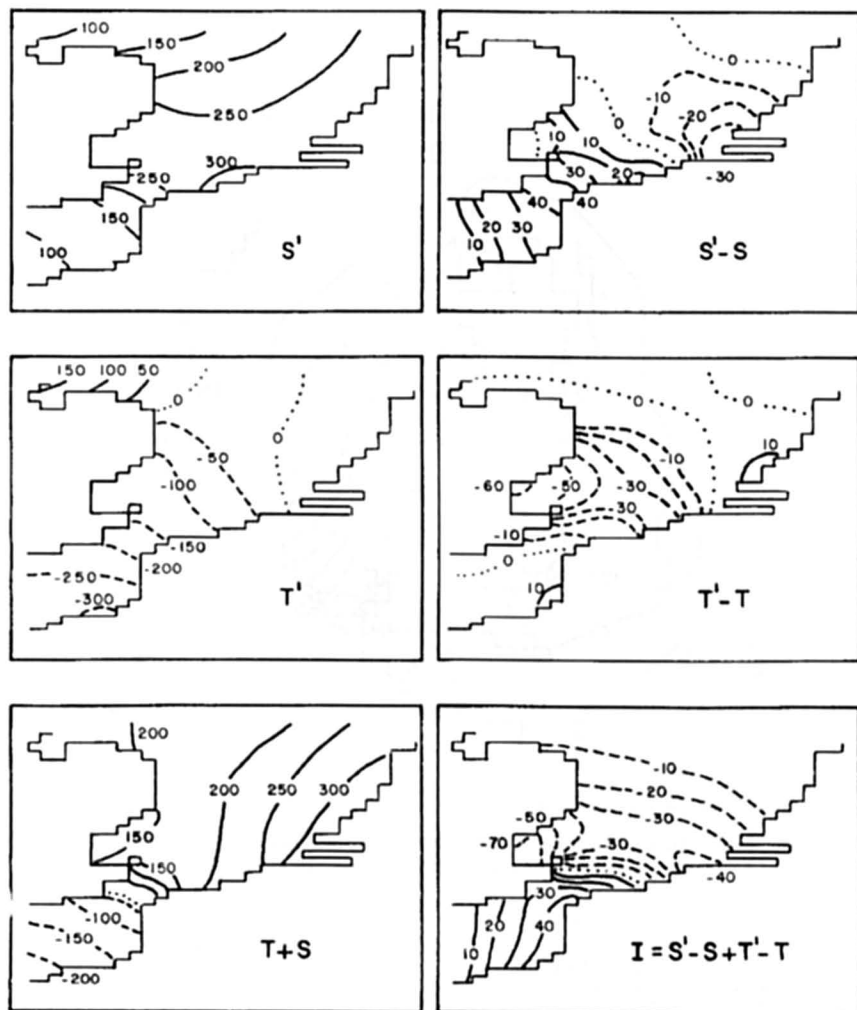


Fig. 7.60: Tide-surge interaction distribution (centimetres) in the southern part of the North Sea. (PRANDLE and WOLF, 1978b)

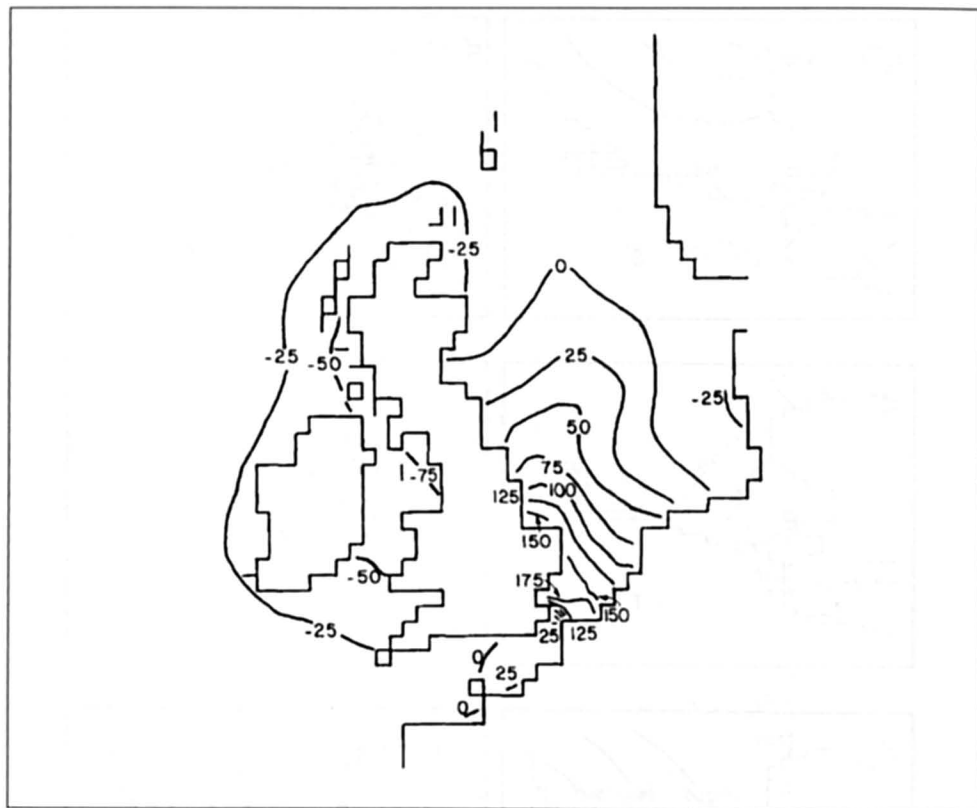


Fig. 7.61: Spatial distribution of surge elevation (centimetres) at 03:00 (GMT) on January 12, 1978, in the northwest continental shelf of Europe. (FLATHER, 1980)

A North Sea model

This chapter follows closely IHP-OHP 1987 and based on RODENHUIS et al. (1978), HAVNOE et al. (1983) and SIEFERT et al. (1987).

The emphasis in hydrographic conditions is often on waves. However, for several important problems, knowledge of currents is also essential. During the past, the technique of simulating currents and surface elevations in sea areas by computer has developed into an accepted engineering method. However, to obtain details of currents, the computations must be made on a high resolution grid. The model presented here permits the use of detailed resolution in selected areas, with the main circulation in the North Sea described on a much coarser grid. With the main grid established for the entire North Sea, the model can be focused on different local areas. Its generality makes refocusing simply a matter of providing the programme with the coordinates for the new local area and its bathymetry.

The model uses the full non-linear equations of nearly horizontal flow, which are solved by implicit, time-centred, finite difference scheme. The effects of wind stresses, Coriolis forces, and bed friction are included. Moreover, such nonlinear equations of shallow water and interaction between tide and storm surges. The System 21 has a high degree of accuracy. This has been demonstrated in practical applications e.g. RODENHUIS et al. (1978).

To provide details for resolving complicated areas, the change of resolution for the North Sea model is shown in Figs 7.62 and 7.63. The grid 1 with low resolution is named SD_0 ; the grid 2 of high resolution is named SD_1 ; and the higher resolution of nested grid 3 is named SD_2 – i. e., subdomains 0, 1, and 2, respectively. In low resolution 1 (SD_0), several grids of finer mesh size can be selected at higher resolution 2 (SD_1). The mesh size is one-third the original resolution 1. In a nested grid of high resolution 2 (SD_1), again several grids of finer mesh size can be selected at higher resolution 3 (SD_2). The reduction in mesh size relative to nested grid SD_1 is again onethird; relative to nested grid SD_0 it is one-ninth. For the North Sea model, this means a refinement from 10 nautical miles in resolution 1 to 1.1 nautical miles in resolution 3. There is no principal restriction for further reduction to higher resolution 4 or 5.

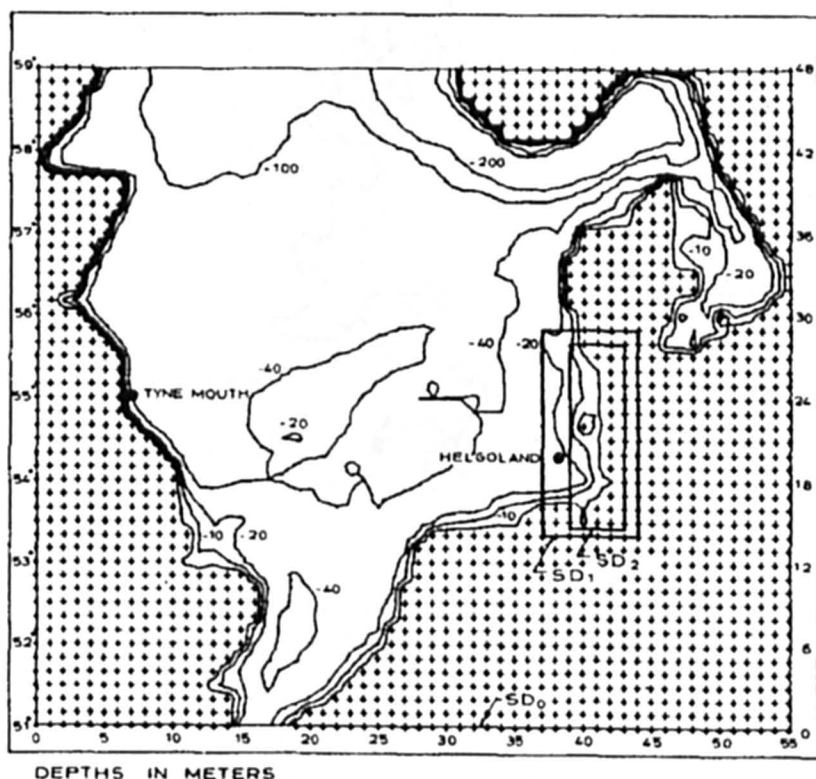


Fig. 7.62: North Sea model with main domain in Scale 1

SD_0 : Mesh size = 18 km, gridpoints: 2.640

SD_1 : Mesh size = 6 km, gridpoints: 945

SD_2 : Mesh size = 2 km, gridpoints: 4.428

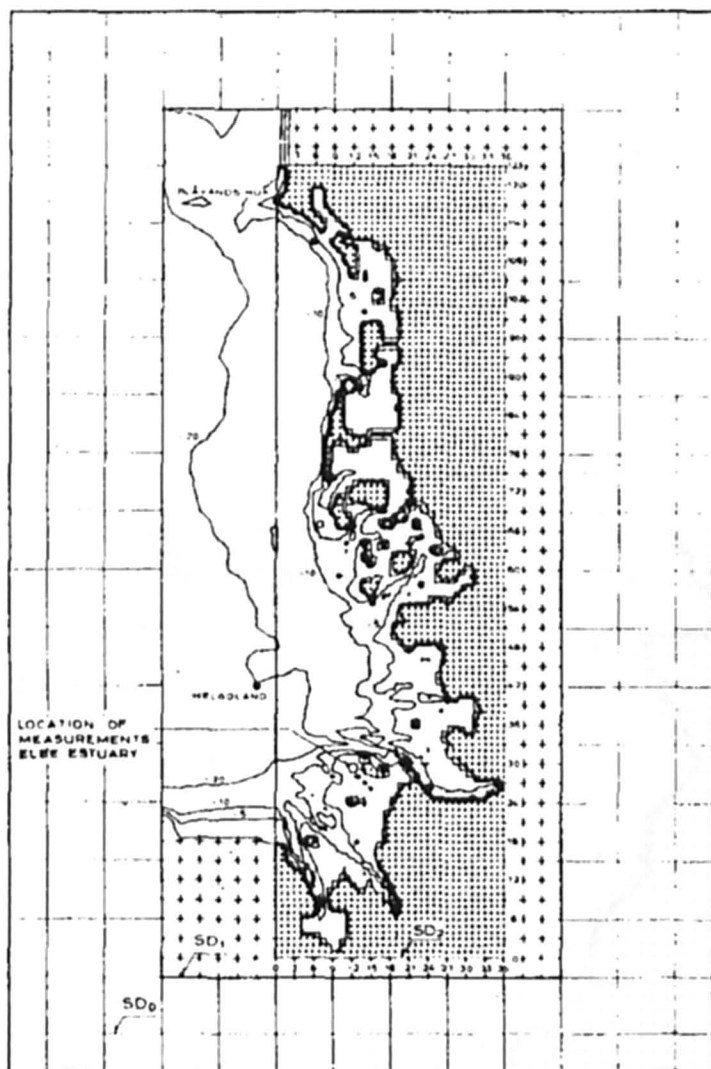


Fig. 7.63: North Sea model with subdomains in Scales 1 and 2

Computations are made simultaneously on all grids. When computing simultaneously, information also can travel from the fine grid to the coarse grid – the conditions in the fine grid can influence the results in the coarse grid.

The model was considered for a storm surge warning system for the Danish west coast and for intended computations of currents in connection with the hydraulic investigations and preliminary design of a gas pipeline that will be brought ashore on the west coast.

The model is set up as follows: The bathymetry of the entire North Sea from Stavanger to the Orkney Islands in the north and Dover-Calais in the south is described on an rectangular finite difference grid with a mesh size of 10 nautical miles. The Skagerak and the Kattegat also are included. The bathymetry off the Danish west coast is described on the finest grid with a mesh size of 2 km. This grid permits detailed representation of this area (Fig. 7.63).

The main grid has to be set up only once, while the fine grid can be refocused on different areas of interest. The only dynamic entry data required are water-level variations along the open boundaries between Stavanger and the Orkney Islands, and between Dover and Calais and the time variation of the atmospheric pressure distribution for the area. The boundary data is computed from tidal constants, in fact, as a tidal prediction for each grid point along the open boundary.

The changing meteorological conditions are represented in the hydrodynamic equations by barometric pressure gradients and wind-stress terms. Meteorological observations are available with 3-hour intervals. The isobar map is based, however, mostly on observations on land, and only a few ship observations are available.

In the model, the atmospheric pressure at sea level is specified every 3 hours in each grid point with a mesh size of 60 nautical miles, with the same boundaries as the main hydrodynamical grid. The actual wind speed is calculated from the geostrophic wind speed.

The square root formula is based on measurements in the German Bight. Coefficients depend on the vertical stability (expressed by the air-sea temperature difference), here corresponding to a neutrally stable atmosphere. The wind direction is found by assuming a cross-isobar angle of 15° . Using interpolation of the wind components in space and time, a wind vector is calculated in each grid point in the main grid and subgrids at each time step.

Calibration of the finest grid off the Danish coast is incomplete, but the accuracy of the model's representation in the finest grid (Scale 3) may be illustrated with results from a similar run for the Elbe Estuary. In Fig. 7.64, the computed and recorded tidal variations at a point 15 nautical miles northwest of Cuxhaven are compared. The location is indicated in Fig. 7.63.

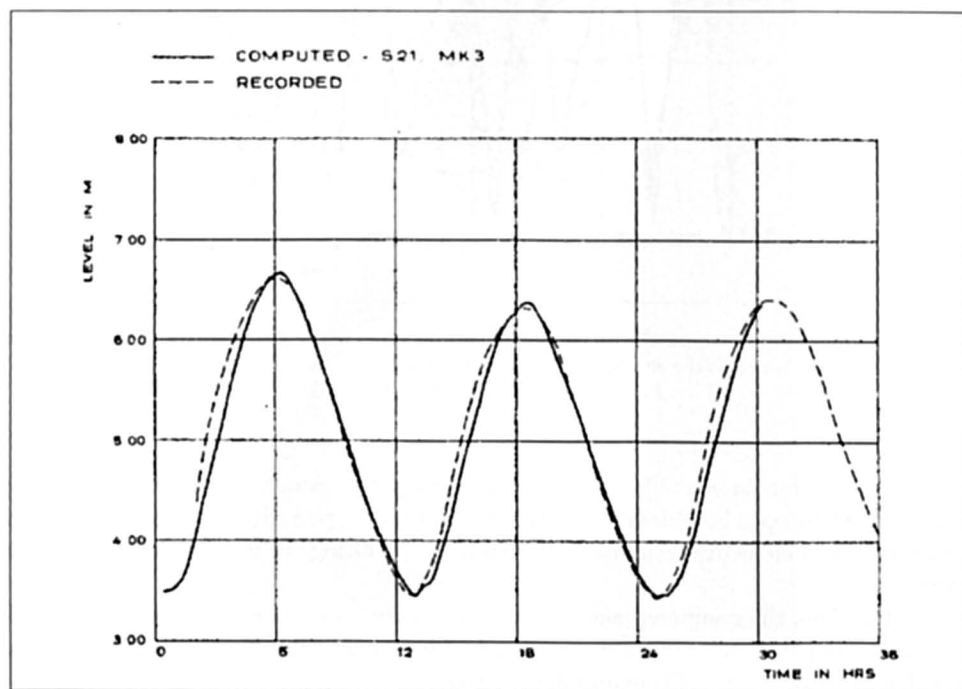


Fig. 7.64: Comparison between recorded and computed tide in Elbe Estuary with subdomain in Scale 3; data source is the Research Group for the Harbour Extension Neuwerk, Hamburg

Note: Location indicated in Fig. 7.63

Again, the computed values agree with the recorded values accurately. Current recordings were made at this location. The computed and recorded currents are compared in Fig. 7.65. The computed current is a depth-averaged current, whereas the recording is at 0.7 m above the seabed in 8 m water. When the velocity profile, U_z over the vertical is expressed as

$$U_z = K \times Z^{1/n}$$

with $n = 5$ or 6 , and K some constant, (7.6) a formulation tested in several areas in the North Sea, the relation between mean current, U , and $U_{0.7}$ is

$$U_{0.7} = 0.8 U \quad (8.3)$$

As shown in Fig. 7.65 this fits accurately for the computed U and recorded $U_{0.7}$.

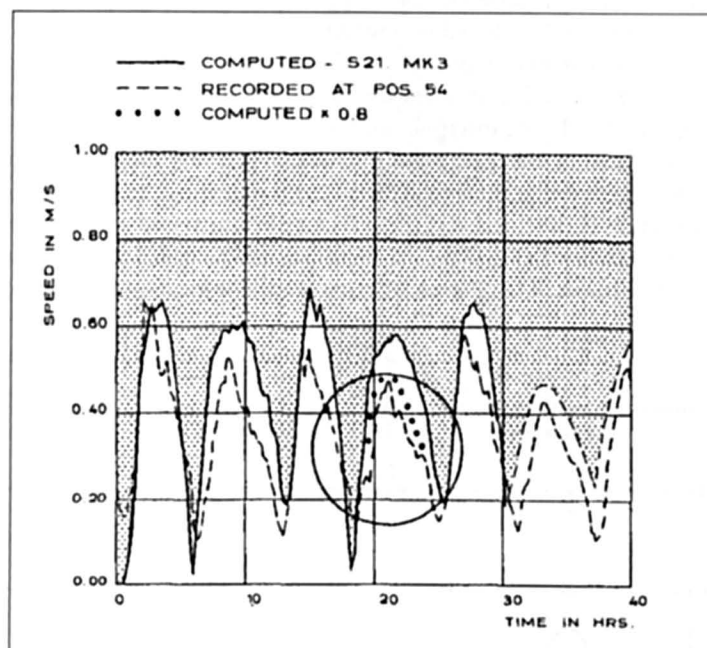


Fig. 7.65: Comparison of recorded with computed current speed in the Elbe Estuary with sub domain in Scale 3; data source is the Research Group for the Harbour Extension 'Neuwerk', Hamburg
Note: Location indicated in Fig. 7.63

The effect of the storm of Jan. 2-3, 1976, was computed, using the storm field previously described. At the open boundaries, the predicted tide for the period and a pressure surge that results as an instantaneous response of the sea level to a change in atmospheric pressure are given.

In Fig. 7.66, the computed and recorded water-level variations at Helgoland for this period are compared. Note that a storm surge builds up gradually over the initial tidal variation. The error is less than 20 cm on a 3.5 m surge.

Fig. 7.67 illustrates the model's ability to resolve the storm surge inside the bays along the Danish west coast: An instantaneous picture of the sea surface in the form of isolines is compared with recordings at two stations at that moment.

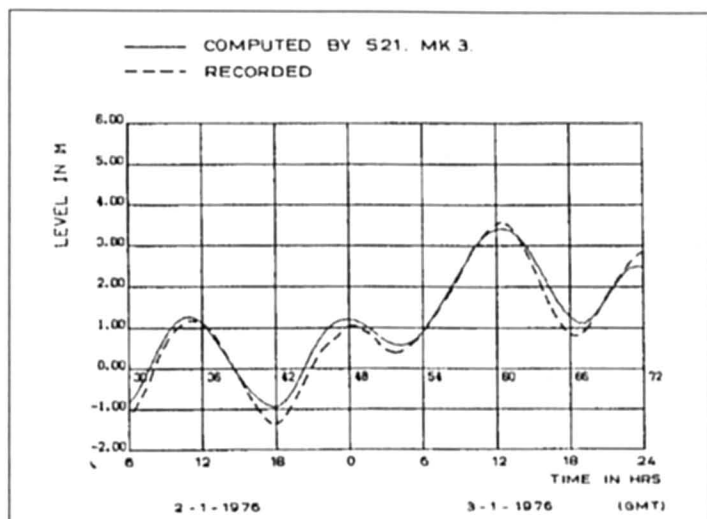


Fig. 7.66: Comparison of recorded with computed storm surge of Jan. 2-3, 1976, at Helgoland with sub domain in Scale 2



Fig. 7.67: Computed water levels inside a bay on the Danish west coast compared with recordings at two stations on March 1, 1976, 15:00 hours GMT

North Sea and Baltic Sea Model

The Federal Maritime and Hydrographic Agency (BSH) developed an operational model system to calculate currents, water level and dispersion processes. Operational model means that the model produces results daily. The description follows closely a paper of the BSH (1992). The model is a predictive one and is based on forecasts of wind and air pressure supplied by the German Weather Service in Offenbach. Tide prediction, current and water levels are computed nightly for periods up to 36 hours.

The water levels are calculated daily using three nested and interactively coupled grid nets. Towards the German Bight the grid resolution increases. Therefore the interaction between the variable coastline (wadden areas, sand banks and island chains) and offshore areas can be represented. Grid spacing near coastal areas in the German Bight and the western Baltic Sea is 1.8 km; in areas further offshore, it is 10 km while elsewhere in the North Sea and Baltic Sea it is 20 km.

In a three dimensional model the following forcing functions were included: wind, air pressure over North and Baltic Seas, tides, external surge and water discharge from large rivers. The model is a valuable tool for the water level and storm surge warning service at the BSH. It is mainly validated by regular comparison between modelled and measured water levels. In addition the model is occasionally checked using measured currents and drift experiments at sea (BSH, 1992).

Baltic Sea

Earlier the one-dimensional model of SVANSSON and SZARON (1975) for the Baltic Sea was discussed. Observed and computed surges at several locations for the storm surge event of August 15, 1964, are compared in Fig. 7.68.

HENNING (1962) numerically simulated the surge of January 3-4, 1954, in the Baltic Sea. This surge caused maximum elevations of 1.7 m in the western part of the Baltic Sea. The surface weather chart at 06:00 GMT on January 5, 1954, is given in Fig. 7.69. The distributions of the surge heights at two different times are shown in Fig. 7.70 and 7.71. Observed and computed surges at five locations are compared in Fig. 7.72. Some relevant data on this surge are given in Table 7.19.

WROBLEWSKI (1978) used stochastic techniques to simulate the following surges at Nowyport (at the Polish coast of the Baltic Sea): January 17, 1955, February 15, 1962, February 18, 1962, and February 21, 1962. DEMEL (1934) studied the surges of 1930 and 1931 at the Baltic coast of Poland.

KLEVANNY (1994) modeled long wave oscillation in the Baltic Sea. He used wind data from a set of meteorological stations along the Baltic Sea and big Islands. The storm surges of December 30-31, 1975 and February 17-23, 1990 are the basis to compare observed data with surface level oscillations obtained from modelling.

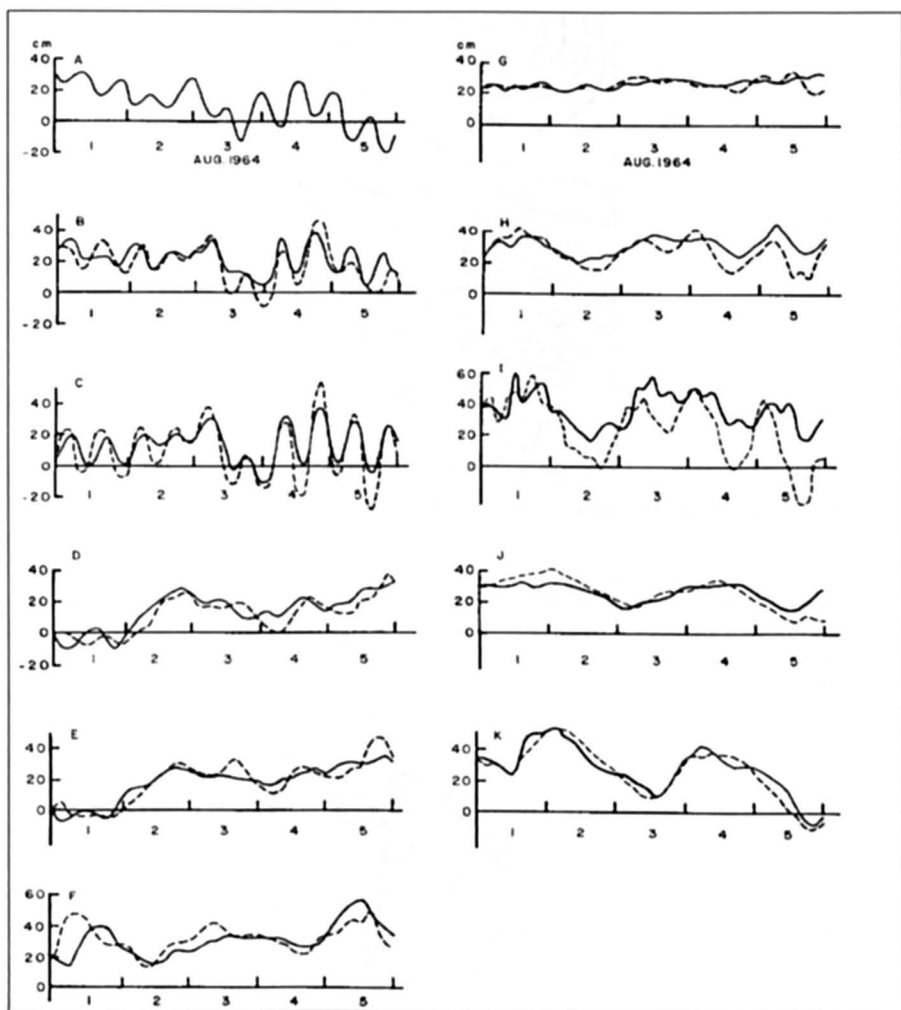


Fig. 7.68: Observed (solid line) and computed (broken line) storm surges at various locations along the Baltic Sea (SVANSSON and SZARON, 1975)

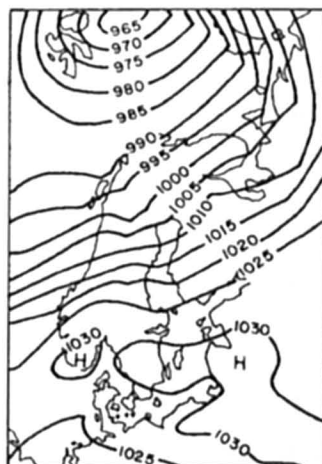


Fig. 7.69: Simplified surface weather chart at 06:00 (GMT) on January 5, 1954, for the Baltic Sea area (HENNING, 1962)

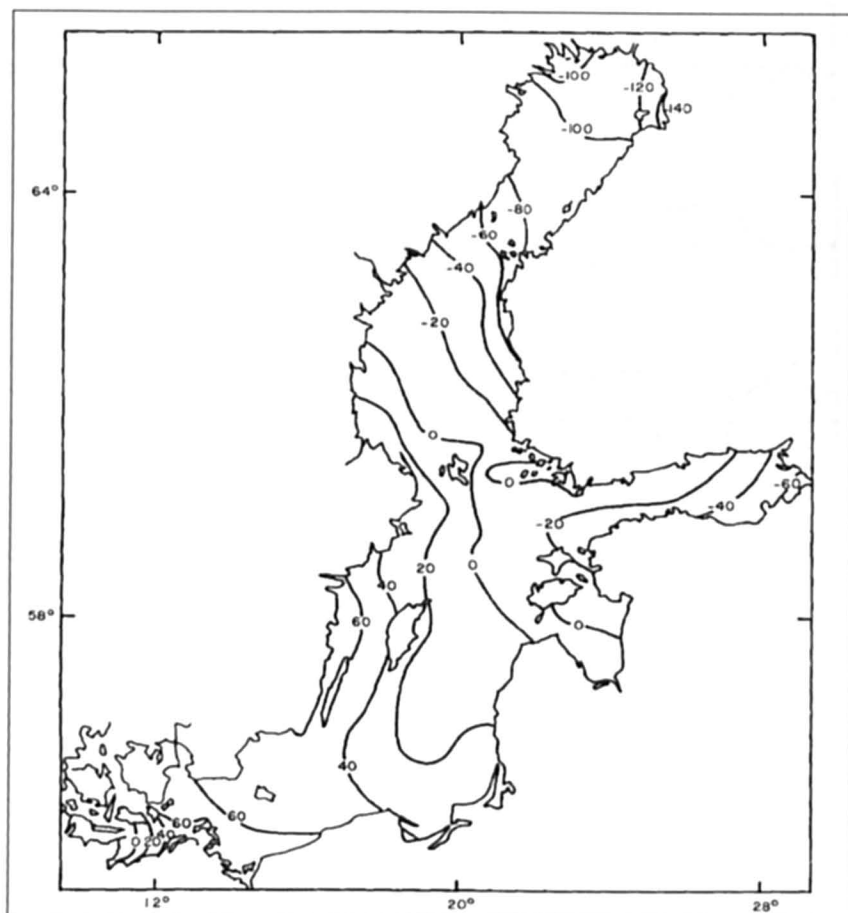


Fig. 7.70: Distribution of storm surge amplitudes (centimeters) in the Baltic Sea at 20:00 (GMT) on January 3, 1954 (HENNING, 1962)

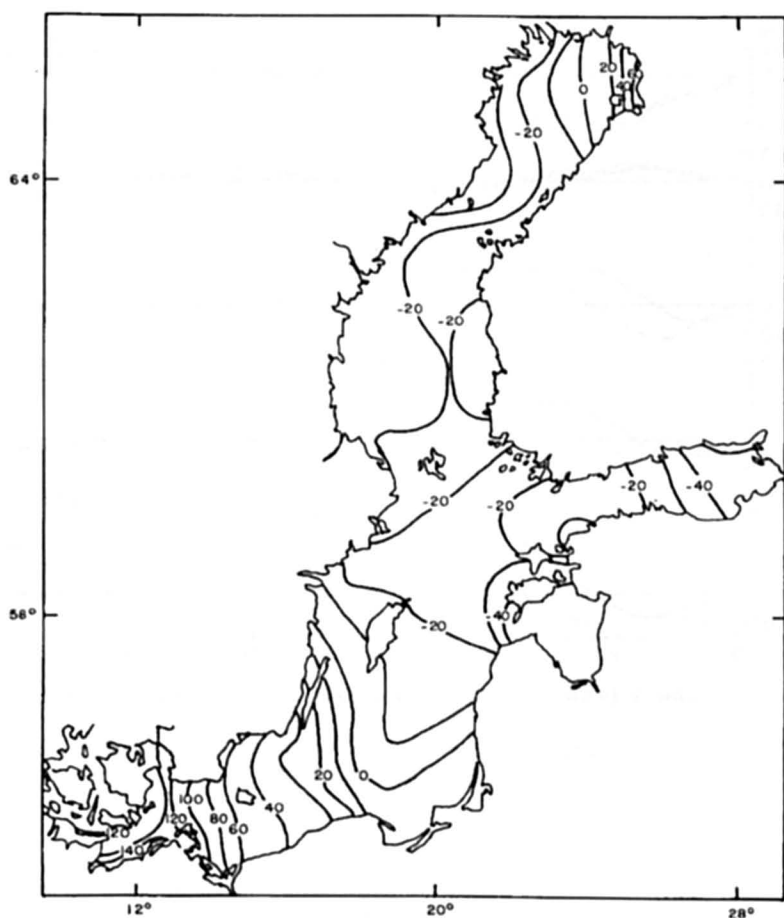


Fig. 7.71: Distribution of storm surge amplitudes (centimeters) in the Baltic Sea at 14:00 (GMT) on January 4, 1954 (HENNING, 1962)

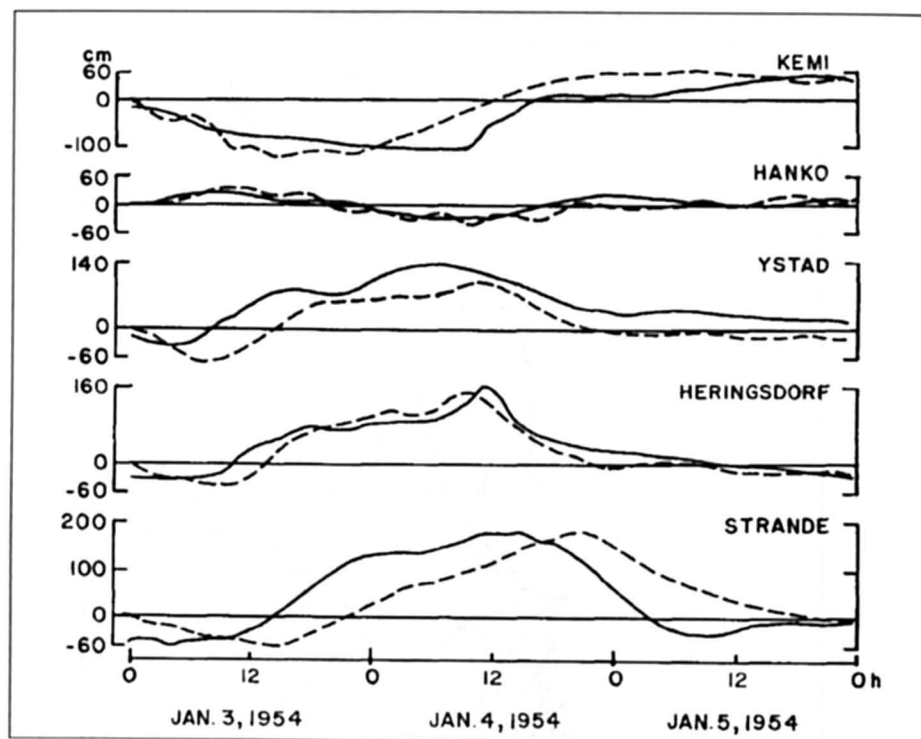


Fig. 7.72: Observed (solid line) and computed (broken line) storm surges in the Baltic Sea during January 3-5, 1954 (HENNING, 1962)

Table 7.19. Comparison between observed and computed storm surges in the Baltic Sea for the event of Jan. 3-4, 1954 (HENNING, 1962)

Water level Gauge	Time of maximum elevation (observed)		Surge (cm)	
	Day	Time (GMT)	Observed	Computed
Degerby	3	8:00	47	52
Landsort	4	0:00	51	77
Kungholmsfort	4	8:00	100	105
Ystad	4	5:00	171	164
Heringsdorf	4	11:00	195	197
Sallnitz	4	11:00	183	171
Kap Arkona	4	10:00	187	193
Daffier Ort	4	12:00	190	195
Warnetminde	4	13:00	224	192
Wismar	4	14:00	291	192
Travernfinde	4	15:00	283	192
Gedser	4	12:00	231	186
Langballigau	4	12:00	236	262
Strande	4	15:00	239	236

7.4 Asia

RABINOVICH and SOKOLOVA (1992) produced a catalogue of storm surges for the Russian coast of the Sea of Japan.

Fig. 7.73 shows the locations of the eleven tide gauges whose data have been used to produce this catalogue. Actually out of the eleven stations, Krilyon is located in the Okhotsk Sea, but close to the Boundary with the Sea of Japan and is influenced by surges from the Sea of Japan.

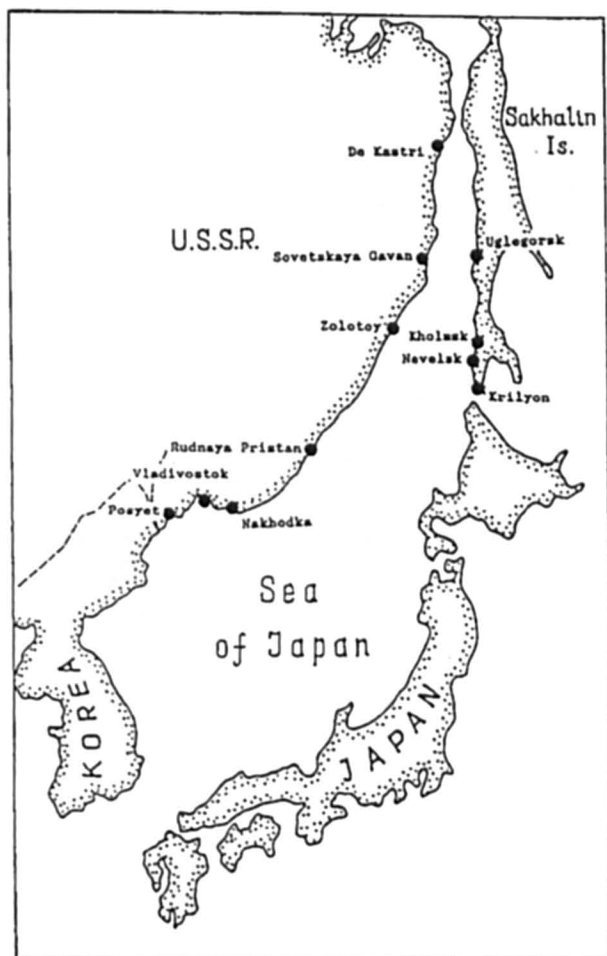


Fig. 7.73: Tide gauge positions (RABINOVICH and SOKOLOVA, 1992)

The residual series (after subtracting predicted tides) $\zeta(t)$, where t is the time, were used to analyse surges. Some simple parameters were chosen to describe each one (Fig. 7.3.2): the maximal height of storm surge h_s , estimated from mean monthly level Z_m , and of storm surge plus tide, h_{st} ; the corresponding moments t_s , t_{st} ; duration of surge T_s and of its half-height $T_{s/2}$; surge steepness $\delta = h_s / T_{s/2}$; the variance

$$D = \sigma^2 = \frac{1}{T_s} \sum_{t=t_b}^{t=t_e} [\zeta(t) - Z_m]^2 \quad (7.8)$$

where, t_b is the time of the beginning and t_e is the end time of the surge; it is supposed that in both moments $\zeta(t_b) = \zeta(t_e) = Z_m$.

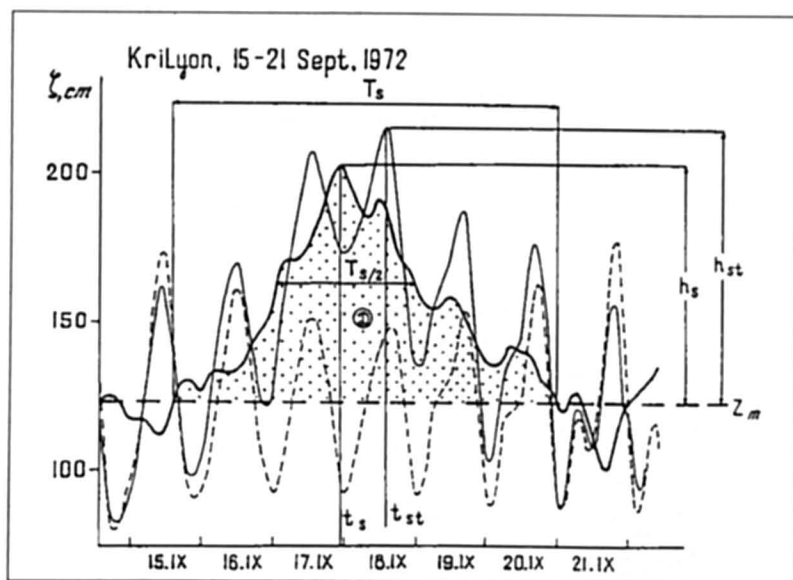


Fig. 7.74: The main parameters of storm surge (RABINOVICH and SOKOLAVA, 1992)

The algorithm of automatic detection of storm surges and calculation of corresponding parameters was used to analyse several years of data. Only the sea-level displacements with $h_s > Z_{cr} = 25$ cm were examined. A number was given to every surge, which had a height $h_s \geq 45$ cm at least at one of the 11 stations mentioned above. This numbering system is similar to that used for typhoons: the first two numbers represent year, the other two are sequential numbers (e.g., 7803, 7911, 8001, etc.) As an example, these parameters for the strongest surges at Nevelsk for 1979–91 are presented in Table 7.20.

Table 7.20: An example of catalogue parameters of several storm surges at Nevelsk (RABINOVICH and SOKOLOVA, 1992)

Station	Year	Number	t_s (day, month, hour)	h_s (cm)	h_{st} (cm) (+t,hr)	T_s (hr)	$T_{s/2}$ (hr)	δ (cm/hr)	D (cm ²)
Nevelsk	1979	7901	11.02.17	48.4	84(+2)	49	15	3.22	—
Nevelsk	1979	7902	9.04.18	43.3	85(0)	78	32	1.35	689
Nevelsk	1979	7904	19.08.08	43.7	104(0)	76	43	1.02	408
Nevelsk	1979	7905	20.12.23	48.3	103(-3)	53	28	1.73	858
Nevelsk	1980	8007	13.12.14	36.2	95(0)	75	67	0.69	447
Nevelsk	1981	8101	24.08.06	49.2	115(0)	71	24	2.05	465
Nevelsk	1981	8102	24.10.04	62.6	123(0)	70	43	1.46	1177

It is interesting to compare the parameters of the same surge for different stations to better understand the peculiarities of surge formation. For example, the surge occurring during 20–22 October 1976 was not noticed at the southern mainland stations Posyet, Vladivostok, and Nakhodka ($h_s < 25$ cm), but was relatively strong on the southwestern coast of Sakhalin Island (Table 7.21).

Table 7.21: The storm surges of October 1976 at different coastal stations. t = time relative to t_s of surge's maximum (RABINOVICH and SOKOLOVA, 1992)

Stations	t_s (day, month, hour)	h_s (cm)	h_{st} (cm) (+t,hr)	T_s (hr)	$T_{s/2}$ (hr)	δ (cm/hr)	D (cm ²)
Krilyon	21.10.00	38.9	57(+3)	23	10	3.9	619
Nevelsk	21.10.17	61.5	63(0)	51	24	2.6	1190
Kholmsk	21.10.16	47.2	50(+2)	46	25	1.9	924
Uglegorsk	21.10.12	49.5	73(-3)	51	27	1.8	880
De-Kastri	21.10.01	34.7	89(-3)	51	7	4.9	267

The processing of tide gauge data makes it possible to obtain statistics of the surges, to estimate their seasonal distribution, and to find the most interesting (dangerous) cases. For these cases at least, but preferably for all, it is useful to define the parameters of the atmospheric processes which forced these surges. The following parameters were fixed at the moment of surge maxima (Fig. 7.75) the atmospheric pressure in the centre of the cyclone P_{os} ; its velocity V_s and direction α_s ; the position of the center relative to the station r_s , θ_s ; the pressure P_s and in wind W_s , ϕ_s at the station. The parameters for the surge of 20–22 October 1976 are presented in Table 7.22. The cross correlation analysis of the parameters from the first (sea level) and second (meteorological) groups for the number of storm surges may be an effective instrument to look for empirical relations which may be used for a surge forecast.

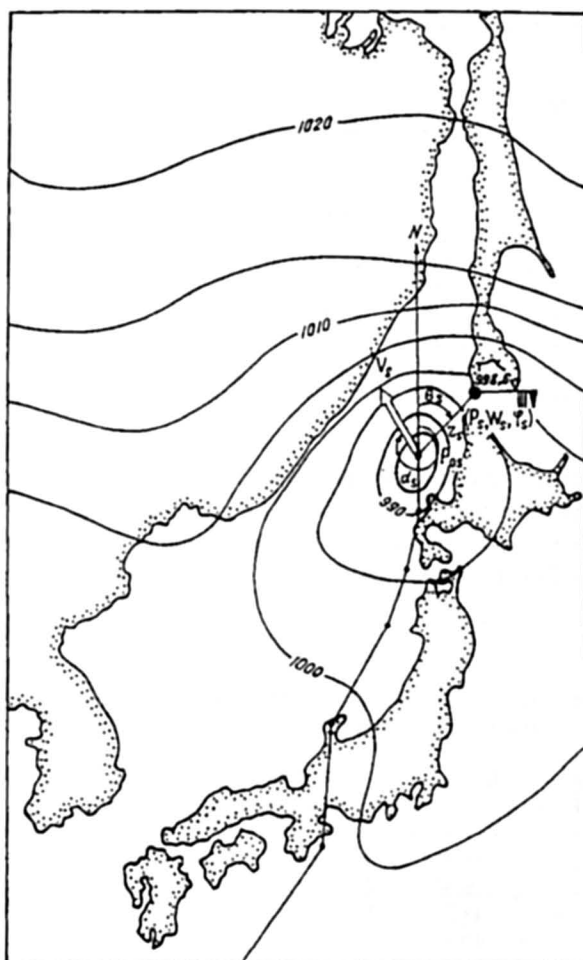


Fig. 7.75: Meteorological parameters of the atmospheric disturbance caused by a storm surge at the Krilyon station (RABINOVICH and SOKOLAVA, 1992)

It is possible also to describe storm surges using regression formulae:

$$\zeta(t) = a_0 + a_1 \cdot P(t) + a_2 \cdot \tau_z(t) + a_3 \cdot \tau_n(t) \quad (7.9a)$$

where, a_i are regression coefficients; $P(t) = P_a(t) - 1000$; $P_a(t)$ is the atmospheric pressure at the station in millibars; $\tau_z(t) = -0.025 \cdot W^2(t) \cdot \sin(\phi(t))$ and $\tau_n(t) = -0.025 \cdot W^2(t) \cdot \cos(\phi(t))$ are zonal and meridional components of wind stress; $W(t)$ and $\phi(t)$ are wind speed and direction at the station. In this case, four coefficients characterize every storm surge. The regression formulae in the form of eq. (7.9a) for the surge of 20–22 October 1976 are given in Table 7.22.

Table 7.22: The main cyclone and meteorological parameters at the maximum of the surge of October 1976 (RABINOVICH and SOKOLOVA, 1992)

Stations	P_{os} (mb)	V_s (km/h)	α_s (deg)	θ_s (km)	r_s (mb)	P_s (mb)	W_s (m/s)	ϕ_s (deg)	Regression Formulae
Krilyon	980	67	30	60	12	980.7	14	135	$\zeta(t) = 12.16 - 0.87P(0) - 14.34\tau_z(0) + 2.30\tau_n(0)$
Nevelsk	965	41	340	210	726	991.7	19	273	$\zeta(t) = 5.70 - 1.64P(0) + 18.50\tau_z(0) + 5.22\tau_n(0)$
Kholmsk	965	41	340	210	670	991.0	21	263	$\zeta(t) = -8.34 - 2.14P(0) + 14.55\tau_z(0) + 1.30\tau_n(0)$
Ulegorsk	965	52	340	225	326	983.8	21	269	$\zeta(t) = -0.76 - 1.66P(0) + 17.50\tau_z(0) + 10.0\tau_n(0)$
De-Kastri	965	79	340	0	780	985.6	7	199	$\zeta(t) = 13.50 - 0.41P(0) - 13.48\tau_z(0) - 6.10\tau_n(0)$

For a better description of individual storm surges, more precise regression formulae may be used:

$$\zeta(t) = a_0 + a_1 \cdot P(t - \Delta t_1) + a_2 \cdot \tau_z(t - \Delta t_2) + a_3 \cdot \tau_n(t - \Delta t_3) \quad (7.9b)$$

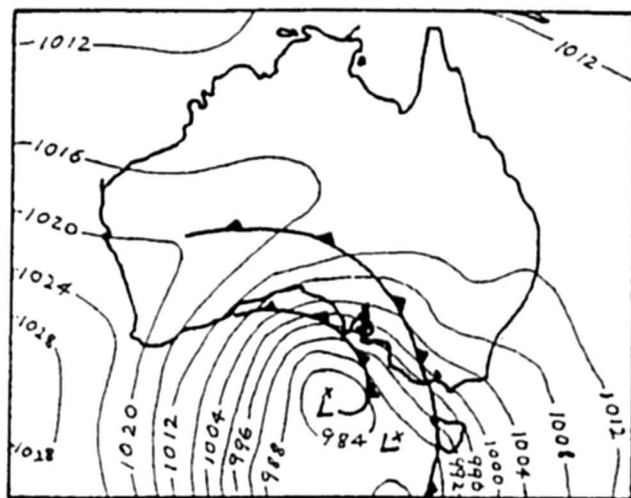
where, Δt_i are the corresponding time lags. Three additional parameters are necessary to determine the surge.

7.5 Australia

Storm surges on the south coast of Australia occur due to extra tropical cyclones (ETC's). According to VECCHIO (1980) storm surges at Adelaide comprise of a locally generated surge due to the interaction of wind stress with local topography and an external effect arising from the passage of winter depressions across the Great Australian Bight. He cautions that the effects may not be totally independent.

For the positive surge, the local effect contributes about 0.75 m and the external effect adds about another 0.5 m. The 0.75 m of the locally generated surge is made up of about 0.25 m due to the decrease of atmospheric pressure and 0.5 m due to the wind stress.

Between 1948 and 1977, there were 12 surge events in Adelaide. Strong northwest winds prevailing for periods of 24 hours or longer, and associated with deep lows over ocean waters, south of the bight, can generate positive surges up to one meter in amplitude. Along the Adelaide foreshore, the most destructive storm surge of this type occurs when the wind direction rapidly shifts from the northwest to a squally southwesterly, the change in wind direction occurring near the time of maximum tide height. Figs. 7.76 and 7.77 respectively show typical synoptic situations for NW and SE winds at Adelaide.



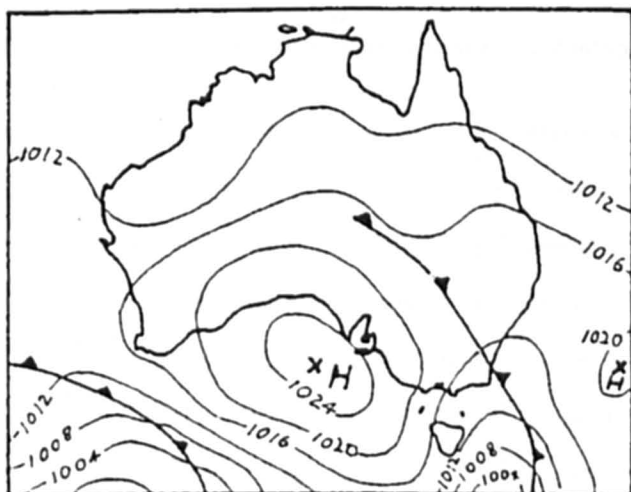
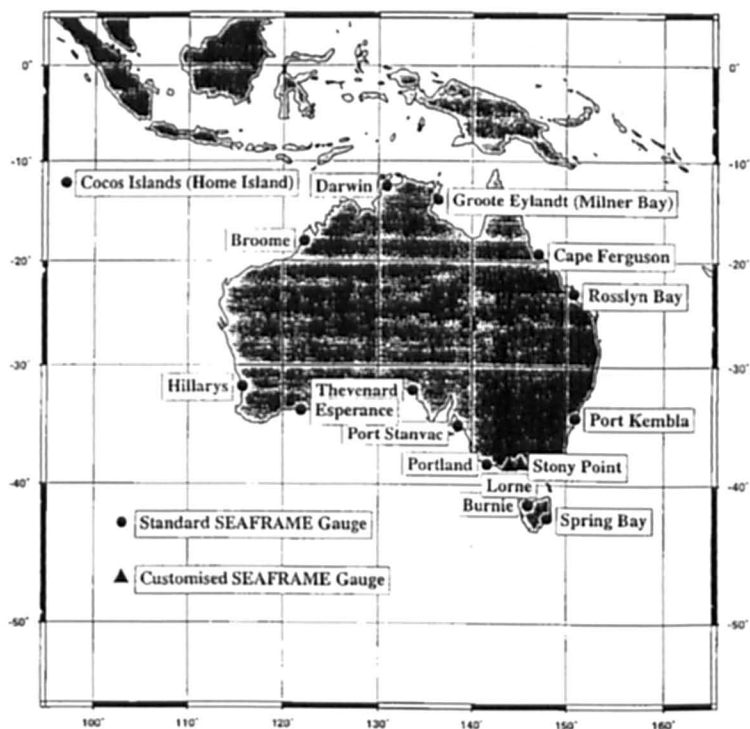


Fig. 7.77: Synoptic chart SE winds at Adelaide (VECCHIO, 1980)

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Fig. 7.78: Tide gauge positions (MURTY, 1995)

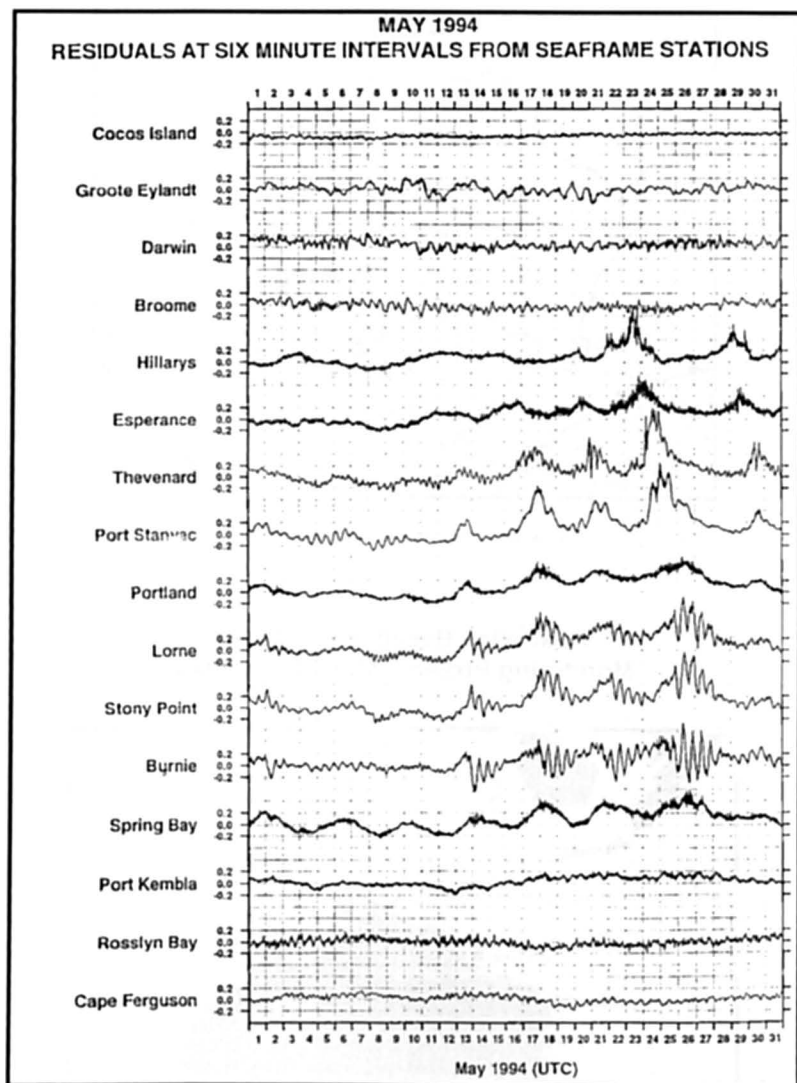


Fig. 7.79: Residuals at six minute intervals from SEAFRAME stations (m) May 1994 (MURTY, 1995)

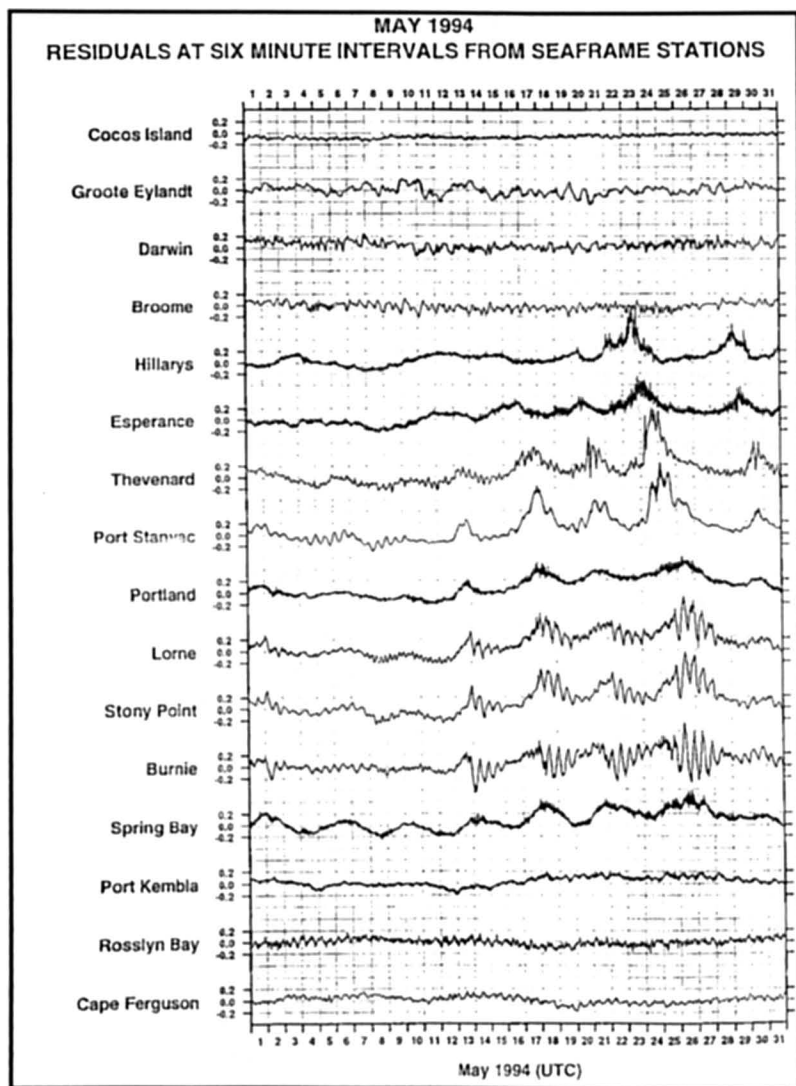


Fig. 7.80: Residuals at six minute intervals from SEAFRAME stations (m) November 1994 (MURTY, 1995)

7.6 Oceanic Regions

Some oceanic islands are influenced by a type of weather system known as sub-tropical cyclones, which are similar to tropical cyclones in terms of having a warm core, but otherwise resemble extra-tropical cyclones (HASTENRATH, 1996). SIMPSON (1952) coined the word "sub-tropical cyclone" which was further elaborated by RAMAGE (1971). The subtropical cyclones of the eastern north Pacific during the winter to spring of the Northern Hemisphere are referred to as Kona storms in the Hawaiian Islands. These originate from cut-off lows in the upper level subtropical westerlies.

According to HASTENRATH (1996) the centre of the system is between 400 to 600 hPa (mid-troposphere) and the pressure gradients, winds and convergence increase from the periphery inward. Strong mid-tropospheric convergence is compensated by divergence in the upper troposphere and to a lesser extent in the lower layers. RAMAGE (1971) proposed a conceptual model, which includes an upward and a downward branch within about 500 km from the centre, strong upward motion gives rise to condensation and deep precipitating clouds. Beyond about 500 km from the centre, there is downward motion with dry adiabatic warming extending to the subsidence inversion (HASTENRATH, 1996).

The relatively warm-cored upper branch is energy producing, while kinetic energy dissipation within a weak surface circulation is small, thus favouring the longevity of the system. Development of an eye similar to tropical systems is common. These subtropical cyclones also occur to the southwest of Azores in the Atlantic Ocean.

Over the northern Indian Ocean, a somewhat different type of a subtropical cyclone can occur. These occur during the southwest monsoon (one to two per month) over the north-western part of the Arabian Sea and occasionally over the northern part of Bay of Bengal and over southern Indochina. According to RAMAGE (1971) the energy exported from the heat low over the South Asian continent is responsible for the origin of these subtropical cyclones. In contrast to the winter subtropical cyclones of the Northern Pacific, those in the monsoon area do dissipate due to the injection of drier air.

It is well known that tropical cyclones get transformed into extratropical cyclones. This extratropical transition (ET) is complex and highly variable process that is currently poorly understood (MALMQUIST, 1999). According to him, the occurrence of ET's also portends the possibility that a single storm system can impact the tropics, midlatitudes and high latitudes. For example, an Atlantic system might track across the Caribbean and the southern part of the U.S.A. as a tropical cyclone and can change to an extratropical cyclone that can strike the New England, States of U.S.A., Canada and Europe. Some new concepts are (1) Maximum Potential Intensity (MPI) of an ET (2) Maximum Potential Extratropical Transition (MPET). These new concepts could be used to produce real time Damage Potential (DP) maps.

8. Impact of Climate Change and Sea Level Rise on Storm Surges

The ideas of Global Change and the Greenhouse Effect are usually interpreted narrowly, in the sense of anthropogenic causes of warming of the earth and climatic change. In reality, the predicted warming of the earth is due to the Greenhouse Effect. However, this is not exclusively a phenomenon of the present, in particular the time since the Industrial Revolution, but, rather, a natural response of the earth and its atmosphere to solar radiation.

The natural Greenhouse gases ensure that the climate remains pretty much constant and that an average temperature between $+15^{\circ}\text{C}$ and -15°C predominates on earth, since they permit the warming sunlight to permeate to the earth and, on the other hand, prevent the thermal radiation from the earth from completely escaping into space. The earth's equilibrium radiation balance is composed of a combination of the following components (GRASSL and KLINGHOLZ, 1990).

An output of 343 Watts reaches each square metre of the earth's surface. Of this, clouds, the brightness of the earth's surface and air molecules reflect 30 %. Opposing this, 49 % of the sun's radiation is absorbed by the earth's surface and 30 % by the atmosphere. This energy also warms the earth and, among other things, causes water to evaporate from the oceans. The earth, in turn, radiates the afore mentioned thermal energy outwards. However, a part is held back because of the clouds and the Greenhouse gases. Whilst the visible sun's energy reaches the earth as short-wave radiation, and thereby penetrates through the earth's atmosphere, the earth in turn emits long-wave radiation.

Carbon dioxide is used here as an example of the Greenhouse gas molecules to explain the "functioning" of the Greenhouse gases. When the thermal radiation hits a carbon dioxide molecule, the oxygen atoms on the side of the carbon begin to rotate and induce the carbon atom to vibrate. In this manner, the carbon atom absorbs the thermal radiation and heats up the atmosphere. A part of the energy that is given off in all directions by the carbon dioxide molecules will be returned to the earth.

The other Greenhouse gases, mainly water vapour, ozone, laughing gas, methane and the anthropogenically-produced chlorofluorocarbons, have a similar effect, so that only 16 % of them will be transmitted to the space directly; the rest will be transmitted through the atmosphere. In this manner a balance arises, which means that out of the 237 W/m^2 of solar energy, which reaches earth, 390 W/m^2 of the thermal radiation will be returned to the atmosphere. However, only the "equivalent" 237 W/m^2 disappears into space the remaining 153 W/m^2 will be emitted again and again, ultimately leaving the earth in equilibrium, as a result of the Greenhouse gases. In this manner the Greenhouse gases operate like a pane of the greenhouse. The climate system, like all complex systems, will be variable, as would also be the case without anthropogenic intervention, "depending on the most dominant timescale of the interacting parts of the climatic fluctuations involved. It is then only a question of the average time intervals chosen as to whether the variability of the climatic fluctuations will be significant" (GRASSL, 1993).

8.1 The Greenhouse Gases

Water vapour, carbon dioxide, methane, ozone and nitrogen dioxide are Greenhouse gases. In combination they make up an extremely small portion of the air. Dry air – dry due to the very variable portions of water vapour in the air – consists of up to 78.08 % nitrogen, up

to 20.95 % of oxygen and up to 0.93 % of the inert gas argon (GRASSL and KLINGHOLZ, 1990), none of which have any relevant role with regard to the terrestrial thermal equilibrium. These components lack the necessary characteristics to absorb solar radiation and thermal radiation.

As already mentioned, the most important Greenhouse gas affecting the heat balance is water vapour. It varies, depending on temperature and air humidity, in its volumetric proportion from one million parts in the stratosphere (the layer of the atmosphere about 50 km above the earth) to over one thousand parts over the polar regions and up to 300 parts in the tropics near the earth's surface (GRASSL and KLINGHOLZ, 1990).

Carbon dioxide, although one of the most important gases in the air only makes up 0.035 % of the air, but next to water vapour, is one of the most important Greenhouse gases. All Greenhouse gases combined make up, in total, only 3 % by volume of the air.

Table 8.1: A sample of Greenhouse gases affected by human activities (IPCC, 1995)

	CO ₂	CH ₄	N ₂ O	CFC-11	HCFC-22 (CFC- substitute)	CFC ₄ (perfluoro- carbon)
pre-industrial concentration	280 ppmv	~ 700 ppbv	~ 275 ppbv	0	0	0
Concentration 1994	358 ppmv	1720 ppbv	312* ppbv	268* pptv	110 pptv	72* pptv
Rate of change of concentration*	1.5 ppmv/yr 0.4 %/yr	10 ppbv/yr 0.6 %/yr	0.8 ppbv/yr 0.25 %/yr	0 pptv/yr 0 %/yr	5 pptv/yr 5 %/yr	1.2 pptv/yr 2 %/yr
Atmospheric life time	50–200§§	12§§§	120	50	12	50.000

The growth rates of CO₂, CH₄ and N₂O are averaged over the decade commencing 1984; halo-carbon growth rates are based on recent years (1990s).

* = Estimated from 1992–93 data.

§ = 1 pptv = 1 part per trillion (million million) by volume.

§§ = No single lifetime for CO₂ can be defined because of the different rates of uptake by different sink processes.

§§§ = This has been defined as an adjustment time which takes into account the indirect effect of methane on its own lifetime.

CFC = Chlorofluorcarbon.

Tab. 8.1 shows the increase of Greenhouse gases due to anthropogenic activity. The figures are taken from the 1995 IPCC report (IPCC, 1995). Clearly, a rise in the concentration of CO₂ has been recorded from 280 ppmv in pre-industrial times to 358 ppmv in 1994. Equally, there is no doubt that this rise is connected with anthropogenic activity, especially the burning of fossil fuels, but also with alterations to the use of land and, to a lesser degree, concrete production. Before the rise in the concentration of CO₂, CO₂ concentration fluctuated about 280 ppmv ±10 ppmv for around 1000 years.

In addition, methane rose, doubtless due to anthropogenic activity, such as rice cultivation, animal husbandry, burning of biomass and gas leakage, as well as the use of fossil fuels. The global average methane concentration has risen by about 6 % in the decade since 1984 and by about 145 % between the Industrial Revolution and 1994.

N_2O (nitrogen dioxide, laughing gas) has a relatively low rate of increase, but, for all that, a long residence time in the atmosphere. The cause of laughing gas is, above all, nitrogenous manure in the landscape and a succession of industrial processes. Since the Industrial Revolution, the proportion of N_2O in the atmosphere has risen from 275 ppv to 312 ppv, in association with a clear decrease in the growth rate in recent years (in the 80s and early 90s close to 0.8 ppbv/year, reducing to 0.5 ppbv/year in 1993).

In the early 90s, the growth rate of CO_2 , CH_4 and N_2O was insignificant. This natural variation is still not clear, but the data from recent years show that the trend of the 80s is continuing.

Halocarbons include chlorine and bromine and result in ozone depletion. The Montreal Protocol sets limits on emissions, as a result of which the growth rate has been reduced. The growth rate of CFC_s has, as a result, been reduced to zero. The Montreal Protocol also ordered reductions in the concentration of CFC_s , HCFC_s and their consumption of ozone.

Greenhouse gases with longer duration times, such as, mainly, HCFC_s , PFC_s and SF_6 , are currently an insignificant influence on radiation intensity. However, their projected growth may greatly increase the intensity of radiation amplification in the twenty-first century.

Ozone, O_3 , is an important Greenhouse gas, present in both the stratosphere and the troposphere. Alterations to ozone result in increased radiative forcing by influencing both the solar incoming radiation and the outgoing terrestrial radiation. The intensity of the solar radiation is strongly related to the vertical distribution of ozone and reacts with particular sensitivity to alterations at the level of the troposphere. The pattern of tropospheric and stratospheric ozone alterations is spatially variable. The estimation of the radiative forcing due to changes in ozone is essentially more complicated than that for the Greenhouse gases.

Tropospheric ozone levels have clearly risen since 1900, with strong evidence that this has occurred in many places since the 60s. In the 1990s, however, the upward trend has slowed and almost come to a halt. Altogether the northern hemisphere has seen a doubling in tropospheric ozone since the Industrial Revolution, an increase of 25 ppbv; whereas, in the southern hemisphere a diminution has been recognised since the mid-80s.

Decreases in stratospheric ozone have been observed since the 70s, mainly in the lower stratosphere, the most obvious feature of which is the phenomenon of the ozone hole over the Antarctic in September and October. A statistically significant decrease in total ozone levels has been noted in the mid latitudes of both hemispheres. In the tropics there is a slight trend towards ozone reduction, rather than an increase.

The calculation of the global average radiative forcing is a good way to get an overall impression of the potential climatic relevance of the individual components. Looking at this from a global angle has limitations:

1. the spatial pattern of the mixture of Greenhouse gases
2. the regional variation of tropospheric ozone and
3. the regional variation of tropospheric aerosols.

Such a global view of the radiative forcing does not reflect the complete pattern of potential climatic variations. It is not permitted to take negative numbers into account as a balancing factor. Table 8.2 presents the average radiative forcing:

Table 8.2: Annually Average Radiative Forcing

Factors	Capacity in Wm ⁻²
Greenhouse gases (CO ₂ , CH ₄ , N ₂ O and Halocarbons)	+ 2.45 Wm ⁻² (from + 2.1 to + 2.8 Wm ⁻²)
Tropospheric ozone	+ 0.4 Wm ⁻² (from + 0.2 to + 0.6 Wm ⁻²)
Stratospheric ozone	- 0.1 Wm ⁻² (from - 0.05 to - 0.2 Wm ⁻²)
Anthropogenic Aerosols (Sulphates, soot from fossil fuel, mainly coal, and organic aerosols resulting from biomass burning)	- 0.5 Wm ⁻² (from - 0.25 to - 1.0 Wm ⁻²)
Sulphate aerosols (fossil fuel emission)	- 0.4 Wm ⁻² (from - 0.2 to - 0.8 Wm ⁻²)
Soot in aerosols from fossil fuel sources	+ 0.1 Wm ⁻² (from 0.03 to 0.3 Wm ⁻²)
Direct radiative forcing of particles associated with biomass burning	- 0.2 Wm ⁻² (from - 0.07 to -0.6 Wm ⁻²)
Tropospheric dust particles influenced by man's activities	not quantifiable
Changes in cloud properties caused by aerosols due to man's activities (indirect effect)	0 to - 1.5 Wm ⁻² (cannot be quantified exactly, which is why, for scenario as a rule, -0.8 Wm ⁻² is used)
Alterations to radiative forcing due to changes in solar radioactive output*	+ 0.3 Wm ⁻² (from 0.1 to 0.5 Wm ⁻²) since 1850
Aerosols resulting from volcanic eruptions*	large for short periods of time (few years), e.g. Mt. Pinatubo -3 to -4 Wm ⁻²

* The past variation can explain climatic changes of periods of time on a decadal basis.

8.2. Global Change

As is seen clearly from the above, changes in global climate are closely correlated with the amount of Greenhouse gases in the atmosphere. In the case of an increase of Greenhouse gases in the atmosphere, the air temperature on earth will also rise, and this, in turn, will stimulate the earth's hydrological cycle: "per degree of temperature change, the amount of water vapour in the air increases by about 10 %" (GRASSL, 1993: 29). It has to be pointed out that the Greenhouse gases are always efficacious at a global scale and cannot be compensated on a regional basis, unlike the anthropogenic alterations of the surface (GRASSL, 1993).

A further feedback arises through alterations of temperature in the hydrological cycle. These temperature variations occur due to the fact that the brightest and darkest natural surfaces of the Earth are constituted of water. The darkest surface is the ocean and powdery snow is the brightest. In the case of warming, the brightness of the surface decreases and it will absorb more solar energy; this means that a further warming will result from the melting of the glaciers.

The clouds, as an additional factor, have two effects: whilst the low clouds mainly have a cooling effect, the high clouds have a warming effect. These thin high clouds are, however, also created by anthropogenic effects through aircraft exhaust emissions. However, the ultimate effect of the clouds on global warming is, currently, not clear.

The mean global surface temperature has risen by about 0.3° to 0.6° C since the late 19th century, and by about 0.2° to 0.3° C over the last 40 years. The warming occurred largely during two periods, between 1910 and 1940 and since the mid-1970s (IPCC, 1995).

The warming has not been globally uniform. The recent warmth has been greatest over the continents between 40° N and 70° N. A few areas, such as the North Atlantic Ocean north of 30° N, and some surrounding land areas, have cooled in recent decades (IPCC, 1995).

It can, however, be pointed out that since 1400 AD the global average temperature has been higher than in all previous centuries during the historic period (IPCC, 1995).

However, this cannot be clearly differentiated from the natural variations of the climate due to the alterations of trace gas concentration since the beginning of the Inertia Revolution, as the uncertainty in the key factors is still too great and the thermal of the ocean to balance the retardation of the effects of the previous influence of each decade have to be considered.

Information on **climatic change in the future** is much more difficult to ascertain, as the main problem lies in the estimation of future anthropogenic trace gas emissions. Therefore different scenarios have been undertaken, which take into account the differing increases in trace gas emissions. Data from the Intergovernmental Panel on Climate Change (IPCC) have been used as a basis for the production of these scenarios. This Panel was founded as an inter-governmental committee and is supposed to be used as the basis for political decisions. However, it must be noted that other institutions sometimes predict a different set of results.

The IPCC differentiates between four scenarios, which are calculated from coupled ocean-atmosphere models. These scenarios, whose assumptions are listed below, take into account the emissions from Greenhouse gases as well as aerosol processes:

- A) Economic development remains as at present, so that the world energy consumption quadruples to the year 2100. At the same time the rate of cutting of the tropical rain-forests continues as before (Scenario "Business As Usual").
- B) Moderate intervention in the global trace gas exchange will occur.
- C) Considerable intervention in the global trace gas exchange will occur.
- D) An immediate and considerable reduction in the ejection of all climatically significant trace material will occur. In spite of this, all Greenhouse gases initially increase in this scenario until the year 2030.

Equally in the case of – as GRASSL and KLINGHOLZ (1990) (in translation) put it so well – “an immediate and complete cessation” there would be a definite rise in the global average temperature over the next 100 years. The clearest conclusion comes, naturally, from Scenario A “Business As Usual”, as a result of which the most favourable outcome for man would be a temperature increase of 2.0° C by 2100, followed by a continued rise with hardly any reduction in rate. “Such a high average temperature has not occurred since at least 200 000 years ago” (GRASSL, 1998). There is, essentially, a slight reduction in the increase for Scenarios B and C. The likely equilibrium response of global surface temperature to a doubling of equivalent carbon dioxide concentration (the “climate sensitivity”) was estimated in 1990 to be in the range 1.5 to 4.5° C, with a “best estimate” of 2.5° C (IPCC, 1995).

Although CO₂ is the most important Greenhouse gas, the other Greenhouse gases contribute a significant portion (30 %) the projected global warming.

8.2.1 Effects

The results of such an increase in temperature would be quite varied and broad. In general, an increase of temperature of just one tenth of a degree would alter the boundary of the deserts by 50–100 km; half a degree would displace the northern forest boundaries by the same distance and cause the glaciers of the mid latitudes to retreat by a vertical distance of at least 200 meters. “The Earth has not experienced a 2 degrees higher average temperature since the existence of modern man, *Homo sapiens*. A four degrees warmer Earth has not occurred since man first appeared four million years ago” (GRASSL and KLINGHOLZ, 1990).

The following effects for temperature and precipitation may be ascertained from the models (IPCC, 1995):

“All model simulations, whether they are forced with increased concentrations of greenhouse gases and aerosols, or with increased greenhouse gas concentration alone, show the following features:

- generally greater surface warming of the land than of the oceans in winter, as in equilibrium simulations;
- a minimum warming around Antarctica and in the northern North Atlantic which is associated with deep oceanic mixing in those areas;
- maximum warming in high northern latitudes in later autumn and winter associated with reduced sea ice and snow cover;
- little warming over the Arctic in summer;
- little seasonal variation of the warming in low latitudes or over the southern circumpolar ocean;
- a reduction in diurnal temperature range over land in most seasons and most regions;
- an enhanced global mean hydrological cycle;
- increased precipitation in high latitudes in winter.

“Including the effects of aerosols in simulations of future climates leads to a somewhat reduced surface warming, mainly in the mid latitudes of the Northern Hemisphere. The maximum winter warming in high northern latitudes is less extensive.

“However, adding the cooling effect of aerosols is not a simple offset to the warming effect of greenhouse gases, but significantly affects some of the continental-scale patterns of climate change. This is most noticeable in summer where the cooling due to aerosols tends to weaken monsoon circulations. For example, when the effects of both greenhouse gases and aerosols are included, Asian summer monsoon rainfall decreases, whereas in earlier simulations with only the effect of greenhouse gases represented, Asian summer monsoon rainfall increased.

“Conversely, the addition of aerosol effects leads to an increase in precipitation over southern Europe, whereas decreases are found in simulations which employ only the greenhouse gases.” (IPCC, 1995).

“All model simulations, whether they are forced with increased concentrations of greenhouse gases and aerosols, or with increased greenhouse gas concentration alone, produce predominantly increased soil moisture in high northern latitudes in winter. Over the northern continents in summer, the changes in soil moisture are sensitive to the inclusion of aerosol effects.” (IPCC, 1995:43).

8.2.2 Ocean circulation

“In response to increasing greenhouse gases, most models show a decrease in the strength of the northern North Atlantic oceanic circulation further reducing the strength of the warming around the North Atlantic. The increase in precipitation in high latitudes decreases the surface salinity, inhibiting the sinking of water at high latitude, which drives this circulation.” (IPCC, 1995).

The alterations of the regional gradients are, as a rule, greater than the global gradients, because the amount of aerosols, the land use and the combined ecological effects of the individual factors can amplify or, depending on circumstances, can also reduce the variation.

The variability of the climatic change has a greater effect than the equivalent changes in average climate variations. They can lead to alterations in the frequency of extremes (IPCC, 1995):

8.2.3 Temperature

A general warming tends to lead to an increase in the occurrence of extremely high temperatures and a decrease in extremely low temperatures (e.g., frost days).

8.2.4 Hydrology

New results reinforce the view that variability associated with an enhanced hydrological cycle translates into prospects of more severe droughts and/or floods in some places and less severe droughts and/or floods in other places.

8.2.5 Mid-latitude storms

Conclusions regarding extreme storm events are, obviously, even more uncertain.

8.2.6 Hurricanes/Tropical cyclones

Although some models now represent tropical storms with some realism for present day climate, the state of the science does not allow assessment of future changes.

8.2.7 El Nino-Southern Oscillation

An average warming of the sea surface in the tropics will result from increased Greenhouse gas emissions, so the variability of the precipitation could be increased, as occurs in connection with ENSO events.

8.3 Sea-Level Rise

One of the major consequences of climate change could be the rise of sea level.

There are hundreds of publications about this phenomenon, these can be distinguished between those, which focus their research on the postglacial sea-level rise, and those, which look at the changes over the last 100 years and calculate future trends.

This chapter concentrates on the second approach. The results and conclusions refer to IPCC 1995, except where indicated to the contrary.

8.3.1 Reasons for Sea-Level Rise (GRASSL, 1993)

In the case of global warming, the sea level will rise. There are mainly two reasons for this reaction to the rise of temperature. Firstly the thermal expansion of the oceans, secondly melting of mountain glaciers. The two other big potential resources of water for sea-level rise are the Antarctic and the Greenland ice sheets.

Thermal expansion of water depends on the depth of the warming of the water body and the ocean currents. Therefore the thermal expansion results in a regional pattern of sea-level rise and global estimation is very difficult. It is certain that areas of the ocean, which are mixed in depth, will have a greater thermal expansion in relation to the warming of the surface.

By contrast, melting of the ice sheets cause a sea-level rise, which results in the same alterations in level globally. Whereas the mountain glaciers can cause a global sea-level rise the reaction of the ice sheet from Greenland cannot be calculated very well, because the answer to the question as to whether it is melting or expanding is not certain.

The IPCC (1995) summarises the function of the Greenland and Antarctic ice sheets as being relatively minor over the next century. However, the possibility of large changes in volumes of these ice sheets (and consequently, in sea-level) cannot be ruled out, although the likelihood is considered low. (IPCC, 1995)

8.3.2 Has Sea-Level Risen? (IPCC, 1995)

The analyses of tide gauge records show a sea-level rise by about 10–25 cm over the last 100 years. The main uncertainty of results from tide gauges is the vertical land movement, but methods for filtering out the effects of long-term vertical land movements as well as greater reliance on the longest tide-gauge records for estimating trends have given greater confidence in the results.

Over the period of the last 100 years much of the sea-level rise has been related to the concurrent rise in the global temperature. The observed sea-level rise may account initially for about 2 to 7 cm from the warming and consequent expansion of the oceans and secondly for about 2 to 5 cm from the retreat of glaciers and ice caps. "Only a small change in sea-level has been caused by surface and groundwater storage."

"The rate of observed sea-level rise suggest that there has been a net positive contribution from the huge ice sheet of Greenland and Antarctica, but observations of the ice sheets do not yet allow meaningful quantitative estimates of their separate contributions. The ice sheets remain a major source of uncertainty in accounting for past changes in sea-level, because there are insufficient data about these ice sheets over the last 100 years." (IPCC, 1995) Furthermore is not really clear if they cause a sea-level rise or decrease (GRASSL, 1993).

8.3.3 Global mean Sea-Level Projections

Projections of the global sea-level rise are taken from the results of IPCC 1995: Summary and 40 ff.; for the calculation for the 21st century IS92 scenarios are used. “For the IS92a scenario assuming the “best estimate” values of climate sensitivity and of ice melt sensitivity to warming, and including the effects of future changes in aerosol, models project an increase of sea-level of about 50 cm from the present to 2100.” (IPCC, 1995). The range between the lowest emission scenario (IS92c) and the highest emission scenario (IS92e) is 15 cm to 95 cm from present to 2100 (Fig. 8.1).

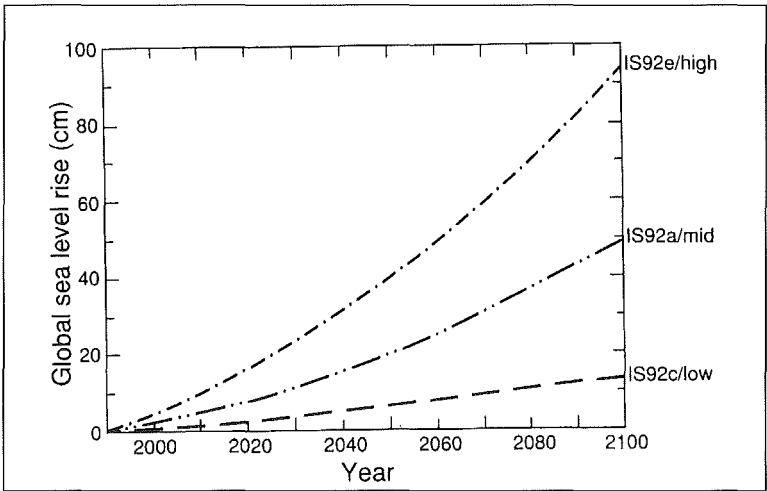


Fig. 8.1: Projected global mean sea-level rise extremes from 1990 to 2100. The highest sea-level rise curve assumes a climate sensitivity of 4.5°C, high ice melt parameters and the IS92e emission scenario; the lowest a climate sensitivity of 1.5°C, low ice melt parameters and the IS92c emission scenario and the middle curve a climate sensitivity of 2.5°C, mid-value ice melt parameters and the IS92a scenario (IPCC, 1995)

Due to the large thermal inertia of the ocean-ice-atmosphere climate system the choice of emission scenario has relatively little effect on the projected sea level rise. In the second part of the 21st century the effects increase.

Moreover the sea-level “would continue to rise at a similar rate in future beyond 2100, even if concentrations of greenhouse gases were stabilised by that time, and would continue to do so even beyond the time of stabilisation of global mean temperature.” (IPCC, 1995)

The future sea-level rise will differ regionally owing to regional differences in heating and circulation changes.

8.4 Possible Impact on the Intensity and Frequency of Cyclones

One of the widely recognized consequences of global warming would be increased sea surface temperature (SST). It is known that the tropical cyclones derive their energy mainly from the latent heat of evaporation from the ocean. Warm water of at least 26–27°C is needed to supply energy for cyclogenesis. The behaviour of tropical cyclones in warmer world, where we may have larger area of sea having temperature over this critical value, has been the subject of considerable speculation and concern.

Although the casual relationship between SST and the formation of tropical cyclones suggest that the theoretical maximum intensity may increase with temperature, the evidence inferred from several observational and modelling studies is still conflicting (RAPER, 1993; RYAN et al., 1992; STEIN and HENSEN, 1994). This may be attributed to the fact that the formation of tropical cyclones depends not only on SST but a number of other factors which include, the vertical lapse rate of the atmosphere, vertical wind shear, mid-tropospheric relative humidity and the prior existence of a center of low-level cyclone vorticity (GRAY, 1979). The factors change in complex ways with changing climate. An estimate of such changes is therefore not straightforward and may only be derived from state-of-the-art climate models. Present day climate models are able to simulate some of the aspects of tropical cyclone occurrence (MANABE and BROCCOLI, 1990; HAARSMA et al., 1993), they are not adequate enough to predict changes in warming climate. Most of the impact assessment studies carried so far use indirect techniques, rather than direct simulation of the tropical cyclones.

EMANUEL (1987) combined the CO₂ induced SST changes simulated by the Goddard Institute of Space Studies (GISS) climate model (HANSEN et al., 1984) with a theoretical tropical cyclone model (EMANUEL, 1986) to estimate the potential change in the intensity of tropical cyclones. His estimate showed that the intensity of tropical cyclones would increase as a result of increased tropical SSTs. However, in the absence of any empirical evidence in this regard, Emanuel's modelling results may not be considered very realistic.

NICHOLLS (1989) examined the activities of tropical cyclones and their intensities with SST from observations. He found little evidence of any relationship between monthly average SST and the number of tropical cyclones.

RAPER (1993) studied in detail the relationship between climate change and the frequency and intensity of severe tropical cyclones for the six tropical cyclogenesis regions, viz., North Atlantic, Western North Pacific, Eastern North Pacific, North Indian and extended Australian region (Southwest Pacific/Australian region). He used the US National Oceanic and Atmospheric Administration tropical cyclone data set (NOAA, 1988) for his study. He did not find any convincing empirical evidence in support of the relationship between SSTs and cyclone intensities. However, an increase in SSTs indicated a threshold effect that could lead to increase in the intensity of most severe storms. With regard to the relationship between tropical cyclone activity and SSTs, RAPER (1993) found different relationships in different areas. While predominantly negative correlation is found in two (North Indian Ocean and West North Pacific) of the six cyclone regions, four other regions showed a predominantly positive correlation. In the regions with highest positive correlation, simple regression suggests an increase of 37–63 % in severe tropical storm frequency per degree increase in SST. However, this relationship may not be constructed as having predictive skill for long term climate change as evidence suggest that the relationship is not necessarily directly casual because the areas of correlation are not always coincident with the areas of cyclone origin and tracks. Thus, the effect of SSTs may be indirect, through the connection with the regional-

scale atmospheric circulation. The main conclusion emerged from the analysis of RAPER (1993) was that changes in tropical cyclone activity in warmer world will depend crucially on the changes that may occur in the regional-scale atmospheric circulation.

A study undertaken by GRAY (1990) suggests that Atlantic hurricane activity over the period 1970 to 1987 was less than half that in the period 1947 to 1969, Western North Pacific also showed a decrease in the number of very intense tropical cyclones. In the Northeast and Southwest Pacific the number of cyclones appears to have increased (THOMPSON et al., 1992; LANDSEA et al., 1996).

EVANS (1993) looked into the relationship between SST and intensity of TCs for different regions where they form. Except for intense storms in the North Atlantic, his results indicate that there is little evidence to support the direct relationship between SSTs and cyclone intensities in most of the regions. CHANGNON (1993) studied historical variations in 146 major storms during 1950–1990 to describe their temporal characteristics and possible relationship to climate change. His results suggest that a warmer regime over North America would be associated with a greater incidence of major storms in the US.

In the North Indian Ocean the frequency of tropical disturbances has noticeably decreased (GADGIL, 1995) since 1970 (Fig. 8.2) while SSTs have risen here since 1970, probably more than in any other region (RAPER, 1993).

PITTOCK (1992) reports that sensitivity studies using limited area models in response to modelled increase in SST, suggests that cyclones may be more intense under warmer conditions. He notes, however, that historical data do not demonstrate any strong link between tropical cyclone numbers or intensity and SST, other than the lower limit for occurrence of around 27° C.

LIGHTHILL et al. (1994) observed that although substantial regional changes are expected but there are no compelling reasons to believe a major change in global tropical cyclone frequency.

As mentioned earlier, present day climate models are not able to simulate tropical cyclones well, nevertheless there have been large numbers of modelling studies carried out using low resolution GCMs. RYAN et al. (1992) used a GCM to assess tropical cyclone frequencies from yearly Genesis Parameter defined by GRAY (1975). He showed that the Gray's parameter forced by the output of a GCM gives a good representation of the observed tropical cyclone climatology. He, however, notes that changes in the Gray's Genesis Parameter due to enhanced greenhouse conditions were dominated by the SST changes.

In another numerical experiment carried out with the GFDL coupled ocean-atmosphere model, STEPHENSON (1993) showed that the Atlantic storm track weakens with increasing CO₂, while the Pacific storm track changes little. HAARSMA et al. (1993) analyzed the results of a GCM to show that the number of simulated tropical disturbance increases by about 50 % with the doubling of the CO₂ concentration. His GCM analysis also indicated a change in cyclone tracks as a result of CO₂ induced global warming. On the other hand, BENGTSSON et al. (1994) indicated that with a doubling of CO₂ over the next 50 years, the global and seasonal distribution of storms should be similar to the present observations. They also found a significantly reduced number of tropical cyclones for enhanced greenhouse scenario. This decrease in the number of tropical cyclones was substantial in the Southern Hemisphere, which seems unusual.

Recently DRUYAN and LONERGAN (1997) adapted hurricane frequency index (GRAY, 1979) so that it can be computed from simulations by the NASA/GISS climate model. Based on simulation experiments, they found that an atmosphere with double the present concentrations of CO₂ could lead to an increase of about 50 % in the number of tropical storms

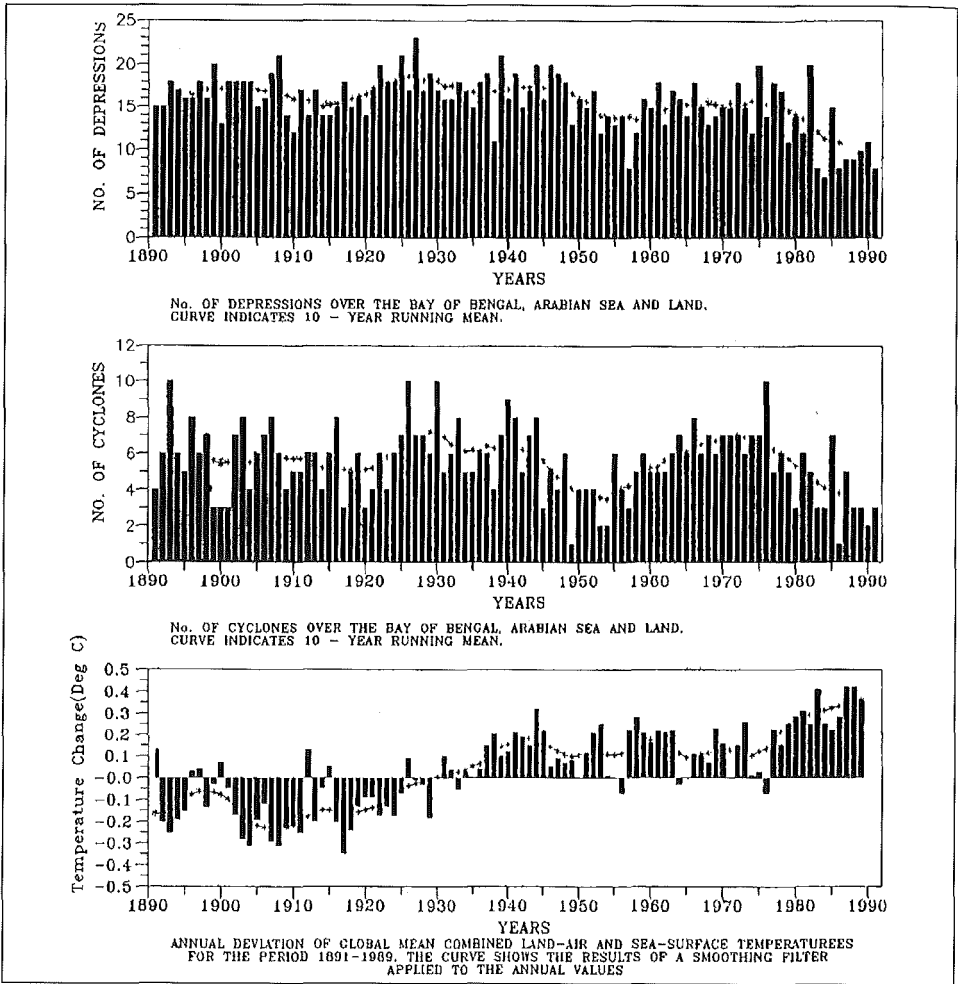


Fig. 8.2: Variation of the frequency of depressions and cyclones over the Indian seas (GADGIL, 1995)

(winds exceeding 64 km/h) and hurricanes that form over the Gulf of Mexico, and an increase of more than 100 % over the tropical North Pacific Ocean.

More recently WALSH and PITTOCK (1998) indicate that because of the insufficient resolution of climate models and their generally crude representation of sub-grid scale and convective processes, little confidence can be placed in any definite predictions of potential changes in tropical storms as a result of climate change. However, a tendency for more heavy rainfall events seems likely, and a modest increase in tropical cyclone intensities is possible. In the views of the author, it would be unwise to exclude substantial local changes in the climatologies of these phenomena, especially at regional (sub-continental) scale.

In the end we can say that the formulation and intensification of tropical cyclones depend not only on SST but also on a number of atmospheric factors. The tropical cyclone activity in a warmer world will, therefore, depend on regional changes that may occur. In the absence of the models that may adequately predict these regional changes, it is not possible to make future projections for changes in global tropical cyclone frequency and intensity.

8.5 ENSO and Tropical Cyclone Activity

8.5.1 Impact on Tropical Cyclone Frequency

The role of environmental or external forcing processes on tropical cyclone formation, structure, structural change and motion has been known and accepted in varying degrees by meteorologists for many years. El-Nino/Southern Oscillation (ENSO) is the most important short-term climatic fluctuation of tropical circulation. In recent years its possible role in modulating tropical cyclone activities in different parts of the world has been emphasized (GRAY, 1984a).

The pioneering work in this field was by NICHOLLS (1979, 1984, 1985) for cyclones in the two Australian basins. He demonstrated an association between the Southern Oscillation Index (SOI) during the Southern Hemisphere winter and the number of tropical cyclones close to Australia (from 105–165 E) during the subsequent cyclone season (i.e., from October to April). The number of cyclone days over a season is correlated with mean sea-level pressure for the preceding July–September. The linear correlation coefficient for the two series over this 25-year sample is -0.68 . NICHOLLS (1985) demonstrated the robustness of the relationship by calculating separate lag correlations for each ten-year data set from 1909 to 1982. For all seven 10-year subsets, the correlation coefficient between July–September pressure and subsequent October–April cyclone numbers ranged from -0.41 to -0.72 .

However, NICHOLLS (1992) detected a sudden decrease in cyclone numbers within the region following the end of the 1985/86 season that has not been accompanied by a corresponding decrease in the Southern Oscillation Index (SOI). Thus, his method would have consistently over-predicted cyclone activity during the 1986/87–1990–91 seasons. This sudden change in the SOI-cyclone numbers relationship may have been a real physical change, or is perhaps a result of changes in satellite imagery interpretation, or inadvertent changes in the Southern Oscillation Index. NICHOLLS (1992) suggests that a possible remedy may be to correlate the trend in the SOI versus the change in cyclone numbers from one season to the next.

The second major work on seasonal prediction of tropical cyclone activity has been for the North Atlantic basin. Relationships between numbers of cyclones and the large-scale pressure patterns were originally found by NAMIAS (1955) and BALENZWEIG (1959). Major developments in documenting the predictability of this basin have been recently achieved (GRAY, 1984a, 1984b, 1990; GRAY et al., 1992, 1993; SHAPIRO, 1982a, 1982b, 1987, 1989). The number of tropical cyclones in a season has been related to various aspects of the large-scale flow, including the sea-level pressure, the patterns of sea-surface temperature, the upper-tropospheric zonal winds, and seasonal rainfall in the Sahel of West Africa. The strongest relationships have been with the Southern Oscillation and with the Stratospheric Quasi-Biennial Oscillation (QBO), which is a quasi-periodic reversal of zonal winds over the Equator. The tropical cyclone activity in seasons during the west phase of the QBO is a factor of 1.4 greater than during the east phase. Ascribing a simple index of +1 for a season in the west phase, 0 for transition seasons and -1 for east phase of the QBO, the correlation of this index with the cyclone numbers accounts for 33 % of the variance. Similarly, large correlations are found between cyclone numbers and an index of Southern Oscillation/El-Nino activity based on SST anomalies over the equator eastern Pacific.

Each of the above three forecast relationships for annual tropical cyclone activity included some aspect of El Nino/Southern Oscillation (ENSO) phenomenon as a key component.

NICHOLLS' forecasts for the Australian region are based completely on various indices of the Southern Oscillation. The correlation of cyclone numbers in the Australian region and the SOI in the months preceding the season is approximately 0.7 (i.e., accounting for 50 % of the variance). Perhaps the physical reason for the association is that the number of tropical cyclones during the season has a simultaneous high negative correlation with the large-scale surface pressure in the region; i.e., a low surface pressure is consistent with a large number of tropical cyclones. Since northern Australia is close to one of the centers of action of the Southern Oscillation, variations in this large-scale pressure are effectively equivalent to variations in the SOI. The predictability (or lag relationship) comes through the slow variation (or large serial correlation) of the SOI at the time of year preceding the Southern Hemisphere cyclone season.

During an ENSO warm event in the eastern Pacific, the pressure over Australia is high, which leads to a reduced number of cyclones in that region. REVELL and GOULTER (1986), HASTINGS (1990) and EVANS and ALLEN (1992) have pointed out that the frequency of cyclone formation at the eastern end of the Australian/South Pacific basin (i.e., east of 170E) actually increases during an ENSO warm event. Although the relationship between the formation longitudes in the region and the SOI is weak, it is statistically significant. However, the relationship appears to be dominated by the extreme events (i.e., warm events). If the relationship is real, the eastward movement of formation locations may be explained in terms of the favorable factors for cyclone formation discussed in Chapter 3.2. During an ENSO warm event, the region with SSTs exceeding 26° C extends much farther eastward across the South Pacific.

A number of authors has studied the association between the SOI and cyclone activity in the western North Pacific basin (ATKINSON, 1977; CHAN, 1985; DONG, 1988; ZHANG et al., 1990; LANDER, 1994). In each study, the simultaneous SOI relationship with the total number of cyclones over the basin has been quite weak. DONG (1988) suggested that the typhoon activity is suppressed by the El-Nino events in the basin west of 160° E but enhanced east of this longitude. Another study for northwest Pacific by AOKI (1985) shows the minimum frequency in typhoon formation during El-Nino events and maximum frequency two years later. CHAN (1985) reports that the number of cyclones east of 150 E increases when the large-scale pressure is high, i.e., during an ENSO warm event. The reason (given by CHAN) is the same as given above for the South Pacific. During an ENSO warm event, the monsoon shearline extends farther eastward than normal, which is a condition conducive for cyclone formation. This was extended by LANDER (1994) who showed that a large number of monsoon-shearline type cyclone formations occur late in the season of a warm event in a region east of 160E and south of 20E. Conversely during a cold event, no formations occur in that southern and eastward part of the basin.

The relationship between ENSO and cyclone activity in the North Atlantic basin apparently is quite different. It has been observed that El-Nino events reduce hurricane activities significantly in north Atlantic during the season following the onset of El-Nino and hurricane activity usually resumes to normal in the second summer following the events (GRAY, 1984a, 1988). Numbers of hurricane days are less by 60 % in moderate and severe El-Nino events in comparison to the non El-Nino years. The seasonal reductions in hurricane activity in the Atlantic in El-Nino years are reported to be due to the development of strong anomalous westerly zonal winds in the upper troposphere over the Lower Caribbean Sea and eastern Tropical Atlantic, which almost always occurred during the El-Nino years in comparison to the other years. SHAPIRO (1987) reports a correlation of -0.34 (only 12 % of the variance) between cyclone numbers and the warm water anomaly in the equatorial eastern

Pacific. Both SHAPIRO (1987) and GRAY (1984a) give evidence that the physical link is that higher equatorial SST values increase the activity of tropical convection, which increases the upper-level westerly zonal winds and the vertical wind shear downstream over the primary formation region of the Atlantic cyclones. As discussed above, large vertical shear represents an unfavorable condition for tropical cyclone formation (on this seasonal timescale).

The relationship between El-Nino events and tropical cyclone activities over northeast Pacific region are reverse to that of the Atlantic and northwest Pacific. It has been observed that in 5 El-Nino events since 1966 there is a strong indication that tropical cyclone activities have increased, especially, in the case of intense tropical storms. During El-Nino events, on the other hand, tropical cyclone activity is found to be suppressed over northeast Pacific.

Results for southwest Pacific (RAMAKRISHNA, 1989) appear to be interesting, as an enhancement in tropical cyclone activity has been observed in both the high and low phases of southern oscillation index.

The relationship between tropical cyclone behaviour and ENSO for North Indian Ocean has been examined by MANDAL (1989), but unlike the Atlantic and the Pacific, the relationship is found to be very weak. There is practically no change in frequency of the tropical cyclones during the ENSO episode in North Indian Ocean in comparison to the non El-Nino years or mean values.

8.5.2 Impact on Tropical Cyclone Tracks

GRAY (1984a, 1988) has shown that to some extent, El-Nino events also affect the intensity and track of the tropical storms in Atlantic. In El-Nino years the storms are less intense and more recurving over the Caribbean Sea. JOSEPH (1981) studied the motion of post-monsoon cyclonic storms over the Bay of Bengal with respect to years of highly deficient rainfall of India. JOSEPH (1976) pointed out that during the epochs of frequent drought years in all India monsoon rainfall, severe cyclonic storms of the Bay of Bengal of the post-monsoon season have preferred northward movement affecting Bangladesh and adjoining Indian coastal areas. A study by SINGH et al. (1987) for North Indian Ocean also shows some influence of southern oscillation on the latitude of the tracks of cyclones during post-monsoon season (October–December) crossing east coast of India. The above study also shows the increase in frequency of cyclones in low latitude (Andhra Pradesh coast) and the decrease in the higher latitude (Orissa and West Bengal coasts) during low phases of southern oscillation (El-Nino years). The study made by MANDAL (1989) for North Indian Ocean (NIO) has, however, shown that numbers of recurving and non-recurving tropical cyclones were found to be in almost equal proportion in El-Nino years. The study takes account of all the storms, which formed over the Bay of Bengal and Arabian Sea during a year (including monsoon season).

A notable study made by GUPTA and MUTHUCHAMI (1991) for the storms of Bay of Bengal region during post monsoon season (October–December) has shown significant relationship between El-Nino and the tropical storm tracks over the Bay of Bengal. The authors studied tracks of the storms during El-Nino and other years such as El-Nino (–1) years, El-Nino (+1) years and so on. After a careful analysis of the storm tracks in these years, it has been seen that the behaviour of storms tracks has some definite patterns during El-Nino and El-Nino (–1) years. While the storms tracks are mostly straight and less recurving during El-Nino years, they are more recurving during El-Nino (–1) years [Fig. 8.3 (a) & (b) and 8.4 (a) & (b)].

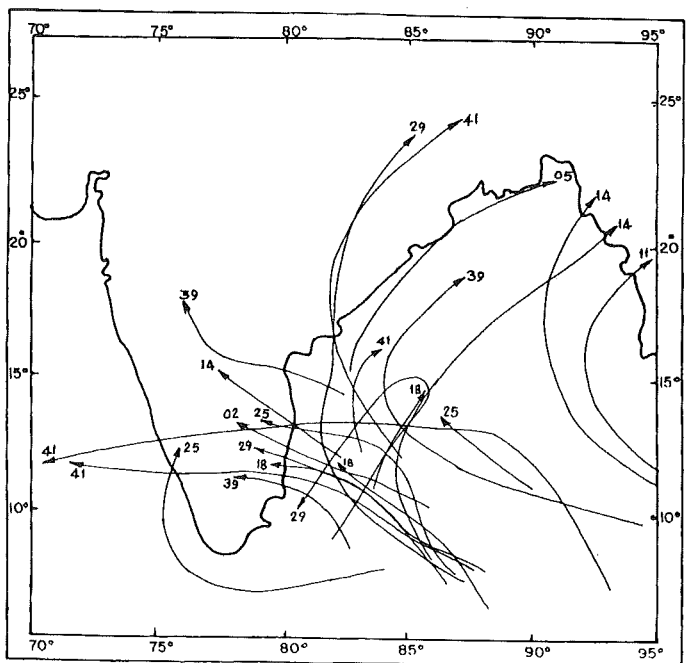


Fig. 8.3(a): Tracks of depression and cyclones over Bay of Bengal during post-monsoon season in El-Nino years (1901–1950). (Number written ahead of tracks indicates years of storm formation)

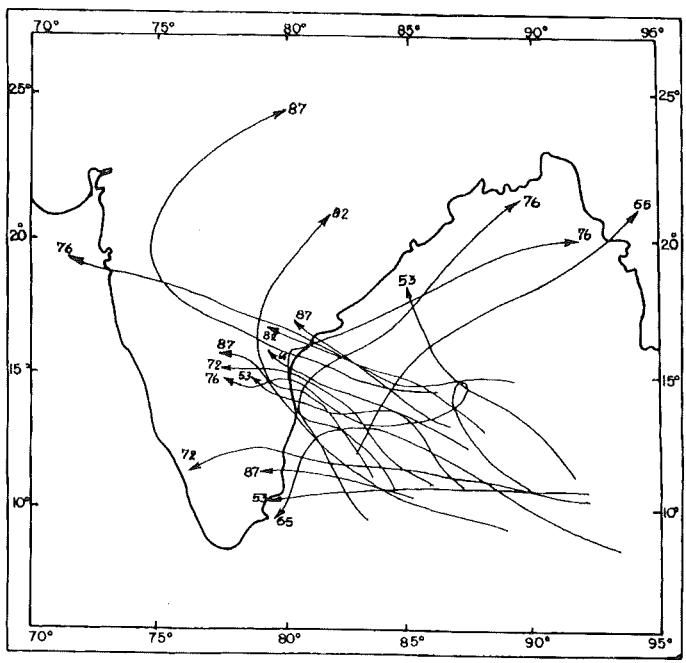


Fig. 8.3(b): Tracks of depression and cyclones over Bay of Bengal during post-monsoon season in El-Nino years (1951–1987). (Number written ahead of tracks indicates years of storm formation)

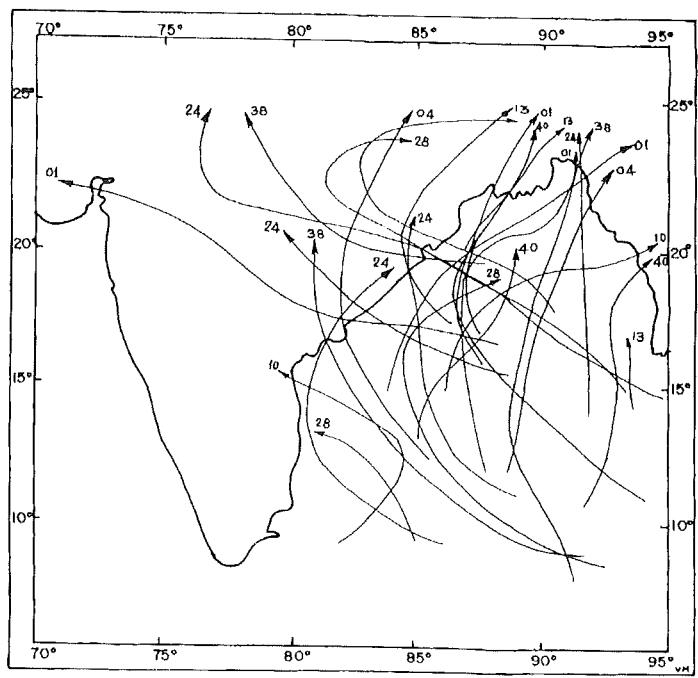


Fig. 8.4(a): Tracks of depression and cyclones over Bay of Bengal during post-monsoon season in El-Nino (-1) years (1901-1950). (Number written ahead of tracks indicates years of storm formation)

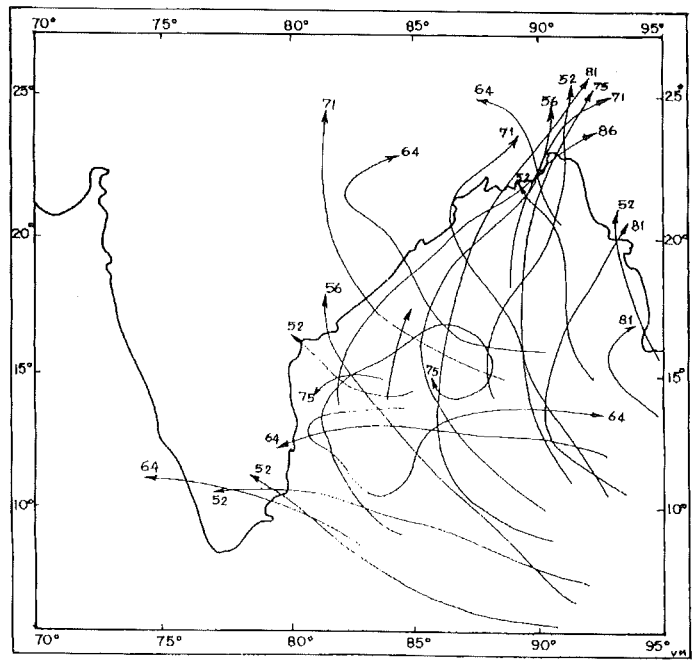


Fig. 8.4(b): Tracks of depression and cyclones over Bay of Bengal during post-monsoon season in El-Nino (-1) years (1951-1987). (Number written ahead of tracks indicates years of storm formation)

These results are opposite to those of GRAY (1984a, 1988) for Atlantic where the storms are found to be more recurving during El-Nino years. It is evident from these figures that El-Nino years have more numbers of storms crossing at lower latitudes on the Indian east coast compared to El-Nino (-1) years. To establish a quantitative approach to this behaviour, the storms were classified into two categories, viz., (1) recurving or those crossing north of 17°N and (2) non-recurving or those of which crossing south of 17°N on the east coast of India. There were mainly two considerations for choosing the latitude 17°N as the boundary between recurving and non-recurving systems. From the analysis of cyclone formation and their movement over the Bay of Bengal, it is observed that no cyclone forms north of 17°N during post-monsoon season and that maximum numbers of recurvature of the cyclones take place between the latitudes 15° and 17°N . Another observation was that almost all the storms crossing north of 17°N move north to northeastward during this season. Table 1 gives the details of the number of storms crossing Indian east coast under these two categories during El-Nino and El-Nino (-1) years. It may be seen from this table that 33 out of 38 tropical cyclones (about 87 %) during El-Nino years are non-recurving or crossing south of 17°N whereas 38 out of 48 tropical cyclones (about 79 %) during El-Nino (-1) years are either recurving or crossing north of 17°N . It may also be inferred from this table that during severe El-Nino years 15 out of 16 storms (about 94 %) have crossed south of 17°N whereas during years previous to these severe El-Nino years, 17 out of 19 storms (about 89 %) were either recurving or crossed north of 17°N .

To establish a correlation between the number of storms crossing south of 17°N during El-Nino years and the number of storm recurving/crossing north of 17°N during El-Nino (-1) years, fractional values of these numbers ($n = 16$) were statistically correlated and test of significance (t-test) was applied. The correlation coefficient of +0.84 was found between these two parameters, which are significant at 1 % level.

Although, considering past 87 years period (1901–1987) the total number of storms during 16 El-Nino years (38), as shown in Table 8.3, is less compared to the number in 16 El-Nino (-1) years (48), no preferred behaviour in terms of reduction or increase in the frequency of the storms is noticed in any kind of year [El-Nino, El-Nino (-1), etc]. Also, though characteristics of the storm tracks are distinctly different during El-Nino years compared to El-Nino (-1) years, but the prediction of onset of El-Nino based on the characteristics of the storm tracks in a particular year may not be possible as the storm frequency over North Indian Ocean is very low. On an average, 2 to 3 storms form over Bay of Bengal during post-monsoon season.

Table 8.3: Number of cyclonic storms recurring/crossing north of 17° N and those crossing south of 17° N during El-Nino and El-Nino (-1) years

El-Nino Years	No. of C.S.	No. of CS recurring/ crossing north of 17° N	No. of CS crossing south of 17° N	El Nino (-1) Years	No. of CS	No. of CS recurring/ crossing north of 17° N	No. of CS crossing south of 17° N
1902 (M)	1	0	1	1901	2	2	0
1905(M)	1	1	0	1904	1	1	0
1911(S)	1	1	0	1910	2	1	1
1914(M)	1	1	0	1913	4	3	1
1918(S)	3	0	3	1917	2	2	0
1925(S)	3	0	3	1924	5	4	1
1929(M)	3	0	3	1928	4	3	1
1939(M)	3	1	2	1938	3	2	1
1941(S)	4	0	4	1940	2	2	0
1953(M)	3	1	2	1952	7	4	3
1957(S)	0	0	0	1956	2	2	0
1965(M)	3	0	3	1964	4	2	2
1972(S)	3	0	3	1971	3	3	0
1976(M)	3	0	3	1975	3	3	0
1982(S)	2	0	2	1981	3	3	0
1987(M)	4	0	4	1986	1	1	0
Total	38	5	33		48	36	10
Mean	2.38	0.31	2.07		3.0	2.38	0.62
In %		13.1	86.9			79.2	20.8

C.S. = Cyclonic Storms; S = Severe El-Nino years; M = Moderate El-Nino years

The fractional values of storms crossing south of 17° N and southern oscillation indices (Tahiti-Darwin pressures) for the period 1901–1987 ($n = 87$) were statistically correlated and test of significance (t-test) was applied. The correlation coefficient of the -0.63 is found between SOI and storms crossing south of 17° N, which is significant at 1 % level. These results are in agreement with those of SINGH et al. (1987).

Similar studies for other basins are yet to be made available.

8.6 Possible Implications of Sea-Level Rise on Storm Surges

Projected sea-level rise due to global warming would inundate low lying areas, erode shore lines and destroy mangrove and Nepa palm forests. This would be particularly hard-felt in the deltaic regions where substantial area is barely above sea-level. Many coastal areas are at present submerging. Fig. 8.5 shows the sectors of the world's coast line that have been subsiding in recent decades, as indicated by the evidences of tectonic movements, logical and ecological indications, geodetic surveys, and groups of tide gauges recording a rise o mean sea level greater than 2 mm per year over the past three decades (BIRD, 1993).

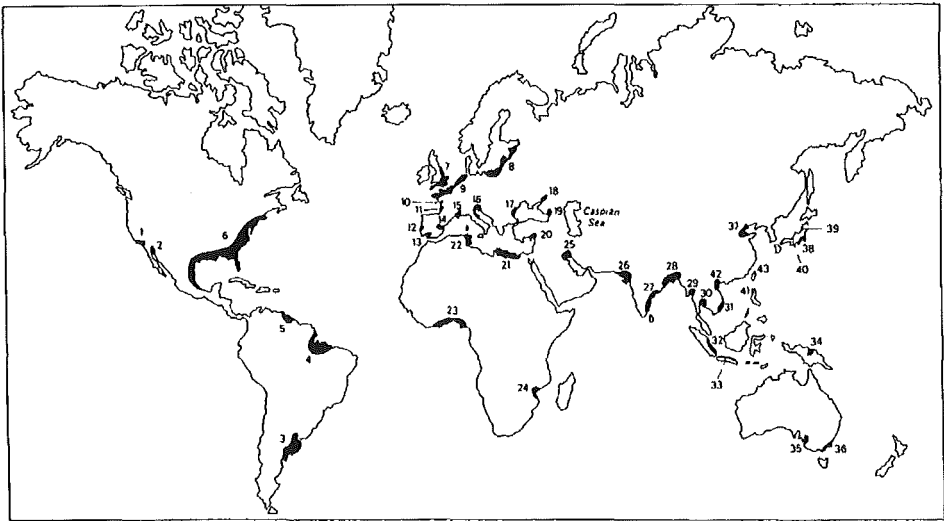


Fig. 8.5: Sectors of the world's coastline that have been subsiding in recent decades, as indicated by evidence of tectonic movements, increasing marine flooding, geomorphological and ecological indications, geodetic surveys, and groups of tide gauges recording a rise of mean sea level greater than 2 mm/yr over the past three decades (BIRD, 1993). 1, Long Beach area; 2, Colorado River delta; 3, Gulf of Laplata; 4, Amazon delta; 5, Orinoco delta; 6, Gulf and Atlantic coasts; 7, southern and eastern England; 8, southern Baltic coasts; 9, southern coasts of the North Sea and Channel coasts; 10, Loire estuary; 11, Vendée coasts; 12, Lisbon region; 13, Gaudalquivir delta; 14, Ebro delta; 15, Rhône delta; 16, northern Adriatic low coasts of Italy; 17, Danube delta; 18, eastern Sea of Azov; 19, Poti swamp; 20, southern Turkey; 21, Nile delta to Libya; 22, northeast Tunisia; 23, Niger delta and north coasts of the Gulf of Guinea; 24, Zambezi delta; 25, Tigris-Euphrates delta; 26, Rann of Kutch; 27, southern India; 28, Ganges-Brahmaputra delta; 29, Irrawaddy delta; 30, Bangkok coastal region; 31, Mekong delta; 32, eastern Sumatra; 33, northern Java deltaic coast; 34, Sepik delta; 35, Port Adelaide; 36, Corner Inlet region; 37, Hwang-He (Yellow River) delta; 38, head of Tokyo Bay; 39, Niigata; 40, Maizuru; 41, Manila; 42, Red River delta; 43, northern Taiwan

According to NICHOLLS and LEATHERMAN (1995), a 1 m sea level rise would affect six million people in Egypt, with 12 % to 15 % of the agricultural land lost 13 million in Bangladesh, with 16 % of national rice production lost, 72 million in China and tons of thousands of hectare of agricultural land. This could greatly increase existing storm surge threat because of the increase in the coastal area exposed to the surges originating in the sea, and loss of

coastal forests, which act as a buffer against the force of storm surges. The situation would be worse if the intensity and frequency of tropical cyclones increases due to warmer SSTs as projected by many workers.

Some conclusions drawn on the global vulnerability of storm surges due to sea level rise are (HOOZEMANS et al., 1993; BAARSE, 1995; IPCC, 1996):

- (i) Some 200 hundred million people are estimated to live currently below the highest storm surge level (the once-per-1000-years storm surge level). Based on this population estimate, as well as on first order estimate on storm surge probability and existing level of protection, 46 million of people are estimated to experience flooding due to storm surge in an average year under present condition. Most of these people live in the developing countries.
- (ii) The figure will double if the sea level rises 50 cm (92 million people per year) and almost triple if it rises 1 m (118 million people per year).
- (iii) Because of regional differences in storm surge regimes, the increase of flood risk due to sea level rise is greater than average for the Asian region (especially in the Indian Ocean Coast), the south Mediterranean coast, the African Atlantic and Indian Ocean Coasts, Caribbean Coasts and many of the small islands.

The surges are superimposed on raised mean sea level (MSL). In view of the dynamical effects in a shallow coastal area, the components of total water level due to storm surge, astronomical tide and MSL are mutual dependent and interact dynamically with each other. Therefore, for estimating the total water level one cannot assume that MSL, tide and surge are linearly additive and there is no non-linear interaction.

There are two important issues associated with implication of sea-level rise on storm surges. Firstly, raised mean sea level implies greater potential inland inundation due to storm surges and in second place higher mean sea level may itself affect the surge and tidal components of the rise. Another issue, which has attracted attention, is related to the sensitivity of storm surges to change in projected cyclone intensity as a result of changes in SST. In the following section we will briefly discuss these issues and describe attempts made by various workers to address the problems of different vulnerable regions.

8.6.1 Bay of Bengal

Storm surges in the Bay of Bengal are the major cause of coastal flooding along the east coast of India and Bangladesh. In the context of the projected rise in the sea level due to green house warming, it may be interesting to examine how changes in mean sea level (MSL) may affect the storm surges and consequently the coastal flooding in the Bay of Bengal.

As mentioned earlier, low lying coastal regions of Bangladesh are worst affected due to storm surges. Exposure of population to sea level rise and storm surges is particularly an extremely grave consideration in Ganga-Brahmaputra-Meghna delta of Bangladesh. Local subsidence in this region is very significant which may increase the relative rate of sea-level rise. Ganga-Brahmaputra-Meghna river systems together deliver approximately 1.6 billion tonnes of sediments annually (MILLMAN and MEADE, 1983). The damming of Meghna River could prevent sediment influx from compensating for local subsidence, increasing coastal erosion. Thus making the problem of coastal flooding due to storm surges and MSL more serious.

BROADUS et al. (1986) and BROADUS (1993) have made a detailed study of the possible effect of sea level rise and damming of rivers in the coastal areas of Bangladesh and Egypt.

The potential economic implications of two relative sea levels rise scenarios for the year 2050 and 2100 has been examined.

Table 8.4 gives these scenarios of relative sea level rise for Bangladesh together with the economic activities/assets in affected areas (BROADUS, 1993).

Table 8.4: Relative Sea Level Scenarios and Economic Activities/Assets in Affected Areas of Bangladesh

Activities/ Assets	1 m (2050)	3 m (2100)
Total sea level rise	0.83 m	3.4 m
(Global)	(0.13 m)	(2.2 m)
(Local subsidence)	(0.70 m)	(1.2 m)
Loss habitable land	7 %	26 %
Population	5 %	27 %
Gross Domestic Product (GDP)	5 %	20 %

Fig. 8.6 gives the landward transgression scenarios from a 1 m, 2 m, 3 m, and 5 m rise in relative sea level. The 1 m and 3 m scenarios correspond to the projected 13 cm and 2 m of global sea level rise by 2050 and 2100 respectively. It may be seen from these scenarios that even with 1 m relative sea level rise large population and economic activities will be exposed to serious threats from storm surge flooding. Percentage of population lying between 1 m and 3 m transgression lines is very high which includes the city of Khulna having population density more than 29000 per km² (BROADUS, 1993).

Another significant consequence of the relative sea level rise pointed out by BROADUS (1993) is the loss of Sunderban Forest Reserve in Khulna district which at present provides vital protection for this area by acting as a buffer against storm surges. Loss of this buffer could increase the threat of storm surge floods, which could reach up to greater inland distances.

DUBE and RAO (1989, 1991) used a continuously moving coastal boundary numerical model to examine how changes in MSL may affect the storm surges and the low lying coastal flooding along the east coast of India. The authors have presented different scenarios indicating the implication of a rise in the sea level on the surge generated by the 1977 Andhra cyclone. Authors found that higher MSL of the Bay of Bengal allows the storm surges to build on a higher base with increased inland inundation along the low lying regions of Andhra coast of India.

Using a numerical storm surge model FLATHER and KHANDKER (1993) examined the effect of rise in mean sea level on tides, storm surges and their interaction for the Bay of Bengal. They simulated the surge generated by the Bangladesh cyclone of May 24–25, 1985 with and without 2 m rise in sea level. For the M2 tides, authors found an increase in amplitude by 10 cm in NE and decrease by similar amount NW of the Bay when the sea level is raised by 2 m. For the storm surge a reduction in the maximum computed surge elevation of 20–30 cm was predicted by a 2 m rise in MSL (Fig. 8.7). Authors attribute this to a decrease in the ratio, wind stress/water depth that occurred in the case of an elevated MSL, which is also consistent with theory and other model studies. Tide-surge interaction response with raised MSL resulted in a reduction of maximum computed water level in the NE and NW corners of the Bay, with an increase in level in an area between (Fig. 8.8 a, b). Authors attribute this more

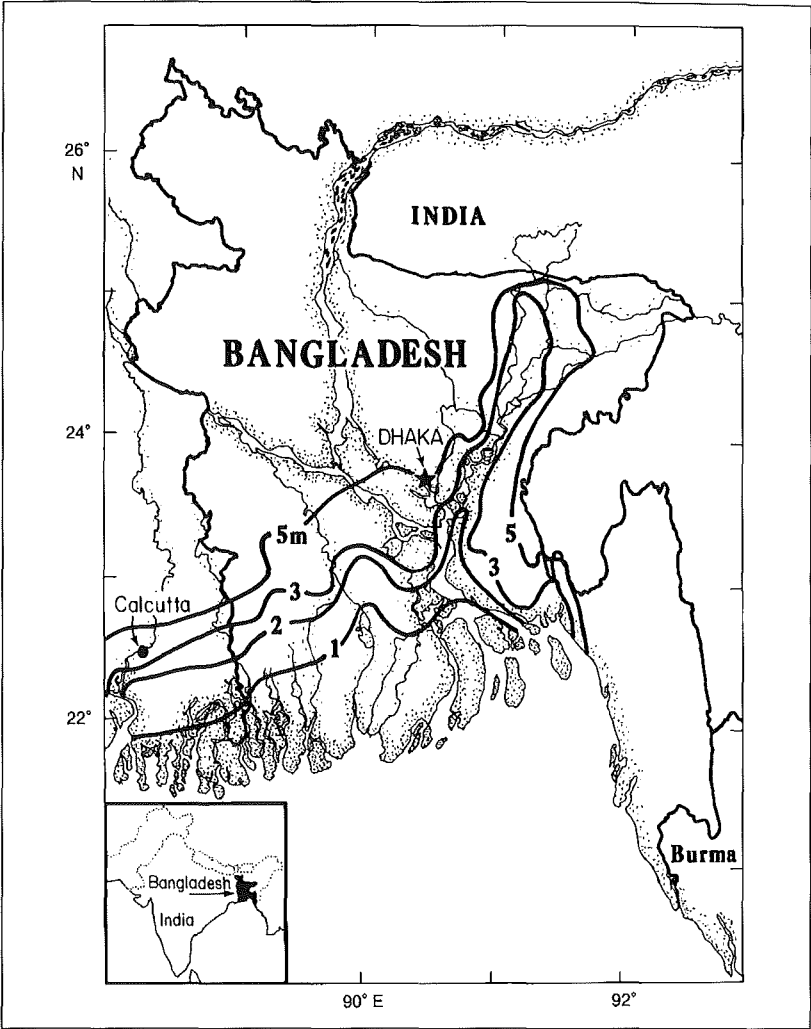


Fig. 8.6: Sea level transgression scenarios for Bangladesh (BROADUS, 1993)

complex behaviour to the variations in the relative timing of tidal high water and peak surge. FLATHER and KHANDKER (1993) further noted that a reduction of 20 cm in maximum computed water level suggests that the effect of the 2 m increase in MSL would be to raise the highest flood level by about 1.8 m above those expected with the present MSL.

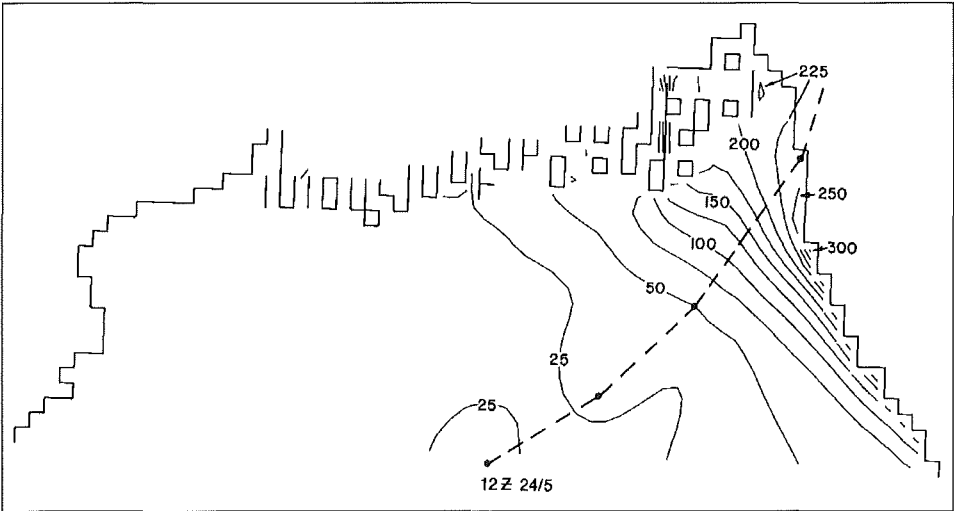


Fig. 8.7(a): Contours of maximum computed surge elevation (cm) in the period 1200 GMT 24 May to 1200 GMT 25 May 1985. The broken line indicates the track of the cyclone (FLATHER and KHANDKER, 1993)



Fig. 8.7(b): Change (cm) in maximum computed elevation (cm) produced by a 2 m rise in MSL (FLATHER and KHANDKER, 1993)

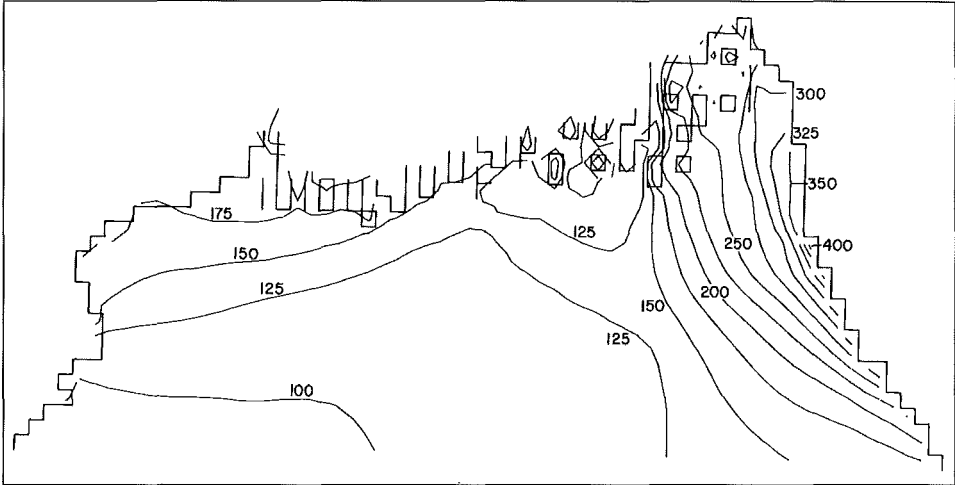


Fig. 8.8(a): Contours of maximum computed elevation (cm) due to tide and surge in the period 1200 GMT 24 May to 1200 GMT 25 May 1985 (FLATHER and KHANDKER, 1993)

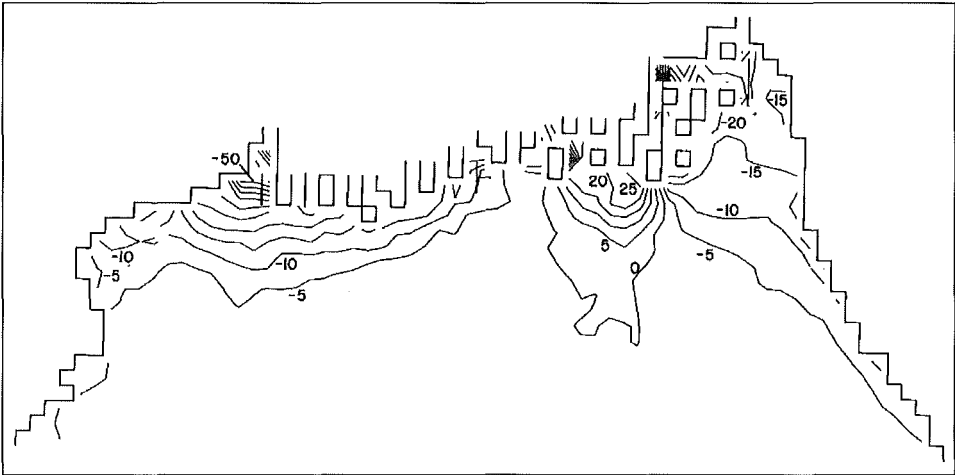


Fig. 8.8(b): Change (cm) in maximum computed tide + surge elevation produced by a 2 m rise in MSL (FLATHER and KHANDKER, 1993)

ALI (1996) used a numerical model to generate storm surge scenarios for Bangladesh under increased cyclone intensity and sea level rise. Using the temperature and wind relation given by EMANUEL (1987), the likely wind speeds of the April 1991 cyclone that hit Bangladesh under two sea surface temperature scenarios of 2° C and 4° C have been estimated by the author. These wind speeds were then used to compute storm surges for a sea surface temperature rise of 2 and 4° C, and sea level rise of 0.3 and 1.0 m. Surge heights computed by ALI (1996) under these conditions are given in Table 8.5. Numbers in parentheses indicate percentage increase or decrease in storm surge heights from the present surge height. It may be seen from the table that a rise in the sea level tends to reduce storm surge heights which is on expected lines as the increase in sea level results in increased water depth over the continental shelf. On the other hand a maximum increase of about 49 % in the surge height is predicted for the increased intensity of cyclone corresponding to a 4° C rise in SST.

Table 8.5: Storm surge heights (m) under different sea surface temperatures and sea level rise scenarios (wind speed of 225 km h⁻¹ corresponds to that of the April 1991 cyclone) (ALI, 1996)

	Current Temp. (27° C)	2° C Increase	4° C Increase
Wind (km h ⁻¹)	225	248	275
No Sea Level Rise Surge Height (% change)	7.6 (0 %)	9.2 (21 %)	11.3 (49 %)
Sea Level Rise = 0.3 m Surge Height (% change)	7.4 (-3 %)	9.1 (20 %)	11.1 (46 %)
Sea Level Rise = 0.1m Surge Height (% change)	7.1 (-7 %)	8.6 (13 %)	10.6 (40 %)

ALI (1996) also used an empirical formula to compute inland inundation along flat land around Meghna estuary associated with April 1991 cyclone under the present and warmer SST conditions. He found increased inland penetration of the surge by 13 % and 31 % for a SST rise of 2° C and 4° C respectively. In conclusion author considers these results as indicative only because of several simplifying assumptions, which are used, and uncertainties concerning the relationship of SST's and cyclone intensities.

In a recent study SINHA et al. (1997) applied a tidal circulation model to examine how a sea level rise might affect the water level and currents in the Hooghly estuary situated in the head Bay of Bengal. For this study the authors did not consider the changes in the shoreline as a result of rise in sea level. Model results show a substantial increase in the amplitude and velocities of the tidal wave due to the sea level rise by 50 cm and 1 m in Hooghly estuary. Results also indicate that variations in the tidal wave due to raised mean sea level become more prominent in the upstream regions of Hooghly estuary. Magnitude of tidal currents is also found to increase significantly with rise in sea level. The results are important as they suggest that these changes in the flow field of Hooghly estuary may increase the salinity intrusion. Besides the increase in currents due to sea level rise may cause more erosion of banks of estuary, shifting the net deposition further northward.

8.6.2 Arabian Sea and Maldives

The threat from sea level rise and storm surges is not a serious consideration in most parts of the west coast of India, coast of Pakistan, Arabian/Persian Gulf, Saudi Arabia, Red Sea and east coast of Africa. The only region that is vulnerable to severe storm surge is the Gujarat coast of India. While projected sea level rise of 50 cm to 1 m by 2100 is expected to affect hundreds of thousands square kilometers of coastal wetlands and low lands in these countries, many small island countries face a bigger threat as they could lose a significant part of their land area.

The problem is particularly acute in the Maldives, which is in southern part of the Arabian Sea. The Maldives archipelago consists of 1,190 islands stretched in a chain 820 km in length extending from Ihavandiffula (6° 57'N) to Addu Atoll (0° 34'S). The average elevation of these islands is 1 to 1.5 m above existing sea level (PERNETTA, 1992). Much of the island, and almost all the village, is 0.8–1.1 m above mean sea level.

Tropical storms are rare in Maldives, but increase in occurrence and intensity towards the north. Storms are experienced on Minicoy, and Lakshdweep Islands of India, which are to the north of Maldives. The tidal range is up to 1.2 m in the north and 1.4 m in the south of Maldives. Occasional storms accompanied by high astronomical tides cause destructive flooding in islands. In fact, flooding is the major concern as 80 % of the nation's land area is less than 1 m above sea level. Particularly affected has been the capital Male' which is heavily crowded with over 70,000 people inhabiting the 1.8 sq. km area. Due to large population pressure the island has been extended in all directions, and the combinations of all reclaimed shoreline and mined reef, have increased the vulnerability of Male. This was especially the case on 10–12 April 1987 when Male' experienced high waves which inundated much of the island.

Rising sea levels would almost certainly cause most of the islands to become uninhabitable, displacing more than 225,000 Maldivians. In fact, a rise of one meter sea level would sink about 80 % of the Maldives beneath the sea.

In conclusion we may say that although storm surge is not a threat to Maldives, the nation stands to lose heavily from the adverse effects of global warming and sea level rise.

Lakshadweep Islands of India are also vulnerable to sea level rise. Anticipated rise of sea level by 1m may cause heavy land loss in Kiltan, Kaviratti, Kadmat, Kalpani, Cheriyan and Agati-Bingaram Islands (NIGAM, 1989).

8.6.3 Persian Gulf, Red Sea and the Mediterranean Sea

The Persian Gulf region is mainly influenced by extra-tropical weather systems, whereas the region south of the Strait of Hormuz is affected by tropical cyclones. The Gulf is subjected to major negative and positive storm surges. Particularly vulnerable to sea level rise in the Persian Gulf is the region Tigris-Euphrates delta (Fig. 8.5), which is characterised by negative surges (EL-SABH and MURTY, 1989). Impact of sea level rise on storm surges, therefore, does not appear to be a threat in the Persian Gulf. On the other hand, there is no present indication of rising sea level in Red Sea.

Regions, which are vulnerable to sea level rise in Mediterranean, are Ebro delta, Rhone delta, northern Adriatic low coasts of Italy, Danube delta, eastern sea of Azov, Poti Swamp, Southeast Turkey, Nile delta of Libya and northeast Tunisia. Regionally, Southern Mediterranean appears to be most vulnerable to sea level rise (Fig. 8.5).

BROADUS (1993) made a detailed study of the impact of projected sea level rise in the deltaic regions of Nile River in Egypt. Scenarios of exposure of population and economic activities relative to sea level rise of 1 m by 2050 and 3 m by 2100 is presented by the author. The analysis suggests that a 1 m rise in sea level (including local subsidence) would cover areas currently accounting for about 12 % of habitable land, 14 % of population and 14 % of Gross Domestic Product (GDP) in Egypt. The figures corresponding to 3 m rise are much higher. Storm surge is not a problem in Egypt; however, with rising sea level the region is likely to be frequently flooded due to waves and tides in the Mediterranean.

8.6.4 European Seas

The regions which are vulnerable to sea level rise in Europe are: Southern and Eastern England, Southern Baltic Coast, Southern Coast of the North Sea and Channel coasts, Loire estuary, Vendée coasts, Lisbon region and Gaudalquivir delta (Fig. 8.5). From the storm surge point of view the North Sea region is of importance and concern and therefore, has been investigated by many workers.

A two-dimensional hydronamic model of the North Sea and part of the continental shelf was used by DE RONDE (1993) to calculate the tidal system changes as a result of arbitrary sea level increase of 2.5 and 5.0 m. He considered the Netherlands' complex coast in detail for his study. The author also examined impact of sea level rise on storm surge. Some of the conclusions reached by DE RONDE (1993) for the case of a 1 m sea level rise are:

- (i) 0.95–1.1 m rise in mean high water level with insignificant changes in the tidal motion in the North Sea and along Dutch coast.
- (ii) Less than 5 cm change in storm surge amplitudes.

JELGERSMA et al. (1995) examined in detail the Holocene storm surge signatures in the coastal dunes along the central Netherlands' coast. They describe and discuss the occurrence and possible significance of Holocene shell deposits, which have been found intercalated in the dune sands. These deposits are believed to be the result of storm surge activity on the foreshore, either through swash or over wash action, and of subsequent preservation due to aeolian coverage of basically sedimentary coastal system. Taking into account of the contemporary mean sea level, the authors gave an interpretation of the surge level elevations associated with the depositions. Authors found an increasing level of storm surge elevations with increasing time. They suggest that climatic variations on the one hand and foreshore bathymetry on the other hand may be factors of relevance to explain these results.

Several observational and modelling studies have been carried out to examine changes in mean sea level on the German Baltic coast and German Bight of North Sea. Mention may be made of some of the recent observation and studies in this regard (SIEFERT, 1990; HOFSTEDE, 1991; SIEFERT and JENSEN, 1993; TOPPE, 1993; PUNNING, 1993; KUNZ, 1993, STIGGE, 1993). Almost all of these studies confirm a rise in mean sea level on both the Baltic and North Sea coast of Germany. Fig. 8.9 shows that observed MSL and its trend at Cuxhaven, (Germany).

STIGGE (1993) investigated sea level changes and high water levels probability on the German Baltic coast with the purpose of defining the defence level (maximum high water crest) for the next fifty years. An accelerated rise of storm surge frequency during last 50 years was observed (Fig. 8.10). He notes that a rise in MSL could produce an increase in the storm

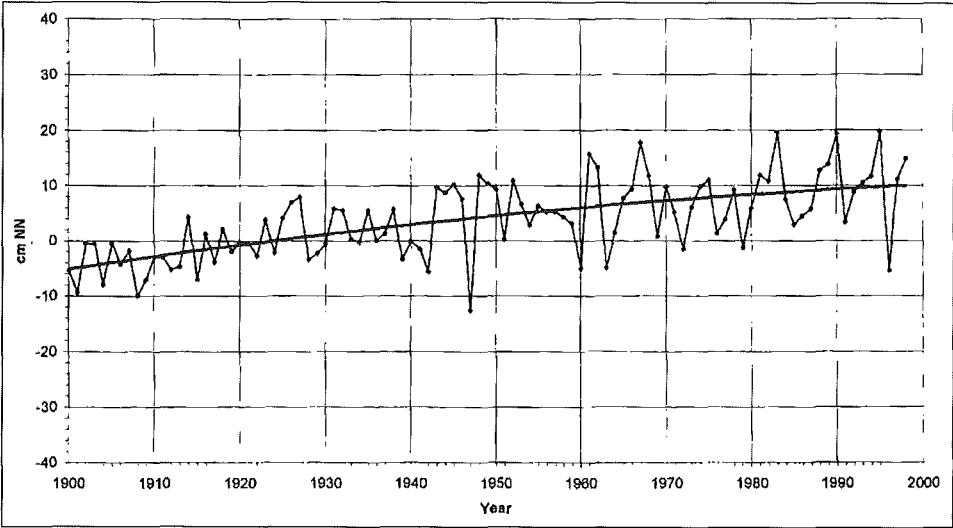


Fig. 8.9: Mean Sea Level at Cuxhaven (FERK, 1999)

surge frequency both in the North Sea and in the Baltic Sea. At first glance a differentiation between these two cases seems of little importance, but it may be noted that storm surges can be influenced by stronger winds associated with intense cyclones, in addition to the effect of a slow rise in MSL. STIGGE (1993), therefore, did not accept the widely held opinion that an increase of storm surge frequency in the western Baltic necessarily has to be connected with a significant increase of the high water crests.

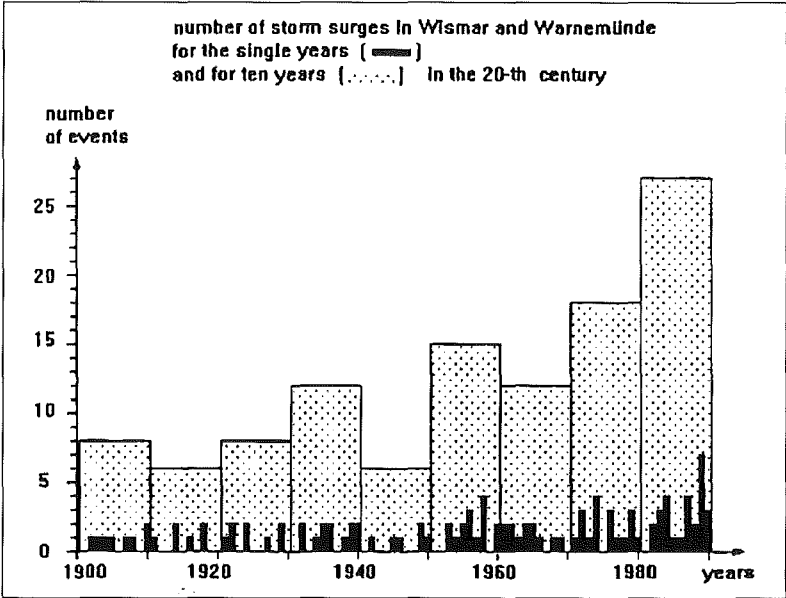


Fig. 8.10: Frequency of storm surges on the German Baltic coast (STIGGE, 1993)

8.6.5 The Americas

Sectors of the American coastline which are particularly vulnerable to relative rise in mean sea level are Long Beach area and Colorado River delta on the Pacific coast and Gulf of La Plata, Amazon delta, Orinoco delta, Gulf of Mexico on the Atlantic coast (Fig. 8.5).

Impact of sea level rise on coastal systems of Mississippi River deltaic plain in the Gulf of Mexico was examined by DAY et al. (1993). Mississippi delta consists of lakes, bays, near sea level wetlands and low-lying uplands. Water levels in this region have increased substantially, primarily from regional land subsidence rather than eustatic sea level rise. Because of continuing subsidence and apparent sea level rise, many low-lying areas are experiencing increased flooding from the river and from the sea (during storm surges).

New England is not frequently visited by hurricanes; however, severe hurricanes about once a decade strike Southern New England. If sea level continues to rise as a result of global warming, the destruction wrought by future storms could wipe out many seaside oases. In the event of a severe hurricane striking the coast, the rise in the sea level would be compounded by a storm surge that would make high 10 to 15 feet water level some to higher than usual (ALLEN, 1998). ALLEN (1998) further indicates that severe hurricanes like the one that struck New England three times between 1938 to 1954 may generate very large amplitudes the storm surge.

Impact of sea level rise on the east coast of south America has been examined in detail by LEATHERMAN (1986) and SCHNACK (1993). This coast is not vulnerable to severe tropical cyclones and storm surges.

8.6.6 Australia

LOVE (1988) derived a number of tropical cyclones storm surge climatologies for three Australian parts, Darwin, Mackay and Port Hedland. For his analysis he considered the present climatological scenario and the scenarios after specifying possible responses of the tropical cyclones climatology to a SST warming of the order of 1.0°C in the oceans surrounding northern Australia accompanied by a sea level rise of 1 m. He demonstrated that sea level rise will have a significant impact on estimates of the return periods for extreme surge events, shortening them at all the three locations (i.e., the frequency of surge events is increased). Table 8.6 gives the return period of tropical cyclone storm surges of 5 m, 2.5 m and 4 m above high astronomical tide (HAT) at Port Hedland, Darwin and Mackay respectively.

Table 8.6: Return period (in years) for tropical cyclone storm surges above specified level for the three selected ports under a variety of warm climate scenarios (LOVE, 1988)

	Port Hedland	Darwin	Mackay
Surge level above HAT	5 m	2.5 m	4 m
“Present”	13 000	36 000	16 000
“Present” plus 1 m sea level rise	1000	4100	600
Increase “Frequency” of cyclones plus 1 m sea level rise	900	1800	650
Increased “Intensity” of cyclone plus 1 m sea level rise	430	650	200
Increased “Frequency” and “Intensity” cyclone plus 1 m sea level rise	350	450	180

MCINNES and HUBBERT (1995) used a sophisticated storm surge model capable of simulating the inundation associated with May 1994 and November 1994 mid-latitudes severe storms of Port Phillip Bay in the southeast part of Australia. They performed three experiments: (i) Exp 1: Controlled experiment, (ii) Exp 2: Sensitivity experiment with increased sea level rise of 80 cm, and (iii) Sensitivity experiment with 10 % increase in the wind forcing in addition to a sea level rise of 80 cm. Results were presented for the entire Port Phillip Bay as well as the three small domains Werribee, Hobson’s Bay and Mordialloc. They found different order of inundation in these three areas, leading to the conclusion that the estimation of the climate impact in the coastal region is highly site-specific problem. The areas of inundation in each of the three regions increased with the increase of sea level and with a further inundation with 10 % increase in wind strength (Table 8.7).

Table 8.7: Summary of the ratio area inundated to the area of inundation in Exp. 1 for the same event and model domains. The three domains are Werribee (W), Hobson’s Bay (HB) and Mordialloc (M). The value in brackets denotes the total area inundated in km² (PITTOCK et al., 1996)

	May 1994			Nov. 1994		
	W	HB	M	W	HB	M
Exp. 1	1.0 (11.2)	1.0 (0.9)	1.0 (0.7)	1.0 (15.8)	1.0 (0.9)	1.0 (0.7)
Exp. 2	2.7 (30.4)	1.9 (1.7)	9.3 (6.5)	2.2 (34.4)	2.0 (1.8)	8.9 (6.2)
Exp. 3	3.1 (34.3)	2.6 (2.3)	11.0 (7.7)	2.6 (41.0)	3.2 (2.9)	12.6 (8.8)

PITTOCK et al. (1996) made a detailed review of the effect of enhanced green house on the climatology of tropical cyclones. They also reviewed the changes in storm surges due to tropical and extra-tropical cyclones as a result of mean sea level rise. They highlighted the requirement of site-specific inundation modelling studies as the magnitude of increase in coastal inundation due to rise in mean sea level heavily depends upon the specific characteristics of the site, including both meteorology and coastal geomorphology. More recently HUBBERT and MCINNES (1999) developed a high resolution storm surge inundation model

for coastal planning and impact studies. Model simulations were successfully carried out for the town of Port Hedland on the northwest coast of Australia and for the Port Phillip Bay, upon which the city of Melbourne is located. Scenarios of sea level rise and increased storm wind strength were imposed on the model simulations to explore the possible impact of climate change on two potentially vulnerable regions in south eastern Australia as well as demonstrate the application of the model to impact studies of this kind.

8.6.7 China

China has extensive coastal low lands with three great deltas of Yellow River, Yangtze River and Pearl River. Although all these deltaic regions are vulnerable to sea level rise, the Yangtze River deltaic plain is most vulnerable to accelerating sea level rise.

REN (1993, 1994) made a detailed study of sea level rise and its impact on coastal regions of China. The most significant impact of future sea level rise will be the increased vulnerability to sea inundation of coastal low land due to storm surges. Heaviest casualties and loss of property from storm surges in China occur in the Yangtze River delta. Shanghai area especially experiences enormous losses as a result of combination of flood, astronomical high tidal level and typhoons.

Rising trends in storm surge levels of Shanghai area is currently indicated by observations (YANG, 1996). ZHU and XIE (1995) used a numerical model to compute tidal current and storm surges in the Yangtze River estuary for a projected sea level rise of 50 cm. According to the results of numerical calculations, slight decrease in surge amplitude is seen with a rise in sea level (average decrease in 9 cm in the northern coast and 6 cm in the southern coast of the Yangtze River). Although, the effect of sea level rise is small, the probabilities of occurrence of the storm surge level at a given height will have significant increase due to raised initial mean sea level. Table 8.8 gives the storm surge level with different probabilities of occurrence in the Yangtze River deltaic plain (YANG, 1996).

More recently QIN (1997) used a numerical storm surge and tide model to estimate the impact of sea level rise in the coming decades on the storm surges and tides in Shanghai regions. He estimated a mean annual relative sea level rise of 15–20 cm by 2010, 25–35 cm by 2030 and 40–50 cm by 2050 in Shanghai region as compared to unaltered sea level in 1990. To examine the impact of relative sea level rise on storm surges and tides, QIN (1997) used six severe tropical cyclones hitting Shanghai region. The effect of sea level rise on the storm surges at Wusong is shown in Fig. 8.11. It may be seen from the figure that the amplitude of storm surge decreases with increasing sea level. The maximum effect of the sea level rise on the storm surges in 2010, 2030, and 2050 relative to 1990 could be –0.5, –2.5, and –5.0 cm respectively.

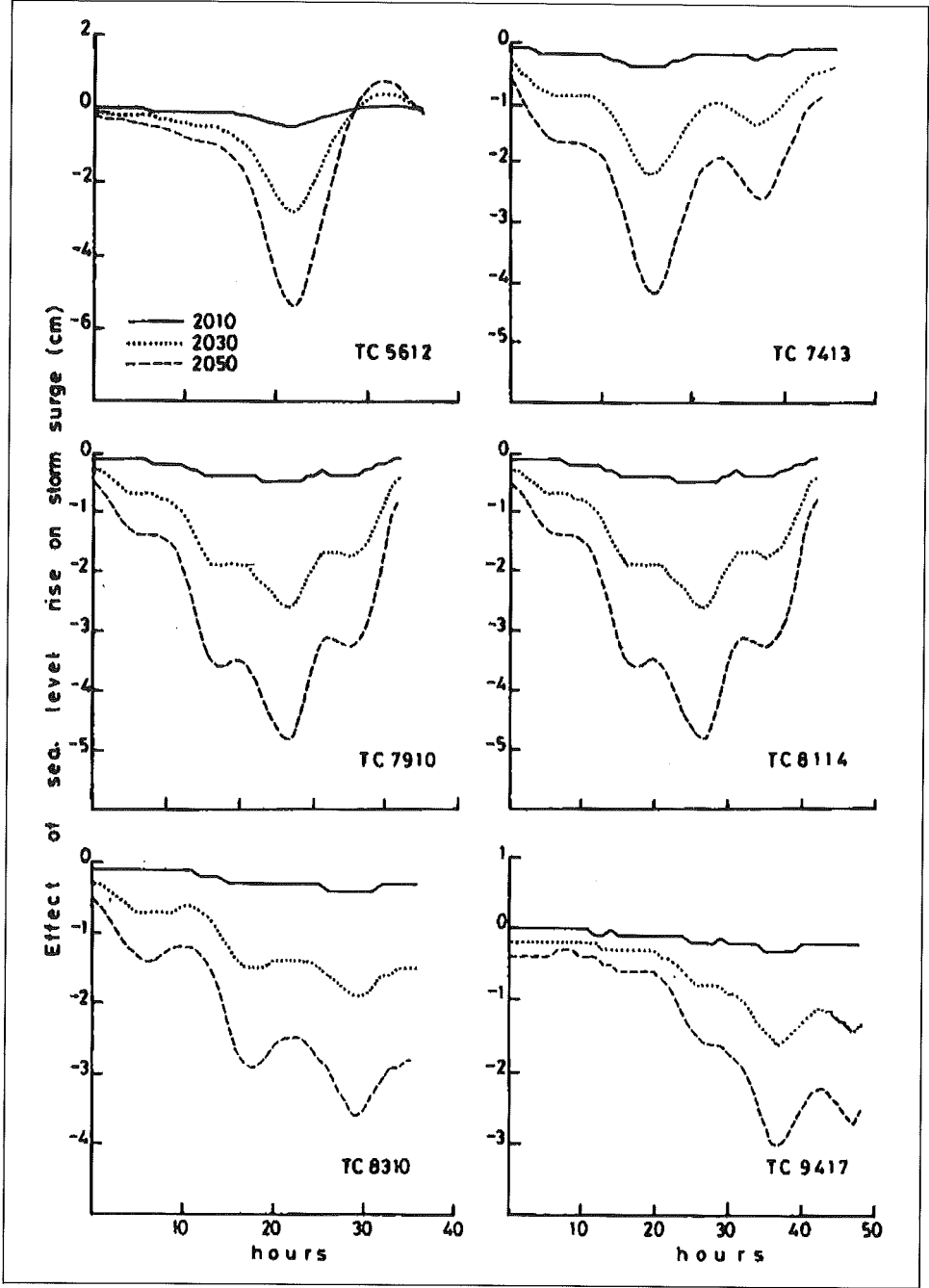


Fig. 8.11: The effect of sea level rise on the storm surge at Wusong (QIN, 1997)

Table 8.8: The impact of sea level rise on storm surge in the Yangtze River deltaic plain (Wusong Datum Plane, m) (YANG, 1996)

Coast section	SLR (cm)	Storm surge level with different probabilities of occurrence					
		1/5	1/10	1/20	1/50	1/100	1/1000
The southern coast	0	5.02	5.17	5.32	5.54	5.69	6.24
The northern coast	50	5.46	5.61	5.76	5.98	6.13	6.68
	0	4.22	4.45	4.68	4.96	5.17	5.88
	50	4.63	4.86	5.09	5.37	5.58	6.29

This negative effect was expected as the rise in sea level results in the decrease of local wind set up and deeper local water than the initial one which leads to decrease of storm surge amplitude. Regarding impact of future relative sea level rise on tides, he found that tides exhibit periodic variations with the same periods as that of tide. The effect increases with increasing rise in relative sea level and retains its period unaltered.

WANG and WANG (1997) calculated maximum storm surge elevations with certain return periods for Guangdong Province of China. They used joint probability method to compute maximum elevations.

Hong Kong is threatened by the possibility of inundation from the sea whenever a tropical cyclone approaches. A number of studies has been carried out in the past (WATTS, 1959; CHENG, 1967; PETERSEN, 1975; LAU, 1980b; CHAN, 1983; CHAN and CHANG, 1997) on maximum sea level during storm surges. Sea level has been rising at an average rate of about 0.3 mm/yr in Hong Kong (YIM, 1993). It is estimated that as a result of global warming sea level may rise 31–110 cm by the year 2100. This will have major environmental effects on coastal lowlands, especially low-lying land reclaimed from the sea in Hong Kong. Although presently there is no evidence for an increase in the frequency of storm surges which may be the result of a rising sea level, Hong Kong is facing a continuing, and perhaps increasing risk of marine inundation from tropical cyclone surges.

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